

Resolution calculation investigation & March '08 results

The Molloy Resolution Calculation

For $P_i = (\text{diff}_i / \text{sum}_i) * C_i + O_i$

i = processor number

P_i = position measured by processor

C_i = calibration constant of processor

O_i = offset of processor

And $A = (P_2 \ P_3)$, $B = (P_1)$

We solve for the set of linear equations $Ax = B$ where $x = A^+B$

Since A & B are not square and there may be no unique set of solutions for x we use the Moore-Penrose pseudoinverse matrix which gives the least squares solution for x .

$PP_1 = x(1)*P_2 + x(2)*P_3 + x(3) =$ predicted position as given by P_2 & P_3

\therefore

Res 1 = std($P_1 - PP_1$)

The Kalinin Resolution Calculation

Using the same notation as for the Molloy method we get;

$$PP_1 = 2 * P_2 - P_3$$

$$PP_2 = 0.5 * P_1 + P_3$$

$$PP_3 = 2 * P_2 - P_1$$

And

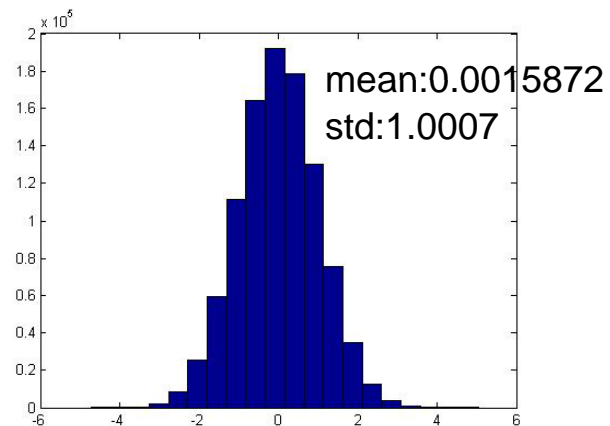
$$Res_1 = \text{std} (P_1 - PP_1) / \text{sqrt}(6)$$

$$Res_2 = \text{std} (P_2 - PP_2) * \text{sqrt}(2/3)$$

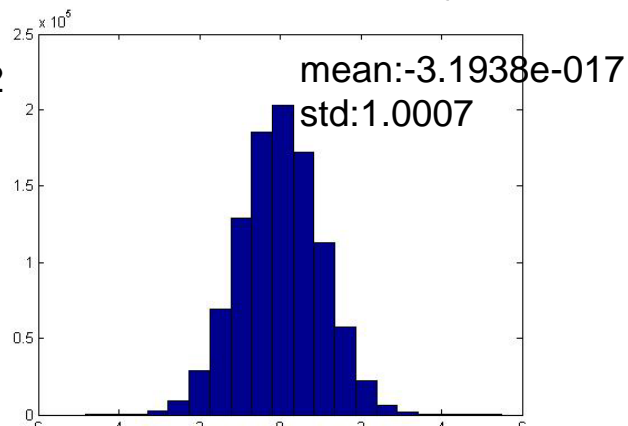
$$Res_3 = \text{std} (P_3 - PP_3) / \text{sqrt}(6)$$

These two methods were then tested using simulated data sets to give the results displayed on the next slide.

