

# LumiCal Performance with a Tracking Detector

Oleksandr Borysov  
Tel Aviv University

FCAL Meeting, Belgrade  
October 13, 2014

# Outline

- Introduction and motivation for the study
- Simulation with LuCaS
- Reconstruction with LumiCal clustering software
- LumiCal with and without tracking detector
- Summary and plans

# Tracking Detector

- Improve polar angle measurement accuracy;
- LumiCal alignment;
- Provide more information to enable  $e/\gamma$  identification, important for various physics study.

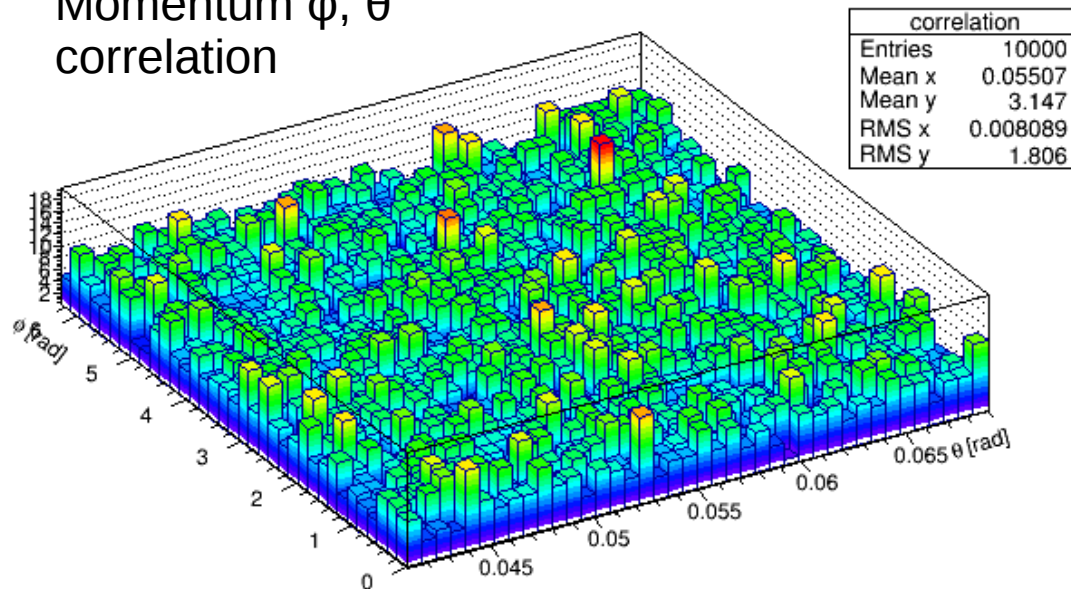
As a possible candidate could be Mimosa sensor

- Mimosa – MOS Active Pixel, developed in Strasbourg.
- Mimosa-28 is used in STAR inner tracker at RHIC, possibly will be approved for ALICE ITS upgrade;
- We are developing the facilities for Mimosa test at TAU;
- Important to evaluate the radiation dose and radiation hardness of the Mimosa sensor.

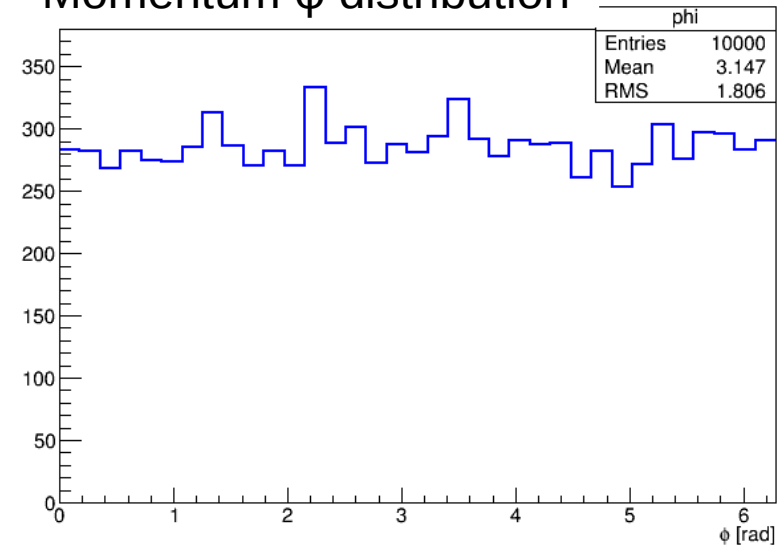
# Generated Events

- Subset of 2000-5000 events out of 10000 were used for simulation
- Each event contains one  $e^-$ , 250 GeV;
- Uniformly distributed on momentum  $\phi$  ( $0, 2\pi$ ),  $\theta$  (41, 69 mrad).

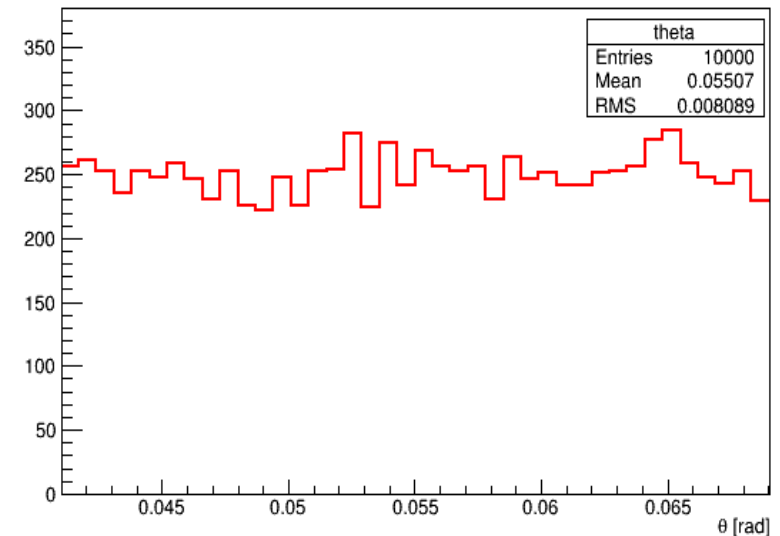
Momentum  $\phi$ ,  $\theta$   
correlation



