



**Detector design optimization
for push-pull IR and
for surface assembly and
corresponding IR requirements**

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SLAC BDS Kick-Off-Meeting
12 October 2007



Charge: System integration and optimization

Quantify the worth/cost value, discuss cost drivers, evaluate performance/cost derivatives, review design decisions in terms of cost impact and discuss possibilities of further refinement.

- Aim to identify the performance driven specifications for accelerator components and especially CFS and discuss how engineering cost-performance trade-offs will be performed.
- Should include discussion of machine-detector connection and optimization, and specifically include discussion of the integrated engineering of push-pull IR, based on [IRENG07 workshop](#), aimed to reduce the risk of performance and cost of this solution.



Detector Truths (IMHO)

- There are no detectors yet, only concepts
 - **Letters of intent are forthcoming**
 - **Detector Engineering lags Machine Engineering**
- GLDc, LDC, & SiD are seriously treating Push-Pull (P-P) & Surface Assembly (S-A)
- Most discussions at IRENG'07 regarding detectors concepts and P-P / S-A touched
 - **Civil: Cavern & surface layout, cranes, services**
 - **Cryo: 2K/4K Refrigerators for QD0 & plumbing**
 - **These will be discussed by Osborne/Parker**
- Will review IRENG'07 detector presentations for comments independent of civil & cryo

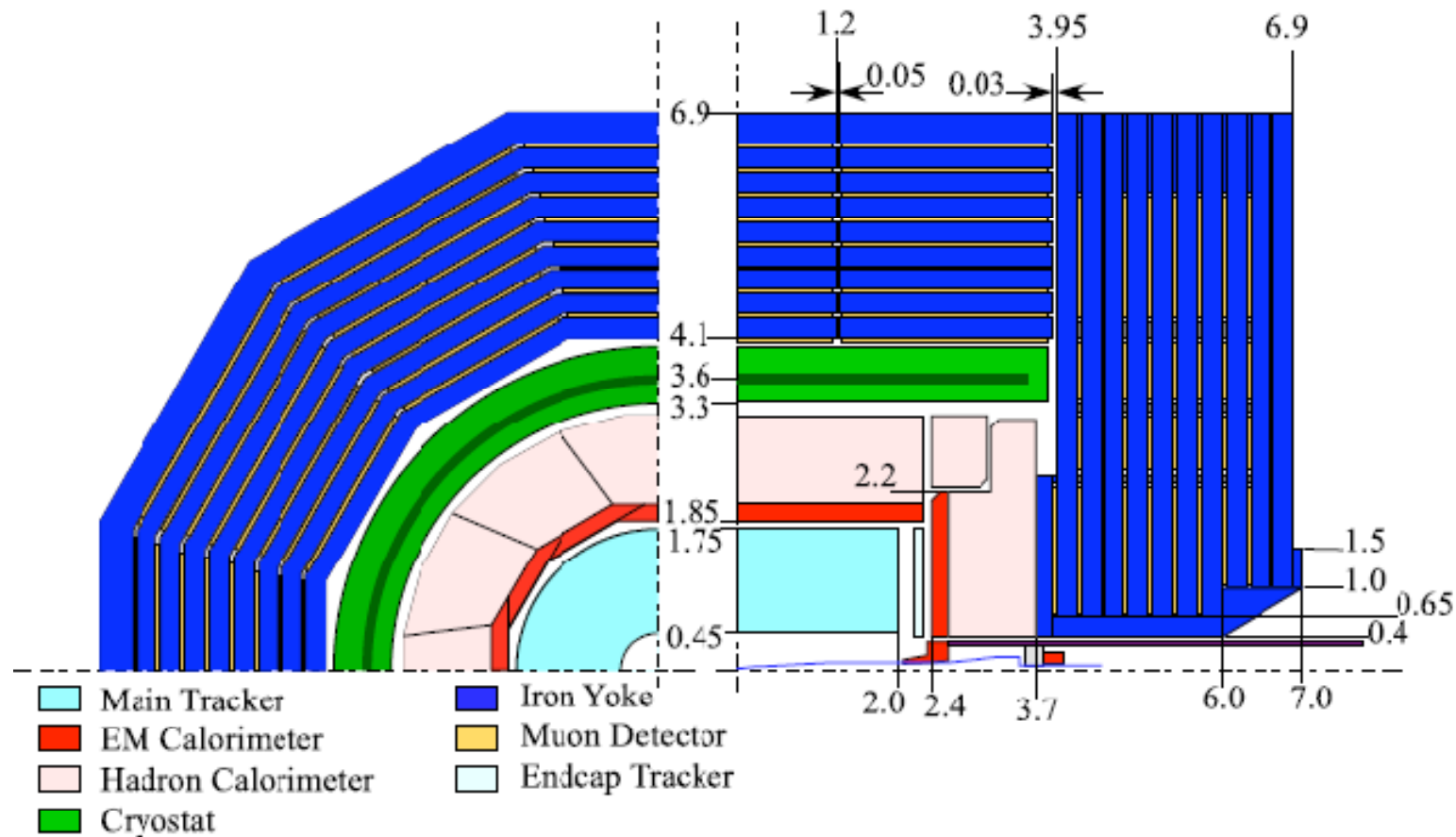


3 Major Developments Since LCWS'07 (DESY)

- GLDc design introduced which incorporates a self-consistent model for push-pull and surface assembly
- Major contribution of CERN civil group to layout/cavern/assembly/platform/access discussion via fabulous layout schematics
- Formation of ~10 member Si D Engineering team



Compact GLD = GLDc



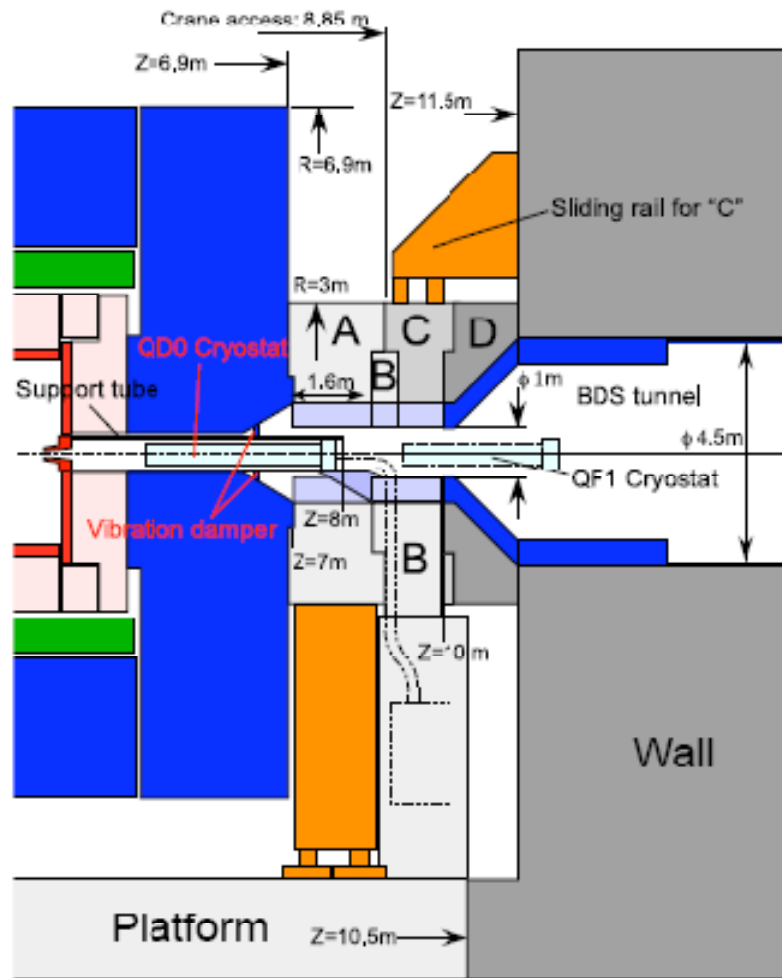


GLDc Assembly: 7 major pieces

- Barrel part (Yoke+ECAL+HCAL)
 - **5080+1130 T = 6210 T**
 - **Pure CMS style assembly can be done by splitting the barrel part into 3 rings**
- Each Door (Yoke + ECAL+HCAL)
 - **3050 T + 270T = 3320 T**
 - **and splitting each end cap part into two halves**
- Cranes:
 - **50~100 T underground depending on Pacman design**
 - **2,000 T crane for the shaft**
 - **80 T crane in the surface assembly hall**
 - set by 24 Fe yoke octants
- Shaft sizes, crane access and underground vault sized by CFS for GLDc as discussed by J. Osborne



GLDc QD0 Support Based on Cantilevered Support Tube with Base on 2 x 10.5m wide Platform

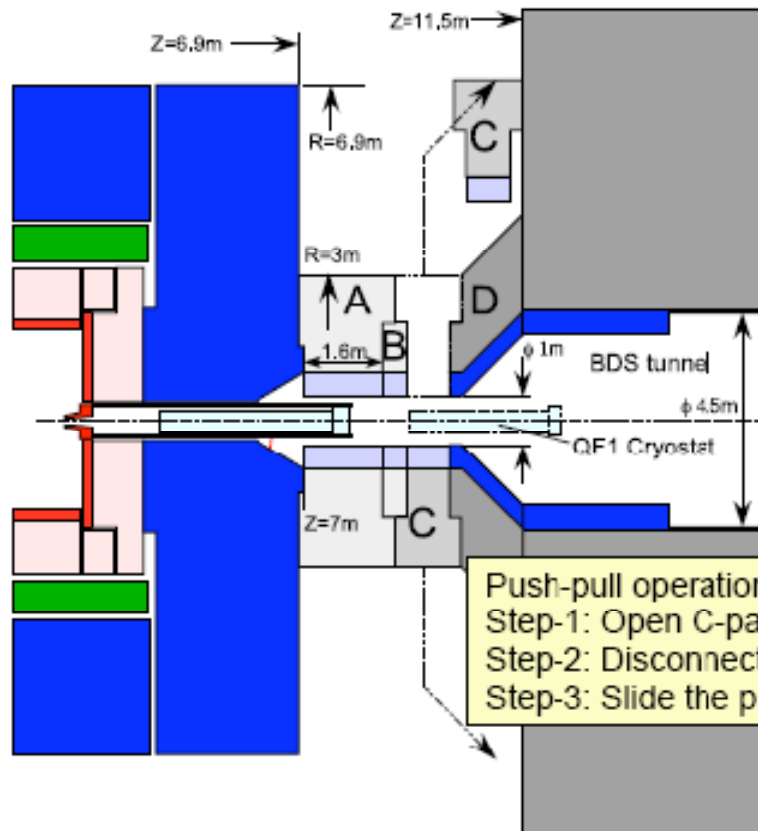


- A: slide sideways using air pad
- B: supported from the floor of platform
- QD0 cryostat is supported by the support tube and the support tube is supported from B
- We can put additional support for the support tube at the entrance of endcap yoke to damp the vibration, if necessary
- Upper part of B (~10 ton) must be removable by crane for installation and removal of the support tube
- C: slide along the wall (D) (common to both experiments) ~50 tonx2
- D: part of the wall
- Wall distance can be as small as 11.5 m from IP, if the crane can access to 2.65m from the wall
- Construction of C is done by a mobile crane (CMS style)
- Inner radius of pacman should be determined after design of gate valve etc. between QD0 and QF1 is fixed

