

Vertex-Detector R&D for CLIC

LCWS 2012

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for the CLIC Physics and Detector study

Outline

- Vertex-detector requirements
- Background conditions
- Simulation layouts
- Readout-technology R&D
- Sensor-simulation studies
- Power delivery / power pulsing

More on CLIC vertex R&D in following talks:

- Massimiliano De Gaspari: Hybrid pixel readout chips
- Fernando Duarte Ramos: Mechanics & cooling

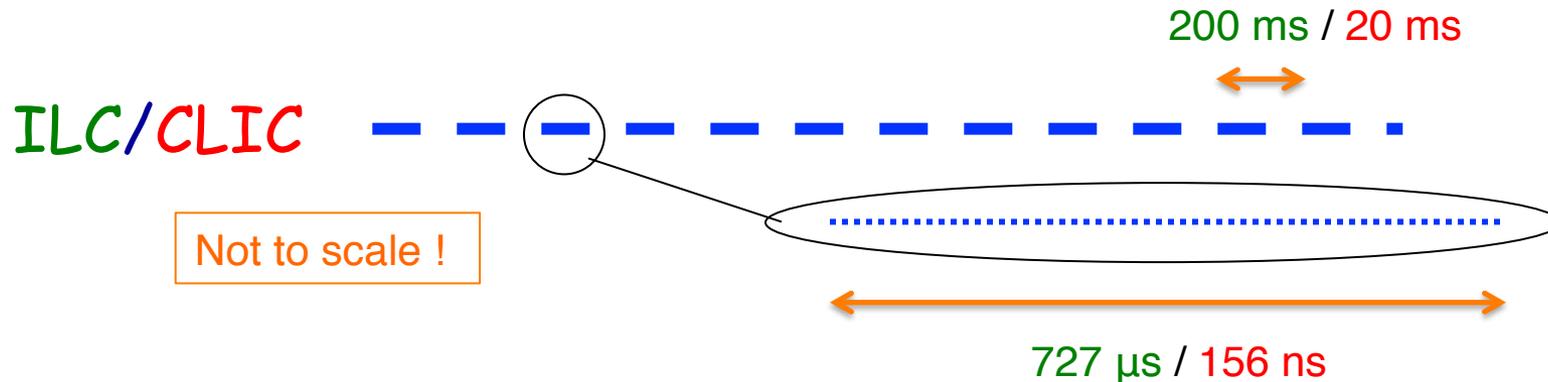
ILC and CLIC machine environment

	ILC at 500 GeV	CLIC at 3 TeV
L (cm ⁻² s ⁻¹)	2x10 ³⁴	6x10 ³⁴
BX separation	554 ns	0.5 ns
#BX / train	1312	312
Train duration	727 μs	156 ns
Train repetition rate	5 Hz	50 Hz
Duty cycle	0.36%	0.00078%
σ _x / σ _y (nm)	474 / 6	≈ 45 / 1
σ _z (μm)	300	44

drives timing requirements for detectors

very small beam sizes

ILC ESD-2012/2 / CLIC CDR



CLIC vertex-detector requirements

- Integral part of **tracking** systems (in particular for low p_T)
- Efficient **tagging of heavy quarks** through precise determination of displaced vertices:

$$\sigma(d_0) = \sqrt{a^2 + b^2 \cdot \text{GeV}^2 / (p^2 \sin^3 \theta)}$$

$$a \approx 5 \mu\text{m} \quad b \approx 15 \mu\text{m}$$

→ **Good single point resolution**: $\sigma_{\text{SP}} \sim 3 \mu\text{m}$

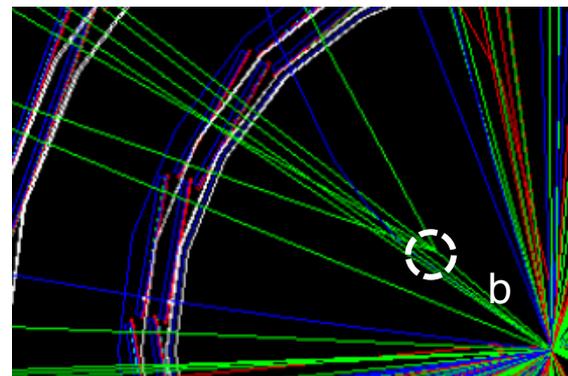
→ Small pixels $\sim 25 \times 25 \mu\text{m}$, analog readout

→ **Low material budget**: $X \lesssim 0.2\% X_0$ / layer

→ Corresponds to $\sim 200 \mu\text{m}$ Si, including supports, cables, cooling

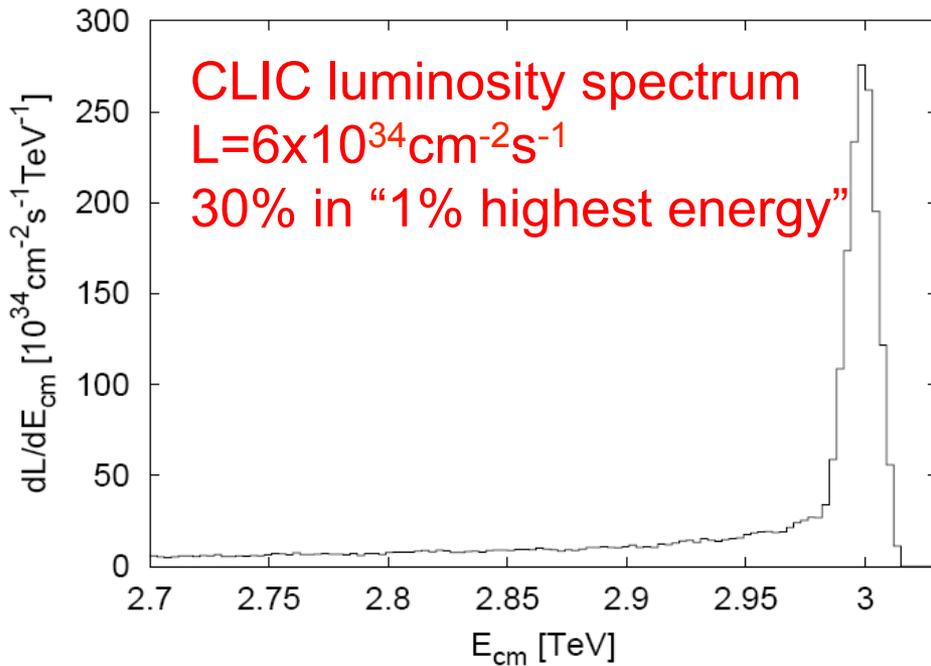
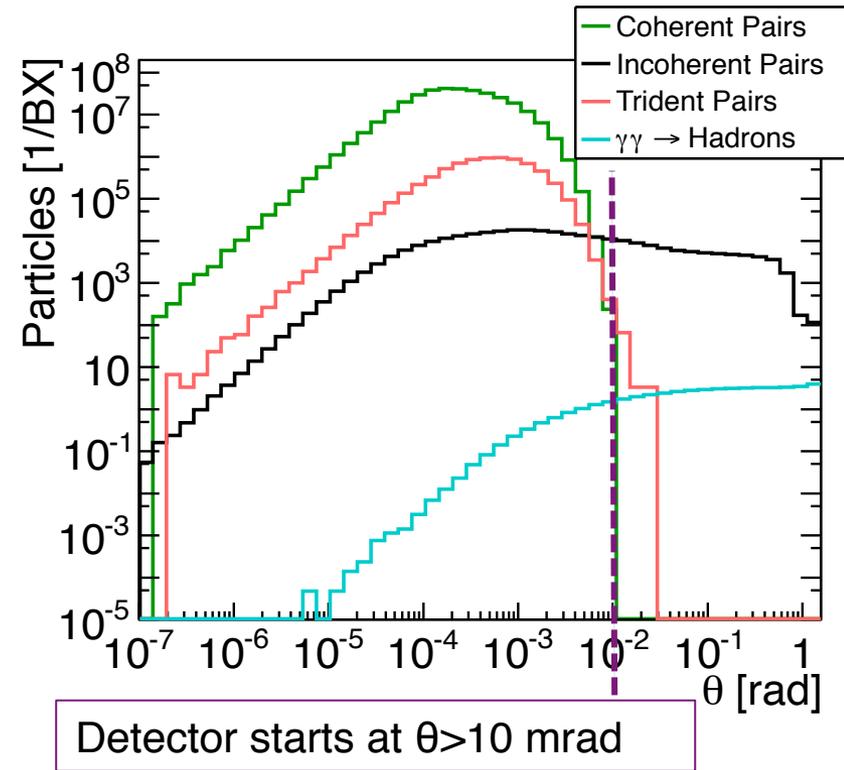
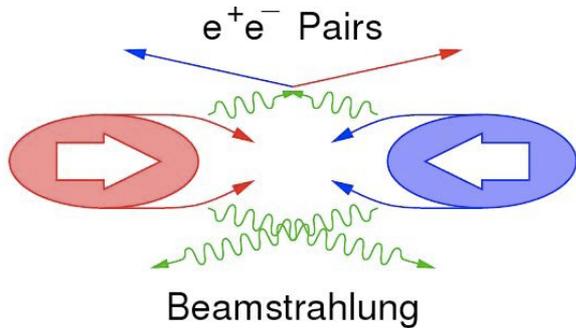
→ Low-power ASICs ($\sim 50 \text{ mW/cm}^2$) + air-flow cooling

- **156 ns** bunch trains, **20 ms** gaps → trigger-less readout, pulsed powering
- **Time stamping** with $\sim 10 \text{ ns}$ accuracy, to reject background (see following slides)
 - high-resistivity sensors, fast readout
- $B = 4\text{-}5 \text{ T}$ → Lorentz angle becomes important
- **Full coverage** down to low polar angles $\theta_{\text{min}} \sim 7^\circ$ → Barrel + EC geometry
- To date: no technology option available fulfilling all requirements
 - **Simulation studies**: impact of layout on performance
 - **R&D on sensors & readout**
 - **Integration/Assembly + power-pulsing + cooling studies**



Beam-induced backgrounds

e^+e^- pairs and $\gamma\gamma \rightarrow \text{hadrons}$ at $\sqrt{s}=3$ TeV



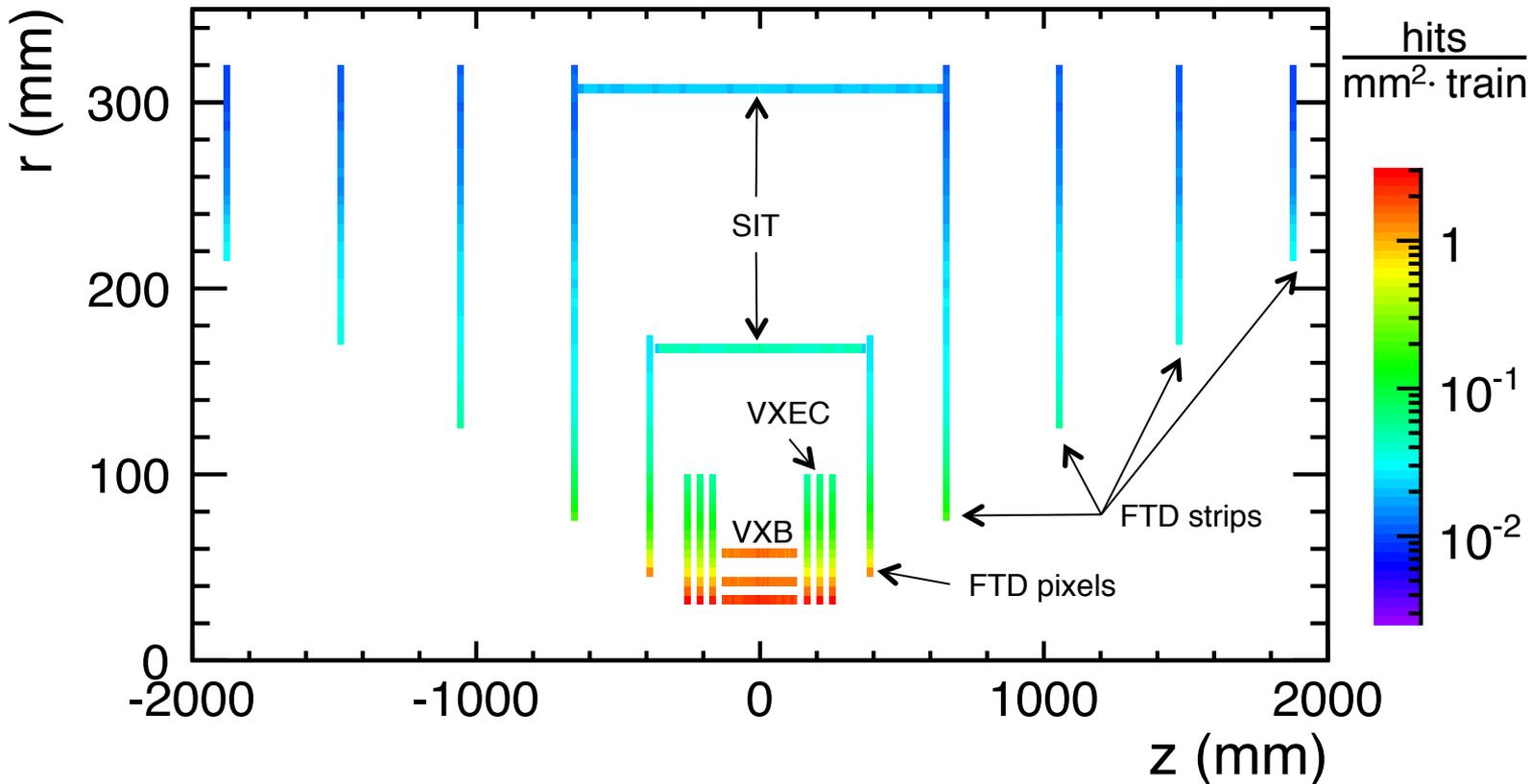
Main backgrounds in inner detectors:

- **Incoherent e^+e^- pairs**: 60 particles / BX
- **$\gamma\gamma \rightarrow \text{hadrons}$** : 54 particles / BX