Momentum  $\phi$  distribution

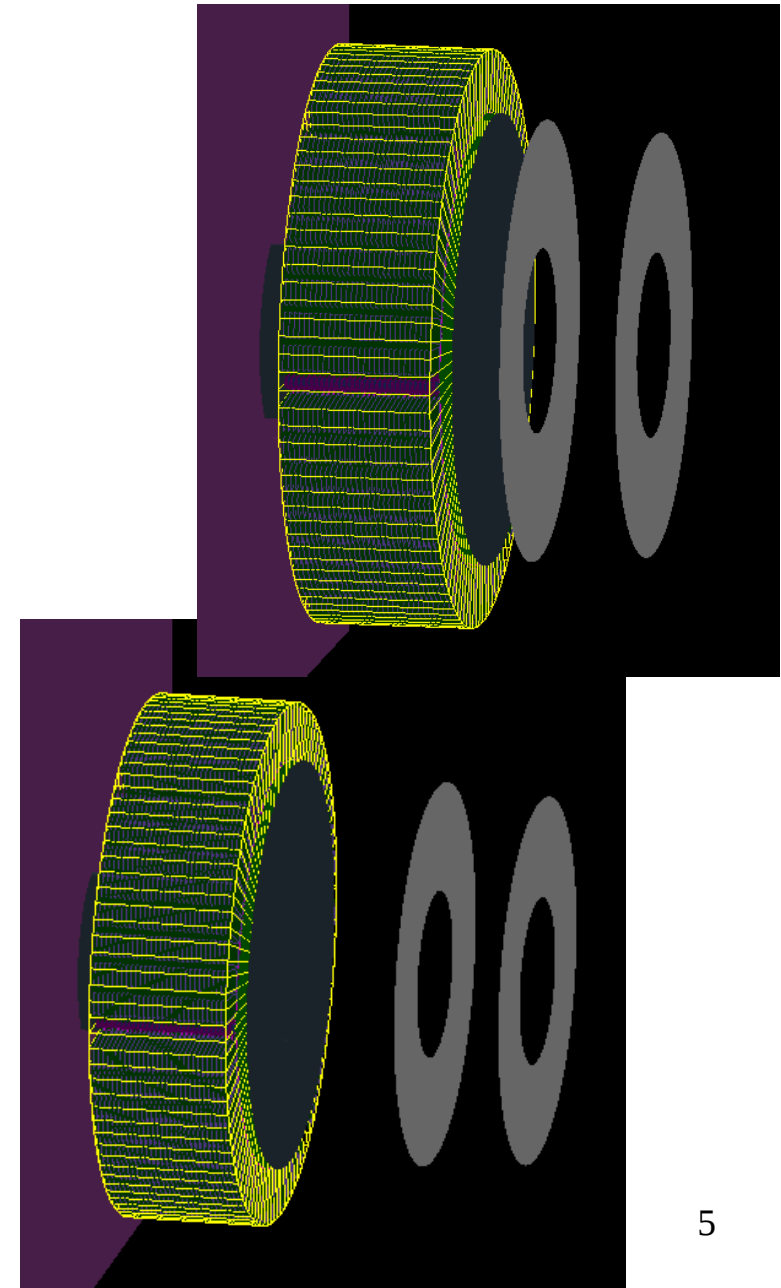


Momentum  $\theta$  distribution



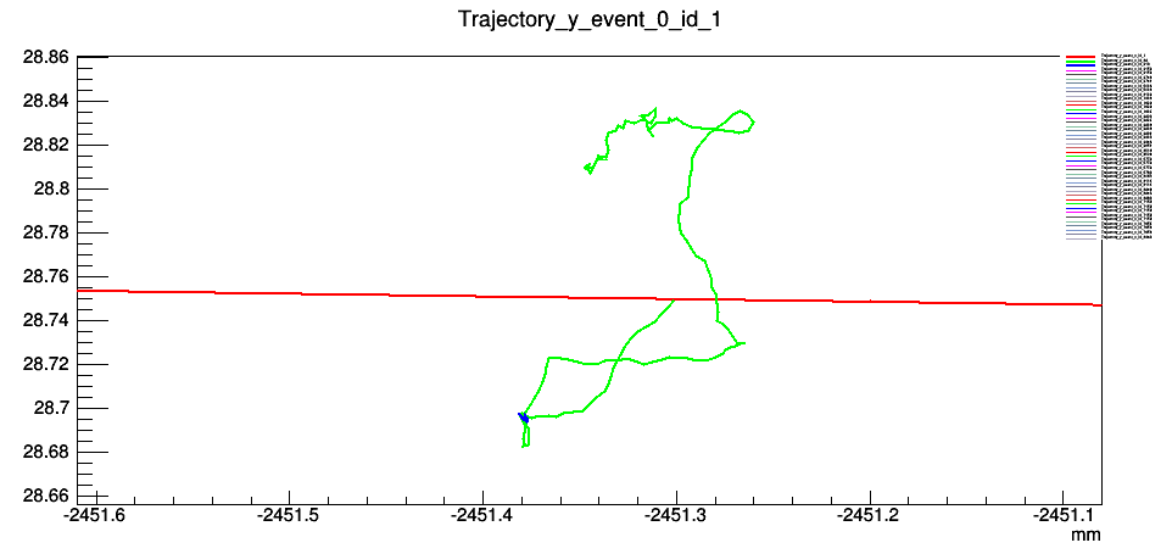
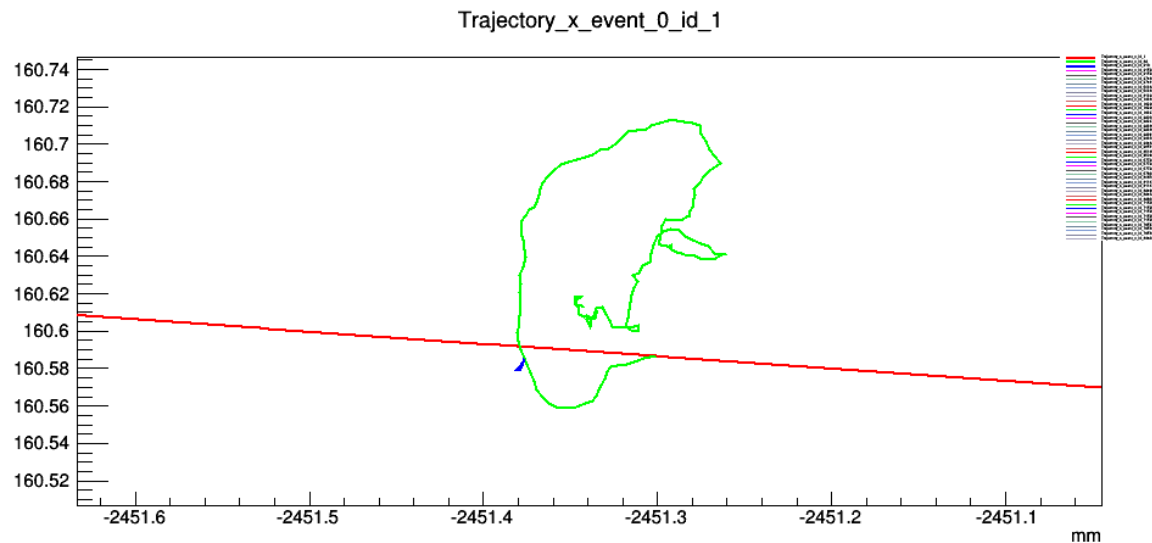
# Simulation

