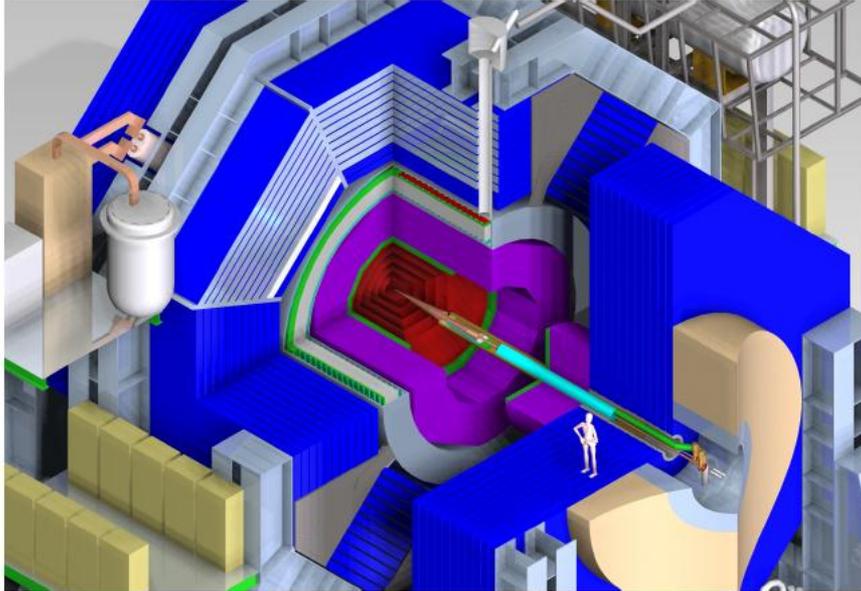


# MDI Update from SiD

Marco Oriunno , SLAC  
LCWS12, UTA Arlington, TX  
October 22-26, 2012

# Detailed Baseline Document Submitted on 9/24



**SiD**

DETAILED BASELINE DESIGN

DRAFT SUBMITTED TO THE IDAG

24/SEPTEMBER/2012

## 7 Engineering, Integration and the Machine Detector Interface

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#### 7.5.1 Radiation Calculations

#### 7.5.2 Fringe Fields and Magnetics

# SID key design features

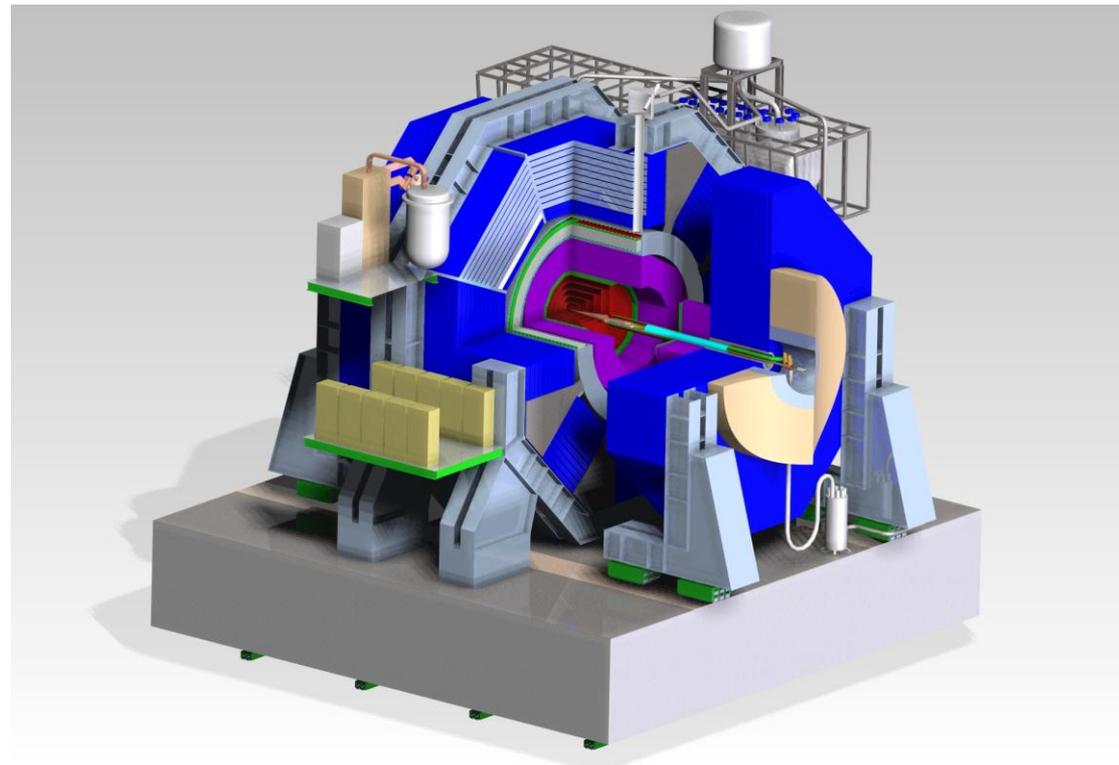
Compact design with 5 T Solenoid

Single Ring Barrel ~ 4'000 tons

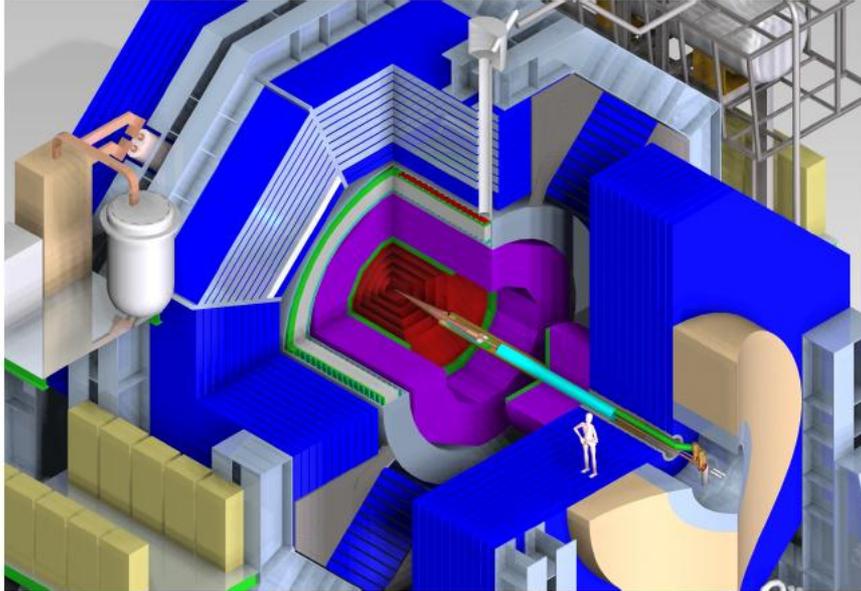
Self Shielded: Stray Fields & Radiation

Short L\* with QD0's supported from the doors

Barrel Ecal	60
Barrel Hcal	450
Coil	192
Barrel Iron	3287
<b>Total Barrel</b>	<b>3990</b>
Endcap Ecal	10
Endcap Hcal	38
Endcap Iron	2100
Pacman	100
Feet	60
BDS	5
<b>Total Door (x1)</b>	<b>2313</b>
<b>Total SiD</b>	<b>8615</b>



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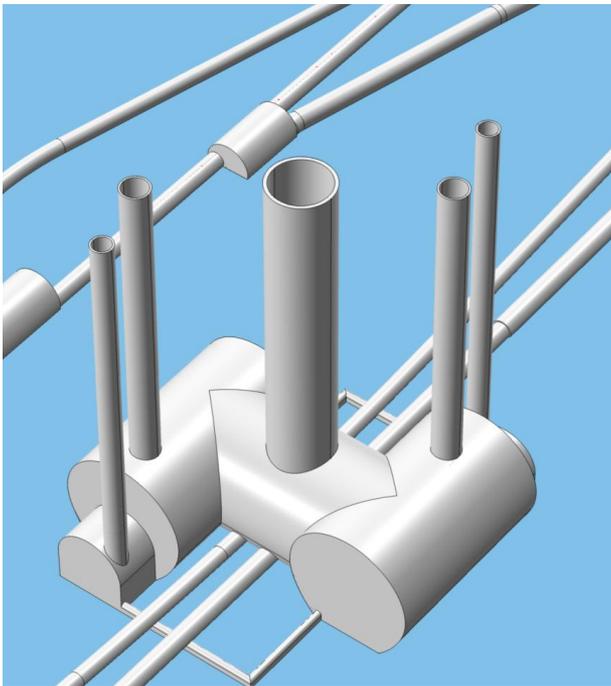
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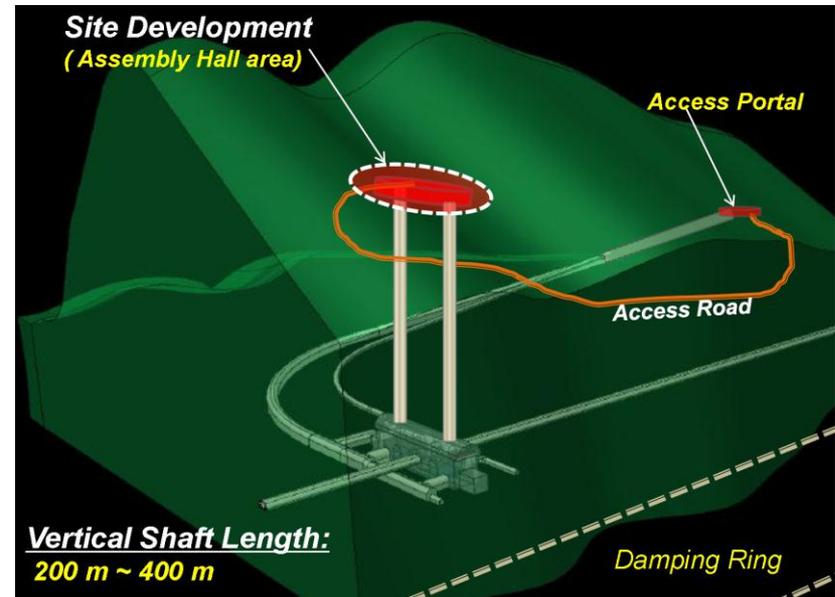
#### 7.5.2 Fringe Fields and Magnetics

# Assembly Procedures for different Sites

- The assembly procedure will be different for the two sites
- Both layouts must satisfy push-pull requirements
- The detector hall must be optimized for costs: benefits vs. features



•Vertical shafts (Europe, Americas)



•Horizontal shafts (Japan)

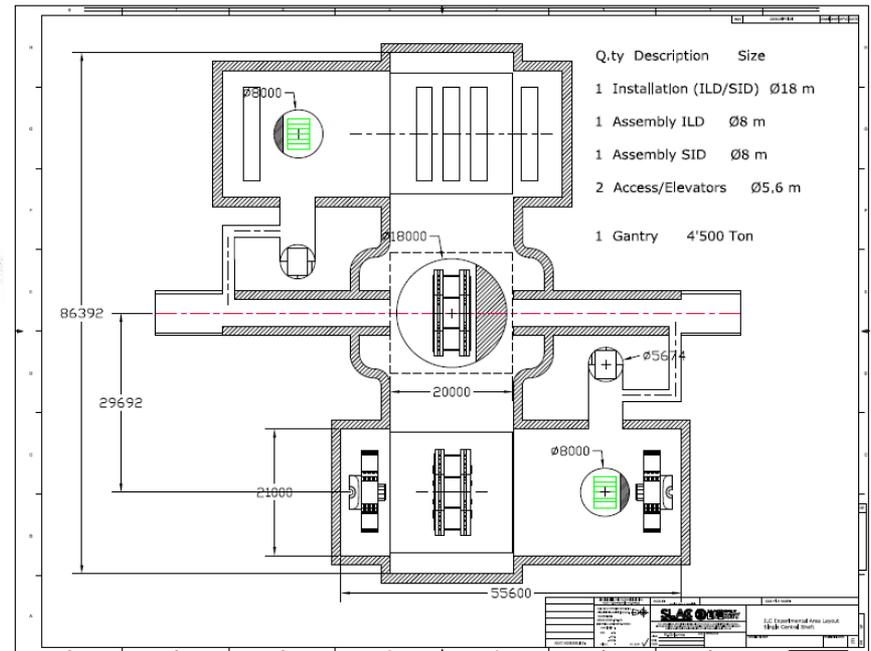
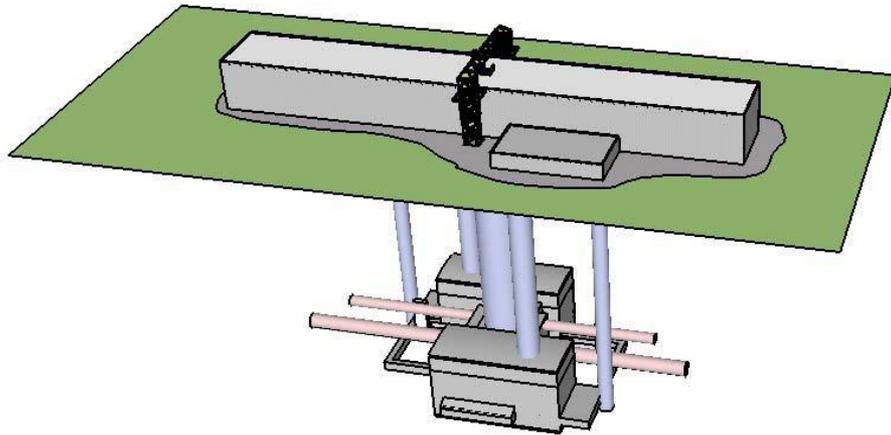
# Vertical Shaft Access



