

Status of TPC tracking in non-uniform magnetic field

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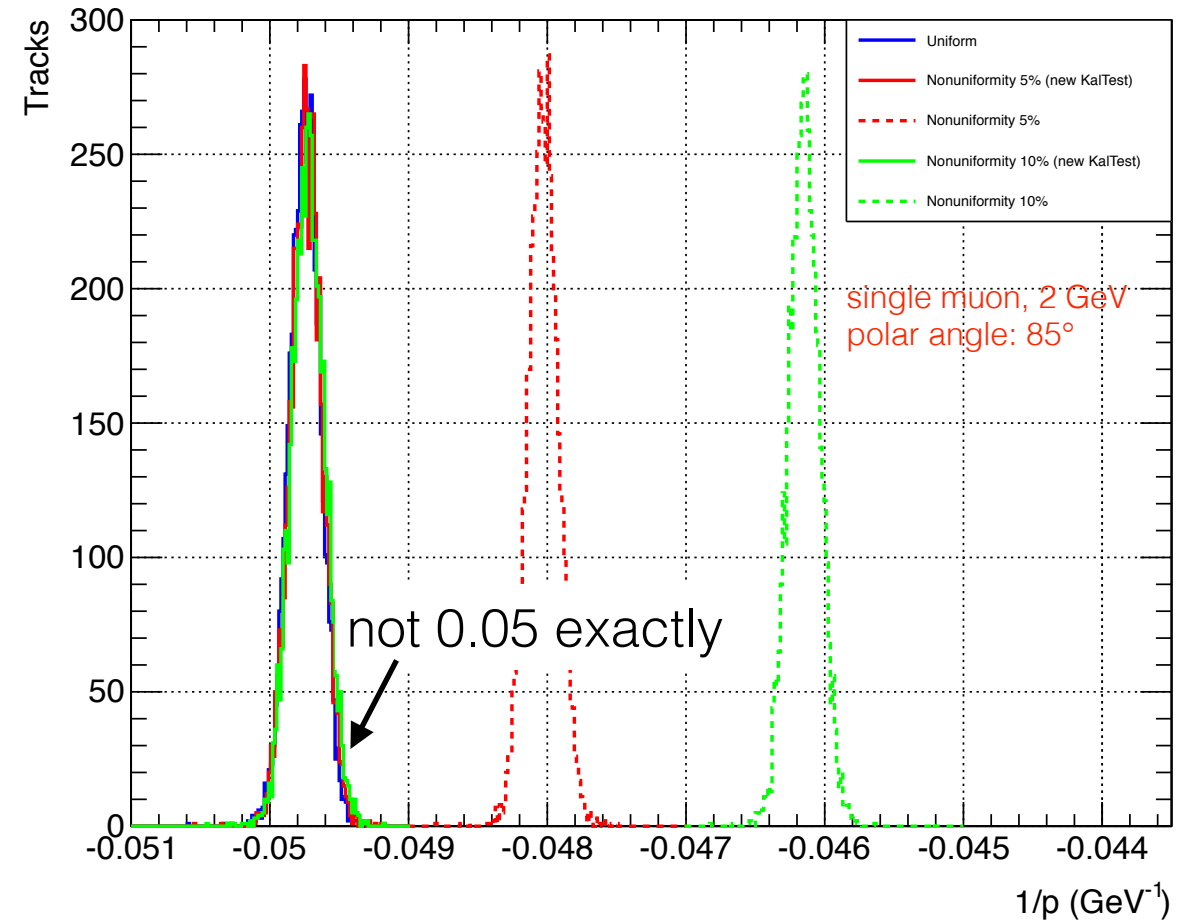
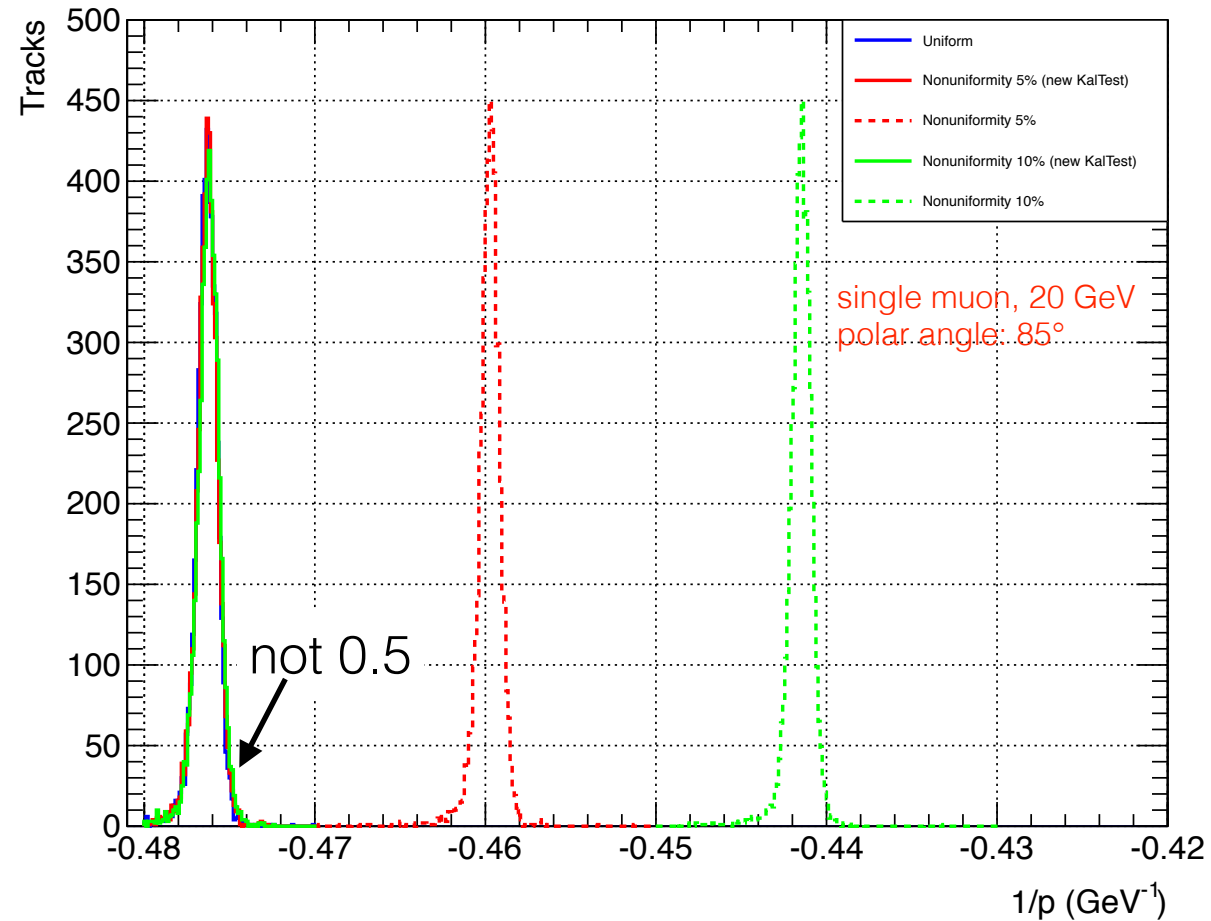
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Introduction