- Modified versions of LuCaS (Geant4 application) was used;
- Range cut: 20  $\mu\text{m}$  (5  $\mu\text{m}$  also was tested);
- Minimum step: 5  $\mu\text{m}$ ;
- Physics list: QGSP\_BERT;
- Two layers of Si 100  $\mu\text{m}$  thick;
- Different distance to LumiCal;



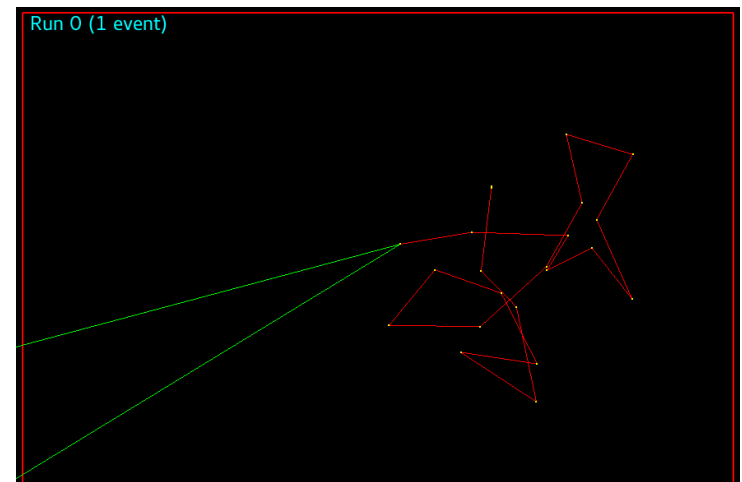
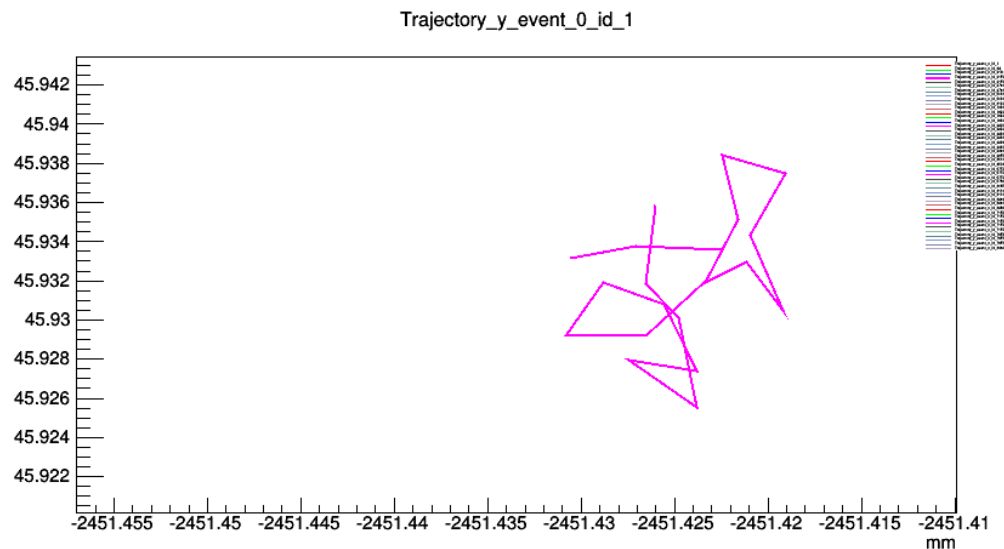
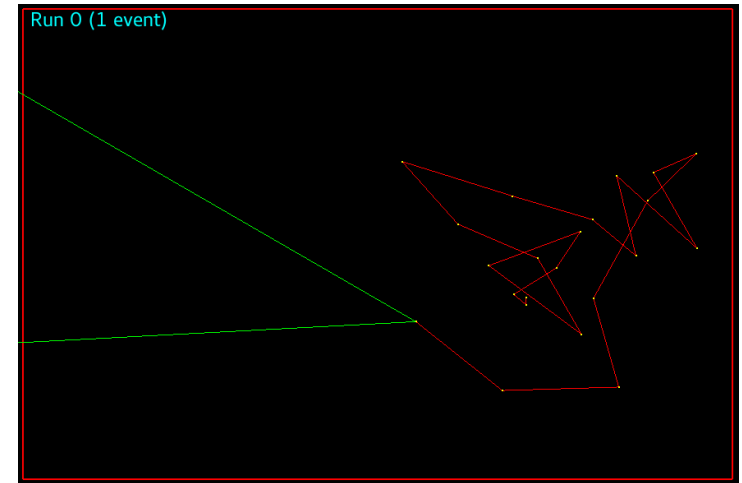
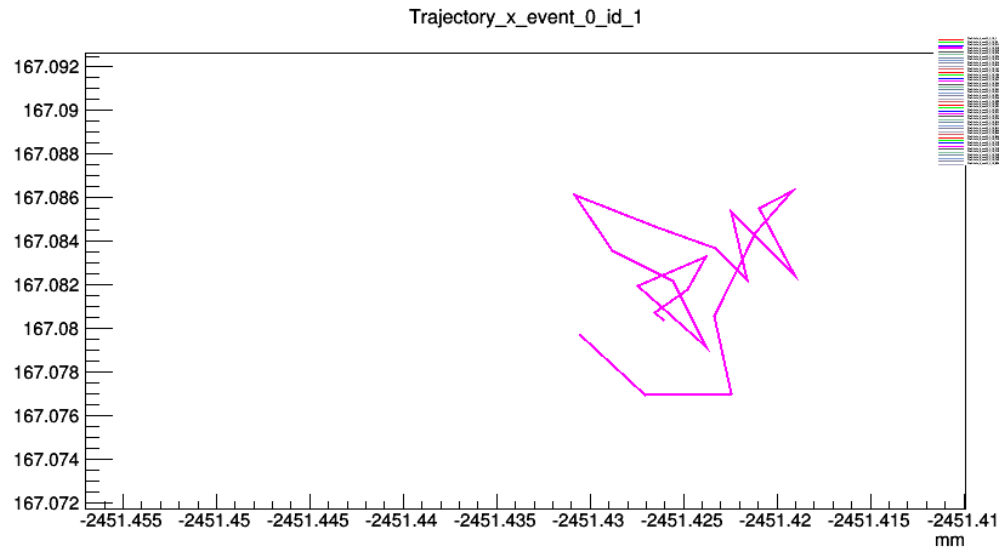
# Comparison of Geant4 visualization and reconstruction from the hits

