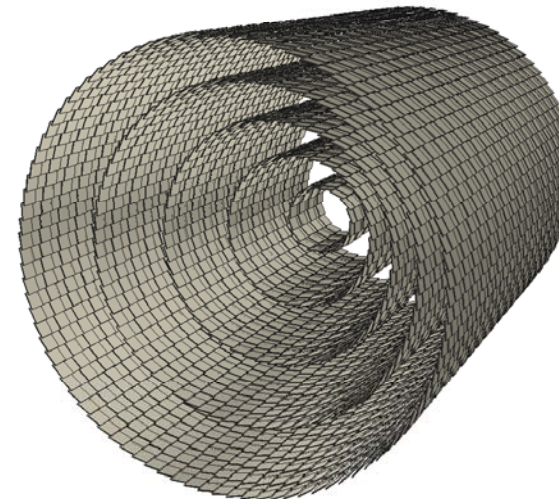
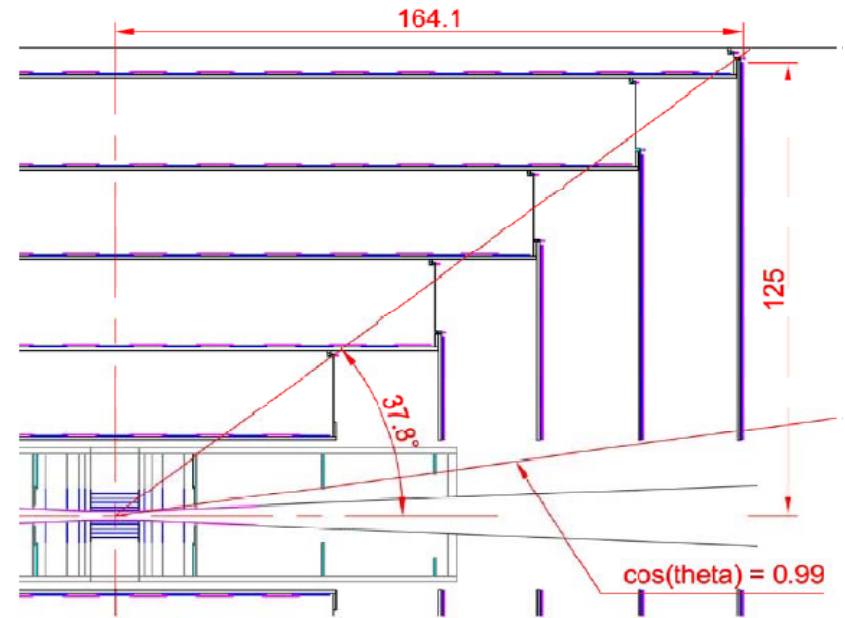


A circular detector layout with concentric rings and radial lines. Data points are shown as small squares in green, yellow, and blue, forming tracks that curve inward from the outer rings towards the center. The text 'SiD Track Reconstruction' is overlaid in red on the left side.

**SiD Track
Reconstruction**

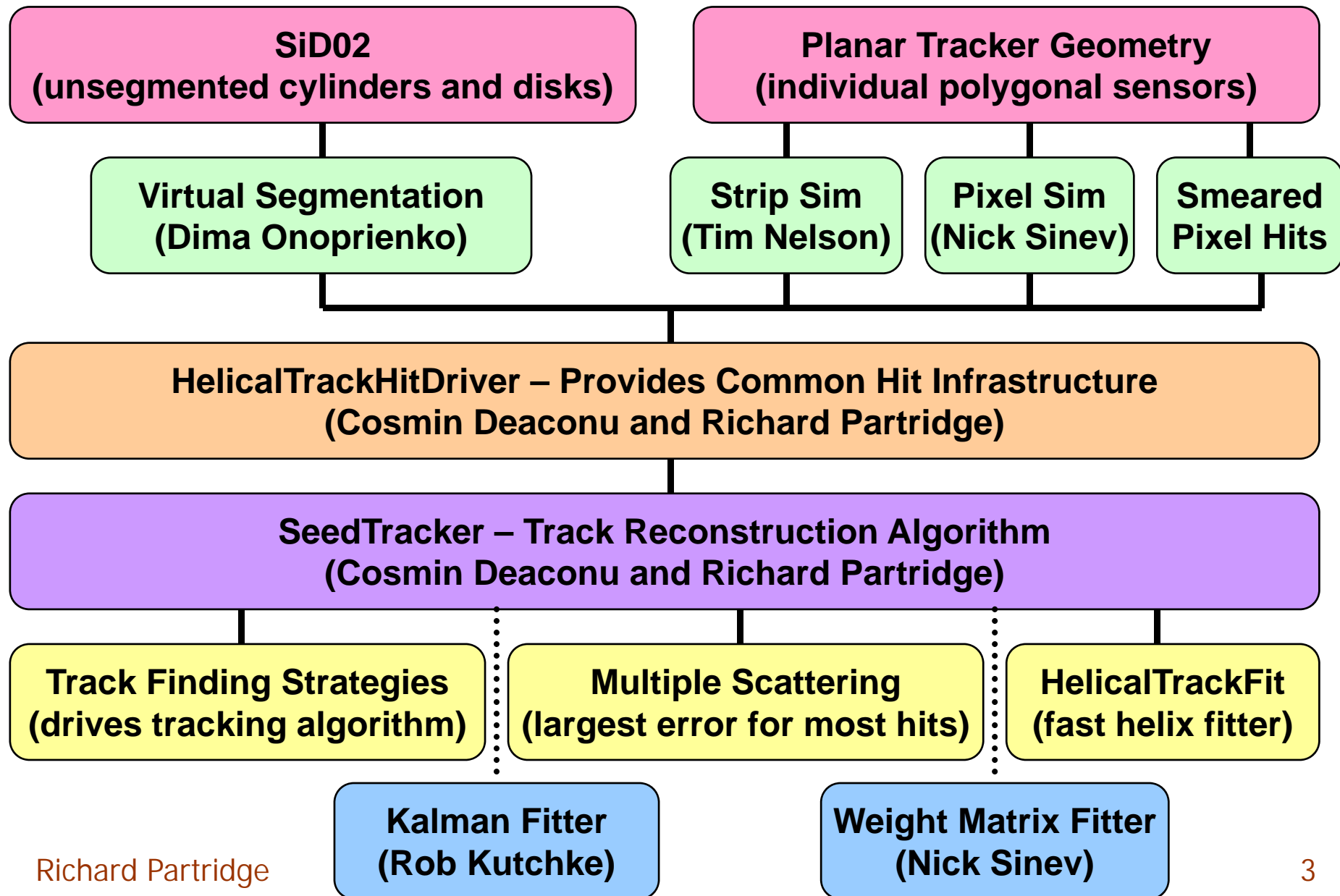
**Richard Partridge
Brown / SLAC
LCWS 2008**