→ Need **pile-up rejection**

Backgrounds in inner tracking region

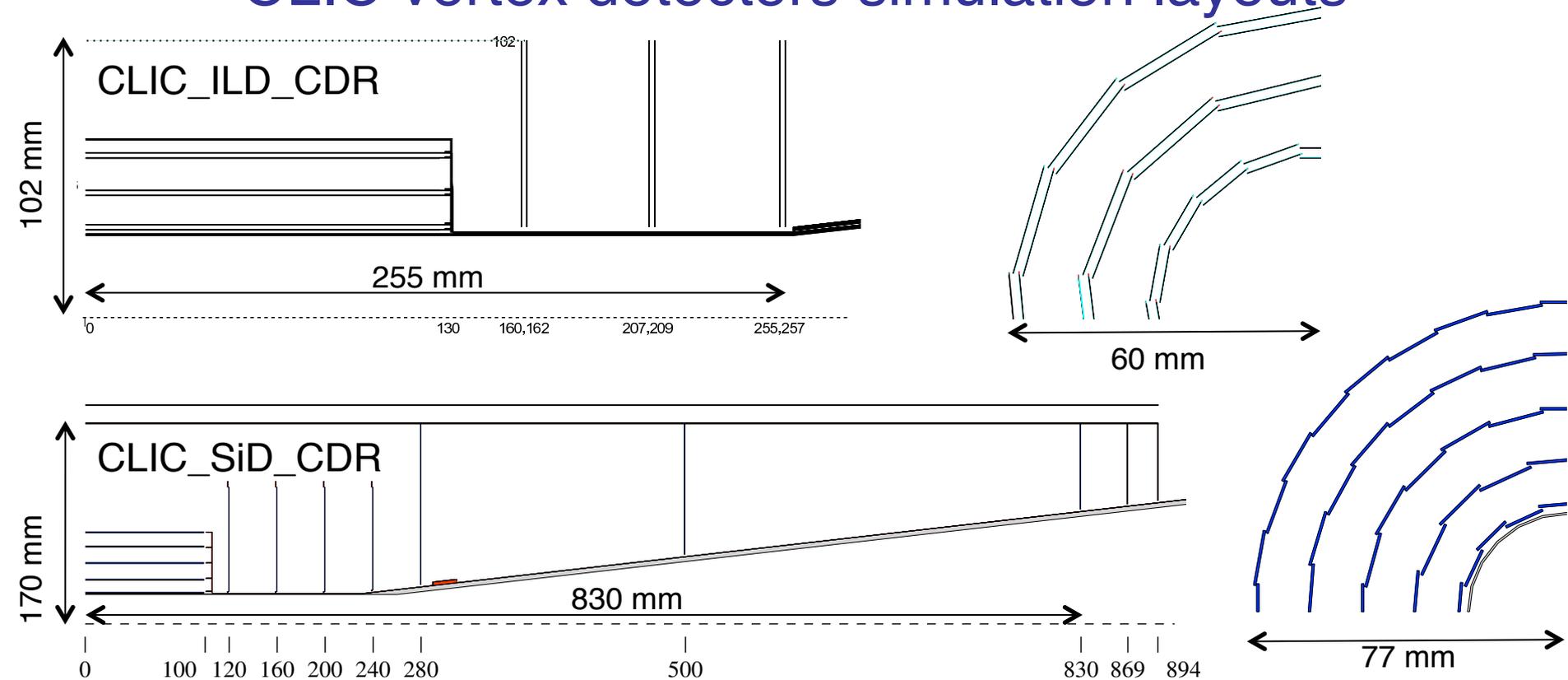
CLIC_ILD incoherent pairs + $\gamma\gamma \rightarrow$ hadrons: silicon hits, no safety factors



- Large hit rates in vertex and forward regions:
 - 2-3% maximum pixel occupancy / train (incl. clustering + safety factors)
 - Constrains inner radius of beam pipe
 - Drives design of forward region

- Moderate radiation exposure:
 - NIEL: $< 10^{11} n_{eq}/cm^2/y$
 - TID: < 200 Gy / year ($\sim 10^4$ below LHC!)

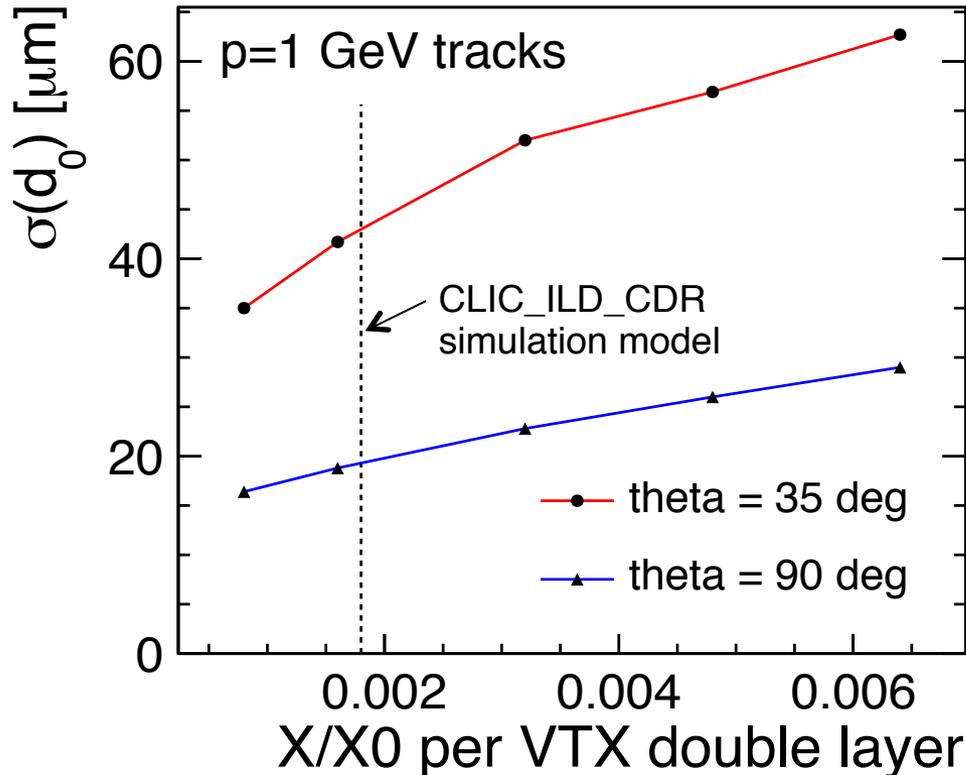
CLIC vertex detectors simulation layouts



	CLIC_ILD_CDR	CLIC_SiD_CDR	CMS
Material X/X0 (90°)	~0.9% (3x2 layer)	~1.1% (5 layer)	~10% (3 layer)
Pixel size	20 x 20 μm^2	20 x 20 μm^2	100 x 150 μm^2
# pixels	2.03 G	2.76 G	66 M
Time slicing resolution	~10 ns	~10 ns	<~25 ns
Avg. power/pixel	<~0.2 μW	<~0.2 μW	28 μW

Vertex-detector performance

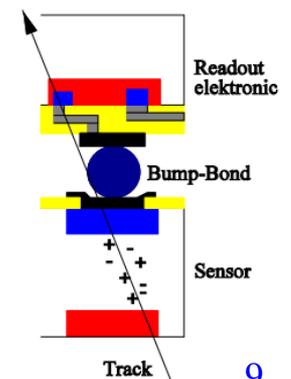
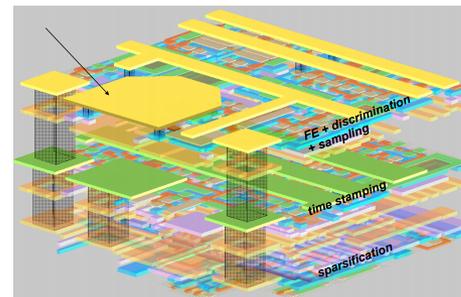
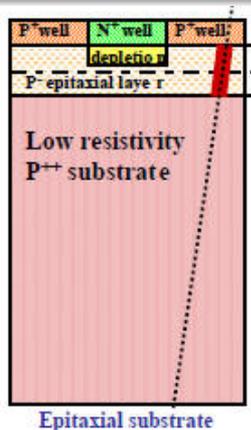
- d_0 : distance of closest approach to interaction point in R-phi plane
→ d_0 resolution closely linked to heavy-flavor tagging performance
→ main benchmark parameter for vertex detector performance



- Simulation models reach required performance
 - Sensitivity to changes in design parameters:
 - **Material budget**
 - Single-point resolution
 - Distance to IP
- Parametric studies

Pixel-detector technologies

	Monolithic CMOS	3D-integrated	Hybrid pixel
Examples	DEPFET, FPCCD, MAPS, HV-CMOS	SOI, MIT-LL, Tezzaron, Ziptronix	Timepix3/CLICpix
Technology	Specialised HEP processes, r/o and sensors integrated	Customized niche industry processes, high density interconnects btw. tiers	Industry standard processes for readout; depleted high-res. planar or 3D sensors
Interconnect	Not needed	SLID, Micro bump bonding, Cu pillars	
granularity	down to 5 μm pixel size		$\sim 25 \mu\text{m}$ pixel size
Material budget	$\sim 50 \mu\text{m}$ total thickness achievable		$\sim 50 \mu\text{m}$ sensor + $\sim 50 \mu\text{m}$ r/o
Depletion layer	partial	partial or full	full \rightarrow large+fast signals
timing	Coarse (integrating sensor)	Coarse or fast, depending on implementation	Fast sparsified readout, $\sim \text{ns}$ time slicing possible
R&D examples	ILC, ALICE, RHIC	ILC, HL-LHC	CLIC, ATLAS-IBL, HL-LHC



Medipix/Timepix hybrid r/o chip family

Chip	Year	Process	Pitch [μm^2]	Pixel operation modes	r/o mode	Main applications
Timepix	2006	250 nm IBM CMOS	55x55	\int TOT or ToA or γ counting	Sequential (full frame)	HEP (TPC)
Medipix3RX	2012	130 nm IBM CMOS	55x55	γ counting	Sequential (full frame)	Medical
Timepix3	2013	130 nm IBM CMOS	55x55	TOT + ToA, γ counting + \int TOT	Data driven	Medical, HEP
Smallpix	2013	130 nm IBM CMOS	\sim 40x40	TOT + ToA, γ counting + \int TOT	Sequential (data comp.)	Medical, HEP, XFEL
CLICpix demonstrator	2013	65 nm TSMC	25x25	TOT + ToA	Sequential (data comp.)	Test chip with 64x64 pixel matrix
CLICpix	\sim 2015	65 nm	25x25	TOT + ToA	Sequential (data comp.)	CLIC vertex detector

TOT: Time-Over-Threshold

→ Energy

ToA: Time-of-Arrival

→ Time stamping

- Taking advantage of smaller feature sizes:
 - Improved noise performance
 - Increased functionality and/or
 - Reduced pixel size
- Details in following talk by Massimiliano De Gaspari

Sensor simulation and digitization

Unprecedented combination of sensor+readout features:

- **Thin sensors** ($\sim 50 \mu\text{m}$)
- **small pitch** (20-25 μm)
- **fast shaping** ($< \sim 50 \text{ ns}$)

→ Need to investigate:

- Charge rise time, collection efficiency, sharing between pixels, signal/noise
- Dependence on momentum, angle, E- and B-field
- Validation in test beam

Simulation frameworks for pixel detectors:

- **Detailed TCAD simulation of thin pixel sensors:**

Slow analytical approach, useful for tuning of simpler models

- **Monte-Carlo Charge Transport coupled to Static TCAD simulation:**

\sim fast, can be coupled to GEANT4, comparison with test-beam data

- **Geant4 simulation + Digitization model (Mokka / SLIC):**

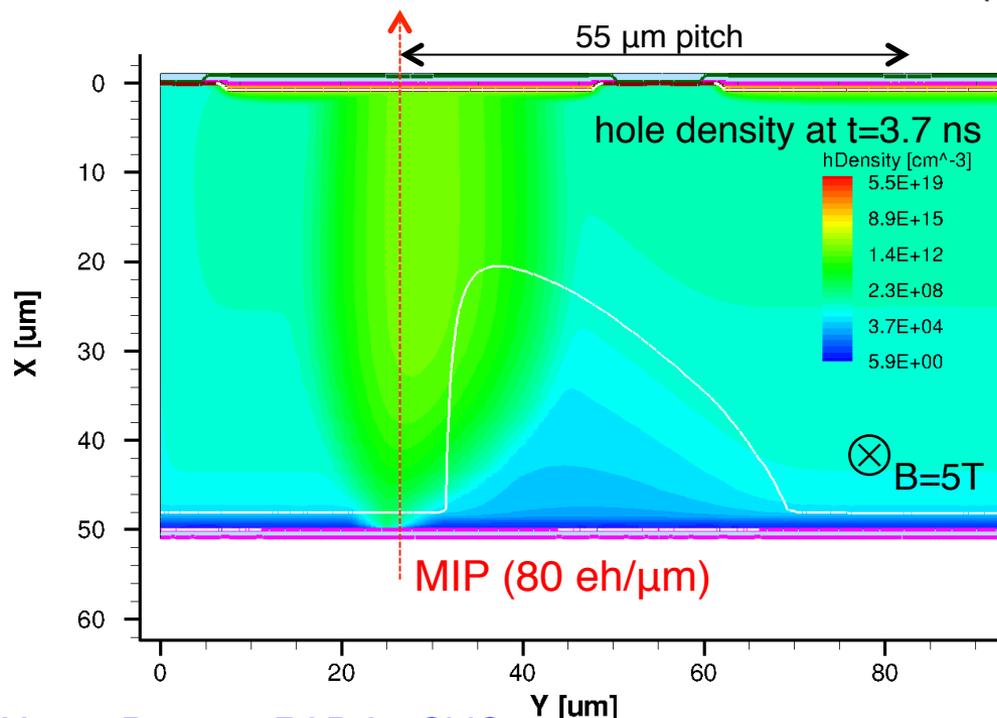
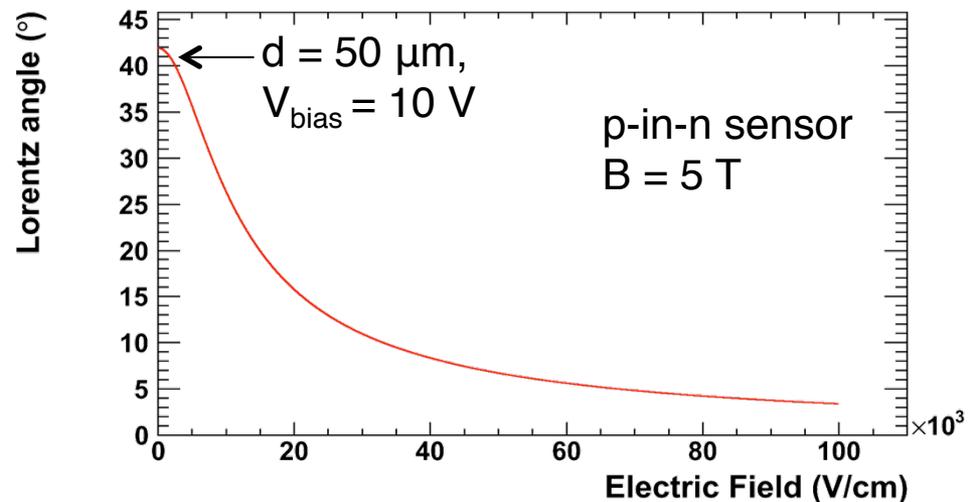
Fast, used for physics studies, needs calibration for sensor + r/o