Tungsten was considered to have more secondary particles

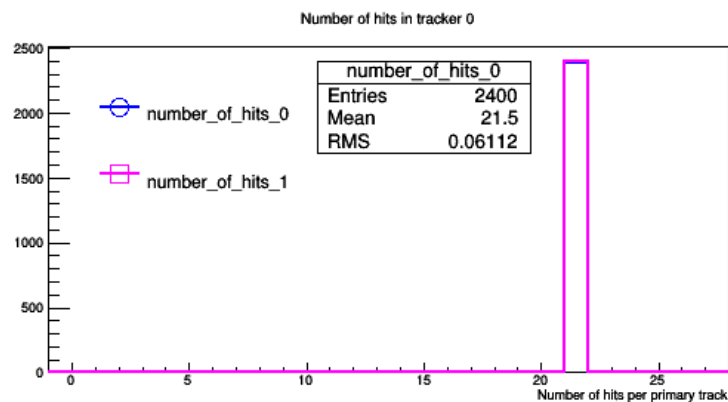
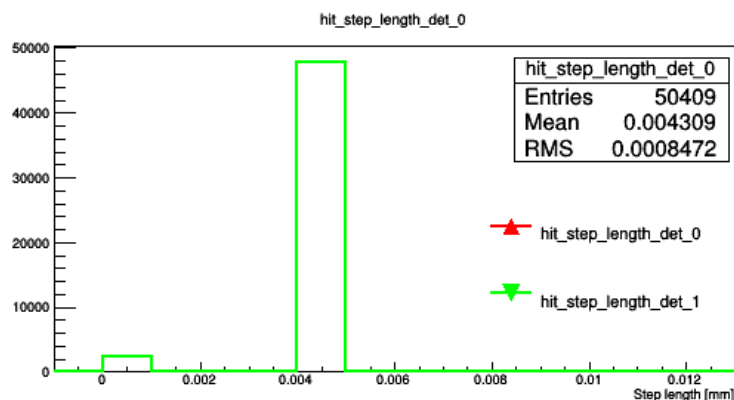


# Comparison of Geant4 visualization and reconstruction from the hits

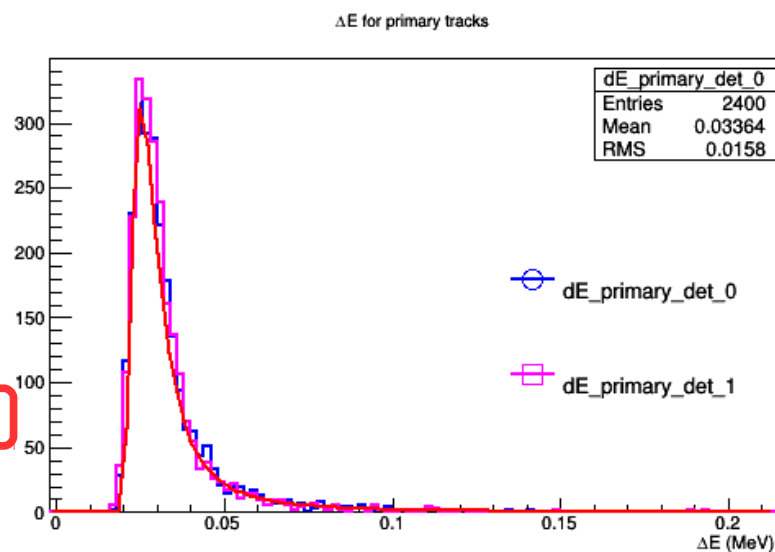
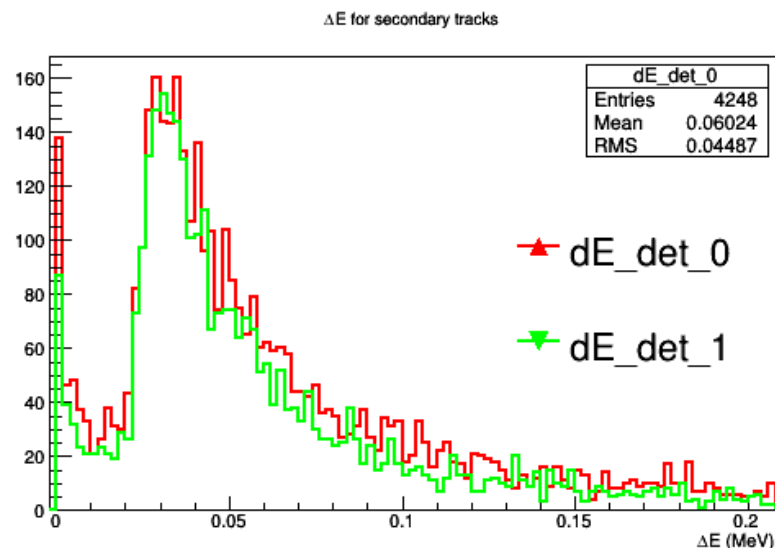
Tungsten was considered to have more secondary particles