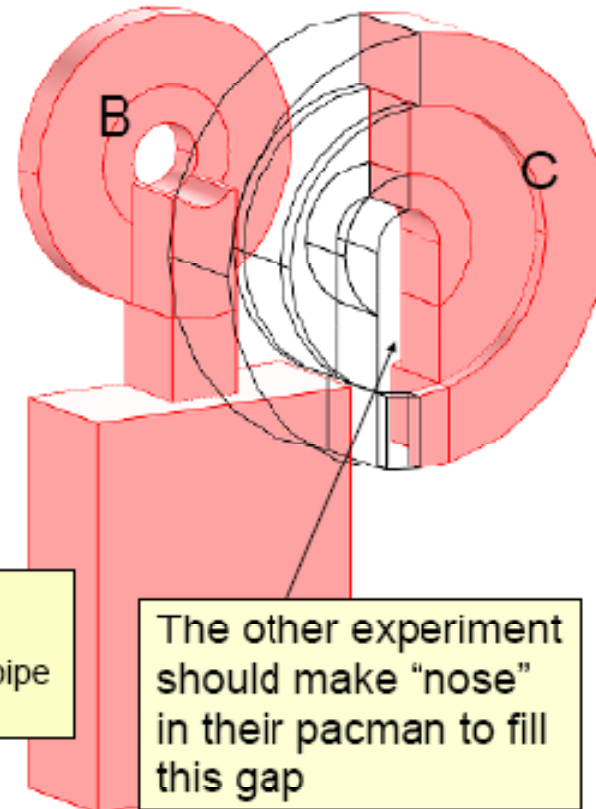


Disassembly of PACMAN for Push-Pull

- Plan view

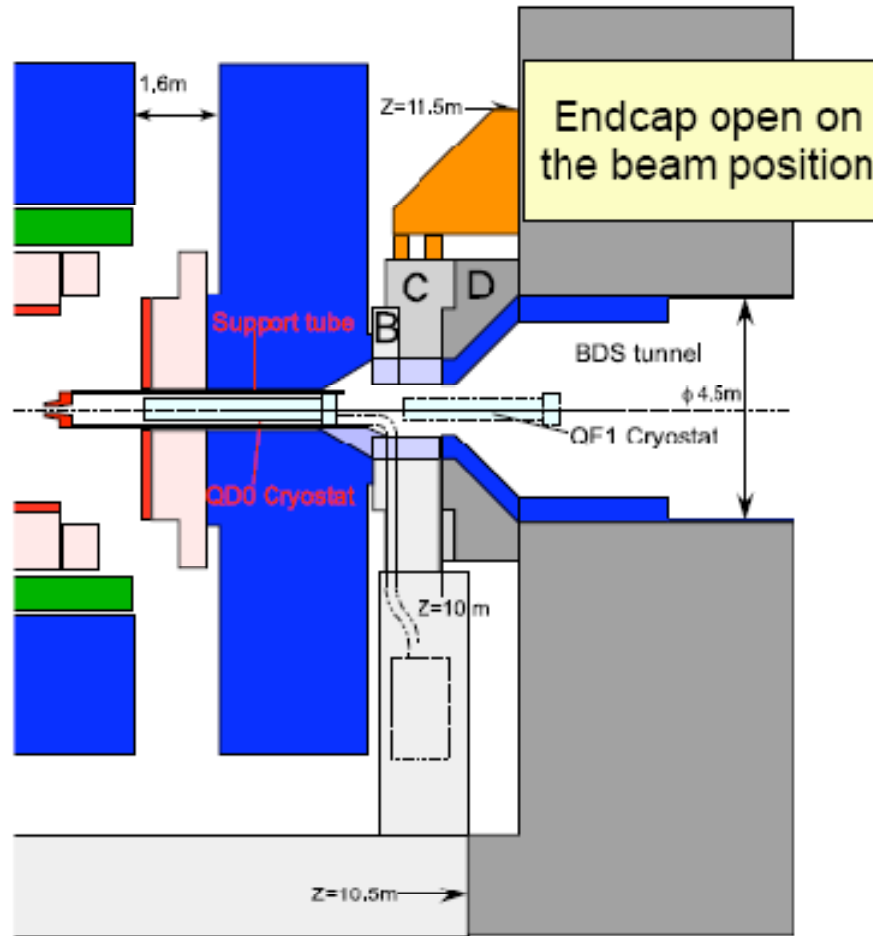


- 3D view

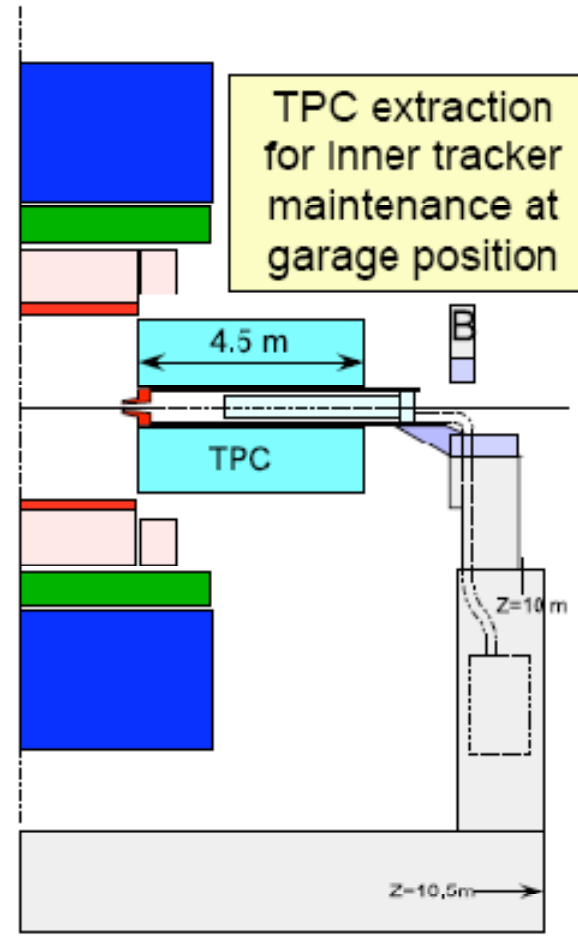




On-beamline & Off-beamline Access



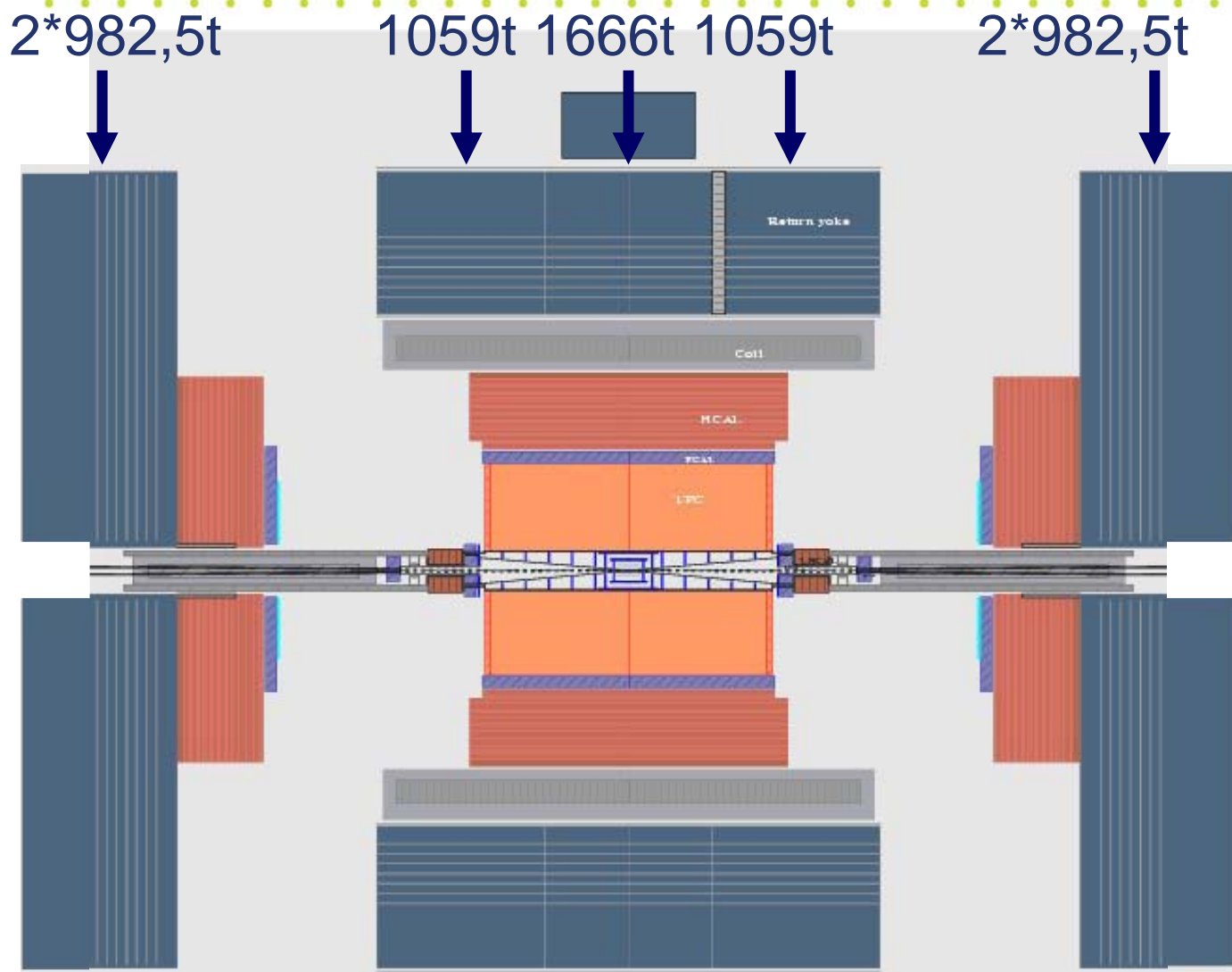
“A” Pacman split back and unsplit door rolls to tube support pillar



“A” & “B” Pacmen and Endcap Door split back



LDC Assembly & Access Model Similar to GLDc



If not split the end cap pieces would be the heaviest part to be lowered!

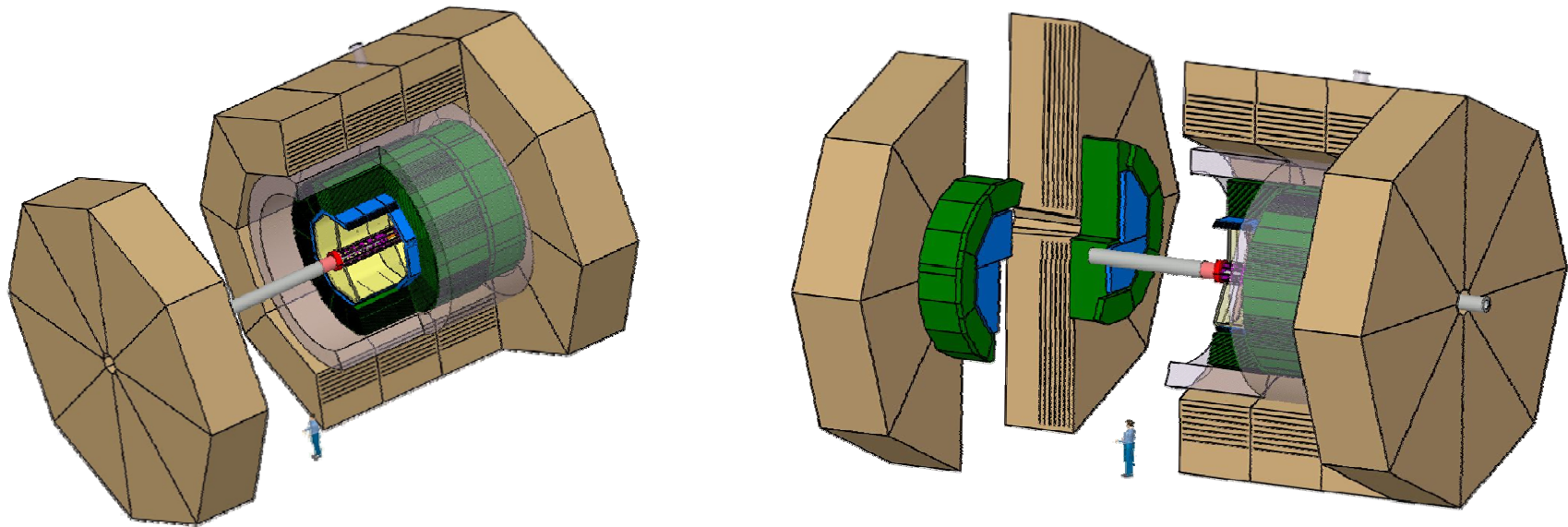


Split Endcaps not Fundamental to Design

Under Study!

- The structure of the detector should allow both.

Factor 2 more bending if split!



