## Machine and Detector Integration

Karsten Buesser DESY



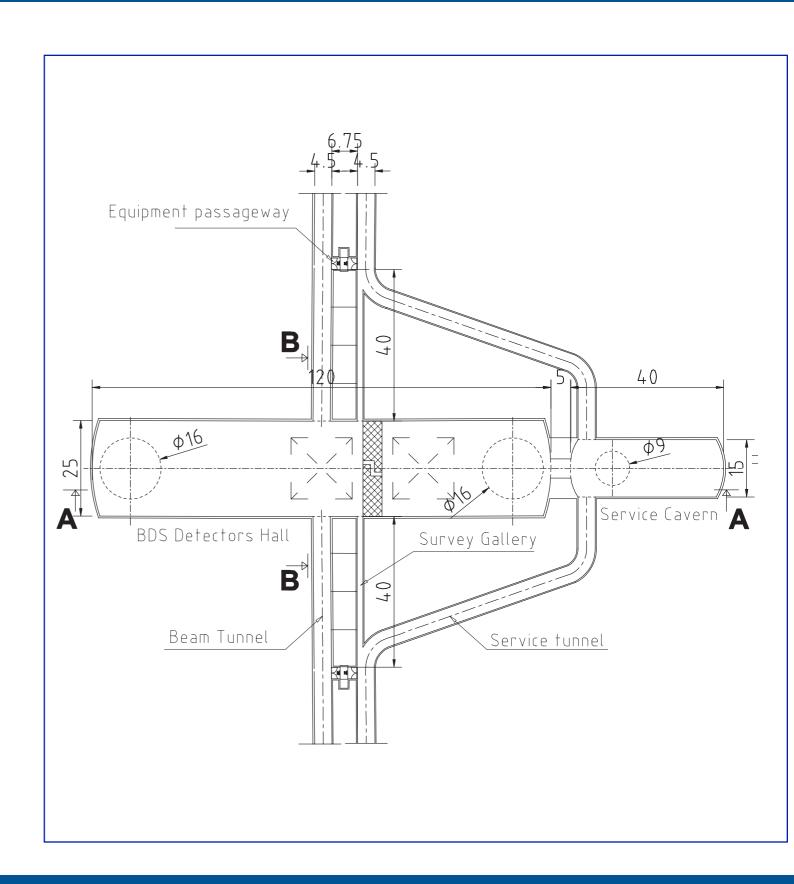
ALCPG 2011 Workshop 22. March 2011

## **High Priority Items**

- Together with SiD and CFS
  - Define underground experimental area design
    - Common platform based push-pull detector motion system
    - Detector services and their impact on CFS issues
  - React on site-specific requirements (e.g. mountainous site boundary conditions)
- ILD internal
  - Design 1st-order engineering model of integrated detector
    - Subdetector services and supplies
    - Cable ways, cooling, support structures
  - Integrate with simulation model
    - Detector integration model in EDMS
    - "Synchronisation" with MOKKA
  - Define the required documents and parameters for the DBD
    - Use the Work Breakdown Structure in ILC-EDMS
- Status:
  - The MDI group is working with all its resources on these topics
  - Unfortunately the resources are small....

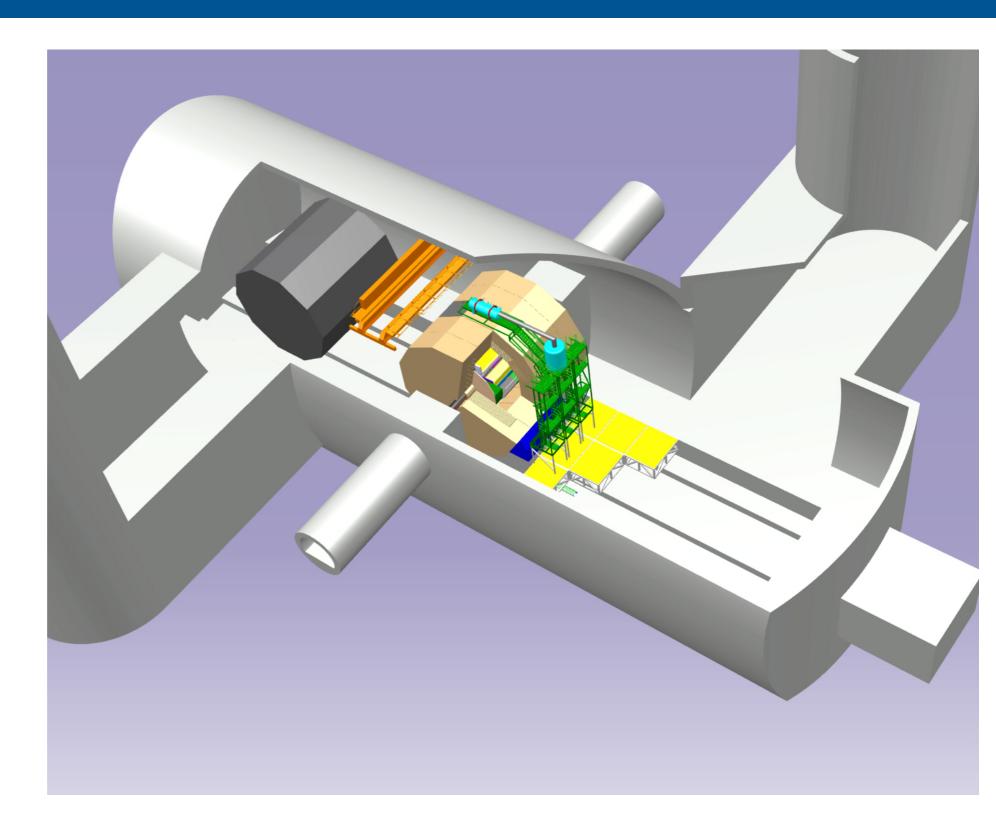
# Experimental Hall (RDR Design)

- Rather large (120m)
- Shafts above experiments
- Not enough space for detector maintenance in parking position
- Unnecessary shielding wall
- No service caverns for detectors

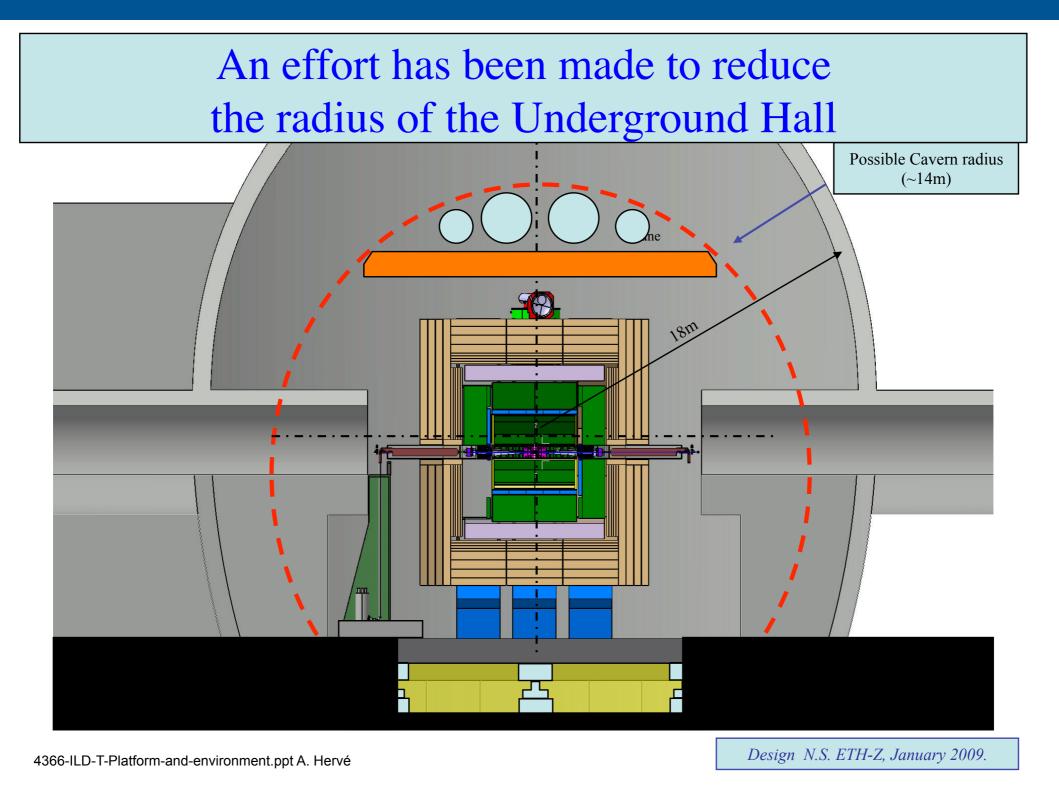


## ILD Experimental Hall Design Study

- Shafts not above experiments
- Alcoves provide access to shafts and space for detector maintenance in parking position
- Additional alcoves for detector services
- Potentially less expensive than RDR hall design (smaller volume)