# Energy Deposition and Step



Name	Fix	Bound	Value
Constant	<input type="checkbox"/>	<input type="checkbox"/>	1878.89
MPV	<input type="checkbox"/>	<input type="checkbox"/>	0.0258505
Sigma	<input type="checkbox"/>	<input checked="" type="checkbox"/>	0.00249702





# Primary Momentum Direction Change

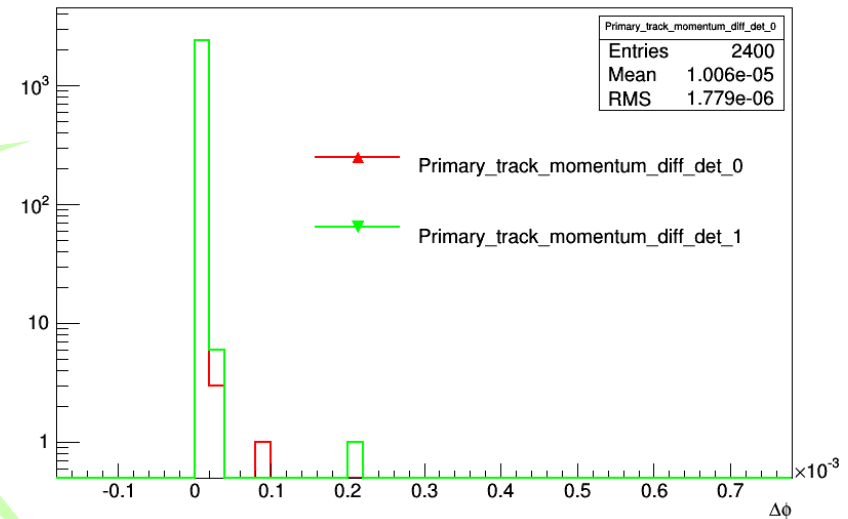
Distance from tracking sensors to LumiCal

5 cm + 5 cm;

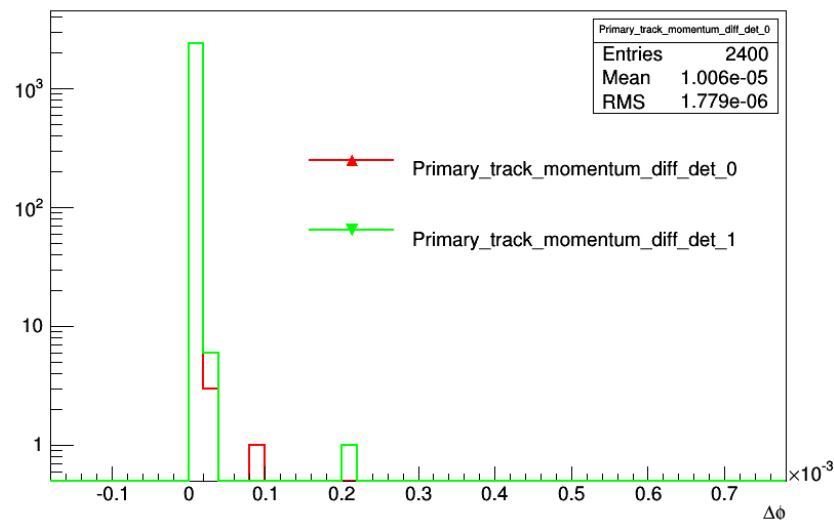
15 cm + 5 cm;

25 cm + 5 cm;

