

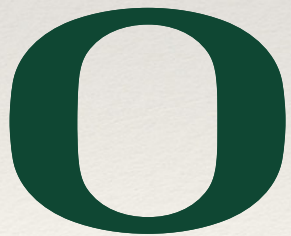


November 2, 2023

**Simulated Performance
of the SiD Digital ECal
Based on Monolithic Active Pixel Sensors**

Jim Brau,
University of
Oregon

on behalf of
the SiD MAPS Collaboration
(M. Breidenbach, A.Habib,
L. Rota, C.Vernieri et al.)



UNIVERSITY OF
OREGON

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"The SiD Digital ECal Based on Monolithic Active Pixel Sensors",
10.3390/instruments6040051, Instruments, 6, 51 (2022)



SiD Digital ECal Based on MAPS

- ❖ Upgrade ILC TDR design to replace sensors with 13 mm² analog pixels with 25 x 100 μm² (or 25 x 50 μm²) digital pixels.
 - ❖ $13 / (.1 \times .025) = 5200x$ granularity
- ❖ How well can we measure energy and structure with digital system:
 - ❖ Compared to SiD baseline of analog measurements?
 - ❖ Can the detailed structural measurements be used to improve measurement?
 - ❖ Would a neural net optimization offer an improvement?
- ❖ What are the limits of transverse separation?

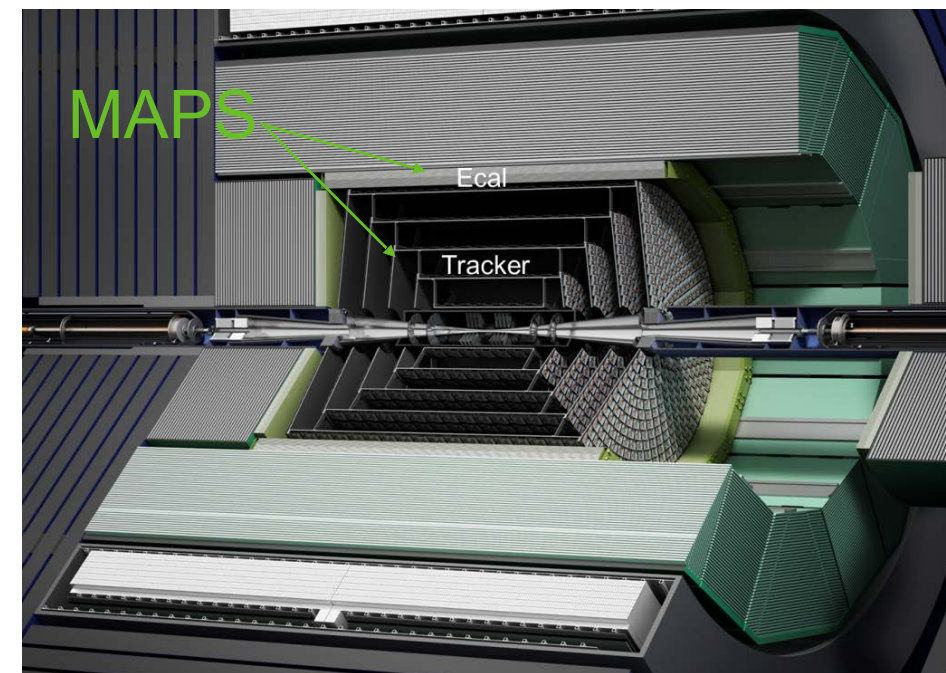
Large area MAPS for SiD tracker & ECal

Benefits of large-area MAPS:

- Standard CMOS foundry, low resistivity: **cost** ↓
- Sensing element and readout electronics on same die
 - In-pixel amplification: **noise** ↓, **power** ↓
 - No need for bump-bonding: **cost** ↓
- Area > 10x10 cm² → enable O(1) m² modules

Several design challenges:

- Large on-die variations, mismatch
- Yield
- Stitching layout rules
- Distribution of power supply
- Distribution of global control signals/references



An example of the SiD Tracker and the ECal overall design

Goals of R&D: find solutions and explore novel design techniques

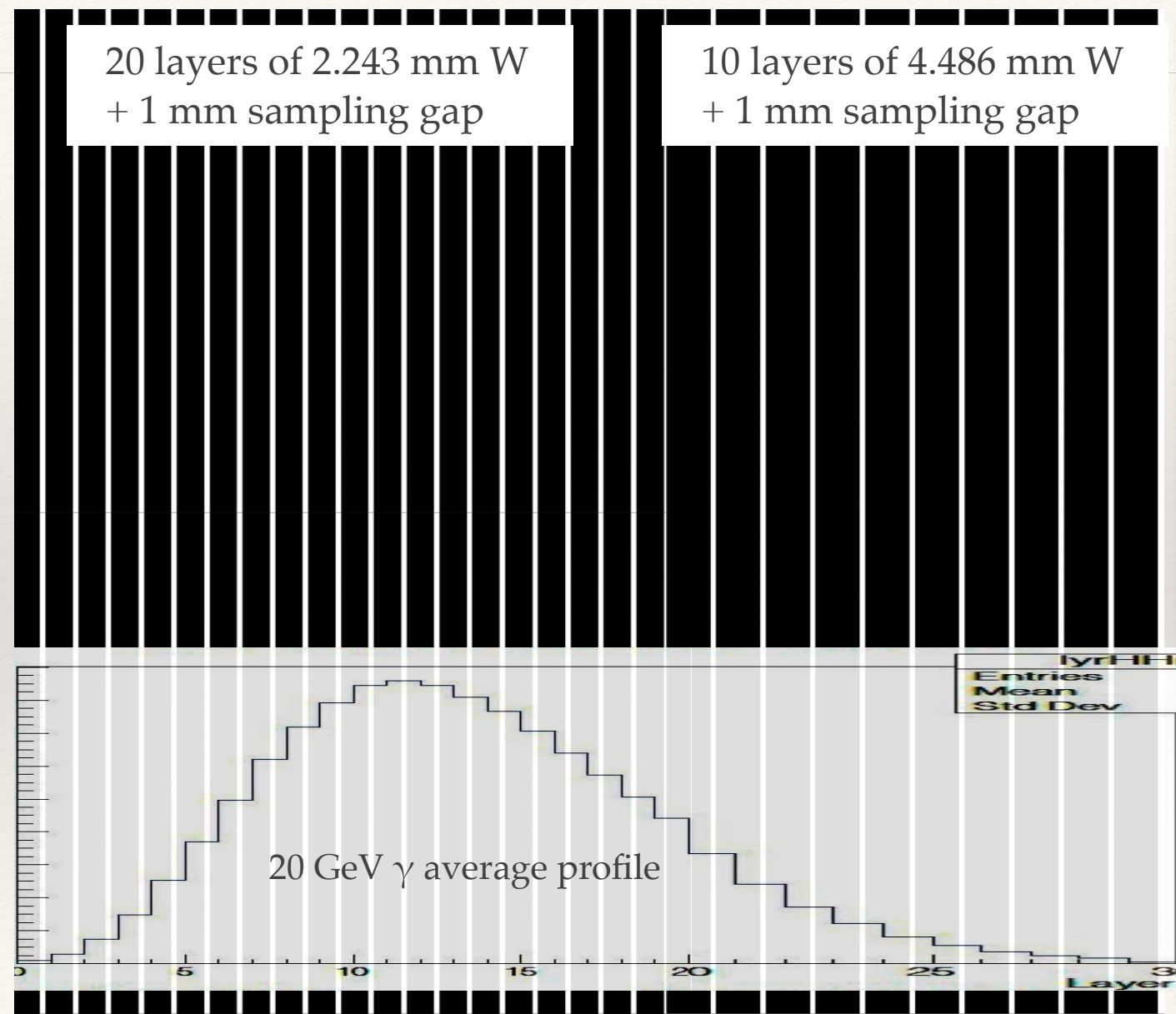


Model of longitudinal structure of SiD ECal

Total = $27 X_0$

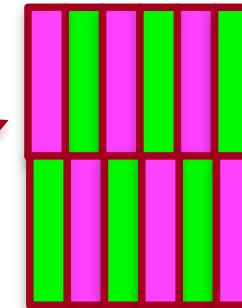


Minimize sampling gap to achieve optimal Moliere radius and shower separation

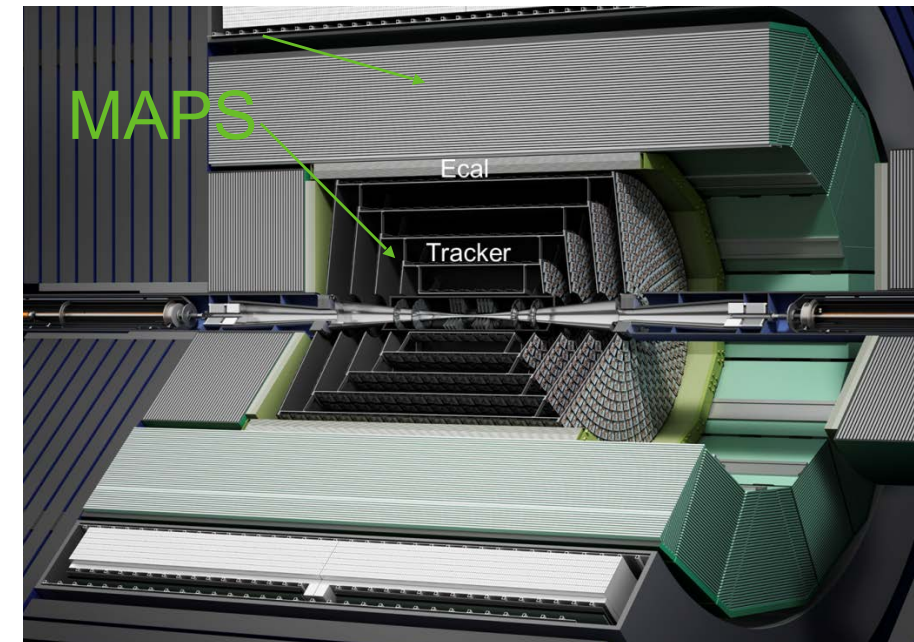


Main specifications for Large Area MAPS development

Parameter	Value	Notes
Min Threshold	140 e ⁻	0.25*MIP with 10 μm thick epi layer
Spatial resolution	7 μm	In bend plane, based on SiD tracker specs
Pixel size	25 x 100 μm ²	Optimized for tracking (note: 25 x 50 μm ²)
Chip size	10 x 10 cm ²	Requires stitching on 4 sides
Chip thickness	300 μm	<200 μm for tracker. Could be 300 μm for ECal to improve yield.
Timing resolution (pixel)	~ ns	Bunch spacing: C ³ strictest with 5.3->3.5 ns; ILC is 554 ns
Total Ionizing Dose	100 kRads	Total lifetime dose, not a concern
Hit density / train	1000 hits / cm ²	
Hits spatial distribution	Clusters	Due to jets
Balcony size	1 mm	Only on one side, where wire-bonding pads will be located.
Power density	20 mW / cm ²	Based on SiD tracker power consumption: 400W over 67m ²



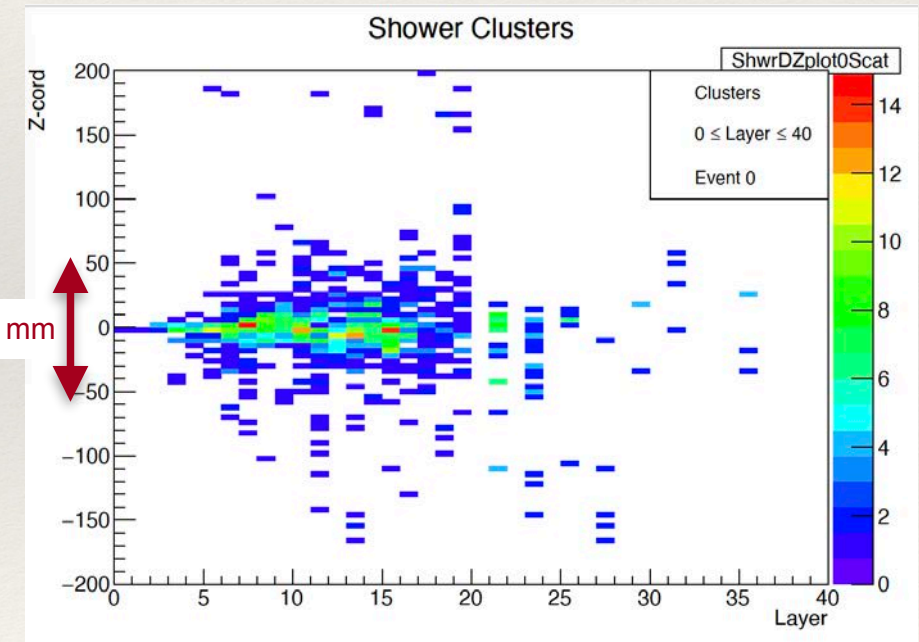
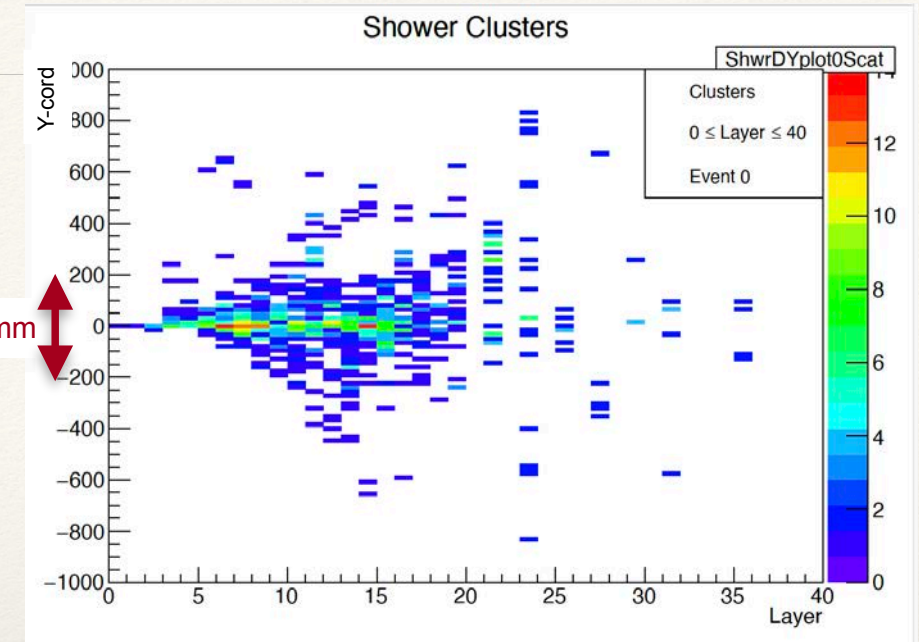
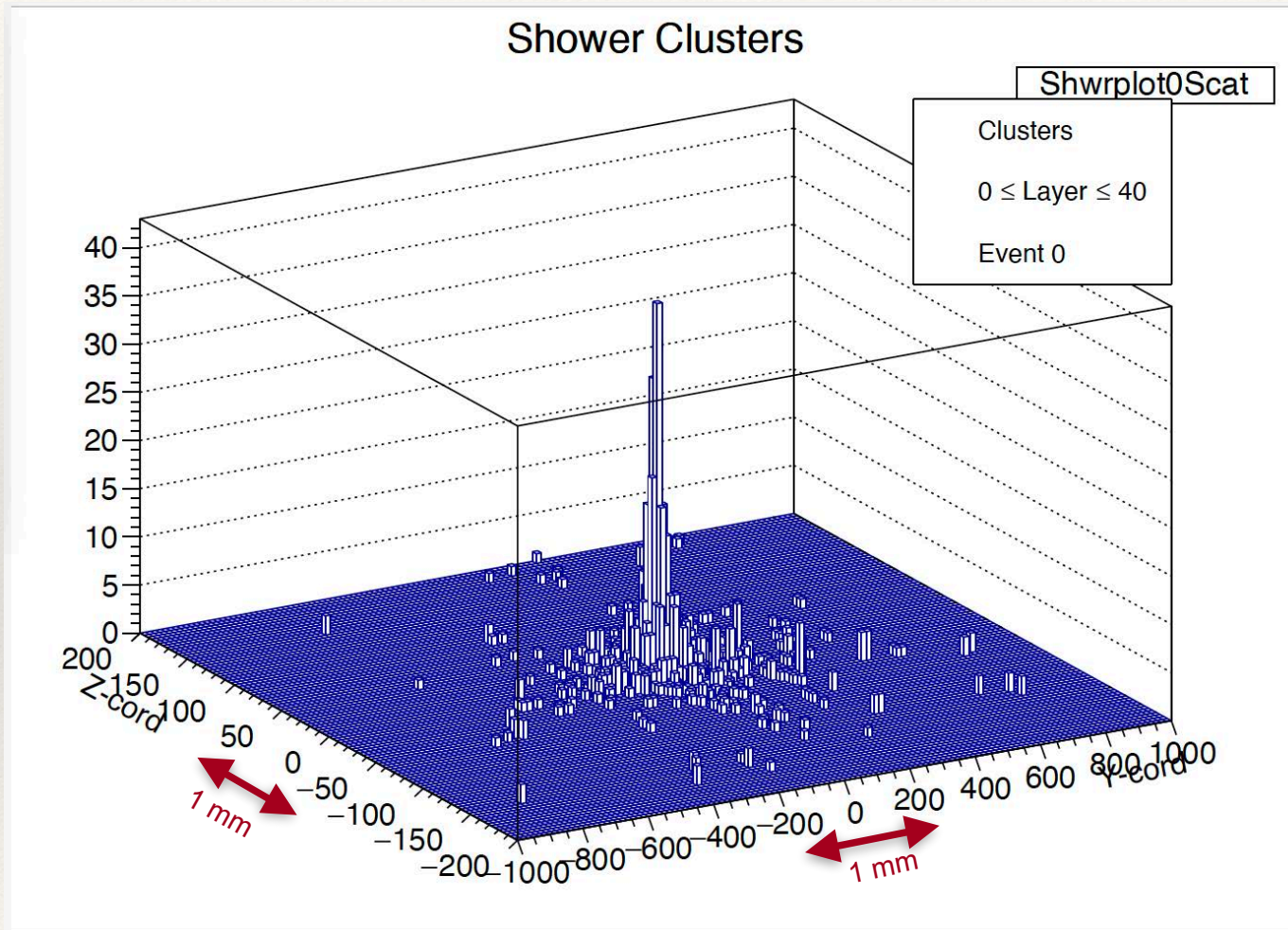
25 x 100 μm²
 ECal performance same as
 50 x 50 μm²
 (Note: may use 25 x 50 μm²)