Silicon device simulation with TCAD

Example:
Hybrid detector with Timepix readout

p-in-n sensor (10 kΩcm)
50 μm thickness → $V_{dep} \sim 1$ V
55 μm readout pitch
 $V_{bias} = 10$ V → $E \sim 2000$ V/cm
Magnetic field: 5 T
→ $\theta_L \sim 40^\circ$

- Spread of charge cloud due to Lorentz-angle effect
- Effect more pronounced for e^-
- Can be partially compensated by rotation of sensors with Lorentz angle
- Over-depletion reduces effect



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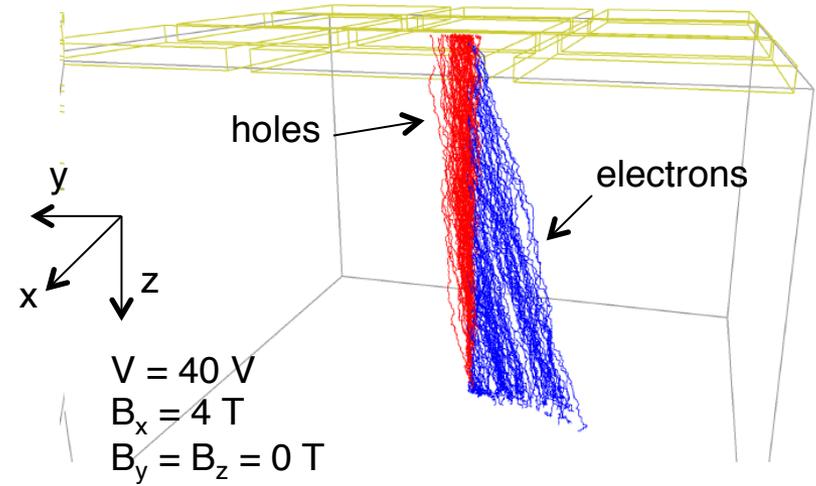
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Vertex-Detector R&D for CLIC

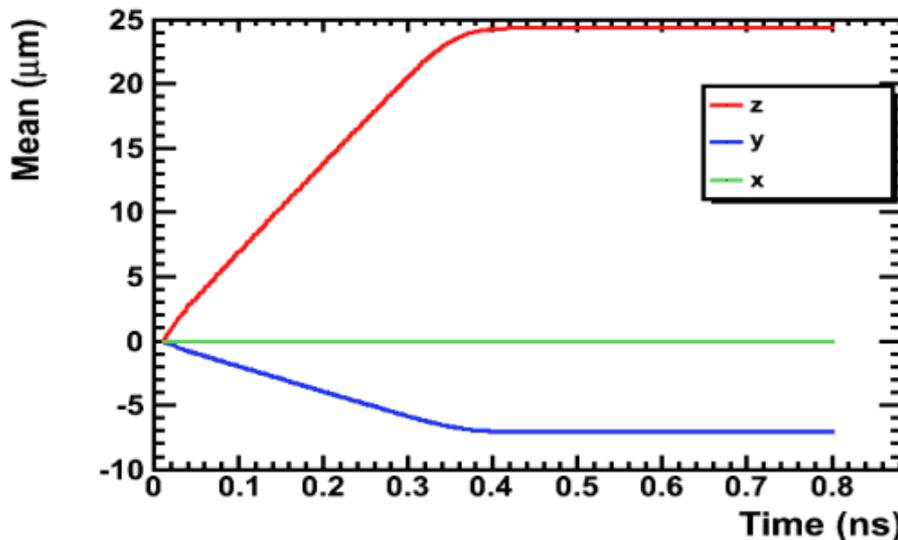
Monte-Carlo simulation of Charge Transport

- Simulate carrier drift in E+B field
- E-field from TCAD (previous slide)
- Takes into account diffusion, mobility, trapping, repulsion
- Validation and simulation tuning in CERN SPS test-beam campaign (Timepix-based hybrid planar pixel sensor)
- Results will be implemented in Geant4-based full-detector simulation frameworks

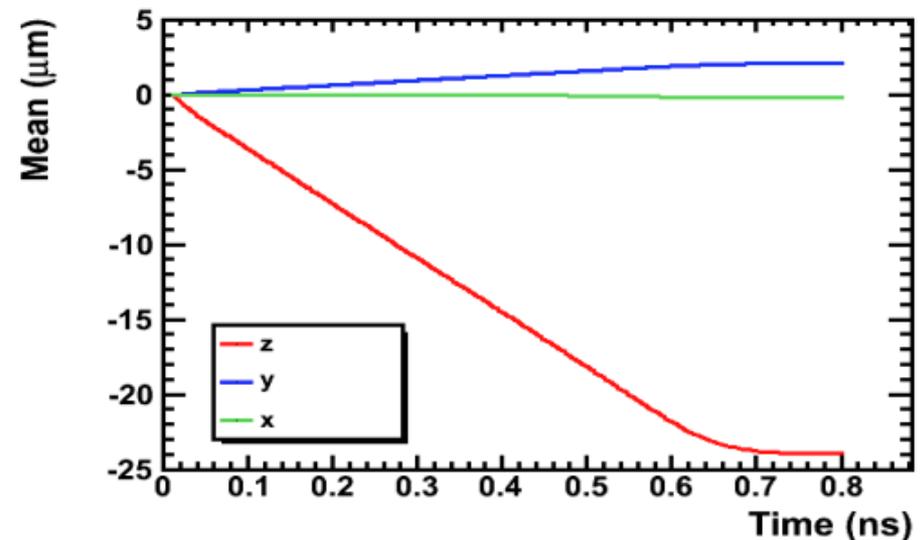
Carrier drift in 50 μm thick fully depleted sensor:



Electrons



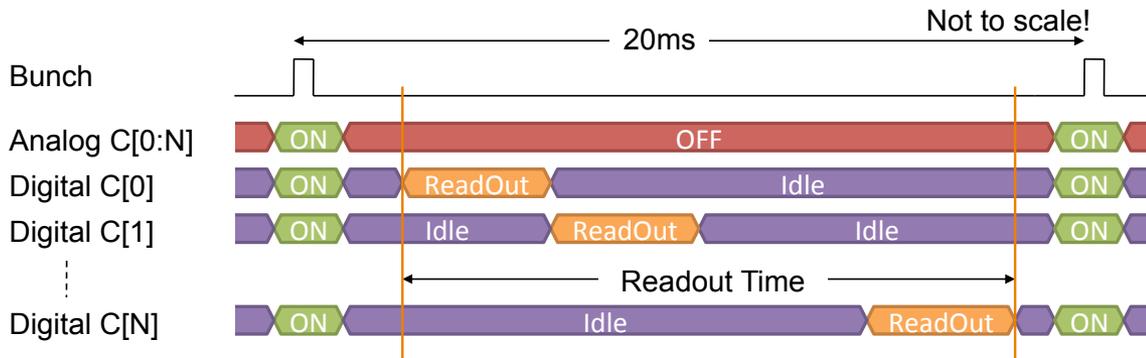
Holes



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CLICPix power-pulsing requirements

- Overall power budget (driven by air-flow cooling): $P_{avg} \sim 50 \text{ mW} / \text{cm}^2$
- Estimation of power consumption for analog and digital blocks of CLICPix readout chip
- Based on measurements with **65 nm test-chip** and projections from current Timepix
- **Power pulsing** with On/Idle/Off states, to reduce average power
- **Very small duty cycle** for analog power
→ Favors **local energy storage**



Bunch Train (3.0 W/cm²)

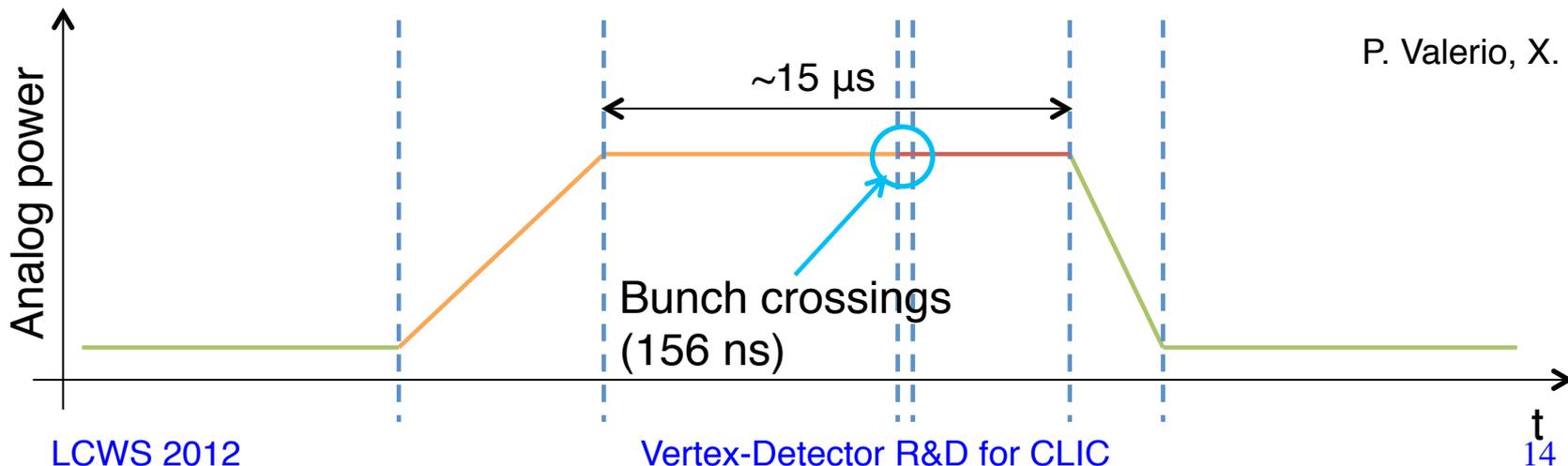
Pixel Analog	ON
Pixel Digital	ON
Periphery Analog	ON
Periphery Digital	ON
IO LVDS Pads	OFF

Chip Readout (360 mW/cm²)

Pixel Analog	OFF
Pixel Digital	ON
Periphery Analog	OFF
Periphery Digital	ON
IO LVDS Pads	ON

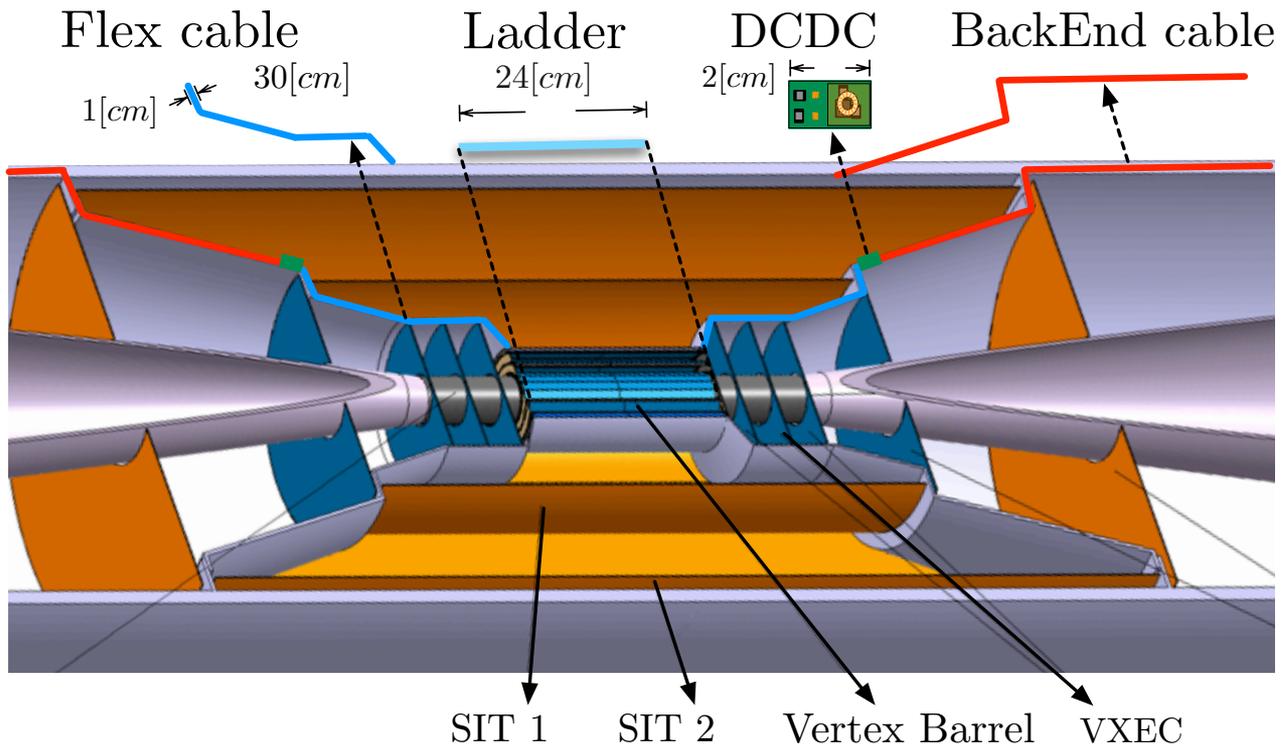
Idle (7.8 mW/cm²)

Pixel Analog	OFF
Pixel Digital	Idle
Periphery Analog	OFF
Periphery Digital	ON
IO LVDS Pads	OFF