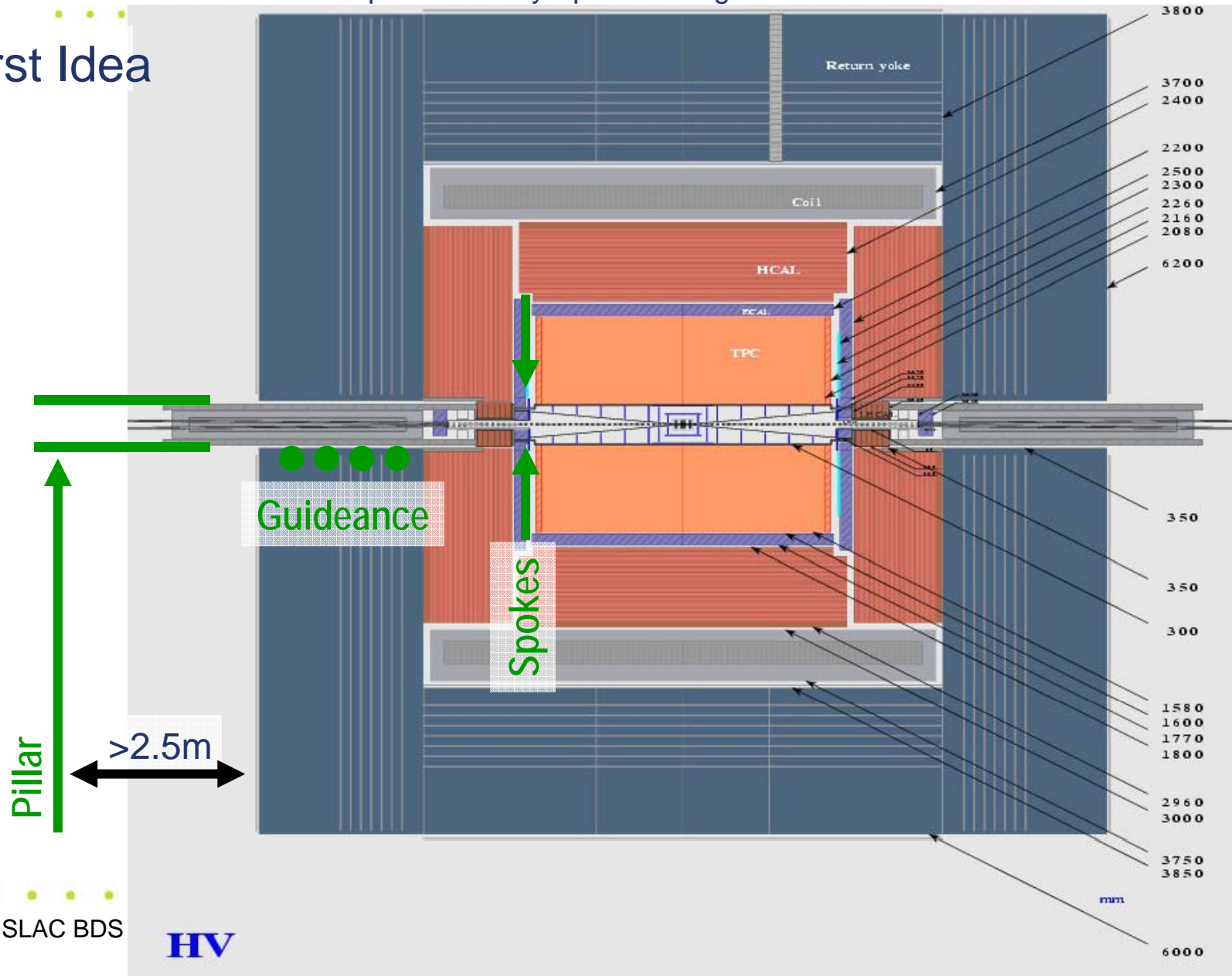
At the moment we prefer end cap halves bolted together with the possibility to open in an major operation if necessary!



QD0/FCAL Held in Support Tube Support Tube Pillar Sets Max Door Opening

Tube Guided in EndCap and Held by Spoke Arrangement at TPC/ECAL Juncture

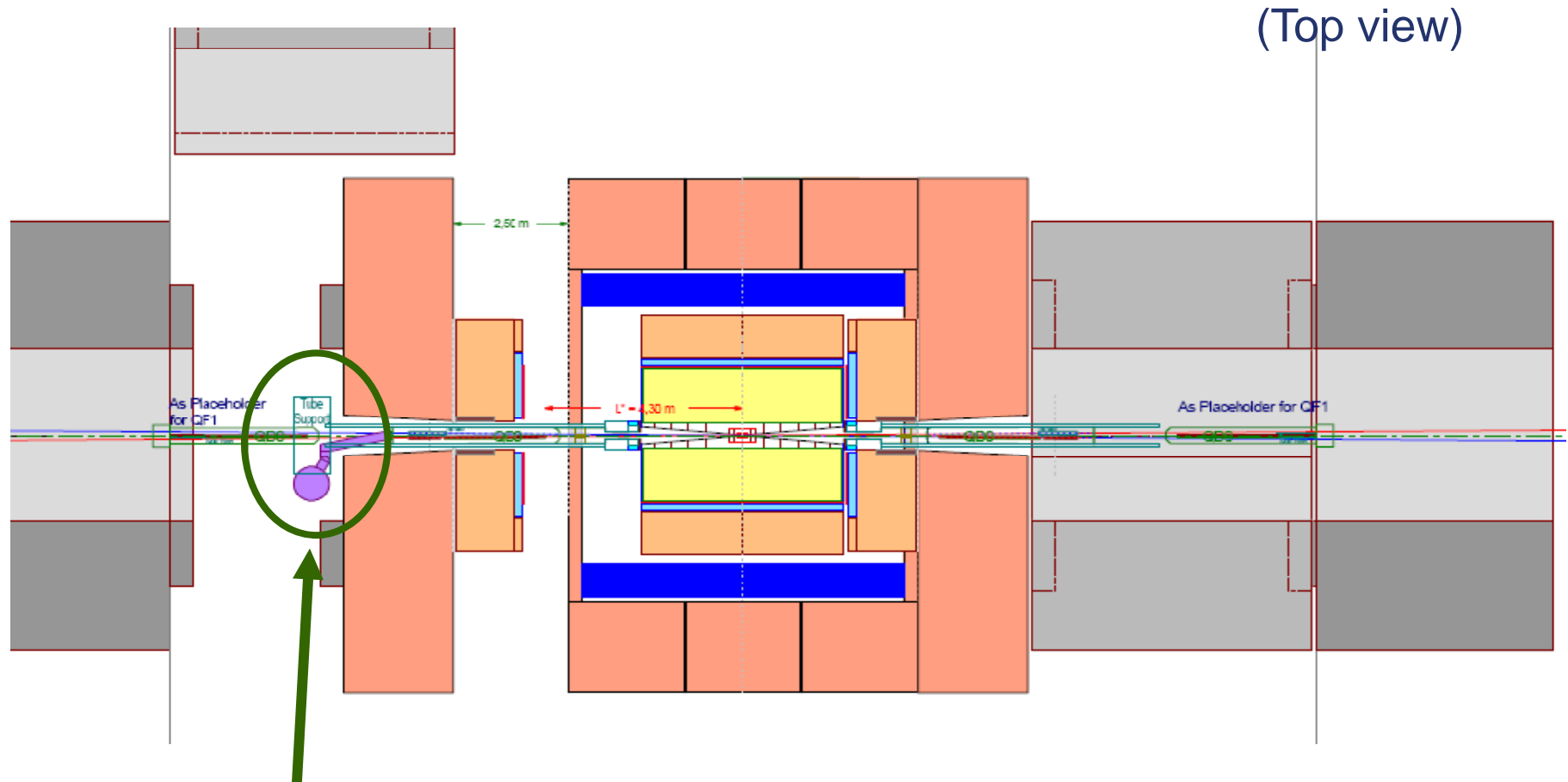
First Idea





LDC Opens On-Beamline Via Split PacMan

Need 2.5-3m to access the detector

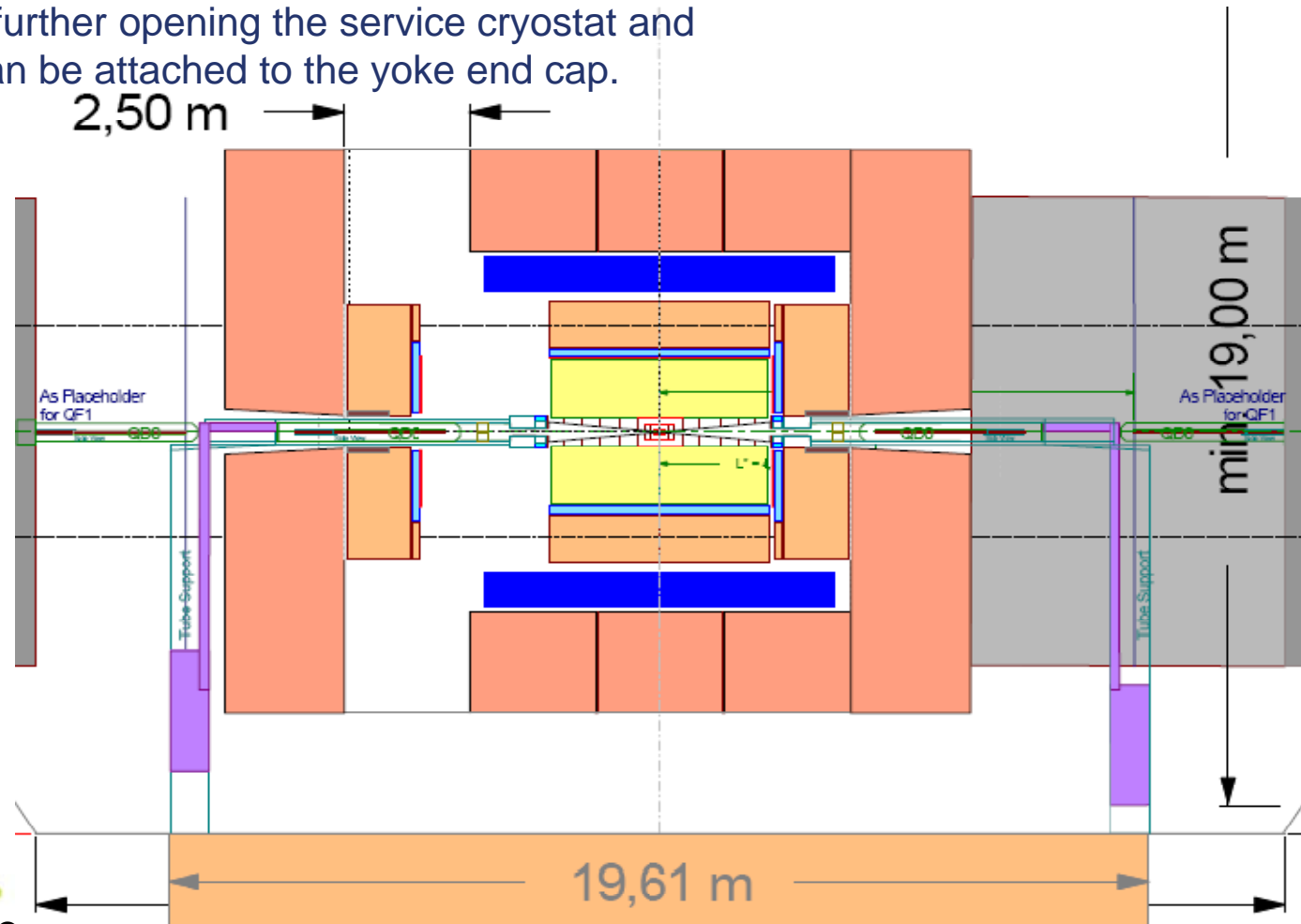


- Support Structure Support
- Service Cryostat
- Supply Line close to QF1



Similar Width “Platform” to GLDc

- The supply lines from the service cryostat to the QD0s go from the bottom through the shielding.
- The cryostats are connected via flexible lines to Helium supply.
- To allow a further opening the service cryostat and the QD0 can be attached to the yoke end cap.