# Detector Hall Design

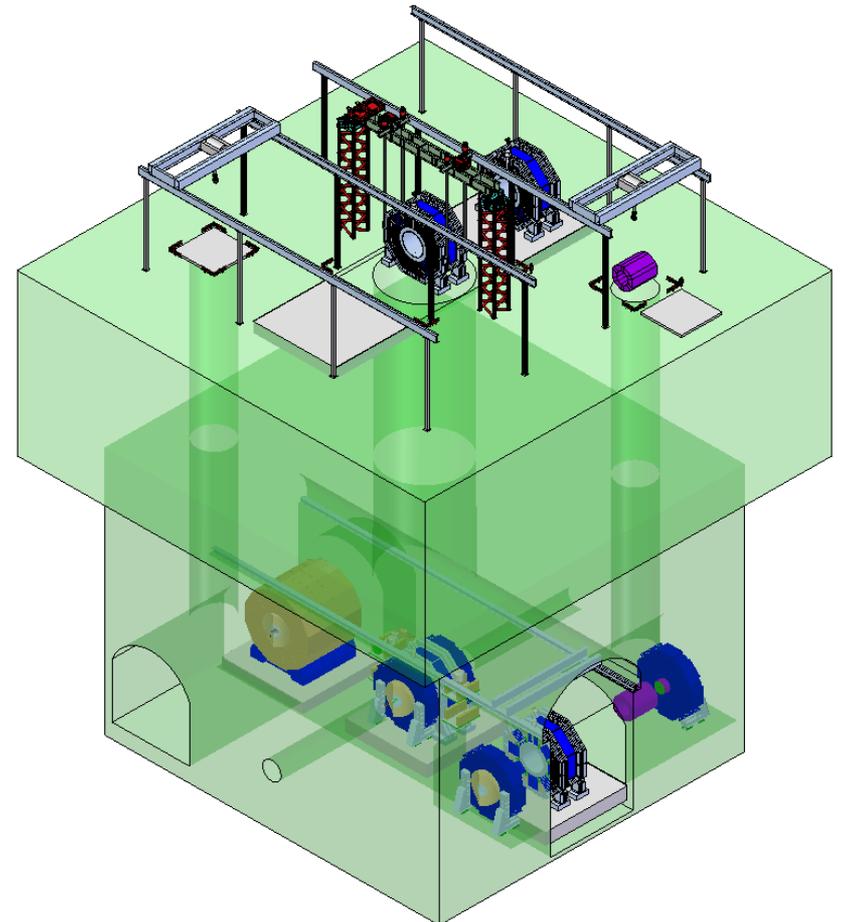
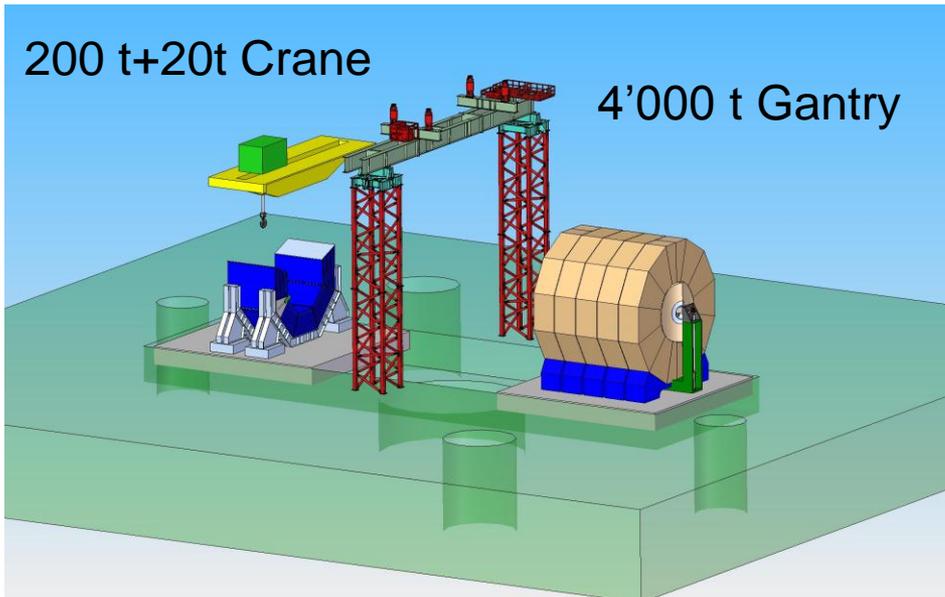
Five shafts Layout : single large shaft above the IP, two smaller shafts on the alcoves, two shafts for personnel access.

Cost optimization vs. features, like IP commissioning without detectors.

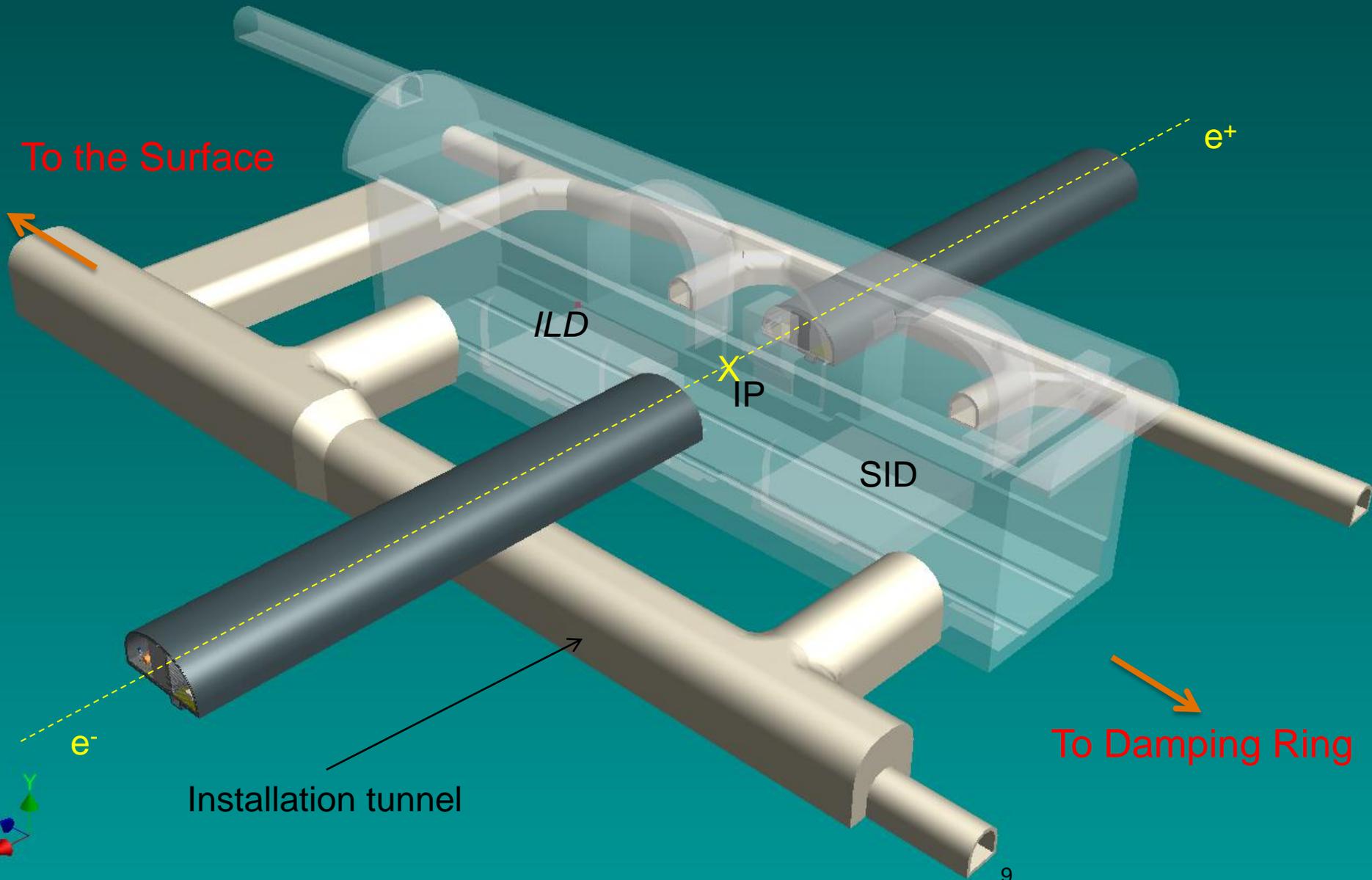


# Surface assembly *a la* CMS

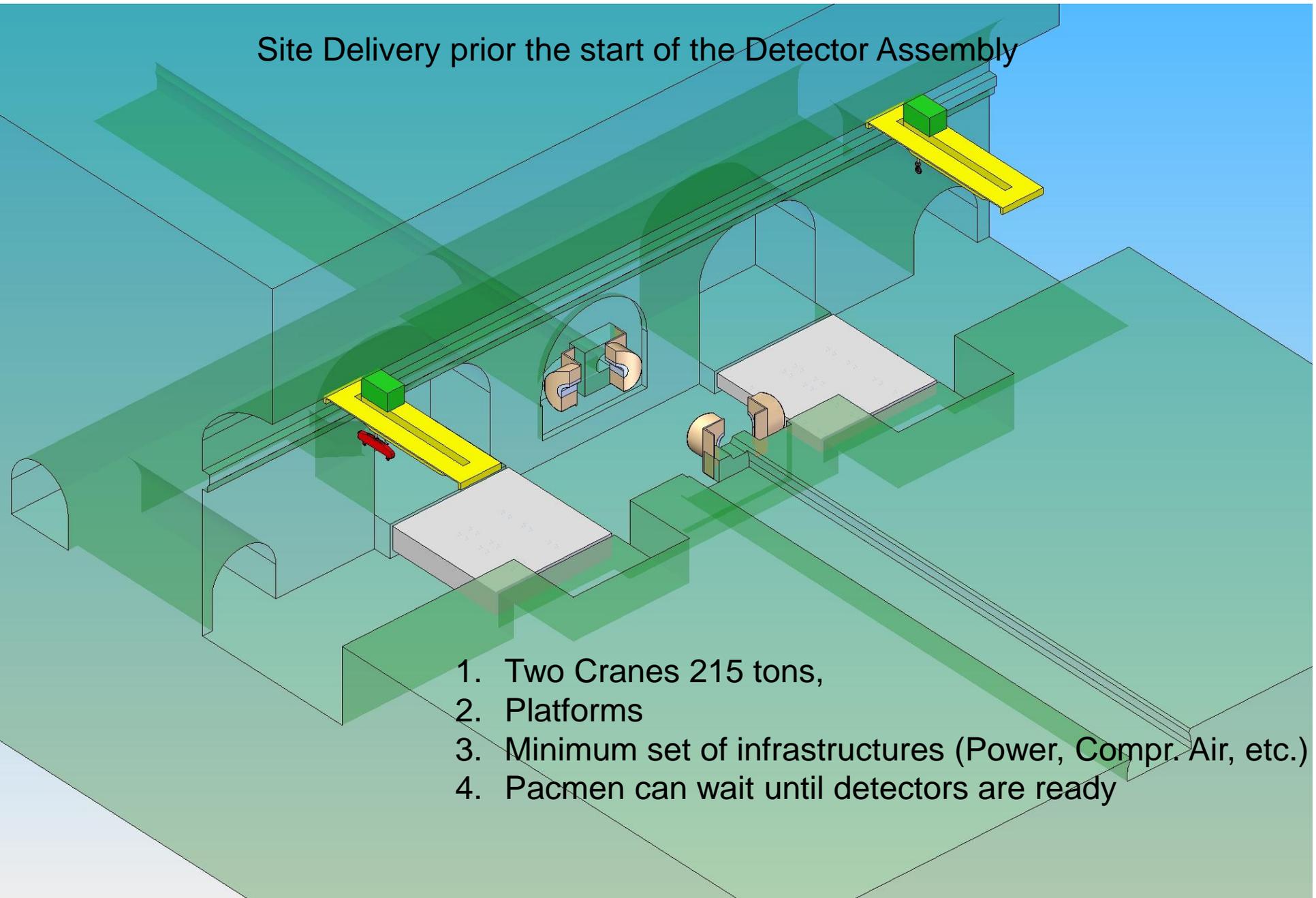
1. Assembly of Iron Doors+Barrel on surface
2. Commissioning of the magnet on surface
3. Large capacity gantry