SiD Tracker and the ECal



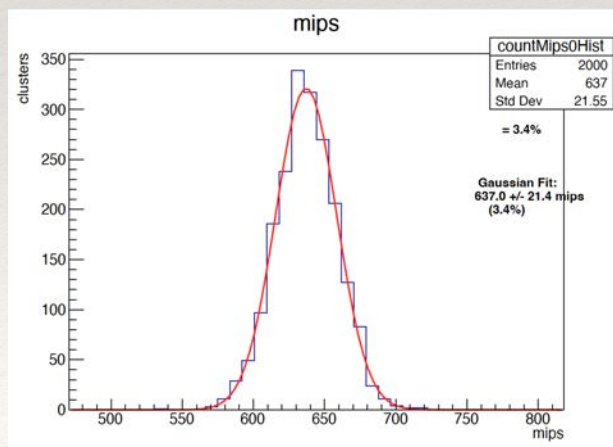
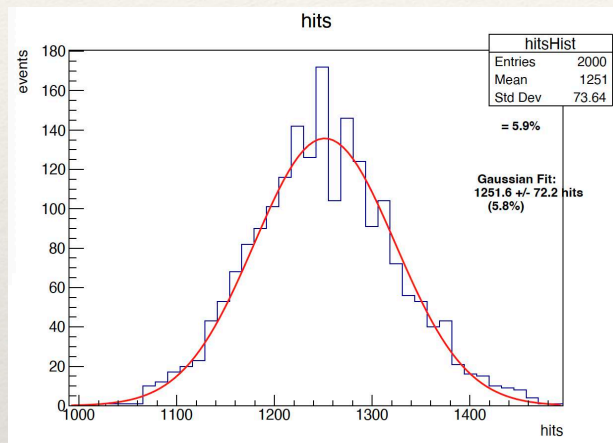
10 GeV Shower in $25 \times 100 \mu\text{m}^2$



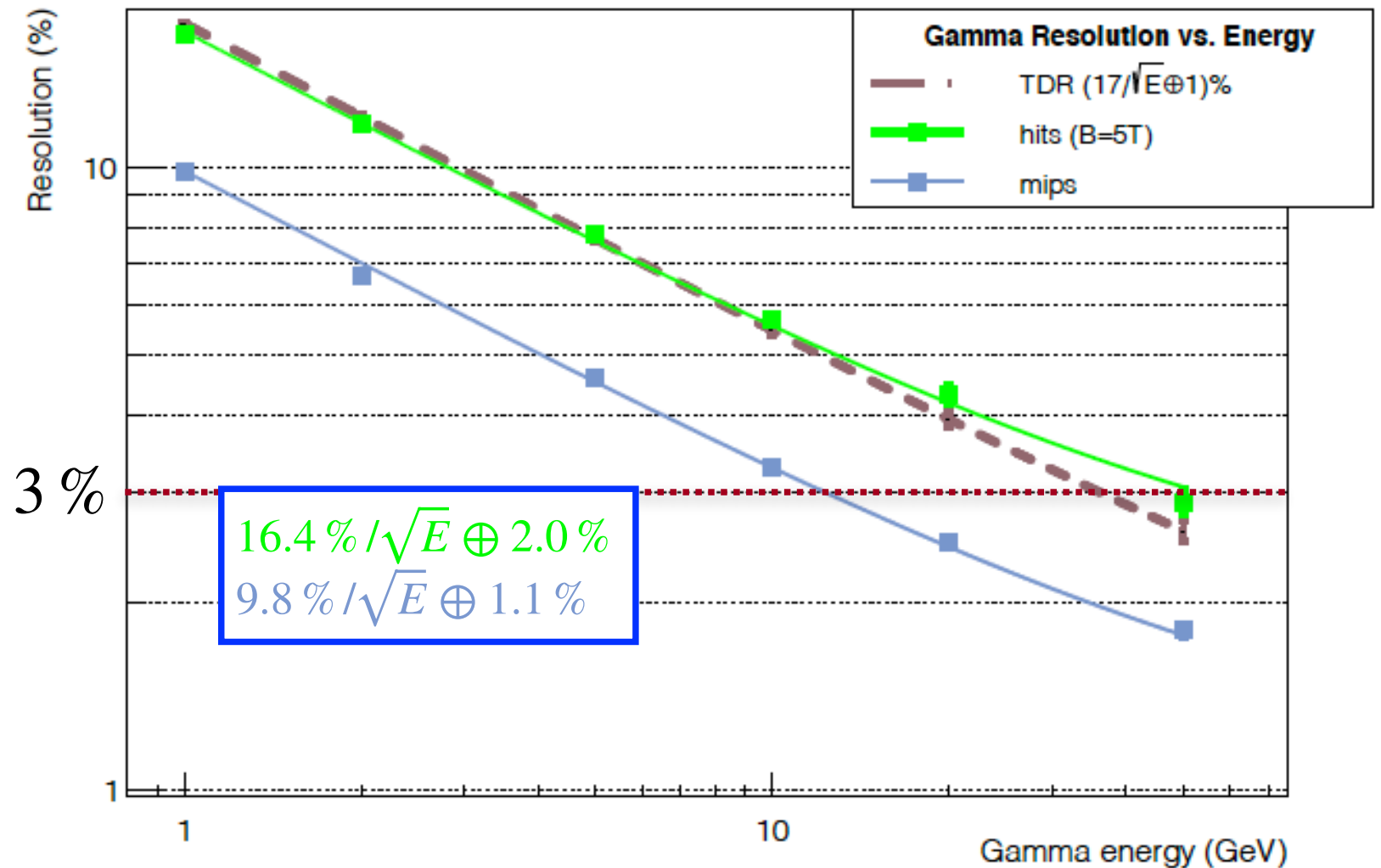


Resolution vs. Energy (hits & mips)

Resolution vs. Energy (hits & mips)



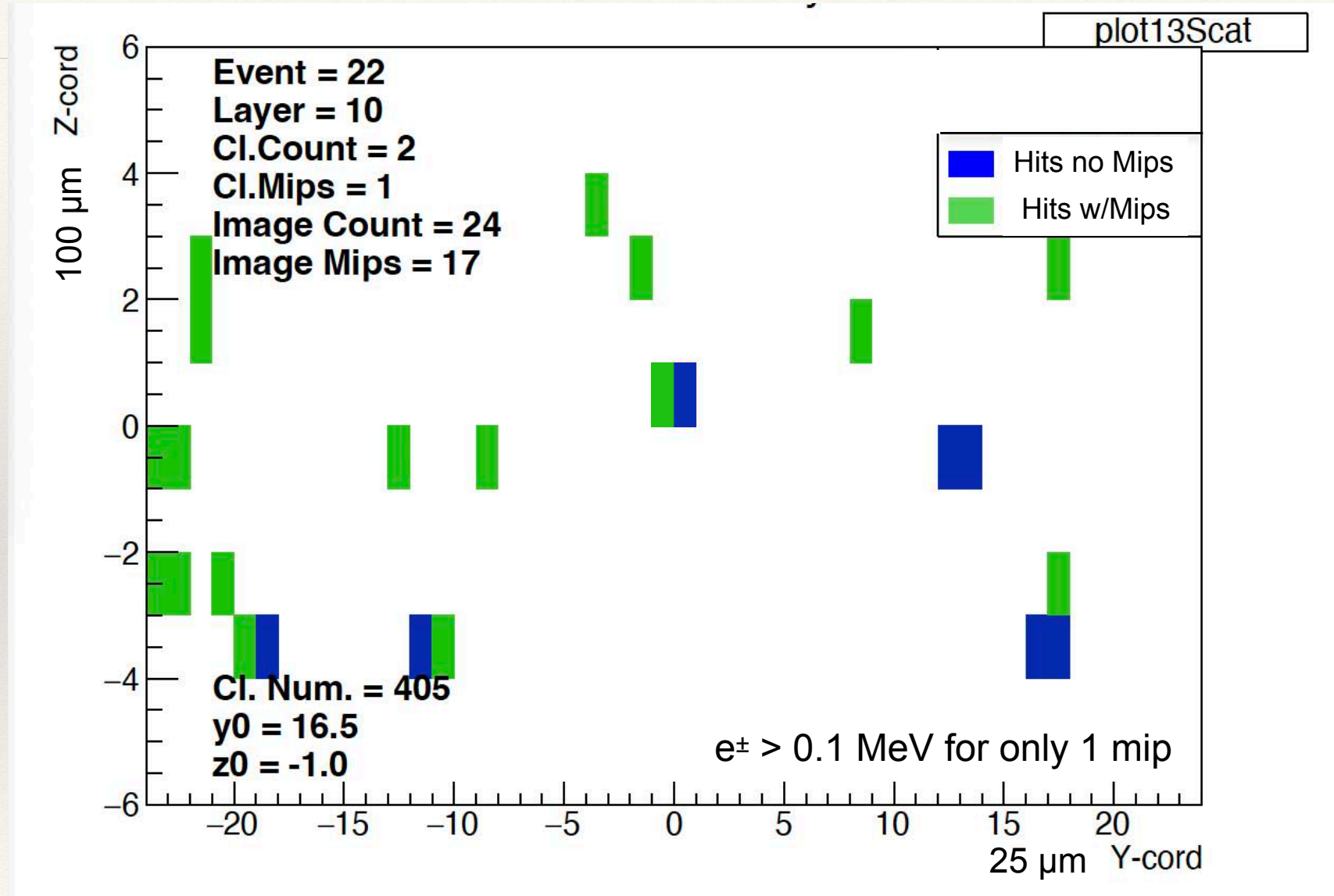
Gamma Resolution vs. Energy (B=5T)





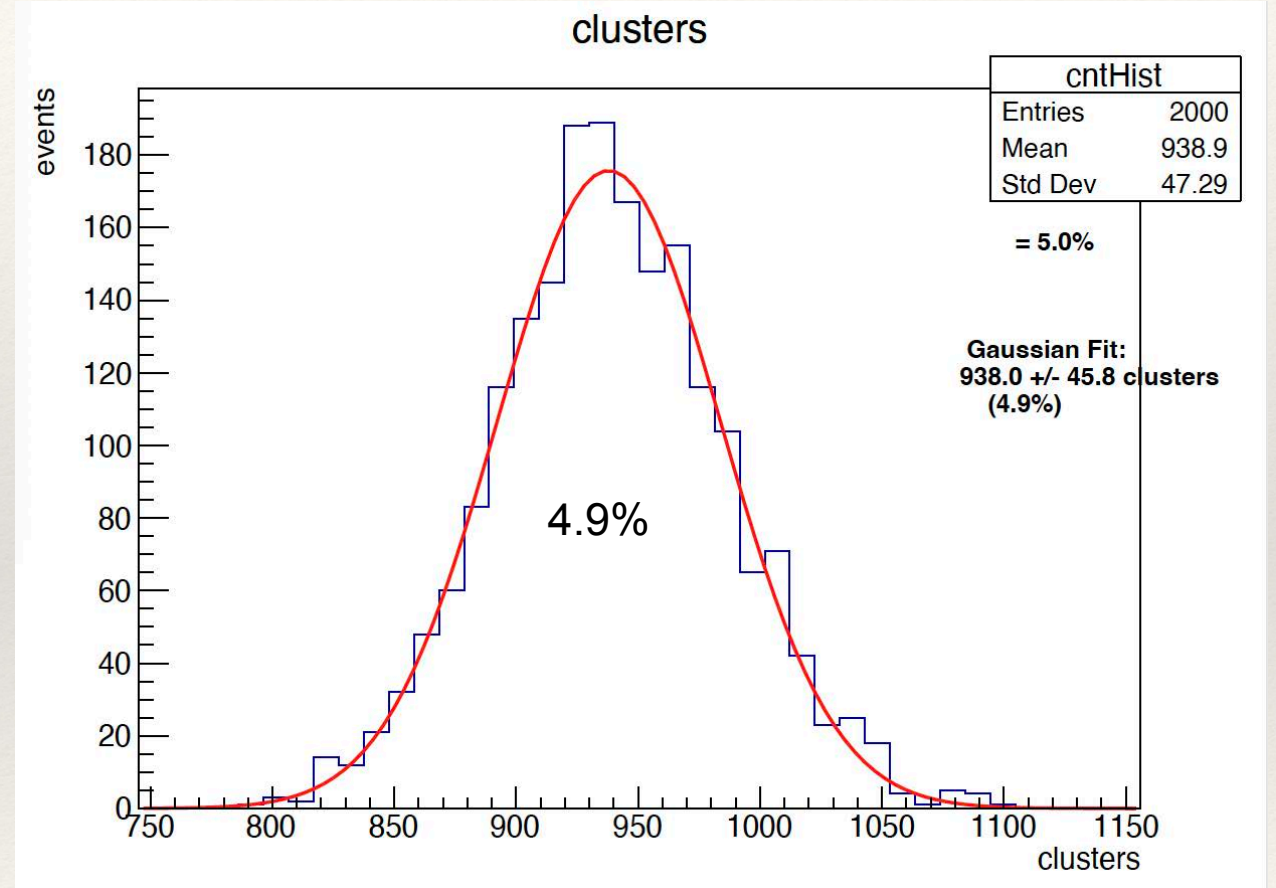
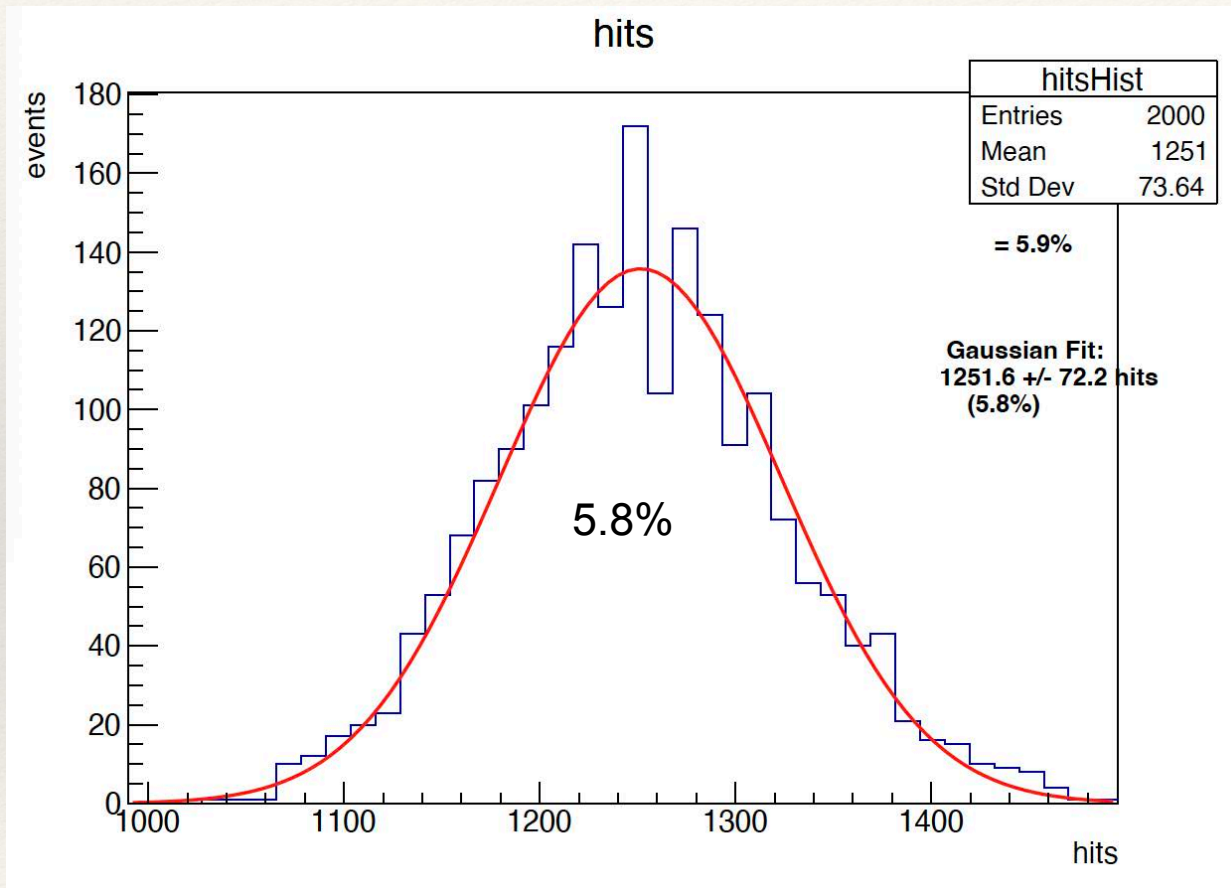
Example of hit distribution in a MAPS

- ❖ Most hits isolated
 - ❖ Single hit cluster
- ❖ Multiple hit clusters
 - ❖ Single mip, or
 - ❖ No mip
- ❖ Counting clusters should reduce fluctuations