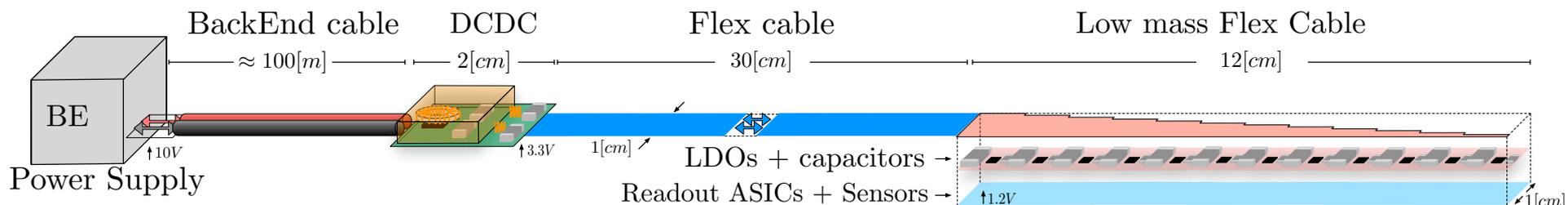


P. Valerio, X. Llopart

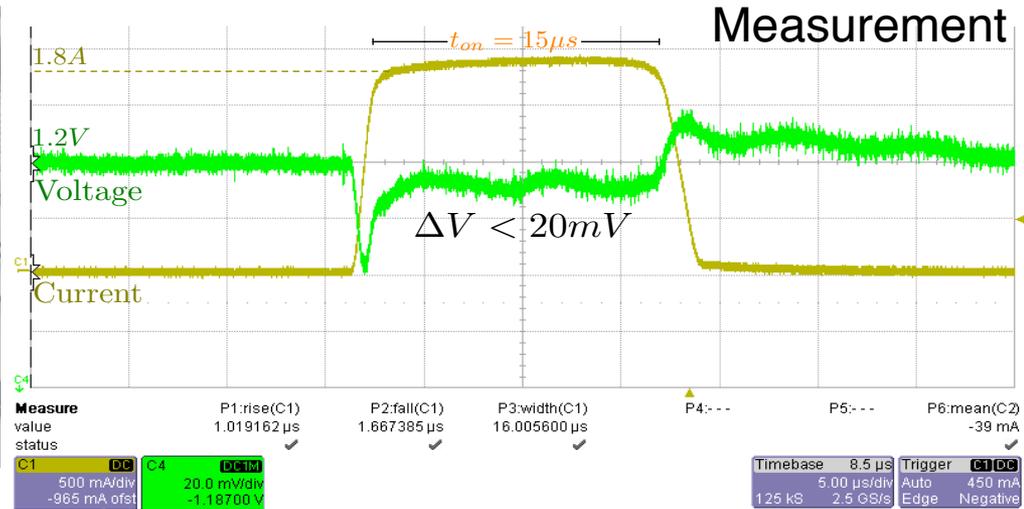
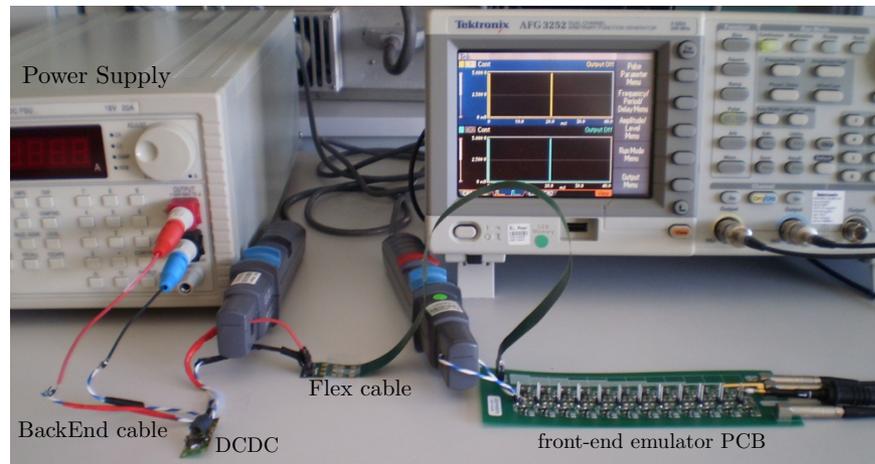
Power-pulsing and power-delivery scheme



- DC/DC converters outside pixel-sensor area
- Flexible Kapton cables with Al conductor for power delivery
- Power pulsing, to reduce average power consumption
- local energy storage and voltage regulation with Si capacitors ($\sim 10 \mu\text{F}/\text{chip}$) and LDO regulators

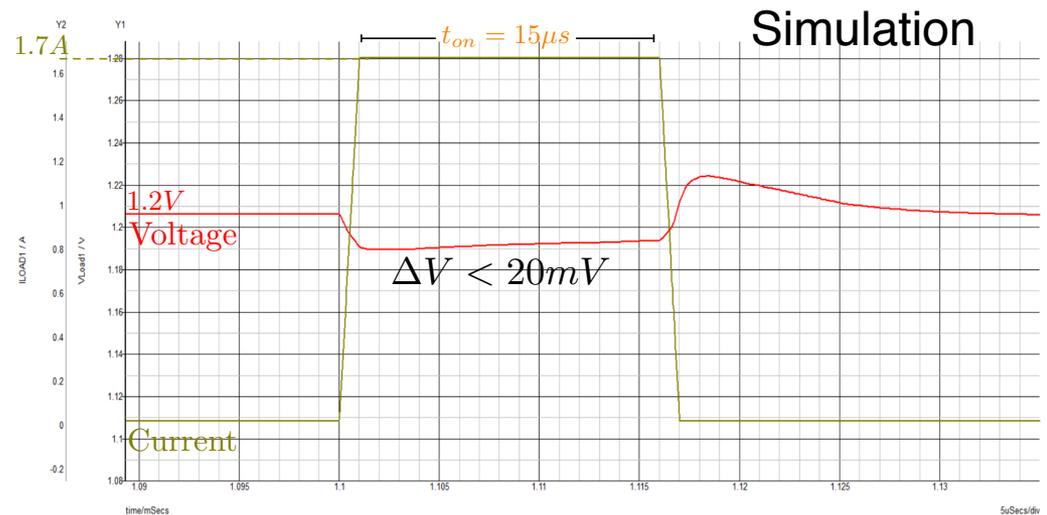


Power-pulsing and power-delivery tests



Test setup with active loads emulating analog pixel F/E:

- Equivalent thickness cable+LDO+cap.: **0.145% X0 / layer** in vtx region
- Power pulsing at **50 Hz**
- Load current of **2 A** (half ladder) during **15 μs**
- Monitor load voltages and currents
- Observed ripple **$\Delta V < 20 mV$** , acceptable for CLICPix
- Agreement between measurement and simulation



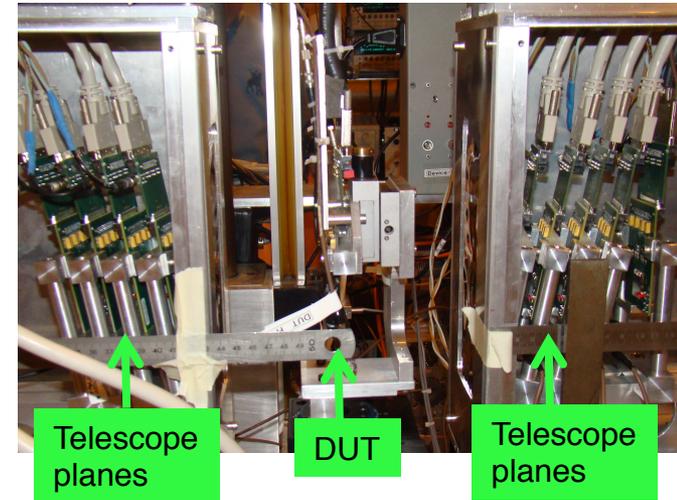
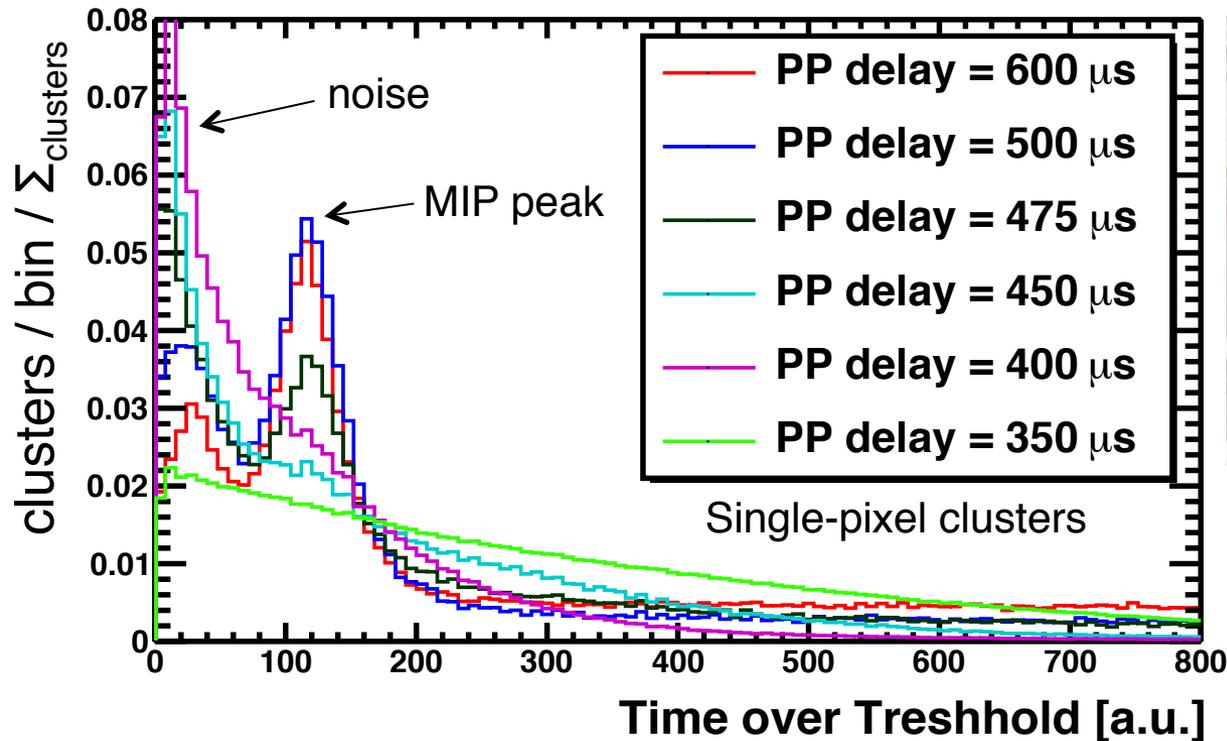
Power-pulsing in test beam

Power Pulsing with Timepix:

- Not designed for power pulsing, single bias line for all pixel rows
- But possibility to switch on/off all preamps through bias DAC

CERN SPS test-beam campaign in June 2012:

- Power pulsing of the Chip and operation in sync with LHCb/Timepix tracking telescope
- Shutter-based readout for 25 μs
- Adjustable delay between power-on and shutter-start times



- Fully efficient after $\sim 600 \mu\text{s}$
- Similar results obtained with [source](#) in laboratory and in [simulation](#)

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Summary / conclusions

- CLIC environment + physics requirements pose challenging demands on vertex-detector systems
- Presented initial layout proposals meeting those demands
- Examples for active R&D on:
 - Sensor + readout technologies
 - Silicon simulations
 - Power-delivery and power pulsing
- More details in CLIC vertex-detector working group presentations:
<http://indico.cern.ch/categoryDisplay.py?categId=2843> and in CDR:
<http://lcd.web.cern.ch/LCD/CDR/CDR.html>

Backup slides

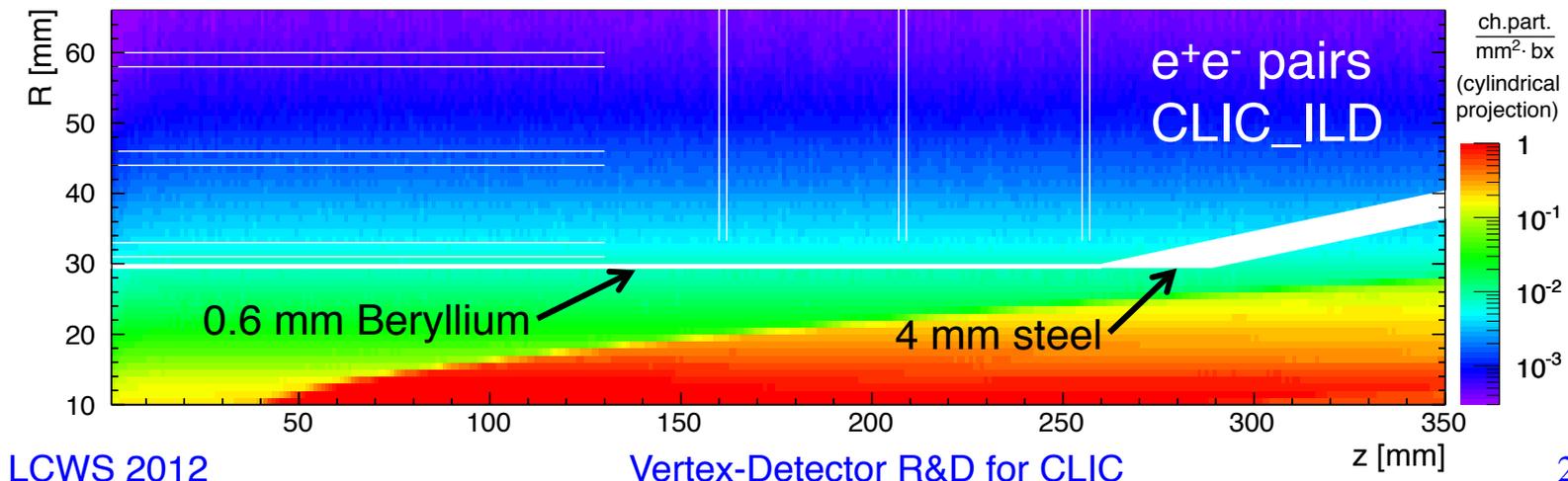
Beam pipe

Requirements for beam pipe:

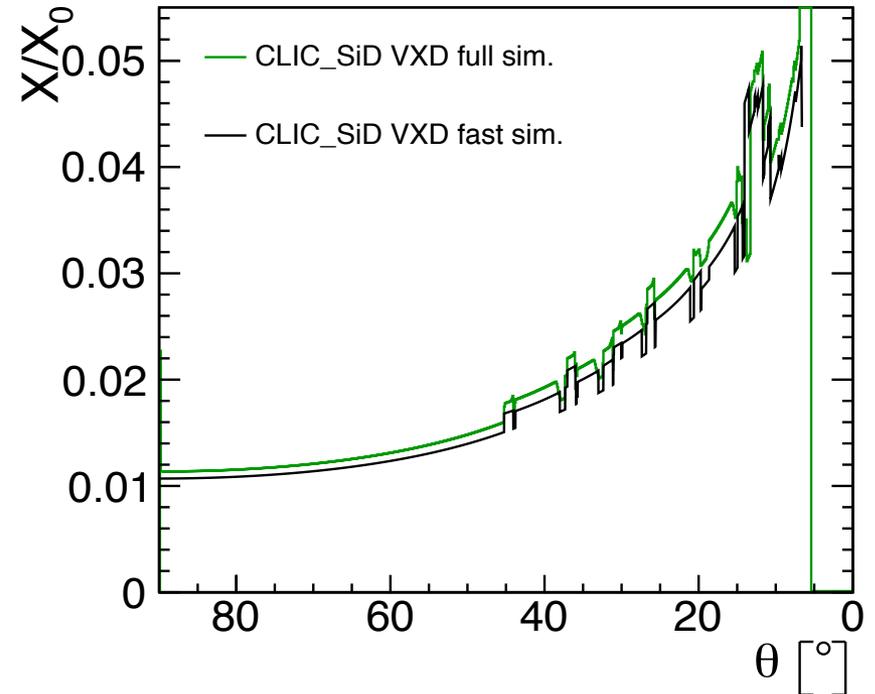
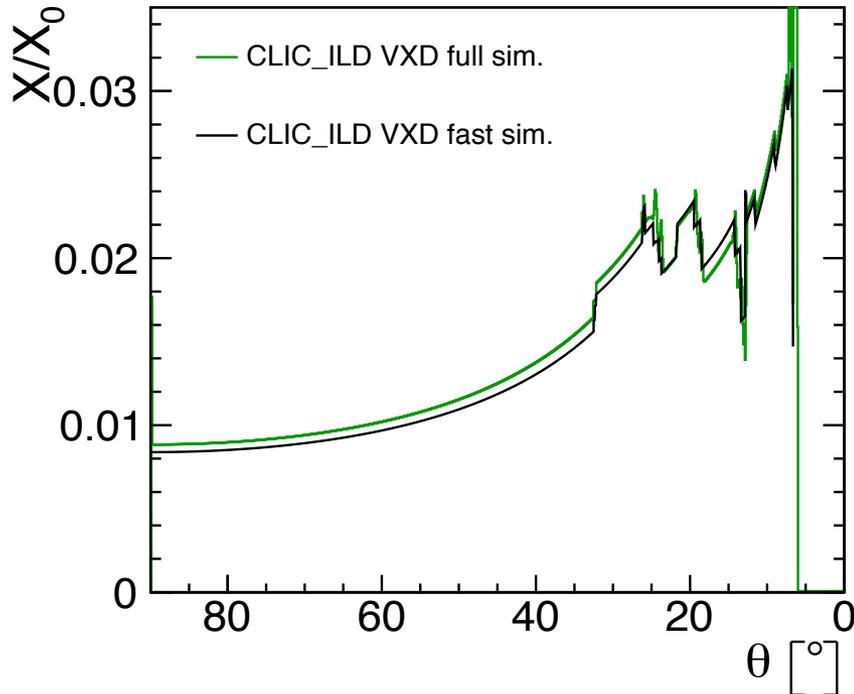
- Provide good vacuum \rightarrow leak tightness
- Minimise multiple scattering \rightarrow small amount of material in central part
- Allow for placement of Si layers close to IP \rightarrow small radius
- Stay outside region of high background occupancy \rightarrow lower limit on radius
- Shield against back scatters from forward region \rightarrow thick conical part outside VTX acceptance

Implementation in simulations:

- Central Beryllium part:
 - CLIC_ILD: $d=0.6$ mm, $R=29.4$ mm ($B=4$ T)
 - CLIC_SiD: $d=0.5$ mm, $R=24.5$ mm ($B=5$ T)
 - Safe w.r.t. backgrounds, vacuum collapse, leak tightness (D0, CDF experience in run II)
 - Unlike ILC: no extra shielding, due to low expected levels of incoh. synchrotron radiation (t.b.c.)
- Forward conical part:
 - 4 mm iron, to shield against back scatters from forward region
 - Pointing to interaction point \rightarrow no extra material inside tracking acceptance

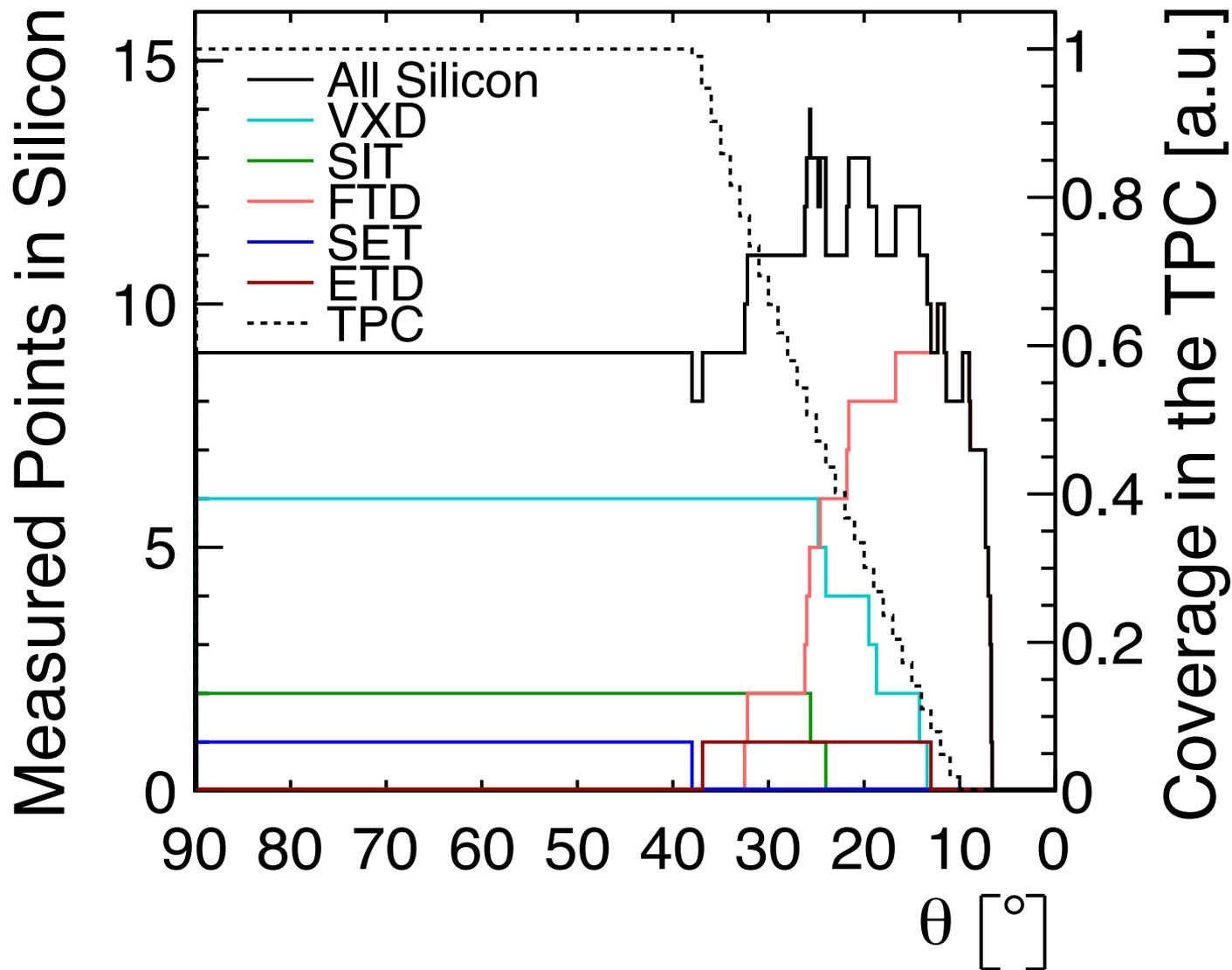


Material budget vertex region



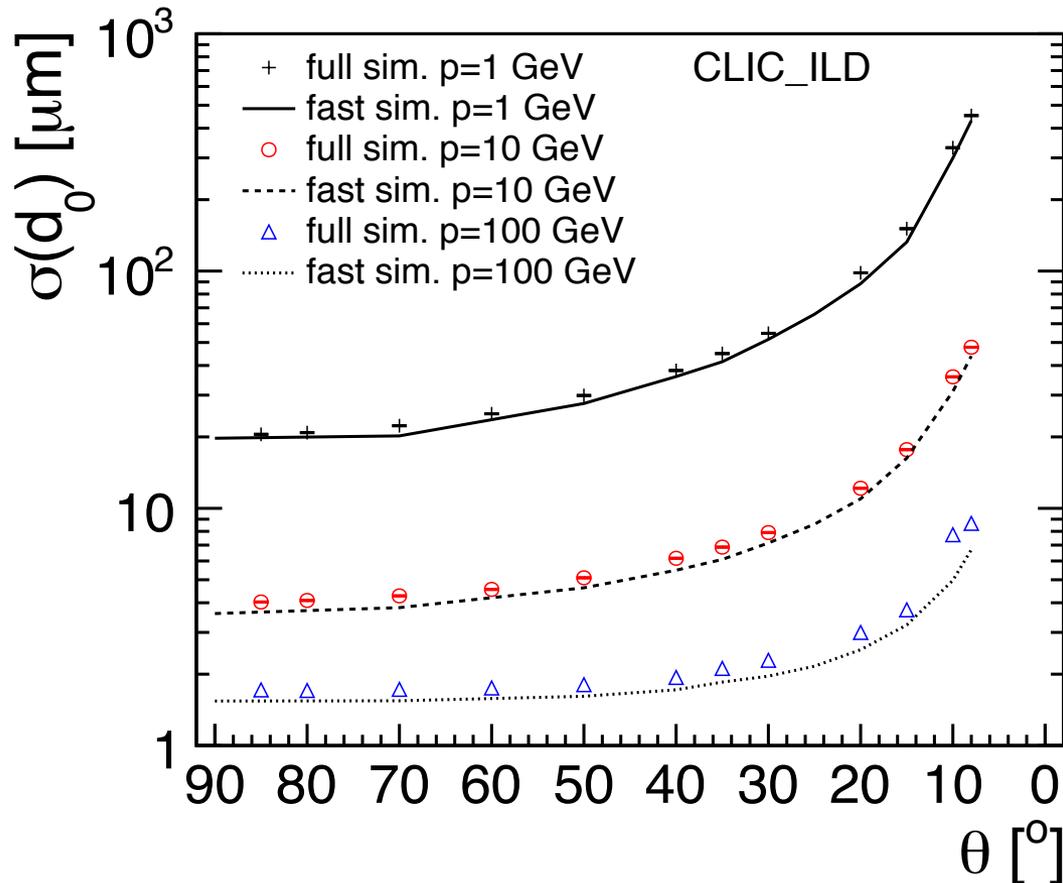
- Integrated amount of material seen by particles originating from the IP:
 $X/X_0 \sim 1\%$ (at $\theta=90^\circ$, averaged over ϕ)
- Good agreement full / fast simulation
(fast simulation has only ideal cylinders and disks, no module overlaps)

Angular coverage CLIC_ILD tracking



Vertex-detector performance

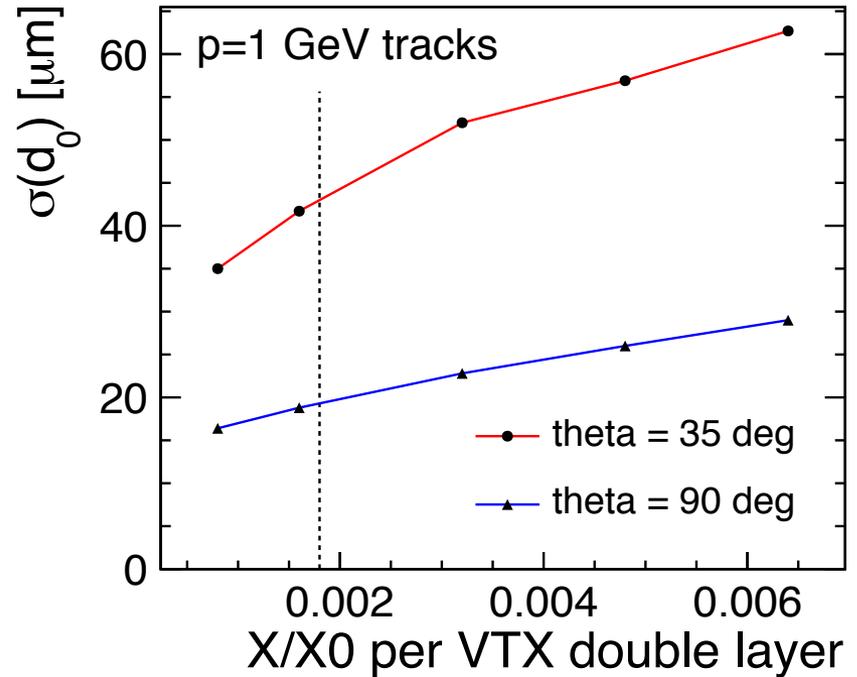
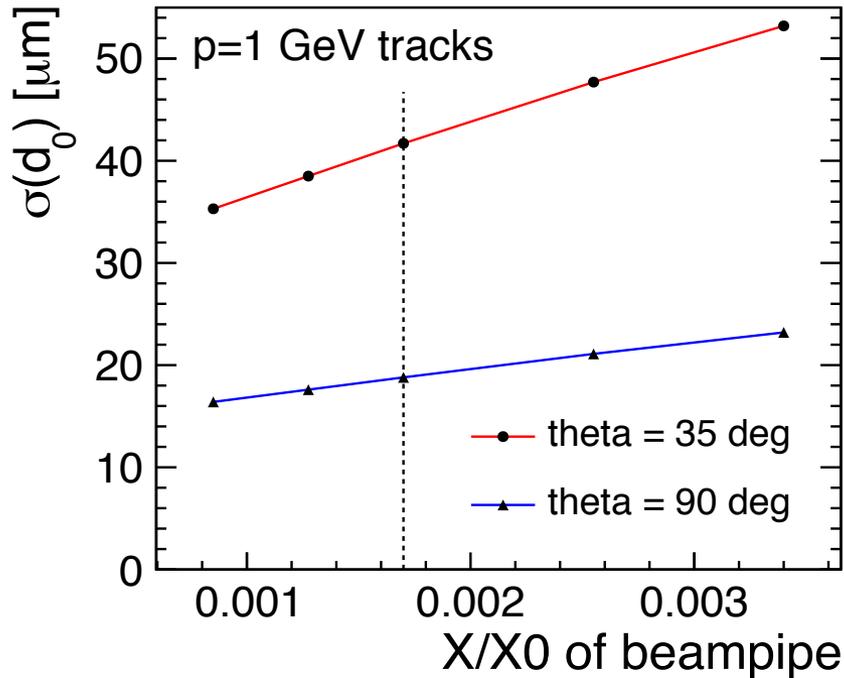
- d_0 : distance of closest approach to interaction point in R-phi plane
→ d_0 resolution closely linked to heavy-flavor tagging performance
→ main benchmark parameter for vertex detector performance



- Simulation models reach required performance
- Sensitivity to changes in design parameters:
 - Single-point resolution
 - Distance to IP
 - Material budget