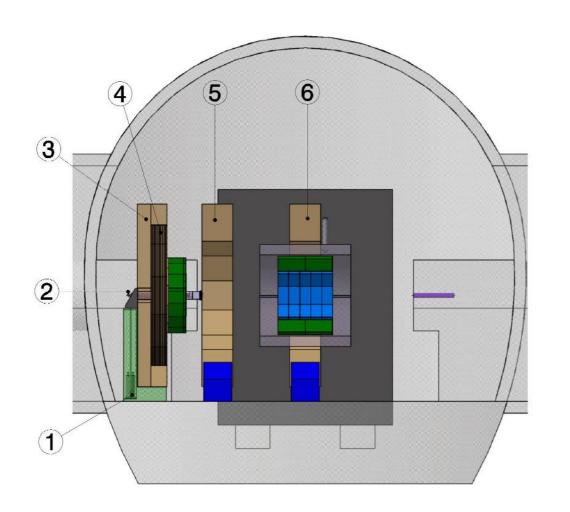


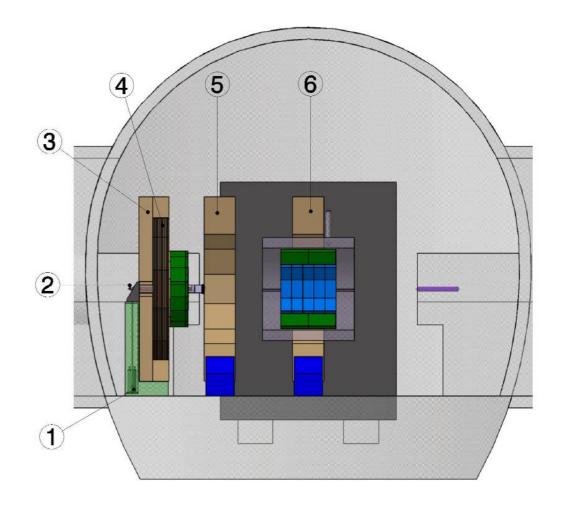
#### Cavern Size



Radius of experimental hall could go down from ~18 to ~14m

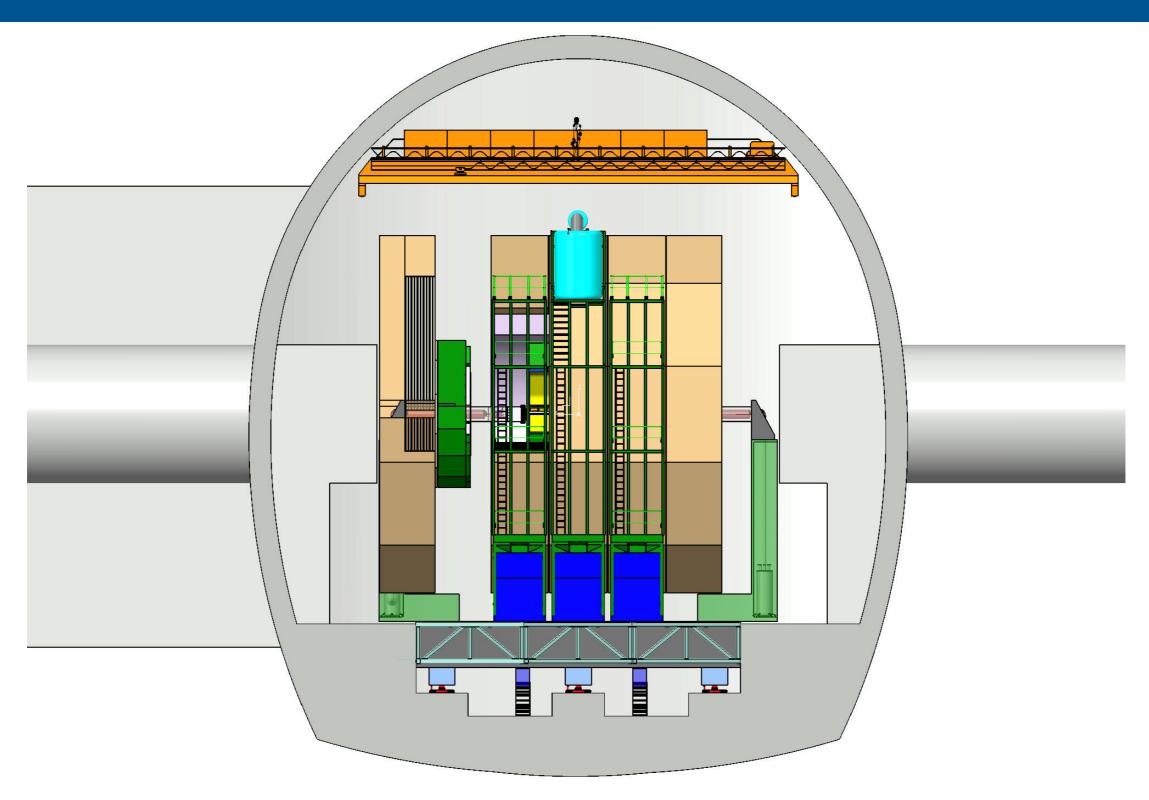
#### **Detector Assembly CMS-Style**





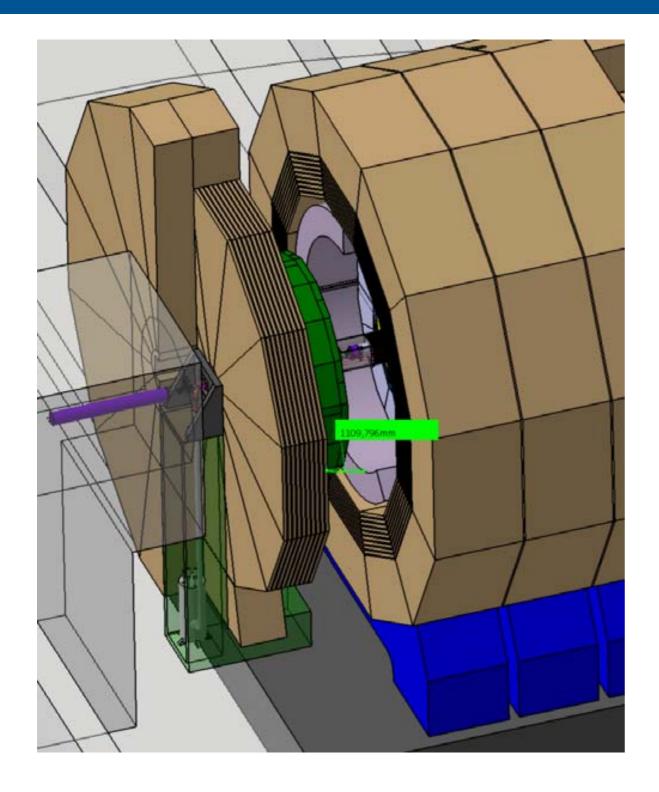
- Pre-assembly of large structures on surface
- Sub-assemblies lowered into the experimental hall
- Main parts:
  - three barrel yoke rings; central carries magnet and barrel detectors
  - two yoke endcaps
  - central tracking system (TPC)

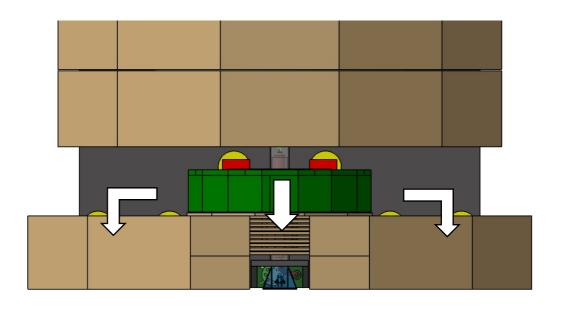
#### **Detector in Beam Position**



NB: Optimised hall size

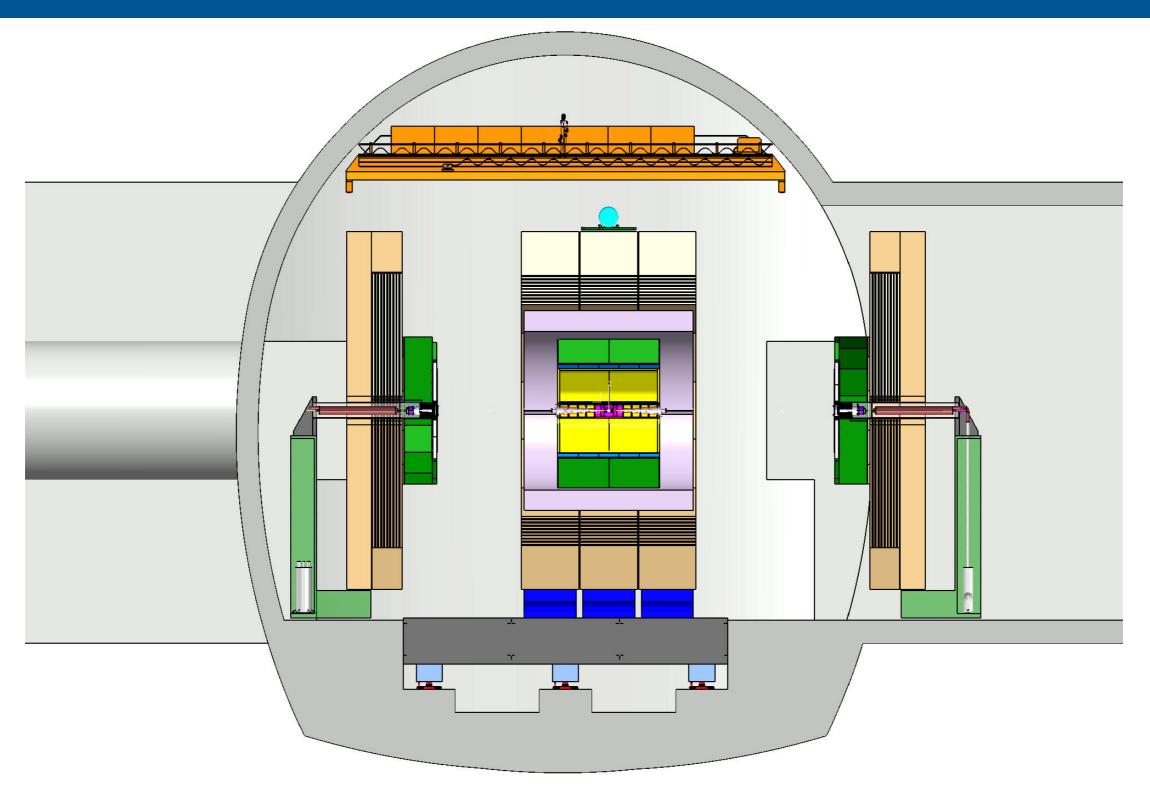
#### **Detector Opening - Beam Position**