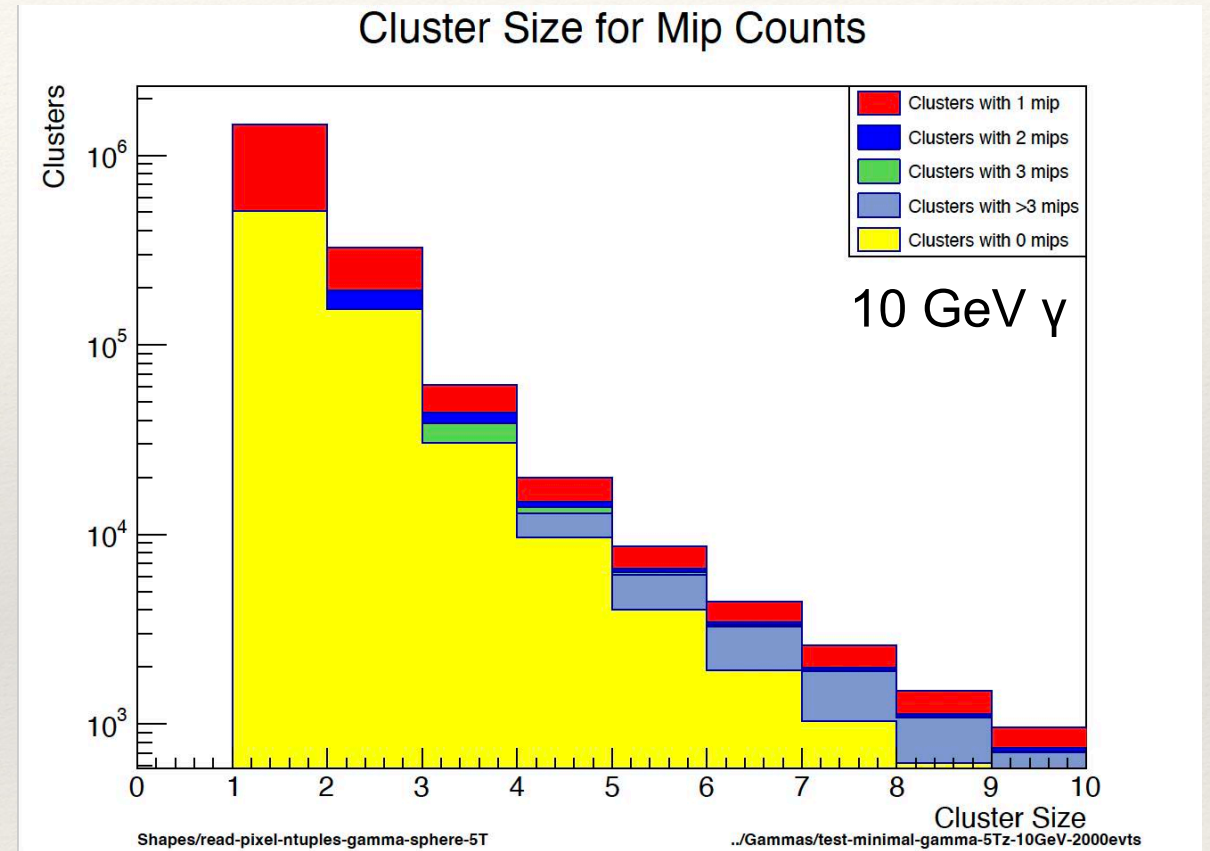
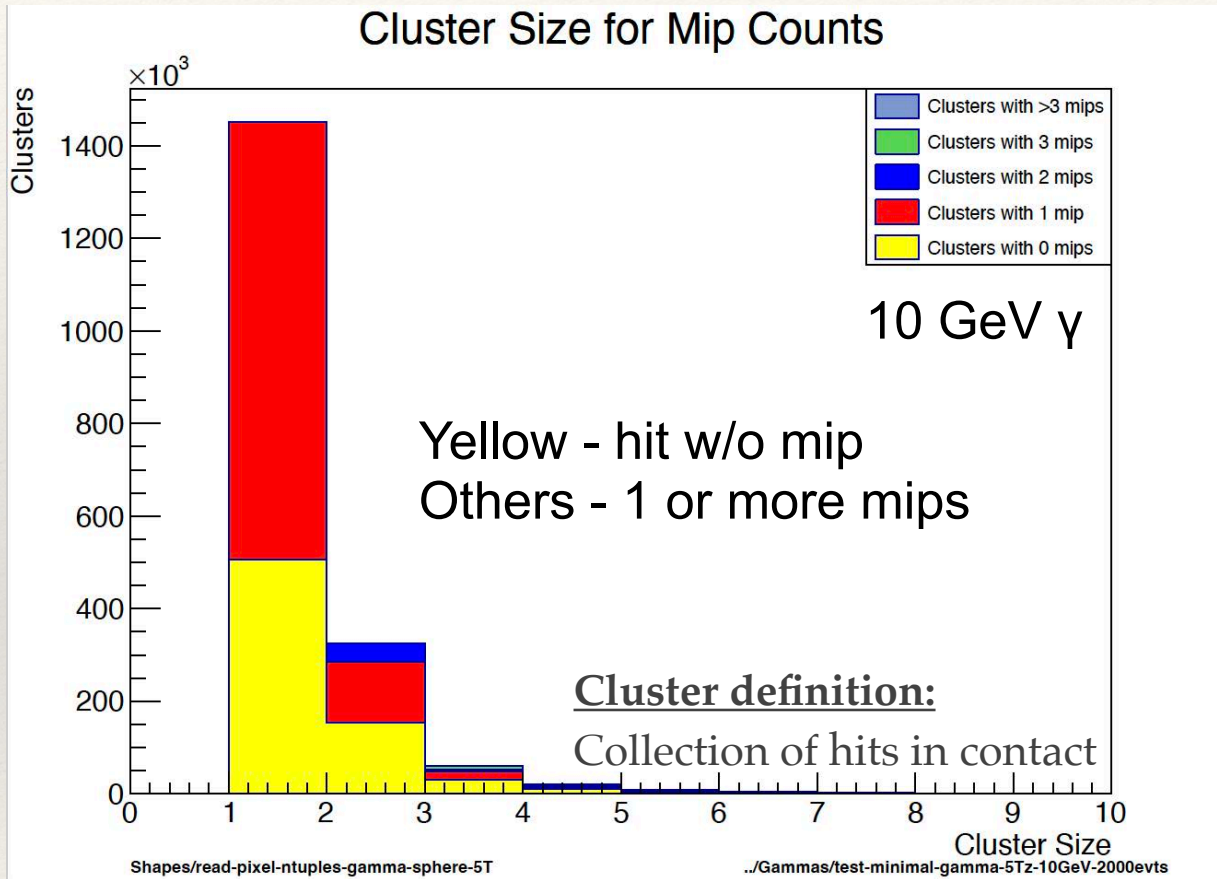




Hits & Clusters (10 GeV γ)



Cluster summary (10 GeV γ)

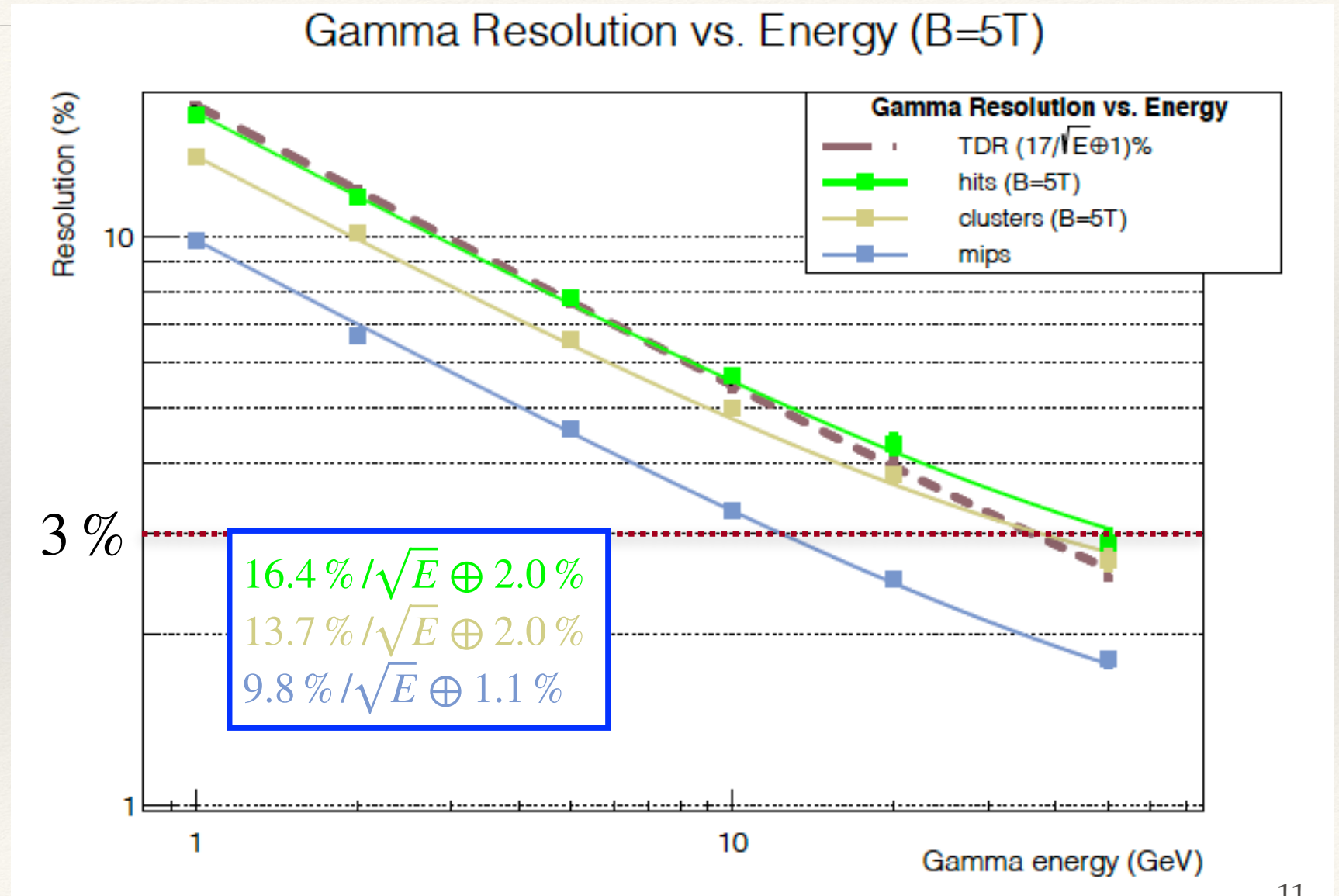


Cluster count is closer to mip count, reducing fluctuations from multiple hits.

Resolution vs. Energy (hits/clusters/mips)

Resolution vs. Energy
(hits / clusters / mips)

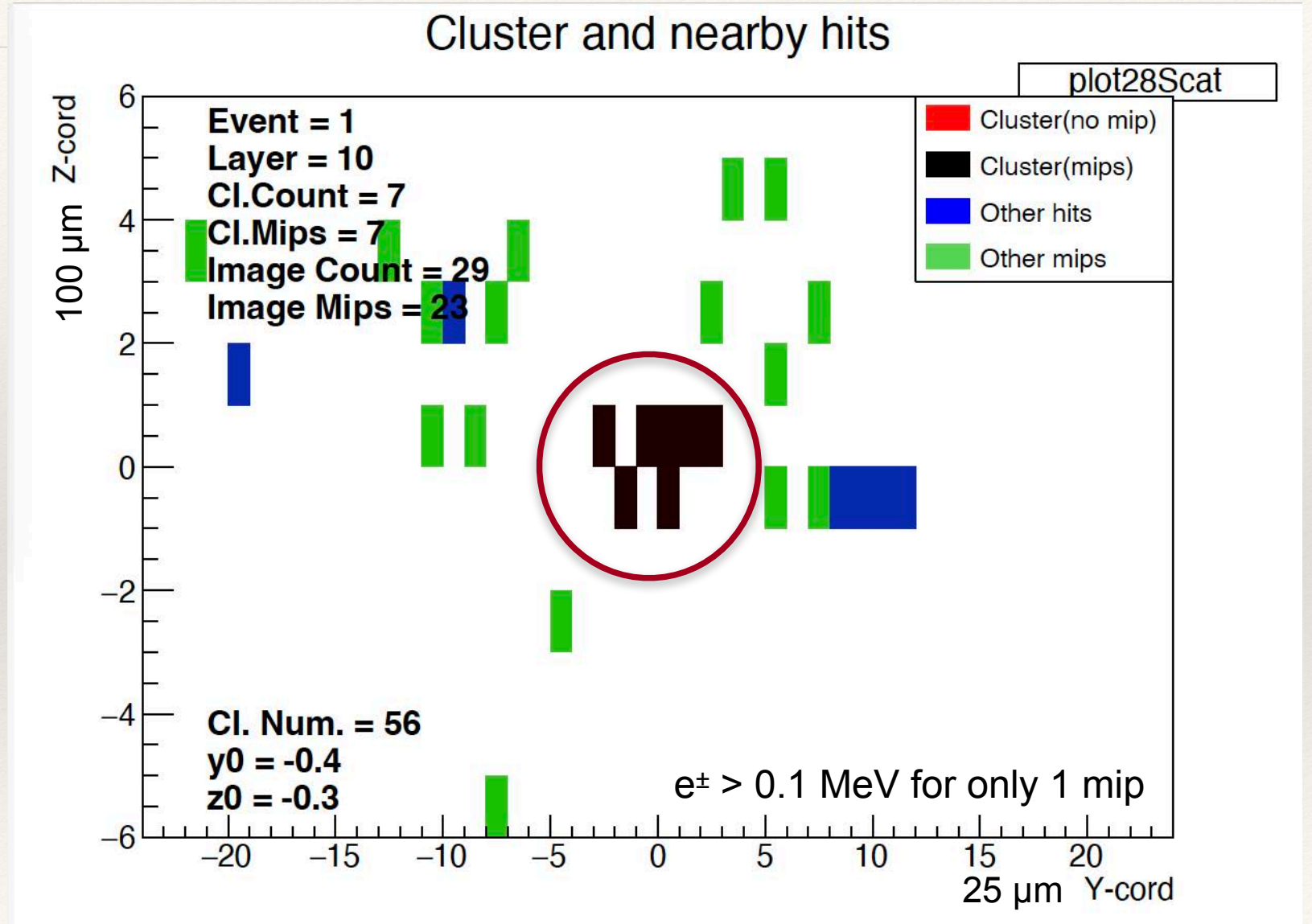
Simple cluster
performance is better
than hit counting.





All Clusters are not the same

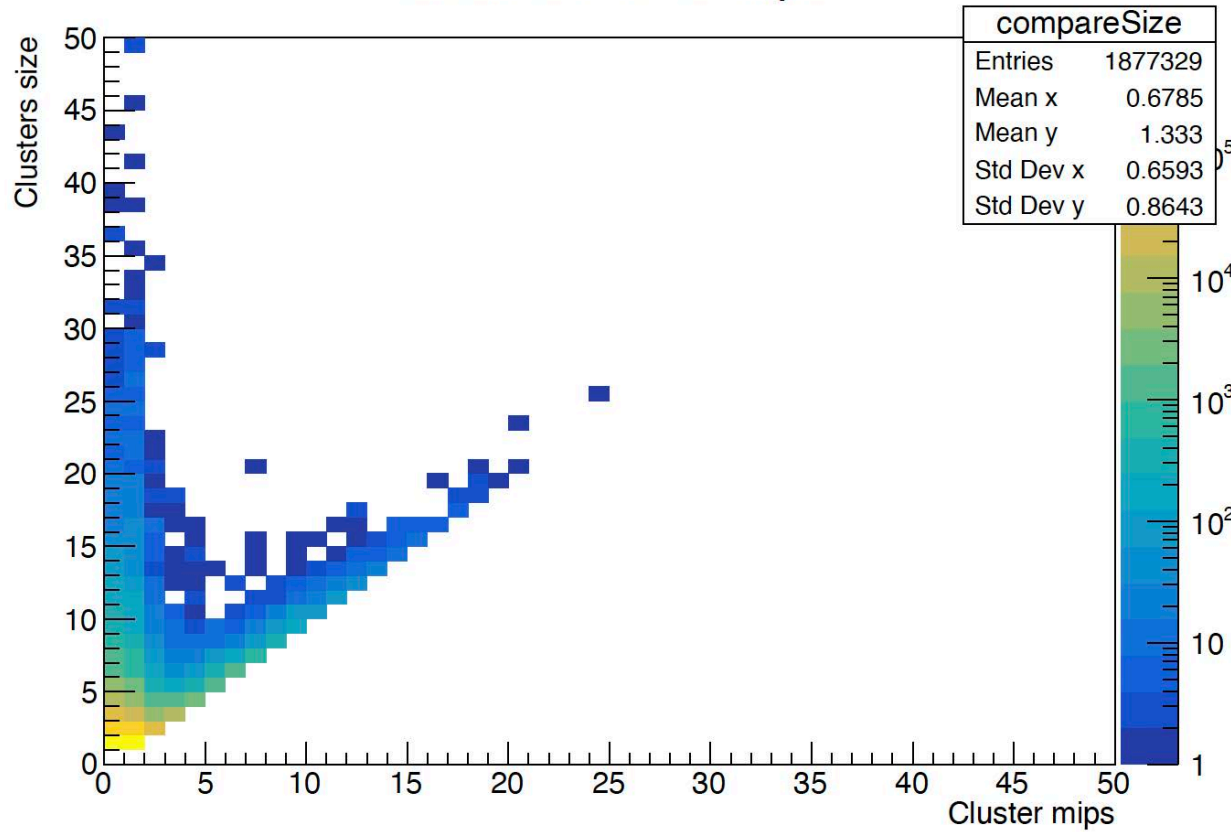
Some clusters are numerous mips.



