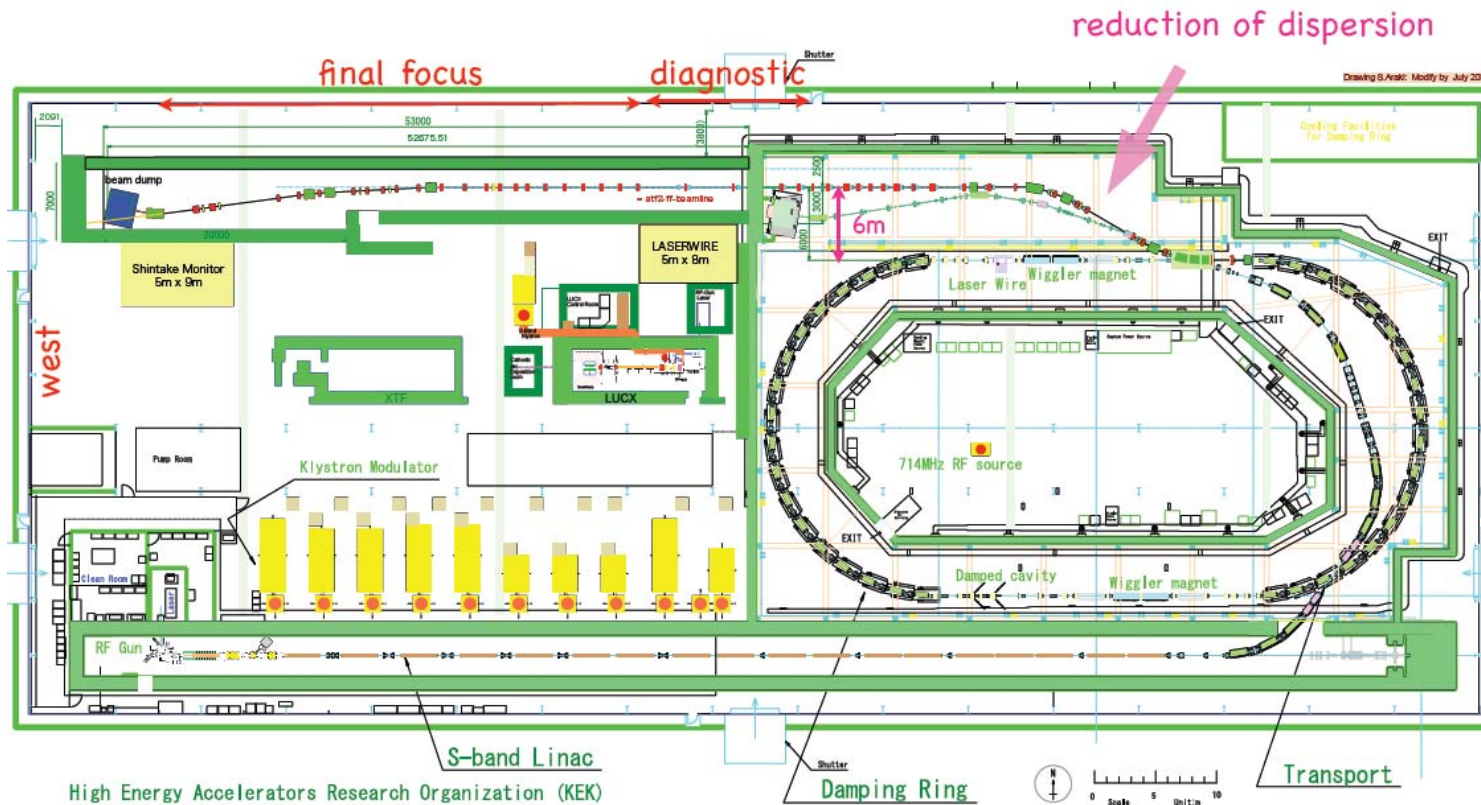
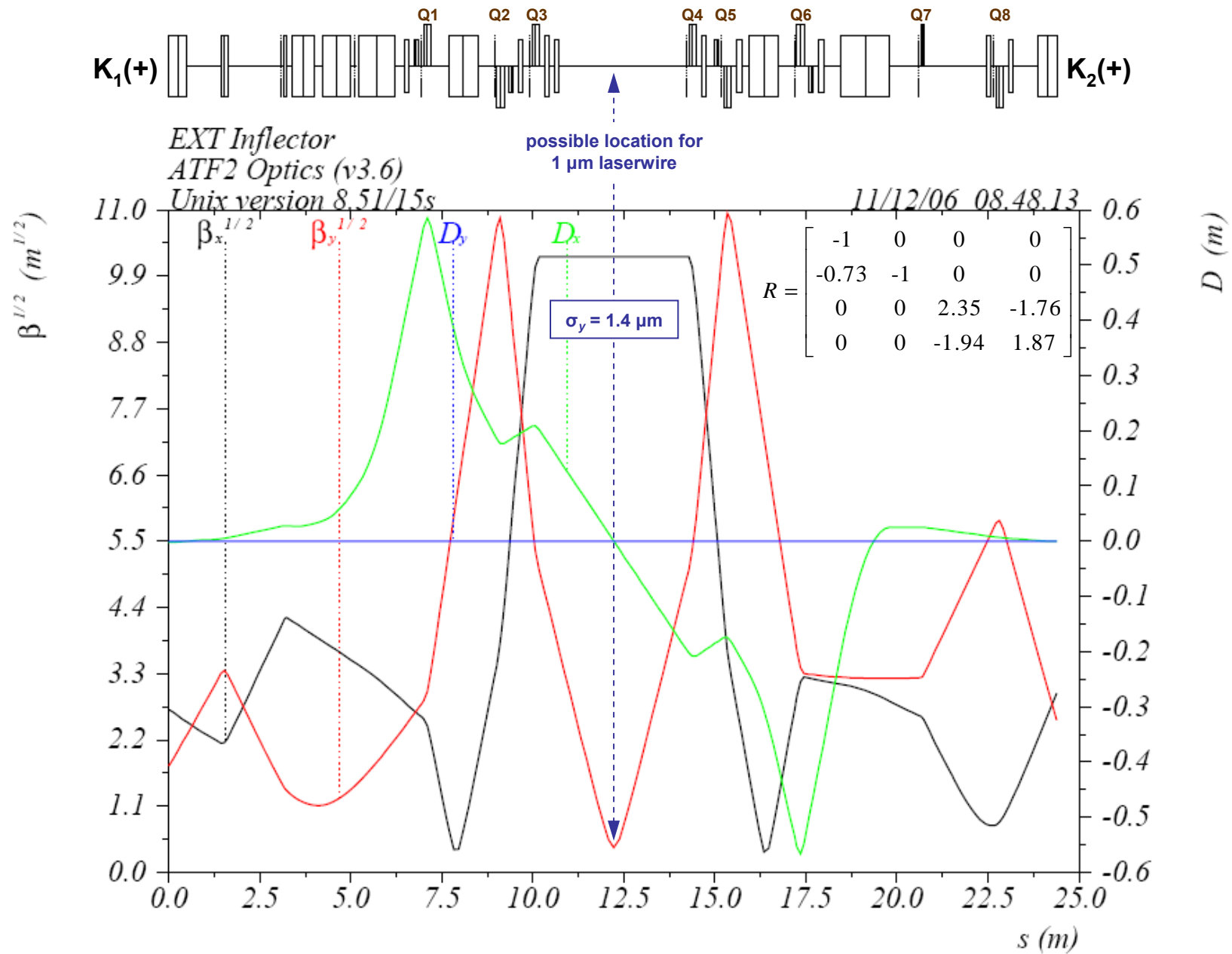




Correction of Anomalous Vertical Dispersion in the ATF2 EXT Line (v3.6)

Optics v3.5, 1 July 2006





For MAD files see <http://www.slac.stanford.edu/~mdw/ATF2/v3.6>

Simulation Parameters

- use Peter Tenenbaum's Lucretia¹ simulation code
- included
 - perfect beam from Damping Ring ($\epsilon_x=2\times 10^{-9}$ m, $\gamma\epsilon_y=3\times 10^{-8}$ m) ... errors begin after extraction septa, unless otherwise noted
 - perfect Final Focus
 - dipole errors²: $\Delta Y = 100 \mu\text{m}$ (rms)
 - quadrupole errors: $\Delta X = 50 \mu\text{m}$, $\Delta Y = 30 \mu\text{m}$, $\Delta\theta = 0.3 \text{ mrad}$ (rms)
 - sextupole errors: $\Delta X = 50 \mu\text{m}$, $\Delta Y = 30 \mu\text{m}$, $\Delta\theta = 0.3 \text{ mrad}$ (rms)
 - BPM resolution: $5 \mu\text{m}$ (rms)
- *not* included
 - quadrupole strength errors ($\Delta K/K$)
 - BPM offsets
 - BPM rolls
 - wire scanner rolls: $|\theta| \leq 0.2^\circ$ (uniform)
 - wire scanner beam size errors: $\sigma = \sigma_0(1+\Delta\sigma_{\text{relative}})+\Delta\sigma_{\text{absolute}}$
 - coupling errors in the DR extraction channel
 - tuning in FF