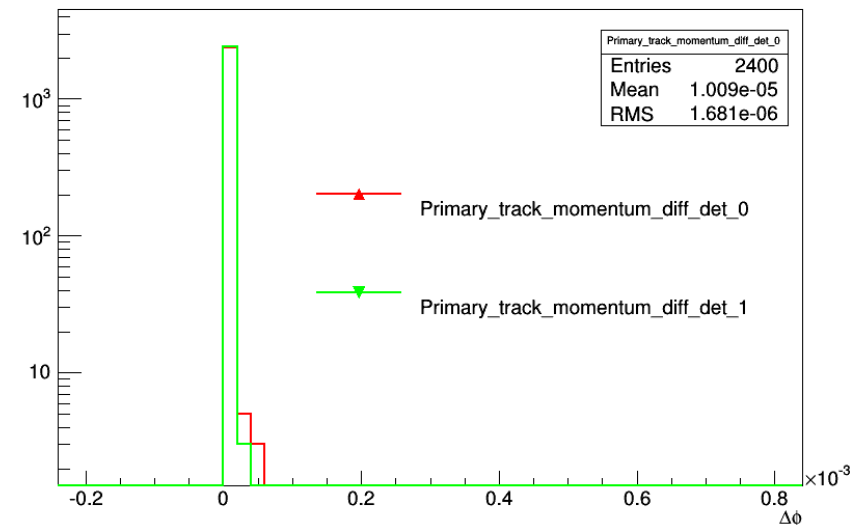
Momentum change of primary track



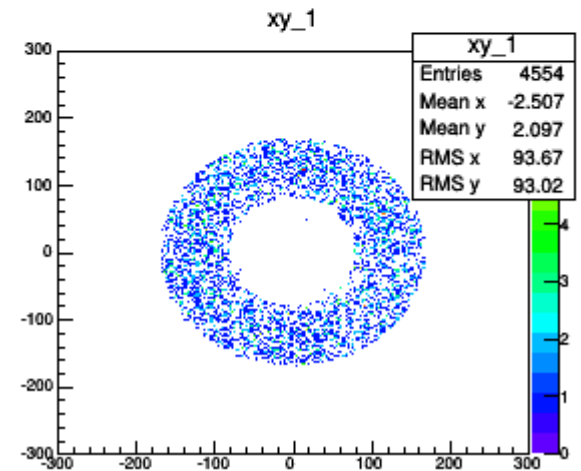
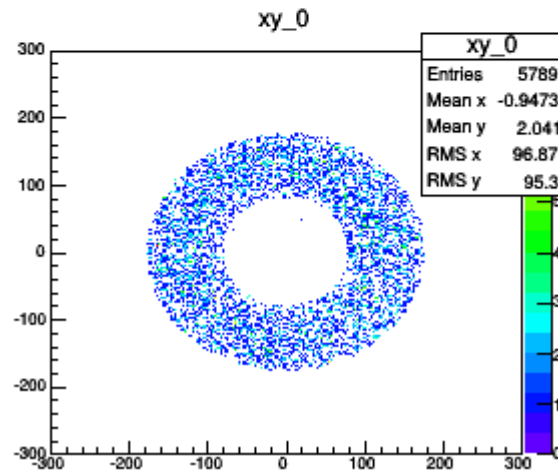
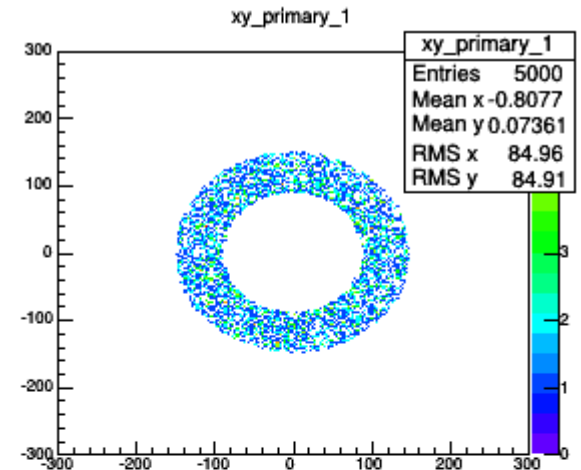
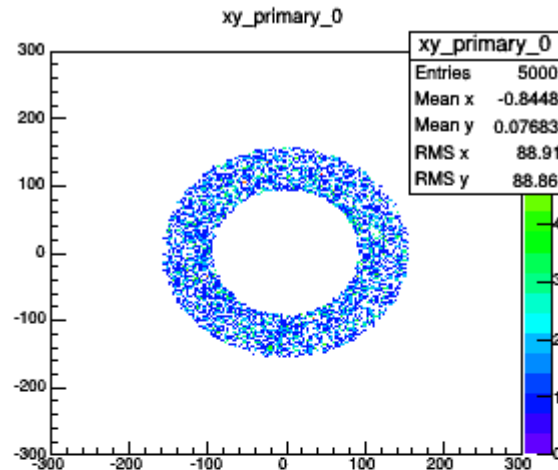
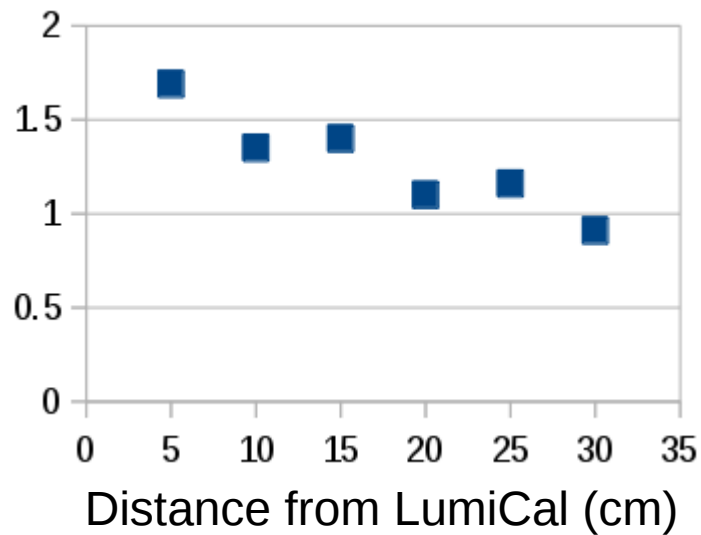
Momentum change of primary track