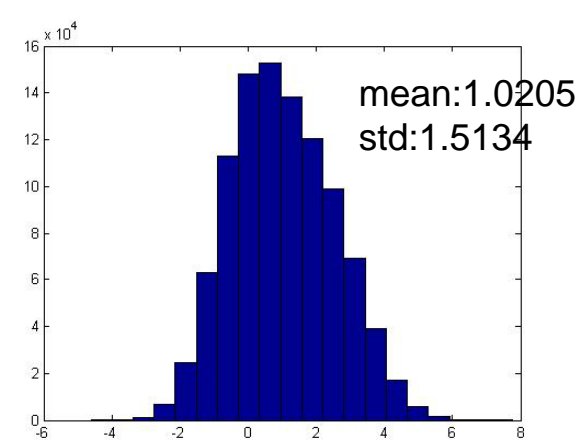
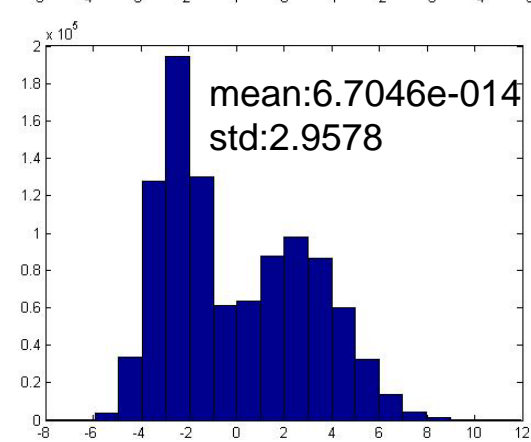
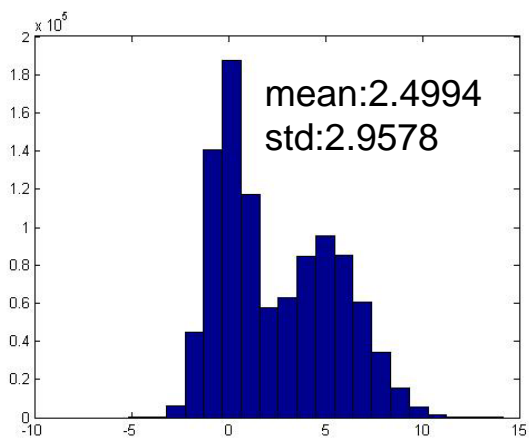
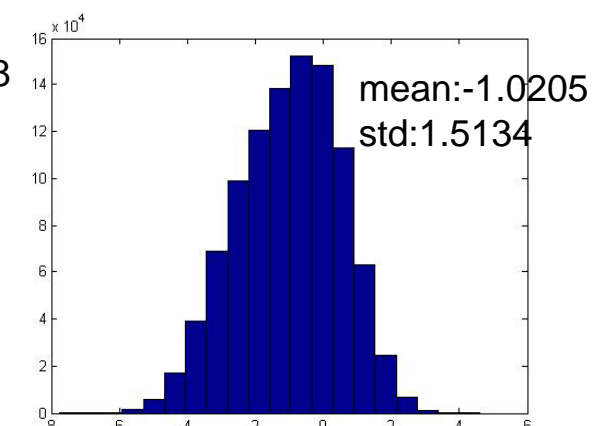
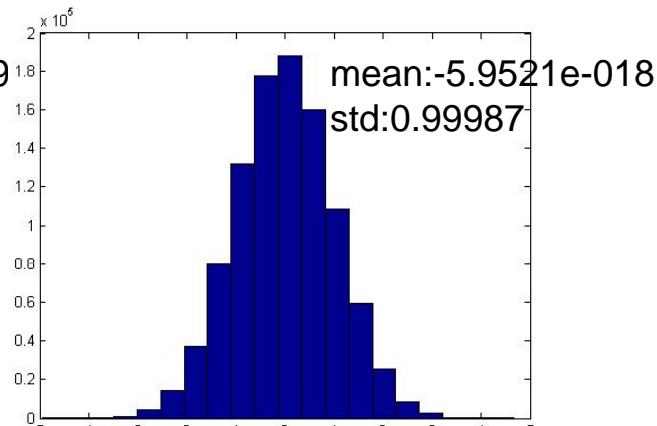
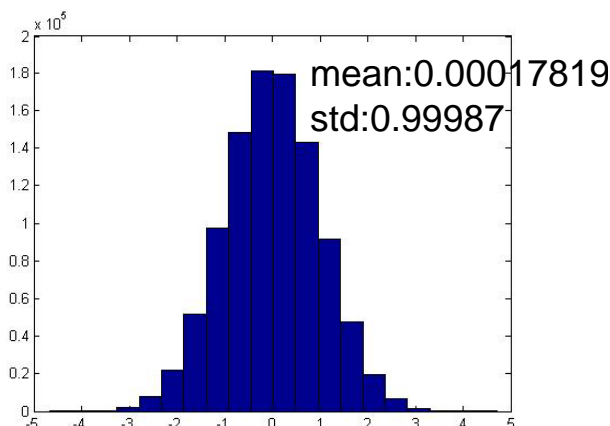
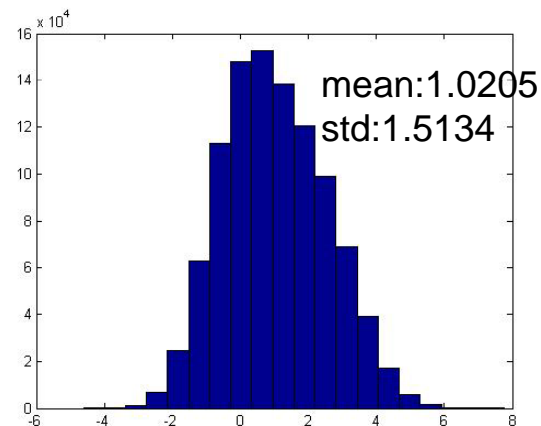
Input