- ◆ SiD proposes an all-Si Tracker
 - 5 barrel + 7 disk pixel inner detector
 - 5 barrel (axial strip) + 4 disk (stereo strip) outer detector
- ◆ New tracking software developed using org.lcsim framework
 - Supports any combination of pixel, axial strip, and stereo strip layers in barrel or disk geometry
 - Detector segmentation can be either cylinders/disks with virtual segmentation or individual planar sensors
 - Digitization options include full simulation of charge collection for strips and pixel detectors (using field map)
 - Flexible track finding developed explicitly for tracker design studies

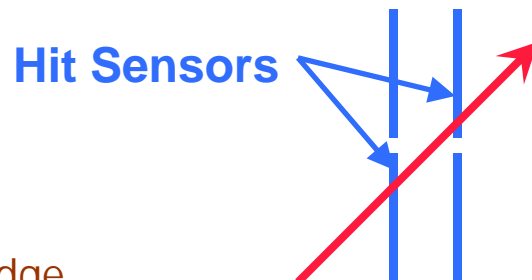




Track Reconstruction Flow Chart



- ◆ Tracker hit infrastructure is rather weak in LCIO
 - Key features (e.g. sensor orientation and endpoints of a strip) hit are missing
 - Hit errors are represented by a 3x3 covariance matrix, which is intrinsically singular for 1 coordinate (strip) or 2 coordinate (pixel) measurements
- ◆ Virtual segmentation and full digitization algorithms extend LCIO conventions, but take different approaches
- ◆ Common hit infrastructure developed to shield the tracking code from the details (and changes) in the hit digitization
- ◆ Infrastructure also provides extensive support for stereo hits
 - Forms stereo hits (and ghost hits) from nearby non-parallel strips
 - Adjusts hit position for track direction
 - Uncertainty in hit position includes uncertainty in the track direction



Common Hit Infrastructure provides robust handling of stereo hits, including cases like the one show here



SeedTracker Philosophy

- ◆ Track finding is guided by a set of user defined “Strategies”
 - A strategy defines layers to be used, their roles, and constraints (e.g. $p_T > x$)
- ◆ All pattern recognition code is agnostic as to the type of hit
 - No differentiation between pixel or strip, barrel or forward sensors
- ◆ Multiple Scattering must be accounted for in track finding
 - Superb intrinsic pixel/strip resolution \Rightarrow MS errors will typically be dominant
- ◆ A fast helix fitter, HelicalTrackFitter, plays a central role
 - This is the only piece of code that needs to understand the differences between pixels and strips, barrels and disks, etc.
- ◆ All decisions based on a global χ^2 from fits, constraints, etc.
 - No internal parameters or tuning is required if tracker geometry changes
 - Constraint example: if ($|z_0| > z_0^{\max}$) $\chi^2 = \chi^2 + (|z_0| - z_0^{\max})^2 / \sigma^2(z_0)$
- ◆ Maximize flexibility for detector design optimization
 - No aspect of the detector geometry is hard coded
 - Automated strategy generation further simplifies performing design studies



SeedTracker Algorithm

- ◆ Track finding begins by forming all possible 3 hit track seeds in the three “Seed Layers” (specified in the strategy)
 - Brute force approach to finding all possible track seeds
- ◆ Typically require the presence of a hit in a “Confirmation Layer” (specified in the strategy)
 - Significantly reduces the number of candidate tracks to be investigated
- ◆ Add hits to the track candidate using hits on the “Extension Layers” (specified in the strategy)
 - Discard track candidates that have fewer than the minimum number of hits specified in the strategy
 - If two track candidates share more than one hit, best candidate is selected
- ◆ Upon each attempt to add a hit to a track candidate, a helix fit is performed and a global χ^2 is used to determine if the new track candidate is viable
- ◆ Hooks for user-defined diagnostics at all decision points



Track Finding Strategy

- ◆ The user interacts with the track reconstruction program by specifying one or more “strategies”
- ◆ Strategies identify:
 - Layers to be used in track finding
 - Role of each layer (seed, confirm, extend)
 - “Cutoffs” on helix parameters (p_T , d_0 , z_0) where a χ^2 penalty is introduced
 - Minimum number of confirmed hits and total hits
 - Cut on global χ^2
 - “Bad Hit χ^2 ” – a χ^2 increase exceeding this amount will flag hit as suspect
- ◆ Tracking code processes all strategies sequentially
 - Final list of tracks is the union of all distinct tracks
- ◆ Strategies can most easily specified using an xml file, but may be hard coded if desired

