

Mount stabilization for Shintake monitor-3

3rd ATF2 project meeting (Dec. 19, 2006)

Tatsuya KUME

Mechanical Engineering Center,

High Energy Accelerator Research Organization (KEK)

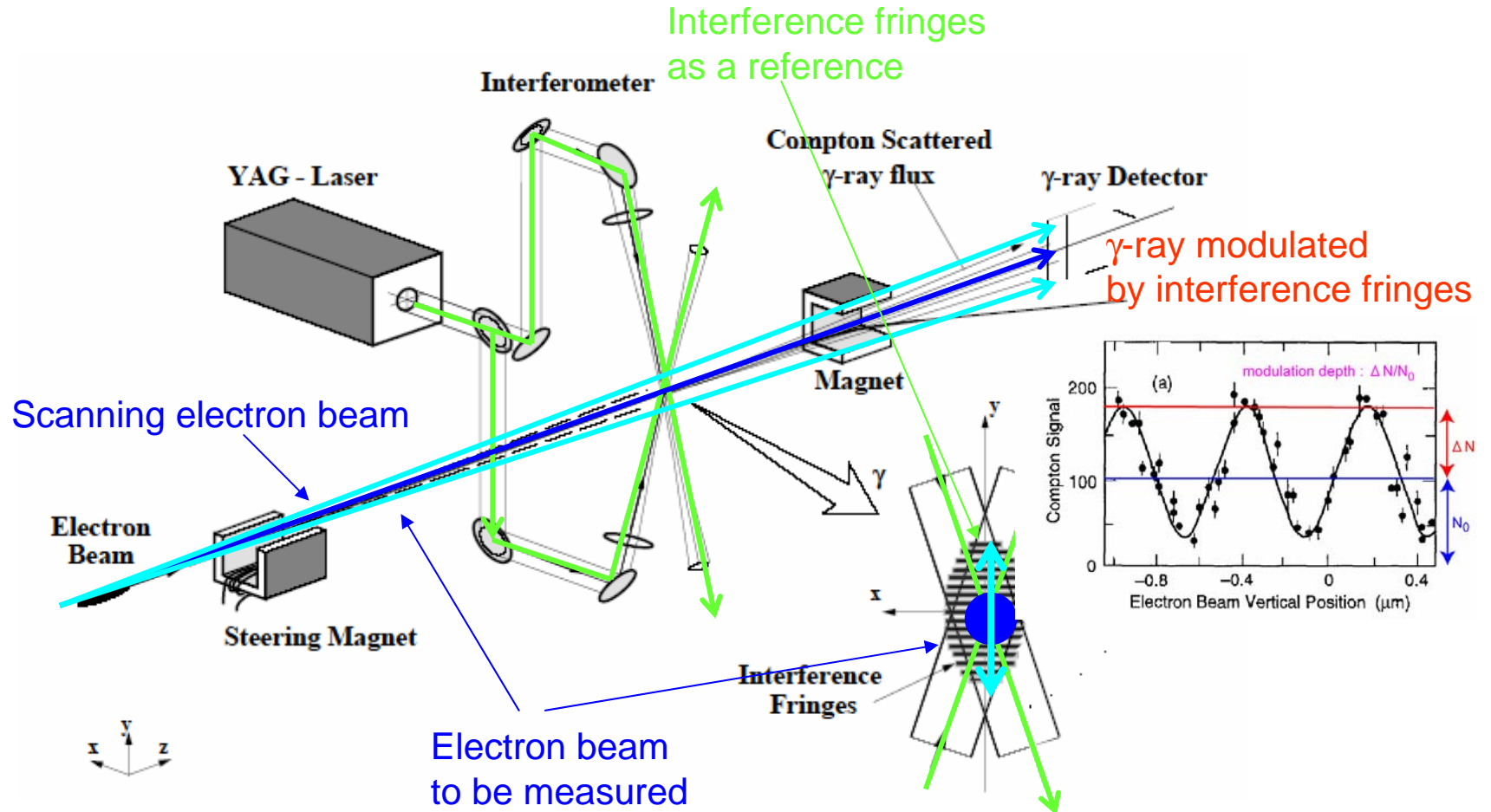


Contents

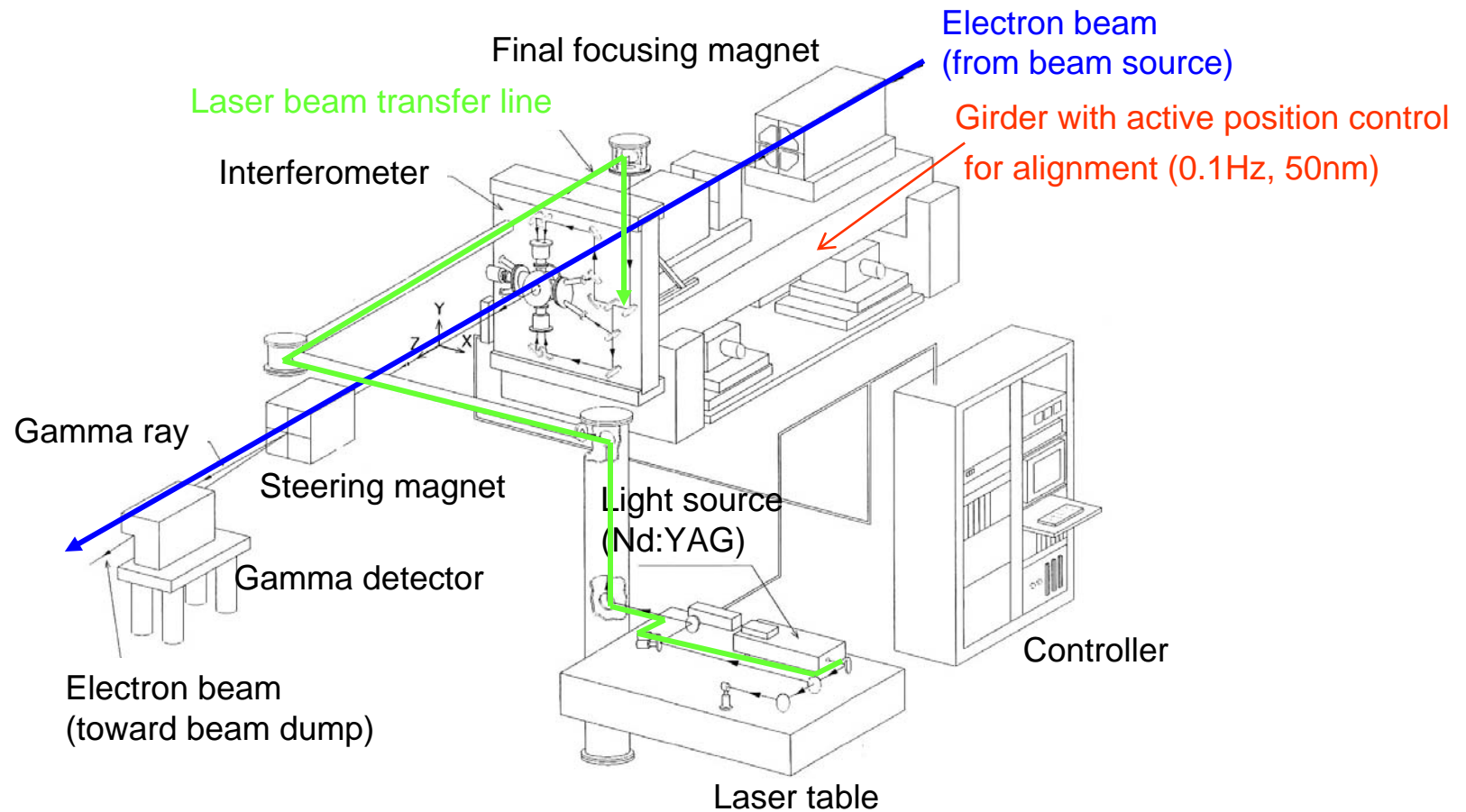
- About Shintake monitor and results in FFTB
- Studies for stabilization around IP
 - Interferometer and final focusing magnet
- Proposals and subjects to be studied for mount stabilization (3 proposals)
 - Proposal 1: Individual rigid mounts
 - Proposal 2: Mount on a stabilized common table
 - Proposal 3: Individual mounts with feedback system

Schematics of Shintake Monitor

Laser fringe(/Compton) beam size monitor



System schematics of Shintake monitor in Final Focus Test Beam (FFTB)



Results of Shintake monitor in FFTB (1993-1997)

- Experimentally measure size of the converged electron beam to be **70 nm** in radius (σ).
- Operated **without** any anti vibration equipments
 - without active control, nor passive air suspension table, etc.
- Signal fluctuation in Gamma corresponded to be **40 nm** with **>10Hz** of jitter was observed.