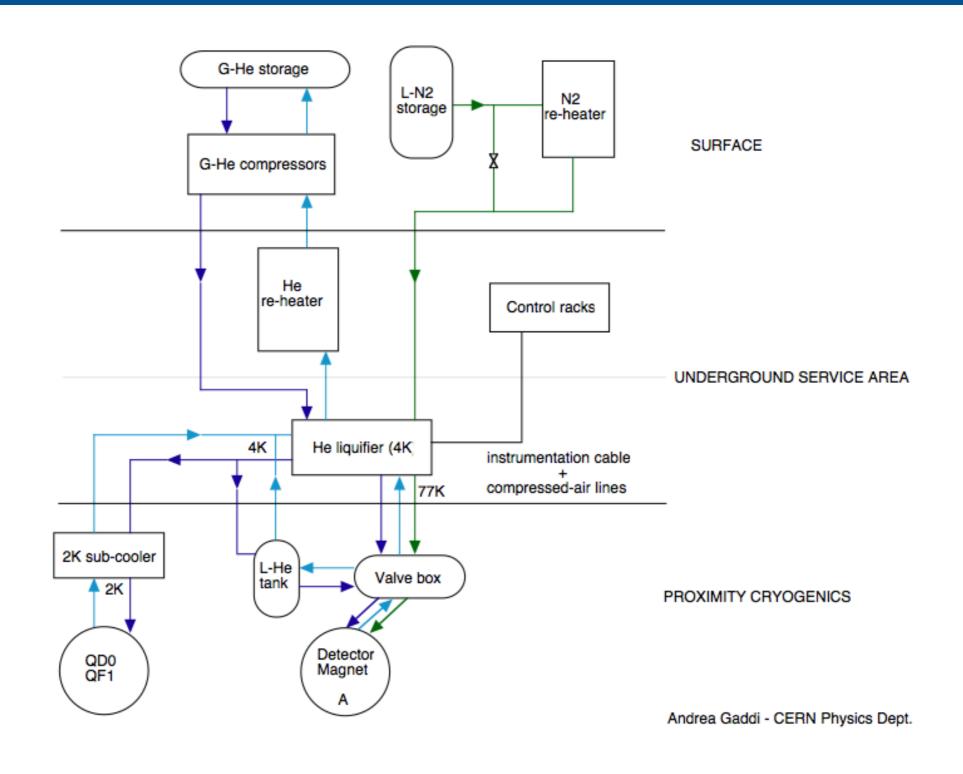
- Option to open the endcap in the beam position for limited access
  - Still under discussion; might not be needed if push-pull concept is taken seriously

## Detector Opening - Garage Position



- Alcove needed for allowing access to subdetectors
  - TPC removal needs ~6m opening

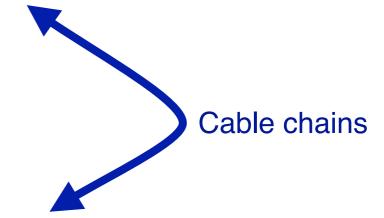
#### **Detector Services**



Cryogenics for the magnets

#### **Detector Services**

- Primary services (on surface)
  - Water chillers
  - HV transformers
  - Diesel and UPS facilities
  - He storage and compressors
  - Gas storage
- Secondary services (underground in alcoves)
  - Cooling water
  - Power supplies
  - Gas mixtures
  - Power converters
  - Cryogenics



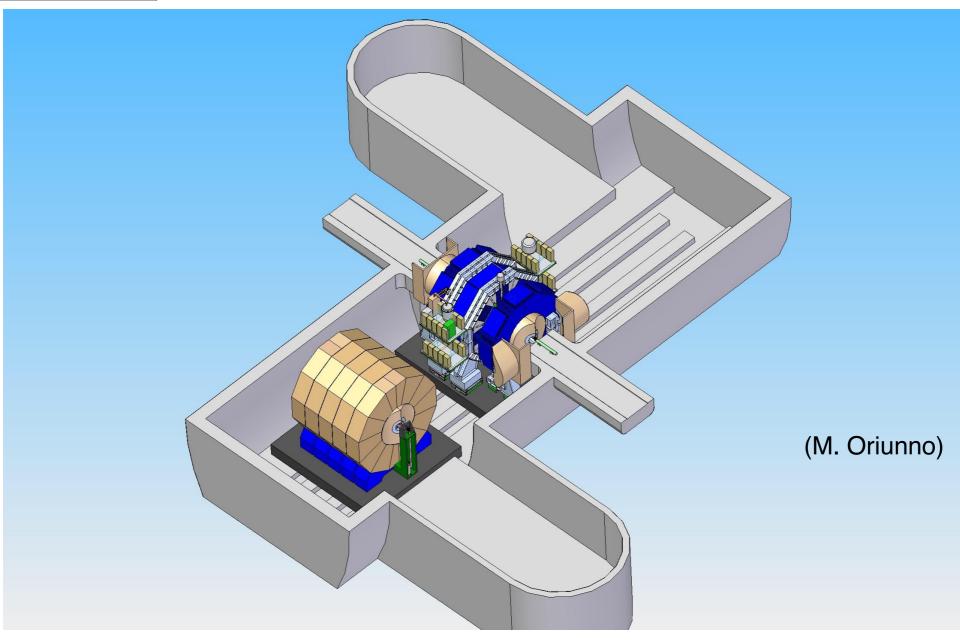
- On-board services (move with detector)
  - Electronic containers
- Need an integrated approach to the service needs of ILD and SiD!