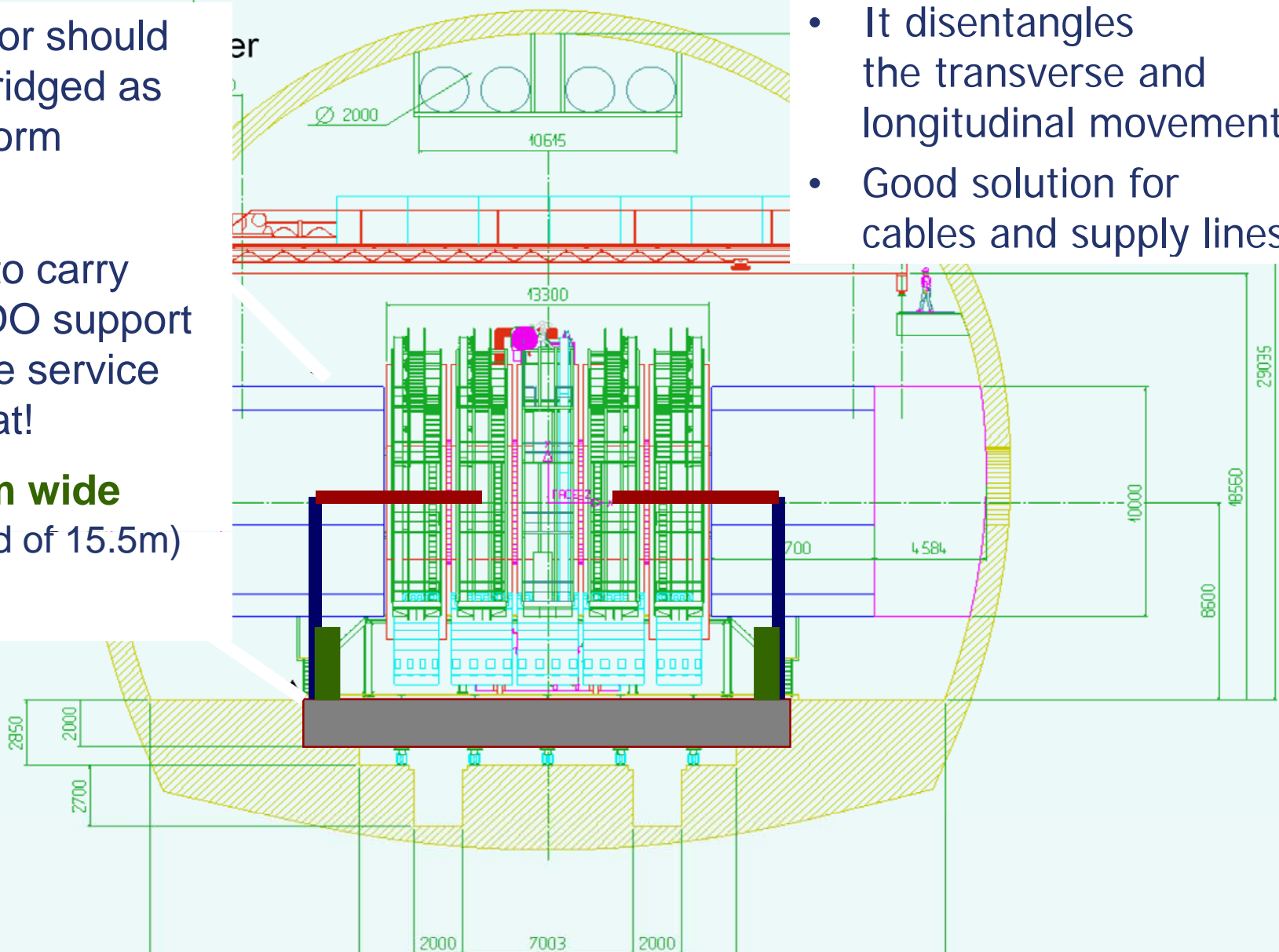


Relative Merits of Platform Under Discussion

EXPERIENCE FERMÉE SUR FAISCEAU

PORTEE PONT ROULANT 4.0L 29120

- Detector should be as ridged as a platform
 - It has to carry the QDO support and the service cryostat!
- **20m wide**
(Instead of 15.5m)

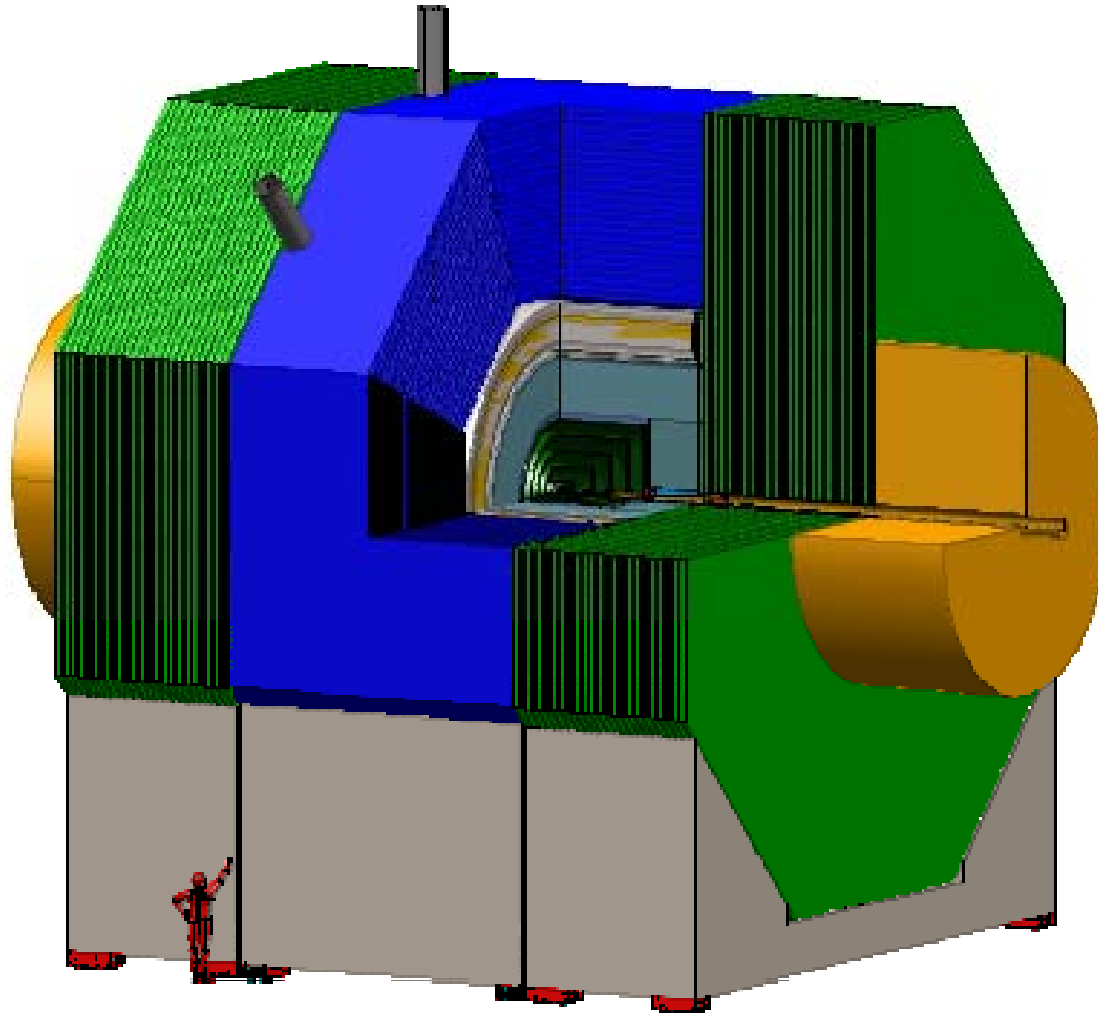


Charming!

- It disentangles the transverse and longitudinal movement
- Good solution for cables and supply lines



SiD: Doors & Barrel Are Not Split Minimum of 3 pieces to lower



“Pure CMS” concept
gantry requirements:

- 4000T Barrel
 - Arch supports,
Yoke, H/E-cals, coil
- 2500 T Doors
 - Yoke, H/E-cals



Sequence of Operations for Surface Assembly/Test & Underground Reassembly

- **Detector subassembly construction & surface tests**
 - Octants of muon chamber instrumented barrel yoke, barrel Hcal, barrel Ecal
 - Four sub-modules of EC return flux instrumented with muon chambers, donut Hcal, Ecal
 - Tracker, vertex and FCAL packages
- **Surface Magnet test**
 - Assemble barrel support and the bottom 5/8 flux return octants
 - Drop in coil & cover with remaining 3/8 octants
 - Assemble two door legs and 4 360° (180 °?) plates of flux return
 - Test magnet and disassemble
- **Lower detector**
 - Reassemble lower barrel with supports below ground
 - Load barrel HCAL and ECAL modules into coil cryostat via threaded beam
 - Lower loaded coil package and capture with upper barrel yoke segments
 - Depending on crane capacity
 - Lower fully assembled door
 - Lower door pieces, the last plate with the Endcap Ecal & Hcal, and reassemble
- **Tracker, VXD and FCAL installed below ground at last minute**



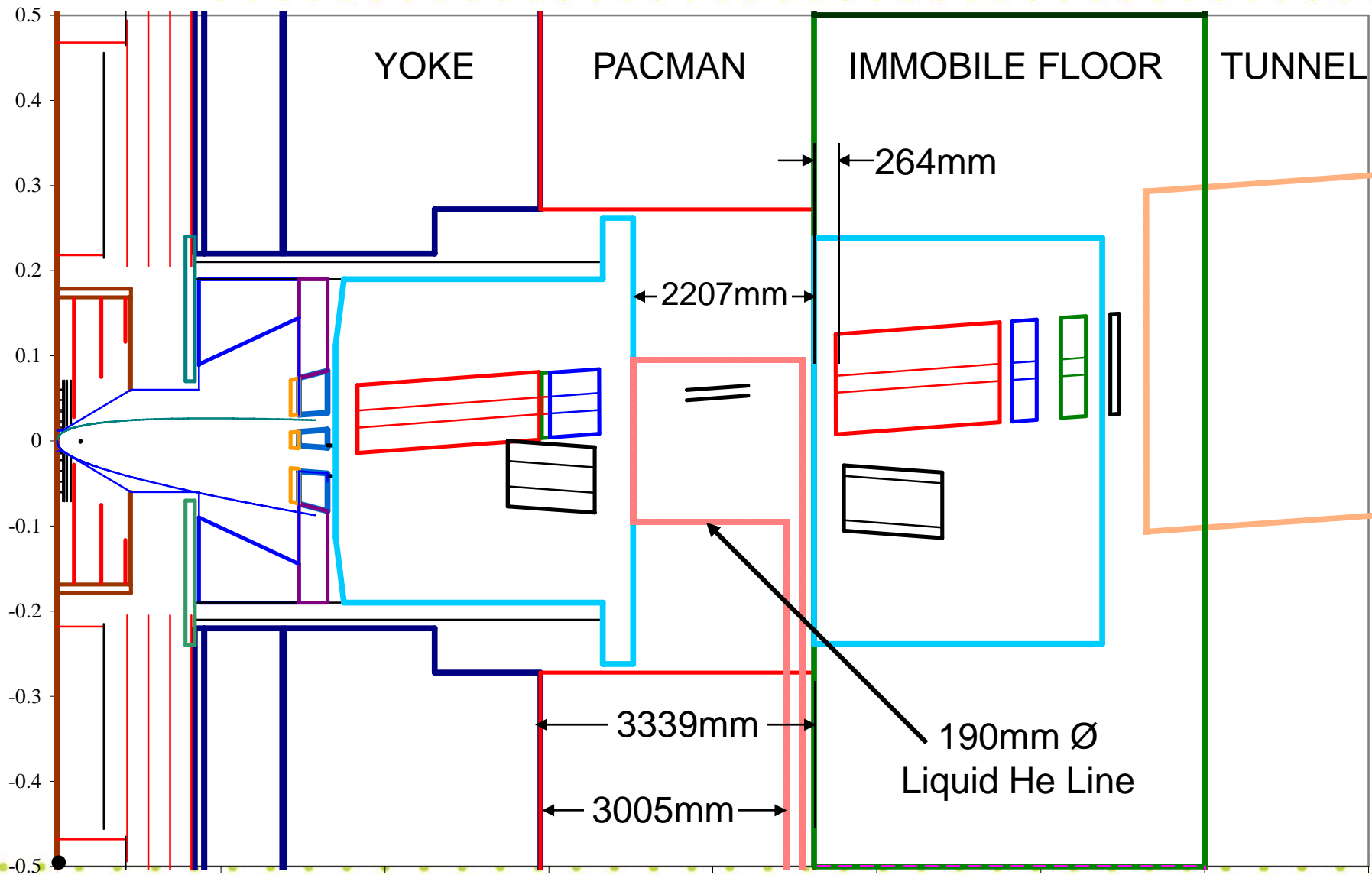
A Surface Assembly/ Underground Reassembly Scenario for SiD

600T Surface crane & No Gantry

M-Tons	Stainless HCAL Radiator		Tungsten HCAL Radiator	
	Barrel	Endcap x2	Barrel	Endcap x2
EM Cal	59	19	59	19
HCAL	354	33	367	46
Coil	160		116	
Iron	2966/8= 374.5	2130/4= 532.5	1785/8= 223.125	1284
Support x 2 (each ~5%Fe)	150	110	90	65
Total to Lower	Loaded Coil=573	Assembled Door=2402	Loaded Coil=542	Assembled Door=1479
Shaft Diameter(m)	8.3m	10.4+2.0m		