System performance expected for Shintake monitor in ATF2 project

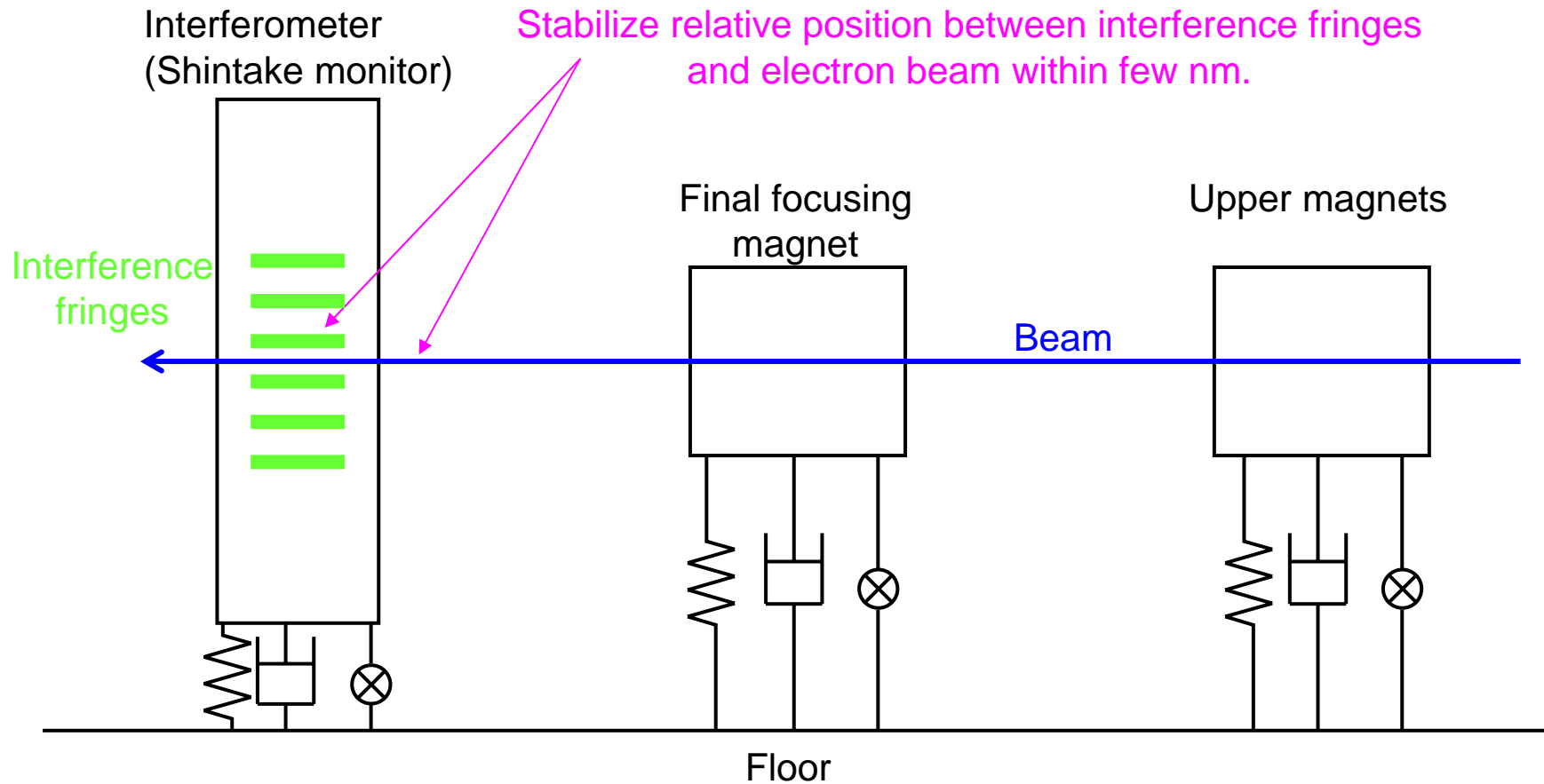
- Measure size of electron beam converged to **35 nm** of radius (σ)

Methods to realize expected performance

- Use shorter (1064->**532 nm**) wavelength of laser
 - >Obtain higher modulation of γ -ray for narrower (60->35nm-in design) electron beams
- Observe and control interference fringes
 - >Stabilize **phase** and **visibility** of interference fringes
- Analyze structure and mount of interferometer
 - >Stabilize and improve rigidity for **mount** and **body** of interferometer