Momentum change of primary track

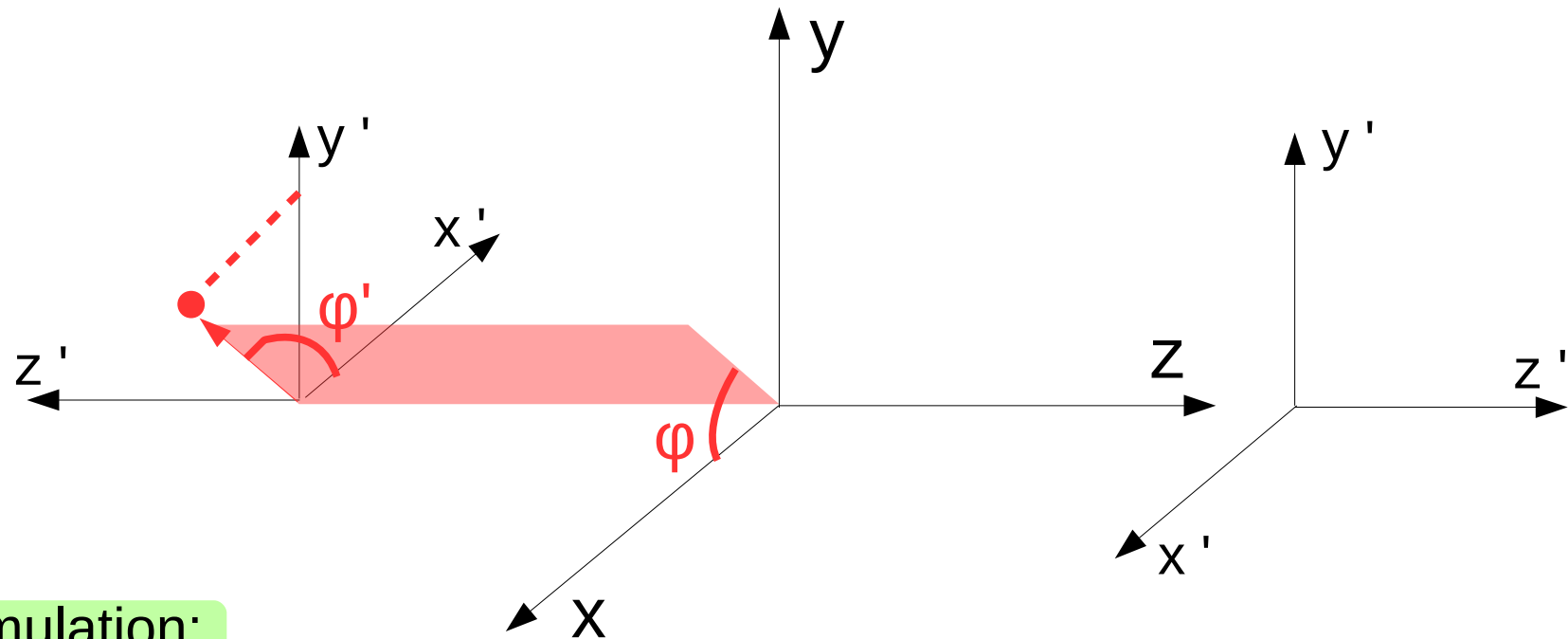


# Secondary Rec. Points



Dist. (cm)	5	10	15	20	25	30
Prim ev.	2400	2400	2400	2400	5000	5000
Second trck	4053	3235	3355	2649	5789	4554
sec/prim	1.69	1.35	1.4	1.1	1.16	0.91

# LuCaS – Reconstruction Coordinates Mismatch



Simulation:

Global hit coordinate

local coordinate in  
LumiCal arm

$R', \phi'$

Cell radial ID,  
Cell azimuthal ID

Global hit coordinate

$R, \phi$

Reconstruction

Cell radial ID,  
Cell azimuthal ID

Cause the problem for  $Z < 0$

# Reconstruction in LumiCal

2 cases:

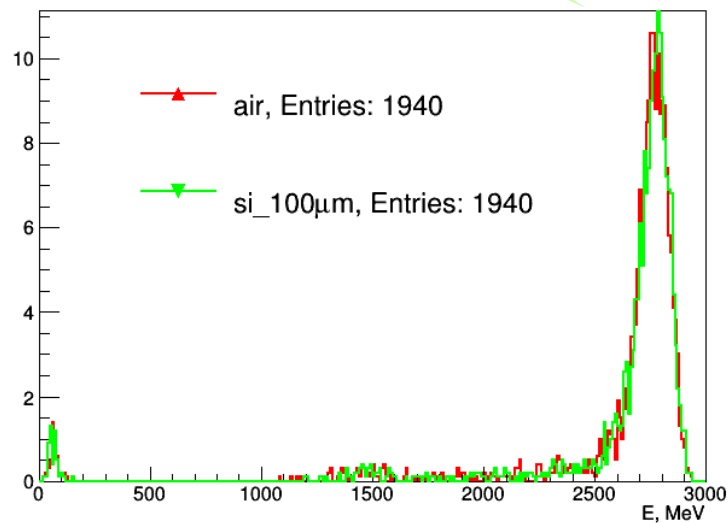
- without tracking detector (air);
- with 2 layer of 100  $\mu\text{m}$  thick Si.

$\theta_{\text{gen}} - \theta_{\text{reco}};$

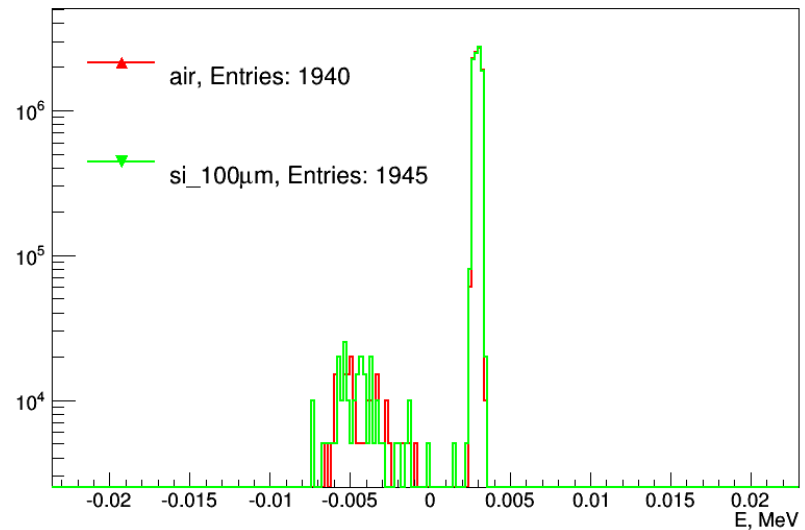
$\phi_{\text{gen}} - \phi_{\text{reco}};$