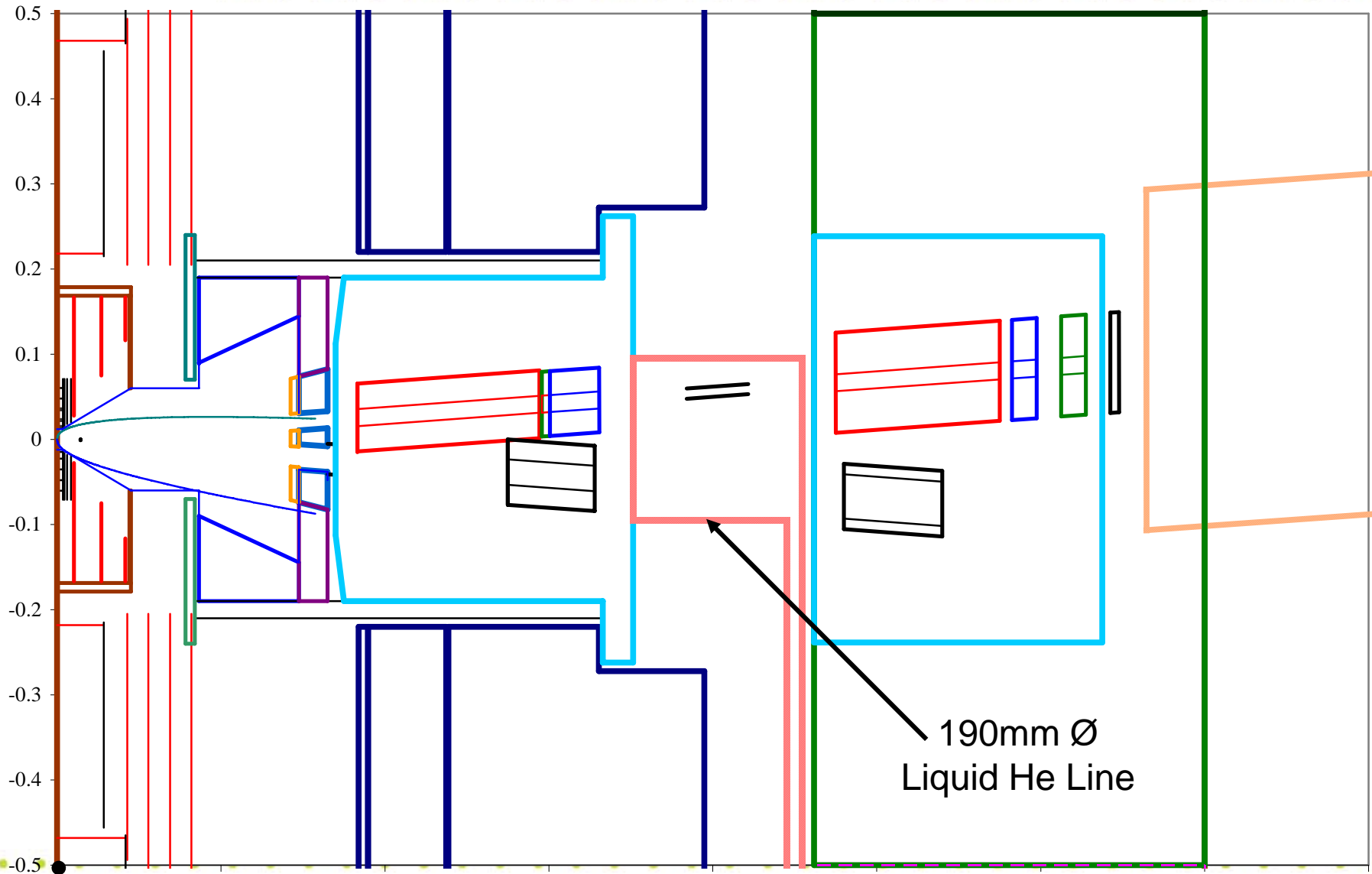


SiD $r < 50\text{cm}$, $L^* = 3.664\text{m}$, 14mrad , Push-Pull, QF @ 9.5m , Door Closed



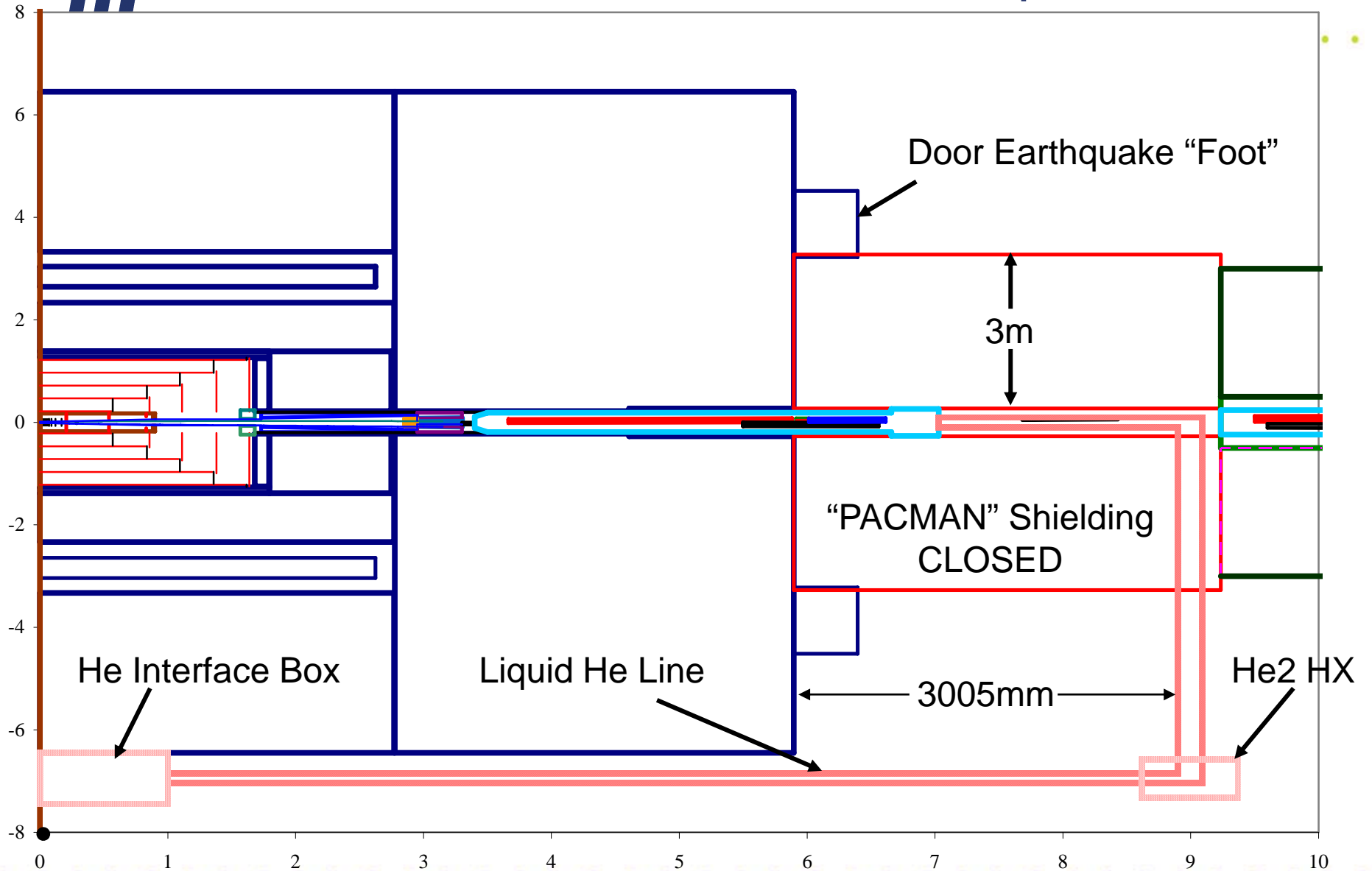


SiD $r < 50\text{cm}$, $L^* = 3.664$, 14mrad Crossing Angle, Push-Pull, Door **Open 2m**