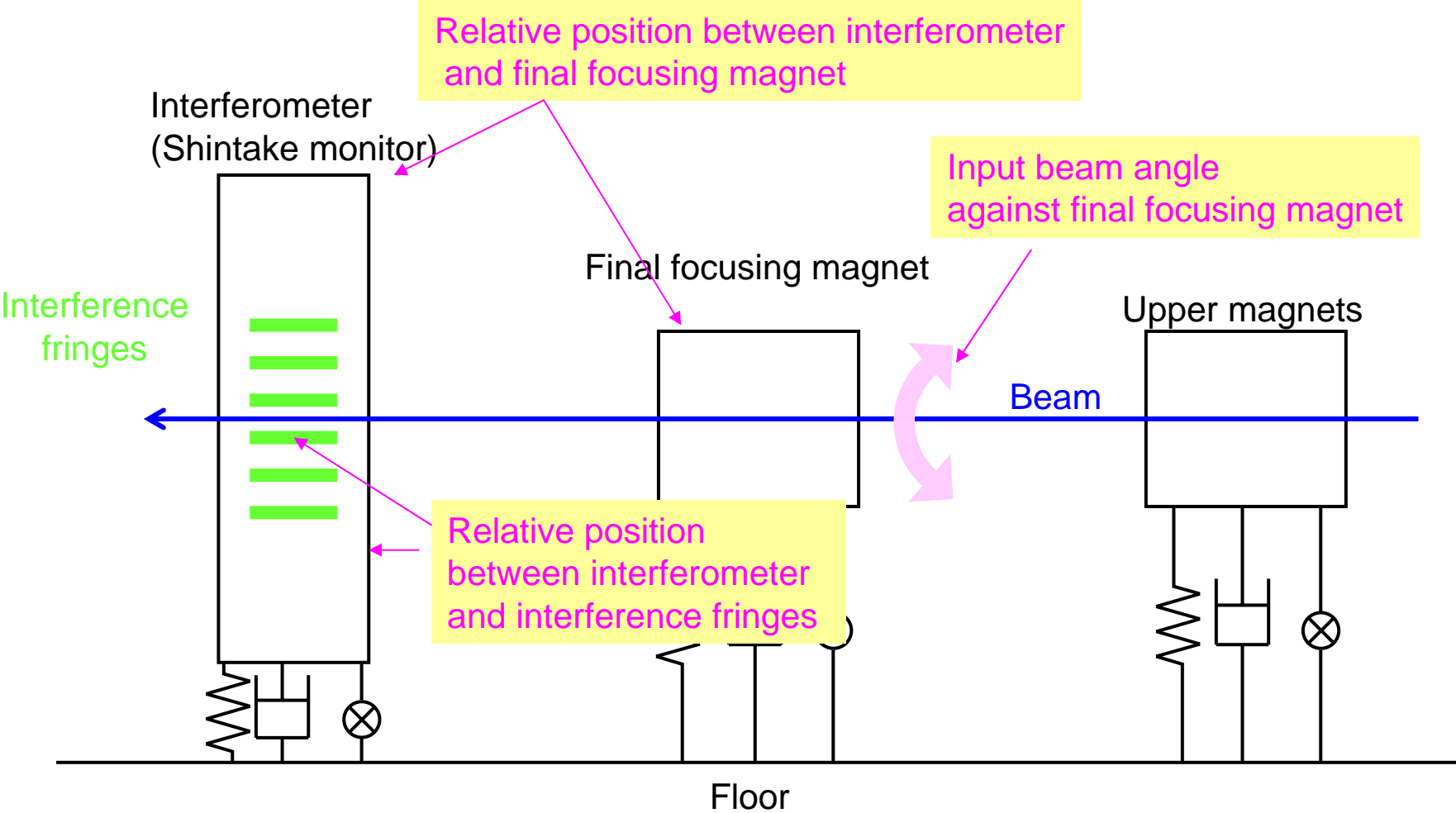
Goal of stabilization for Shintake monitor