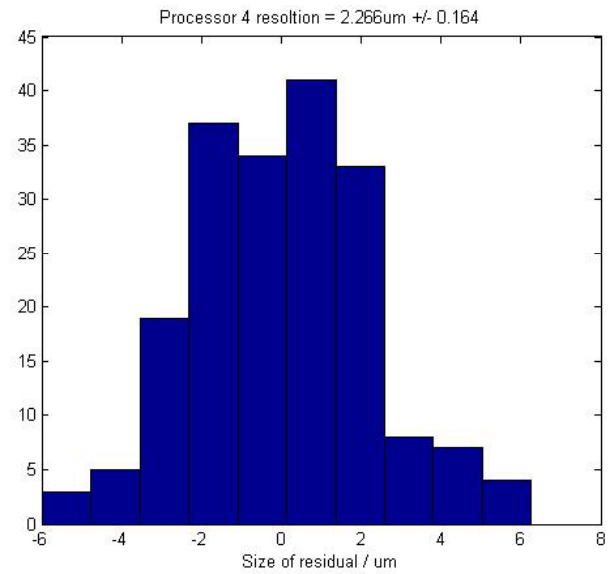
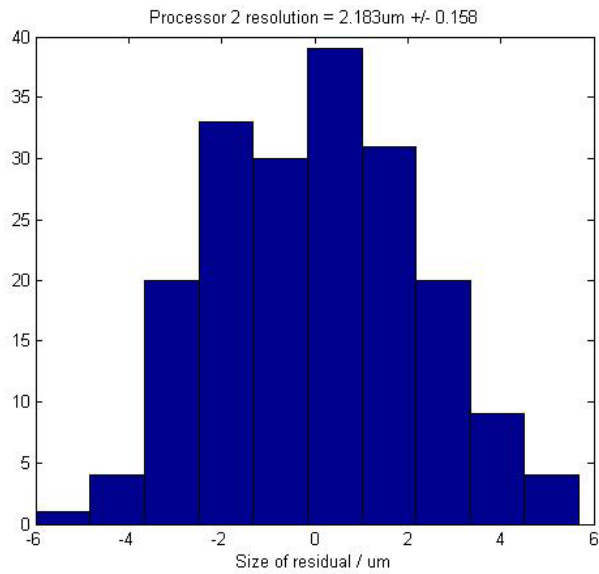
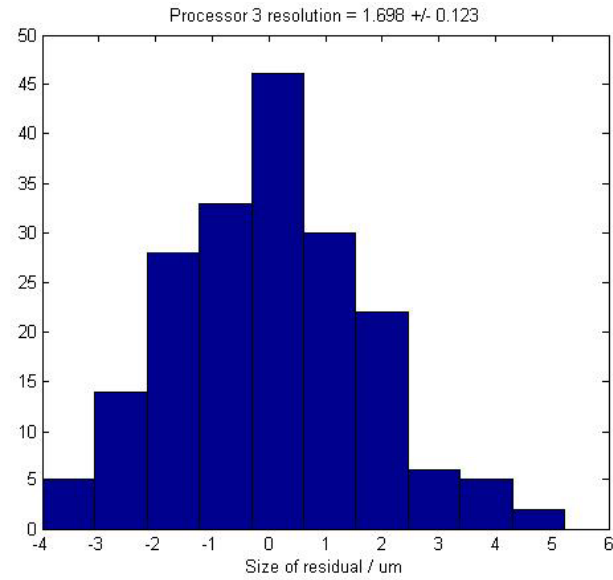
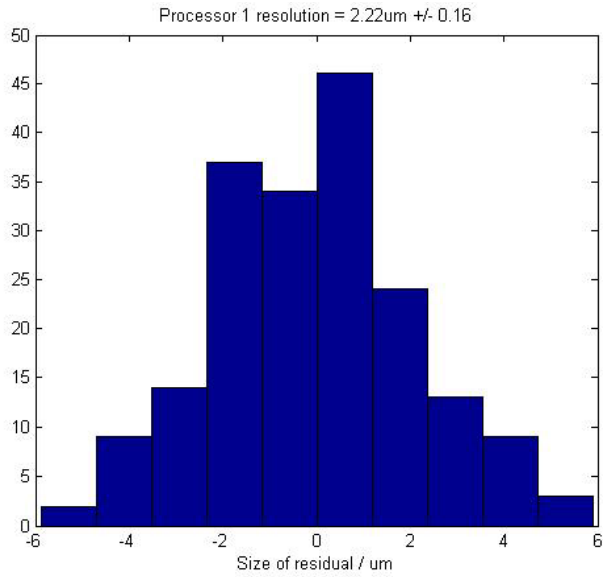
Output (Molloy)



Output (Kalinin)



May '08 results for 4 processors on 1 pickup



Resolution vs position for 4 processors on 1 pickup

