

# **Tuner, Coupler WP & specification table**

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# Work Package

## Cavity Package

### WP-CP1. Tuner

Tuner Selection ( Saclay tuner, Brade tuner, Slide-jack tuner, Ball-screw tuner, together with Fast tuner selection)

Lorentz detuning compensation (specification, method, required rigidities, fast tuning specification,...)

Motor location ( inside/outside/inside with accessible )

Piezo location ( inside/ accessible)

**[Baseline Selection at end of 2008]**, then detail engineering design.

### WP-CP2. Coupler

Baseline coupler : TTF-III (variable coupling)

Consideration of fixed coupling for easy installation/handling, cost point of view.

Re-visit of port diameter, etc.

**[Selection of fixed/variable coupling at end of 2008]**, then detail engineering design.

# Work Package (cont.)

## WP-CP3. Cavity Magnetic shield

Magnetic shielding method (inside or outside vessel)

[Selection of magnetic shield inside/outside at end of 2008], then detail engineering design.

## WP-CP4. Cavity vessel

Vessel material ( material selection, metal junctions, HPV regulation) including alignment method.

[Engineering design detail at end of 2009]

## WP-CP5. Cryomodule Operation ( S1 task )

Demonstration of 31.5MV/m operation by at least one cryomodule.

Possibility of STF phase 1 connected module with cavities from US, EU to be a S1 module (S1 global).

[demonstration by end of 2009]

## Plan for developing WPs and Spec. tables

- Call of EOI for proposed WP, done. (from IHEP, KEK-WG5 already received, LAL)
- Develop WP, with interested Institute, with resource(?), ~end of November.
- Revise specification profile table, ~end of November.
- **Finalize WP & spec. tables, Feb.2008**

3 - 7 March, ILC-GDE meeting at Sendai

# Specification tables

## which allow a plug-compatible concept (1)

tuner	specification item	specification	unit and comments	
Slow tuner	Tuning range	>600	kHz	
	Hysteresis in Slow tuning	<10	μm	
	Motor requirement	step-motor use, Power-off Holding, magnetic shielding		
	Motor specification	5 phase step motor	match to driver unit, match to connector pin assignment	xxA/phase to be specified later.
	Motor location	inside 4K? / outside 300K? / inside 300K accessible from outside?	need availability discussion, MTBF	need more discussion
	Magnetic shielding	<20	mG at Cavity surface, average on equator	
	Heat Load by motor	<50	mW at 2K	
	Physical envelope	do not conflict with GRP, 2-phase line, vessel support, alignment references, Invar rod, flange connection,...		cable connection, Mag shield
	Survive Frequency Change in Lifetime of machine	~20 Mio. steps	could be total number of steps in 20 years,	

Slow Tuner

# Specification tables

## which allow a plug-compatible concept (2)

Fast tuner	Tuning range	>1	kHz over flat-top at 2K	
	Lorentz detuning compensation	<100	Hz at 31.5MV/m flat-top	
	Actuator specification	low voltage piezo 0-200V	match to driver unit, match to connector pin assignment	
	Actuator location	inside 4K?/inside 4K accessible/inside 100K? accesible / inside 300K accessible from outside?		need more discussion
	Magnetic shielding	<20	mG at Cavity surface average	
	Heat Load in operation	<50	mW	measure first, decide later
	Physical envelope	do not conflict with GRP, 2-phase line, vessel support, alignment references, Invar rod, flange connection,...		
	Survive Frequency Change in Lifetime of machine	>10 <sup>10</sup>	number of pulses over 20 years, (2E9:operational number)	

Fast Tuner

# Specification tables

## which allow a plug-compatible concept (3)

Coupler

specification items	condition	specification	unit and comments		
Power requirements	Operation	>400	kW for 1300 us		
	Processing	>1000	kW upto 400 us	need after vac break, & cool-down	
		>600	kW larger than 400 us	need after vac break, & cool-down	
	Processing with reflection mode	>600	kW for 1300us	in Test stand	
Processing time	warm	<50	hours	after installation	
	cold	<30	hours	after installation	
Heat loads /coupler	2K static	<0.1	W		decide later
	5K static	<0.5	W	depend on tunability	decide later
	80 K static	<3	W		decide later
	5K dynamic	<0.3	W		decide later
	80K dynamic	<3	W		decide later
Cavity vacuum integrity		2	# of windows		
		NO	bias capability		
RF Properties	Qext	Yes/No	tunable		need more discussion,decide later
	Tuning range	1-10	10^6 if tunable		need more discussion,decide later
Physical envelope	Position		compatible to TTF-III		
	Flange		compatible to TTF-III		to cavity, to cryostat
	waveguide		compatible to TTF-III		
	support		compatible to TTF-III		
Instrumentation					
vacuum level		>1			
spark detection		0	at window		
electron current detection		>1	at coax		
temperature		>1	at window		

# Specification Table

Determine the design profiles/outlines.

To be used for the plug compatible design.

The plug compatible design, the alternate design must meet this specification table.

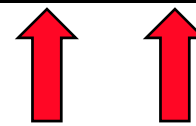
They should demonstrate the specification with required number of validation test.