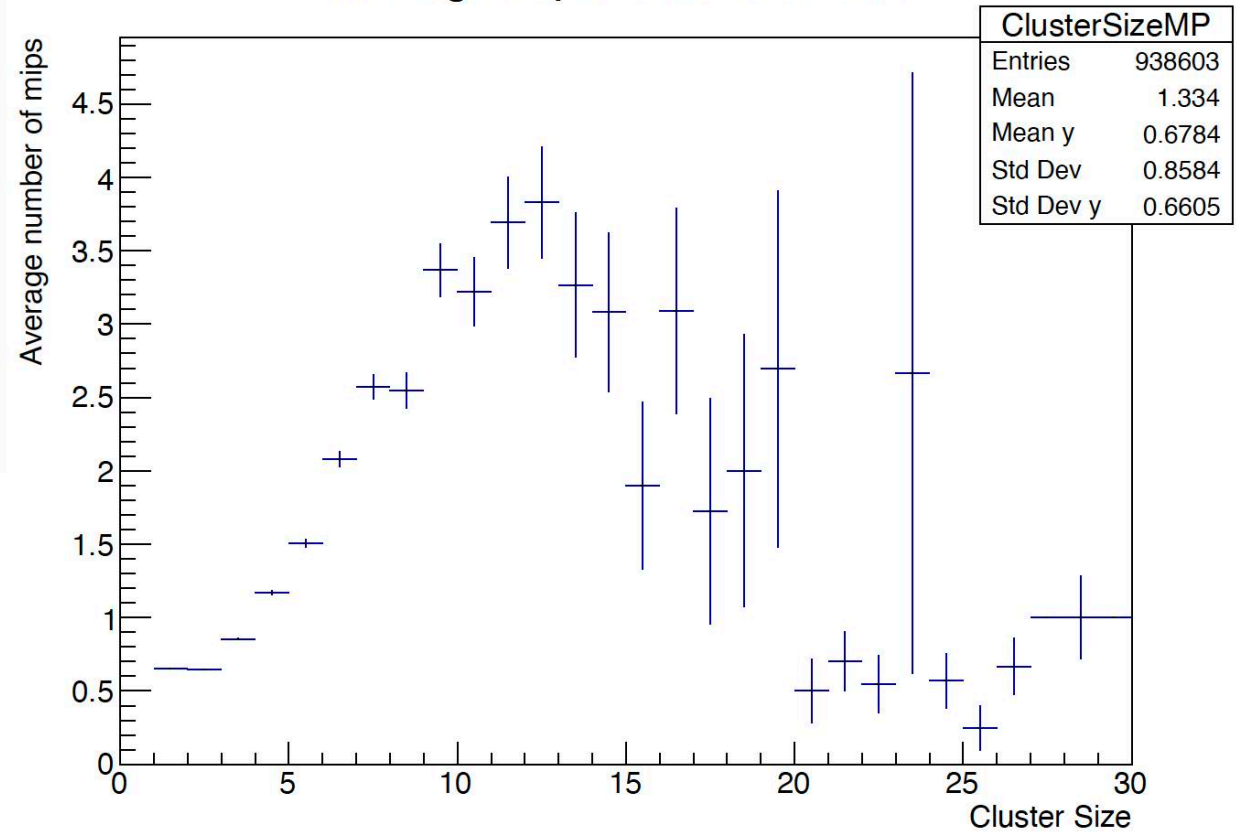


10 GeV γ s - 2000 showers

Clusters size vs. mips

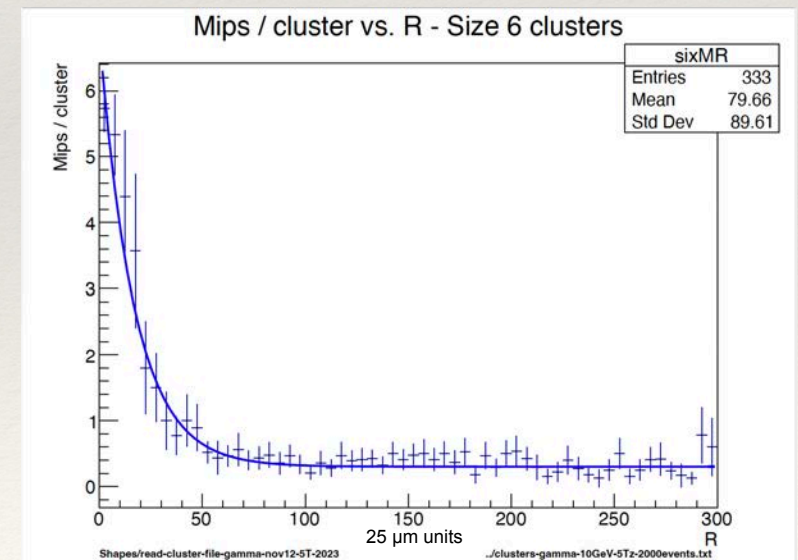
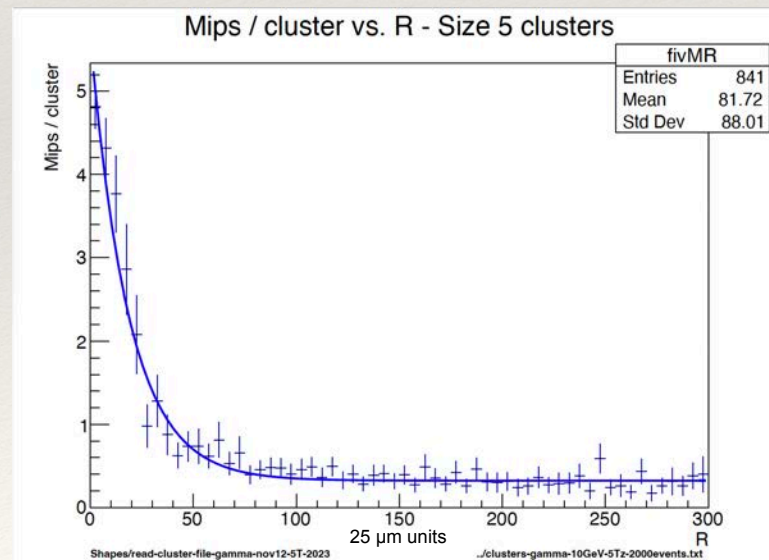
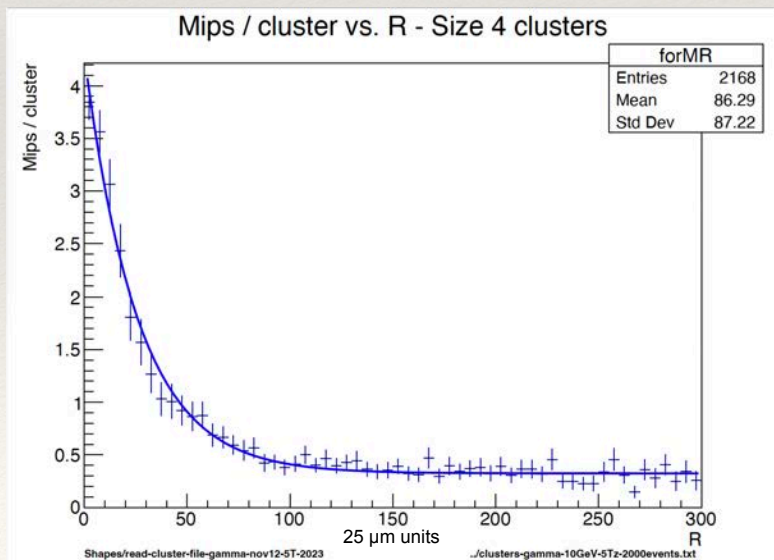
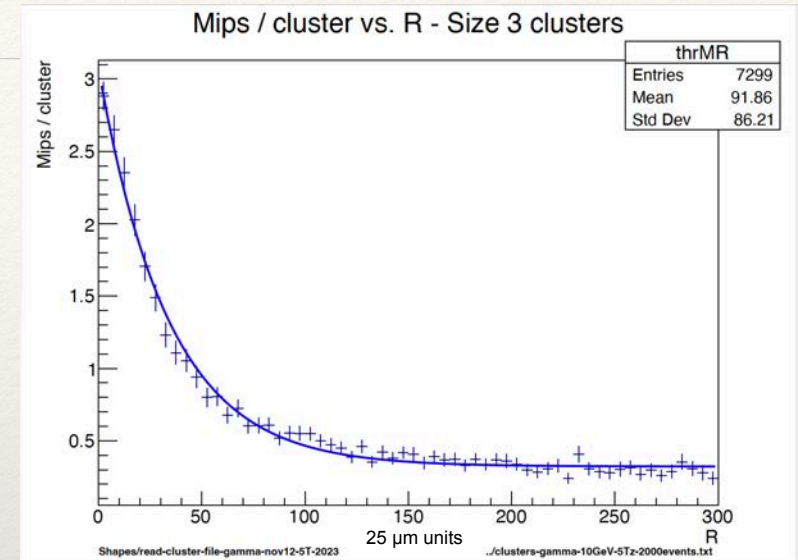
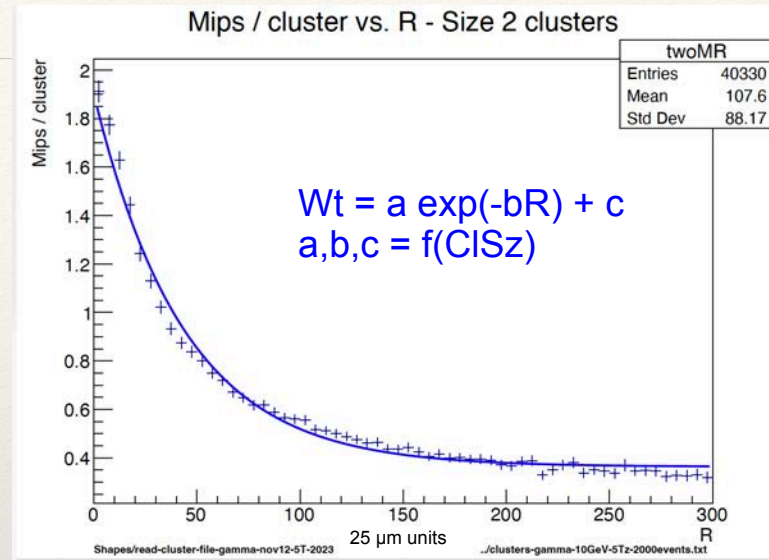
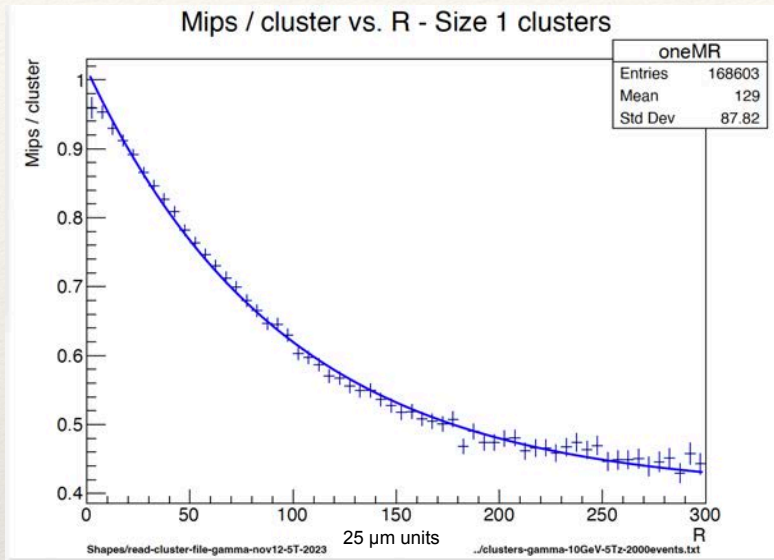


Average mips vs. Cluster Size



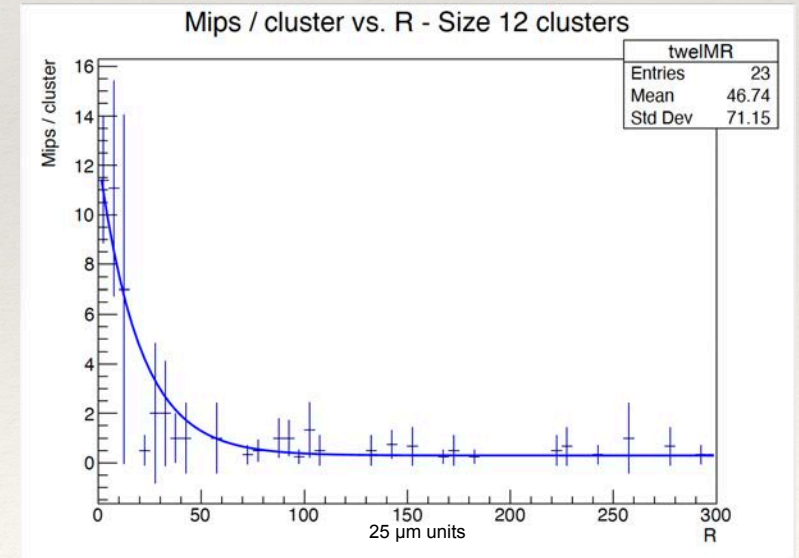
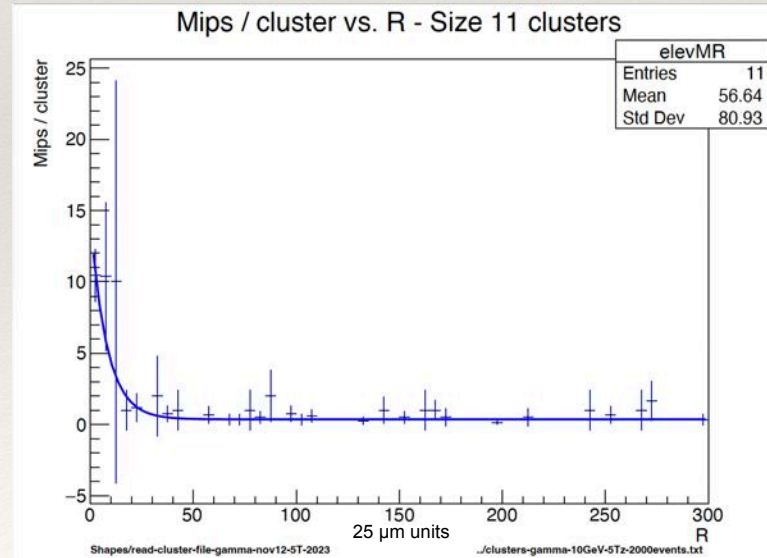
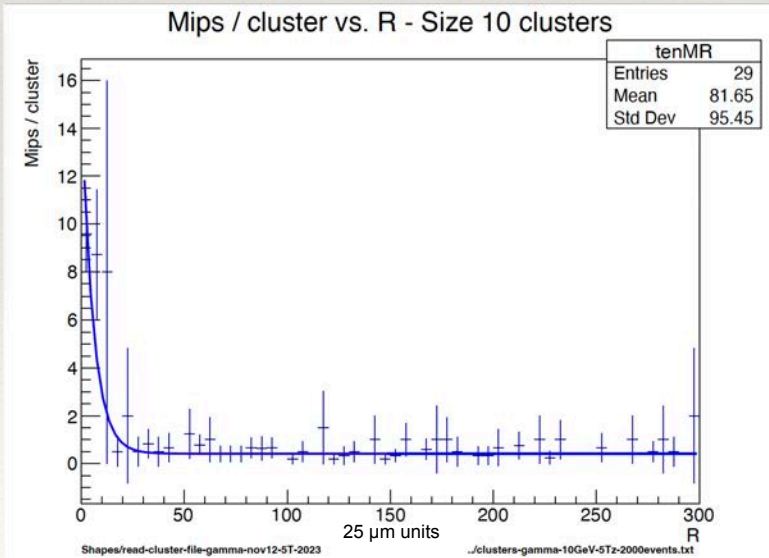
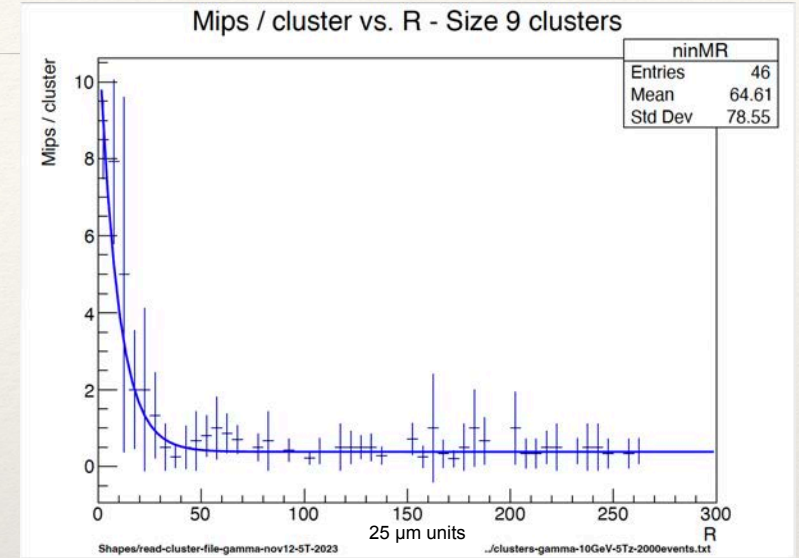
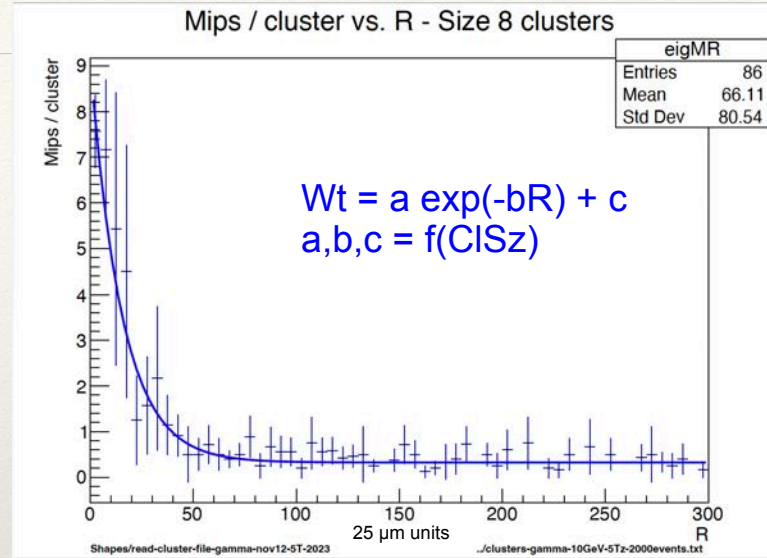
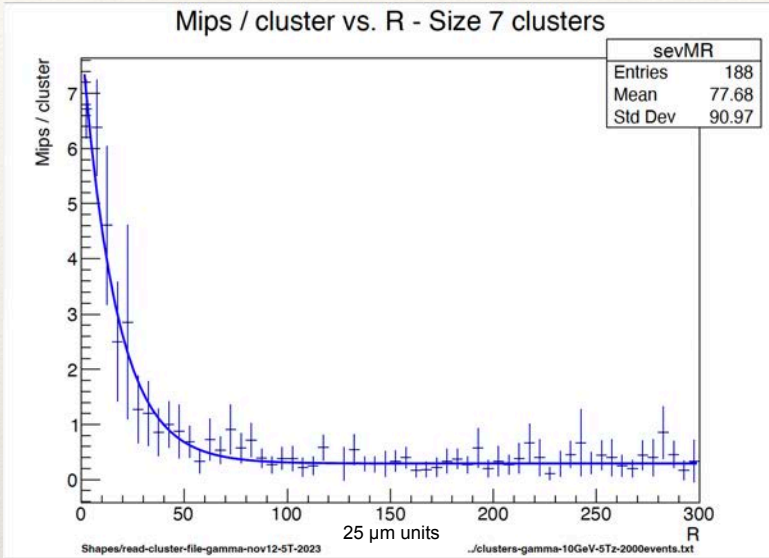