# Detector Hall, Japanese Mountain Site

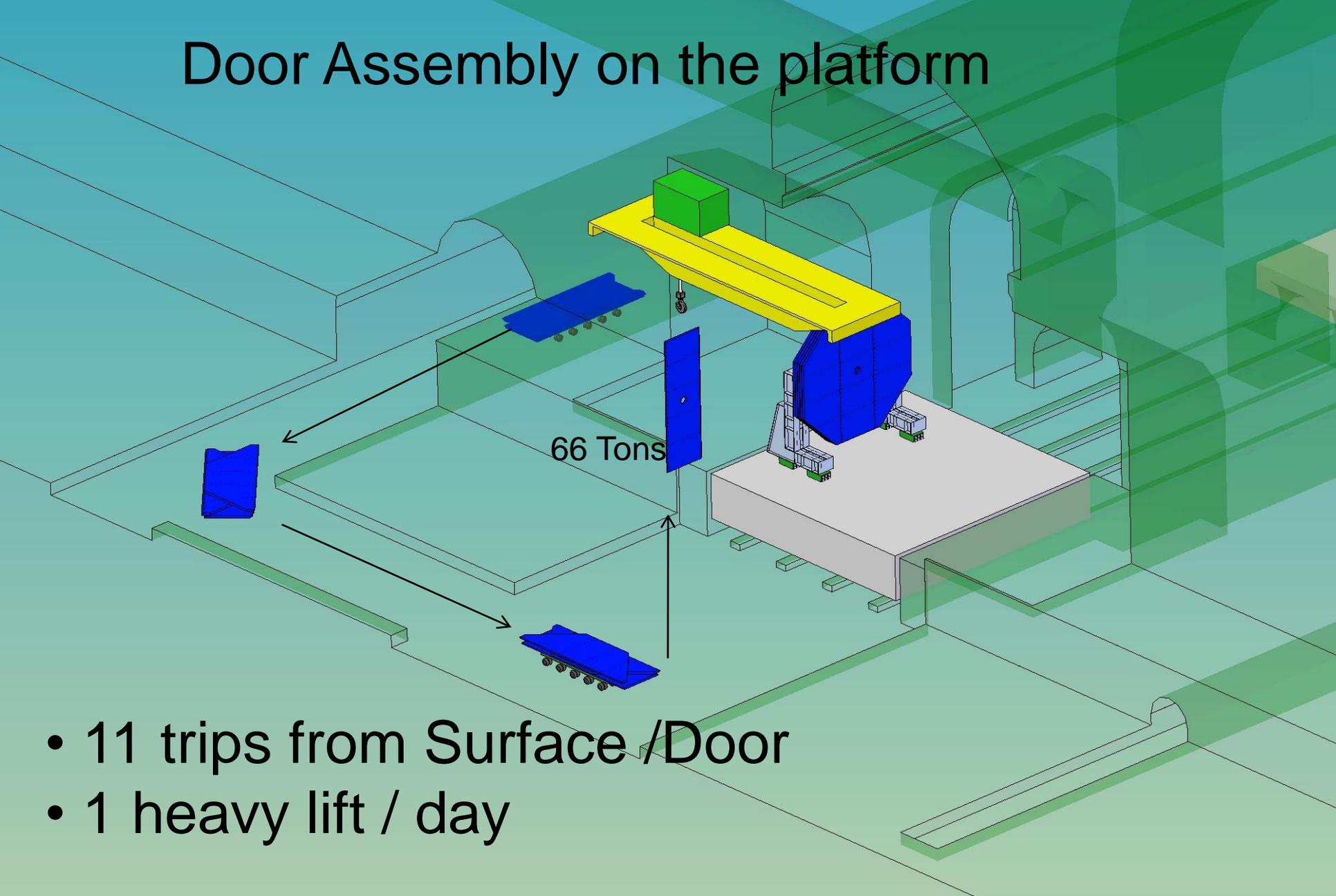


## Site Delivery prior the start of the Detector Assembly

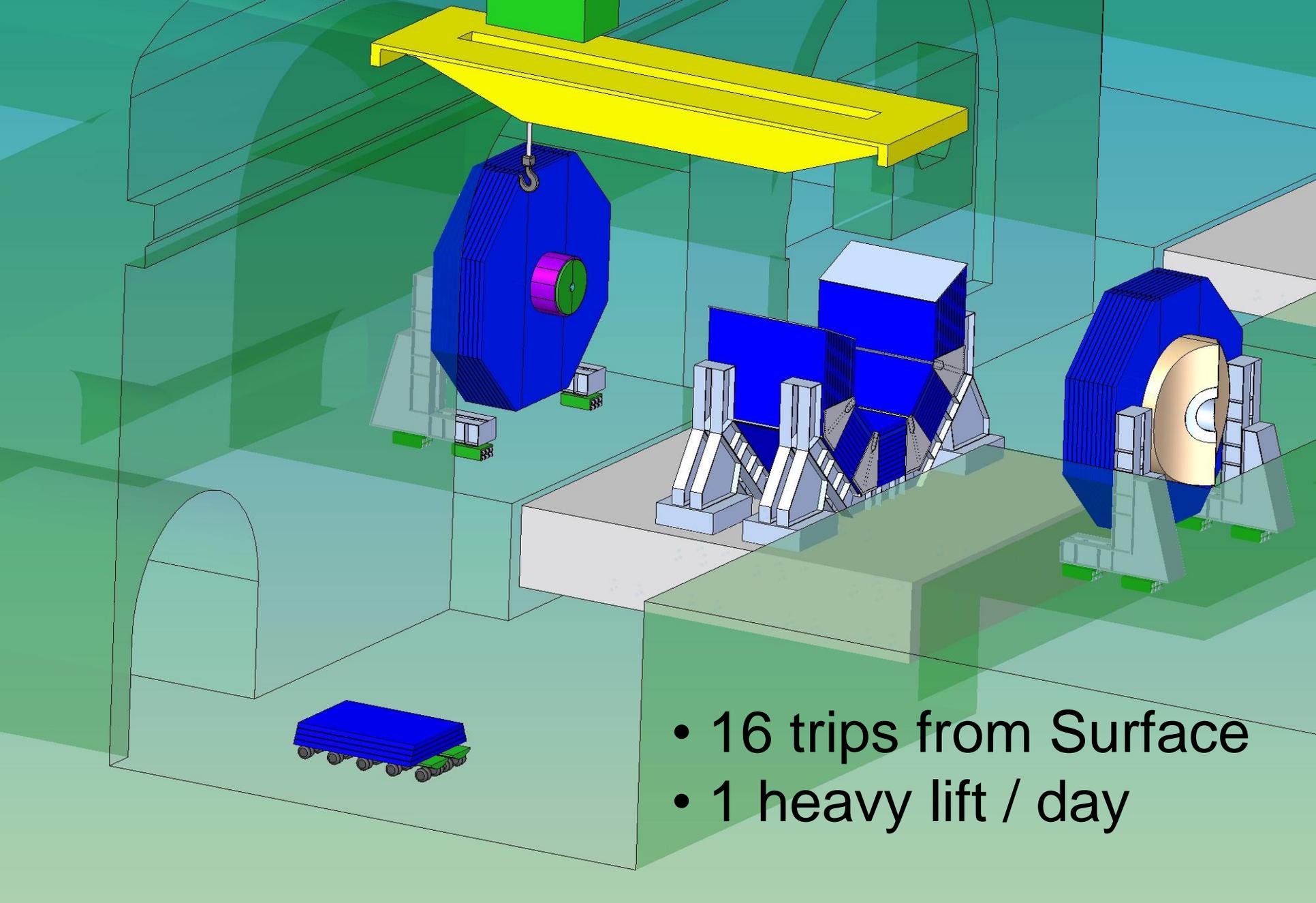


1. Two Cranes 215 tons,
2. Platforms
3. Minimum set of infrastructures (Power, Compr. Air, etc.)
4. Pacmen can wait until detectors are ready

# Door Assembly on the platform

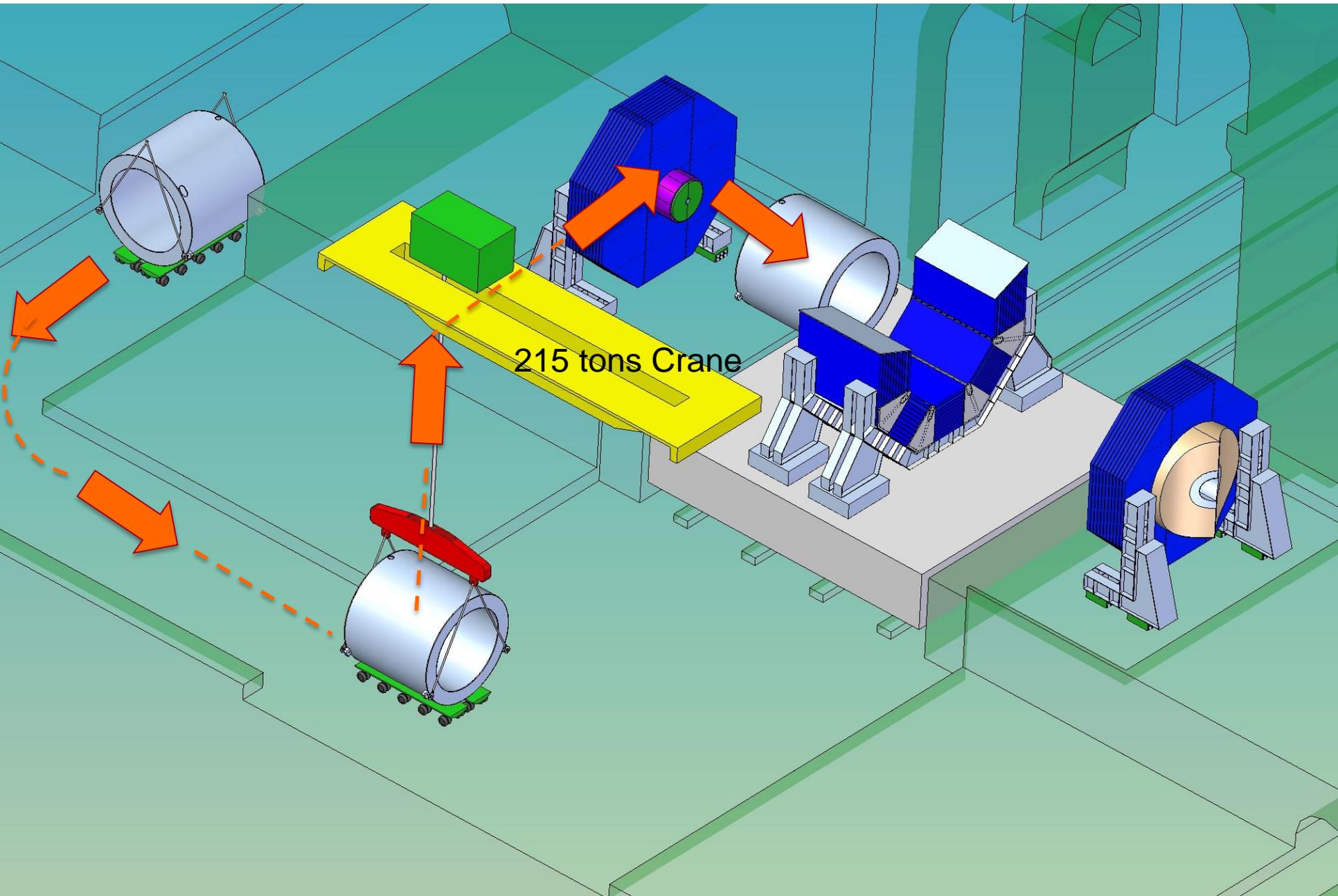


- 11 trips from Surface /Door
- 1 heavy lift / day

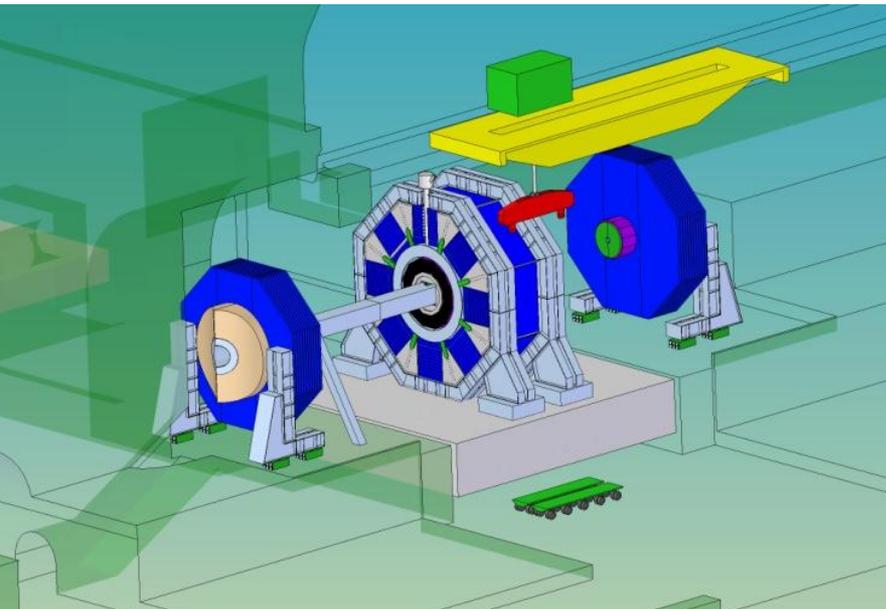
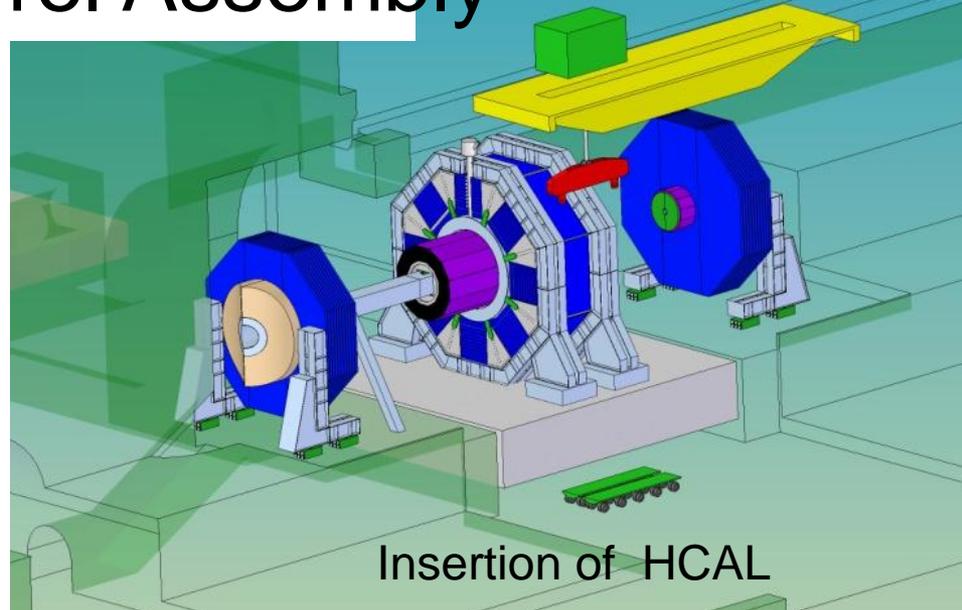
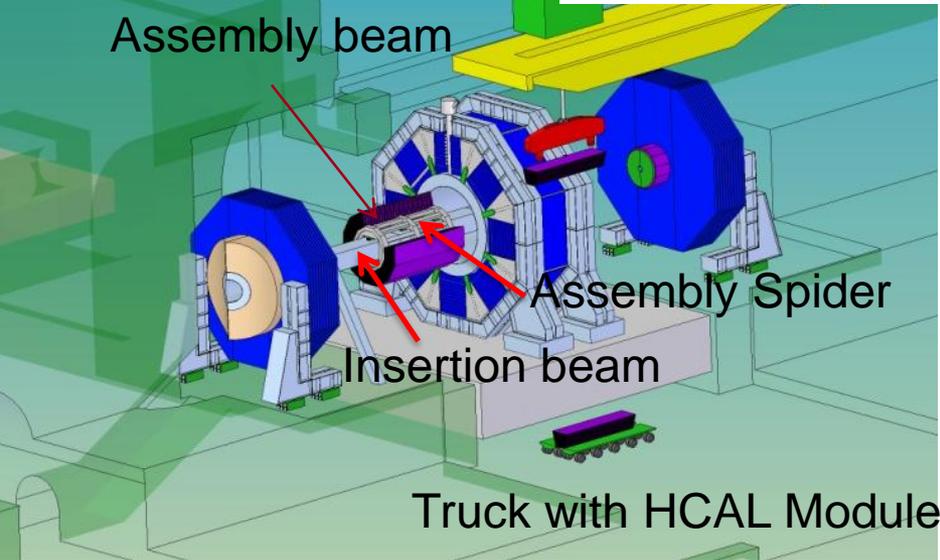