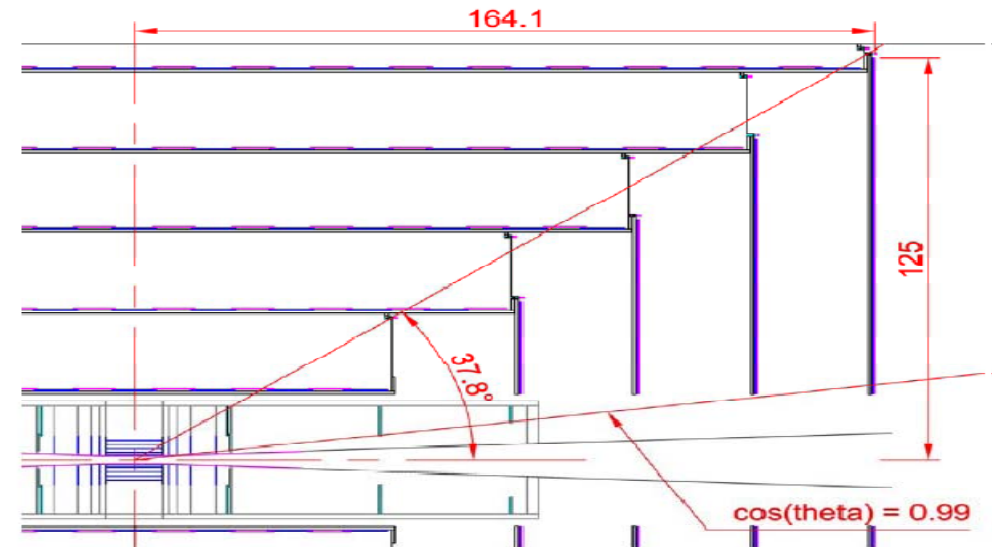
```

<?xml version="1.0" encoding="UTF-8"?>
<StrategyList>
  <Strategy name="OutsideInBarrel">
    <!--Cutoffs-->
    <MinPT>1.0</MinPT>
    <MinHits>7</MinHits>
    <MinConfirm>1</MinConfirm>
    <MaxDCA>10.0</MaxDCA>
    <MaxZ0>10.0</MaxZ0>
    <MaxChisq>50.0</MaxChisq>
    <BadHitChisq>15.0</BadHitChisq>
    <!--Layers-->
    <Layer type="Extend" layer_number="1" detector_name="SiVertexBarrel" be_flag="BARREL" />
    <Layer type="Extend" layer_number="2" detector_name="SiVertexBarrel" be_flag="BARREL" />
    <Layer type="Extend" layer_number="3" detector_name="SiVertexBarrel" be_flag="BARREL" />
    ...
    <Layer type="Confirm" layer_number="2" detector_name="SiTrackerBarrel" be_flag="BARREL" />
    <Layer type="Seed" layer_number="3" detector_name="SiTrackerBarrel" be_flag="BARREL" />
    <Layer type="Seed" layer_number="4" detector_name="SiTrackerBarrel" be_flag="BARREL" />
    <Layer type="Seed" layer_number="5" detector_name="SiTrackerBarrel" be_flag="BARREL" />
  </Strategy>
  <Strategy name="OutsideInEndcap">
    ...
  </Strategy>
  ...
</StrategyList>

```

Example xml Strategy File

- ◆ Finding an optimal set of strategies that provides complete coverage turns out not to be so easy
 - Many distinct sets of layers are required, especially in the forward region
 - Requires carefully examining possible track paths looking for coverage holes
 - Typically need ~ 20 strategies to have full coverage for baseline tracker design to find ≥ 7 hit tracks with $p_T > 1.0$ GeV for 100% detector efficiency
- ◆ Strategy list needs to be re-optimized whenever:
 - Change detector geometry
 - Change helix cutoffs
 - Change number of hits required



- ◆ Strategy Builder automates creation of optimized strategy list



Strategy Builder Algorithm

- ◆ Starting point is a file of simulated events that you want to use for optimization
 - Simulated top events would be a good choice since they have a wide variety of particles in them
- ◆ Findable MC particles are identified based on helix cutoffs and minimum hit requirements
- ◆ All potential combinations of seed / confirm layers are identified and ranked by a weighted frequency of occurrence
 - Weighting can favor / disfavor using particular layers
 - Weighting can also favor combinations with greater adjacency between layers
 - Can optionally randomly discard MC hits to simulate detector inefficiency
- ◆ Strategy builder chooses the highest ranked strategy
 - Remove MC Particles from top ranked strategy and re-do ranking
 - Iterate until desired track finding efficiency is achieved