- The algorithm (KalTest) was updated for tracking in non-uniform magnetic field already. (The code is in my branch of KalTest on ILCSoft repository.)
- It is now meaningful to study the performance of new KalTest in the ILCSoft (such as Clupatra and MarlinTPC)
- Simulation in Mokka: a non-uniform magnetic field is hard-coded in the class Field00.

Track momentum

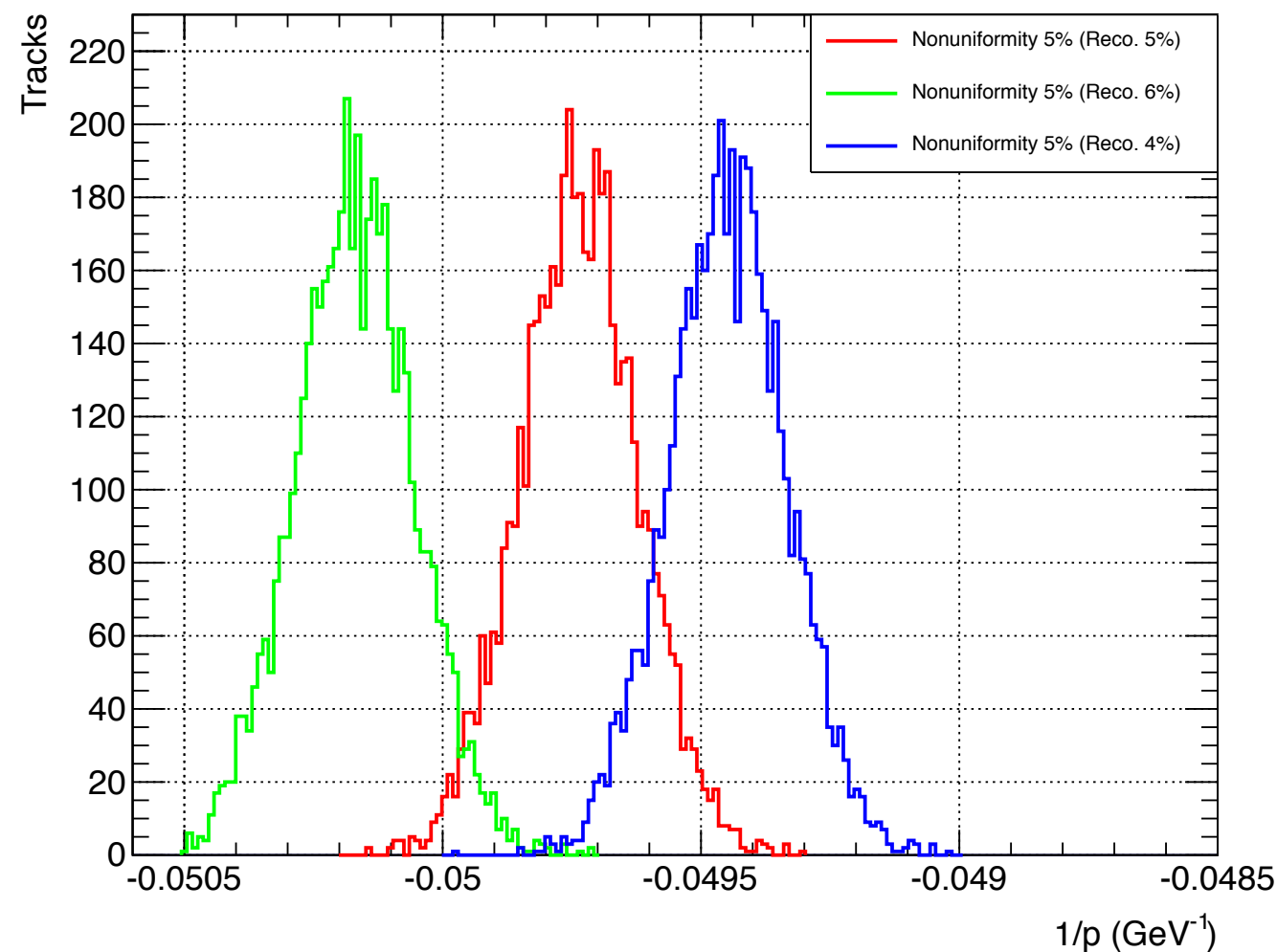
- The track momentum fitting results by new KalTest in the non-uniform magnetic field are consistent with that of original KalTest in uniform magnetic field 😊