10 GeV γ s - 2000 showers





10 GeV γ s - 2000 showers

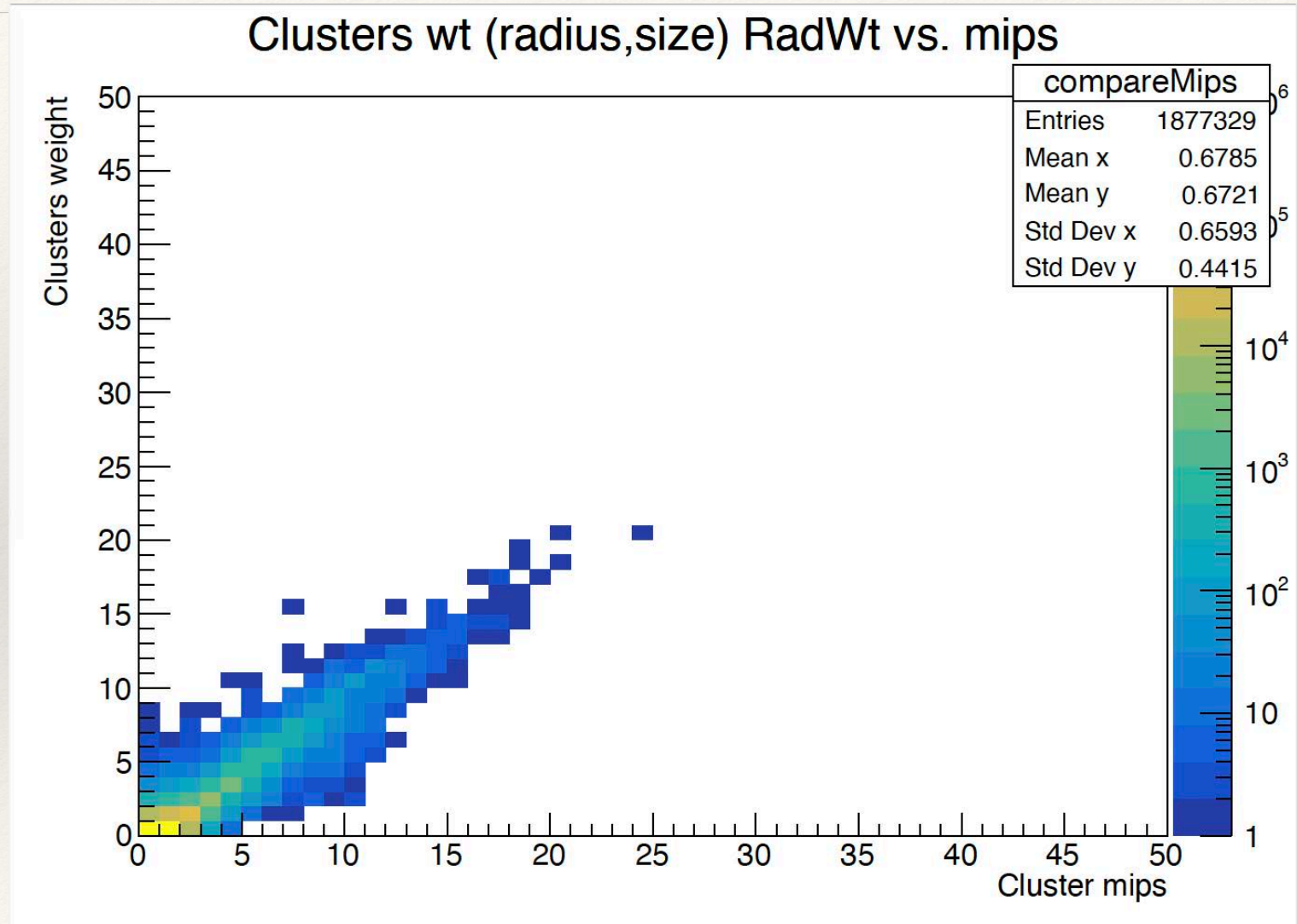




10 GeV γ s - 2000 showers

$$\text{RadWt} = a \exp(-bR) + c$$

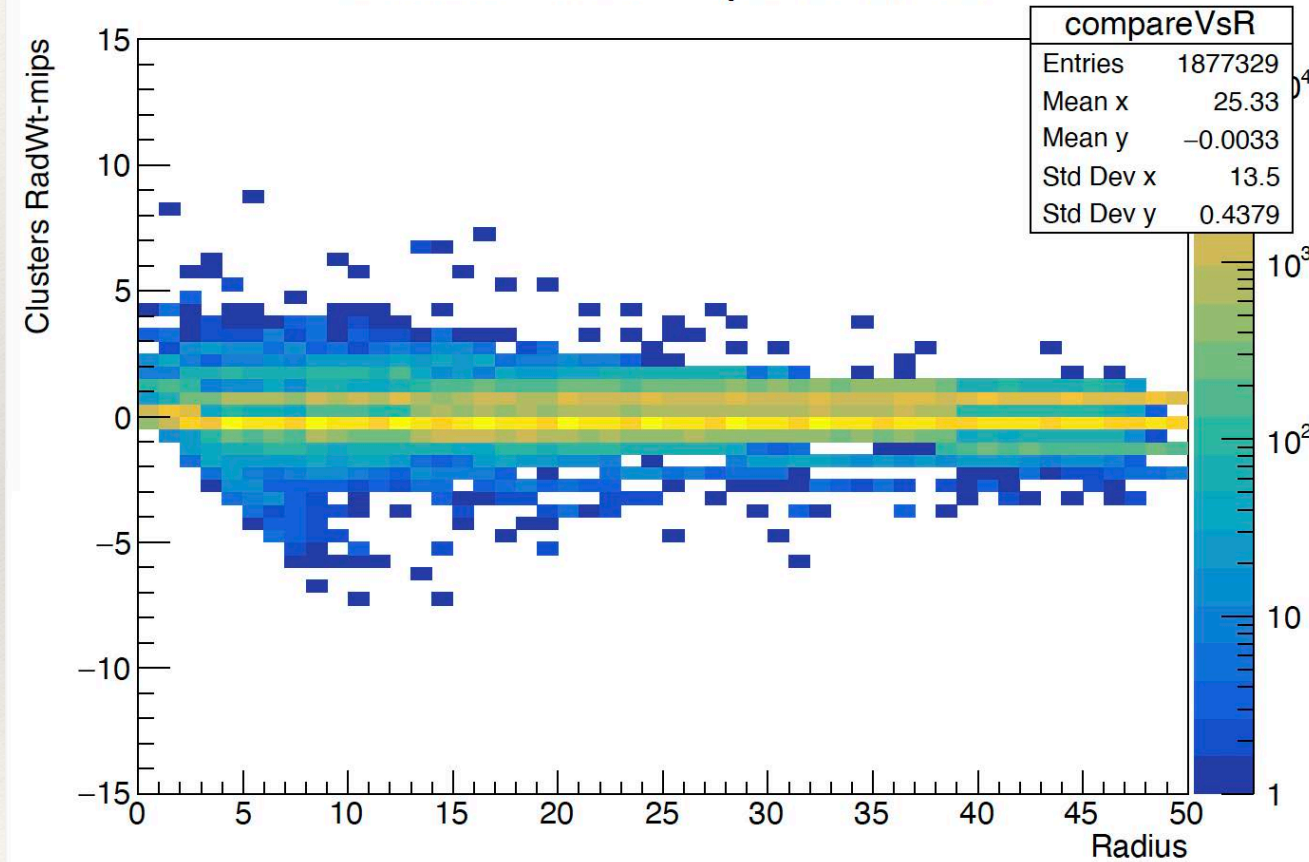
$$a, b, c = f(\text{ClSz})$$



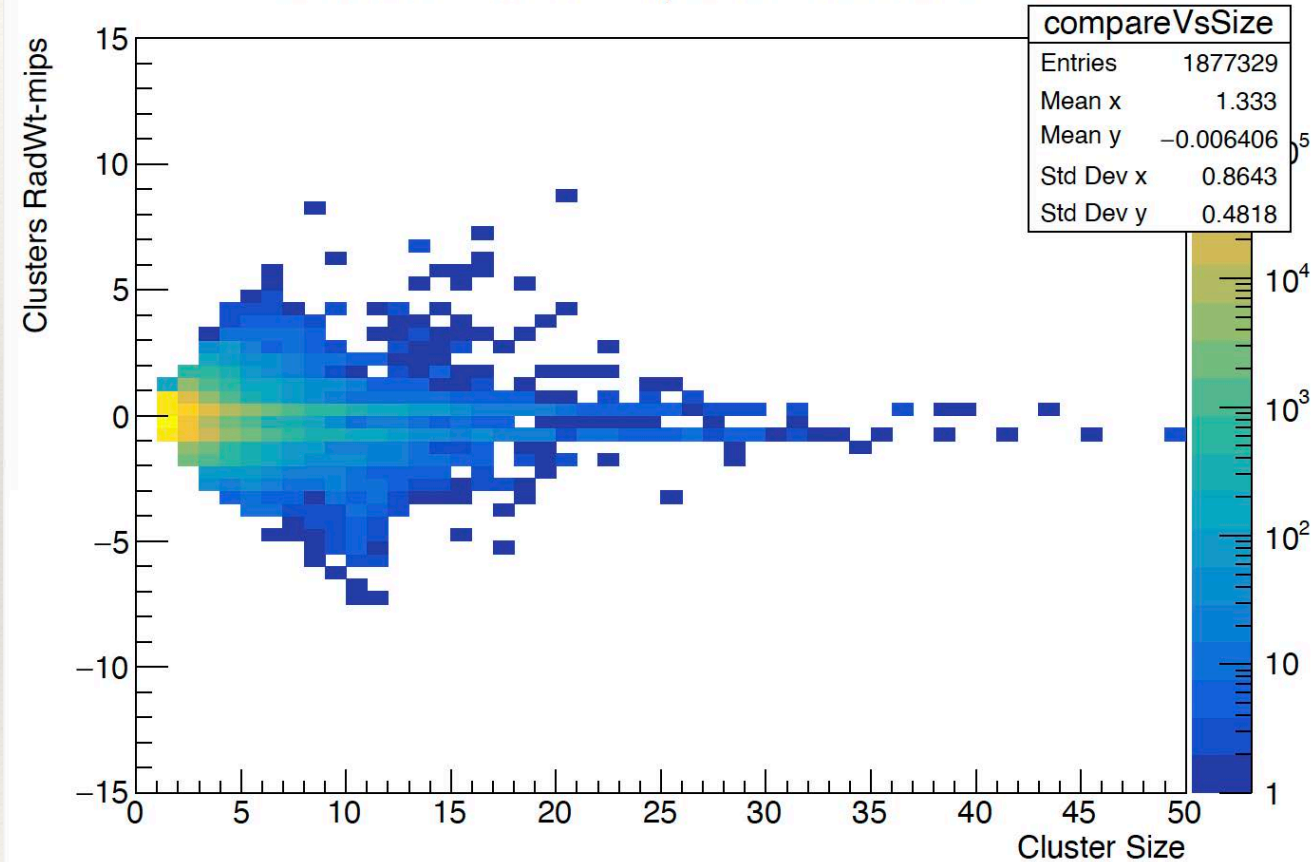


10 GeV γ s - 2000 showers

Clusters RadWt-mips vs. radius

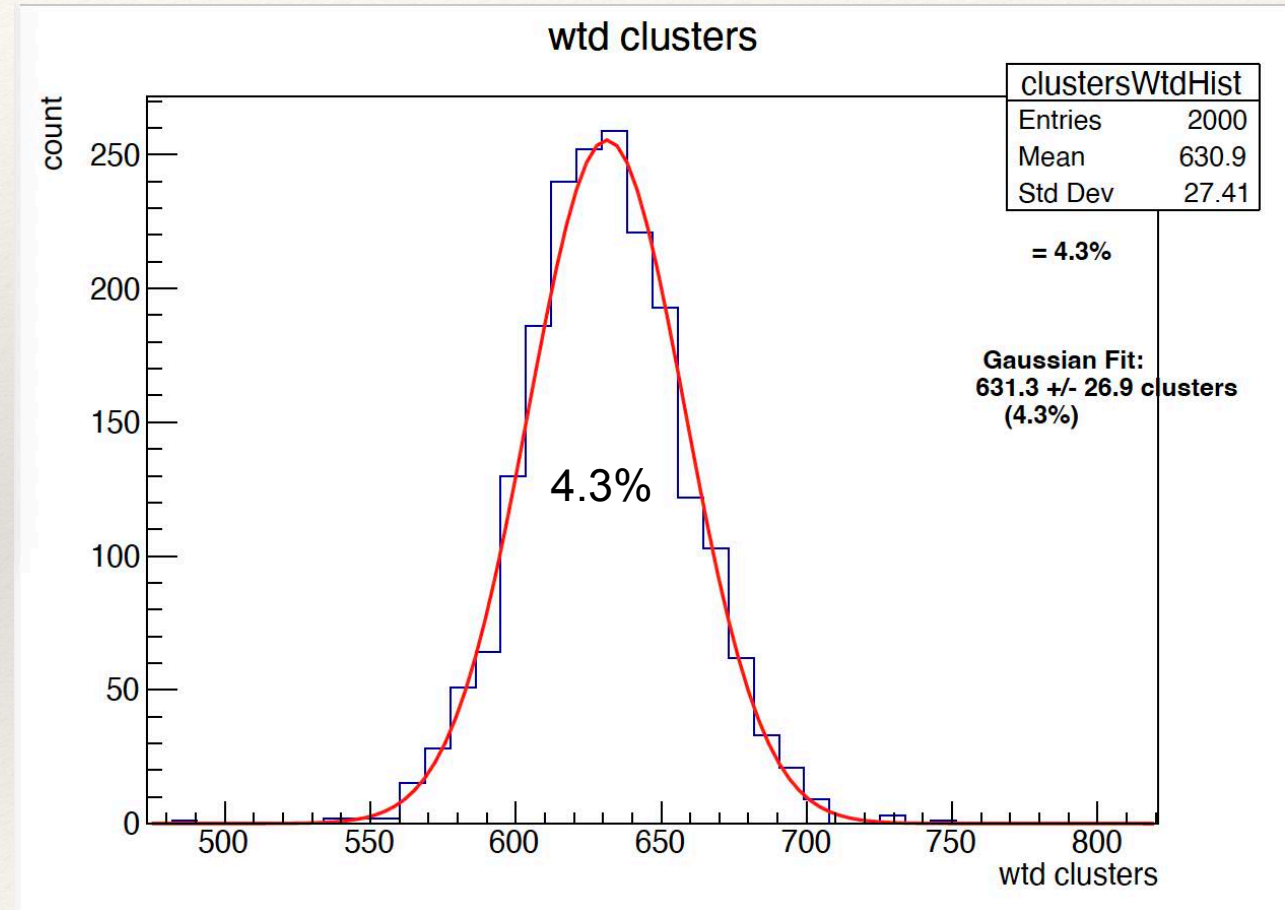
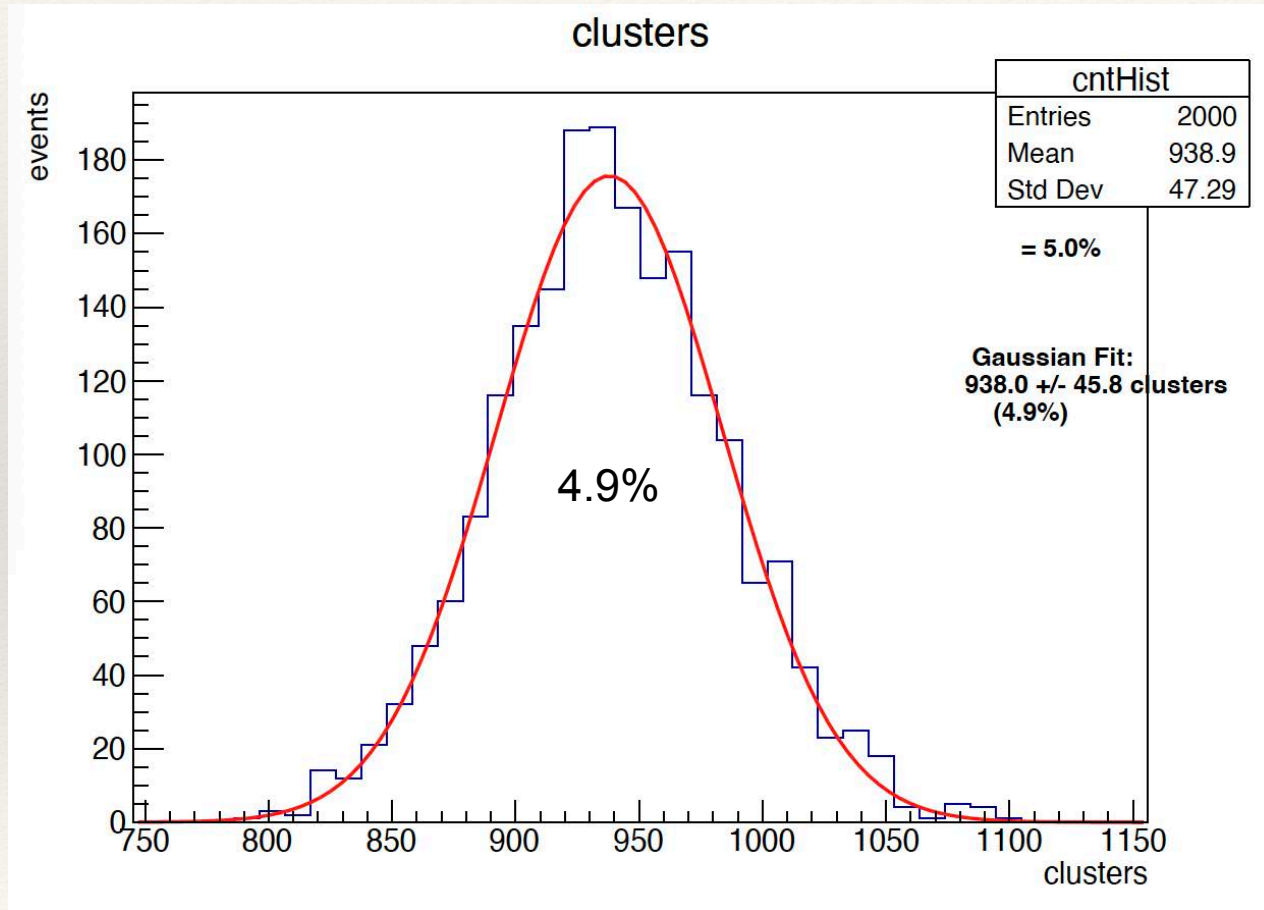


