LumiCal Clustering Algorithm

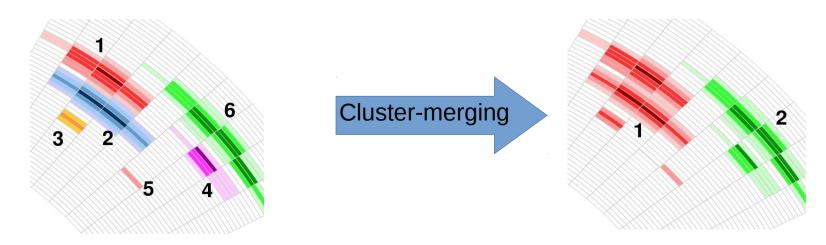
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LumiCal Clustering Algorithm

- The goal is to measure polar and azimuthal angles
- Studied by Iftach Sadeh at TAU
- Code reworked by Andre
- Reconstruction stages:
 - 2D clustering;
 - Composing 3D clusters;
 - Correcting the parameters of the cluster based on their energy density distribution.

LumiCal 2D Clustering Algorithm

- There are only a few hits from the shower in the first layers of LumiCal
- In the first layer may also be contributions from the backscattered particles or background processes
- Clustering algorithm starts by considering the information in the shower-peak layers
- Near-neighbor clustering approach uses gradient of energy around local shower-centers (figure in the bottom)
- Cluster-merging based on the weights proportional to energy and inverse proportional to the distance. Several approaches to the weight calculation were implemented.



LumiCal Shower Shape

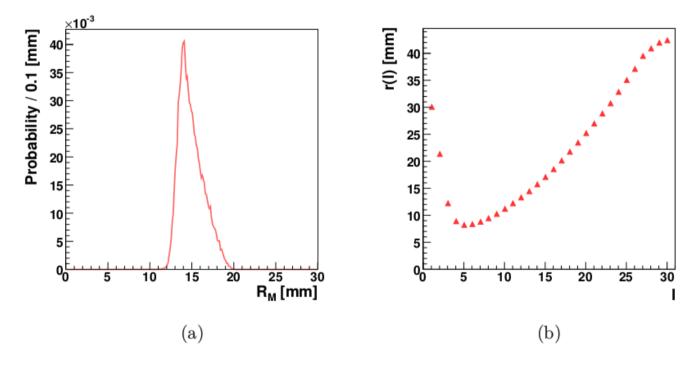


Figure 3.5: (a) Distribution of $R_{\mathcal{M}}$, the distance around the global-shower center, in which 90% of the integrated shower energy may be found. (b) Dependence on the layer number, ℓ , of the layer-radius, $r(\ell)$, which is the distance around the local shower-center in which 90% of the energy of a layer is deposited.

LumiCal 3D Clustering Algorithm

- The aim is to determine the total number and position of the showers.
- The number of showers is determined as the most frequent value of the layer-cluster number in the collections in the shower-peak layers
- Propagation of each shower through LumiCal, using the information from the shower-peak layers and association of the cells from non-shower-peak layers with one of the global showers.
- Weighing method is used, similar to the one in the 2D reconstruction.

Implementation

- https://svnsrv.desy.de/public/FCAL/Software/FcalClust erer/trunk
- LumiCalClustererClass::processEvent(EVENT::LCEve nt * evt)
- Practically each step of the algorithm is implemented as a method of LumiCalClustererClass class extensively using c++ standard containers.

Summary and Plans

 Use LumiCal cluster reconstruction with LuCaS for tracking detector study.