

Digitisation in MarlinTPC

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- 1 Structure of the simulation and digitisation in MarlinTPC
- 2 How it works
- 3 Status and outlook



General Tasks

- processes MC data from (full) detector simulation (Geant4, Mokka...)
- simulates detector response
- provides realistic data samples



Helper / Data classes

- VoxelTPC
- TPCVoxel
- EFieldVector

MarlinTPC Detector Simulation

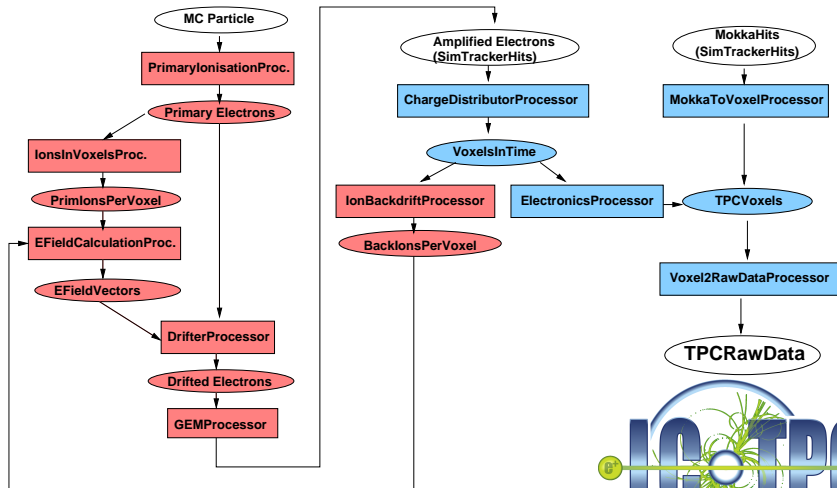
- PrimaryIonisationProcessor
- IonsInVoxelProcessor
- DriftProcessor
- GEMProcessor
- IonBackdriftProcessor
- EFieldCalculationProcessor

MarlinTPC Digitisation

- ChargeDistributionProcessor
- TPCElectronicsProcessor
- MokkaToVoxelProcessor
- VoxelToRawDataProcessor



Structure



Central helper class: VoxelTPC

- bins TPC in voxels:
 - binning in x,y by `gear::padIndex`
 - binning in z in arbitrary units
- fills/removes charge in/from `TPCVoxel`
- distributes charge according to longitudinal and transversal diffusion
- intrinsic pile-up of charges
- supports both geometries of the pad plane:
 - `gear::FixedPadSizeDiscLayout`
 - `gear::RectangularPadRowLayout`

Container class: TPCVoxel

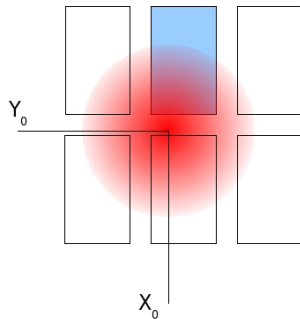
- derived from `LCIO::LCFixedObject`
- 3D bin of the TPC:
 - x,y defined by `gear::padIndex`
 - z by user defined unit (arbitrary)
- stores charges

Charge Distribution

- integration over a 2D gaussian
- rotation in case of circular pad layout

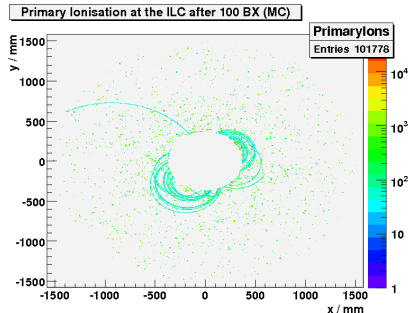
$$C(x, y) = Q_{hit} \cdot e^{\left(\frac{-(x-x_0)^2}{2\sigma^2}\right)} \cdot e^{\left(\frac{-(y-y_0)^2}{2\sigma^2}\right)}$$

$$Q_{pad} = \int_{x_{min}}^{x_{max}} \int_{y_{min}}^{y_{max}} C(x, y) dx dy$$



Processors using VoxelTPC:

- IonInVoxelProcessor
- IonBackDriftProcessor
- ChargeDistributionProcessor
- MokkaToVoxelProcessor



done:

- basic detector simulation
- implementation of VoxelTPC and TPCVoxel

to do:

- completion and implementation of the MokkaToVoxelProcessor
- completion and implementation of the VoxelToRawDataProcessor
- implementation of inhomogenous fields in DriftProcessor