Clusters RadWt-mips vs. Cluster Size





Weights (mips/hit in cluster) improve resolution 10 GeV γ s



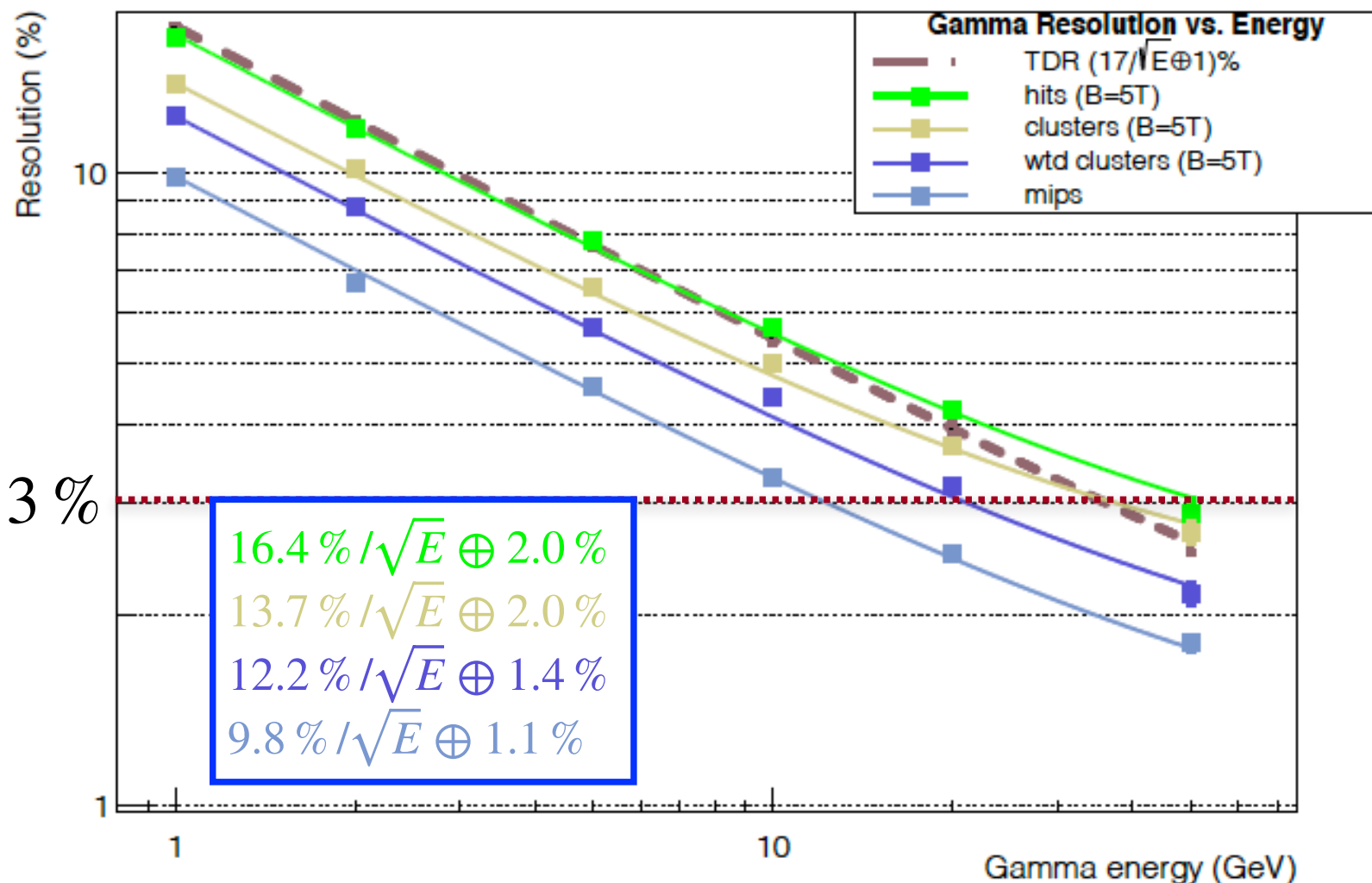
Resolution vs. Energy (hits/clusters/mips)

Resolution vs. Energy
(hits / clusters / mips) &
weighted clusters.

Simple cluster
performance is better
than hit counting.

When cluster properties
are taken into account
with weighting,
performance improves.

Gamma Resolution vs. Energy (B=5T)





TMVA Neural Net

TRAINING - 10 GeV
2000 events
2,502,000 hits
1,878,999 clusters

```
# Store model to file
```

```
model.save('modelRegression%s.h5'%Efact)  
model.summary()
```

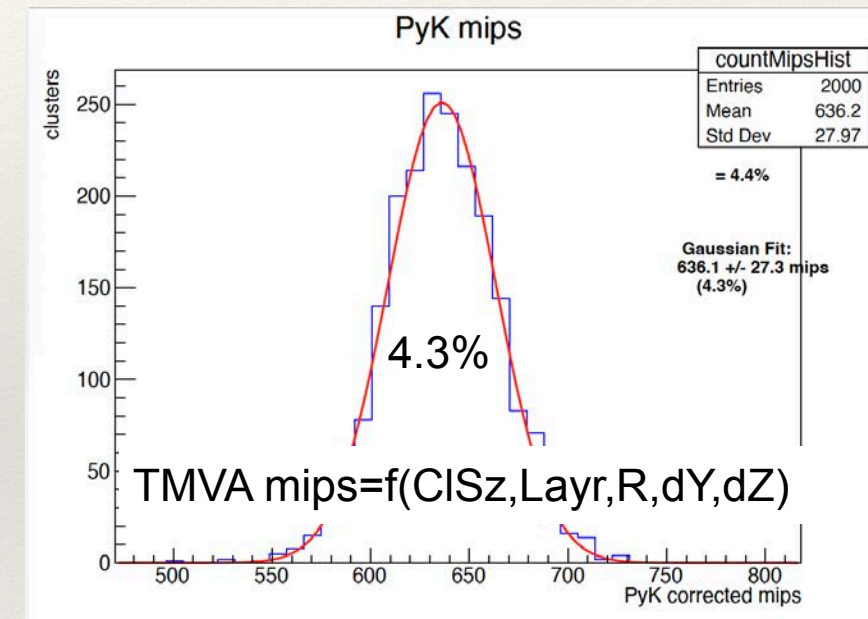
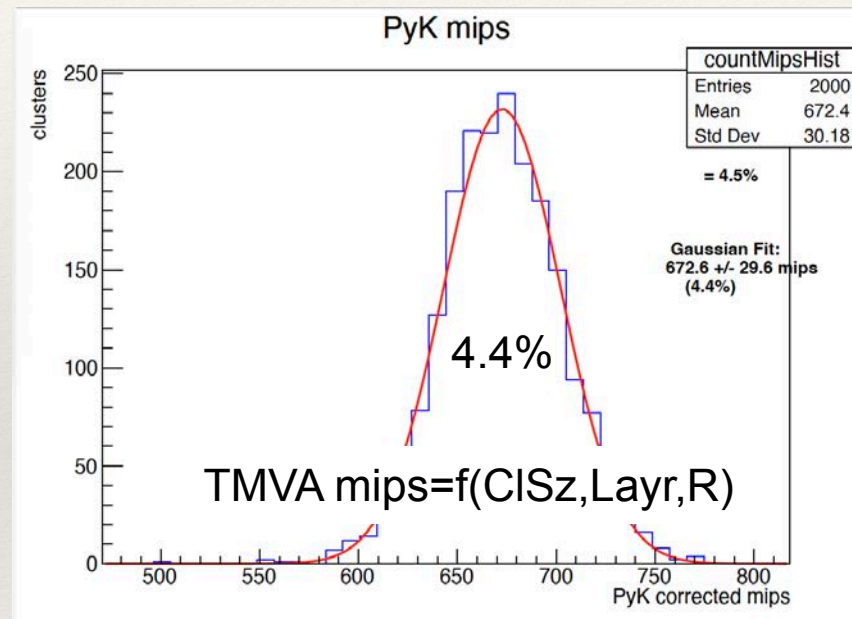
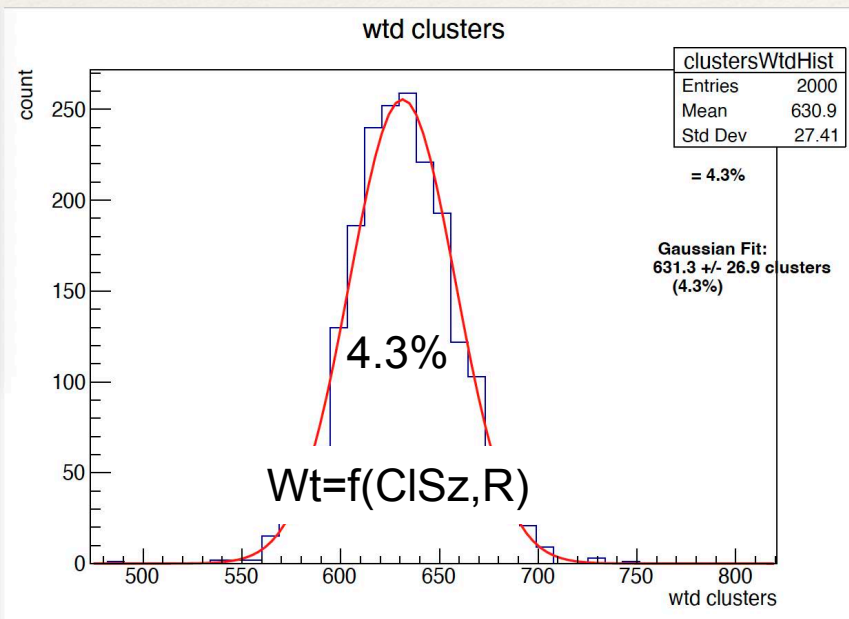
```
# Book methods
```

```
factory.BookMethod(dataloader, TMVA.Types.kPyKeras, 'PyKeras',  
                  'H:!
```

```
V:VarTransform=D,G:FilenameModel=modelRegression%s.h5:FilenameTrainedModel=  
trainedModelRegression%s.h5:NumEpochs=20:BatchSize=32'%(Efact,Efact))
```



Weighted function vs. TMVA neural net (10 GeV γ s)





Results: Energy Resolution

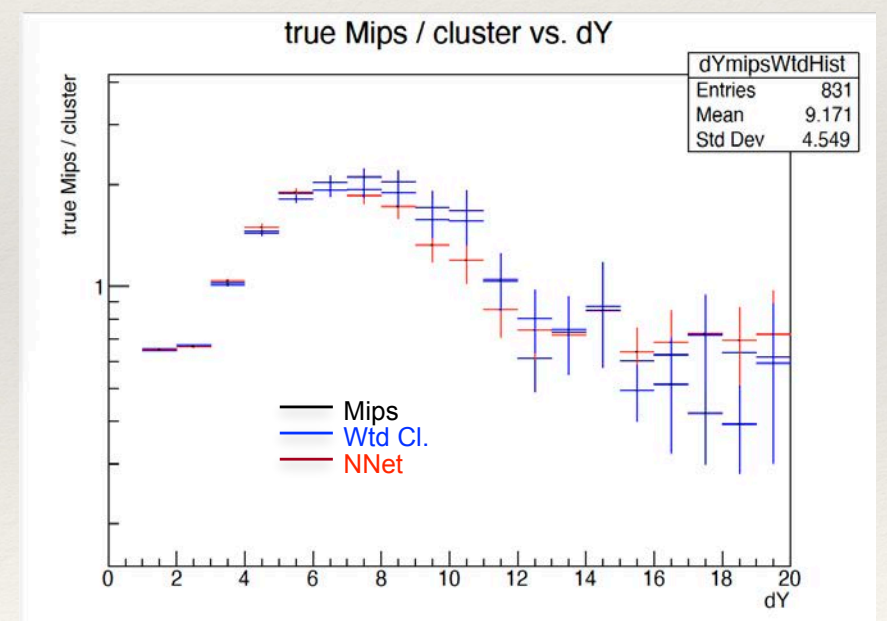
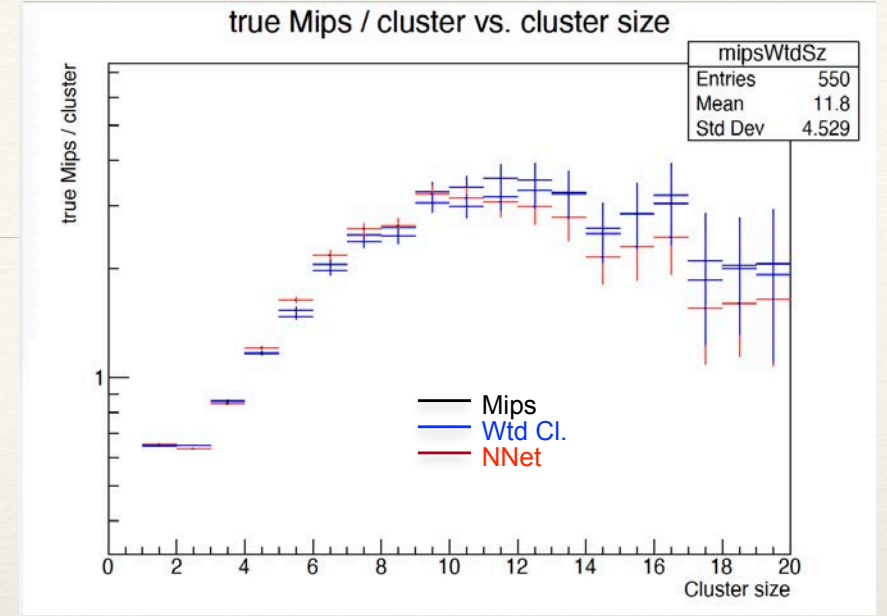
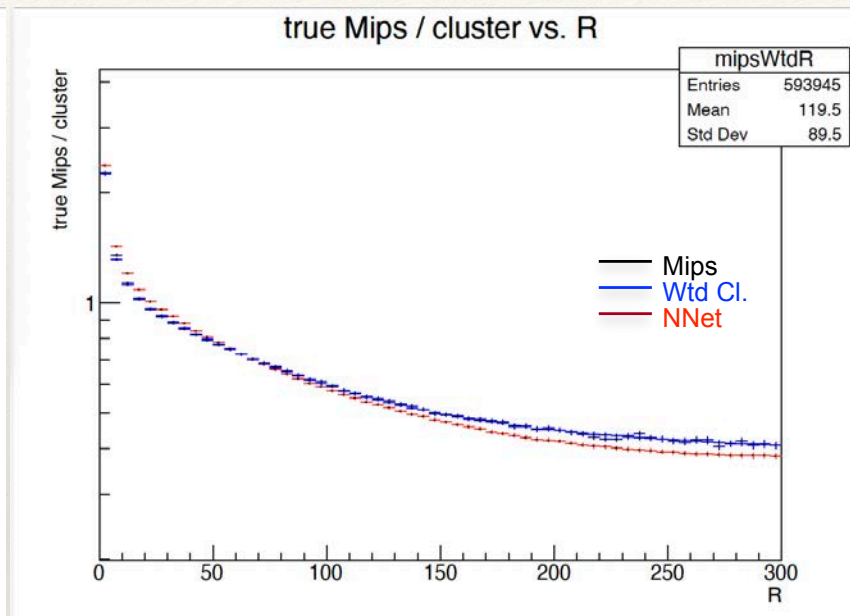
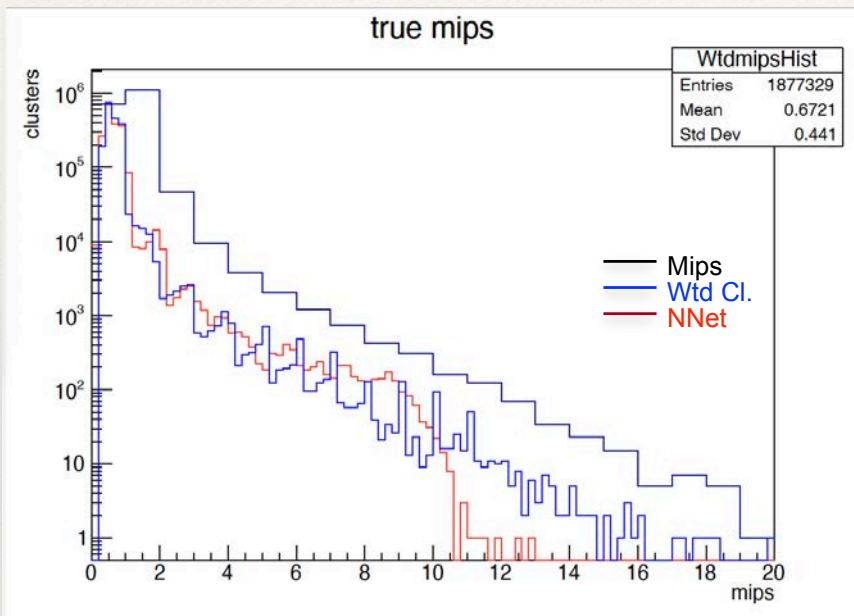
Energy	1	2	5	10	20	50
clusters	13.8%	10.1%	6.6%	5.0%	3.7%	2.7%
wtd clusters	12.3%	8.8%	5.7%	4.4%	3.2%	2.2%
3 par TMVA	12.6%	9.5%	6.2%	4.4%	3.4%	2.2%
5 par TMVA	12.8%	9.4%	5.9%	4.3%	3.1%	2.2%

- ❖ Weight fits for 2, 10, 50 GeV; extrapolated for 1, 5, 20 GeV.
- ❖ NN optimized for each energy
- ❖ 3 par = cluster size, layer, radius
- ❖ 5 par = cluster size, layer, radius, dY , dZ

Weighted clusters already achieve performance of this neural net.