Multiple Scattering

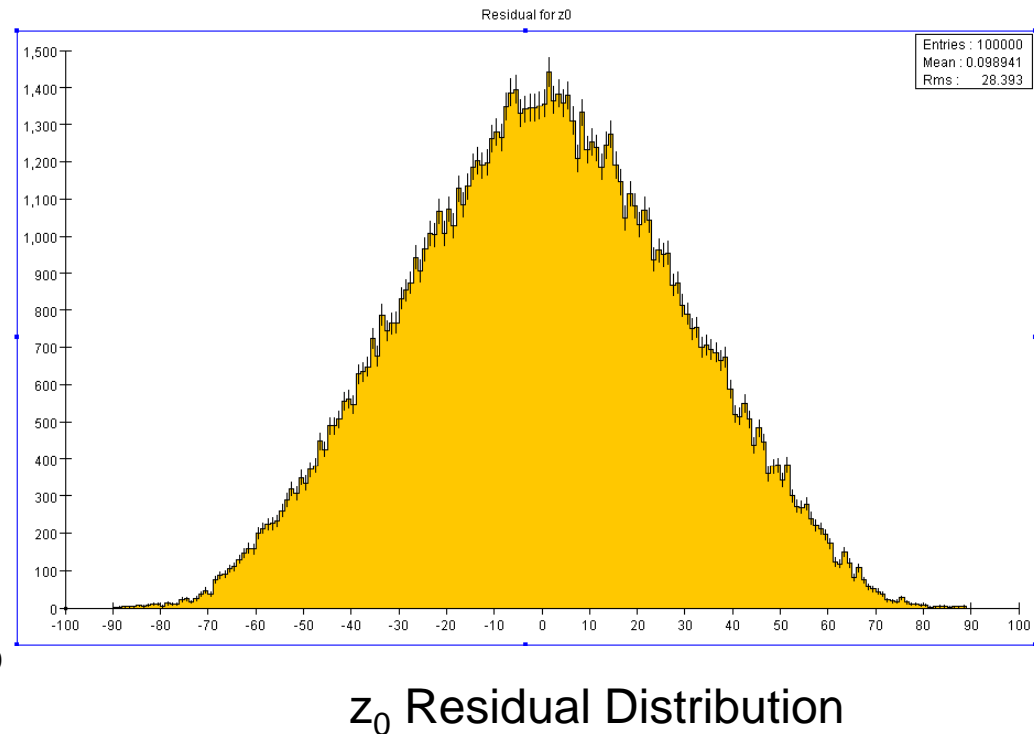
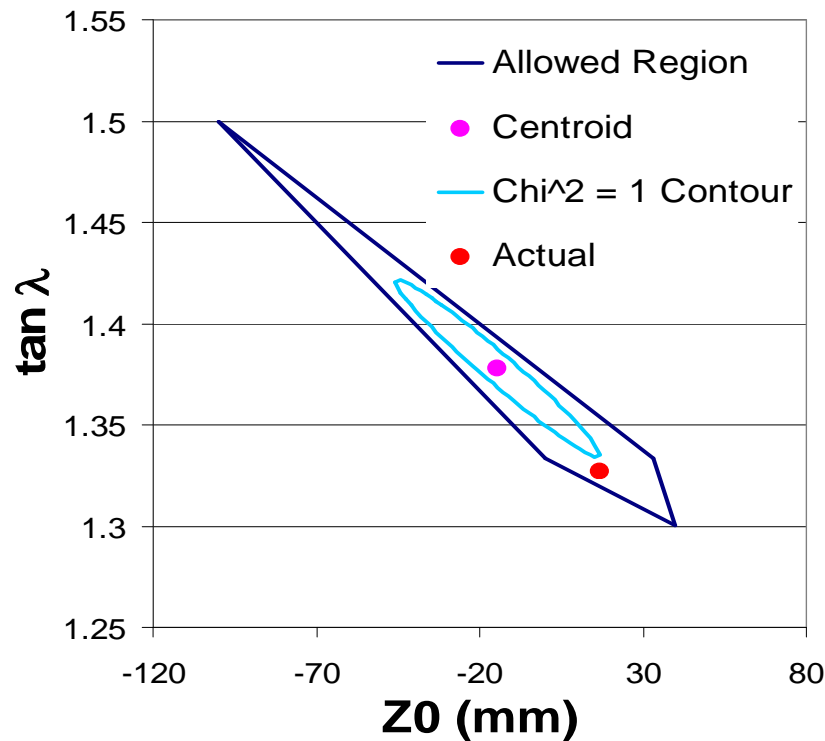
- ◆ Multiple scattering errors dominate for most tracks, so having a reasonable estimate of these errors is critical to form a sensible χ^2 discriminator
- ◆ SeedTracker constructs a model of the tracker material
 - All material that derives from a common element in the compact.xml description is lumped together
 - Material is modeled as either a cylinder or disk depending on aspect ratio as seen from the origin
- ◆ Multiple scattering errors are assigned to each hit
 - Tracks are assumed to originate from the point of closest approach
 - For a given hit, the multiple scattering error is the cumulative error from all the material crossed in getting from the point of closest approach to the hit
- ◆ Multiple scattering correlations are ignored for track finding
 - This isn't really true - a given multiple scattering will systematically affect all subsequent hits – but shouldn't have a big effect on track finding

- ◆ Approximate helix by fitting a circle in $x - y$ and a line in $s - z$
 - Circle fit uses Karimaki algorithm
 - $s-z$ fit uses a straight line fitter or ZSegment fitter when there are < 2 3D hits
- ◆ First fit for a given 3 hit seed is performed without MS errors
 - First determination of the helix parameters $\omega \equiv 1/R$, d_0 , ϕ_0 , z_0 , and $\tan(\lambda)$
- ◆ Calculate the MS errors for each hit using this helix
- ◆ Perform a second helix fit including MS errors
- ◆ If necessary, calculate a constraint χ^2 to estimate the increase in χ^2 needed to pull helix into compliance with the constraint
 - Kinematic constraints: $p_T > p_T^{\min}$, $|d_0| < d_0^{\max}$, $|z_0| < z_0^{\max}$
 - Geometric constraints: ensure helix is consistent with strip endpoints
 - Example: if $(|z_0| > z_0^{\max})$ $\chi^2 = \chi^2 + (|z_0| - z_0^{\max})^2 / \sigma^2(z_0)$
- ◆ Reject seeds that fail the χ^2 cut
 - χ^2 cut is applied to the sum of the fit χ^2 and the constraint χ^2



Helix Fitting with only Strip Hits

- ◆ Strips are bounded in $z \Rightarrow$ for 2 or more strip layers there are constraints on the helix parameters z_0 and $\tan\lambda$
 - Results in a polygonal allowed region in $z_0 - \tan\lambda$ parameter space
 - “Fit parameters” are taken from centroid of allowed region
 - Covariance matrix calculated assuming all points in allowed region of parameter space are equally probable





Track Fitting

- ◆ Reconstructed tracks are saved into the event with helix parameters and covariance matrices obtained from the fast helix fitter
- ◆ These fits are not true helix fits
 - Separate circle / line fits instead of a true helix fit
 - Multiple scattering correlations not included
- ◆ Two track fitting approaches have been pursued in SiD
 - Kalman filter track fitter
 - Weight matrix track fitter
- ◆ Additional work is required before we can perform true helix fits on the reconstructed tracks
- ◆ Goal is to have at least one helix fitter running by the time the LOI is submitted