#### Platform Based Detector Motion System



#### Both detectors on a platform



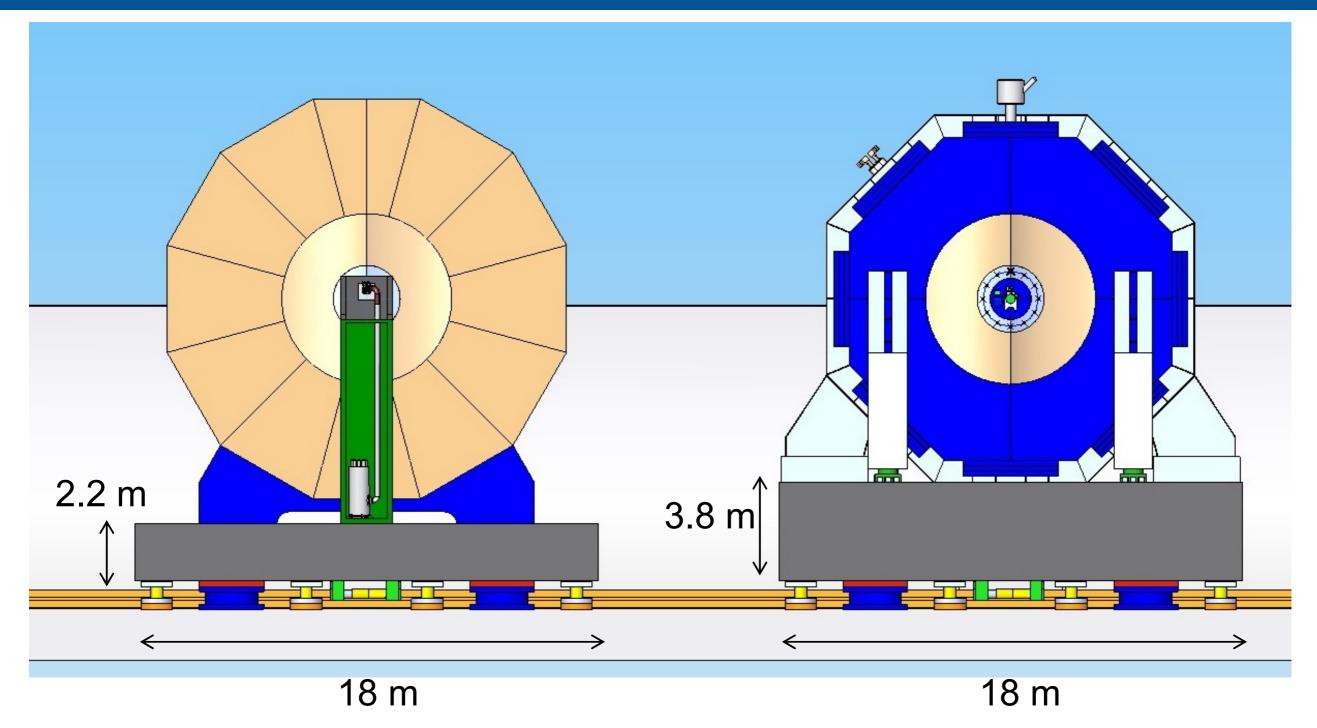


Alain Hervé, CLIC08 Workshop, 16 October 2008

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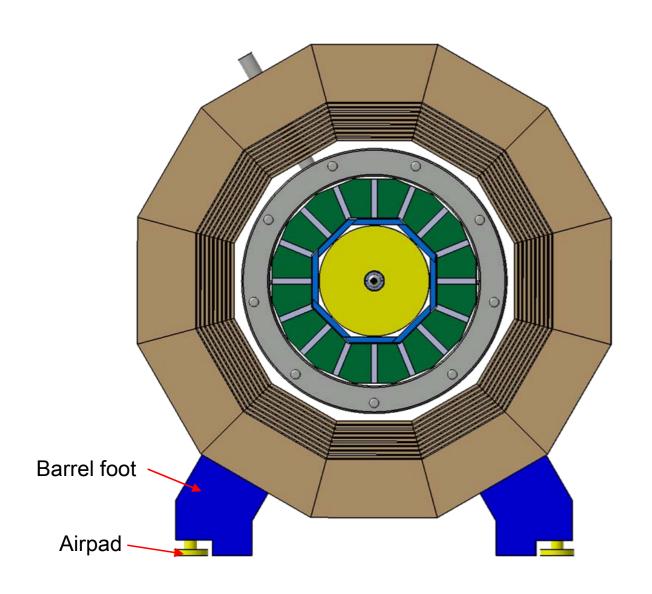
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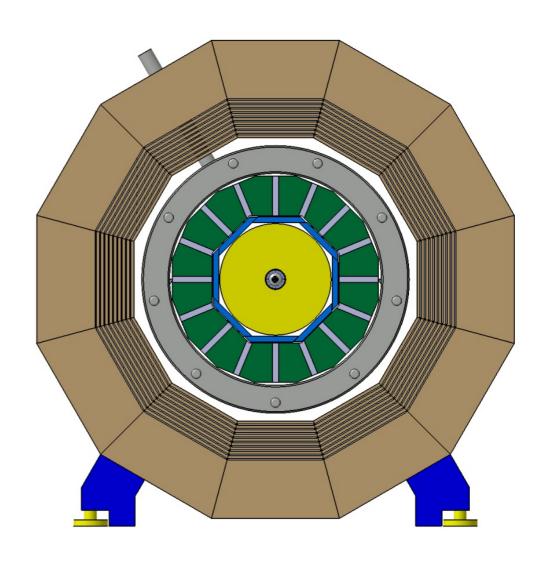
Common working assumption



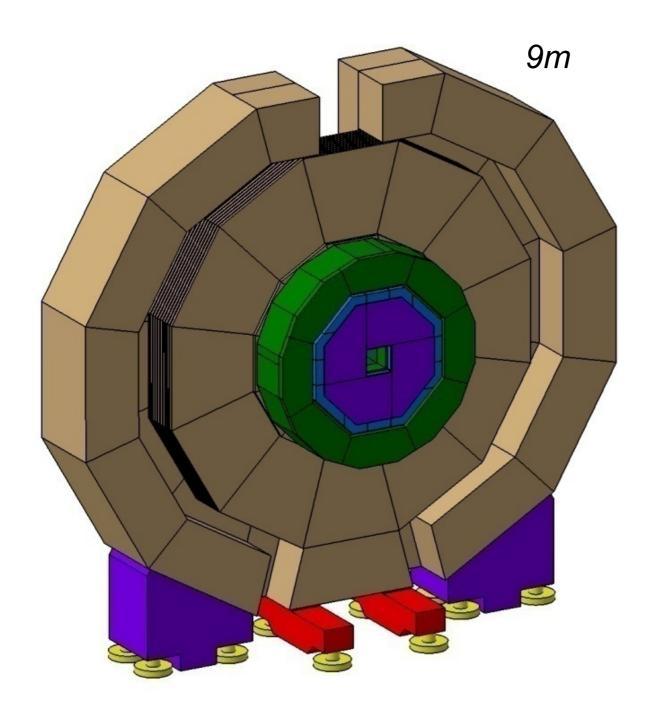
From M. Oriunno @ SiD workshop 2010 after CERN workshop

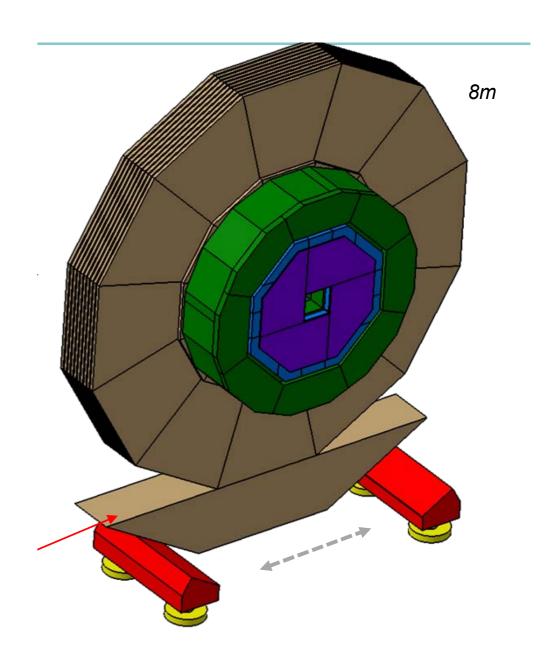
- Beam height difference between SiD and ILD: 1.6m
  - This results in different floor levels in the underground hall