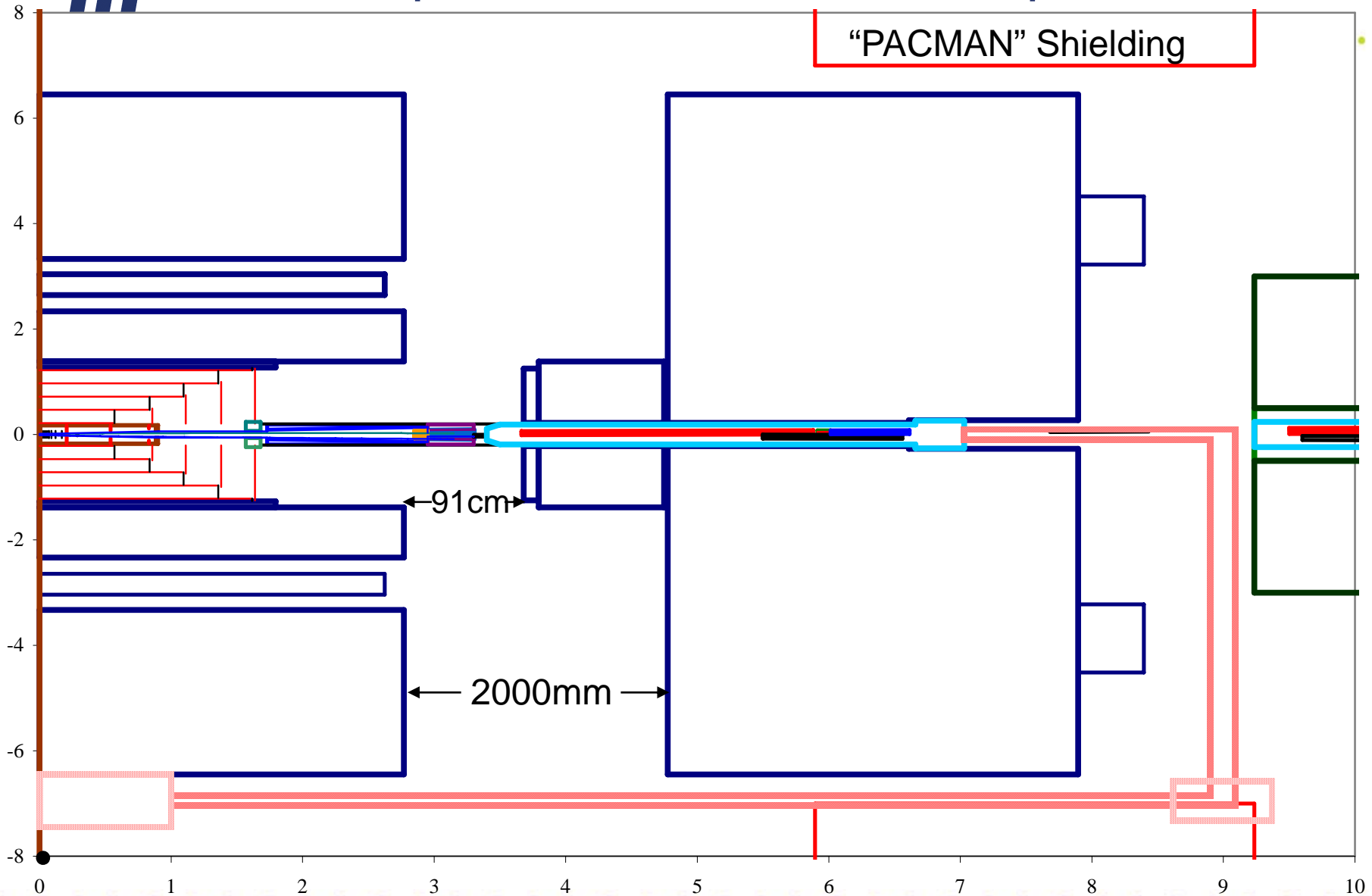


Door Closed, Permanent QD0 Liquid He Line



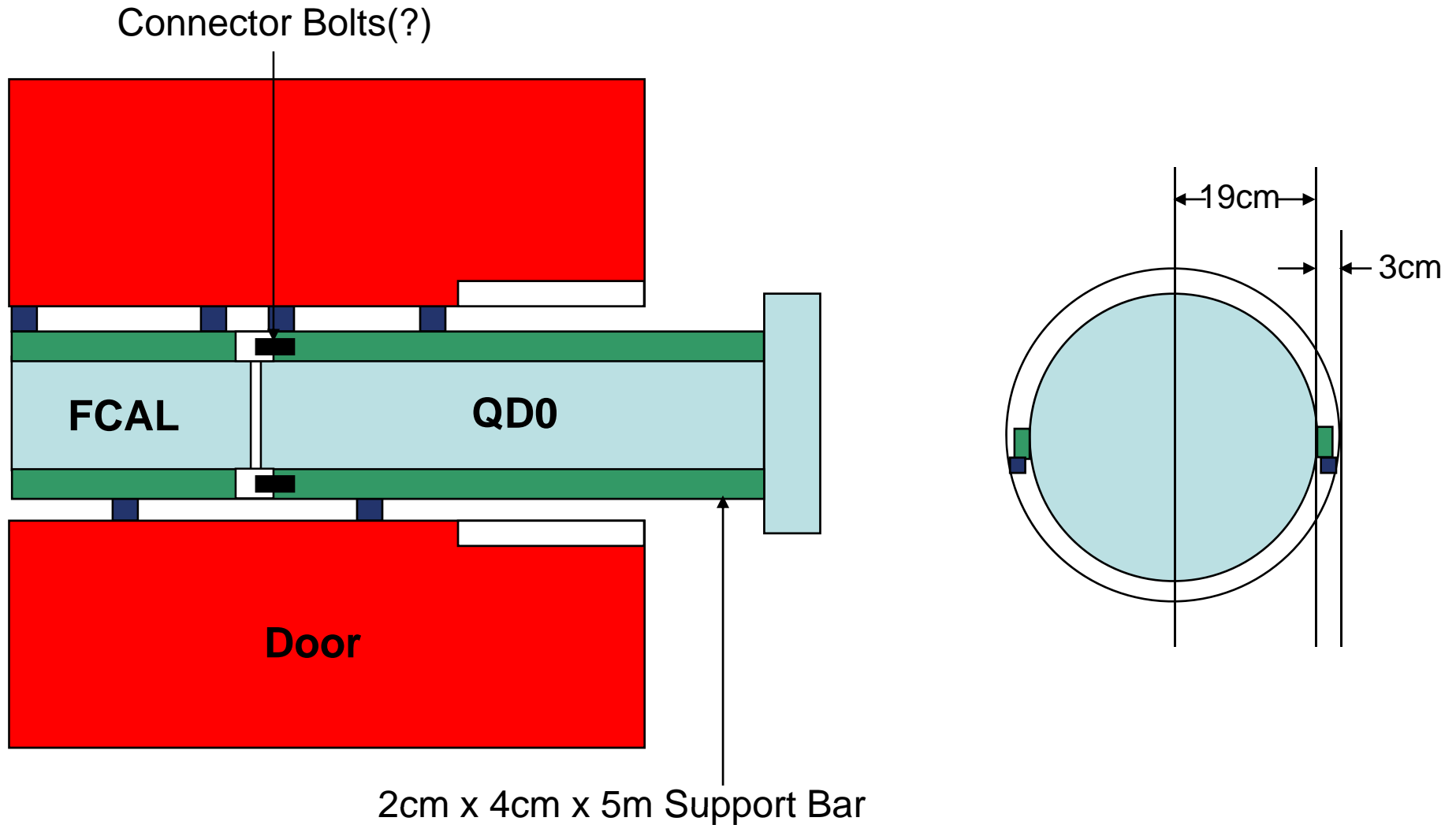


Door Open, Permanent QD0 Liquid He Line



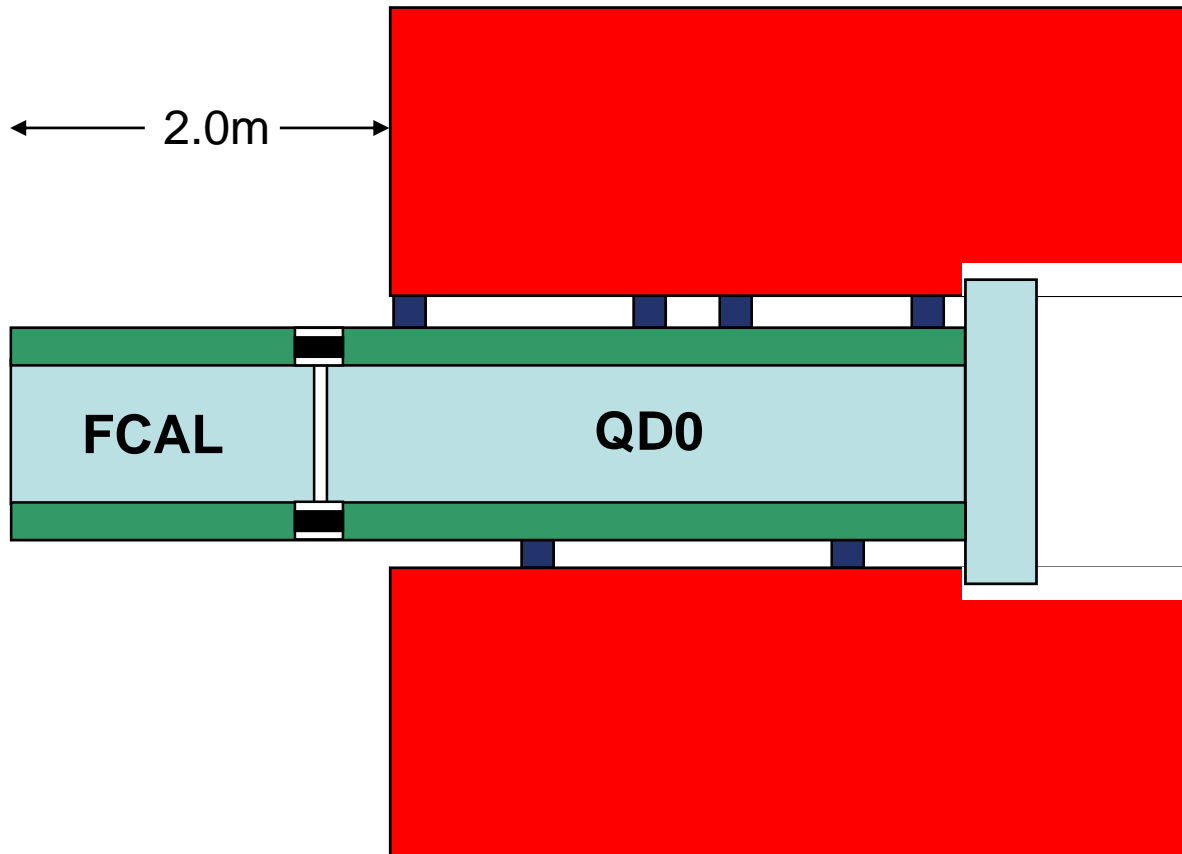


FCAL/QD0 Supported with Door Closed





FCAL/QD0 Supported with Door Open

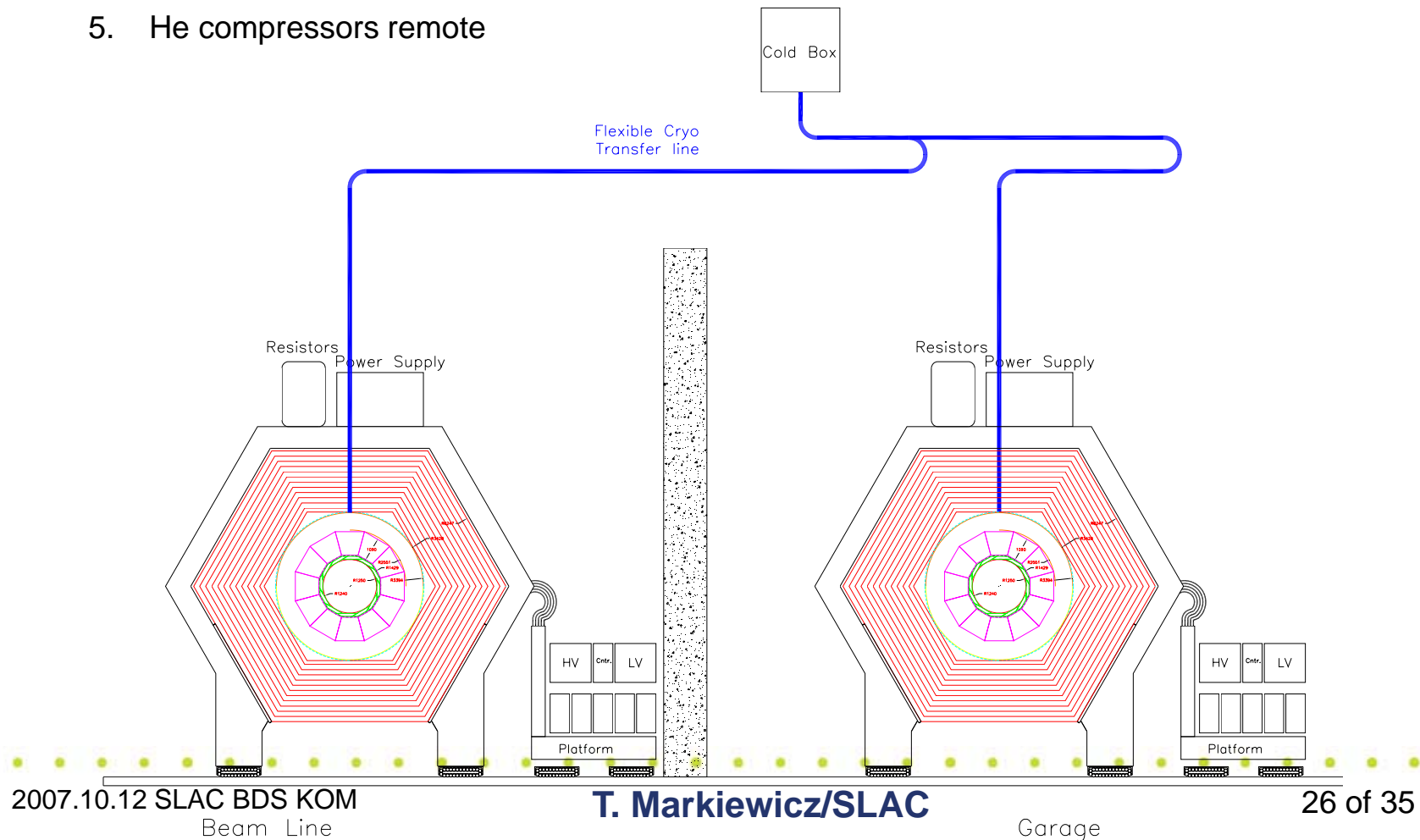


Whether Spider or tube used for Support, SiD has assumed it will be completely supported by door (not cantilevered off a post to the ground) but has not proposed a way to fix it in z when door opens