In order to measure beam size with nm resolution



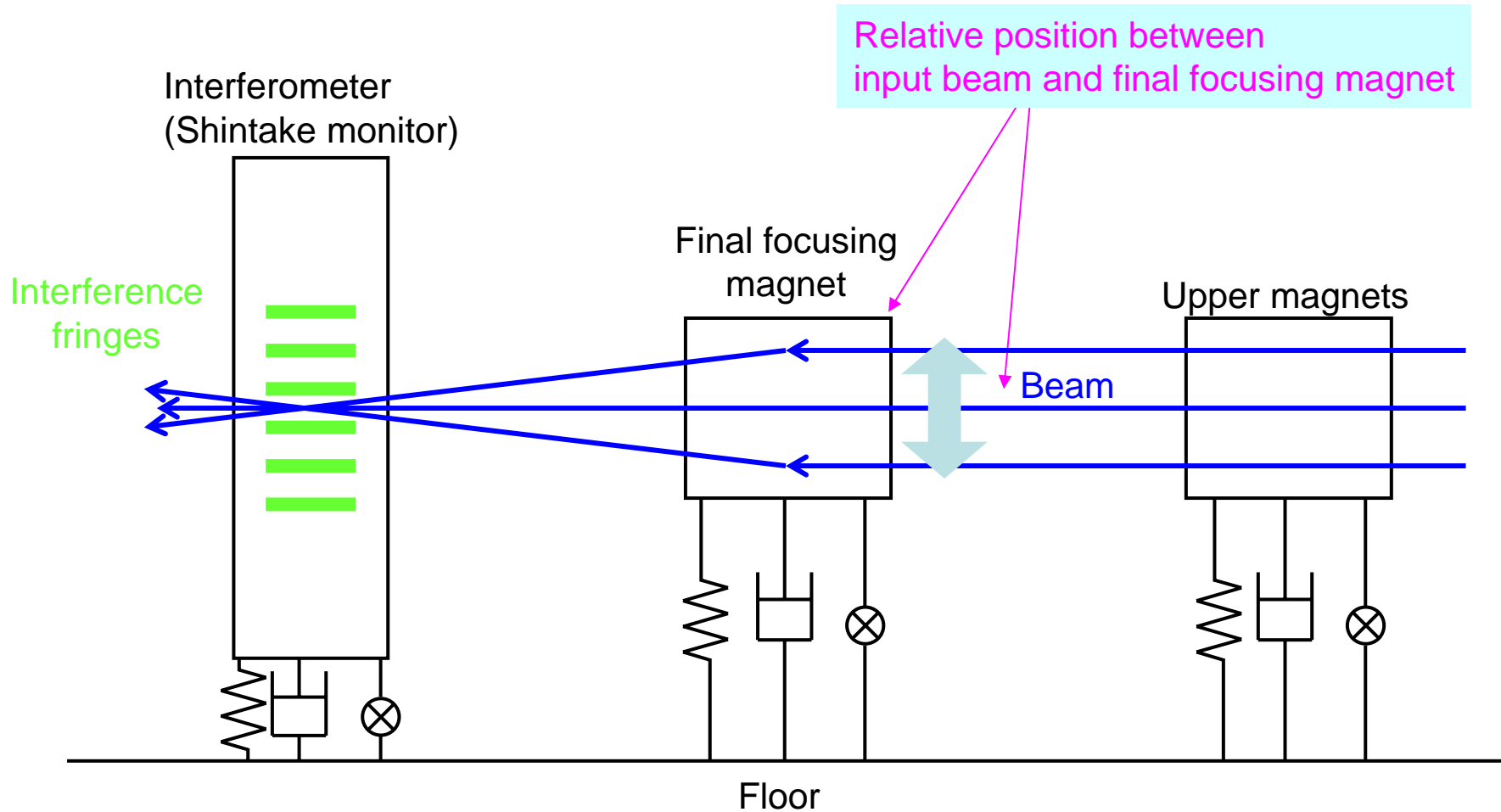
What affects stability?