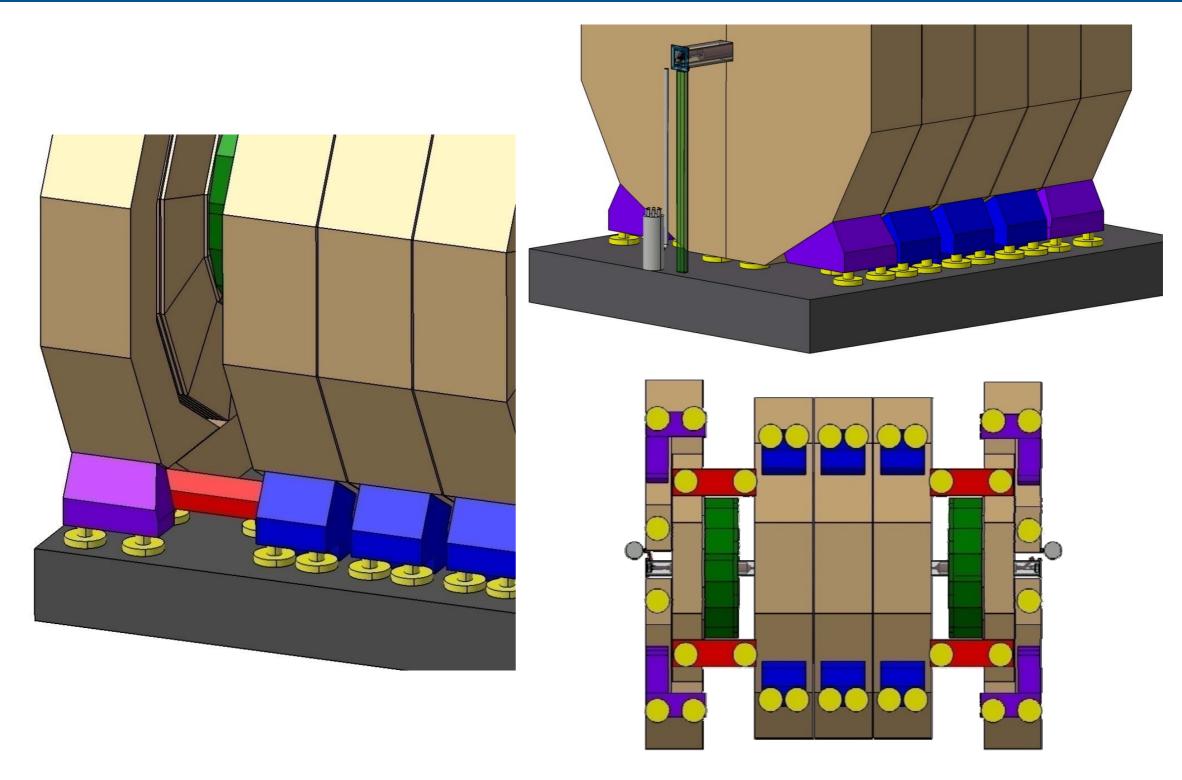


Barrel yoke modification

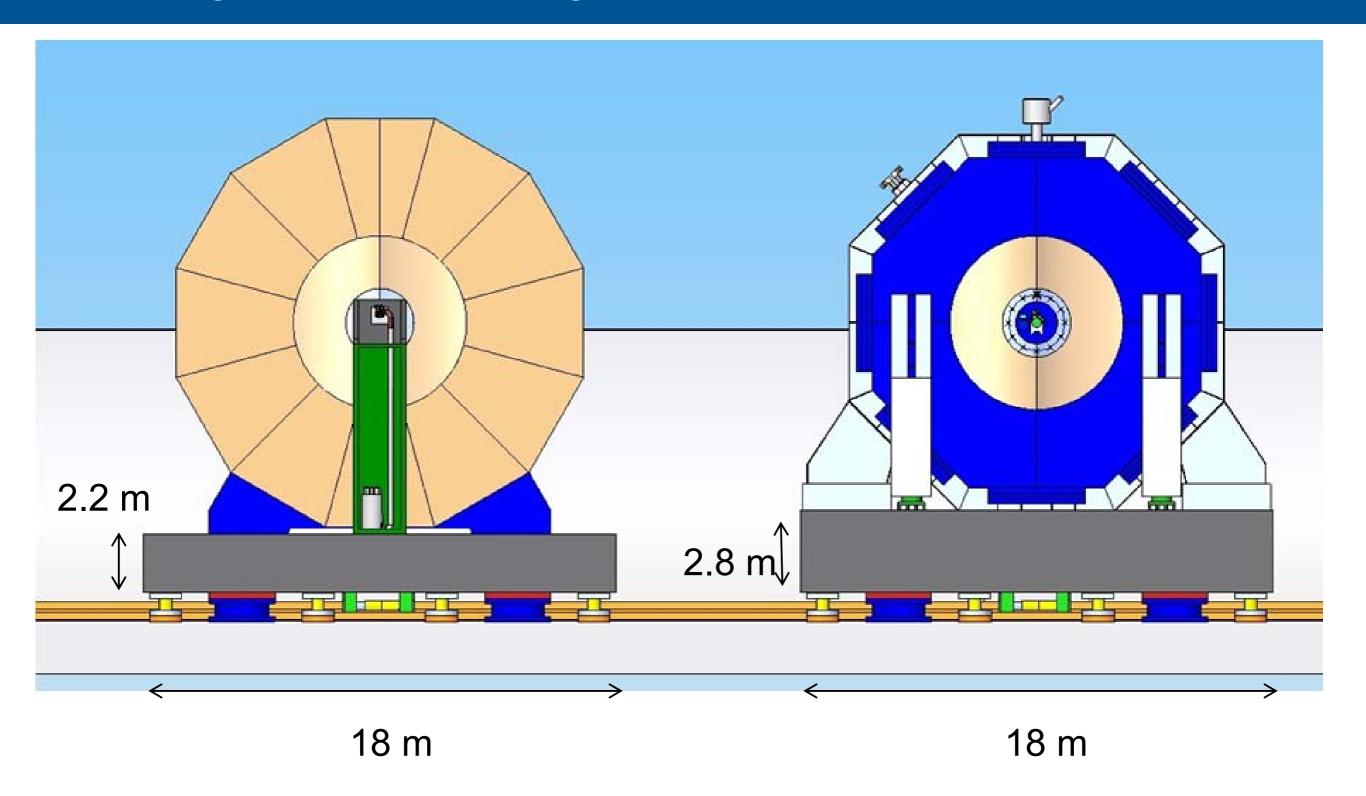




- Endcap yoke is more problematic
  - Split endcap design gets complicated



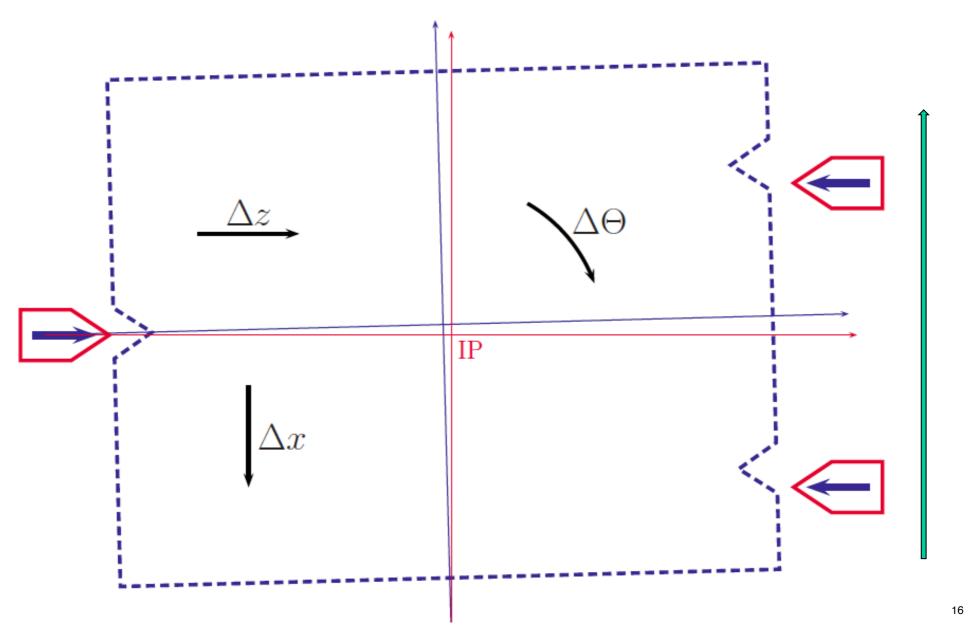
Possible configuration of feet and airpads



- Reducing difference to 0.6m
  - Maybe even less if yoke instrumentation design will be changed

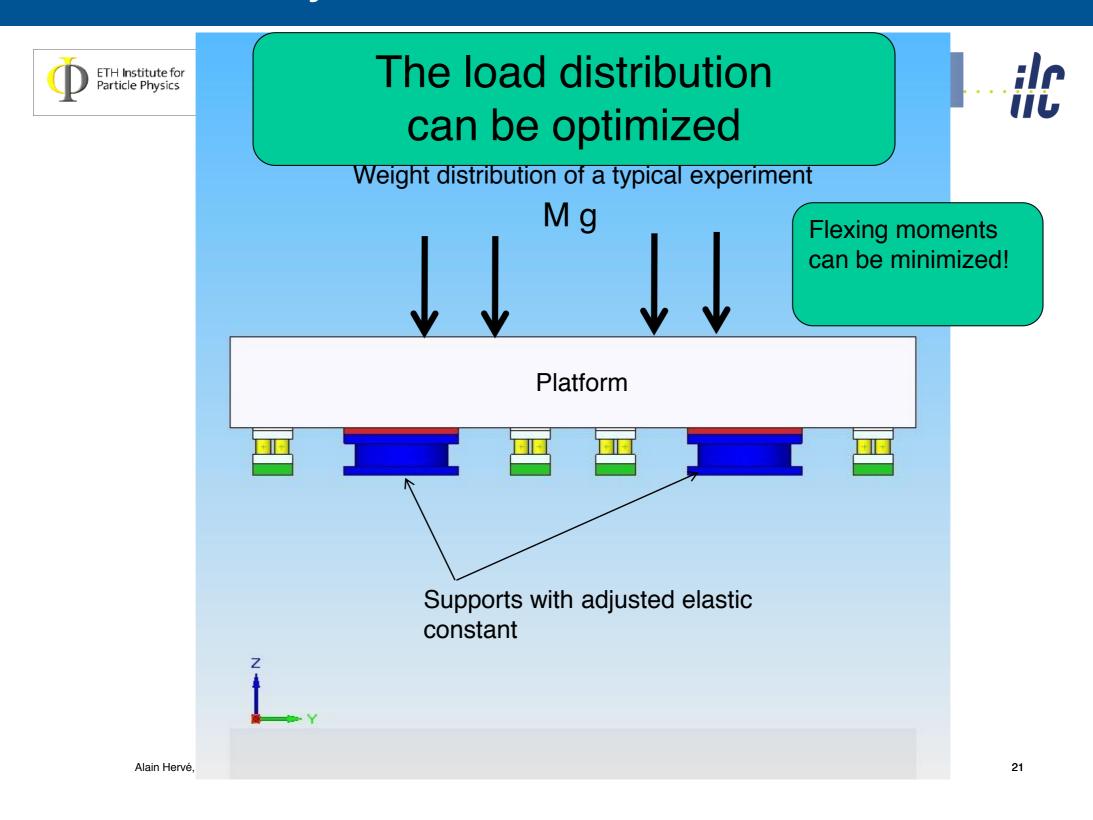
## Platform Motion System

With Airpads a simple positive indexing mechanism is possible giving ≈mm precision