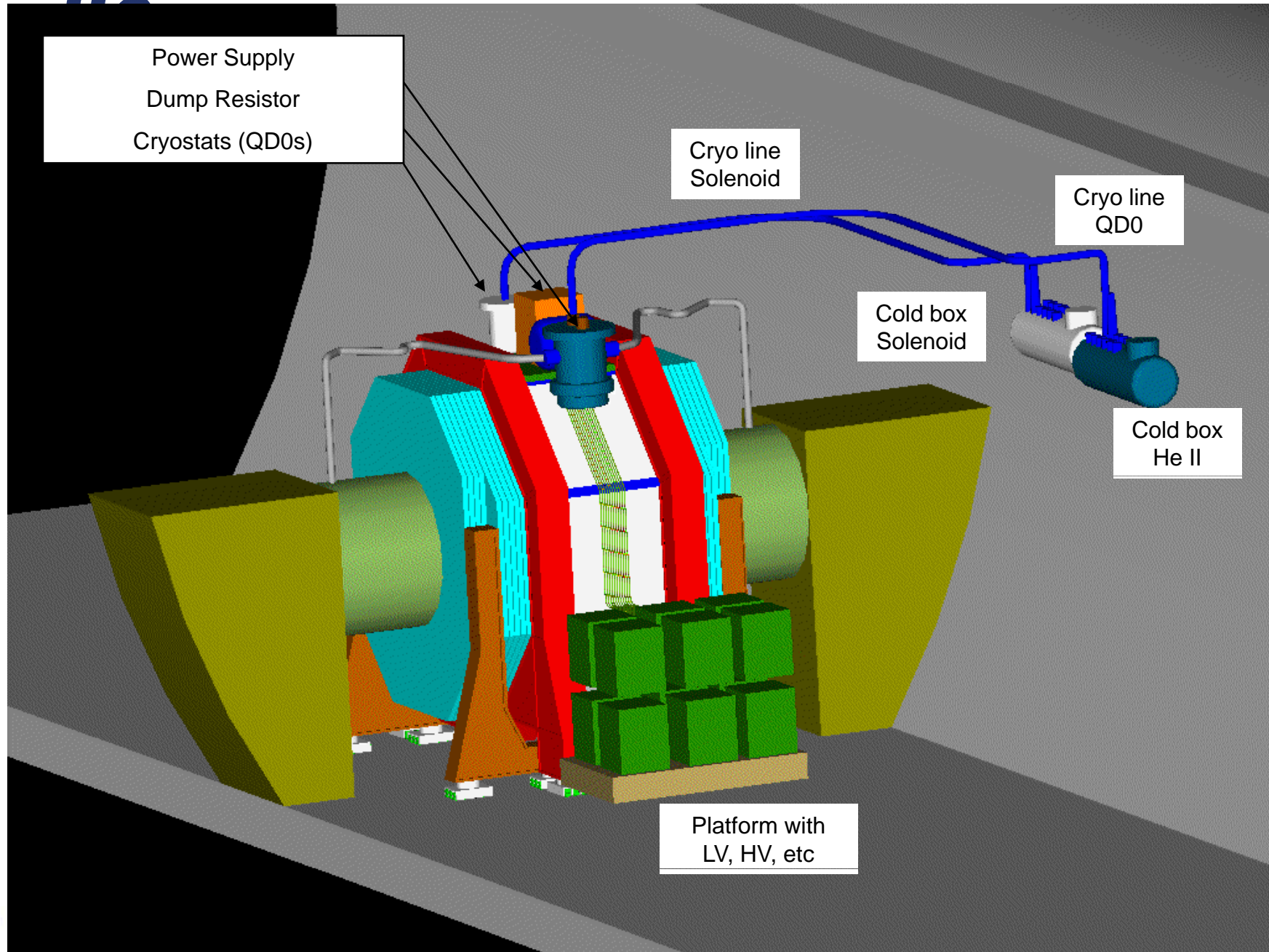


SiD IR Hall Assumptions

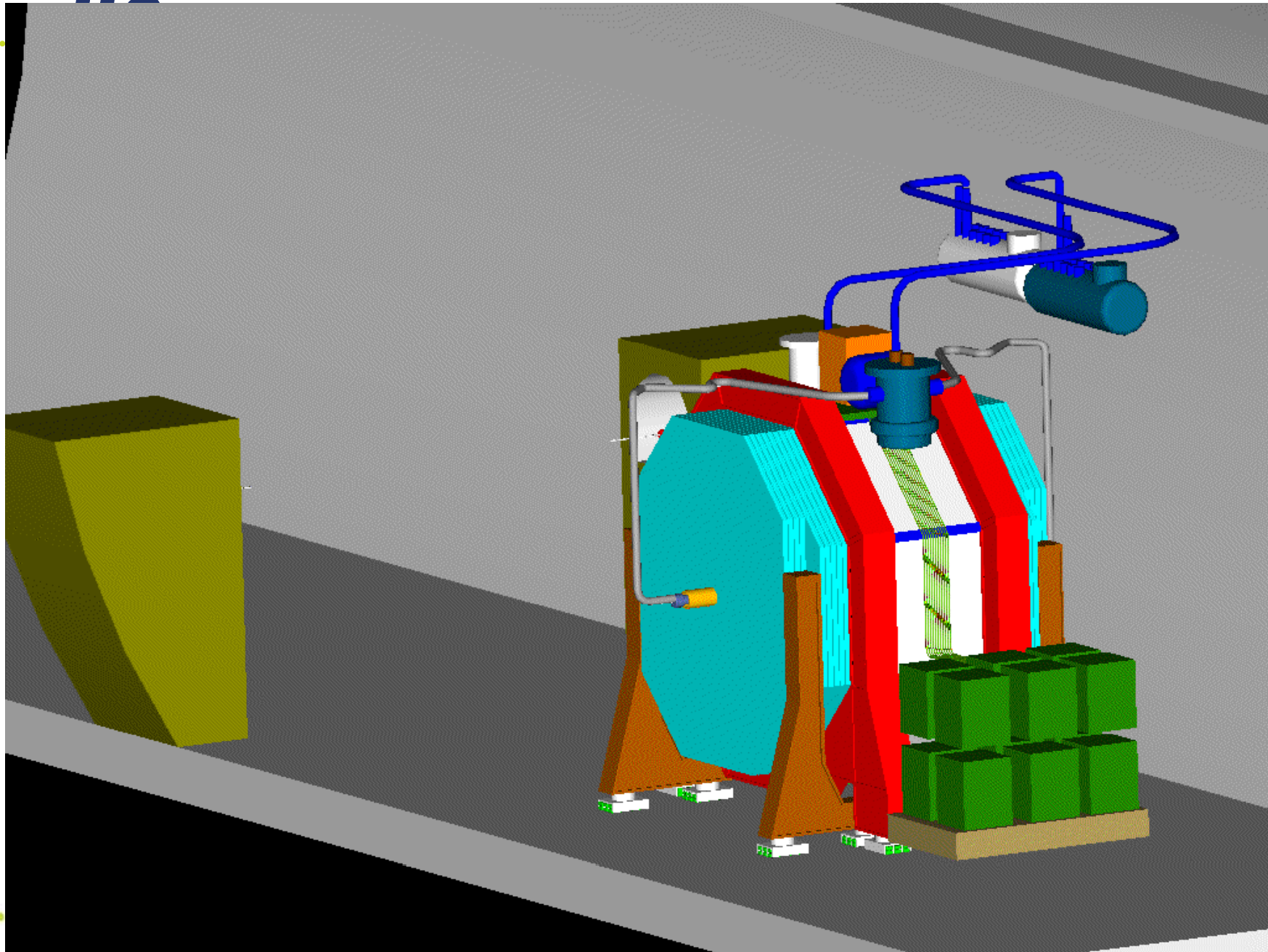
1. Push-Pull and doors opening with Hilman Rollers
2. Racks and ancillaries on SiD or on a side platforms (location driven by the the fringe field)
3. Cold Box off detector (in the hall)
4. Flexible cryogenic transfer line (100mm OD) Solenoid-Cold box
5. He compressors remote



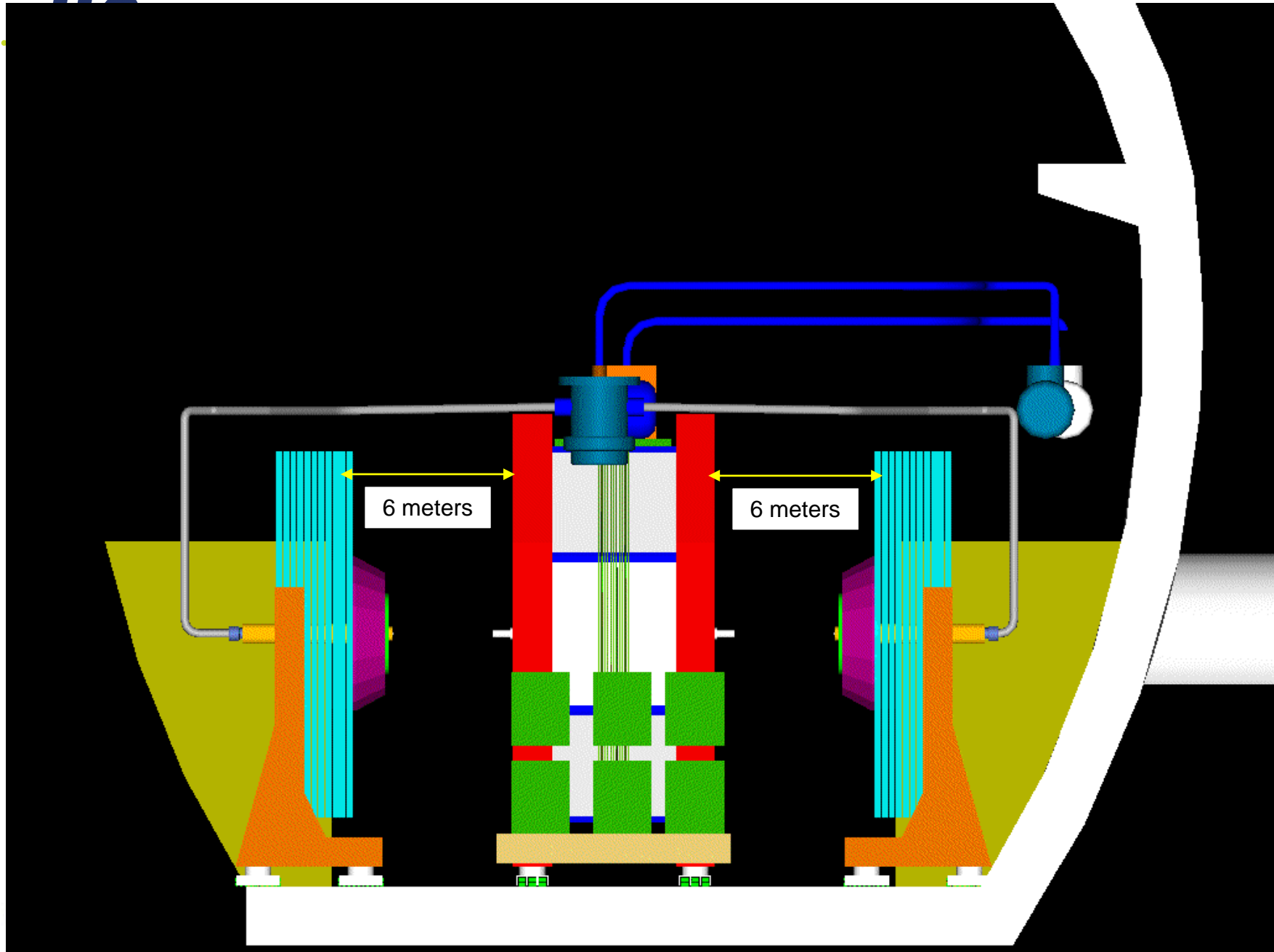
SiD closed on the beam



SiD push-pull (30 meters stroke)