- A difference between expected value and the reconstruction 😞

Field precision

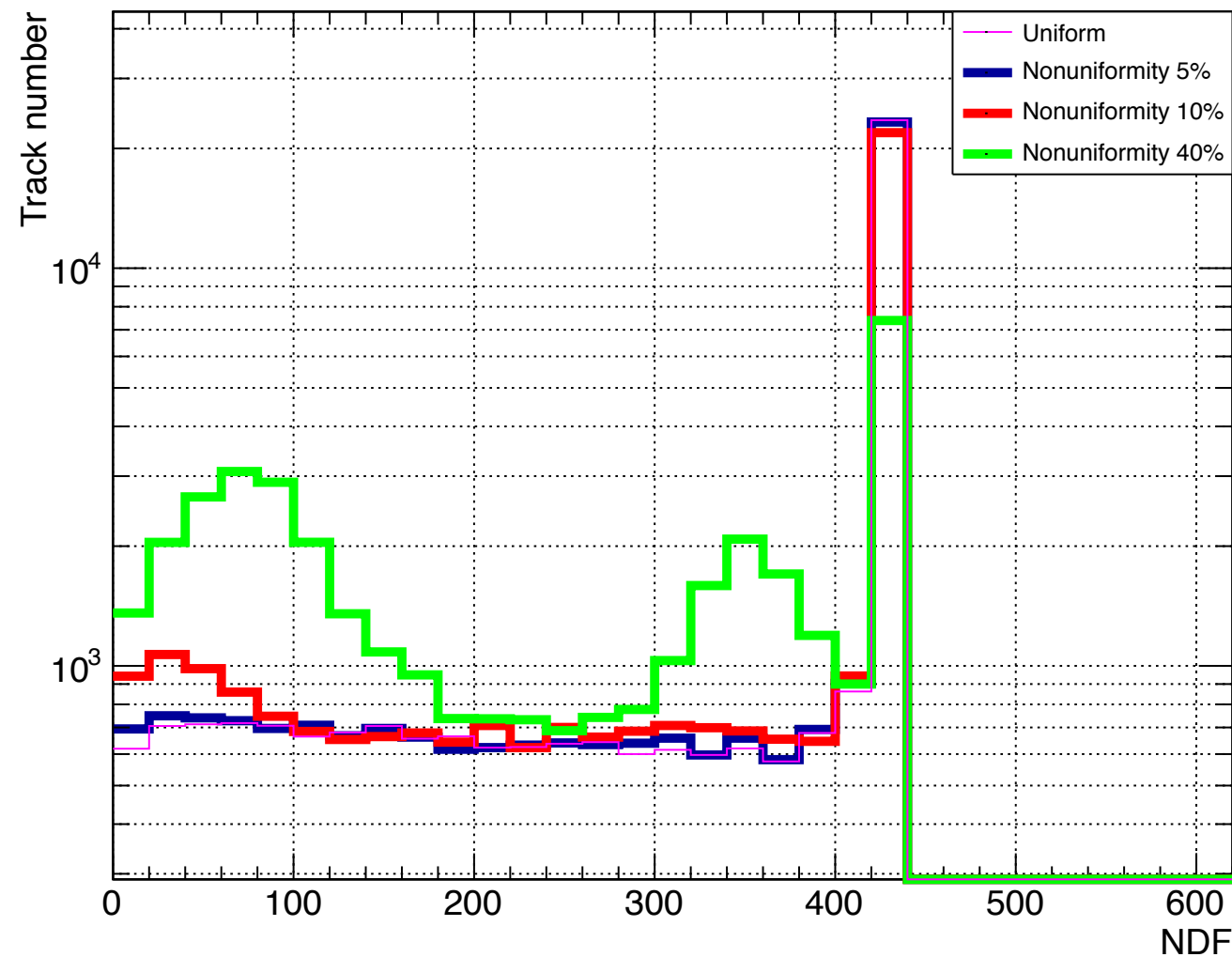
- If the measured field map is not precise enough, we may wonder its influence on momentum.



- At 20 GeV, the momentum bias introduced by the error (20%) of measured field map is about 0.1 GeV.