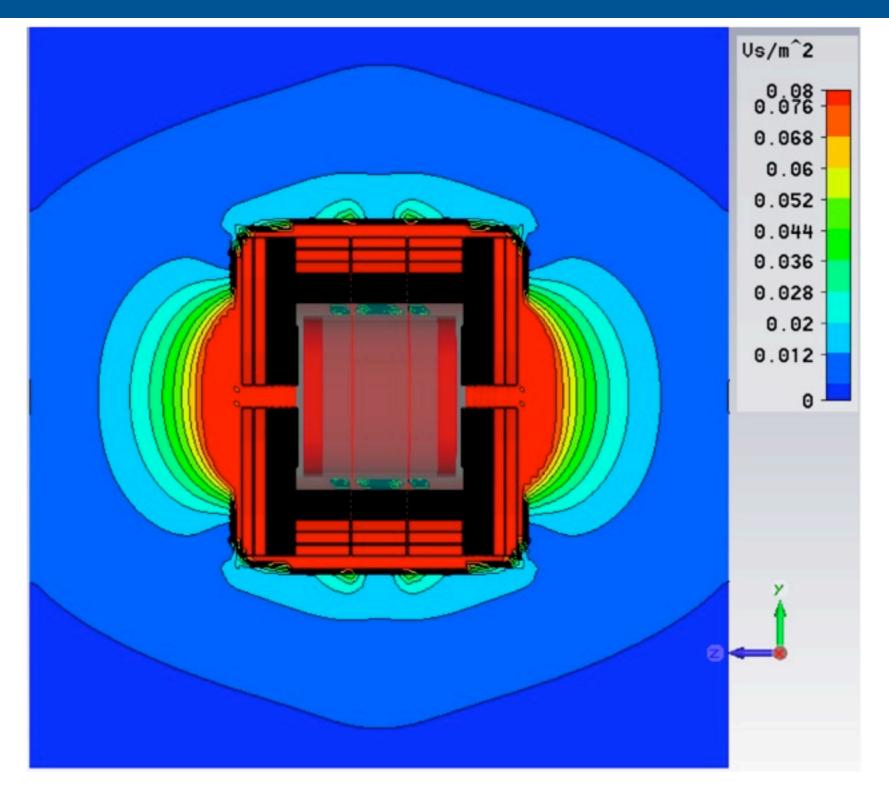
Final precision: +-1 mm and +- 0.1 mrad

## Platform Motion System



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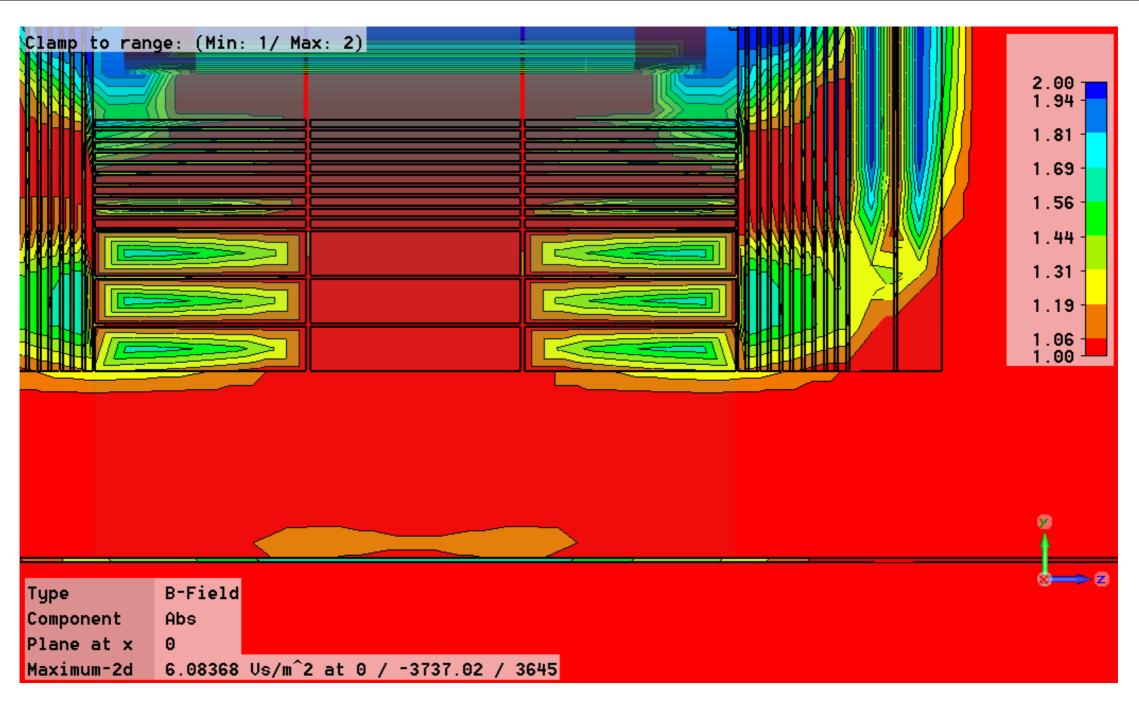
## **ILD Magnetic Stray Fields**



- ILD barrel yoke: ~3m of iron to ensure 5mT at 15m from beam pipe
  - main cause of ILD mass: ~15000 tons

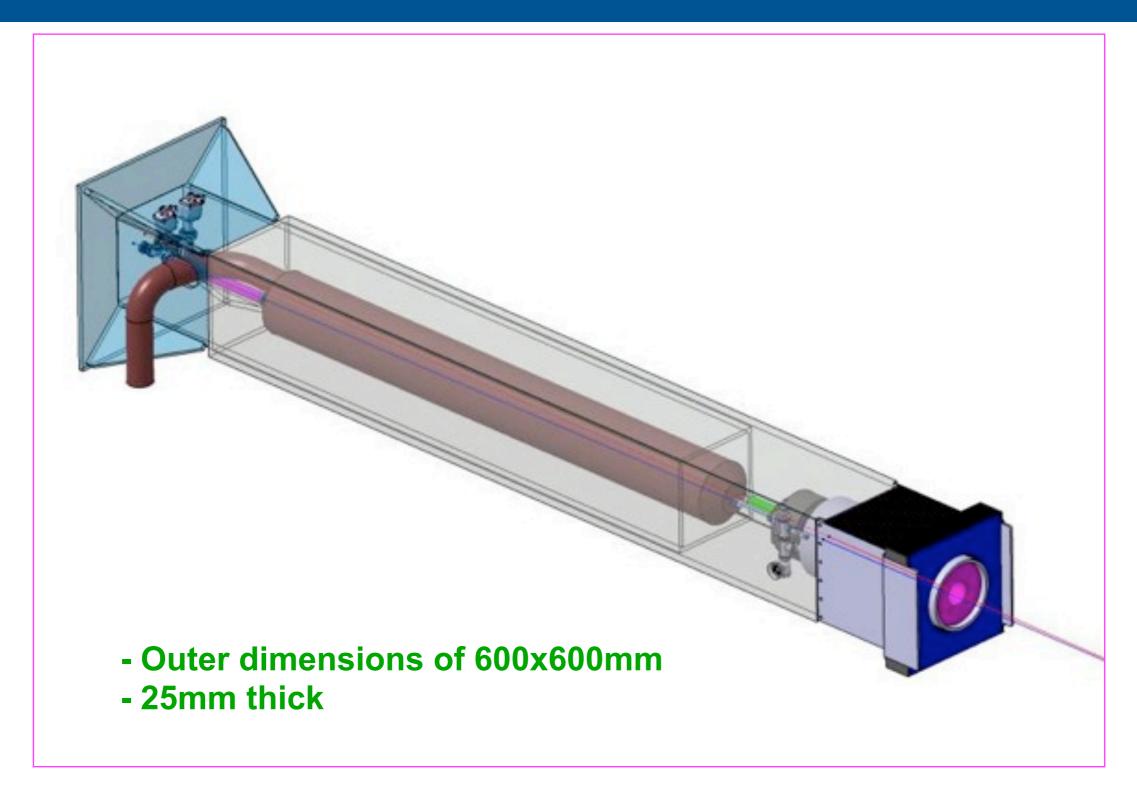
#### Magnetic Field on Steel Floor

CST EM STUDIO 09/08/2010 - 09:30



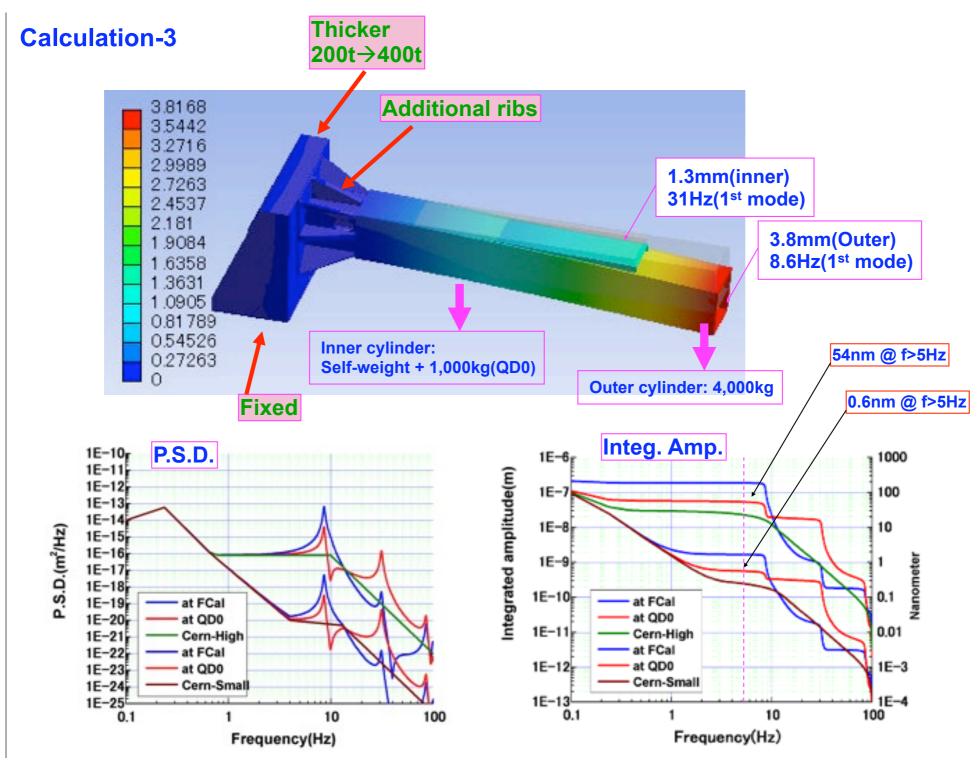
- Simulation with steel layer on platform
- Large induced magnetic fields! Might have consequence on reinforcements in concrete?