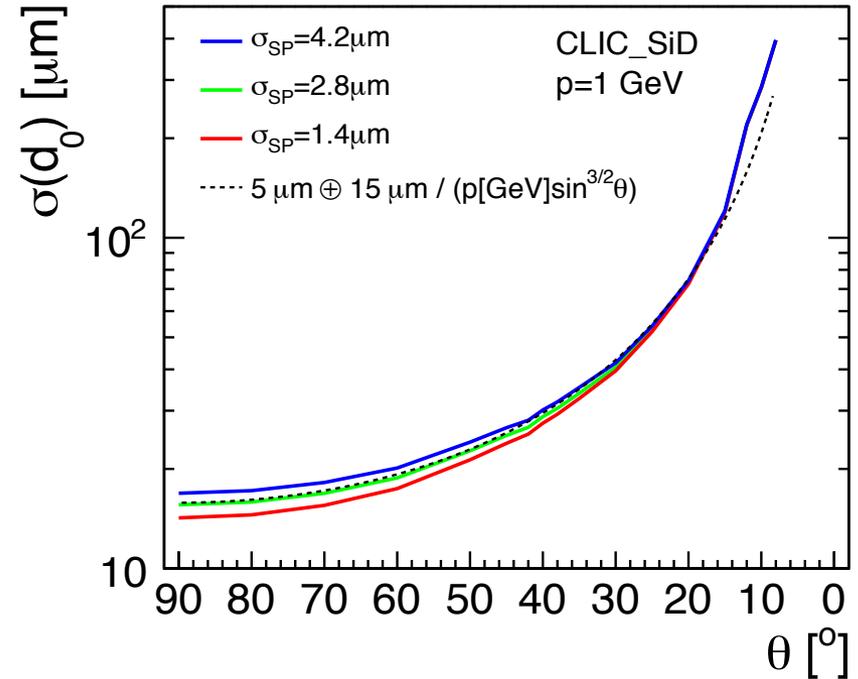
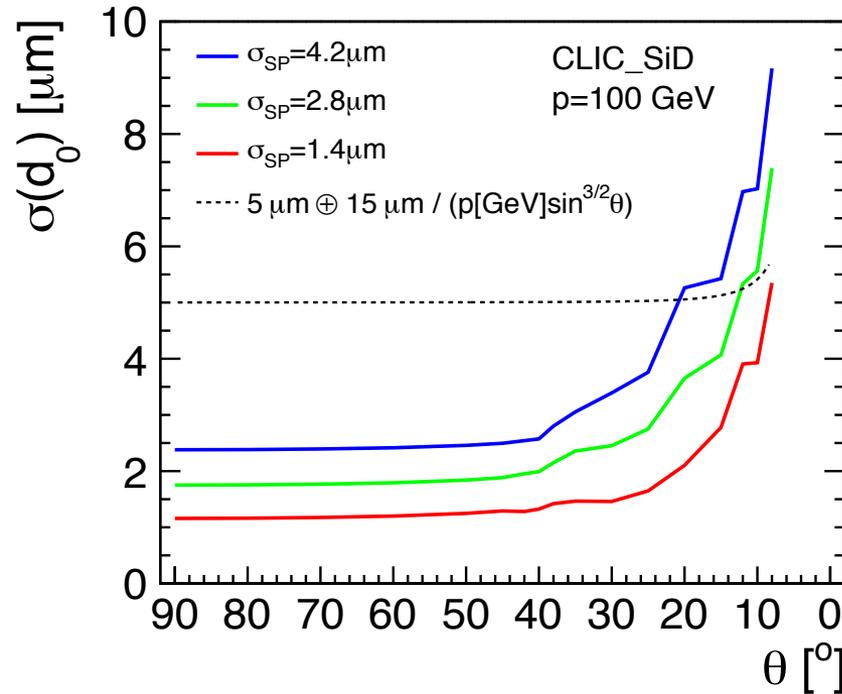
→ Parametric studies

Dependence on material



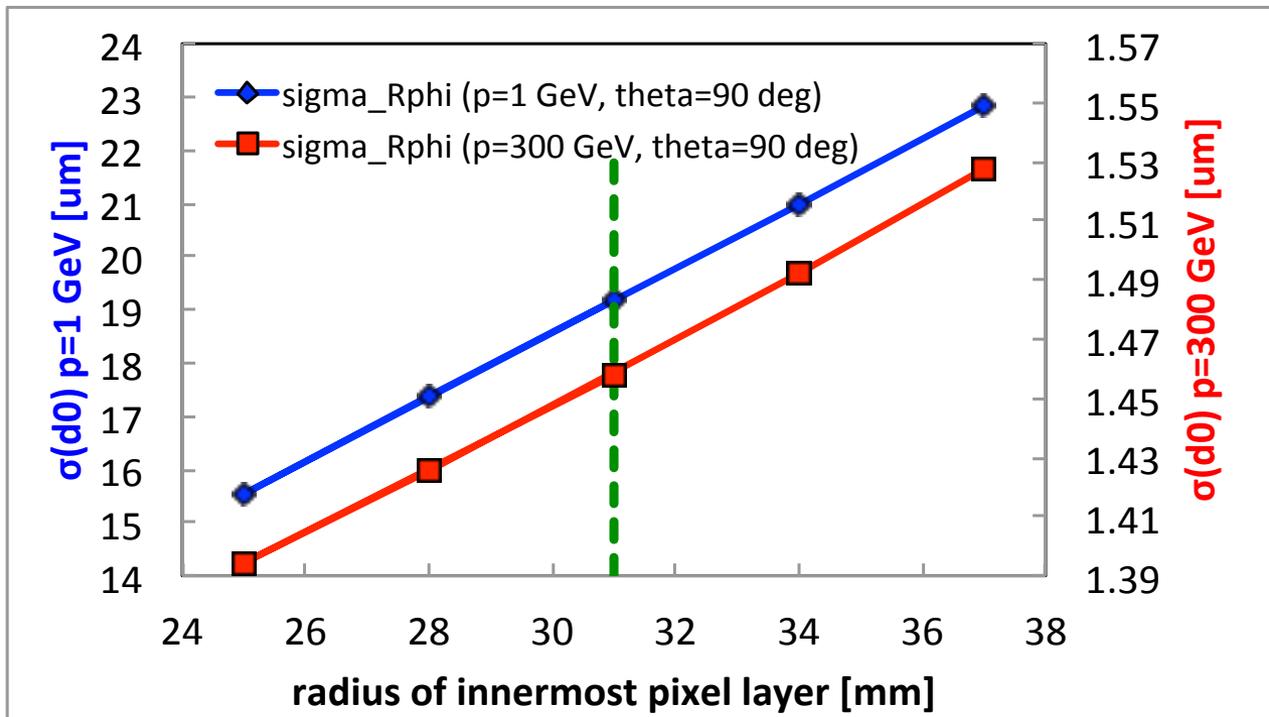
- Studied sensitivity of d_0 resolution for low momenta on material in beampipe and silicon pixel layers of CLIC_ILD
- Doubling beam-pipe thickness \rightarrow $\sim 20\%$ worse resolution at 90°
- Doubling material in silicon layers \rightarrow $\sim 20\%$ worse resolution at 90°
- Steeper slope in forward region

Dependence on single-point resolution



- Varied **single-point resolution** by $\pm 50\%$ (\sim pixel sizes 10×10 , 20×20 , $30\times 30\ \mu\text{m}^2$)
- Observed change in d_0 -resolution:
 - $\pm 40\%$ for $p = 100\ \text{GeV}$
 - $\pm 15\%$ for $p = 1\ \text{GeV}$
- Resolution close to or better than target values for all cases
- Pixel size is also constrained by:
 - Expected background occupancy
 - Ability to separate adjacent tracks in dense jets

Dependence on distance to IP



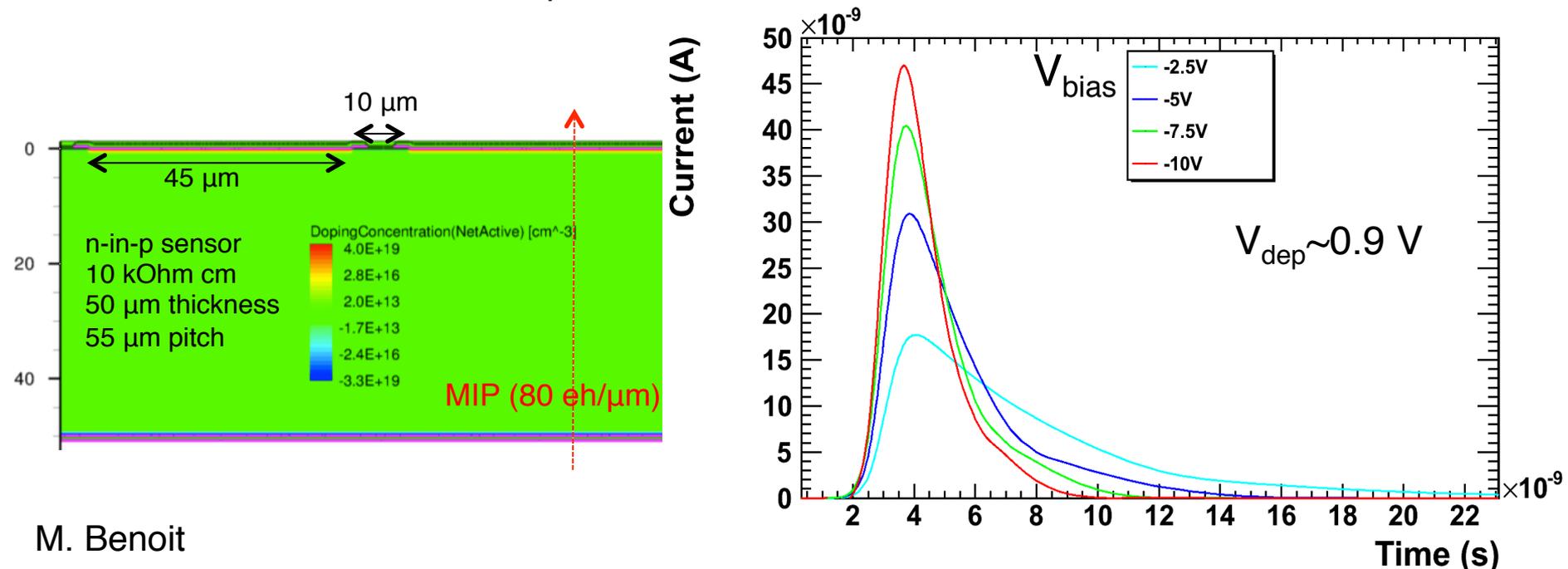
- Varied **distance to interaction point**, by changing radii of beam pipe and barrel vertex layers in CLIC_ILD model
- Observed change in d_0 -resolution:
 - 3.2% / mm for high momenta (parameter 'a')
 - 0.8% / mm for low momenta (parameter 'b')
- Distance to interaction point is constrained by direct hits from incoherent pairs

Signal rise time

- Need time-stamping precision of ~ 10 ns, to suppress beam-induced backgrounds
- Peaking time in sensor should be $\ll 10$ ns, to optimize S/N and reduce effect of time walk
- electron collection faster than holes → favors n-in-p sensors

Example:

- $55 \times 55 \mu\text{m}^2$ pixels
- $50 \mu\text{m}$ thinned n-in-p sensor, $\rho = 10 \text{ k}\Omega\text{cm}$
- ~ 2 ns peaking time with weak dependence on V_{bias}
- For higher V_{bias} better S/N expected after shaping, due to higher peak value; also less time walk due to reduced dispersion



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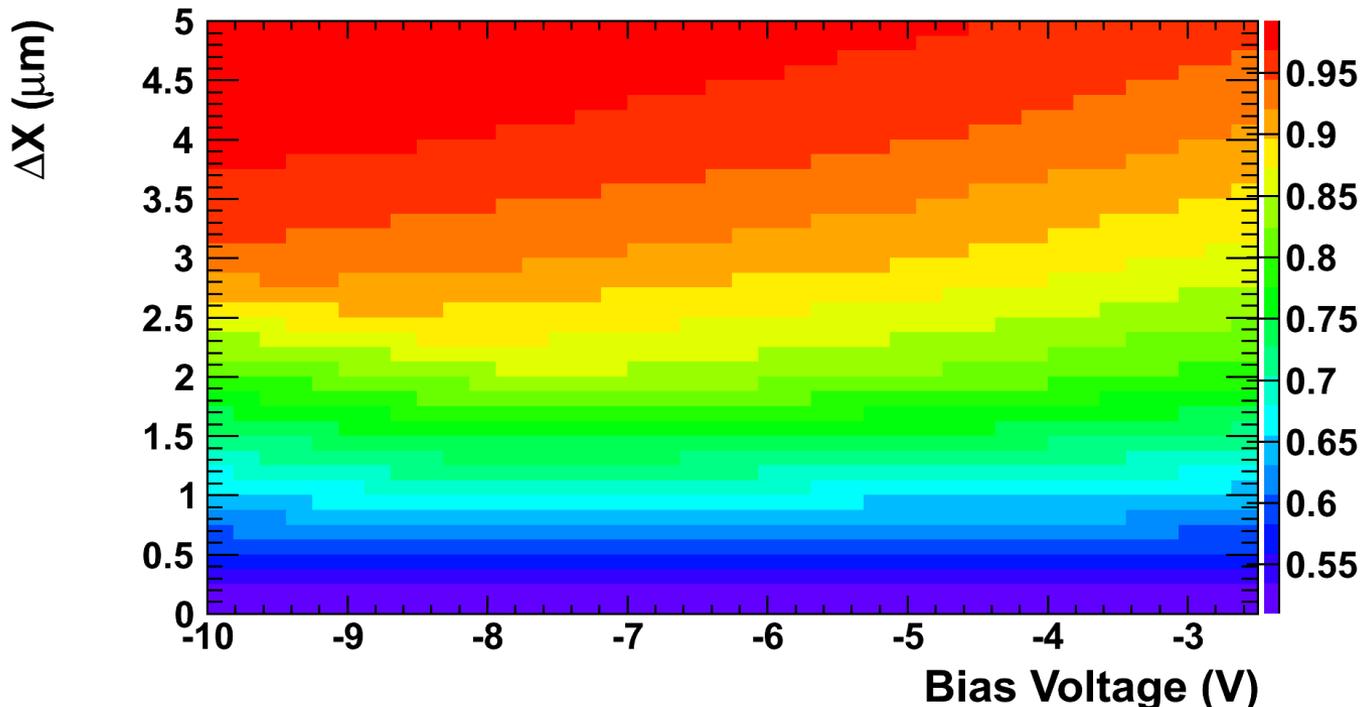
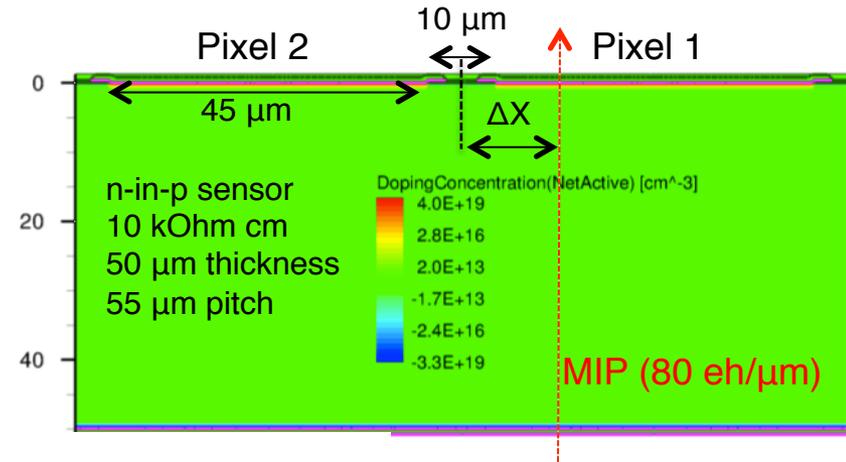
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Charge sharing