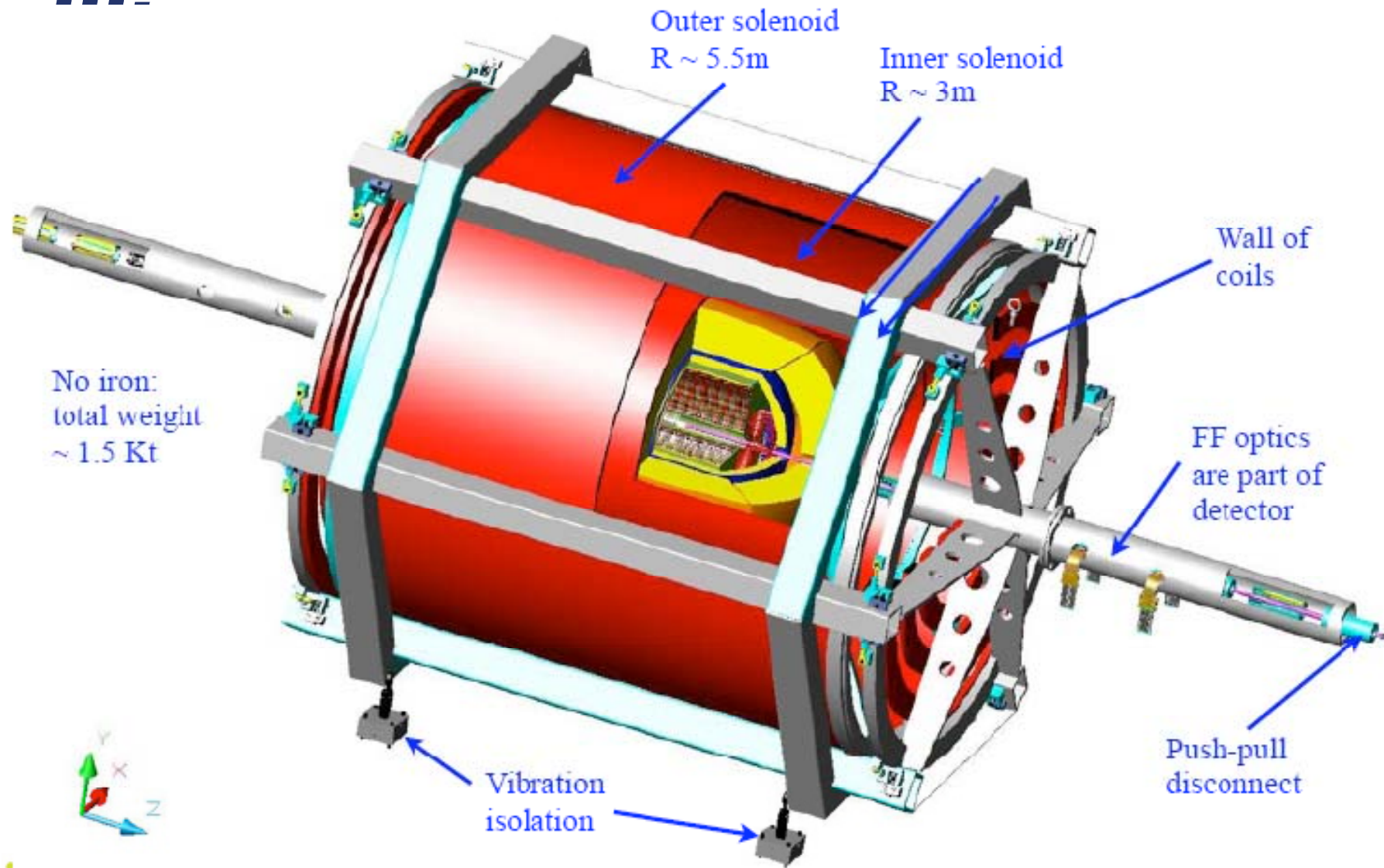


SiD opening @ 6 m off the beam



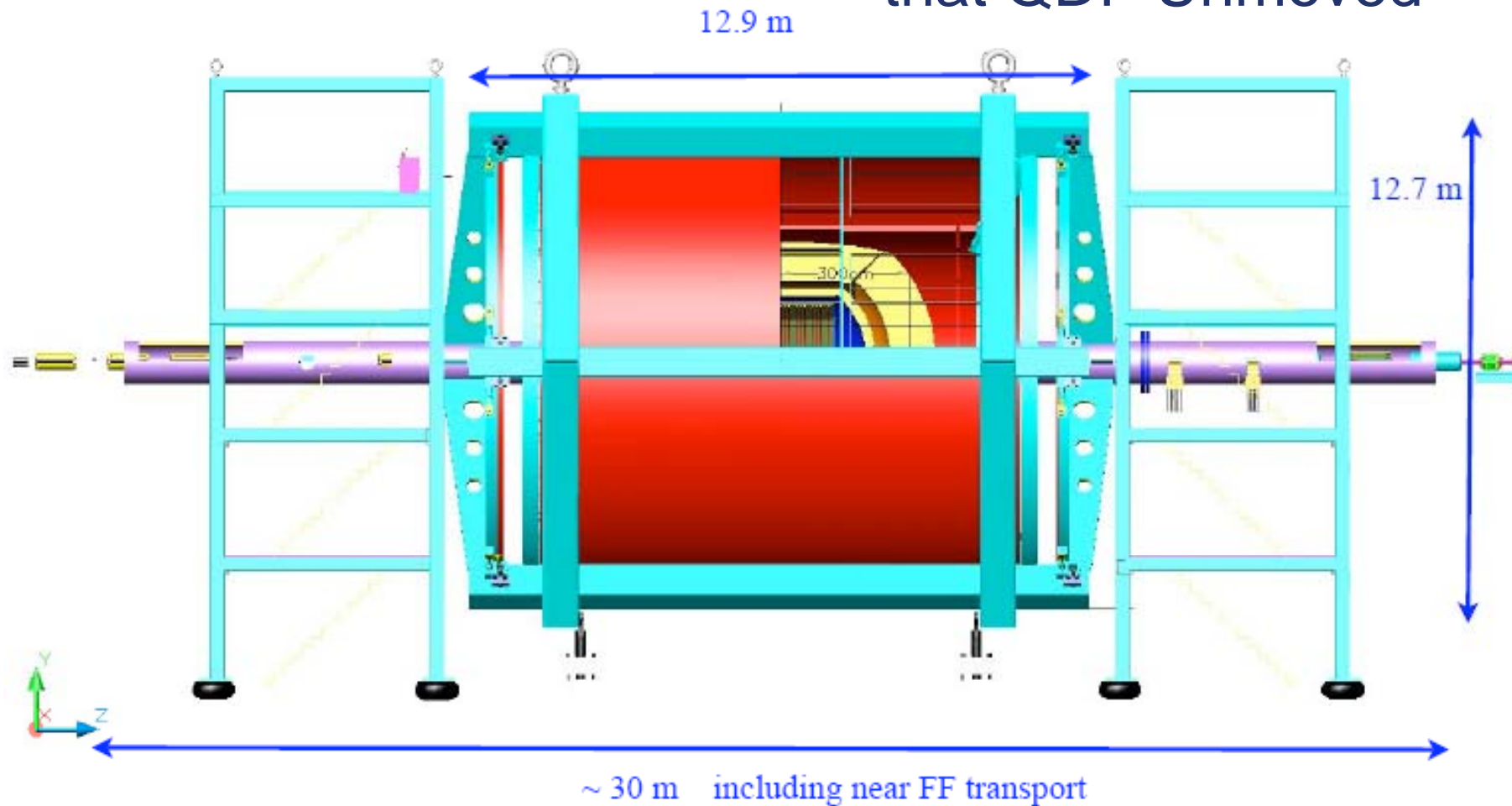


4th Detector Concept





Gross Dimensions 4th Does not respect BDS Requirement that QDF Unmoved





4th Underground Assembly

“CMS” Surface Assembly not addressed

– Space and volume

- 30m x 50m x 25m is ample space

– Crane

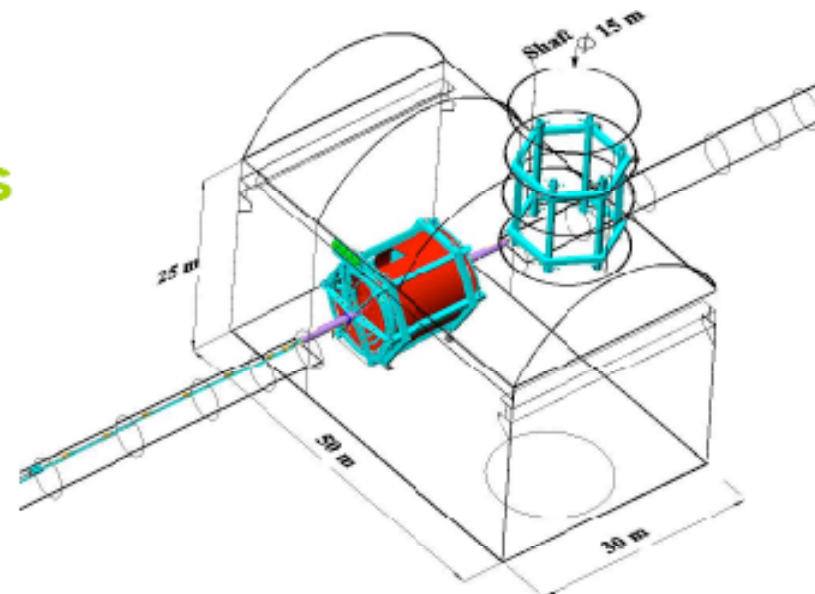
- 225 t (~ CMS coil cold mass) - this is maximum
- Calorimeter in 10t wedges

– shaft size

- 15 m diameter

– disassembly and access

- Titanium frame;
- wall of coils
- muon chambers
- calorimeter wedges





To Open 4th On-Beamline

I do not understand “move Lumi/Beam cals out”

- on beamline
 - **move Lumi/Beam-Cals out**
 - **move wall-of-coils out 2m**
 - **lift muon spectrometer chambers out vertically**
 - **move calorimeter modules out axially**
- At this point, the interior and the tracker ends are accessible. The FF support has not been moved.
 - **the tracking chamber can be ‘push-pulled’ to the other end**
 - **vertex chamber is moderately accessible in this position**



Summary of Push Pull & Surface Assembly Aspects of MDI

- GLDc and LDC have similar designs with similar crane/shaft requirements wherein FCAL/mask/QDO package supported in a tube off cantilevered off a pillar to ground (or platform)
- GLDc shows a moving platform while LFC says either platform or rollers would work
- SiD requires 2x gantry capacity for “CMS” surface assembly
 - **not convinced that non-CMS-like underground assembly is better**
 - **Feels (MIB at least) that platform is expensive solution germane to CERN geology & LHC detector complexity**
- SiD FCAL/mask/QDO package supported in a spider or tube directly from doors
 - **Needs to address how z motion of support tube is controlled**
- 4th does not consider surface assembly and wants to translate the QF1-QD0-Detector-QD0-QF1 package in push/pull



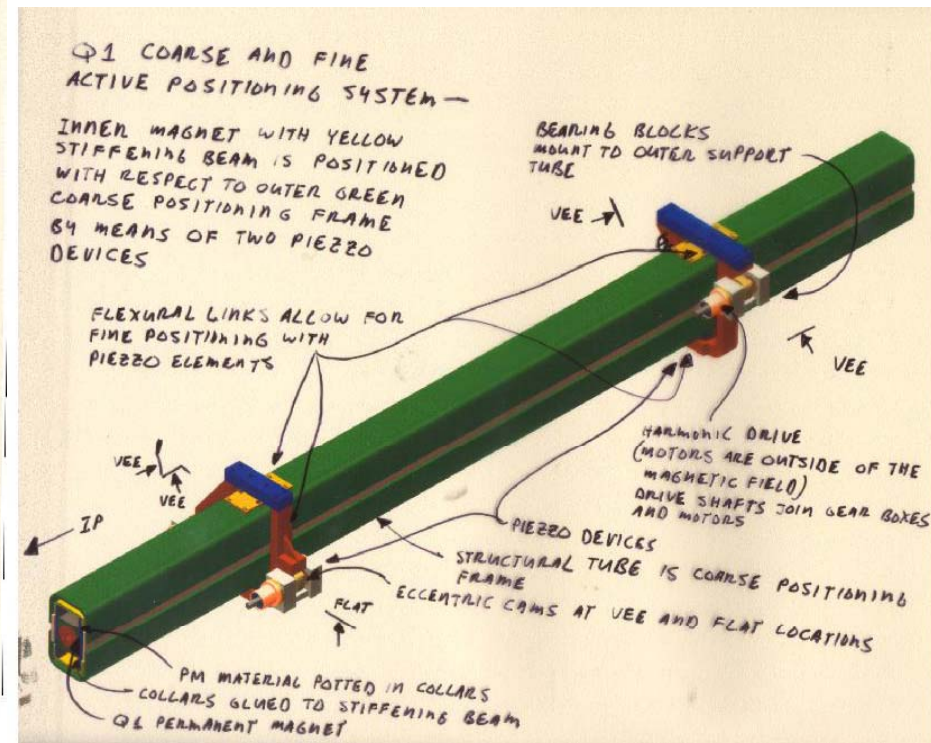
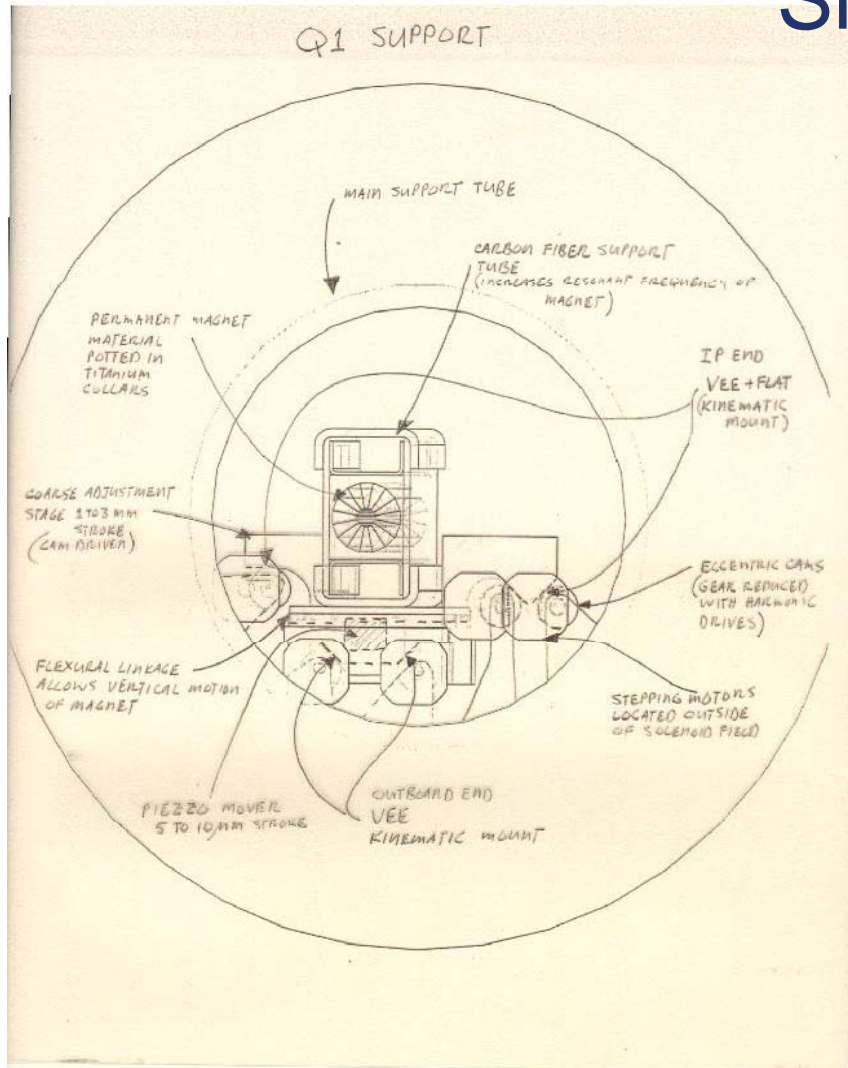
Interface Issues

- 1st order self-consistent PACMAN shielding invoked by GLDc, LDC, SiD. However, engineering required
 - **To see underground crane capacity required**
 - GLDc shows 0.5m Fe / 2.0m concrete from $r=0.5\text{m}$
 - SiD shows 1.0m Fe/ 2.0m concrete from $f=0.25\text{m}$
 - Rad Phys calculation done for 0.5 m Fe / 2.0m Con from $r=1.25\text{m}$
 - **To understand where detector A to detector B PACMAN interface occurs**
 - **To understand how to remove detector A specific PACMAN shielding “trapped” on detector B side of the beamline**
 - Hinged to the doors of detector A?
- Platform A, platform B, Floor, detector A, detector B interfaces
 - **If “A” needs/desires moving platform solution, must “B” adopt as well**



QD0 Package Adjustment Mechanism Likely to Require Significant Radial Space

Knut Skarpaas 2000 Design of Integrated Coarse/Fine Cam/Piezo Mover System for a stiffened PM QD0



KIEWIT/SLAC

00 01 00

Hall Parameters - Length around 90 m