# QD0 Support



• M. Joré, H. Yamaoka

#### **QD0 Support Vibration Analysis**



- · H. Yamaoka
- Ok for quite site

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## Vibration Issues



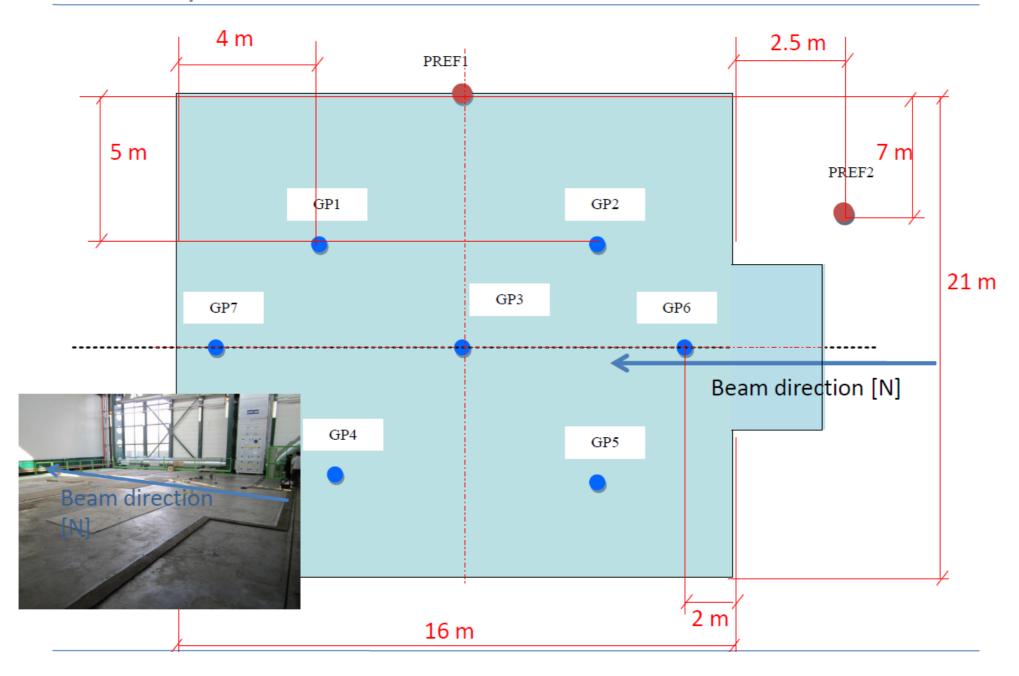
# CMS Plug finished





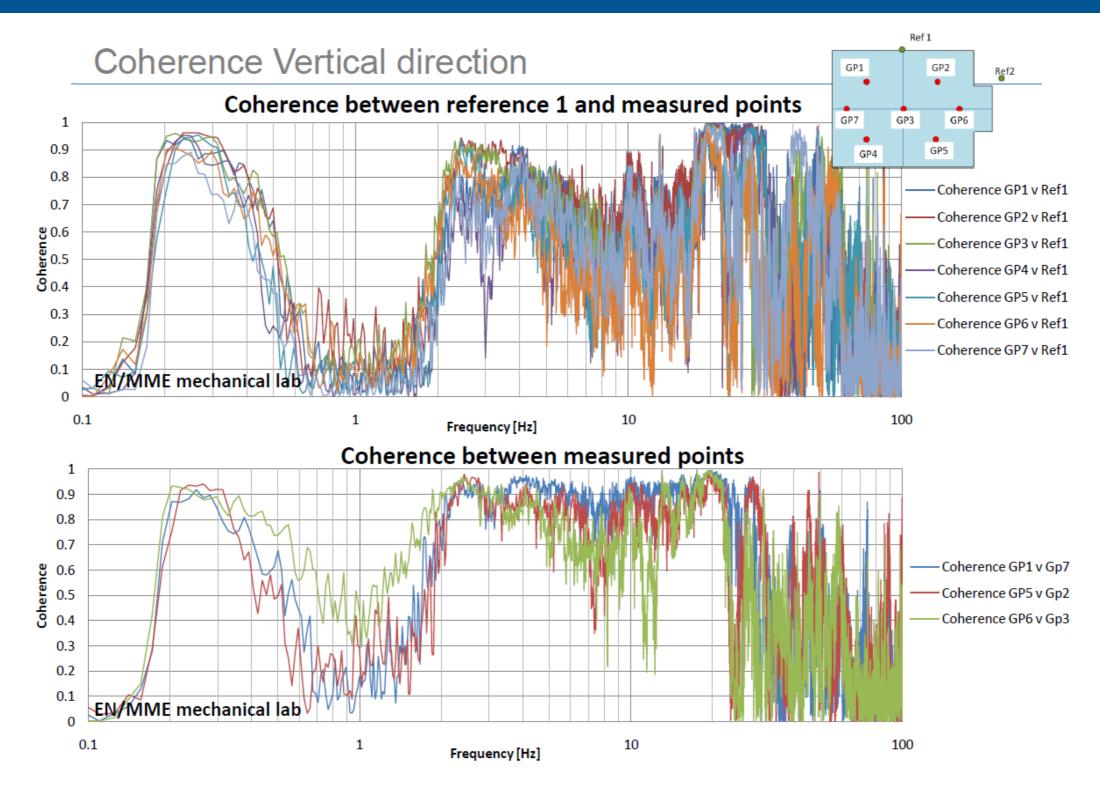
#### Platform Vibration Measurements and Modelling

#### Sensor position



• M. Oriunno

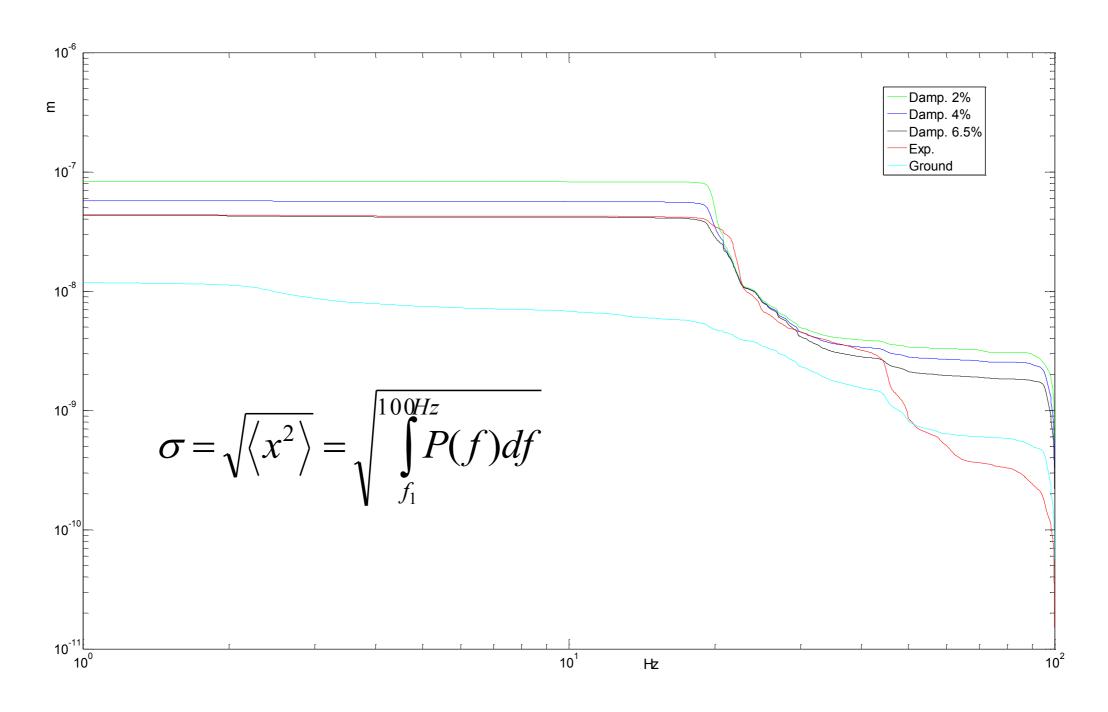
#### Platform Vibration Measurements and Modelling