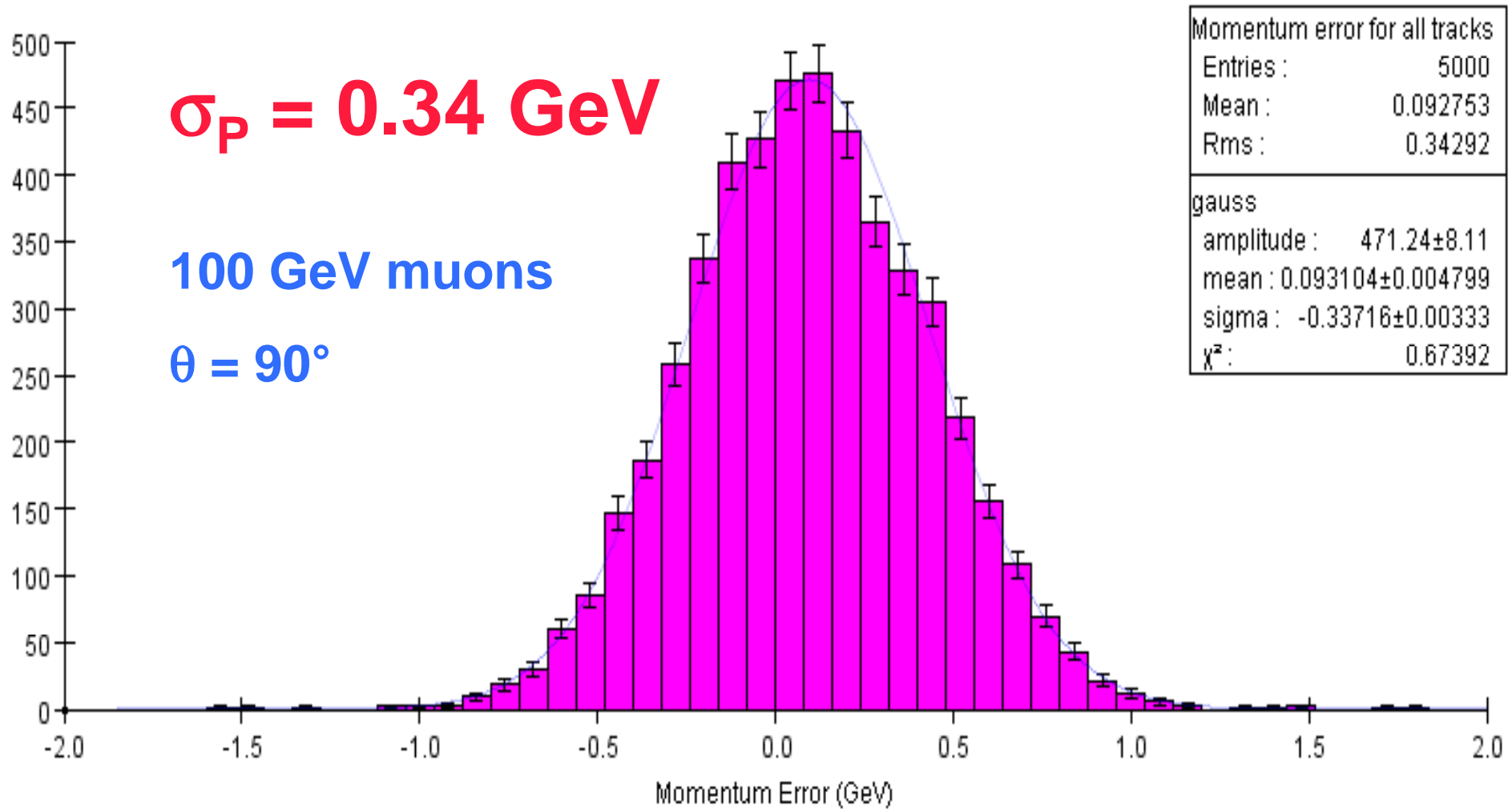
Tracking Resolution Study

- ◆ Tracker resolution has been studied using samples of single muons at various momenta and angles
- ◆ Resolution measured by comparing the measured track parameters with the MC parameters for the muon
- ◆ Some caveats on these results:
 - Results are from fast fitter used in track finding – not a true helix fitter
 - Expect that these are “worst case” results