Tracking performance

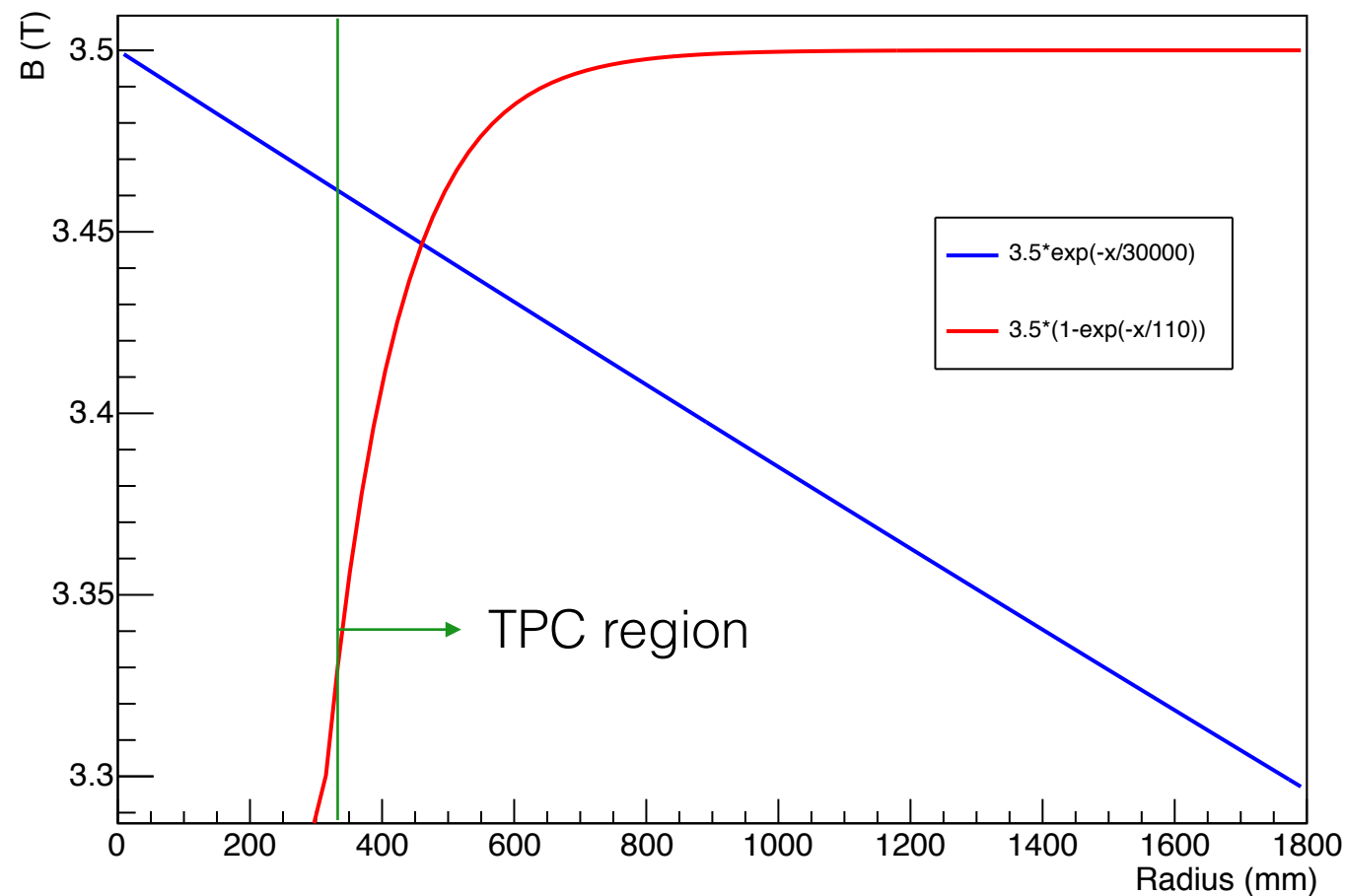
- Tracking efficiency: 99%
- The degree of freedom per track:



- When the non-uniformity is less than 10%, its affect on track finding can be neglected.