10 GeV γ s





TMVA Code

```
# Define model
model = Sequential()
model.add(Dense(64, activation='tanh', input_dim=5))
model.add(Dense(1, activation='linear'))

# Set loss and optimizer
model.compile(loss='mean_squared_error', optimizer=SGD(learning_rate=0.01), weighted_metrics=[])

# Store model to file
model.save('modelRegression%s.h5'%Efact)
model.summary()

# Book methods
factory.BookMethod(data_loader, TMVA.Types.kPyKeras, 'PyKeras',
                  'H:!',
                  V:VarTransform=D,G:FilenameModel=modelRegression%s.h5:FilenameTrainedModel=trainedModelRegression%s.h5:NumEpochs=20:BatchSize=32'%(Efact,Efact))

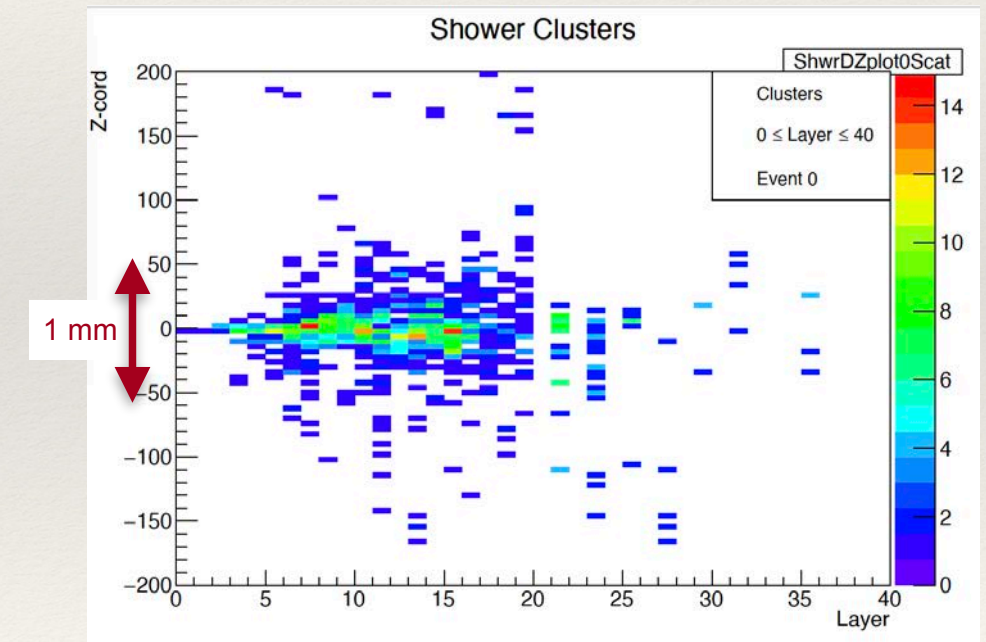
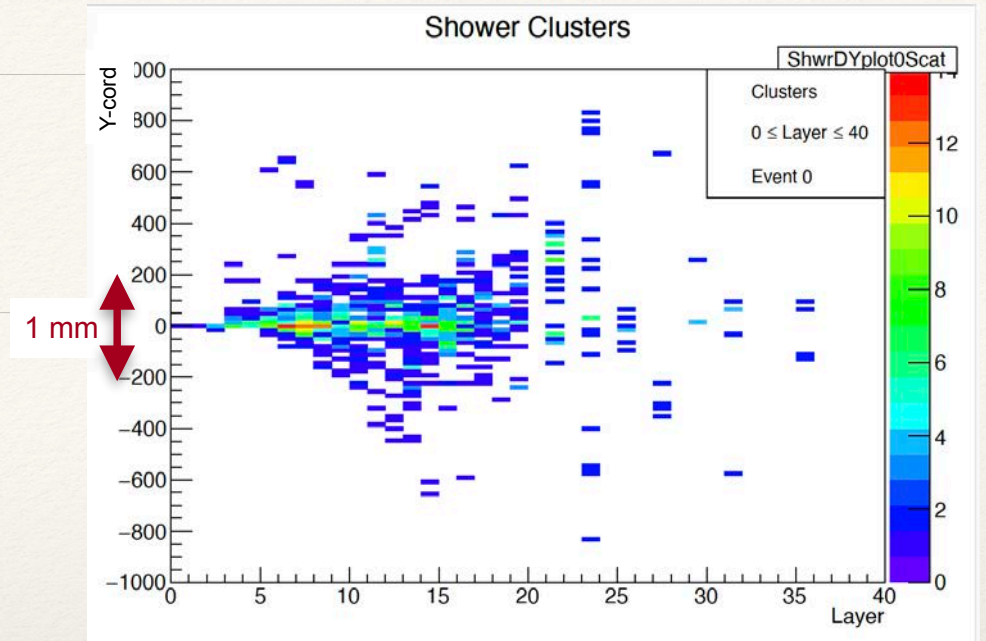
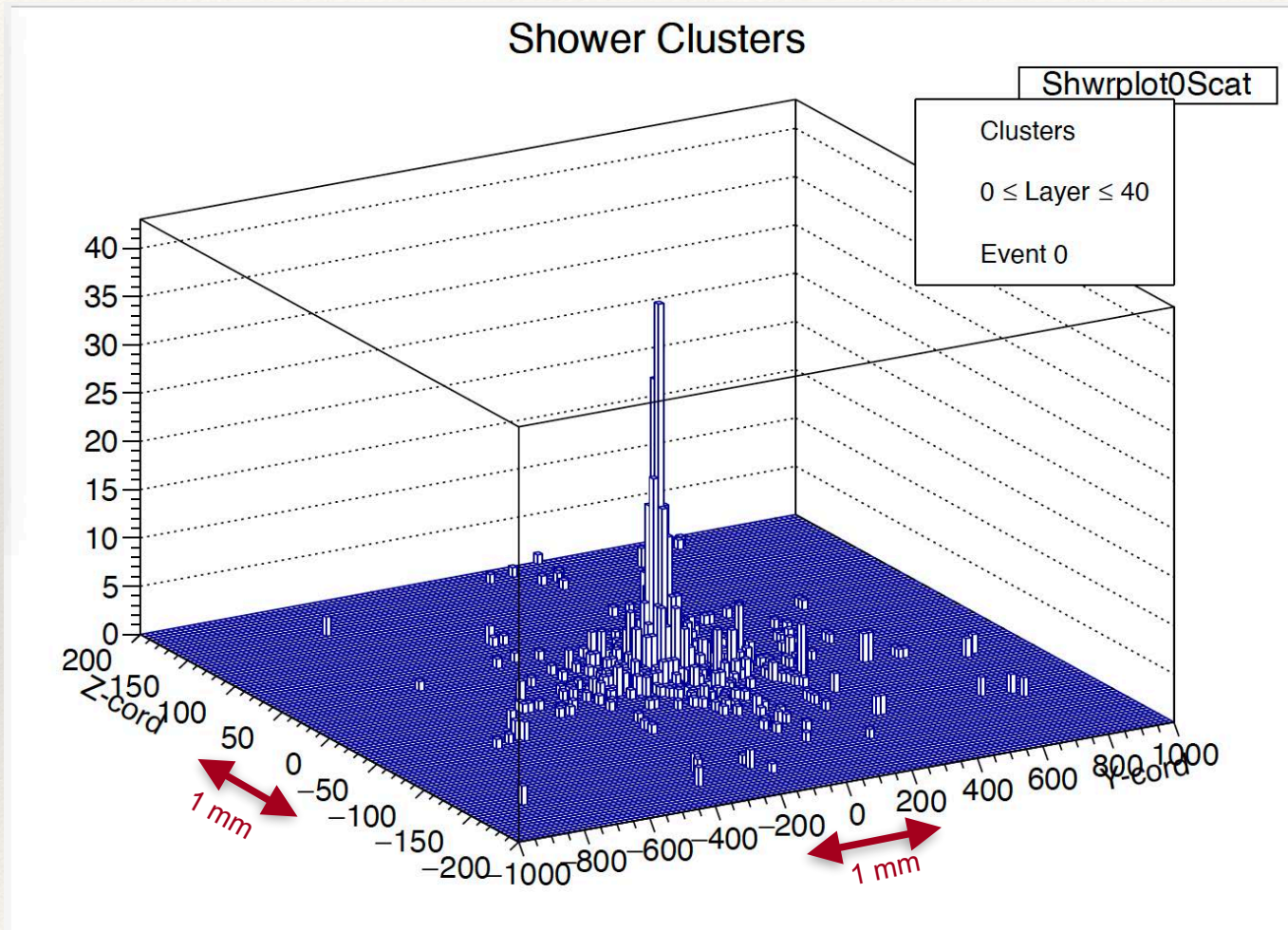
# Run TMVA
factory.TrainAllMethods()
factory.TestAllMethods()
factory.EvaluateAllMethods()
```