- Charge spread in sensor leads to sharing of charge between neighboring pixels
- Over-depletion increases E-field, thereby reduces charge spread and charge sharing
- Charge sharing can improve resolution through interpolation (with analog readout)
- However: signals below threshold are lost

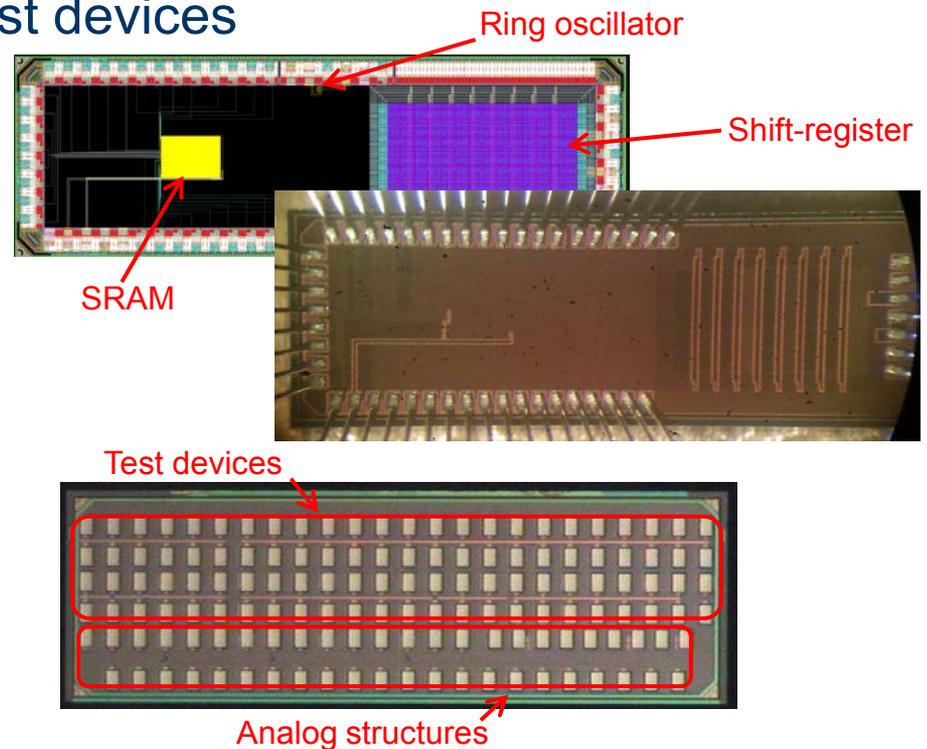


Hybrid approach: R&D examples

- Thinned high-resistivity fully depleted sensors
 - Several producers for $\sim 50 \mu\text{m}$ thick silicon sensors (e.g. IZM, Micron, CNM, VTT)
 - Handling + flip-chip bonding is a concern, in particular for larger structures
- Fast, low-power readout ASICs in Very-Deep-Sub-Micron (VDSM) technology
 - Timepix3 2013: 130 nm IBM CMOS, $55 \mu\text{m}^2$ pitch
 - SmallPix 2013: 130 nm IBM CMOS, $\leq 40 \mu\text{m}^2$ pitch (medical applications, XFEL)
 - CLICPix ~ 2015 : 65 nm, $25 \mu\text{m}^2$ pitch
 - CLICPix demonstrator prototypes 2013: 64x64 pixel array
 - [See talk on hybrid pixel readout chip developments by Massimiliano De Gaspari](#)
- Low-mass interconnects and pixel connectivity
 - [Micro bump bonding](#) or [Cu pillars](#) for pixel interconnects
 - Through Silicon Vias ([TSV](#)):
 - fan out ASIC contacts to backside through vertical conducting channel
 - avoids dead areas from wire-bonding pads around the chips
 - Example: CEA-Leti via-last process with Medipix 3, prototypes under test
 - Lateral interconnectivity
 - [Slim-edge/edgeless](#) sensors
 - [Stitching](#) of neighboring chips

CLICPix 65 nm test structures

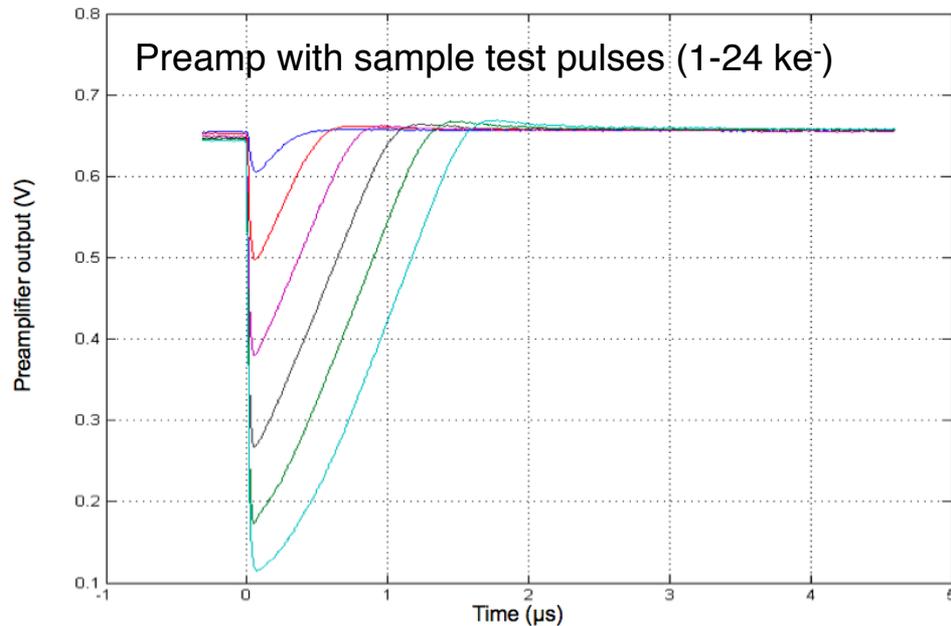
- Radiation and functional tests
- Total size: 3x4 mm
- Divided in three sub-chips:
 - 1 chip for analog structures and test devices
 - ❑ 1 pad per multiple gates
 - ❑ Analog structures
 - 1 chip w/ test structure/devices
 - ❑ 1 pad per gate
 - ❑ 142 total pins
 - 1 chip for digital logic
 - ❑ 64 kbit Shift-register
 - ❑ 56kbit Memory
 - ❑ Ring oscillator (1025 gates)



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CLICPix 65 nm test structures

- 65 nm technology allows for performance improvements w.r.t. 130 nm:
 - Smaller pixel sizes (10-30% less area for analog part, 60% less for digital part)
 - More functionality in each pixel
 - Lower noise (due to lower capacitances)
- Analog+digital test structures (pixel sub-circuits) produced 2011 in 65 nm TSMC multi-project wafer run



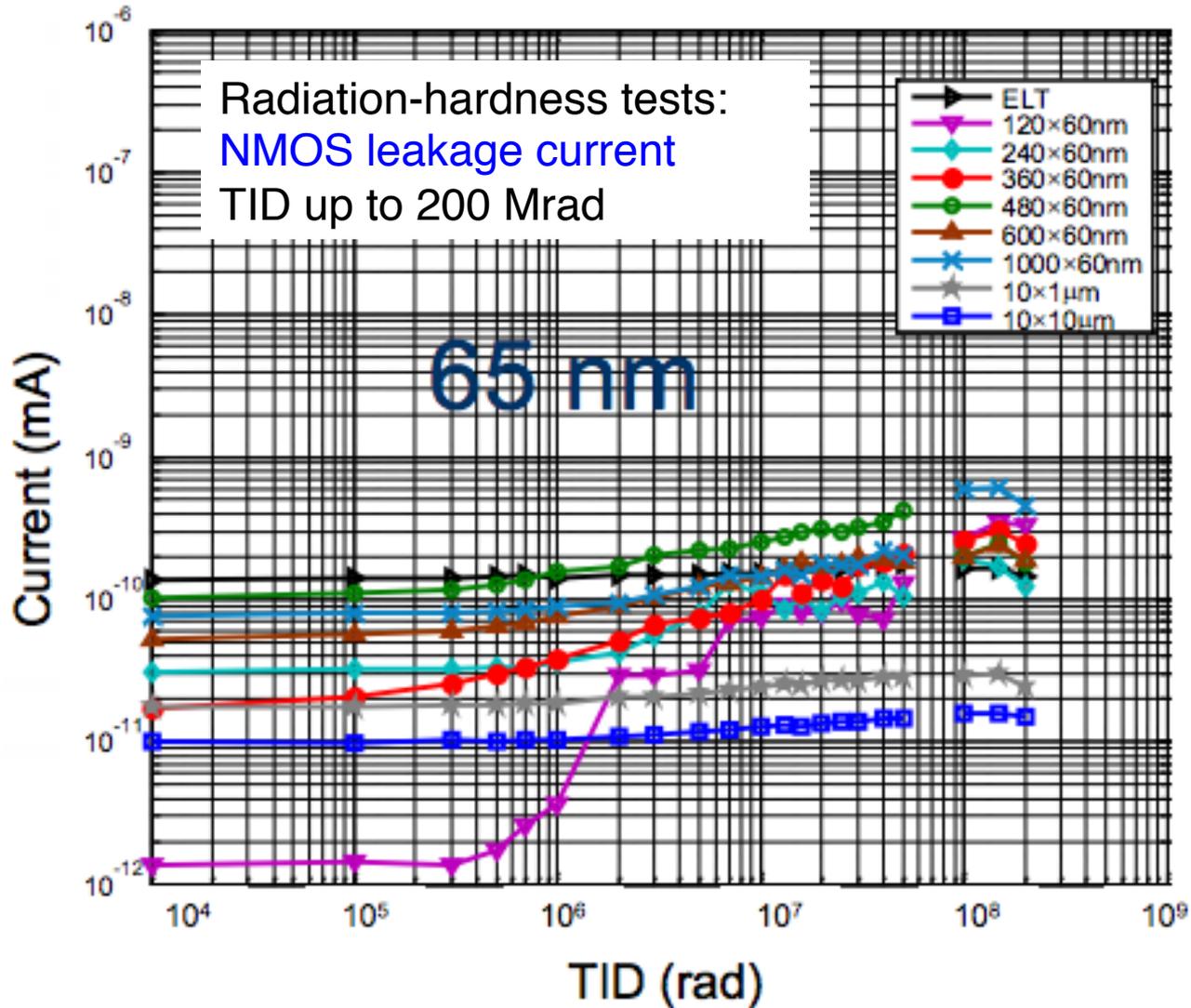
- Results according to simulations
- Improved radiation tolerance w.r.t. 130 nm observed (TID up 200 Mrad and SEU)
- Results allow for projections to CLICPix performance (e.g. power consumption)

Preamp measurements:

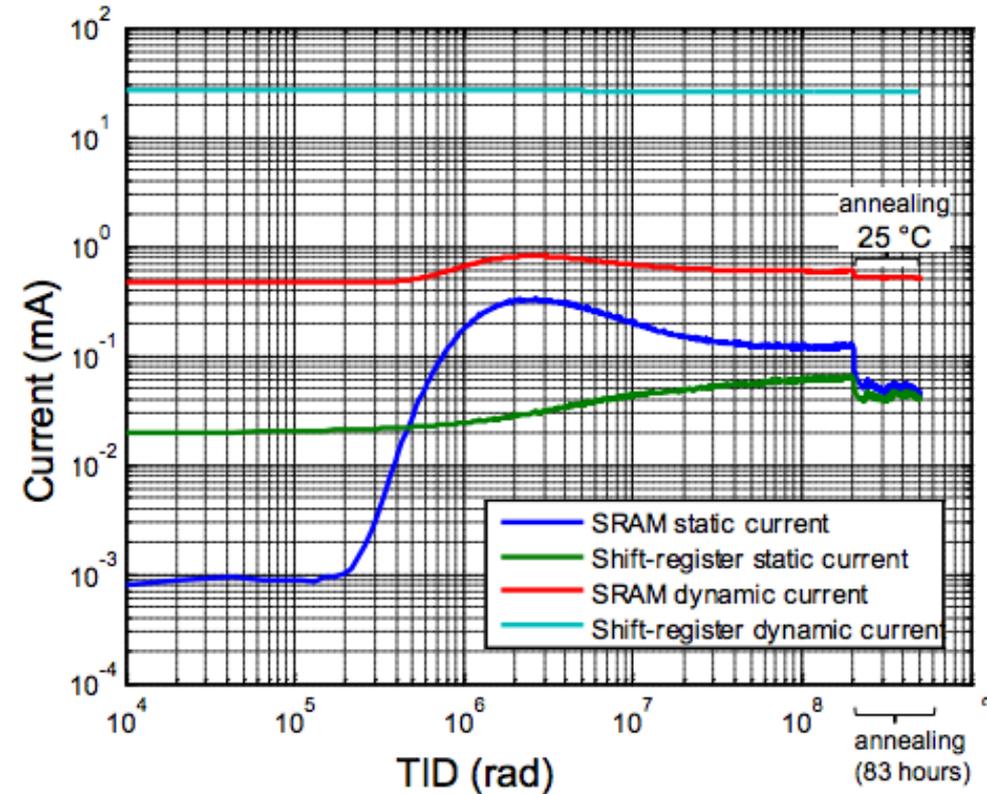
	Simulations	Measurements
Rise time	50ns	65ns
Gain	30mV/ke ⁻	29.1mV/ke ⁻
Linearity	5% at 16ke ⁻	5% at 15ke ⁻
Noise	55e ⁻	60e ⁻ (70e ⁻ for ELT channel)