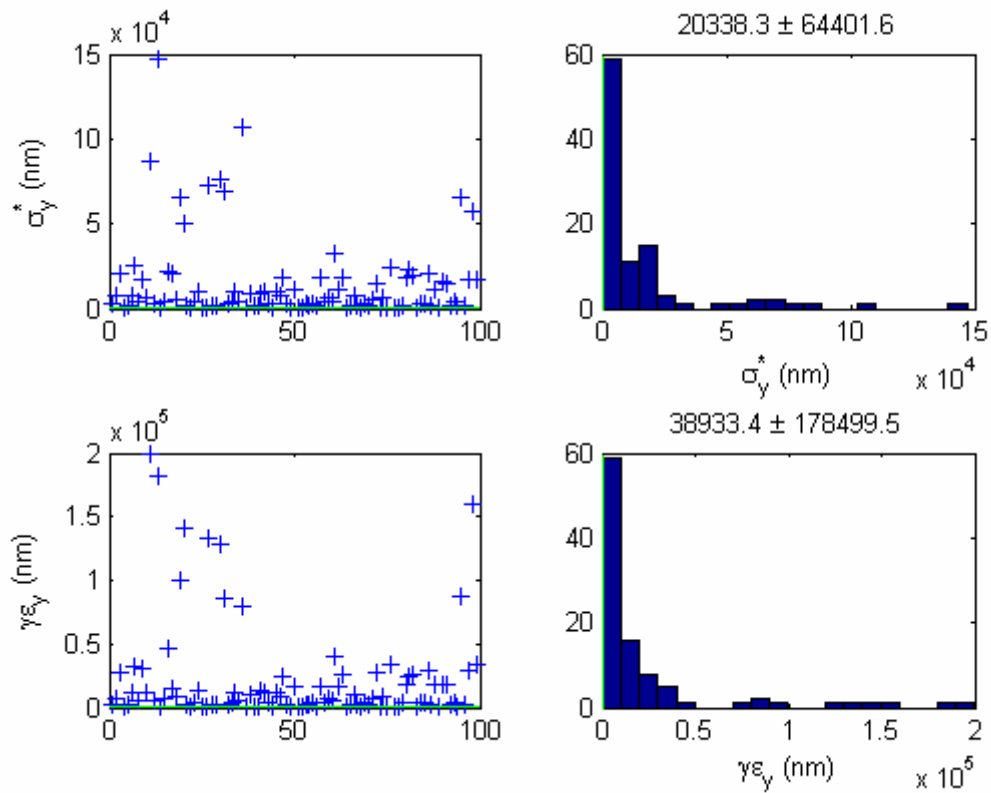
¹<http://www.slac.stanford.edu/accel/ilc/codes/Lucretia/>

²EXT dipoles BH1 and BH2 are assumed to have nonzero sextupole components

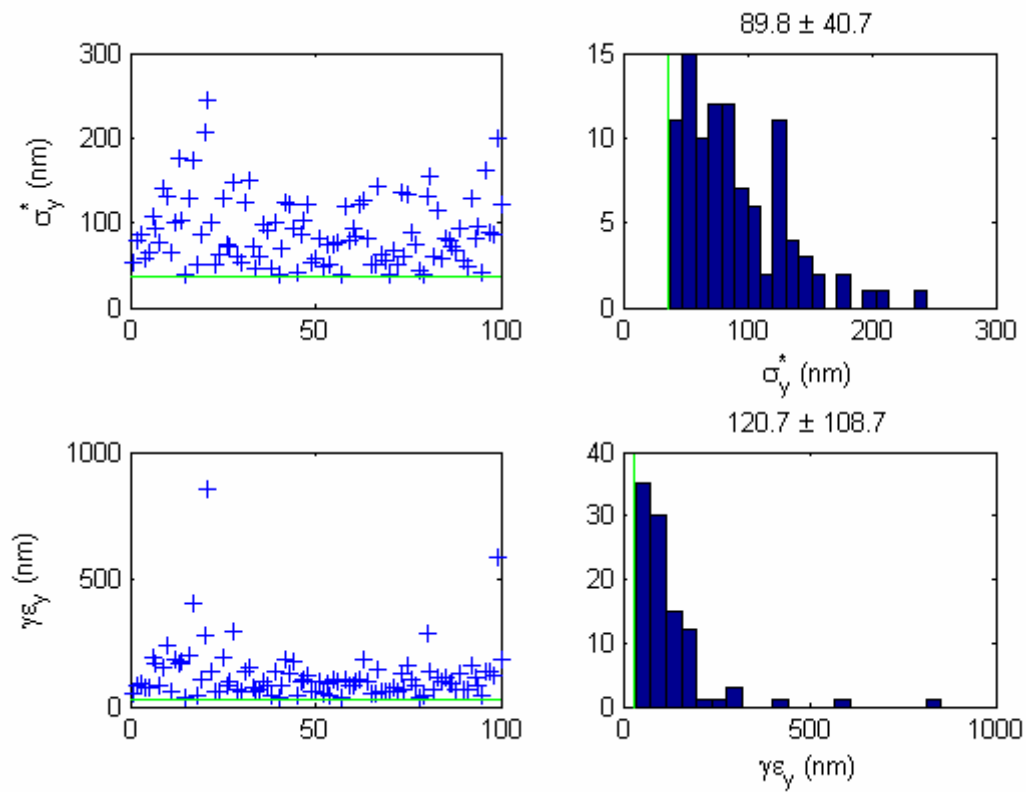
Simulation Procedure

1. apply errors
2. steer flat (EXT only)
3. launch into FF
 - use 2 virtual correctors
 - steer to 2 virtual BPMs (one at the IP and one 90° upstream)
 - virtual BPMs are perfect
4. measure dispersion in diagnostic section
 - scan input beam energy
 - measure orbits
 - fit position vs energy at each BPM ... linear correlation is η
 - back-propagate measured η to start of diagnostic section to get η_0 and η'_0
5. correct dispersion in diagnostic section
 - use QF1X + QF6X multiknobs for η_x and η'_x
 - correct η_y using skew quads in inflector (thin lenses at quad centers)
6. correct coupling
 - scan 4 skew quadrupoles sequentially
 - deduce projected ϵ_y from wire scanner measurements
 - set each skew quad to minimize projected ϵ_y

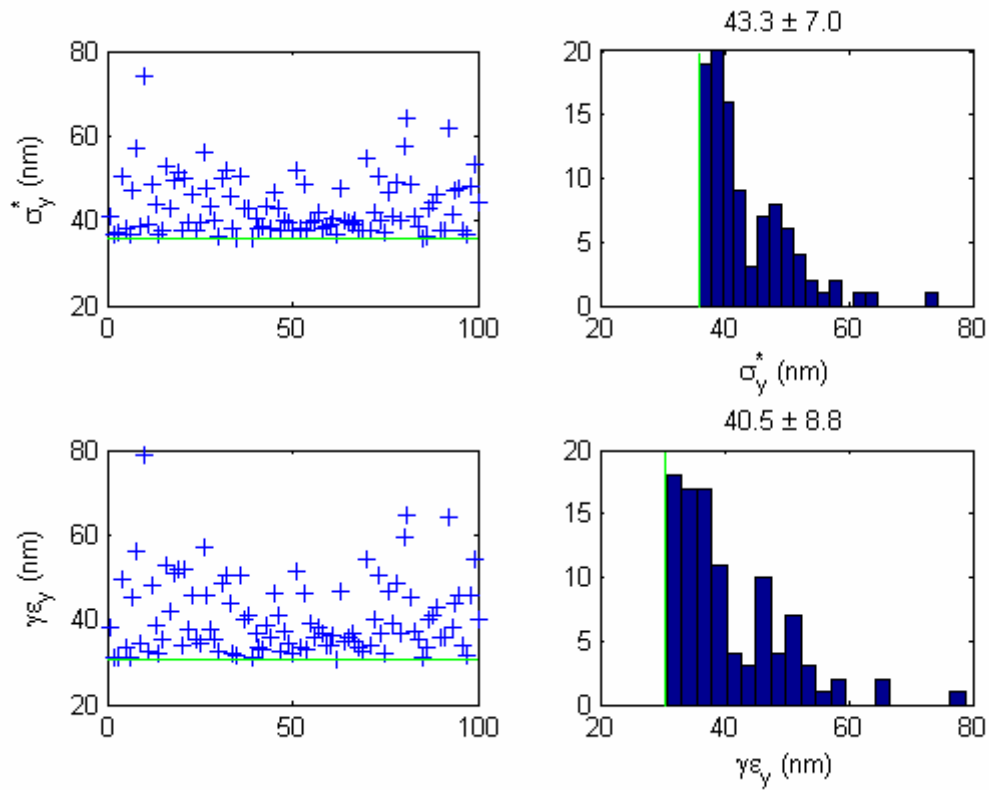
errors only (100 seeds)