Relative position stability between interference fringes and electron beam

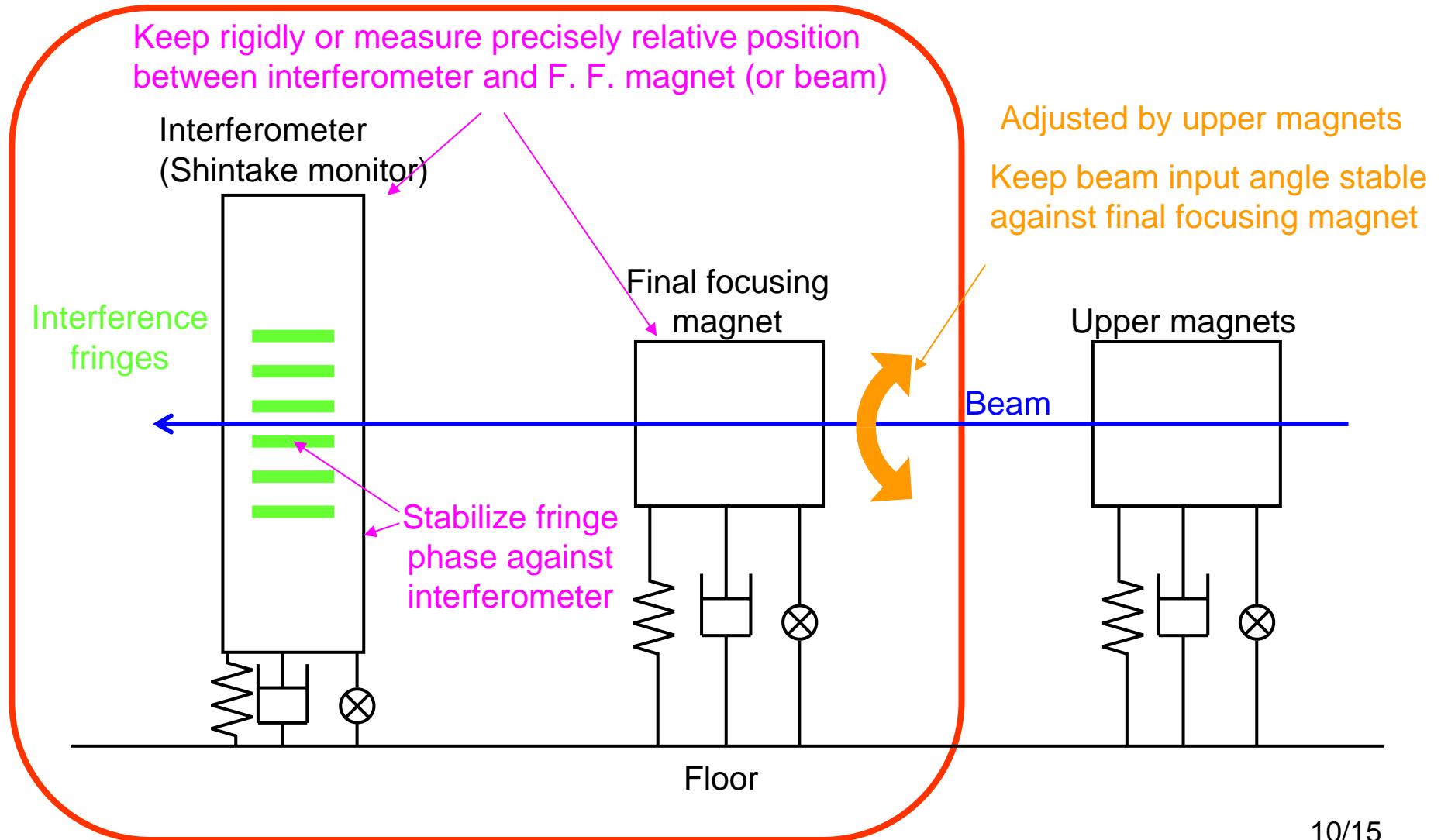


What does not so seriously affect stability?

changes of relative position between input beam and f.f. magnet are canceled by focusing effect of f.f. magnet.



In order to obtain good stability



Proposal 1 for relative stability around IP 1:

Rigid mount on floor

using individual rigid mount for supporting interferometer and f.f.magnet

Confirm rigidity of interferometer body

Advantage

- Tolerant for coherent (slow $<0.1\sim 1\text{Hz?}$) floor motion
- Simple & low cost