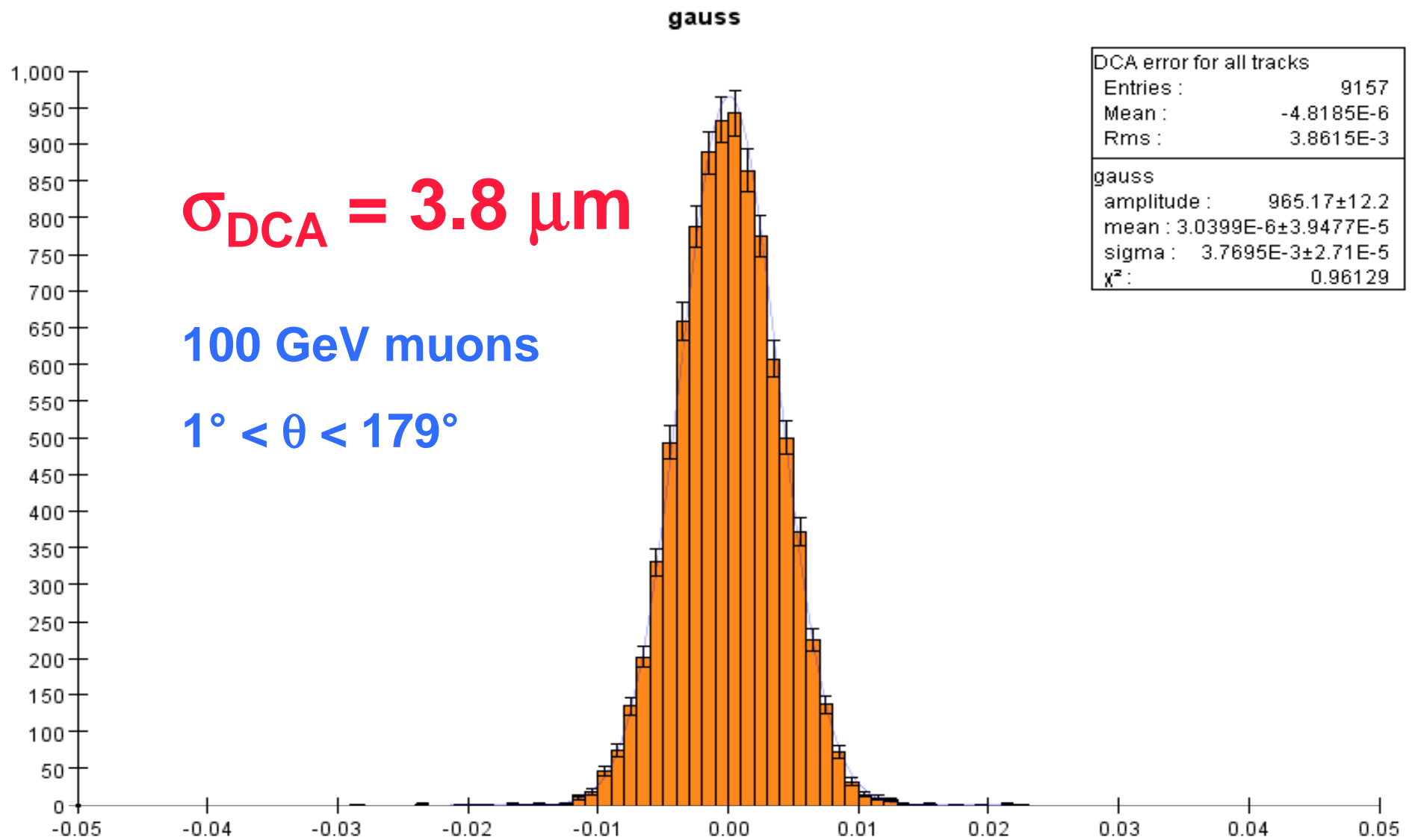
Momentum Resolution

Reconstructed Momentum - Generated Momentum



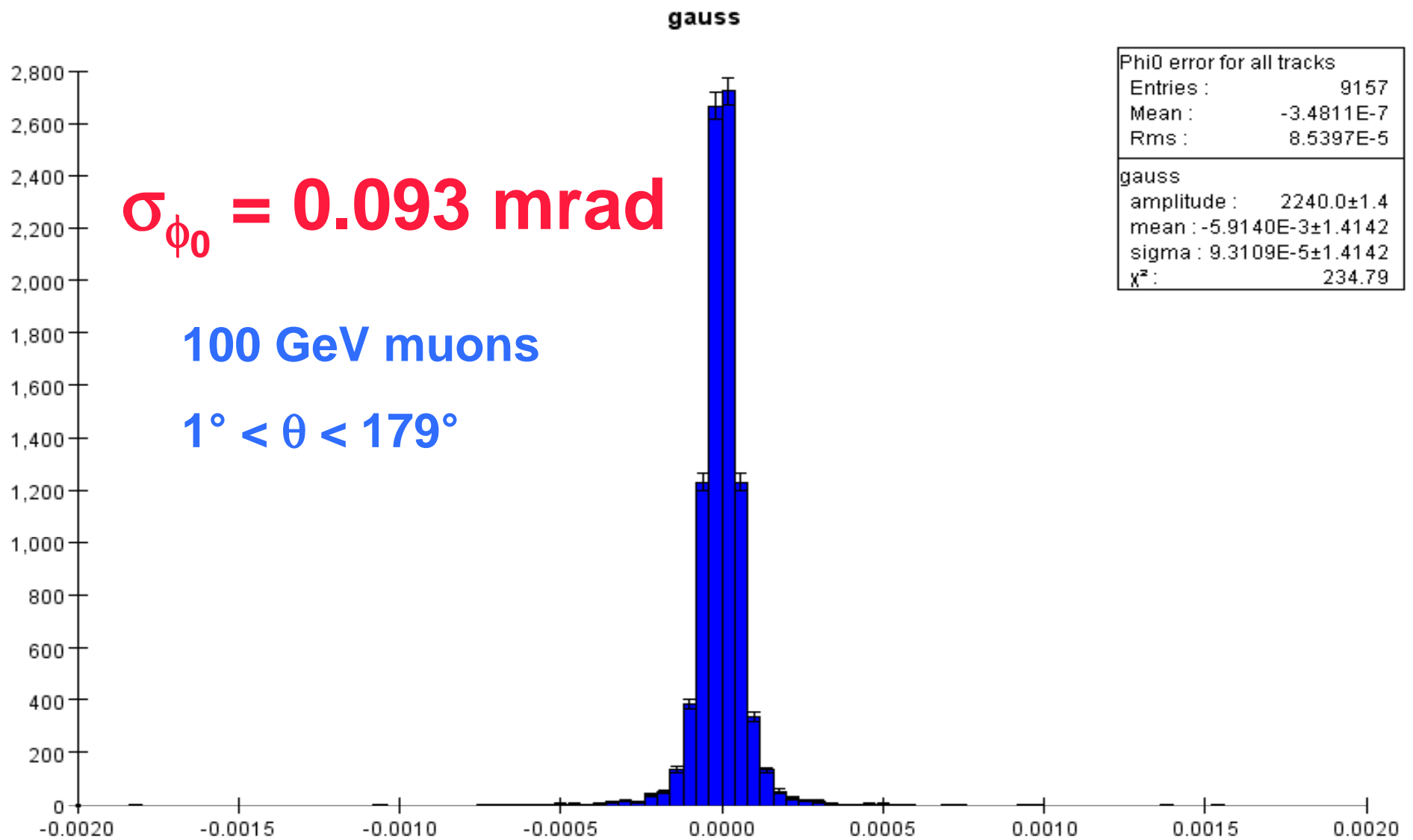