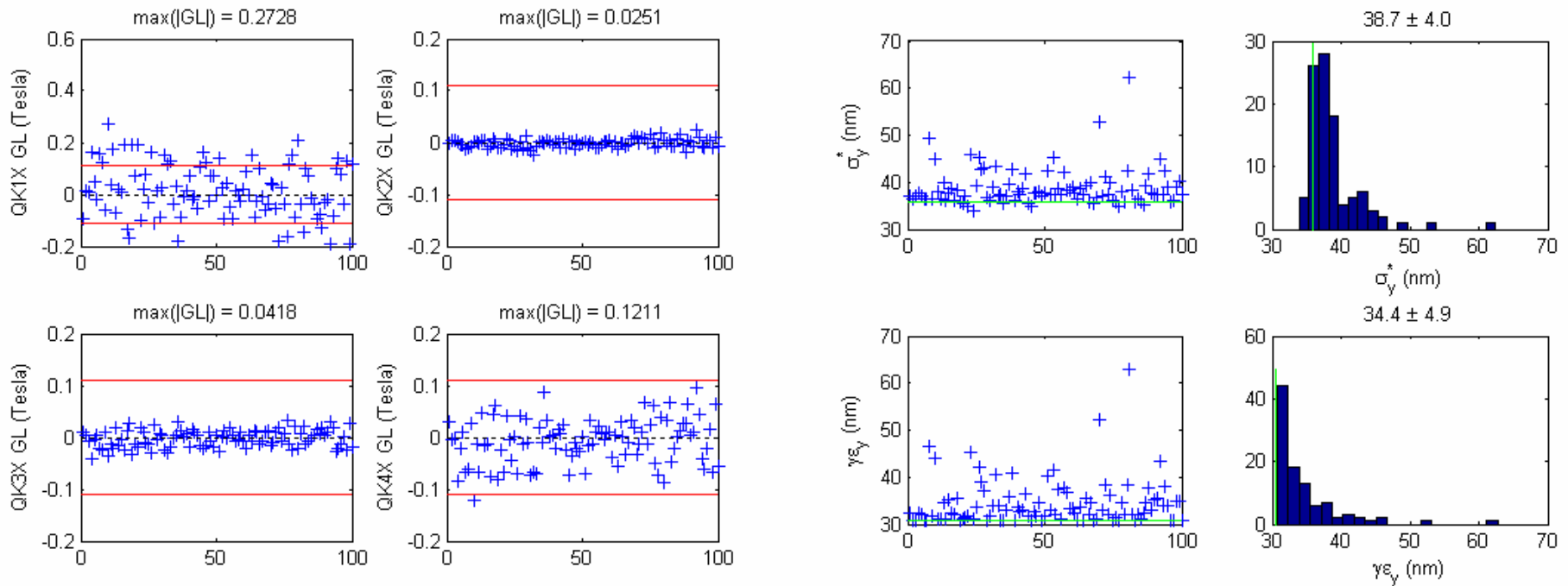
errors, FF launch



errors, steer flat, FF launch

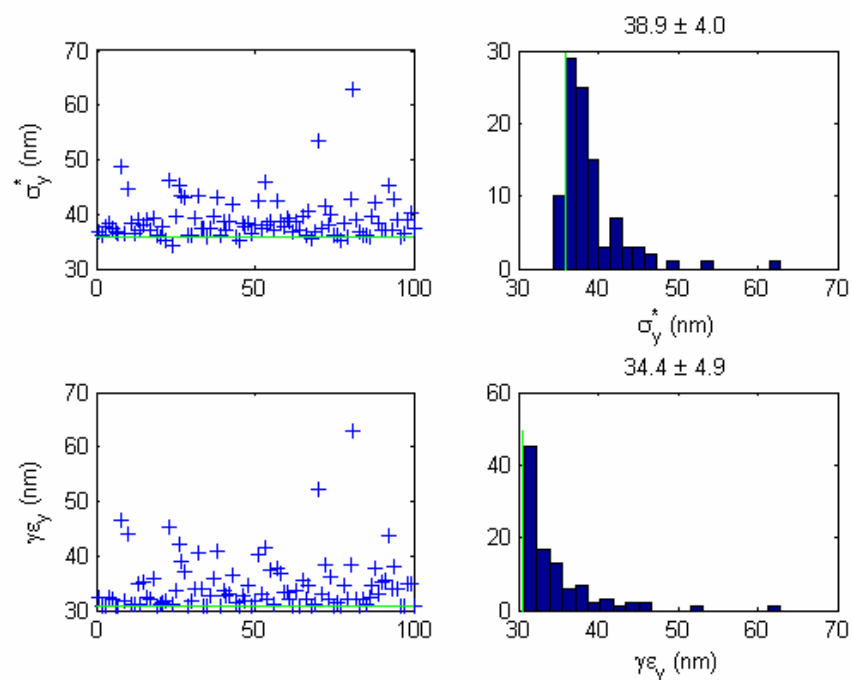
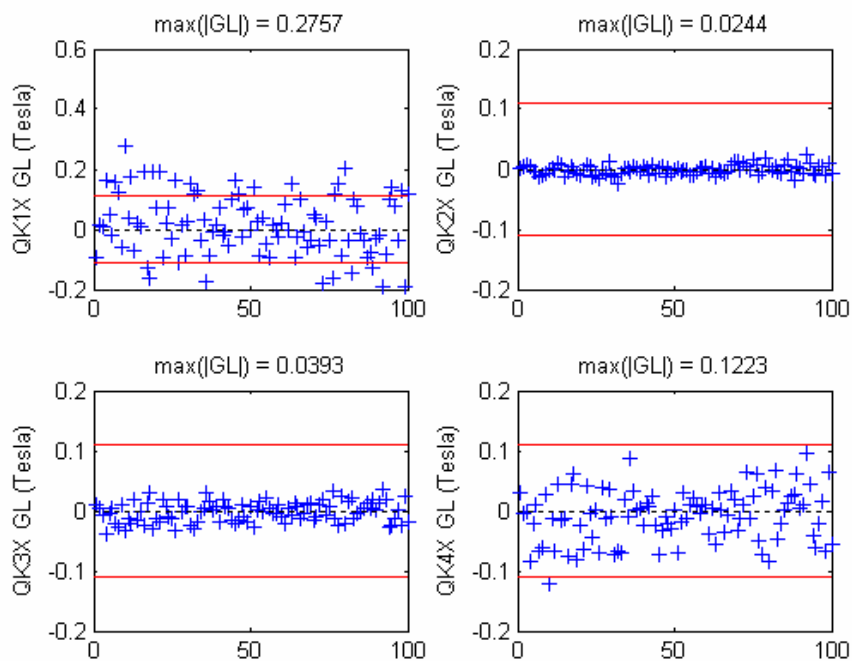


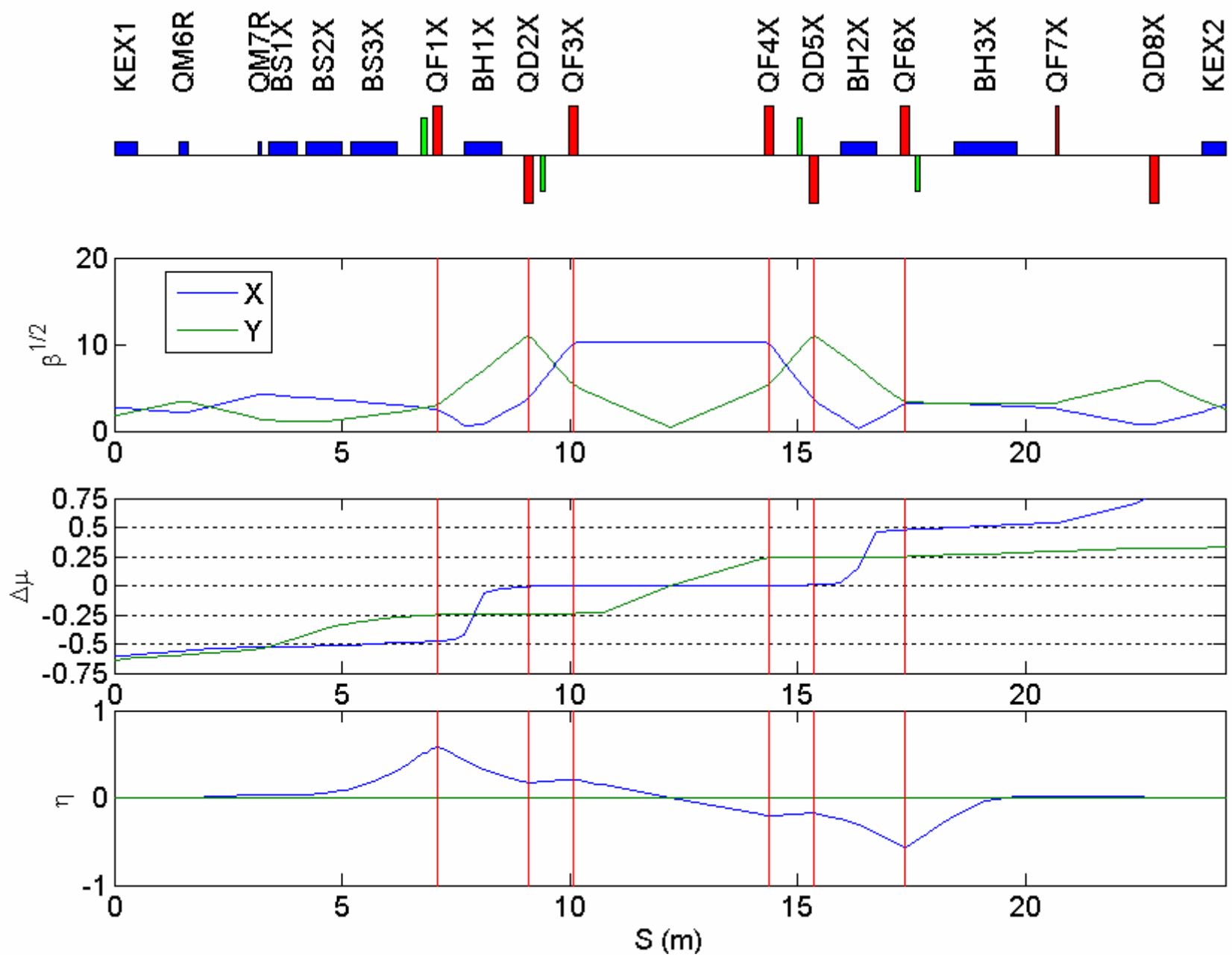
errors, steer flat, correct coupling, FF launch