Magnetic field

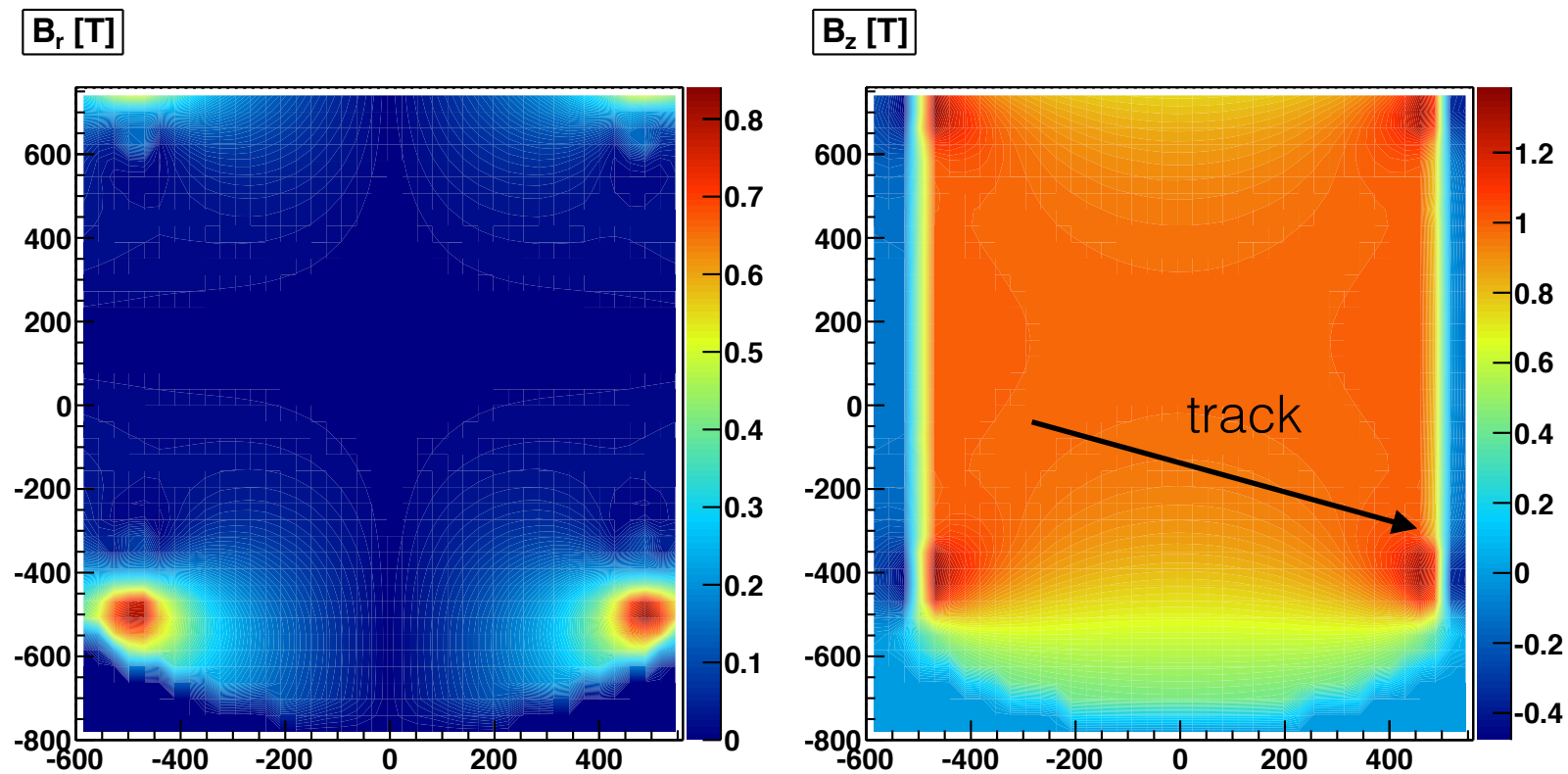
- For the previous studies, a field map having a form the blue curve is hypothesized.



- It seems that reconstruction result by the current ILCSoft is good enough. (However, I will check this further.)
- A map field close to the real case is very useful.

Reconstruction in MarlinTPC

- The field map of PCMAG:



- Reconstructed momenta of 5 GeV tracks (polar angle: 0.5 rad):