DCA Resolution



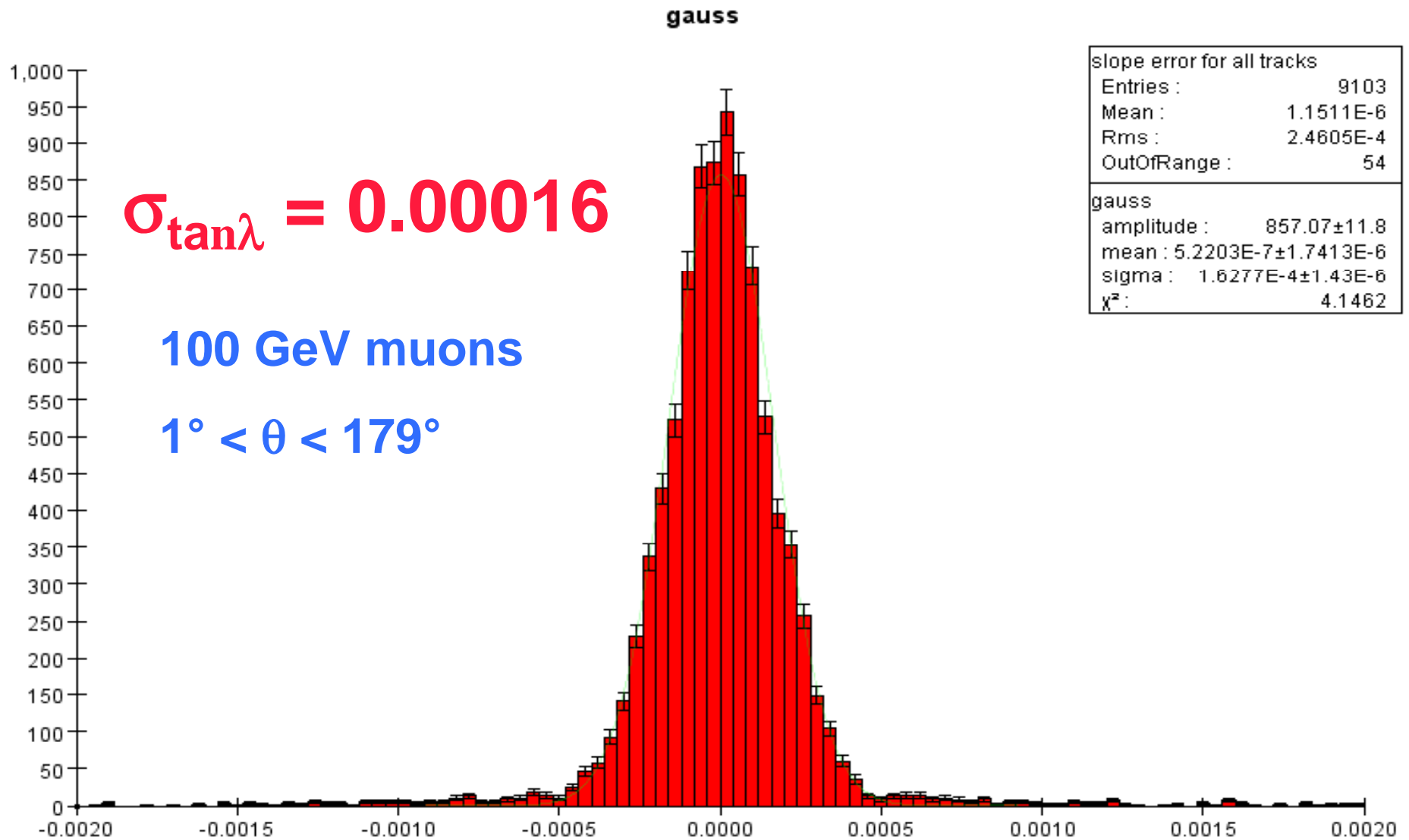


ϕ_0 Resolution



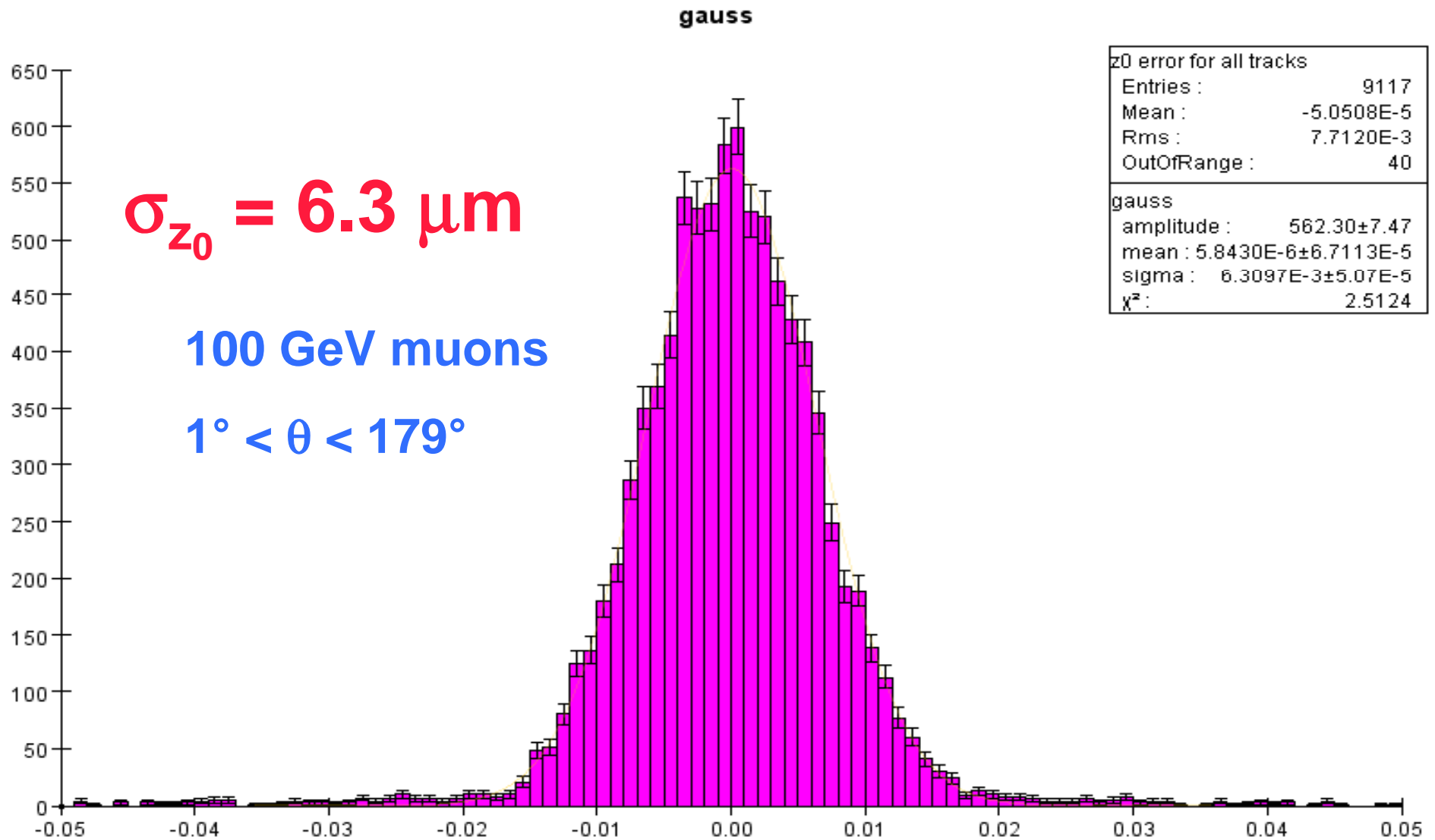