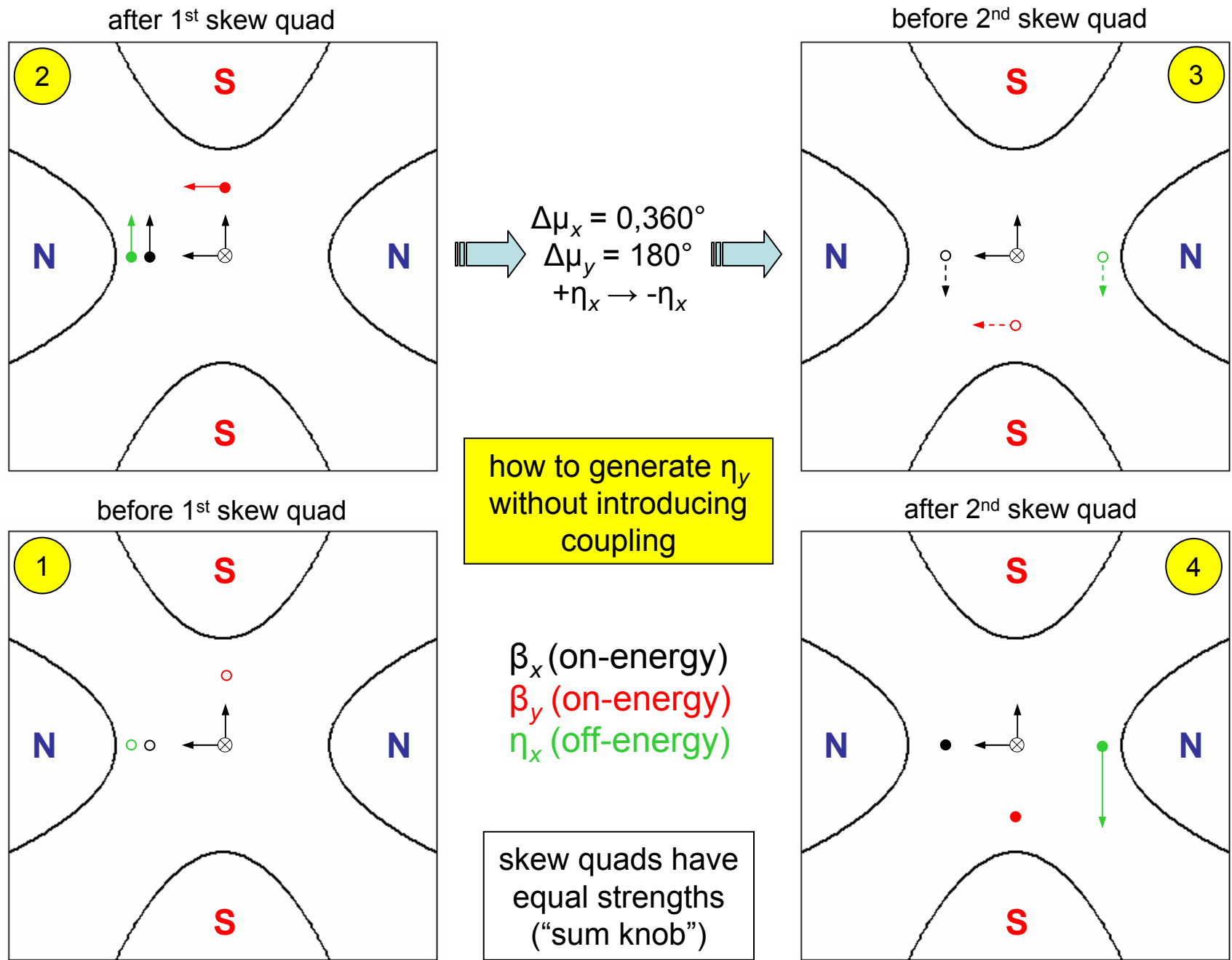


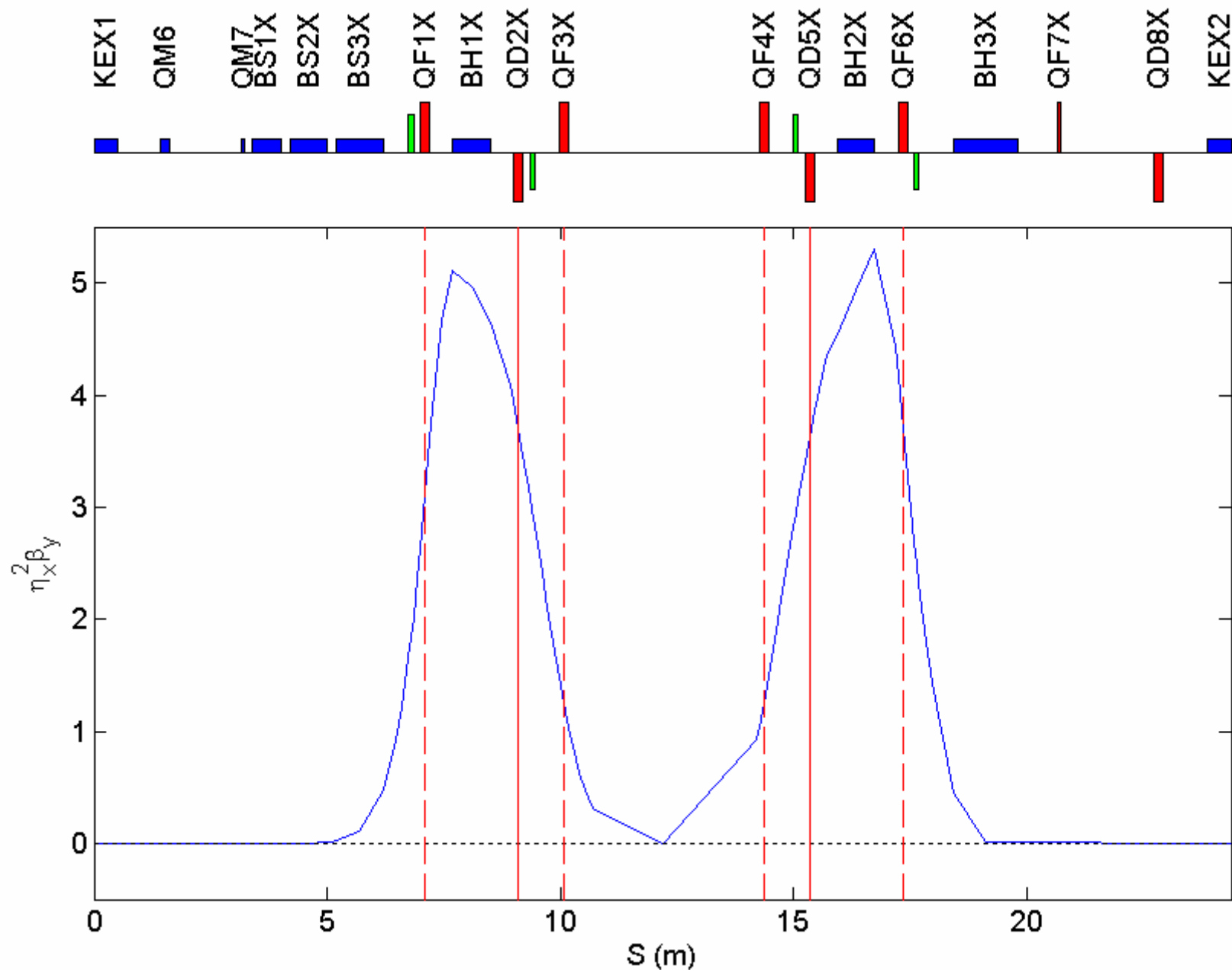
Note: red lines represent maximum integrated strength of IDX-type skew quadrupole (KLmax \approx 0.1 T @ 5 amp)

errors, steer flat, correct η_x , correct coupling, FF launch









η_y correction: residual x-y coupling

$$R = \begin{bmatrix} R_{11} & R_{12} & R_{13} & R_{14} \\ R_{21} & R_{22} & R_{23} & R_{24} \\ R_{31} & R_{32} & R_{33} & R_{34} \\ R_{41} & R_{42} & R_{43} & R_{44} \end{bmatrix} \equiv \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

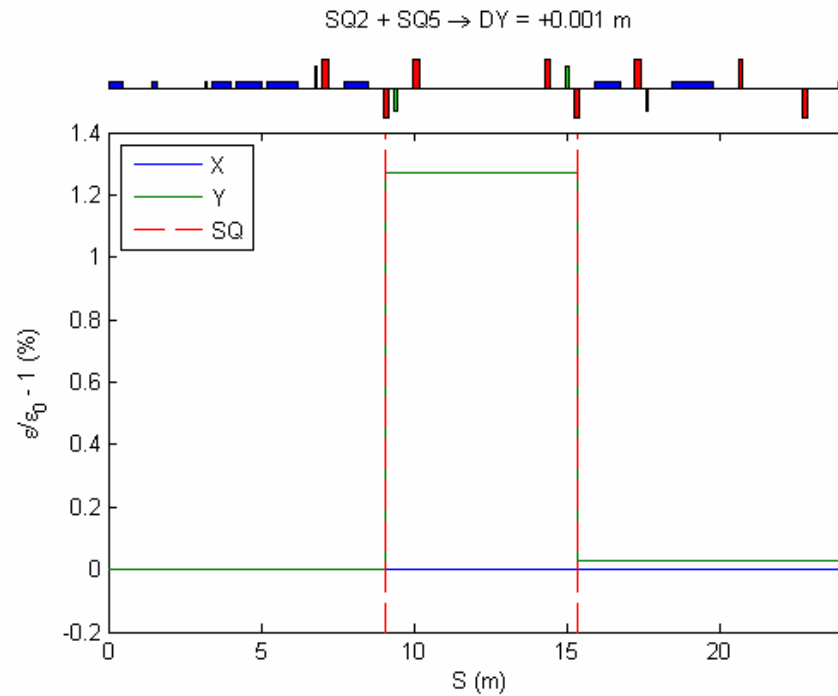
$$Q_{x,y} \equiv \frac{1}{\sqrt{\beta_{x,y}}} \begin{bmatrix} \beta_{x,y} & 0 \\ -\alpha_{x,y} & 1 \end{bmatrix}$$