Transverse Shower Structure

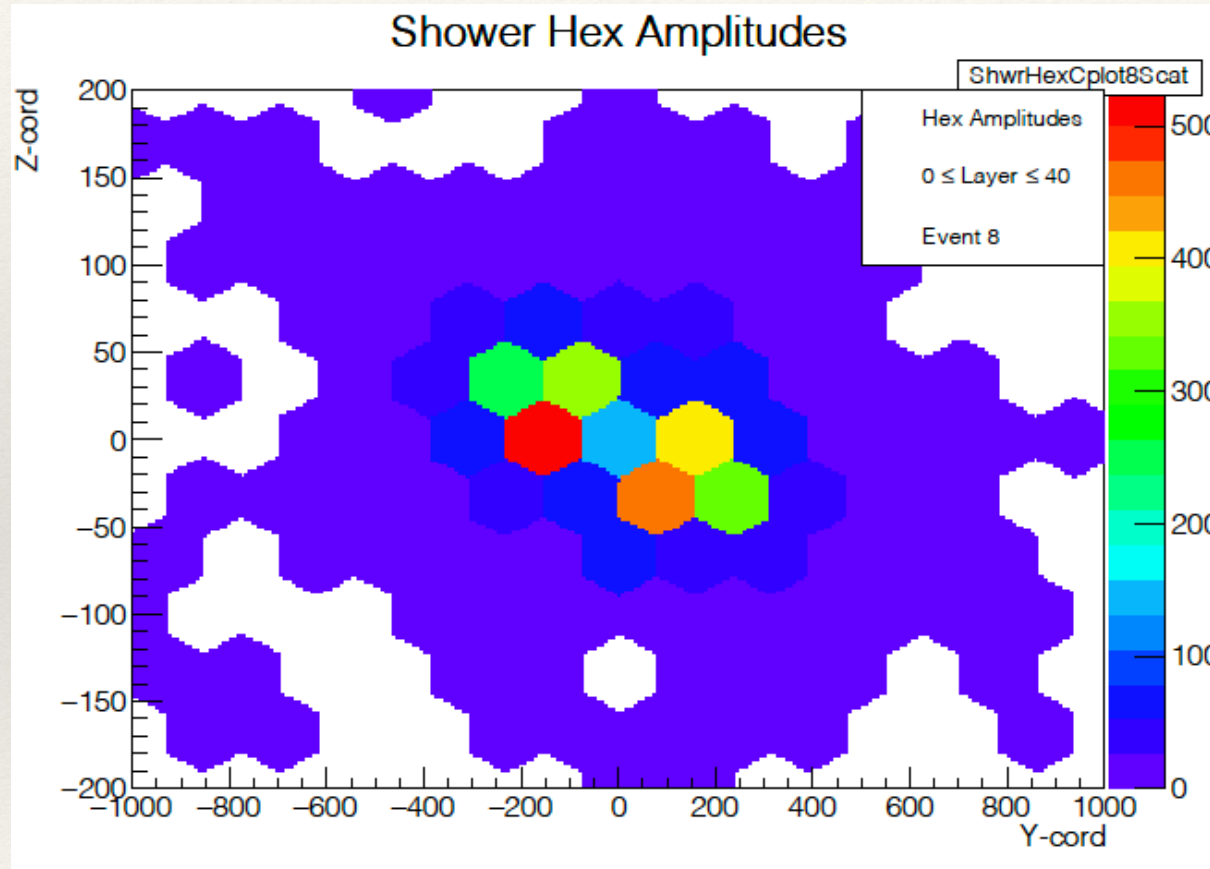


10 GeV Shower

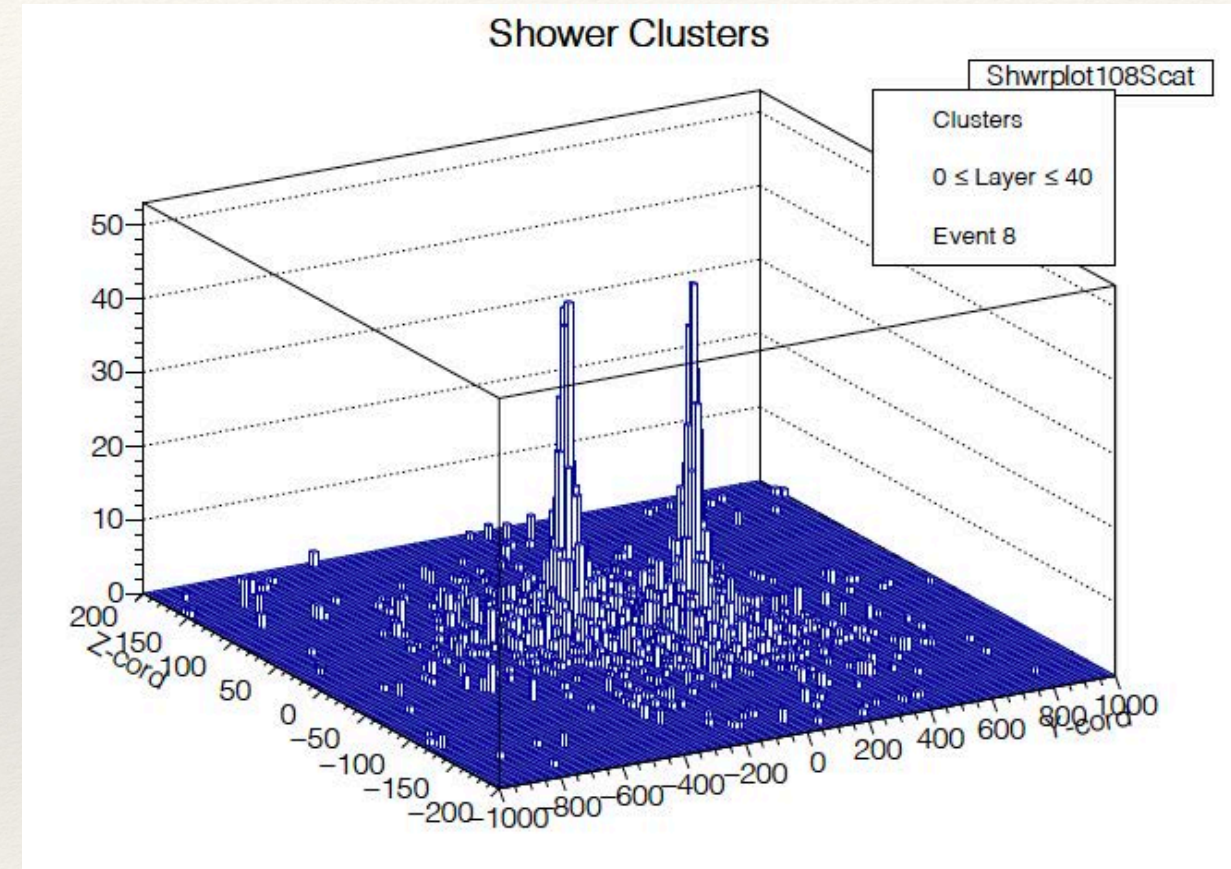


Multi-shower of SiD MAPS compared to SiD TDR

40 GeV $\pi^0 \rightarrow$ two 20 GeV γ 's



SiD TDR hexagonal sensors
13 mm² pixels



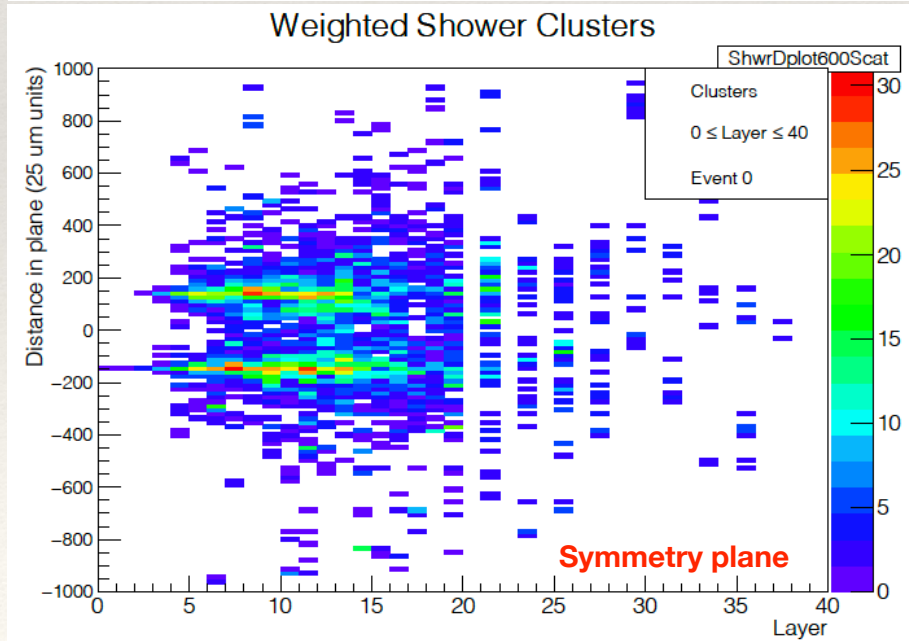
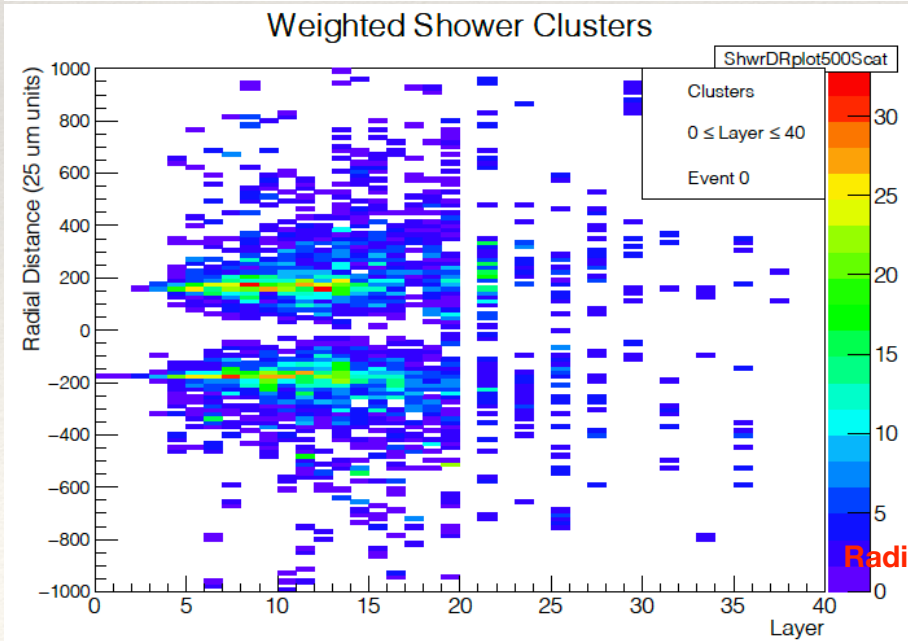
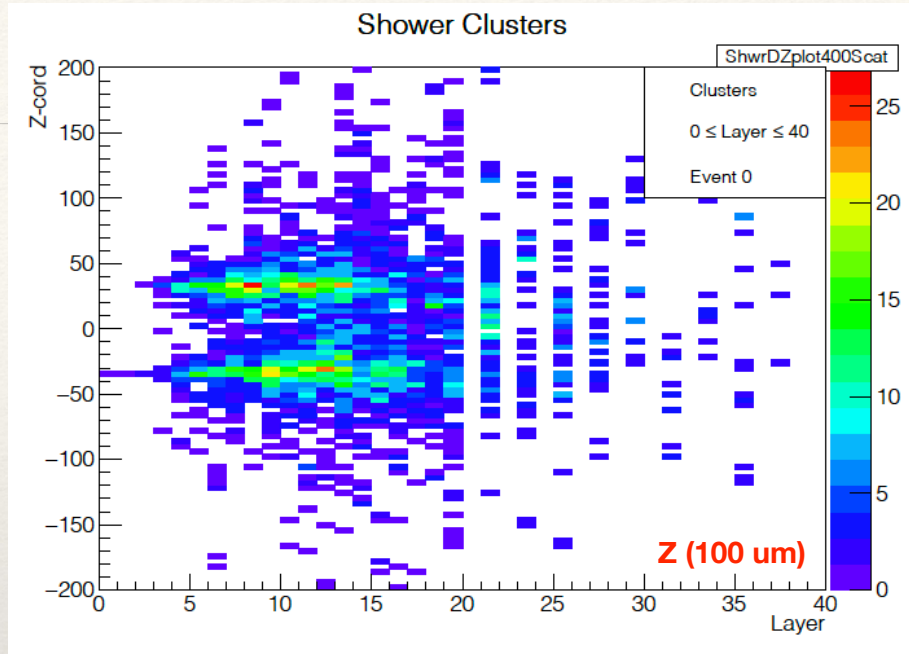
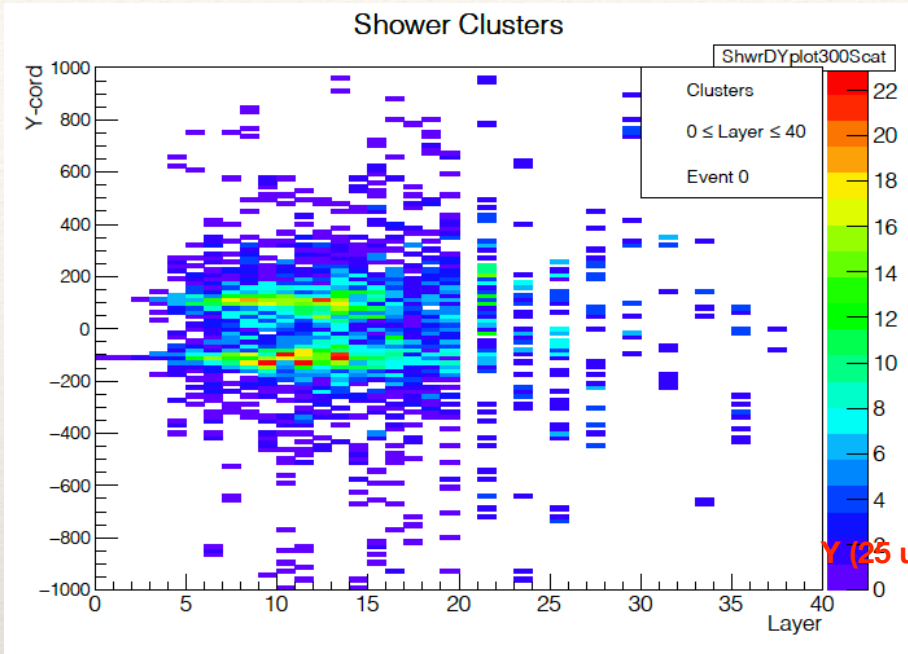
New SiD fine pixel sensors
25 μ m x 100 μ m pixels

40 GeV $\pi^0 \rightarrow$ two 20 GeV γ 's

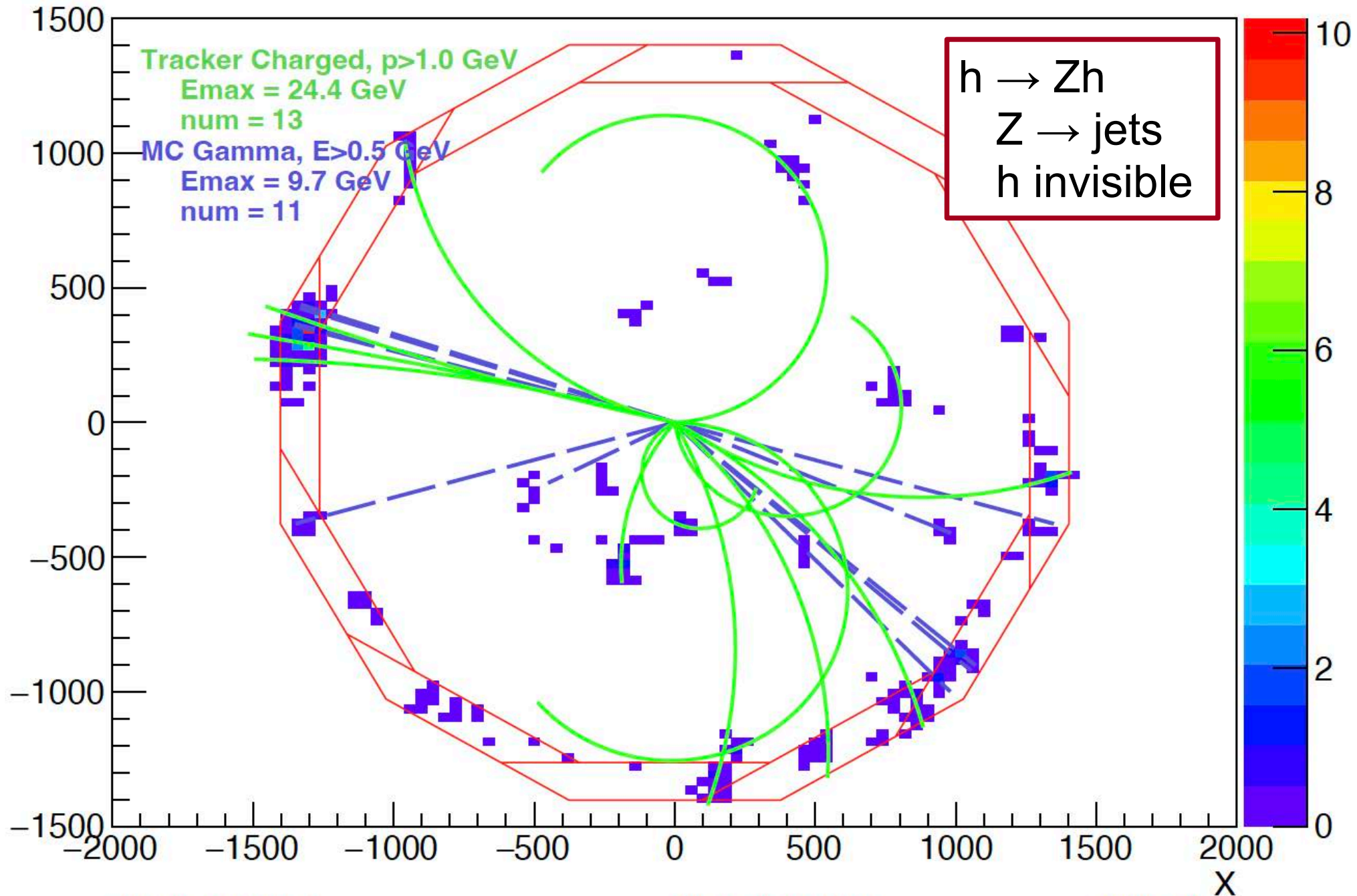


Vertical bin
400 μm

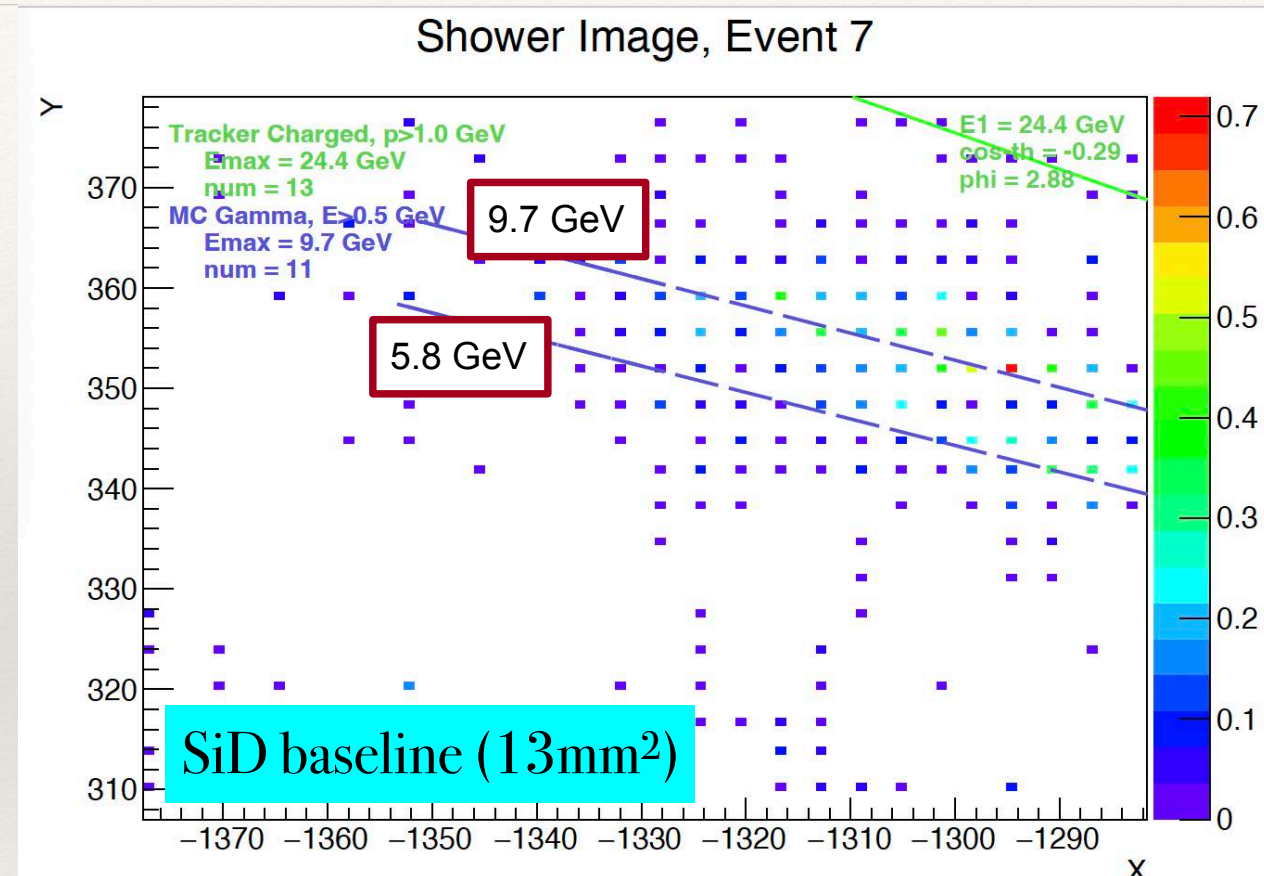
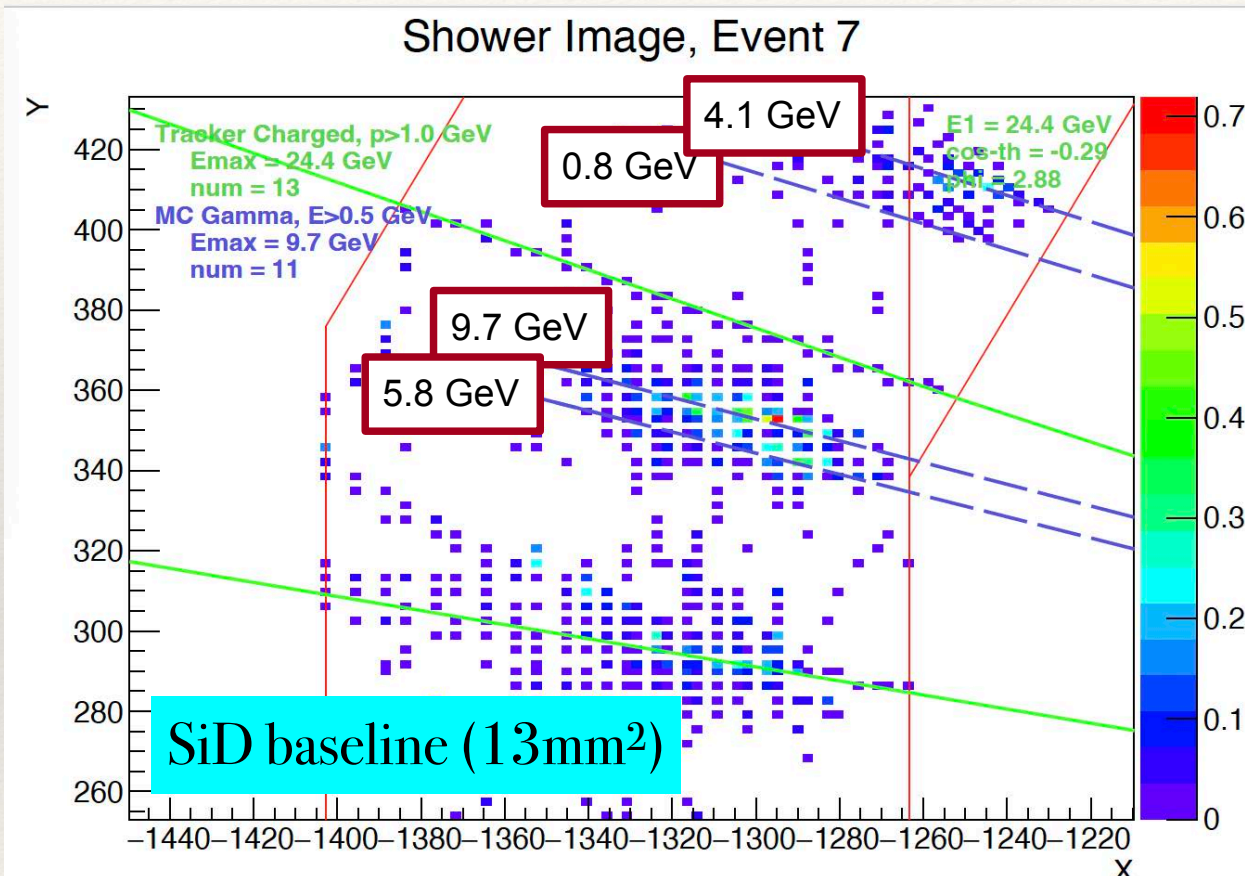
SiD Digital ECAL based on Silicon MAPS J. Brau - 2 November 2023



Shower Image, Event 7



γ 's in jet / SiD baseline ECal (13mm² pixels)



- ❖ 13 mm² pixels of analog SiD ECal
- ❖ 5000x granularity with digital MAPS ECal - What is scale of improvement?



Conclusion

- ❖ Application of monolithic active pixel sensors to SiD digital ECal offers excellent performance:
 - ❖ Energy measurement
 - ❖ Transverse energy containment & multiple shower separation
- ❖ The well defined structure of EM showers allows simple algorithmic improvement in energy measurement.
- ❖ Neural nets have been studied to improve energy measurement:
 - ❖ They have not yet provided improved performance over the simple algorithm.
- ❖ Future - simulation of full SiD detector with high granularity of MAPS ECal