P. Valerio

CLICPix 65 nm test structures: results



CLICPix 65 nm digital test structures



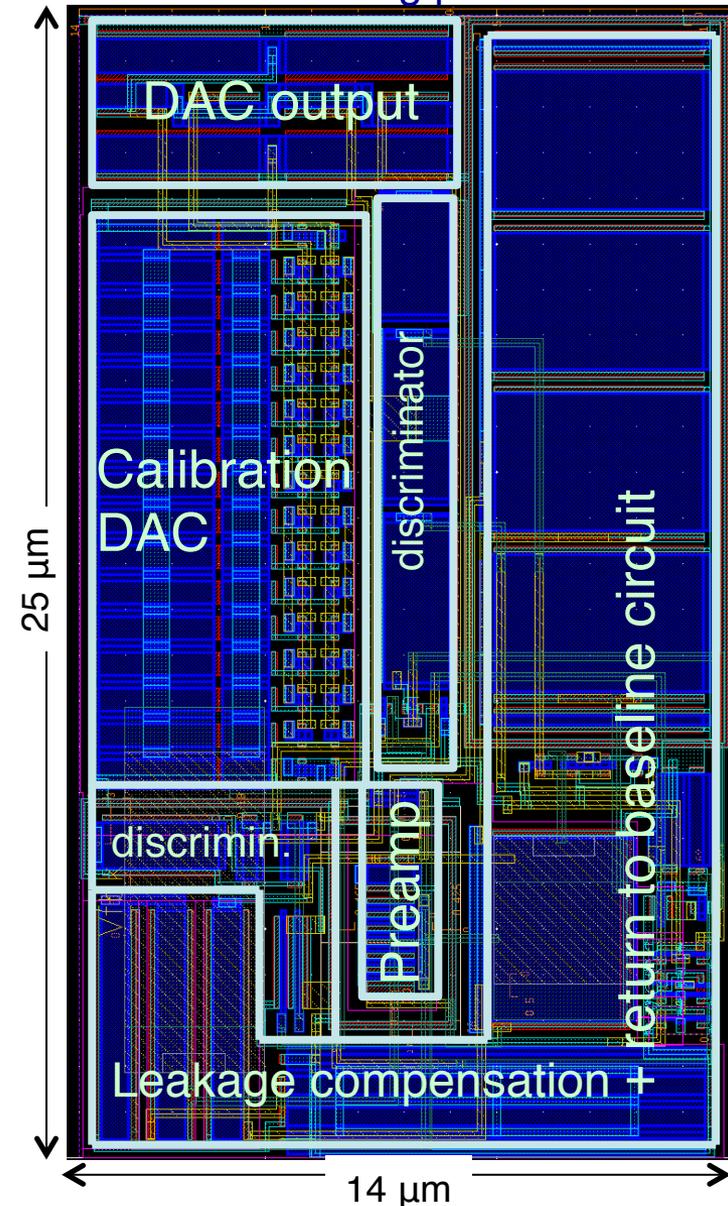
- Measured static and dynamic currents of SRAM and shift-register
 - Dynamic test run @ 30MHz
- SRAM static current increases by 300×
 - Dynamic current reflects this change with a small increase
 - Ultra-narrow devices are used in the SRAM from foundry (W=80nm)
 - Peak current at ~2-3 Mrad
- Shift-register static current changes very little
 - ~12.5 nW/MHz per D-FF
- Visible partial annealing effect at room temperature
 - Time constant ~ 1.5 hours

CLICPix 65 nm demonstrator chip

- **65 nm CMOS**, targeted to CLIC vertex detectors
- **25 μm** pixel pitch
- simultaneous **4-bit TOA and TOT per pixel**
- **Photon Counting Mode** for threshold equalization
- Front-end **time slicing < 10 ns**
(time-walk correction using TOT)
- Selectable compression logic:
 - Zero suppression
 - **cluster-based + column-based compression**
- Full chip r/o in less than 800 μs (for 10% occupancy) using a 320 MHz read-out clock
- $P_{\text{analog}} \sim 2 \text{ W/cm}^2$ (peak power)
- **power pulsing scheme** (Clock gating, power gating for analog part) $\rightarrow P_{\text{avg}} < 50 \text{ mW/cm}^2$
- Demonstrator chip designed with **fully functional 64 by 64 pixel matrix**
- **Submission November 2012**
in TSMC Multi-Project Wafer run

P. Valerio

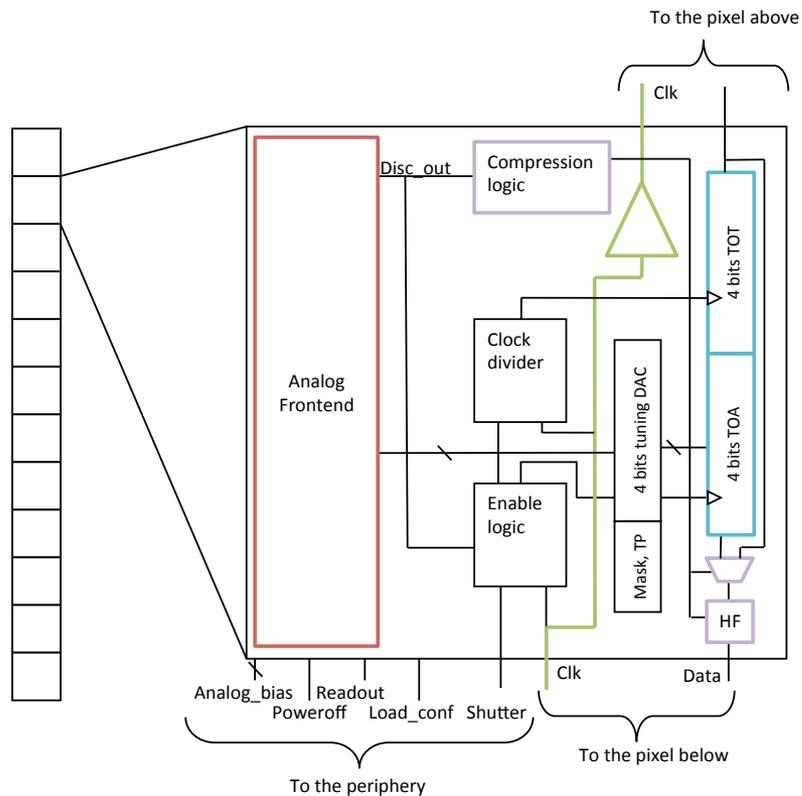
analog pixel:



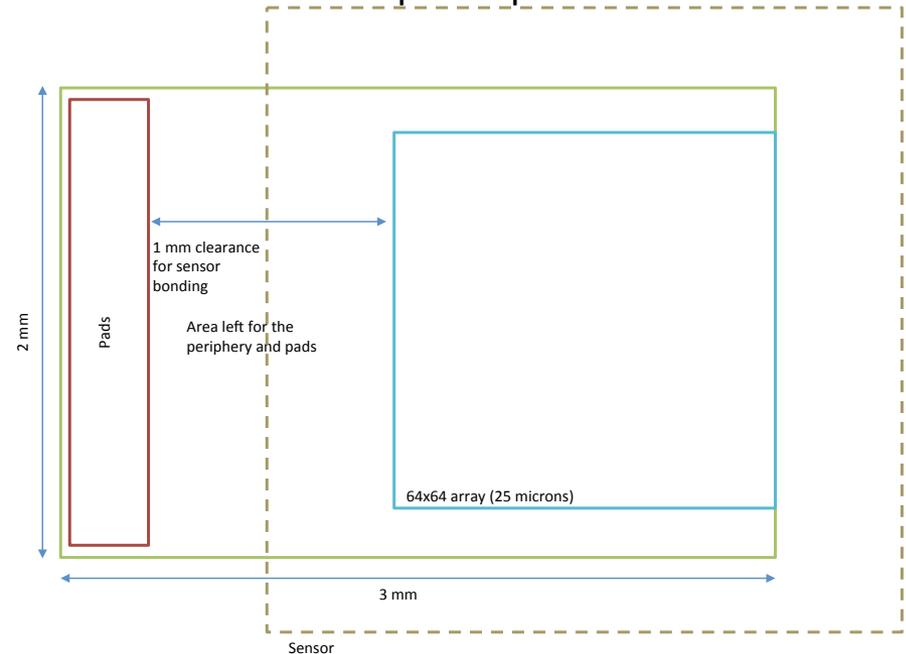
CLICPix 65 nm demonstrator chip

Demonstrator chip for next 65 nm MPWR

- First prototype with **full pixel-readout functionality**
- Submission end of 2012
- Includes **64 x 64 pixel array** with **25 μm pitch**
- Will try to (partially) bond to **sensor**



Chip floorplan



- simultaneous **4-bits TOA** and **4-bits TOT** measurements per pixel (100 MHz reference clock)
- Compression logic allows for sparse readout; **Cluster-based compression** is being evaluated
- **Power saving** techniques include clock gating when the pixel is not being read out and power gating (with an external signal) for the analog part when the chip is not acquiring data

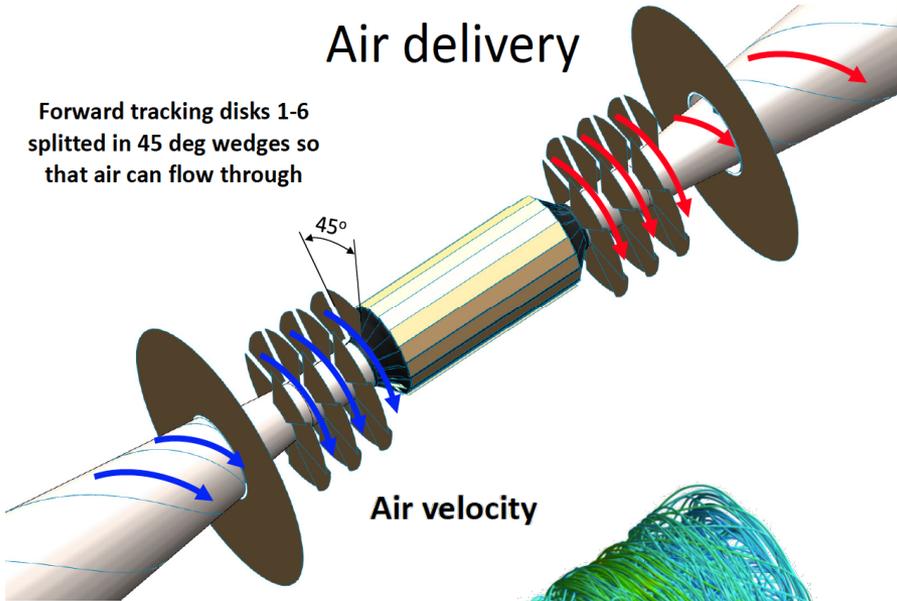
P. Valerio, X. Llopart

Low-mass cooling

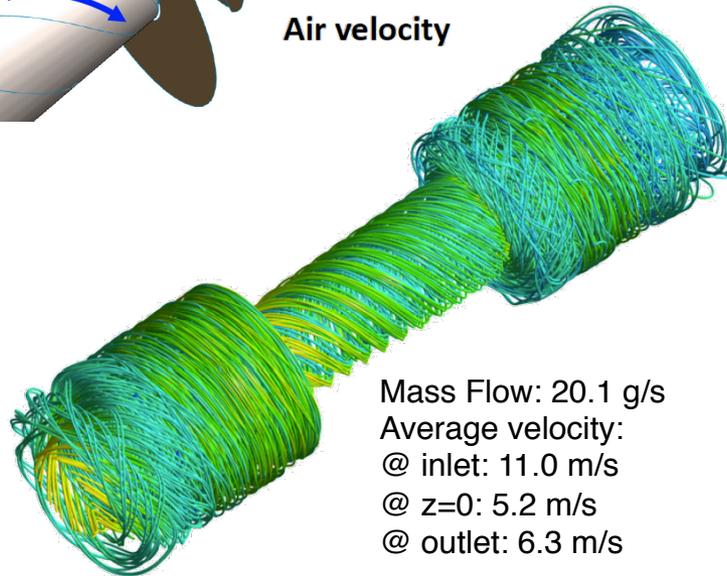
- $P \sim 500$ W in vertex detectors (50 mW/cm²)
- Need efficient cooling, meeting material budget requirements

Air delivery

Forward tracking disks 1-6
splitted in 45 deg wedges so
that air can flow through



Air velocity



Mass Flow: 20.1 g/s
Average velocity:
@ inlet: 11.0 m/s
@ z=0: 5.2 m/s
@ outlet: 6.3 m/s

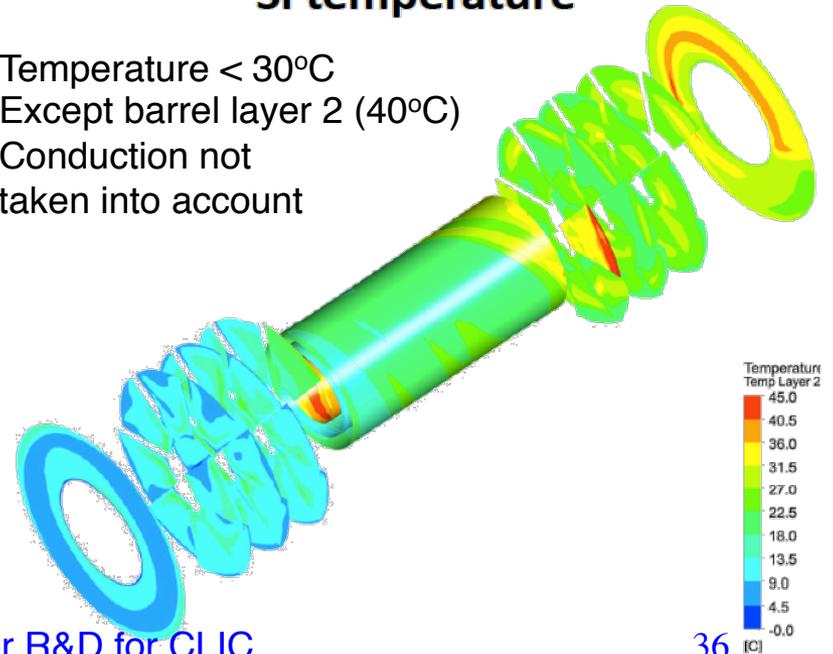
LCWS 2012

ANSYS finite element simulation
of air-flow cooling:

- Spiral disk geometry
→ allows for air flow into barrel
- Sufficient heat removal
- See talk on vtx mechanics + cooling
by Fernando Duarte Ramos

Si temperature

- Temperature < 30°C
- Except barrel layer 2 (40°C)
- Conduction not
taken into account



Vertex-Detector R&D for CLIC