$$P \equiv Q_x^{-1} A^{-1} B Q_y$$

$$\lambda = \text{tr}(PP^T)$$

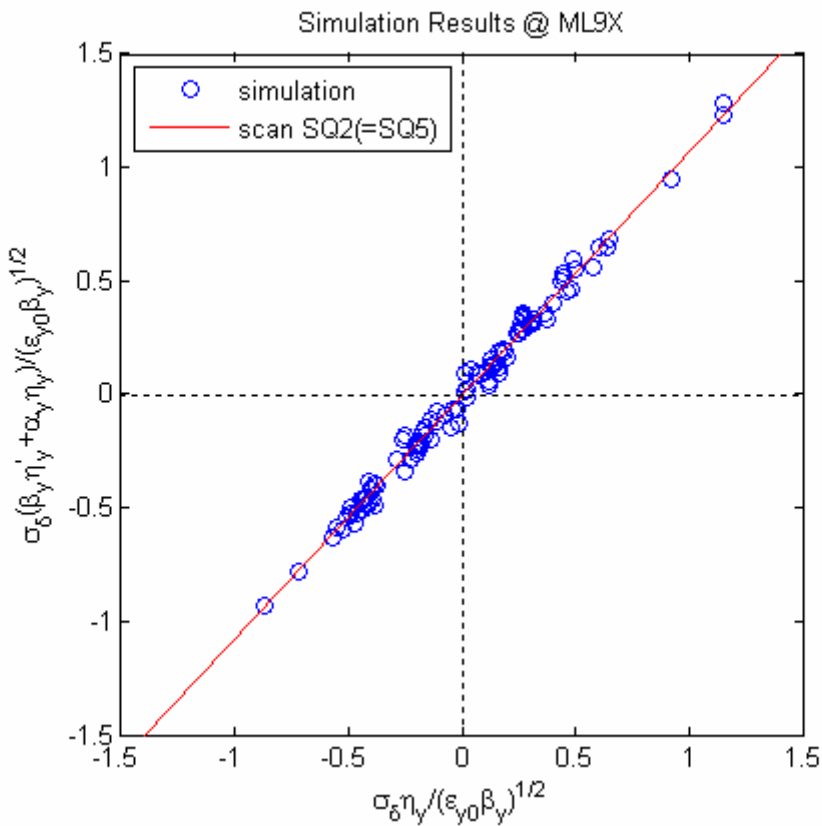
$$\epsilon_x^2 = |A|^2 \epsilon_{x0}^2 + |C|^2 \epsilon_{y0}^2 + |A|^2 \epsilon_{x0} \epsilon_{y0} \lambda$$

$$\epsilon_y^2 = |C|^2 \epsilon_{x0}^2 + |A|^2 \epsilon_{y0}^2 + |A|^2 \epsilon_{x0} \epsilon_{y0} \lambda$$



	SQ2	SQ5
β_x	14.557	13.494
α_x	-18.187	18.354
η_x	0.177	-0.174
β_y	118.109	119.830
α_y	10.711	-12.069
$\Delta\mu_x$	-	5.337
$\Delta\mu_y$	-	172.957
kl/klmax	0.012	0.012
residual	0.0003	

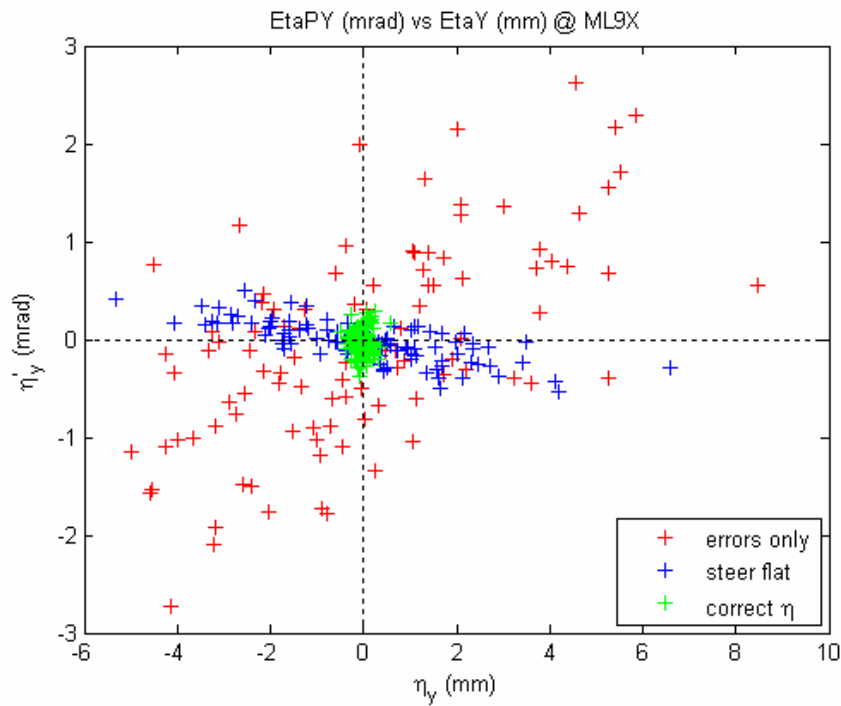
η_y and η'_y at ML9X (start of diagnostic section)
after steering EXT flat (100 seeds)



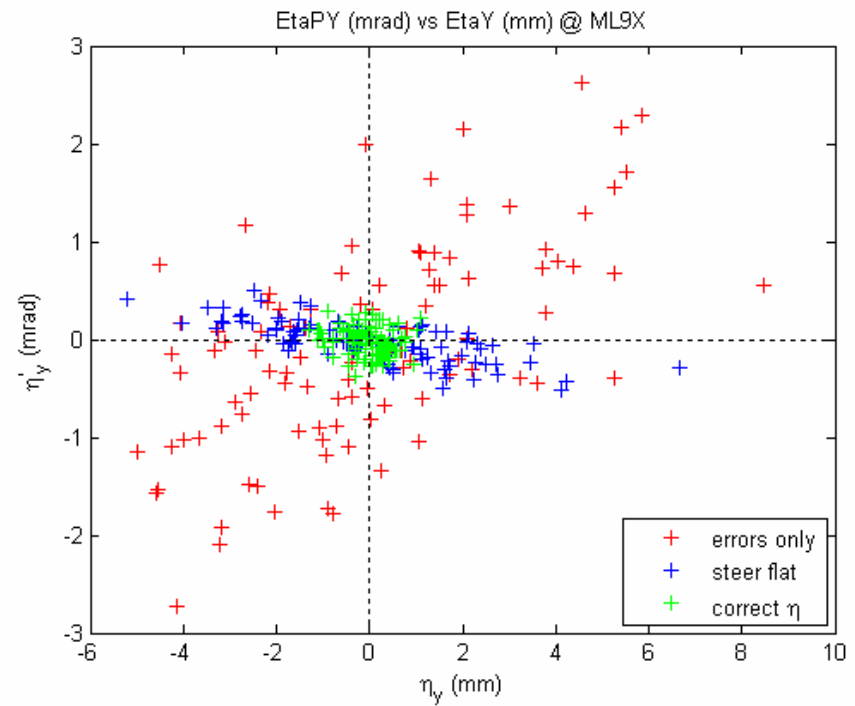
$$\frac{\epsilon_y}{\epsilon_{y0}} = \sqrt{1 + \sigma_\delta^2 \left\{ \frac{\eta_y^2 + (\beta_y \eta'_y + \alpha_y \eta_y)^2}{\epsilon_{y0} \beta_y} \right\}}$$