# Survey Results (abbreviated)

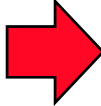
Rich Stanek

Validation Survey	NOTE: Validation tests occur after all R&D and prototype work is complete & design change is mature enough to be considered as change to baseline													
If you make a change in this →	Cavity Shape LL OR RE	Cavity Material Large Small Grain	Magnet Shield Location	Quad Design	Quad Position	BPM Design	He Vessel SS vs. Ti	Tuner Design	Coupler Design	Pipe Size (dia)	Rad Shield Design	Support Design Transport fixture	Instrumentation	Align System
You validate the change by doing this ↓														
Can design change be made without testing? (Y/N)	N	N	N	N	N (few Y)	N	N	N	N	Y (few N)	Split	N	N	N
Number of components fabricated & tested?	24-30	30	10	1-3	3	3	24-30	10	24	1	1-3	1-3	1	1
Does design change require only component level testing? (Y/N) Component level testing equals Vert or Horiz testing or cycle test	N	Y (V&H)	N	N	N	N	Split (H)	N	N	N	Split	N	N	N
Hours of component level testing?		1000hrs		40hrs		500hrs	1000hrs	1000hrs	1000hrs			250 hrs	250 hrs	
Does design change require testing in cryomodules (without beam)? (Y/N)	Y	N	Y	Y	Y	Y	Y (few N)	Y	Y	Y	Y	Y	Y	Y
Number of cryomodules?	3		1	1	3	3	3	1-3	3	1	1	1-3	1-3	1
Does design change require testing in RF Unit/String test (with beam)? (Y/N)	Y	N	N	N	Split	Y	N	Split	Split	N	N	N	N (few y)	N
Hours of string testing?	1000hrs	0	0	0	1000hrs	1000hrs	0	1000hrs	500hrs	0	0	0	100hrs	0



Results from survey can be used to identify dependencies in design schedule

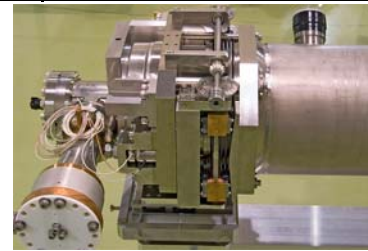
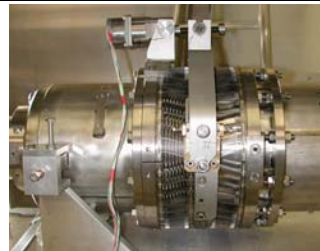
# Tuner selection

- ✓ 1. Identify the down-selection item.
- ✓ 2. Identify the proposal & proposer of the technology.
-  3. Make comparison tables for advantages & disadvantages from each proposer.
4. PM Make fair-minded comparison table to be filled in by each proposer.
5. PM decide the technology according to the table.

# comparison table for baseline tuner selection

**Need to develop the table!**

<b>Slow Tuner</b>					
		TTF	INFN/FNAL	STF	STF
		<b>Saclay -1</b>	<b>Blade</b>	<b>Slide Jack</b>	<b>Ball Screw</b>
		Lifetime Test (~ 0.1mm x 10000 Times) is necessary.			
Mechanism		Double Lever	Blade+Lever+Screw	Wedge+Screw+Gear	Screw+Worm Gear
			Blade has the potential Problem of Fatigue?		Life time of Coating?
Stiffens	N / $\mu$ m	40	25	290	1000
		Seems not stiff enough	Seems not stiff. If used to TESLA Cavity DLD at Flat-Top becomes ~900Hz.		
Stroke	mm		< 2	3.5	Long enough
Location		Beam Pipe	Jacket Cylinder	Jacket Cylinder	Jacket Cylinder
		The room for tuner is small. Top Heavy. Alignment?			
Cost					



Cont.

<b>Fast Tuner</b>					
		TTF	INFN/FNAL	STF	STF
		<b>Saclay -1</b>	<b>Blade</b>	<b>Slide Jack</b>	<b>Ball Screw</b>
		Piezo(200V)	Piezo(200V)	Piezo(150V)	Piezo+Blade
			Speed ?		Blade has the potential Problem of Fatigue. Speed ?
		NORIAC (1 Spare)	NORIAC (1 Spare)	Piezo Mechanic x 1	Piezo Mechanic x 1
Size	mm	10 x 10 x 26	10 x 10 x 38	φ20 x 18	
Stiffness	N / μm	105	70	500	
Max. Load	kN	4	4	14	
Stroke:RT	μm	40	60	20	
Stroke:2k	μm	4	6	2	
Compensation	μm	3.4	6	1	
Speed					
Delay		0.6 msec.			
<b>Repairability</b>					
Motor		need Disassemble	need Disassemble	Outside	Accessible?
Piezo		need Disassemble	need Disassemble	Repairable	Accessible?
		US Study on this Subject exists.			
		How to check Piezos just we install. There are no experience for long term operation in Pulsed mode. Life time Test is necessary.			

**Would like to call Tuner discussion as follows;**

for DESY (Saclay) Tuner,

for INFN Tuner,

for KEK (Noguchi) Tuner,

.... Later, KEK (Higashi) Tuner,

discussion of Lorentz detuning compensation.

discussion of motor/piezo maintainability.

**Would like to call Coupler discussion as follows;**

for strategy of using fixed coupling

for improvement of coupler process.