$E_{\text{reco}};$

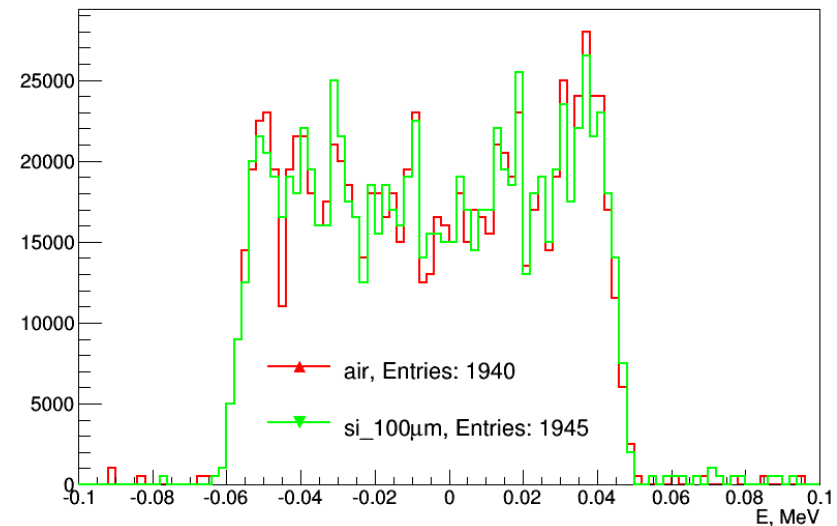
Energy reconstruction



$\theta$  reconstruction



$\phi$  reconstruction

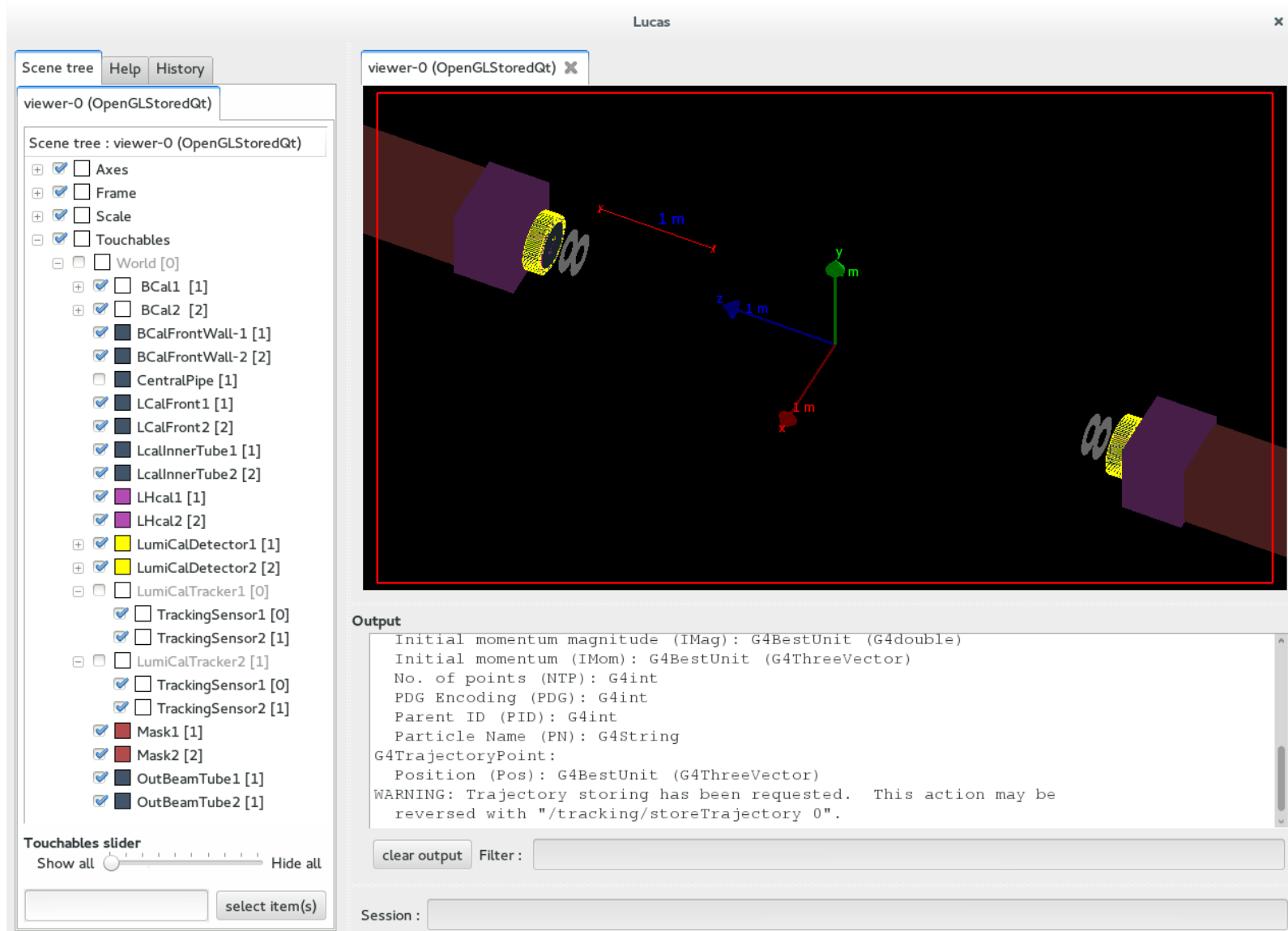


# Summary and Plans

- There is significant occupancy of tracking detector caused by the scattered particles from LumiCal. It decreases as we move further from LumiCal.
- There is no visible influence of tracking detector on LumiCal performance, though more tests should be made with higher statistics and numerical evaluation.
- Include tracking detector in  $\varphi$ ,  $\theta$  reconstruction.
- Study different configurations of tracking detector.

# Backup

# LuCaS with qt UI



# Geometry and Hits Implementation in LuCaS

```
rotAng      = Setup::Beam_Crossing_Angle / 2.;
rotAng1     = 180.*deg - rotAng;
rotAng2     = rotAng;
.....
G4Transform3D trans1( G4RotationMatrix().rotateY(rotAng1),
                      G4ThreeVector( 0., 0., zpos).rotateY(rotAng1));
G4Transform3D trans2( G4RotationMatrix().rotateY(rotAng2),
                      G4ThreeVector( 0., 0., zpos).rotateY(rotAng2));

    new G4PVPlacement( trans1 ,
                        logicWholeLC,
                        "LumiCalDetector1",
                        logicWorld,
                        false,
                        1);
    new G4PVPlacement( trans2,
                        logicWholeLC,
                        "LumiCalDetector2",
                        logicWorld,
                        false,
                        2);

.....
    G4ThreeVector LocalHitPos = theTouchable->GetHistory()-
GetTopTransform().TransformPoint(GlobalHitPos) ;
    G4double rho = LocalHitPos.getRho();
    G4double phi = LocalHitPos.getPhi();
```



$$\Delta\phi$$