@ ML9X: $\beta_y = 1.675$ m, $\alpha_y = 1.195$

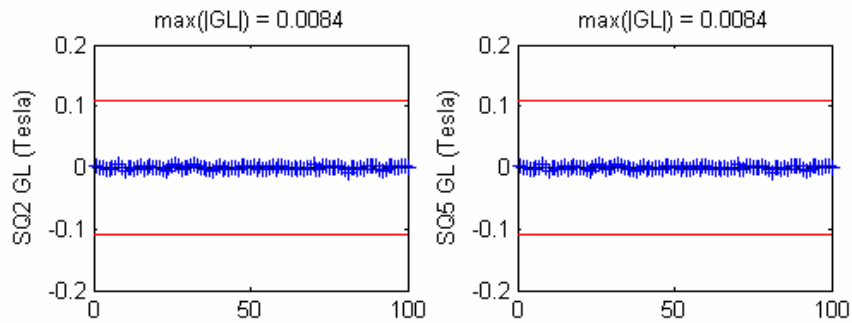
use SQ2 and SQ5 for η_y correction



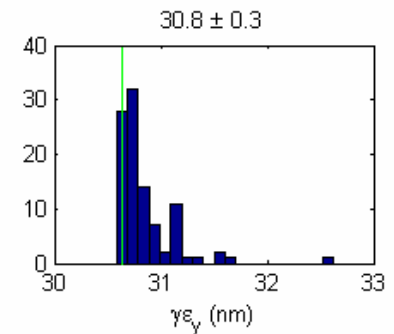
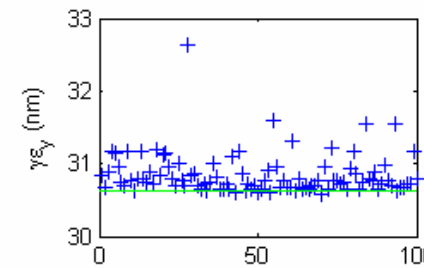
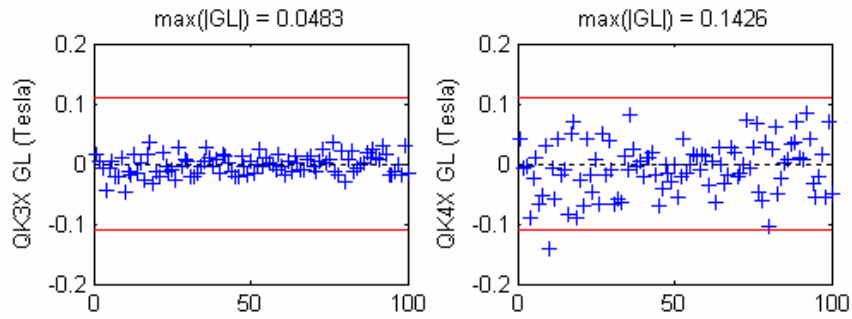
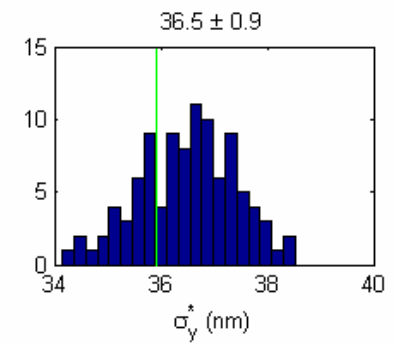
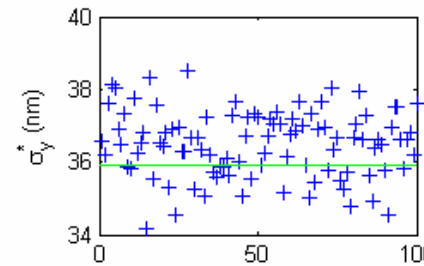
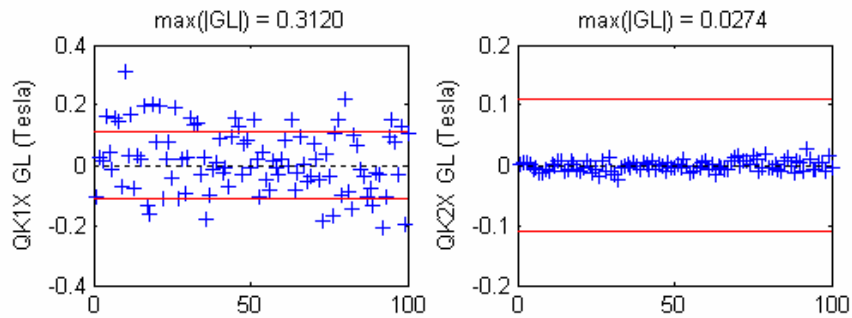
BPM resolution = 0

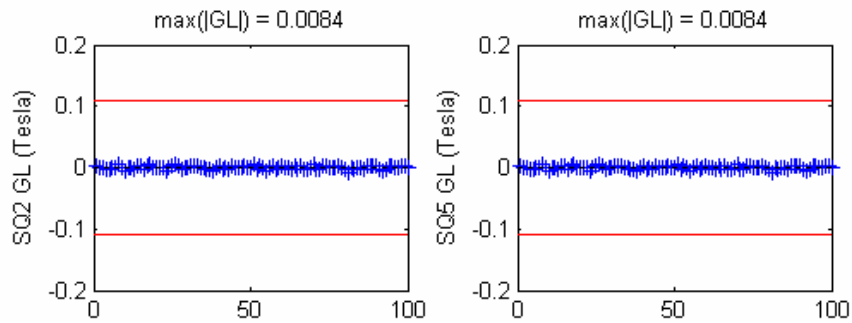


BPM resolution = 5 μm

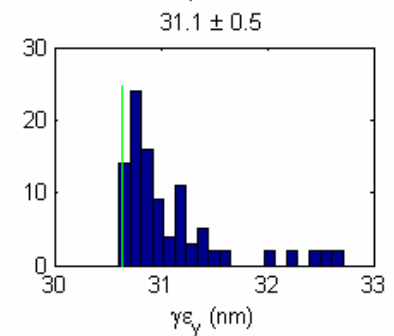
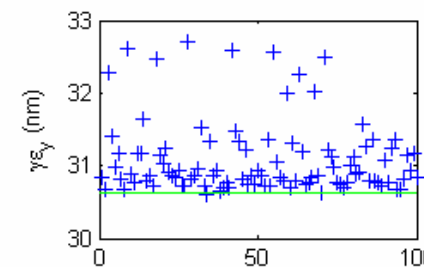
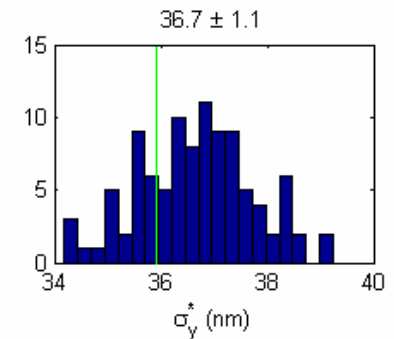
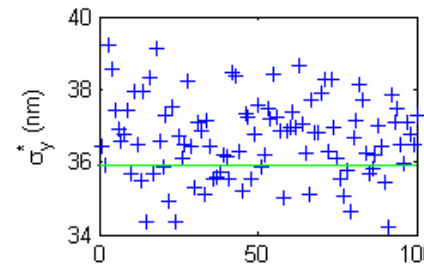
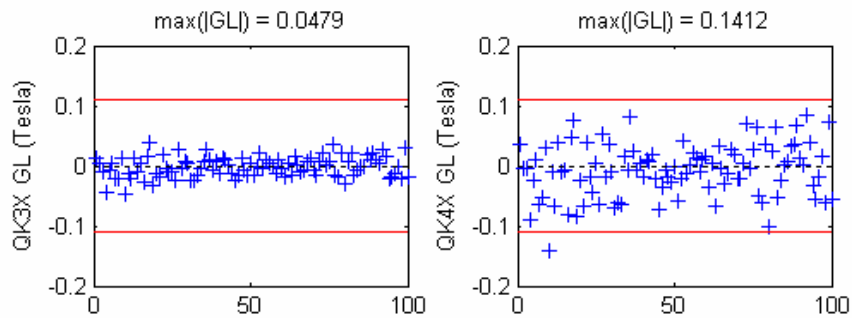
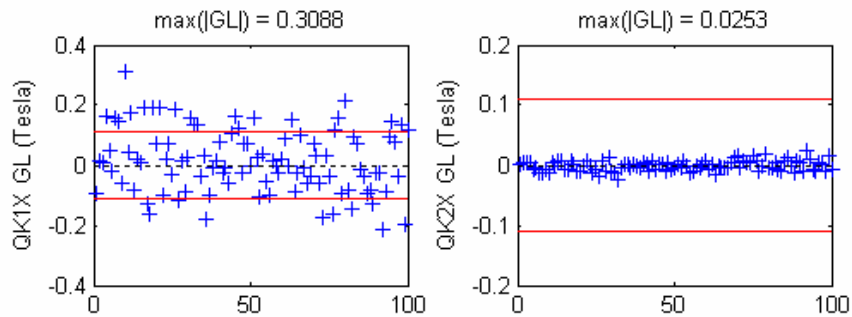


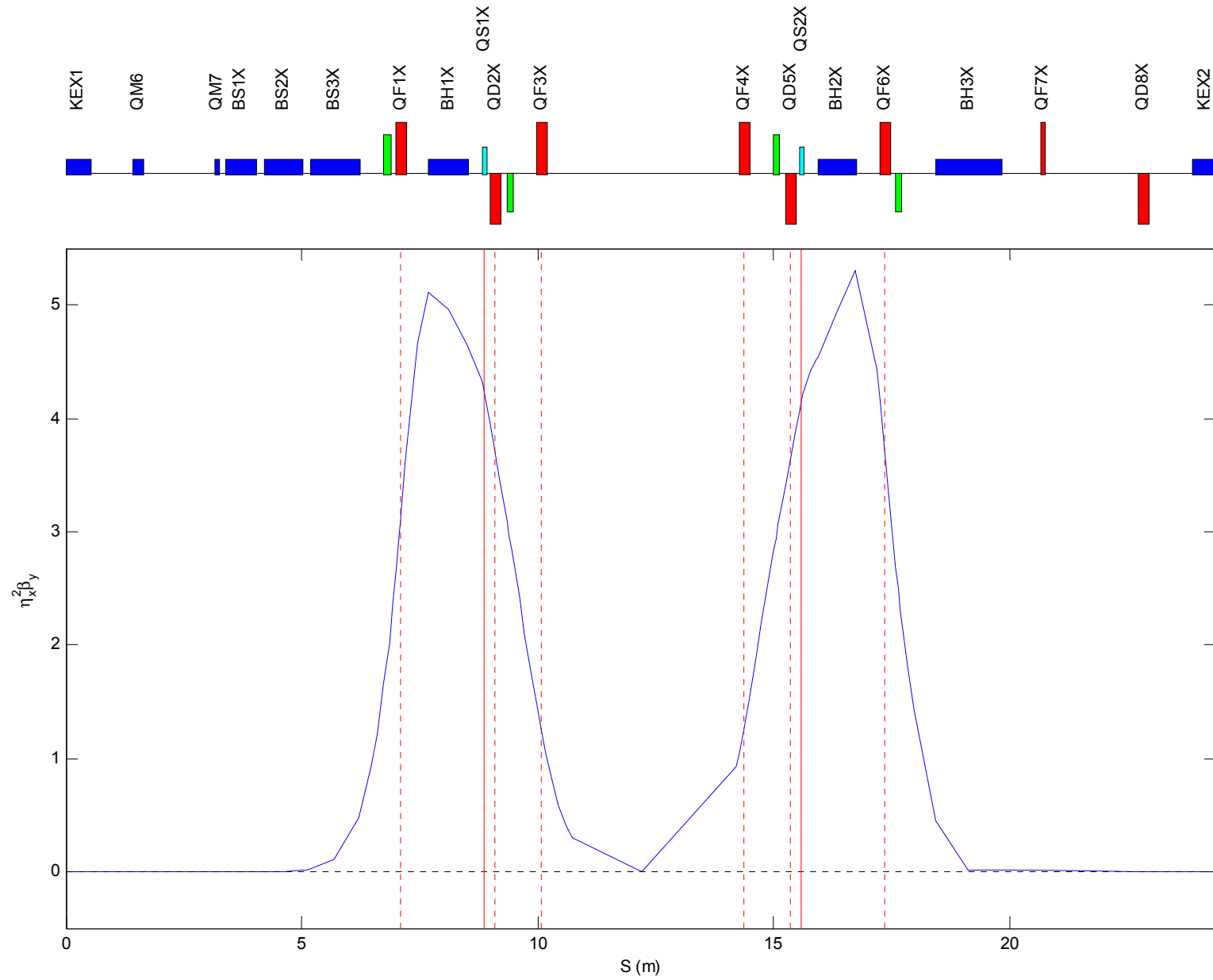
use SQ2 and SQ5 for η_y correction
(BPM resolution = 0)