#### M. Oriunno

#### Platform Vibration Measurements and Modelling

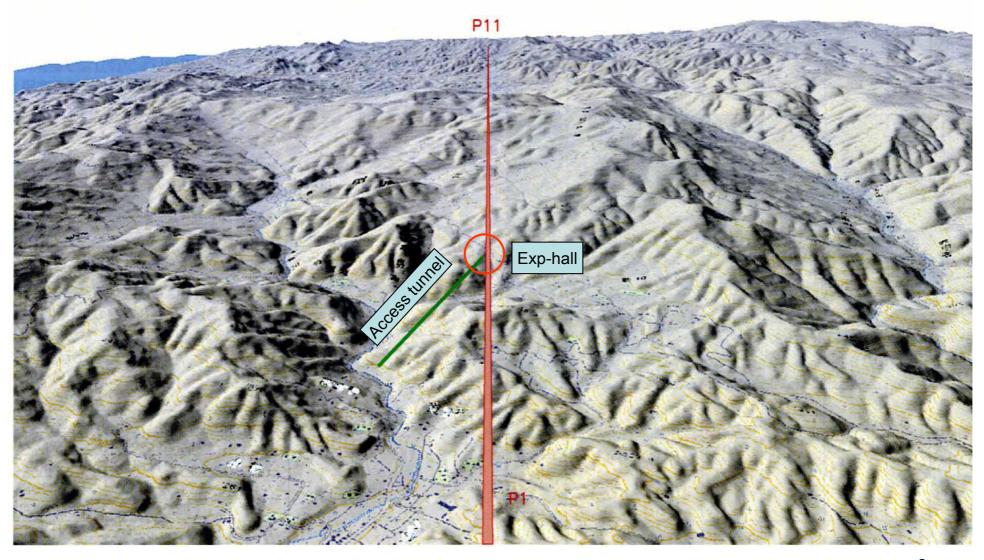
Integrated Displacement (r.m.s.)



Ground motion amplification of factor ~3

#### Alternative Detector Assembly Studies (Y. Sugimoto)

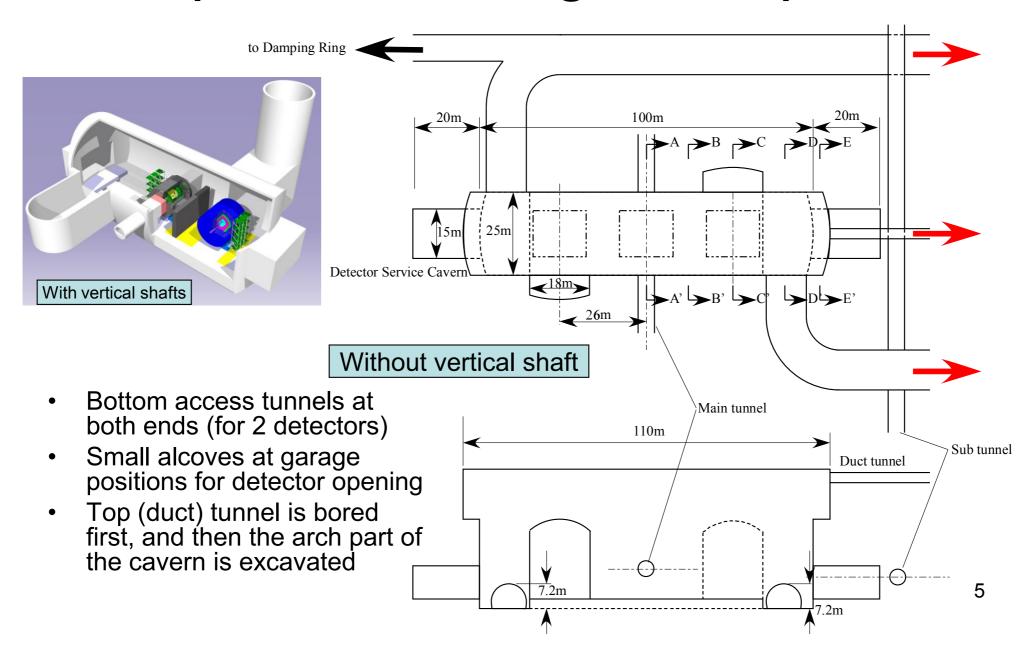
#### An example of Asian mountain site



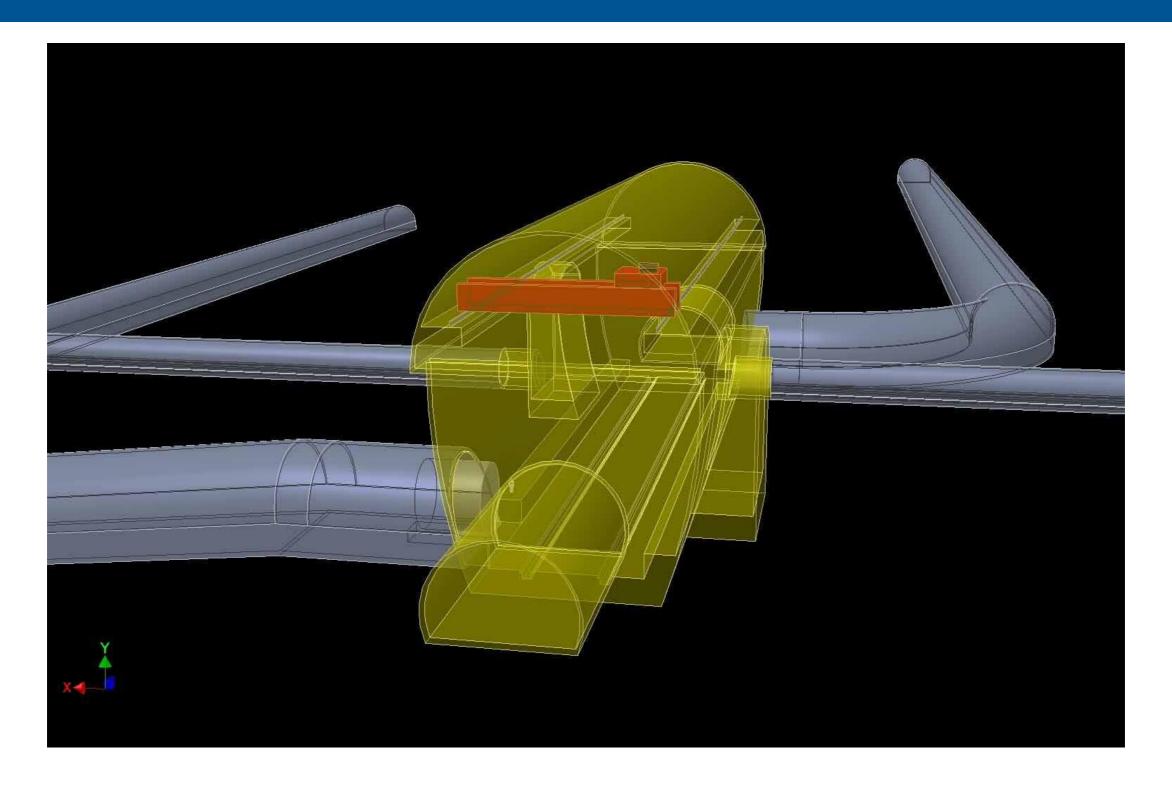
- ,
- ILC site could be quite different from "plain field" assumptions
- No vertical access shafts (~100m) but horizontal access tunnels (~1km)
- CMS-type assembly of detector needs to be reviewed

#### Alternative Detector Assembly Studies (Y. Sugimoto)

# A possible design of exp-hall



# Alternative Detector Assembly Studies (Y. Sugimoto)



## Who is doing what in ILD

- Hall design and push-pull system:
  - MDI group: ETH-Zürich, LAL, LLR, DESY, CERN, KEK
  - Collaboration with SiD, GDE-CFS, GDE-BDS and CLIC is natural
- Vibration studies:
  - System: ground platform detector FF magnets
  - Simulations at KEK, LAL and SiD
  - Measurements at CERN (CMS)
- Magnet and Yoke
  - Magnet: CEA, ETH-Zürich, CERN
  - Yoke: DESY
- Subdetector integration mostly done in the R&D collaborations:
  - CALICE, LC-TPC, SILC, FCAL, Vertex
  - Coordination of subdetector design and ILD integration model is not always easy
- Detector models
  - Detailed CAD model of ILD: LAL (M. Joré)
  - Integration model defining workspaces for subdetectors and supplies: DESY (R. Volkenborn)
  - EDMS integration: Work Breakdown Structure, Required Documents: LLR, DESY

#### Summary

- The list of tasks is long, the time to the DBD/RDR is short:
  - The underground hall design presented in the RDR is not optimal for ILD
    - Common design needed that fits ILC, SiD, ILD and is aligned with the push-pull paradigm
    - Common collaboration between ILD, SiD, ILC-BDS and ILC-CFS started
    - Site-specific modifications need to be taken into account
  - A platform based push-pull motion system seems feasible but needs detailed engineering work
    - Common collaboration between ILD, SiD, ILC-BDS and ILC-CFS started
  - Detector integration is ongoing
    - close collaboration with R&D collaborations
    - CAD/EDMS process is evolving
    - Need to define list of required supporting documents for the WBS
- All tasks are unfortunately resource-driven and not goal-driven
  - The content of the DBD will be defined by the work done, not by the work planned