- 16 trips from Surface
- 1 heavy lift / day

# Solenoid Installation



# HCAL Barrel Assembly



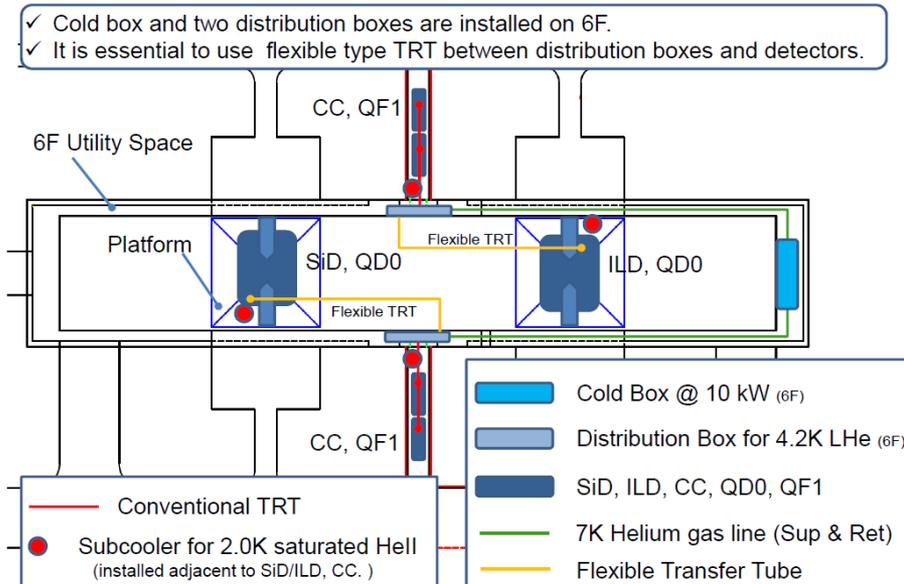
SLD, Liquid Argon Calorimeter  
Assembly Beam

# Cryogenic Layout : Two options

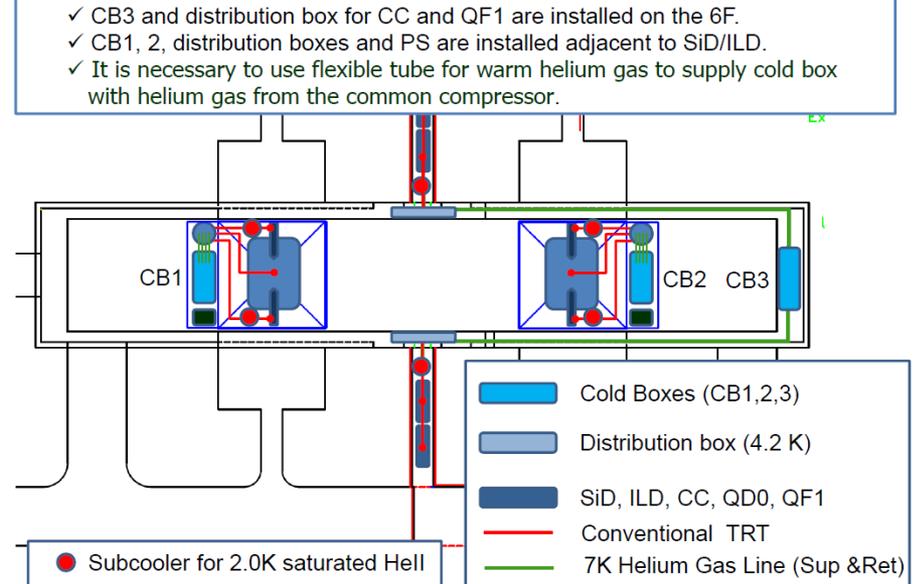
Plan A : Cold Boxes are stationary. Cold Transfer lines to each detector. **Reliability for push-pull. Not off-the-shelf.**

Plan B : Cold Boxes on the platform. Warm Transfer lines to each cold box. **Vibrations, fringe field effects, space**

**Plan-A: Layout of cryogenic equipment**

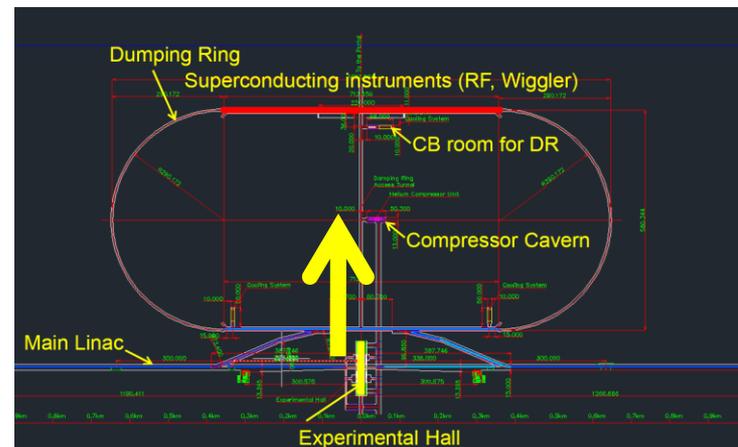
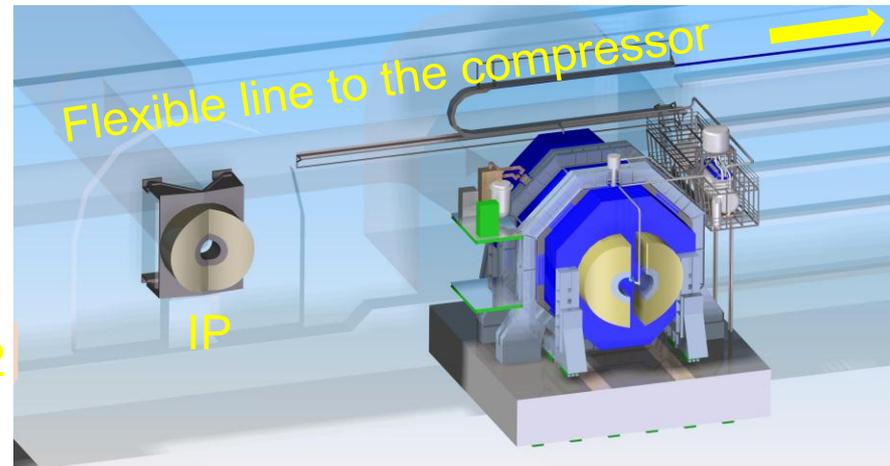
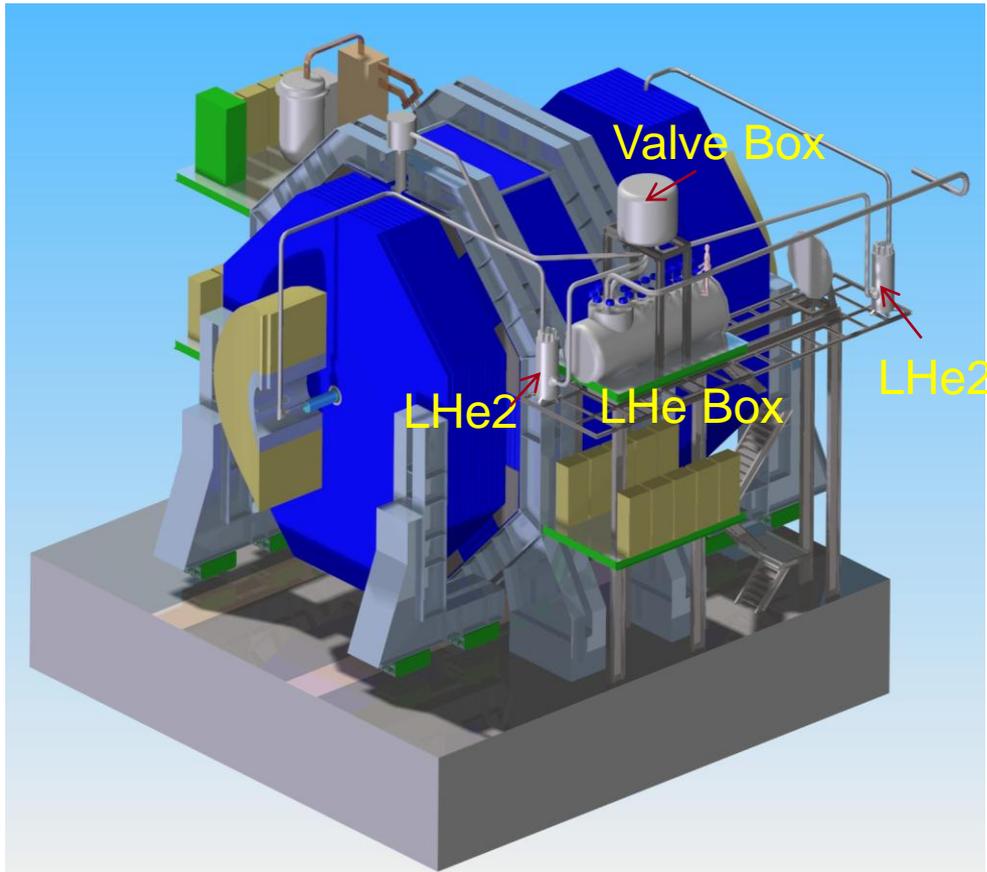


**Plan-B: Layout of cryogenic equipment**

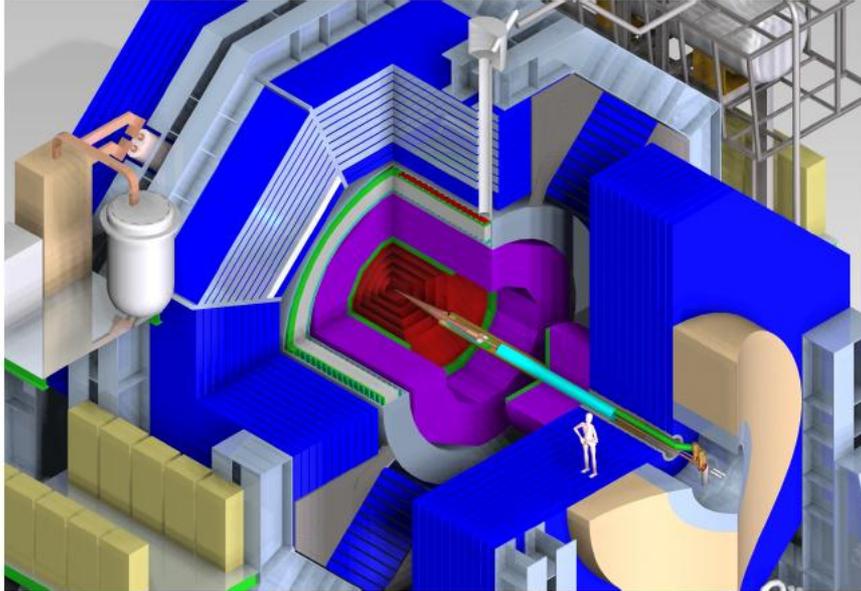


# Integration of the Cryogenic plant on the platform

Main LHe refrigerator and LHe2 for the QD0's above level on metallic structure.



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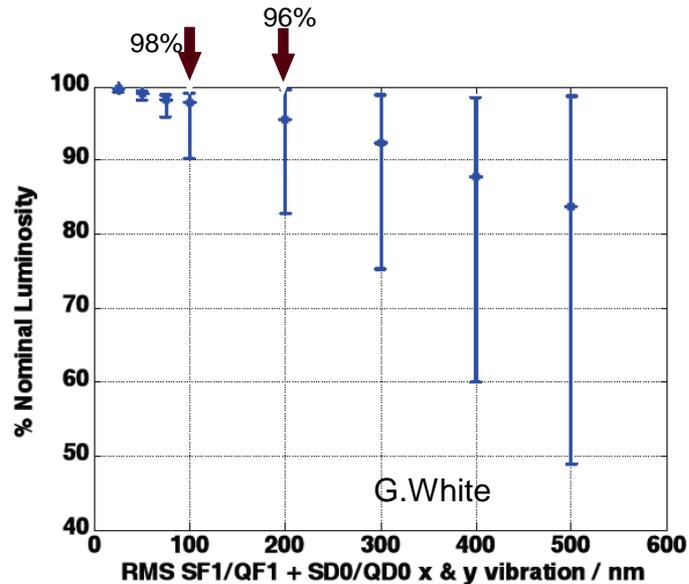
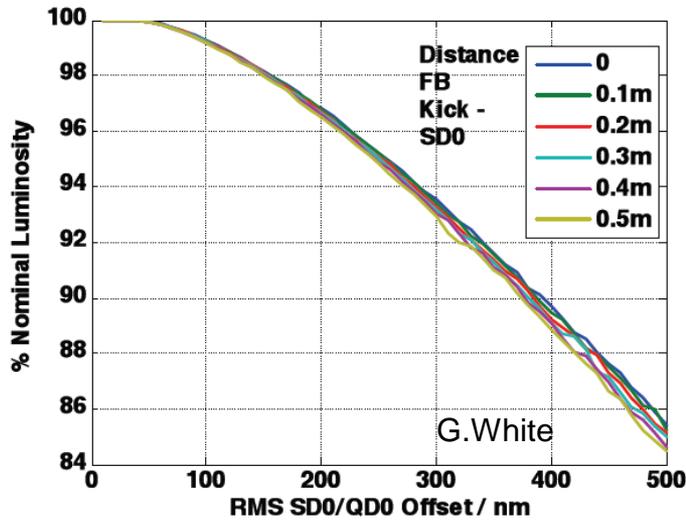
#### 7.5.2 Fringe Fields and Magnetics

# Vibrations

Most acute luminosity loss mechanism due to relative jitter of final focusing magnet elements : Ground Motion and Mechanical vibration sources