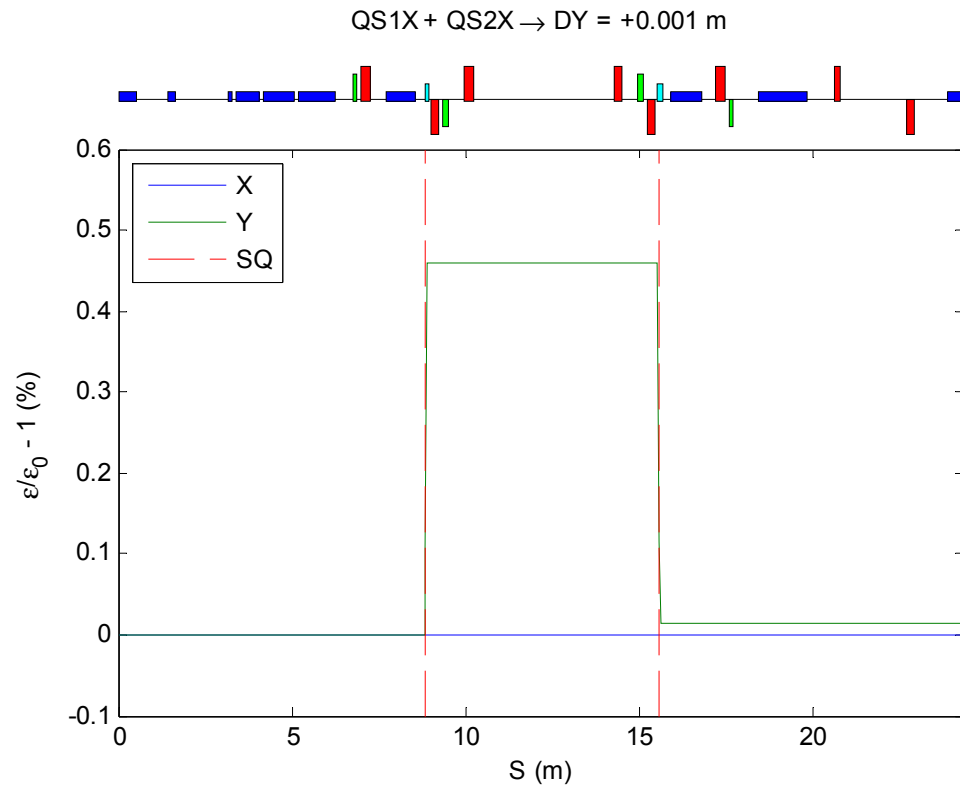




use SQ2 and SQ5 for η_y correction
(BPM resolution = 5 μm)

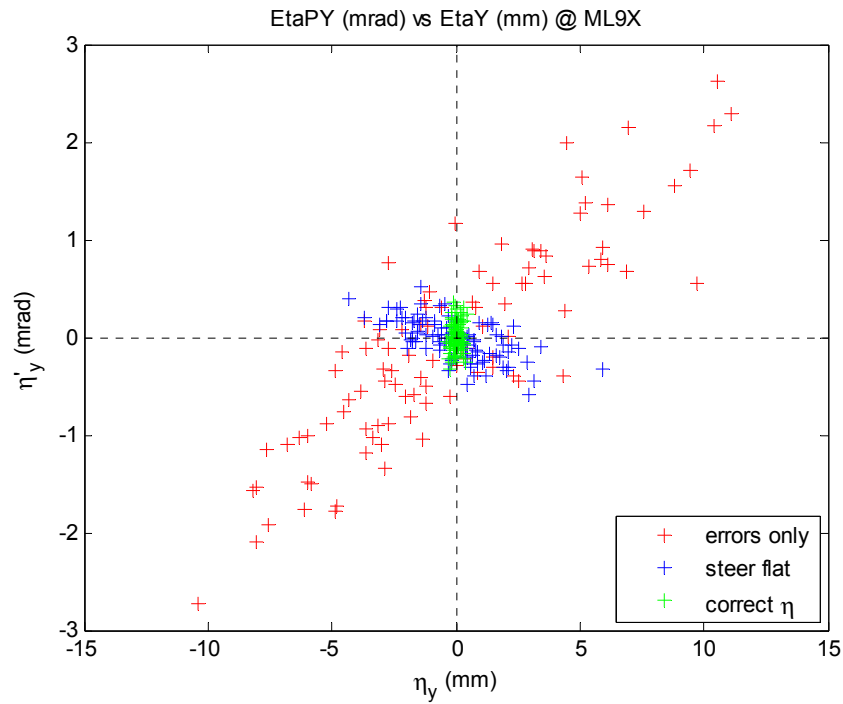




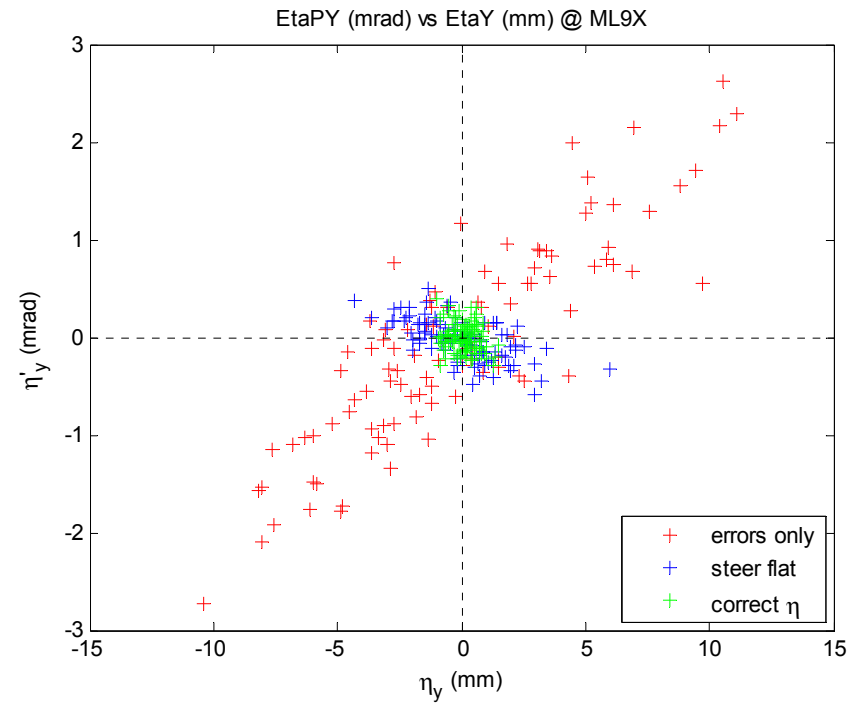


	QS1X	QS2X
β_x	= 9.005	9.005
α_x	= -9.192	9.192
η_x	= 0.203	-0.203
β_y	= 102.805	102.805
α_y	= -41.677	41.677
$\Delta\mu_x$	= -	7.710
$\Delta\mu_y$	= -	173.207
k_l/k_{lmax}	= 0.121	0.121
residual	= 0.0001	