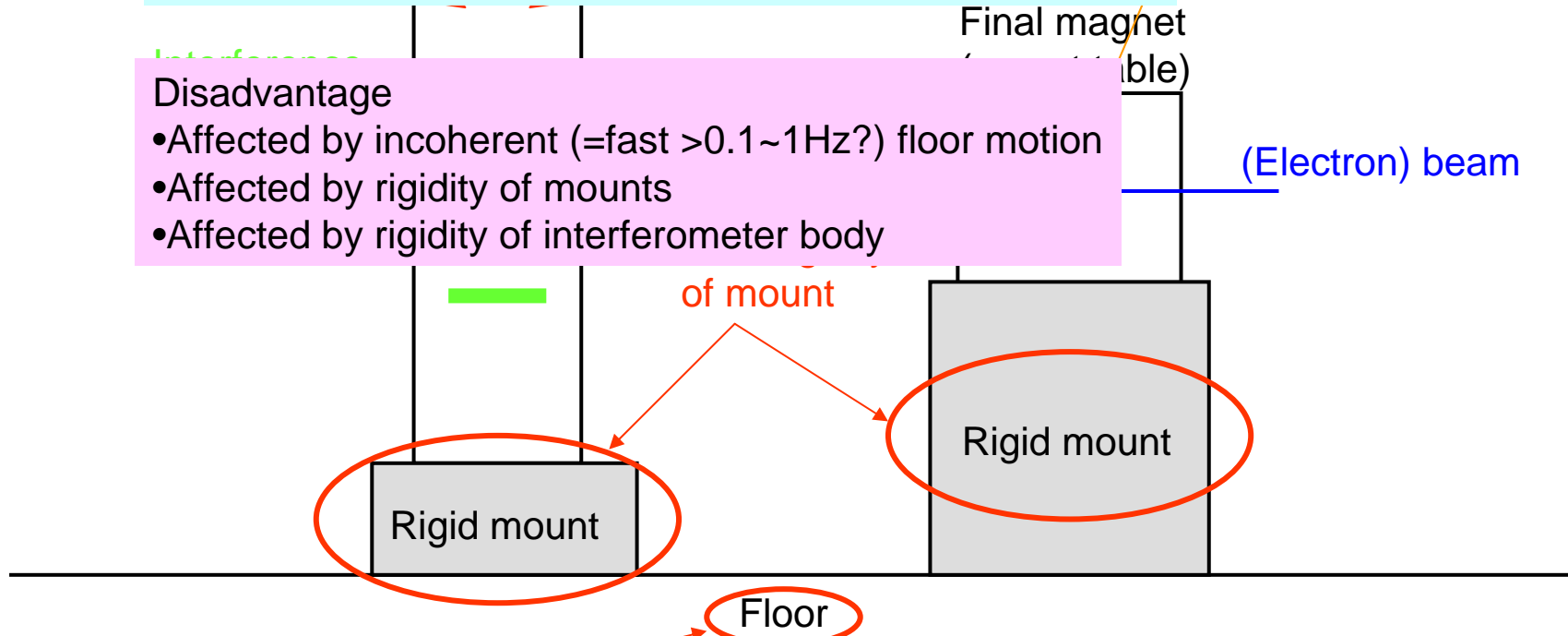
(Estimate effects of magnet induced vibration)

Disadvantage

- Affected by incoherent (=fast $>0.1\sim 1\text{Hz?}$) floor motion
- Affected by rigidity of mounts
- Affected by rigidity of interferometer body

Final magnet (variable)

(Electron) beam



Confirm rigidity of floor (vibration coherence)

Proposal for relative stability around IP 2:

Mount on a common stabilized table

using an anti-vibration common table for interferometer and f.f.magnet

Confirm rigidity of
interferometer

Advantage

- Tolerant for floor motion and rigidity (distortion)

magnet

(originated vibration)

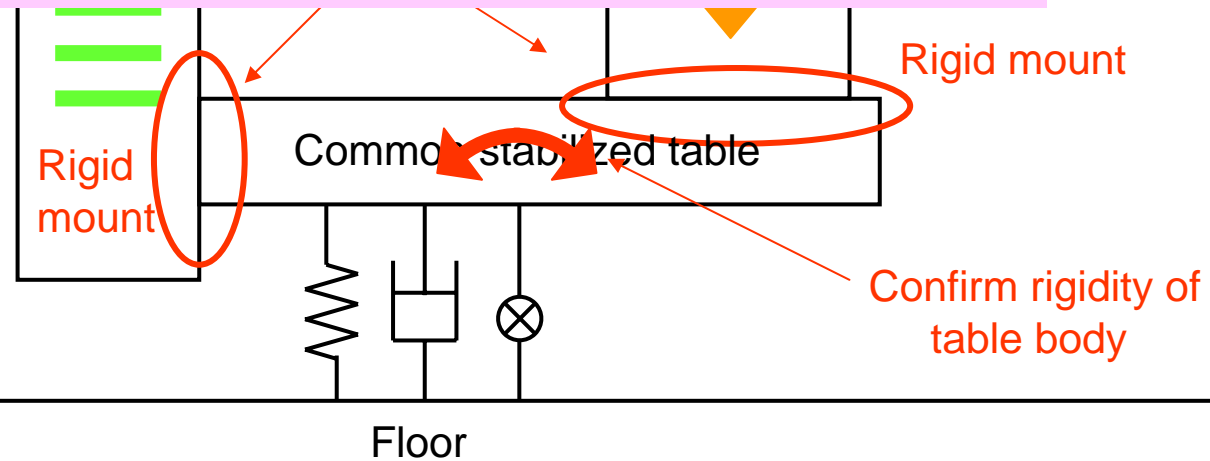
Disadvantage

- Affected by rigidity of common table and mounts
- Affected by rigidity of interferometer body