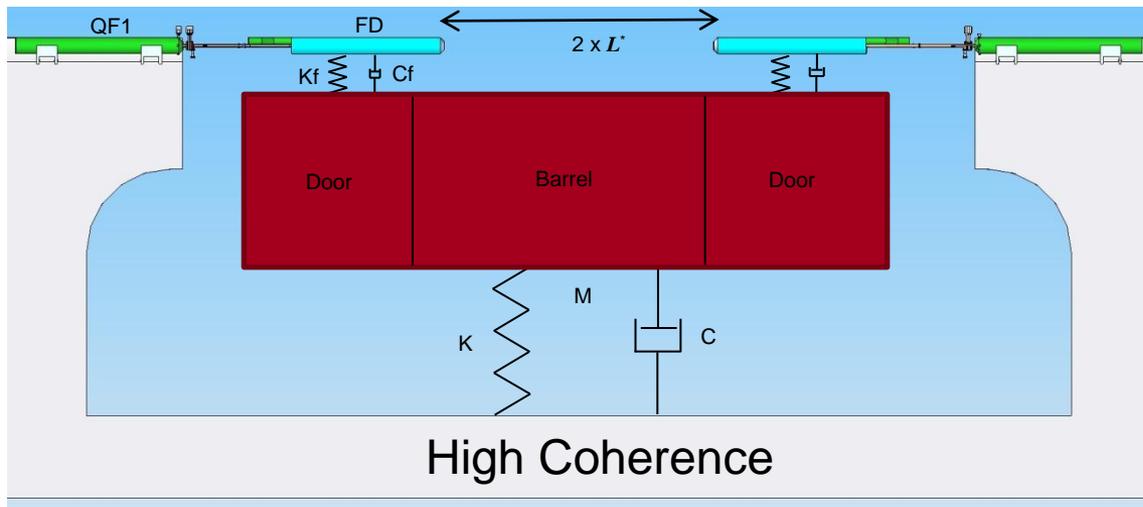
ILC has Active Fast Feedback based on beam trajectory after collision

Max. Integrated displacement: 50 nm > 5 Hz



Lumi loss due to beam offset in SD0 (beamsize growth) and IP misalignment of beams

# Full Dynamic Model ground-to-QD0

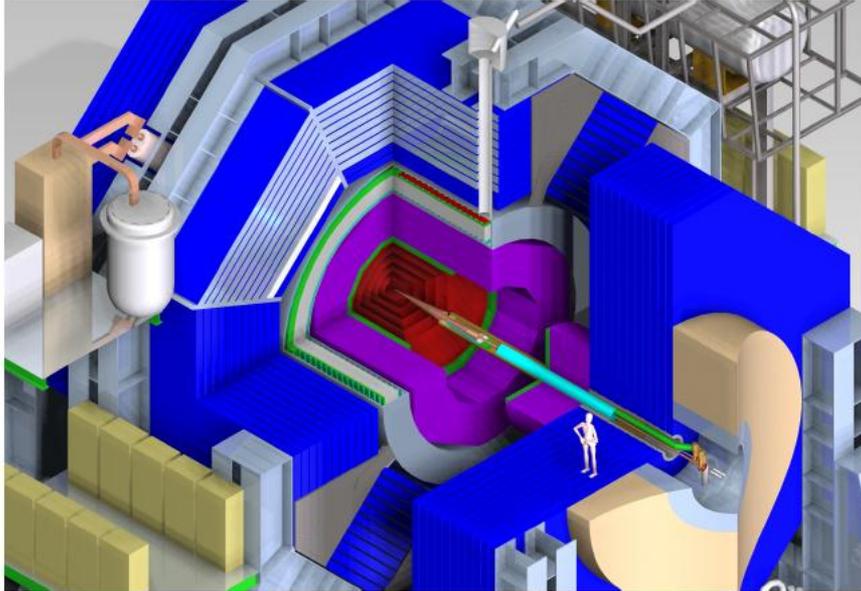


see C.Collette's talk in this workshop at the Joint BDS/MDI.....

Other Vibrations Study activities :

- Ground vibrations (Correlation) measurements at LHC, Point4
- Experimental vibrations of the CMS Platform
- Benchmark of FEA with concrete reinforced structure
- Ground geology modeling

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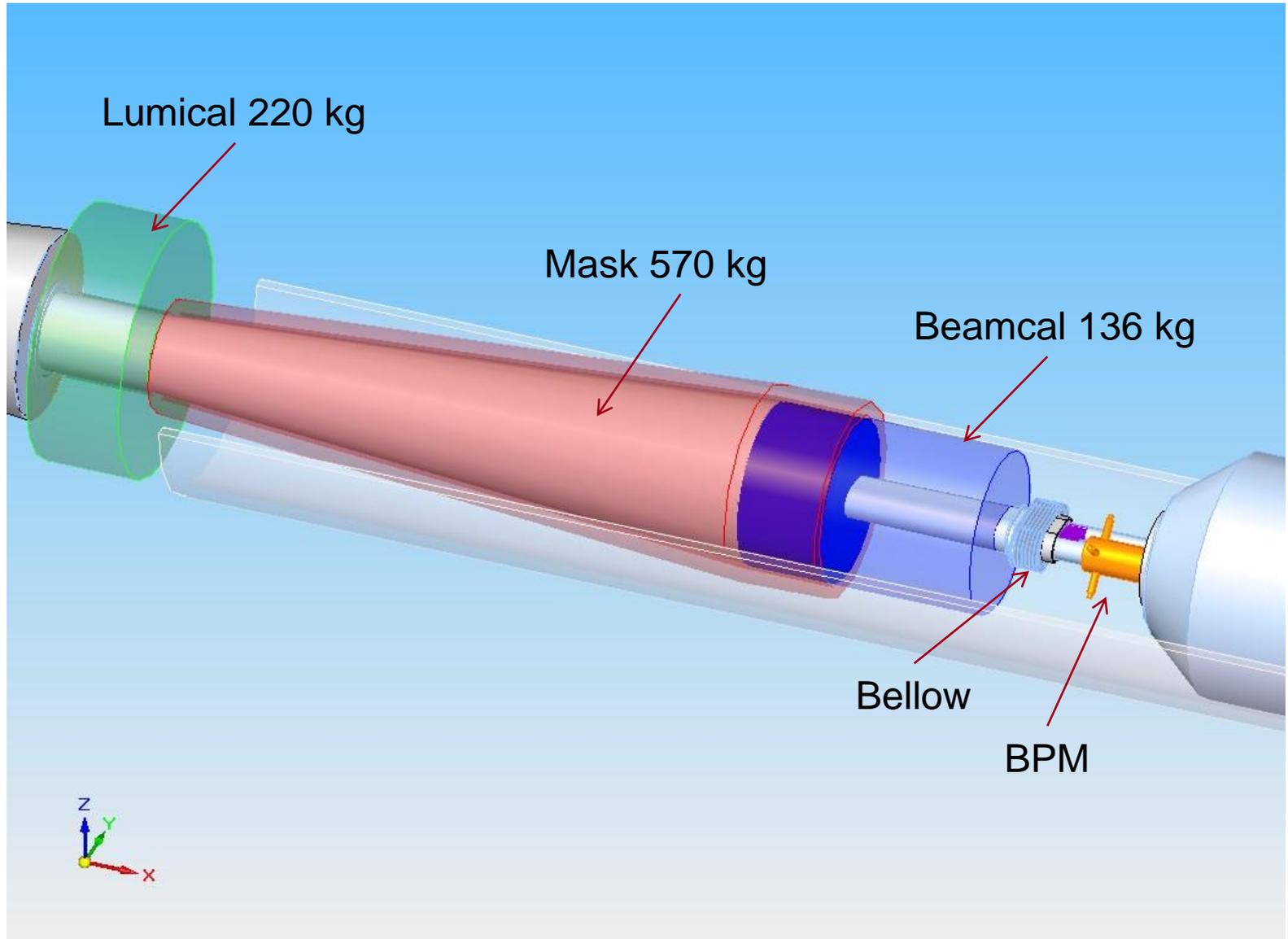
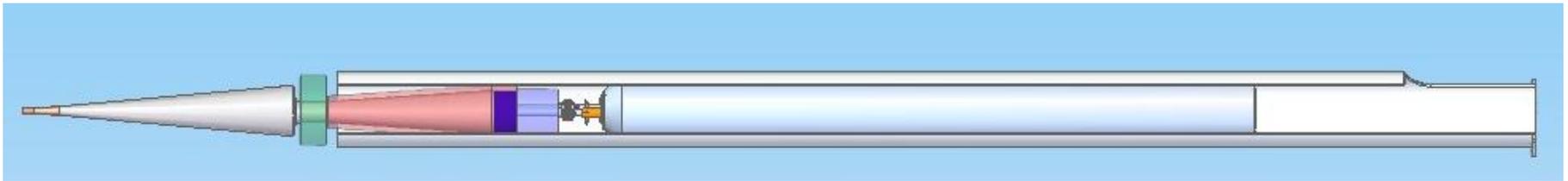
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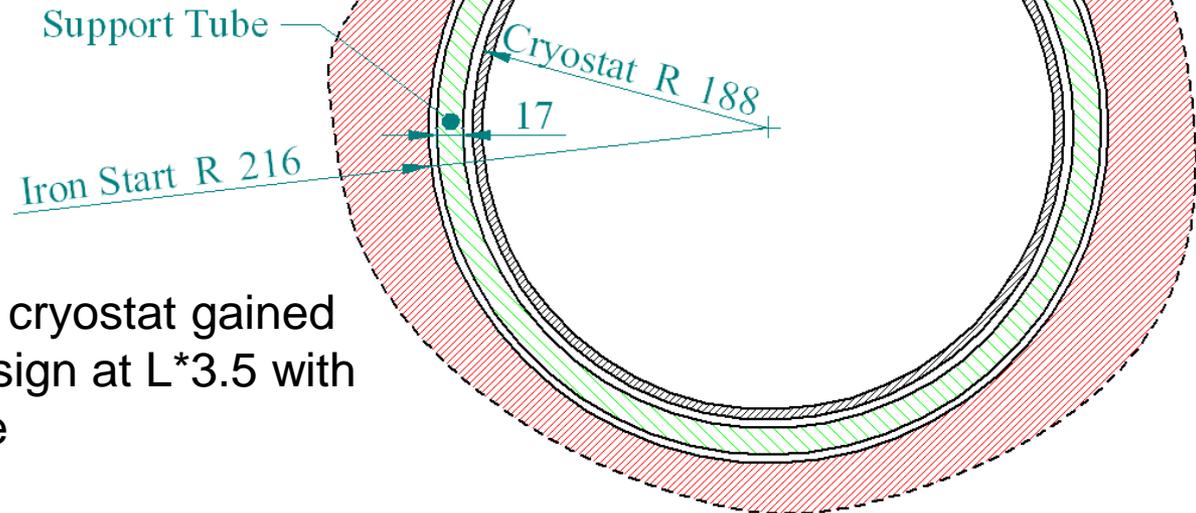
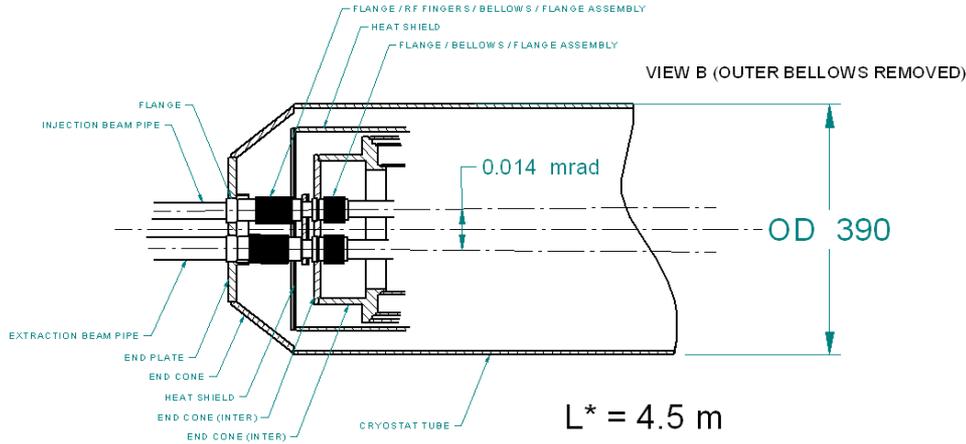
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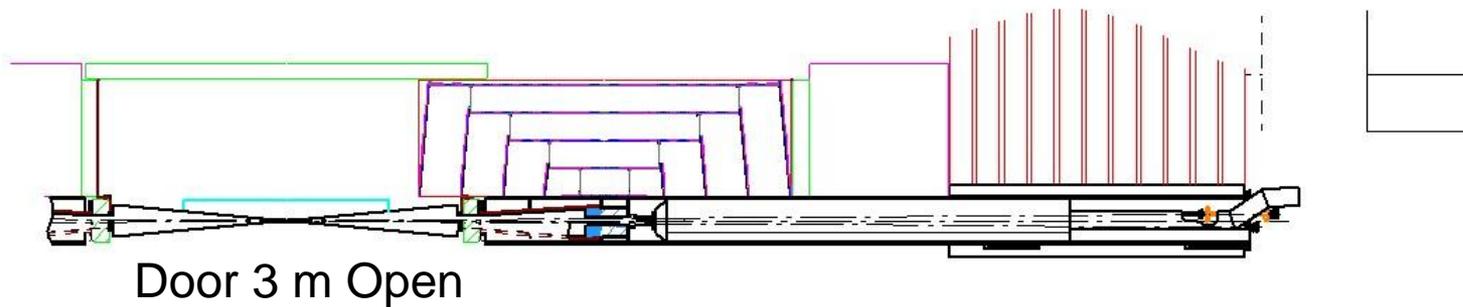
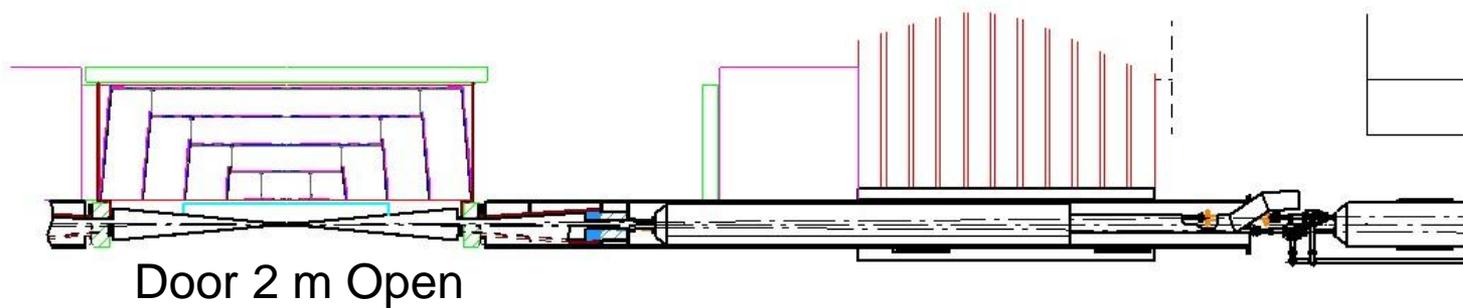
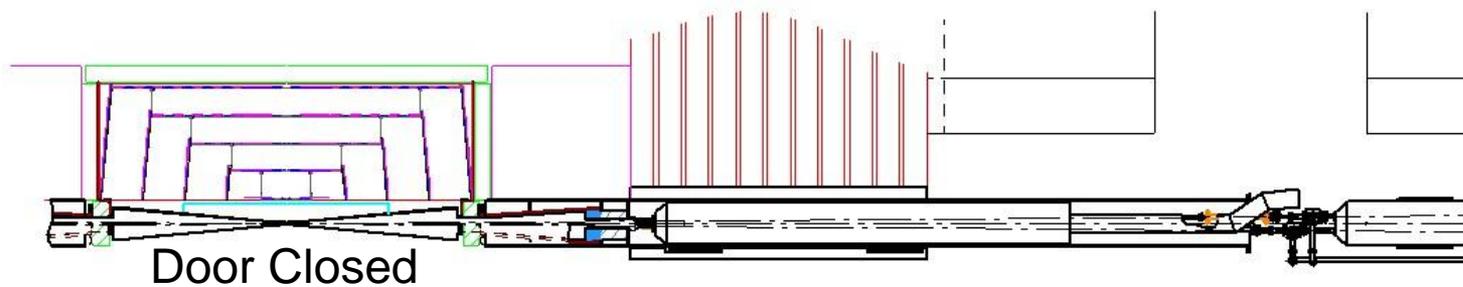
# Space Requirements