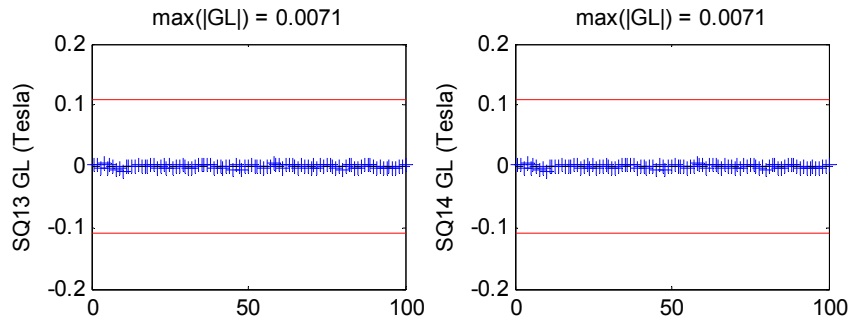
use QS1X and QS2X for η_y correction



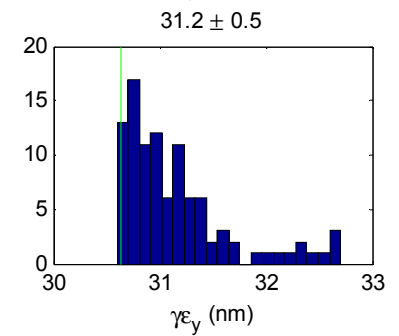
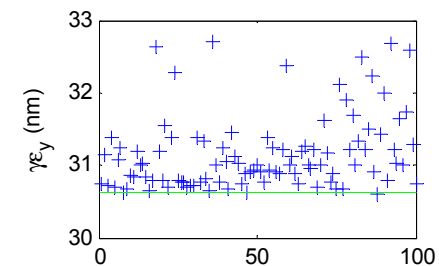
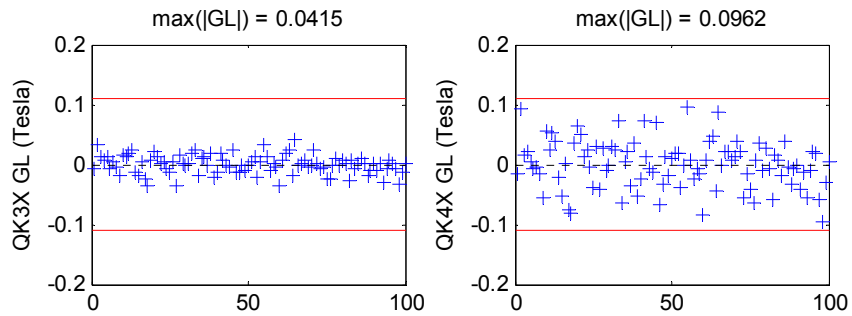
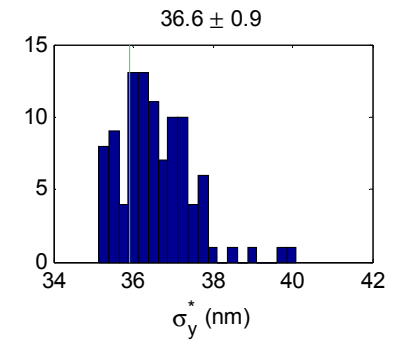
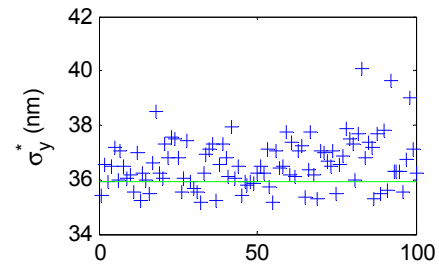
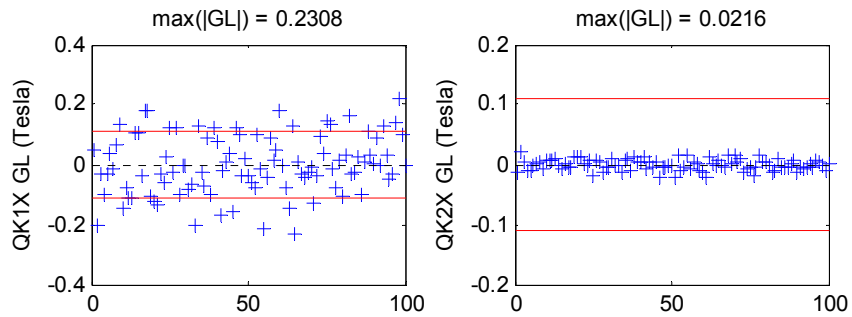
BPM resolution = 0

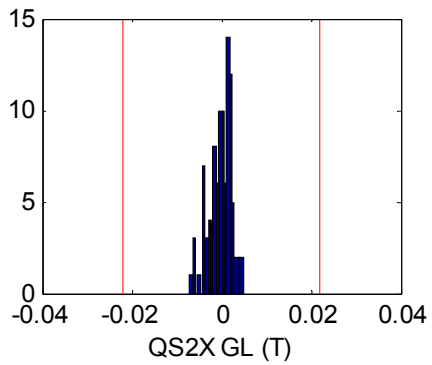
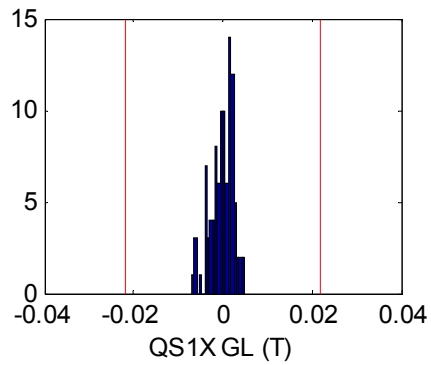


BPM resolution = 5 μm

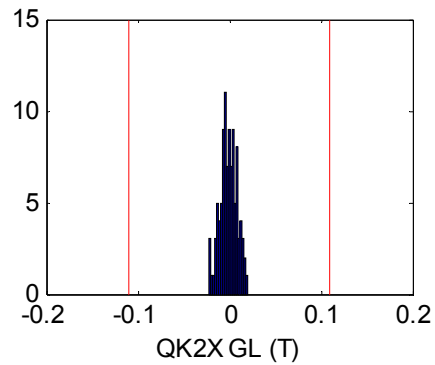
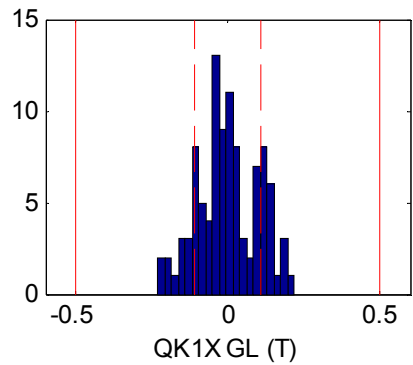


use QS1X and QS2X for η_y correction
(BPM resolution = 5 μm)

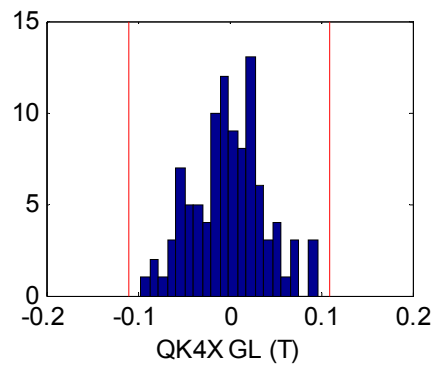
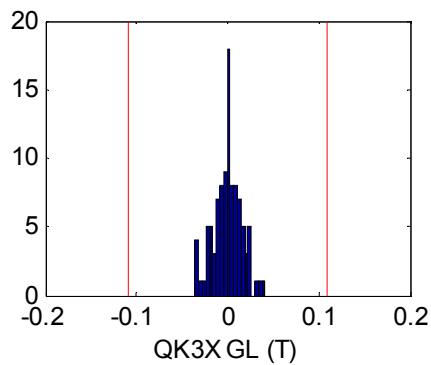




QS1X, QS2X
 GLmax = 0.022 T
 (20% IDX @ 5 amp)



QK1X
 GLmax = 0.5 T
 (Tokin 3393 @ 38 amp)



QK2X, QK3X, QK4X
 GLmax = 0.11 T
 (IDX @ 5 amp)

Conclusions

- simulated system performance, for the given errors and diagnostic resolution, is adequate for the achievement of ATF2 goal “A” (35 nm IP σ_y)
- including vertical dispersion correction provides 5% improvement in IP σ_y (10% in ϵ_y), and can be achieved with two skew quadrupoles (near QD2X and QD5X) with maximum integrated strengths of ≈ 0.02 T (corresponds to an IDX skew quad at 1 amp)
- coupling correction provides 10% improvement in IP σ_y (20% in ϵ_y)
- two of the coupling correction skew quadrupoles (QK2X and QK3X) can definitely be IDX skew quadrupoles; QK4X can probably be an IDX skew quadrupole (maybe with slightly higher maximum operating current?)
- QK1X, because it is in phase with all errors in the inflector that cause coupling, requires up to 3 times the strength of an IDX skew quadrupole at 5 amps, at least in these simulations ... a Tokin 3393 quadrupole, converted to a skew quadrupole and operating at 40 amps maximum, would provide $\approx 50\%$ overhead in strength

Continuing Work

- correction of vertical dispersion from the inflector is done by running QS1X and QS2X in “sum mode” (both with the same strength), which generates dispersion but no coupling ... running these skew quadrupoles in “difference mode” (opposite strengths) should generate coupling but no dispersion; because these skew quadrupoles are in phase with the coupling errors in the inflector, perhaps this effect can be used to reduce the required strength of QK1X
- coupling errors in the DR extraction channel must be included in future simulations ... if emittance growth is happening there now, it will still be happening after the EXT rebuild, and our diagnostic and correction tools must be able to deal with such errors
- the effects of finite wire scanner resolution on the tune-up scheme must be studied
- magnet strength errors, BPM offsets, and BPM rolls should be included
- it should be possible to correct the vertical dispersion by minimizing the projected vertical emittance, similar to scanning one of the coupling correction skew quadrupoles, rather than by changing the DR energy, measuring dispersion on BPMs, and back-propagating ... these two methods should be compared