Interferometer

- High cost -> needs new common anti-vibration table

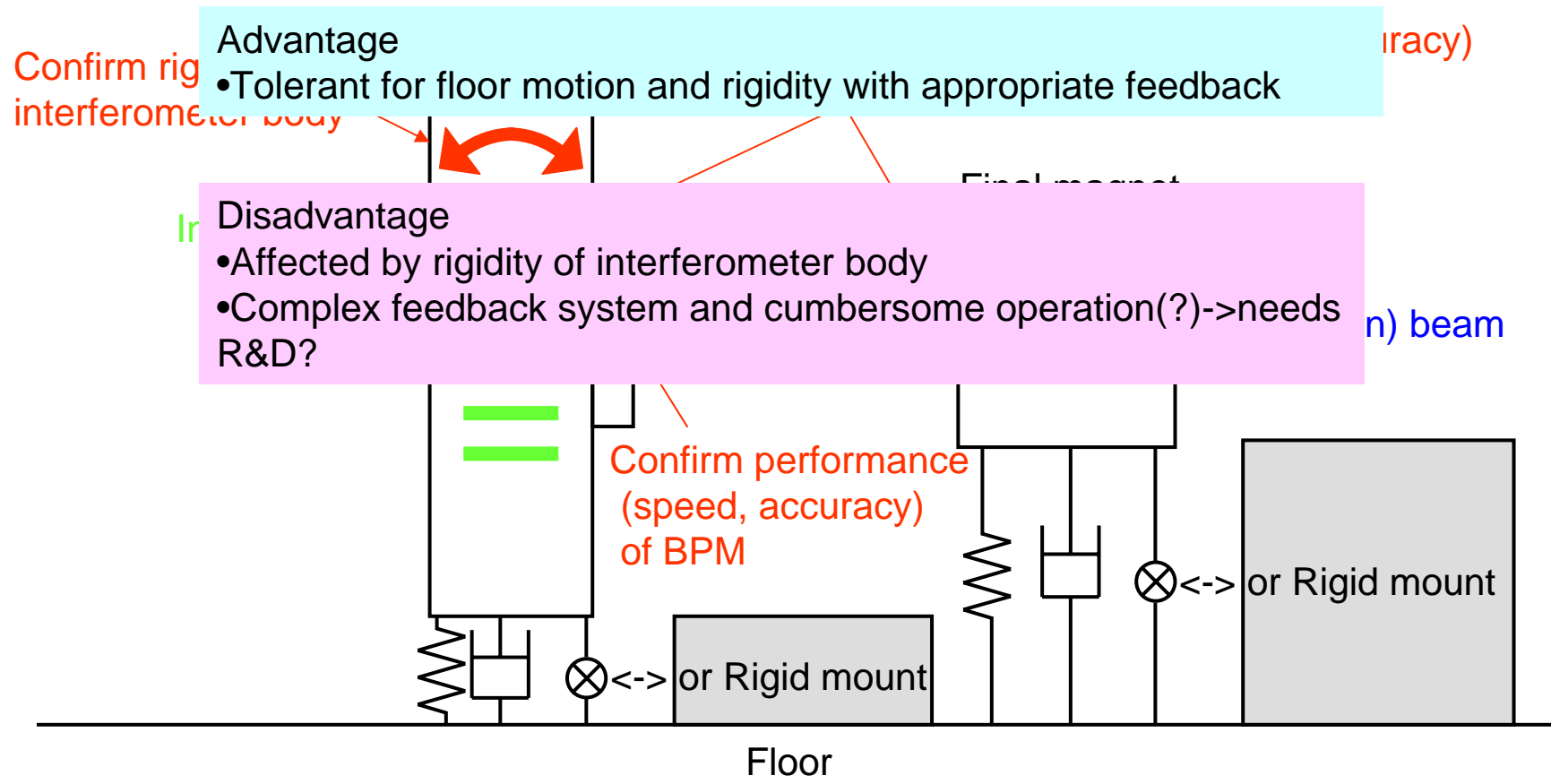
in beam



Proposal for relative stability around IP 3:

Feedback position between beam and fringes

in case using individual mount for interferometer and f.f.magnet with feedback



Summary

- It's necessary to stabilize **relative** position between interference fringes and electron beam for precise beam size measurement.
- The relative stability are to be obtained by
 - stabilizing relative position between **interferometer** and interference **fringes**.
 - stabilizing relative position between **interferometer** and final focusing **magnet** or between **interferometer** and **beam**.
- It's necessary to confirm **rigidity** of interferometer.
- Proposal 1 and 2 are recommended for **mechanical stabilization** around IP.

Plan

- Confirmation rigidity of interferometer body is planned (under cost estimation).
 - by **measuring impulse response** of the interferometer
 - not by simulation (<-problem of accuracy of the analysis models)
- Rigid mount for the interferometer is to be designed using the results as a first step.