Current QD0 Prototype is designed for  $L^* 4.5 \text{ m}$



14 mm reduction of the QD0 cryostat gained moving the present QD0 design at  $L^* 3.5$  with the 14mrad crossing scheme  
(1 m x 14 mrad = 14 mm)

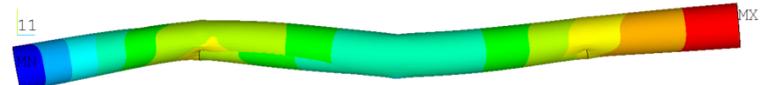
$L^* 3.5 \text{ m}$  cross section



# Displacements (mm)

1 NODAL SOLUTION  
 STEP=1  
 SUB =1  
 TIME=1  
 UY (AVG)  
 RSYS=0  
 DMX =.116897  
 SMN =-.116837  
 SMX =.034659

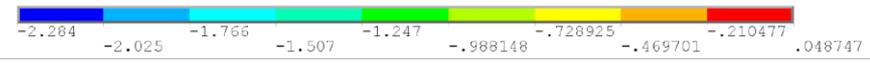
TIME=1  
 UY (AVG)  
 RSYS=0  
 DMX =2.286  
 SMN =-2.284  
 SMX =.048747



Door Closed, Max sag = 0.1 mm

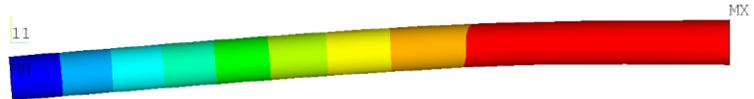


Door Open 2 m, Max sag = 2.3 mm

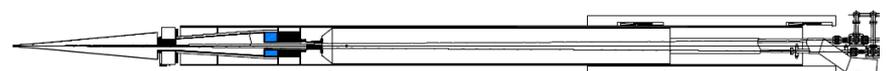
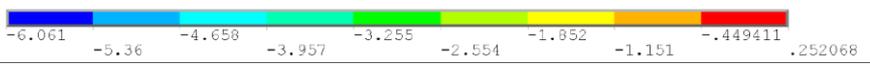


1 NODAL SOLUTION  
 STEP=1  
 SUB =1  
 TIME=1  
 UY (AVG)  
 RSYS=0  
 DMX =6.065  
 SMN =-6.061  
 SMX =.252068

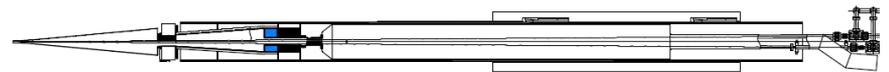
MAR 19 2012  
17:02:32



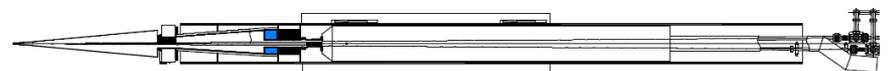
Door Open 3 m, Max sag = 6 mm



Door Open 3 m

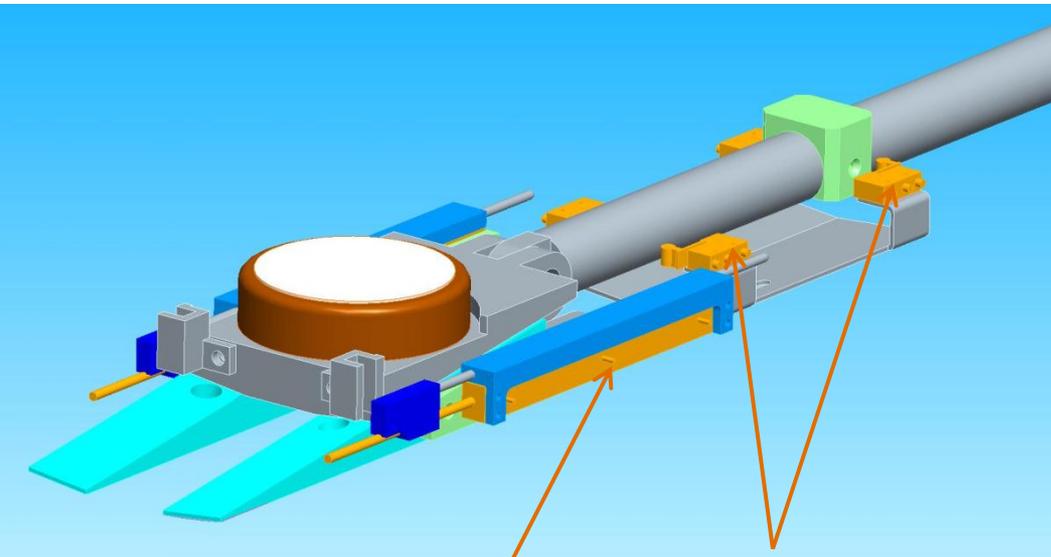
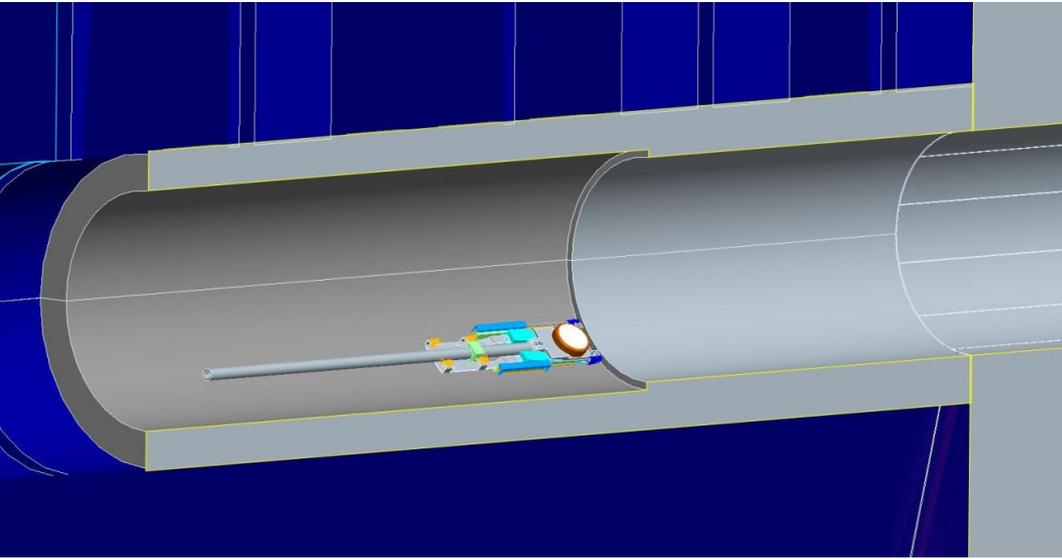


Door Open 2 m



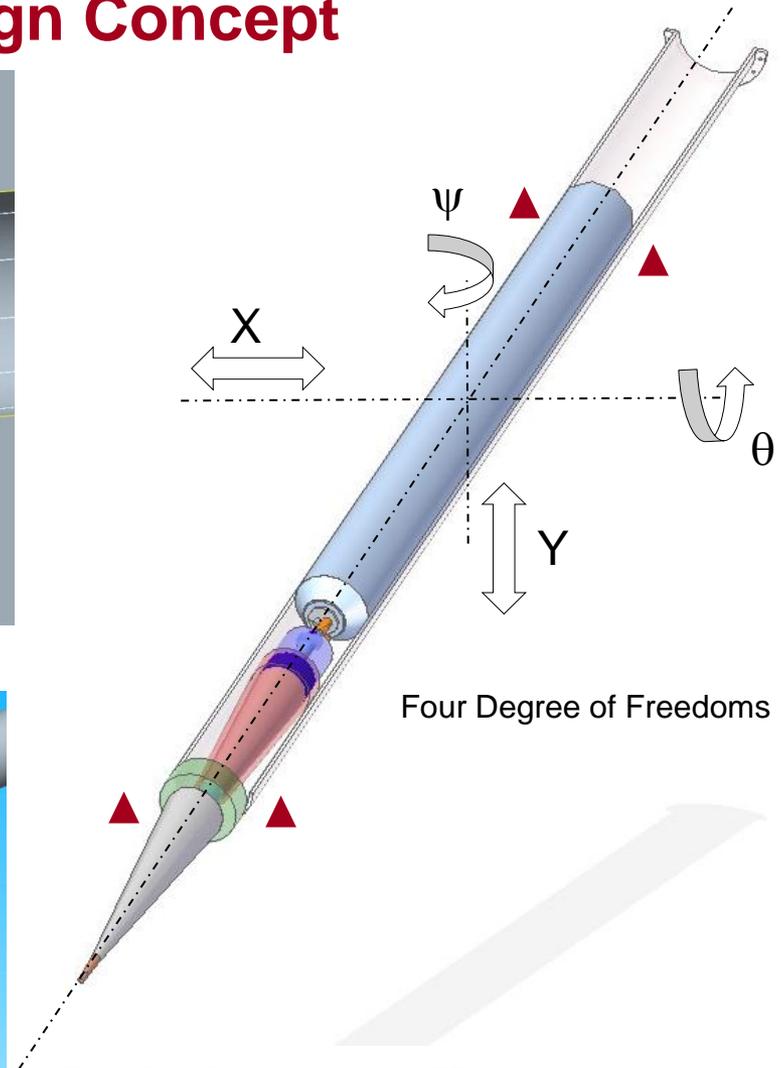
Door Closed

# QD0 Wedge Design Concept



Potentiometer

Limit  
Switches



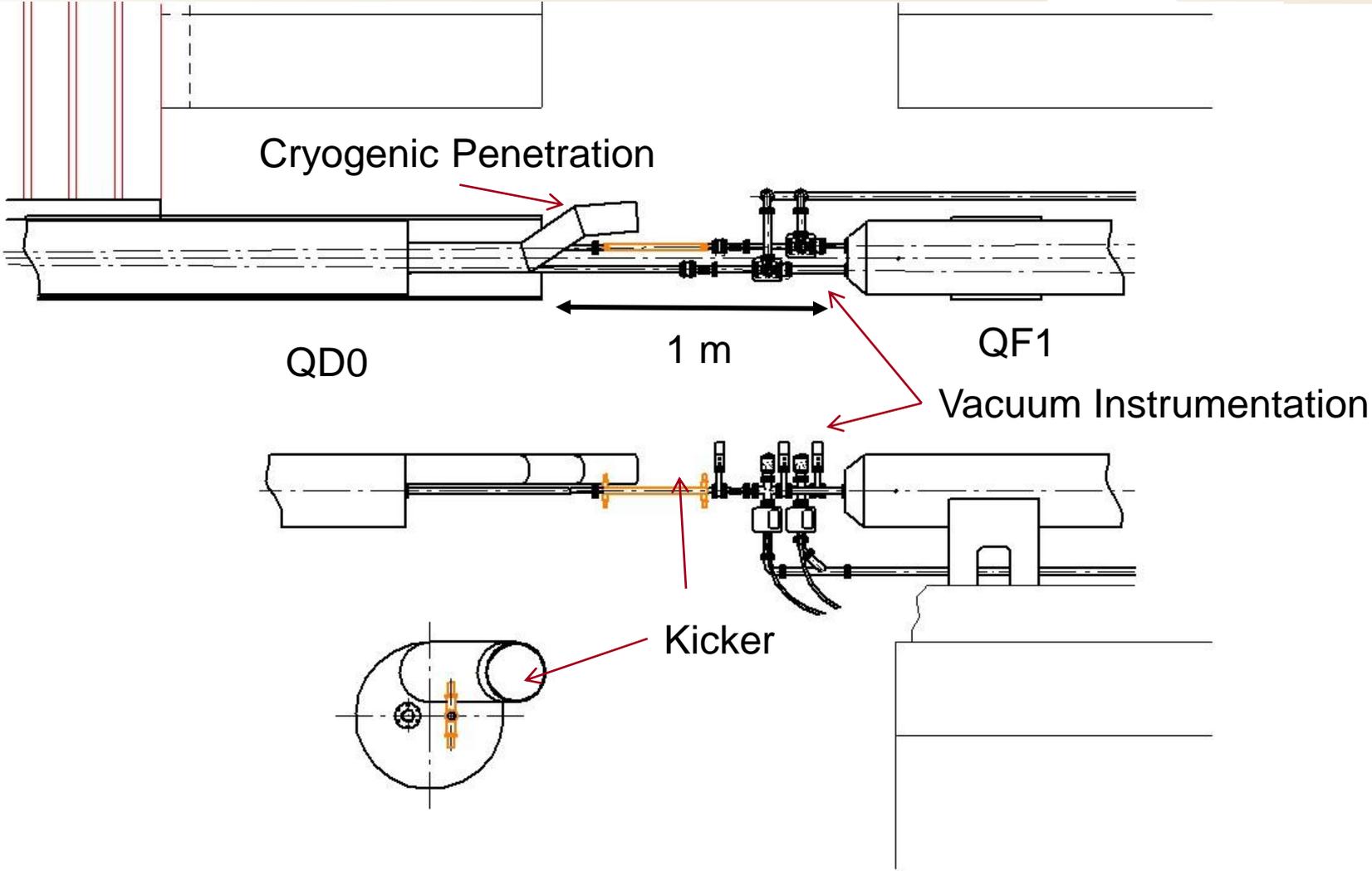
Four Degree of Freedom

Total Pad Travel as is = .475in

Height of pad and distance of displacement will be changed pending analysis on sagging of beam line.

Conceptual design only at this point

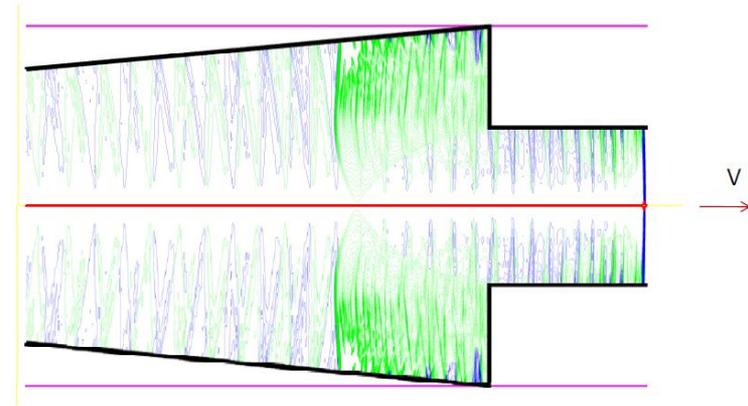
# Interface QD0-QF1: Critical for Fast&Reliable Push-Pulls



# HOM heating at the IP and in QD0 (S.Novokhatski, SLAC)

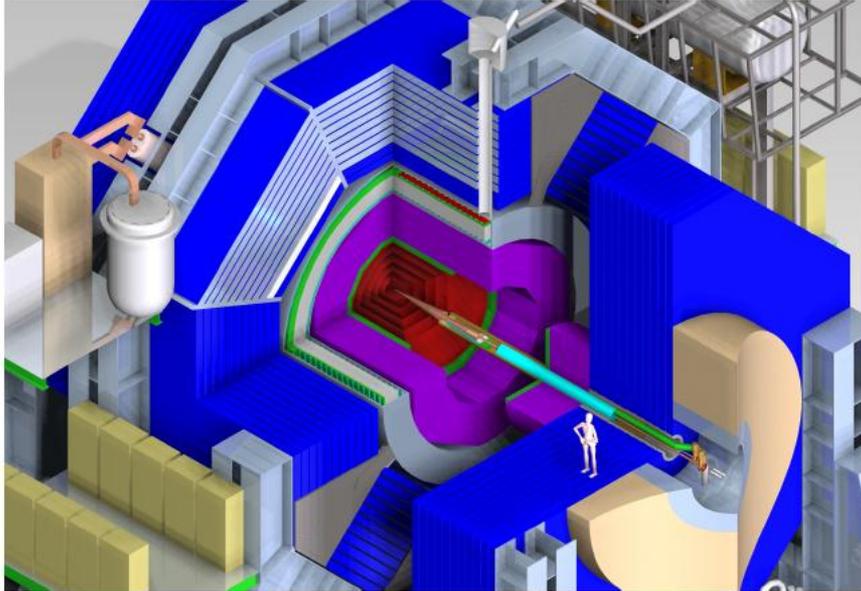
- *Beam fields*
- *Wake potentials and loss power*
- *Trapped and propagating modes*
- *Frequency spectrum*
- *Resistive wake fields*
- *Total power loss*

Example of Wakefields



- The amount of beam energy loss in IR is very small.
- Spectrum of the wake fields is limited to 300 GHz
- Average power of the wake fields excited ~30 W nominal (6 kW pulsed)
- In the QD0 region the additional losses are of 4W (averaged) .
- BPMs and kickers must be added.

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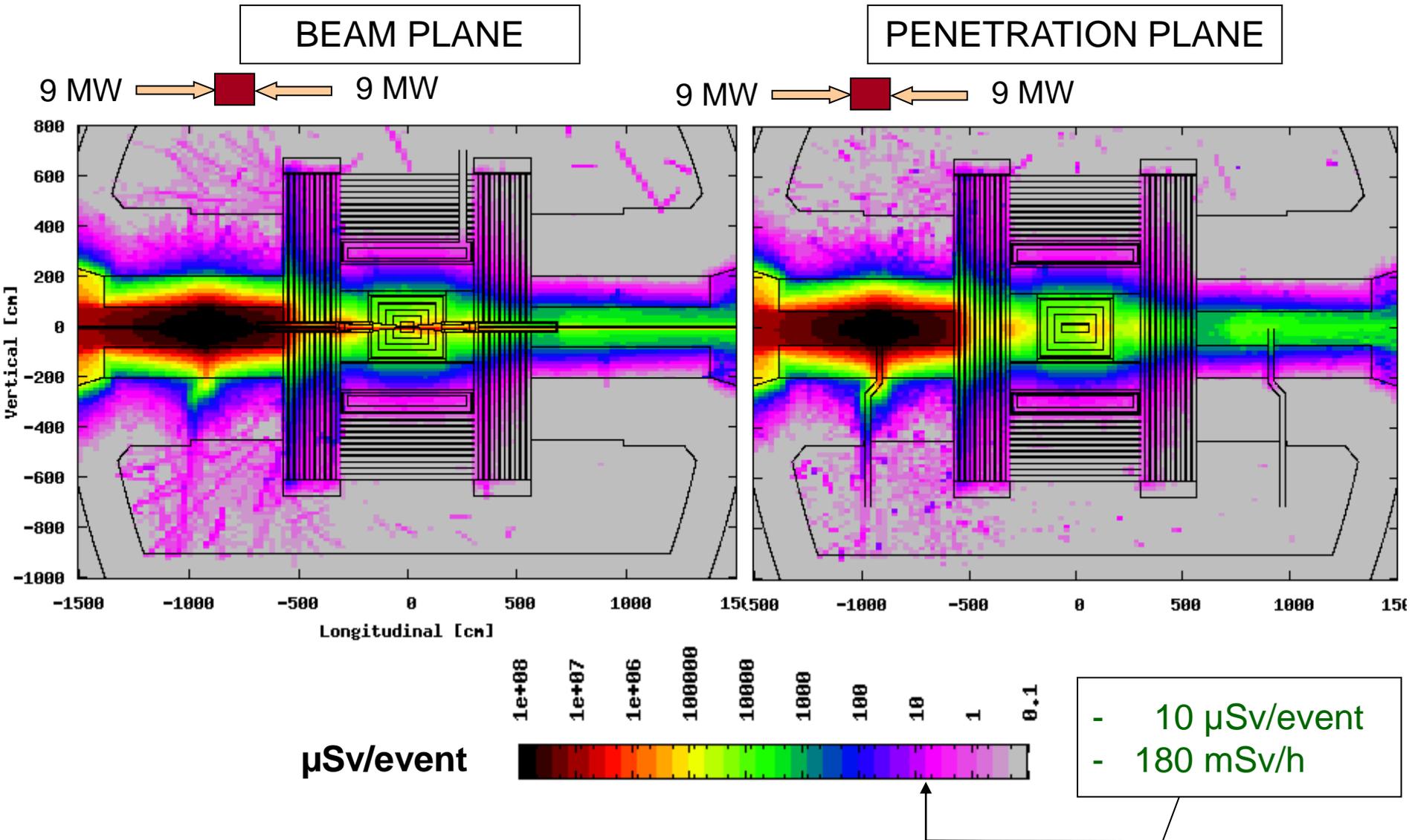
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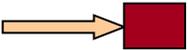
# 20 R.L. Cu target in IP-9 m. Large pacman.

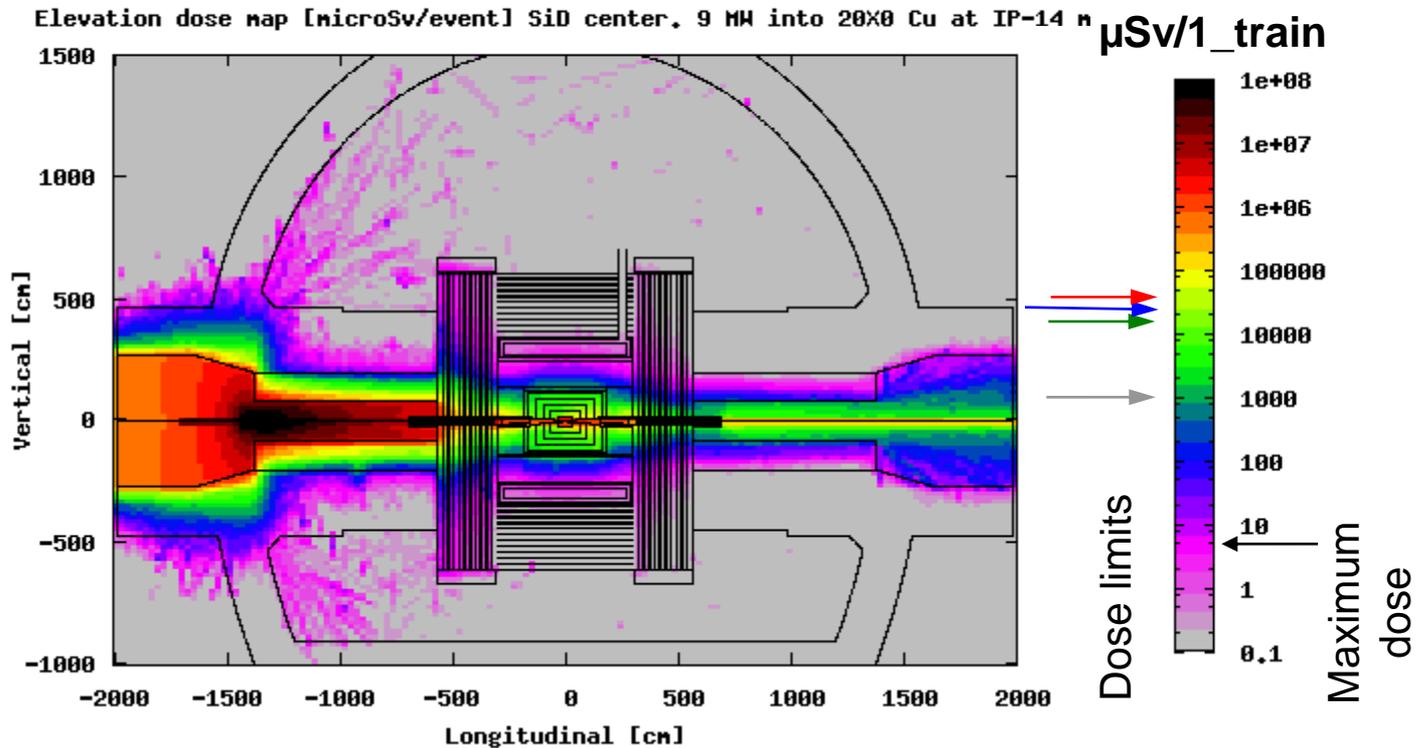
M.Santana, SLAC



# 20 R.L. Cu target in IP-14 m. Large pacman.

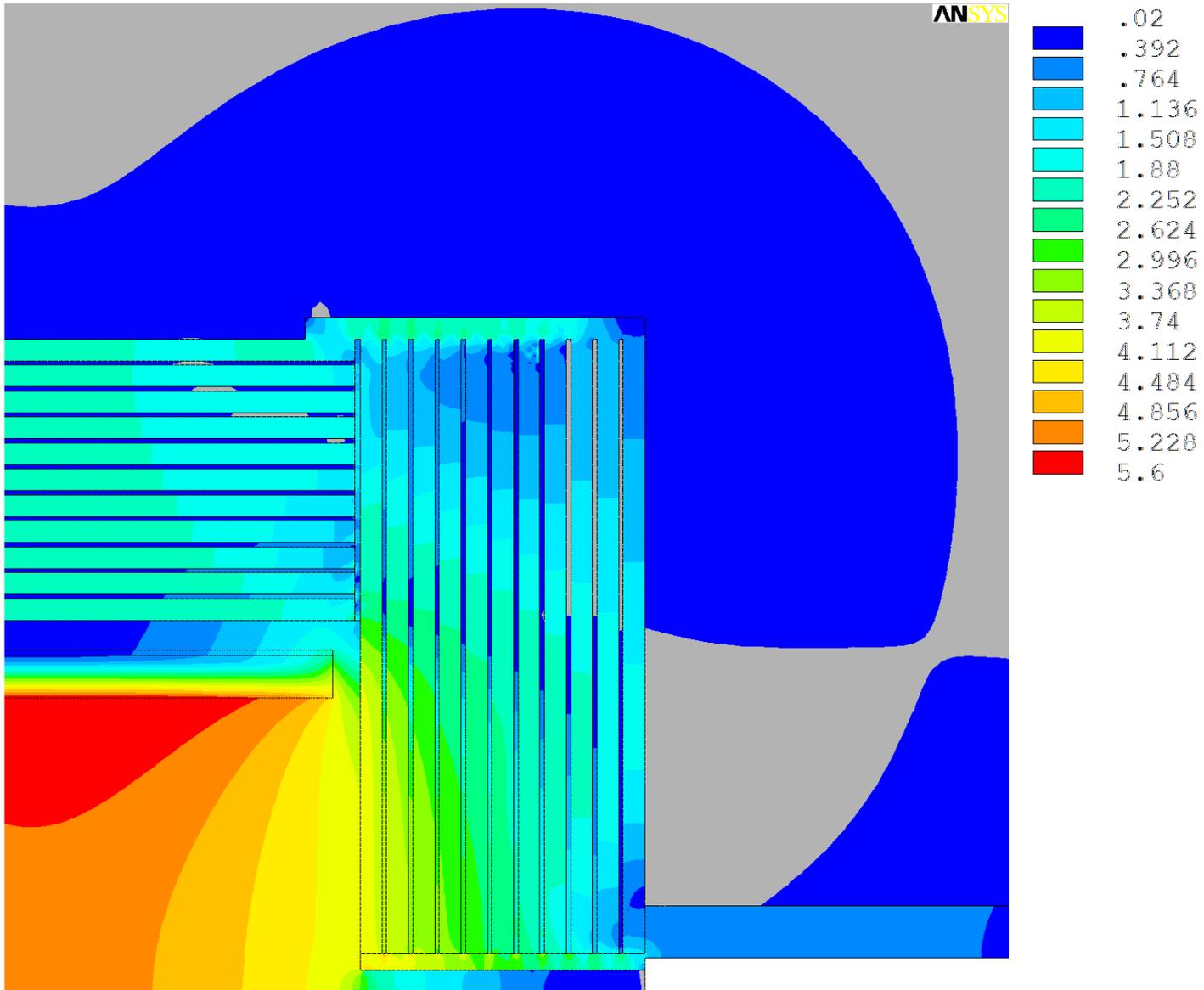
M.Santana, SLAC

9 MW 



- The maximum **integrated dose** per event is  $\sim 8 \mu\text{Sv} \ll 30 \text{ mSv}$
- The corresponding peak **dose rate** is  $\sim 140 \text{ mSv/h} < 250 \text{ mSv/h}$

# Fringe Field for a quadrant view of SiD Cut off @ 200 Gauss



# What next:

## A list of MDI and Integration issues need further development

### **Machine – Detector Integration**

- Alignment of detector to beam line after transport on platform.
- Platform design progress.
- Surface Assembly Facilities.
- Local Control Rooms.
- Interaction Region Hall utilities:
- Welding constraints: Ventilation, permits, etc.
- Local machine shop.
- Detector access: Man lifts, crane baskets?

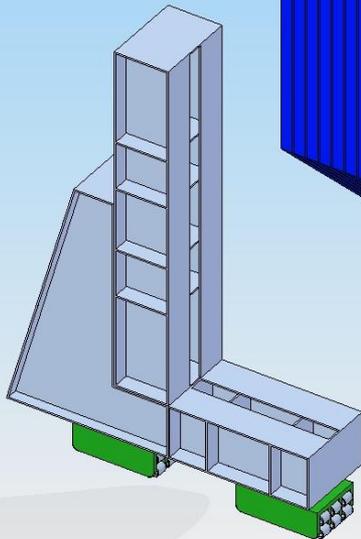
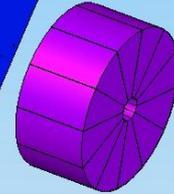
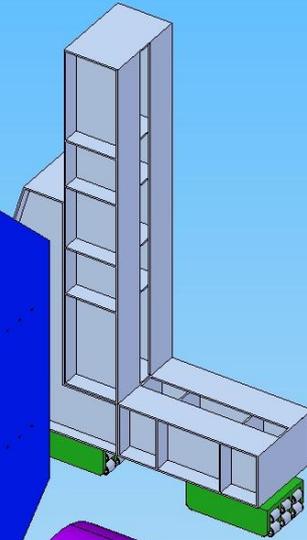
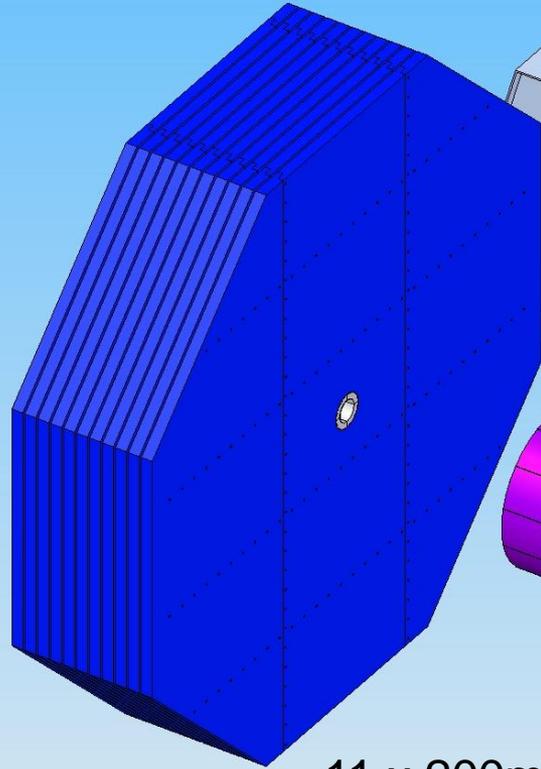
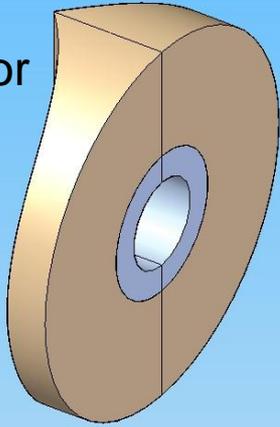
### **Detector Specific Integration**

- Iron optimization: Review:
- Detector Alignment Procedures:
- Internal Detector Services:
- Vents:
  - 1.He
  - 2.Steam? (Dump resistor)
  - 3.Other
- Detector platforms and access stairs.

# EXTRA SLIDES

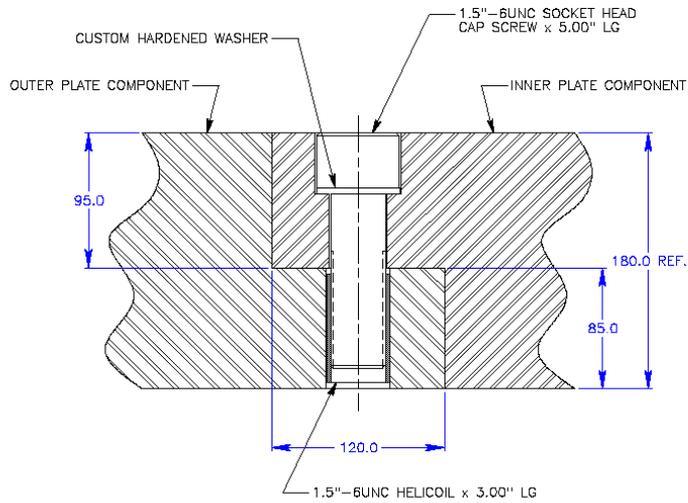
# End Door

Pacman  
on the door

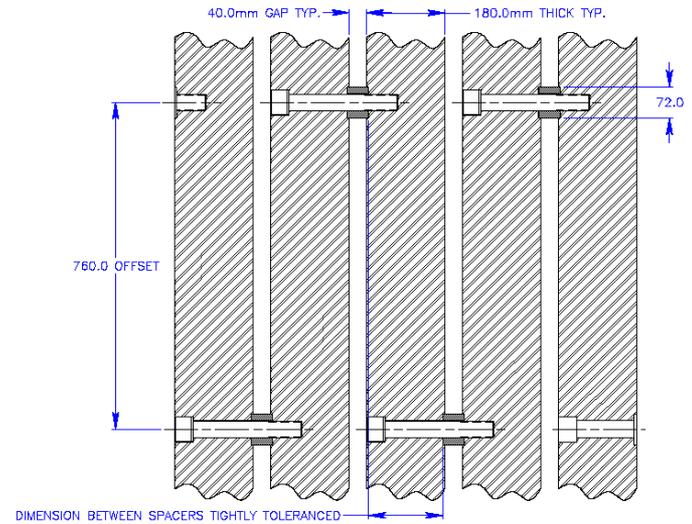


11 x 200mm Iron plates  
40mm gap

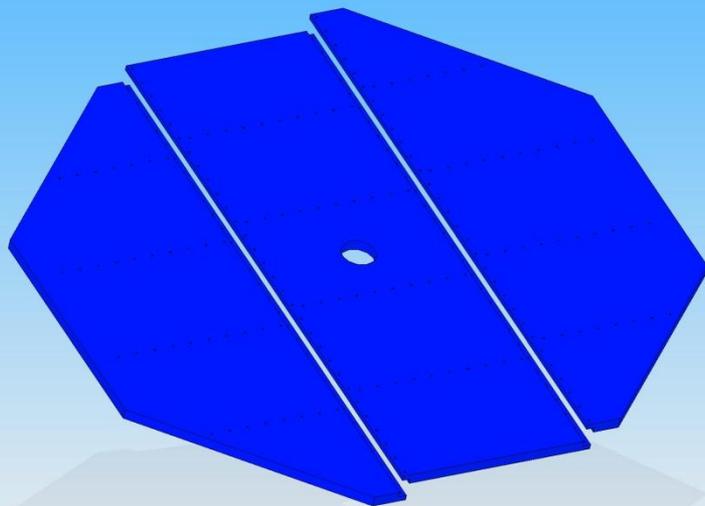
Total Mass ~ 2'300 Tons



Intraplate connections

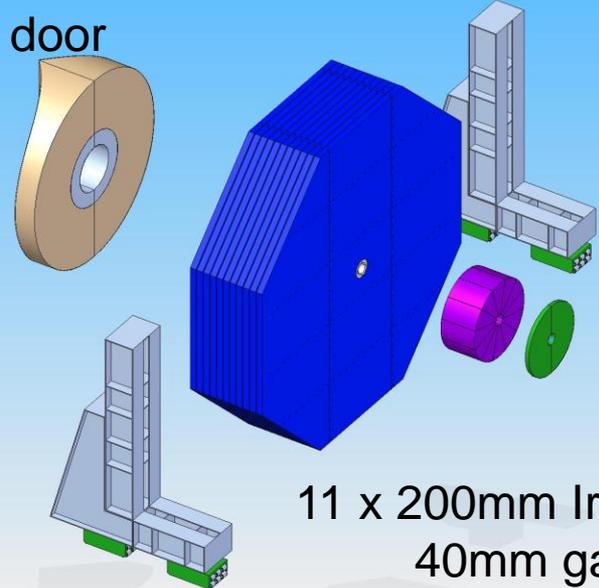


Spacer Offset



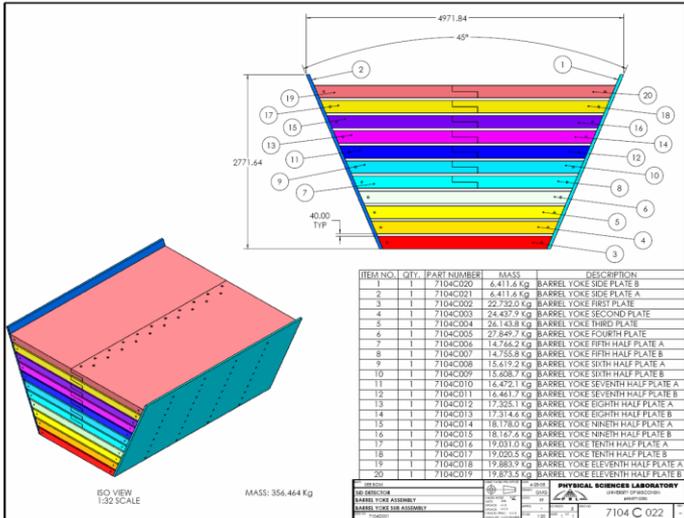
Pacman  
on the door

Total Mass ~ 2'300 Tons



11 x 200mm Iron plates  
40mm gap

# Iron Barrel Yoke layout

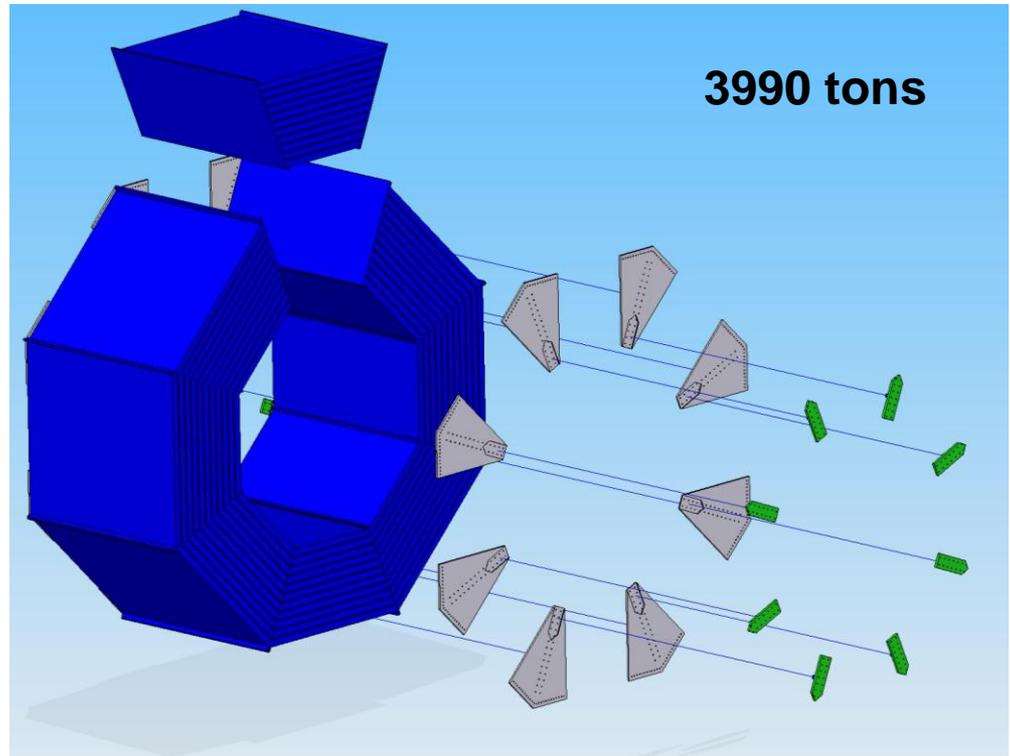
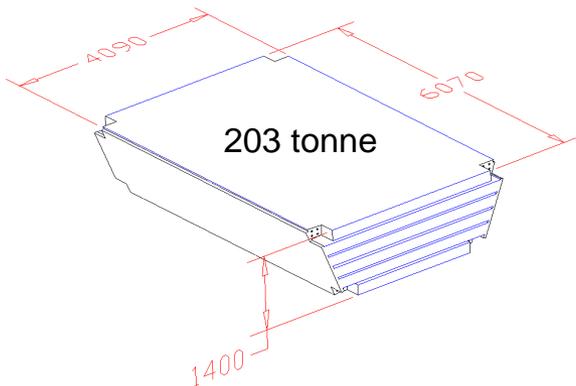


Bolted assembly, 144 plates 200 mm thick, 40mm gap  
 Opportunity to make blank assembly at the factory before shipping  
 Preliminary Contacts with Kawasaki Heavy Industries

- Plate thickness tolerance for each: 0.1mm
- Plate flatness: 4mm (in a plate)
- Fabrication (assembling & welding) tolerance: 2mm
- Full trial assembly: capable (but need to study)

211 tonne

Max. Crane capacity 215 Tons



1. Assembly on Site (surface)

2. Test with low current