$\tan(\lambda)$ Resolution





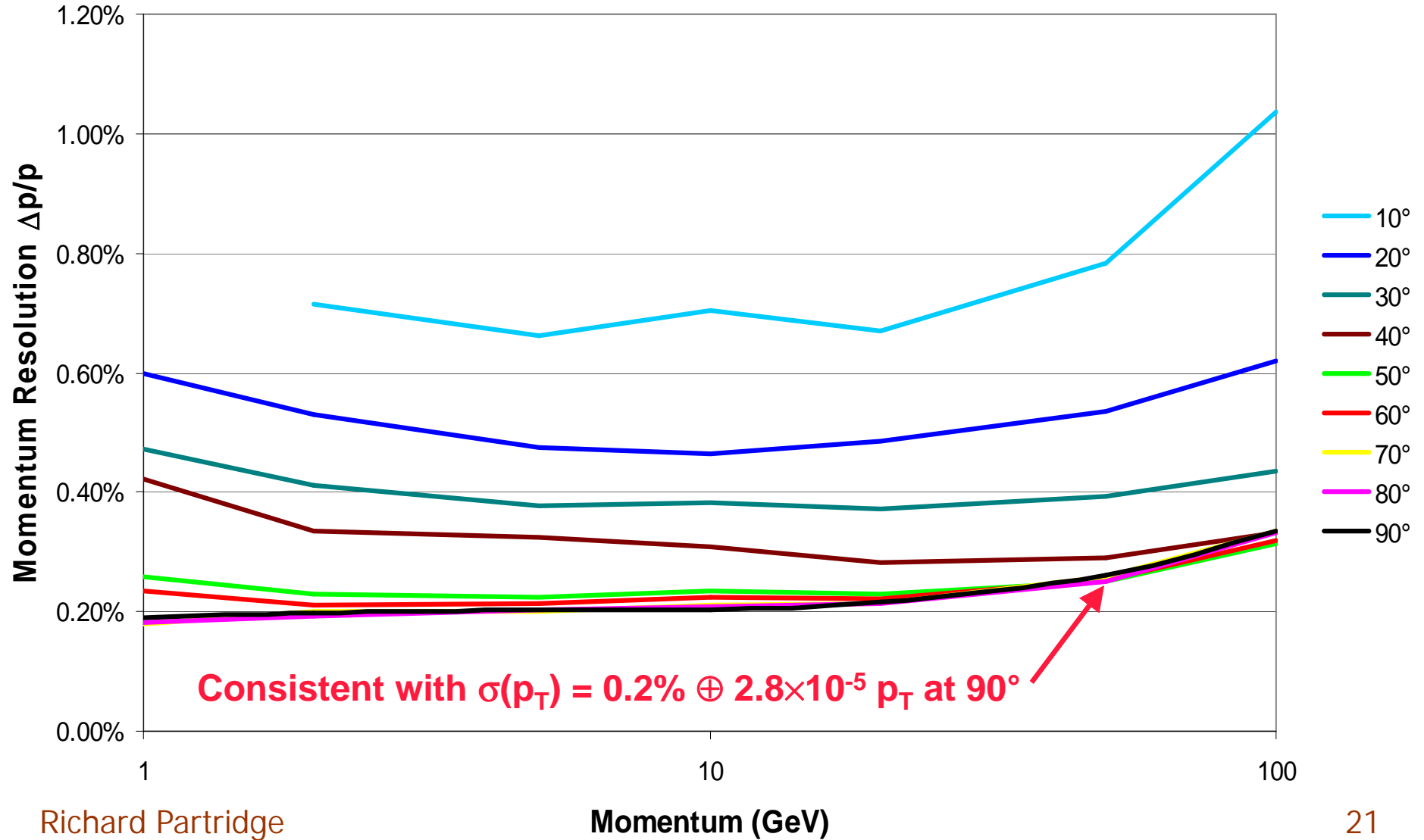
z_0 Resolution





Momentum Resolution

◆ Good momentum resolution everywhere!

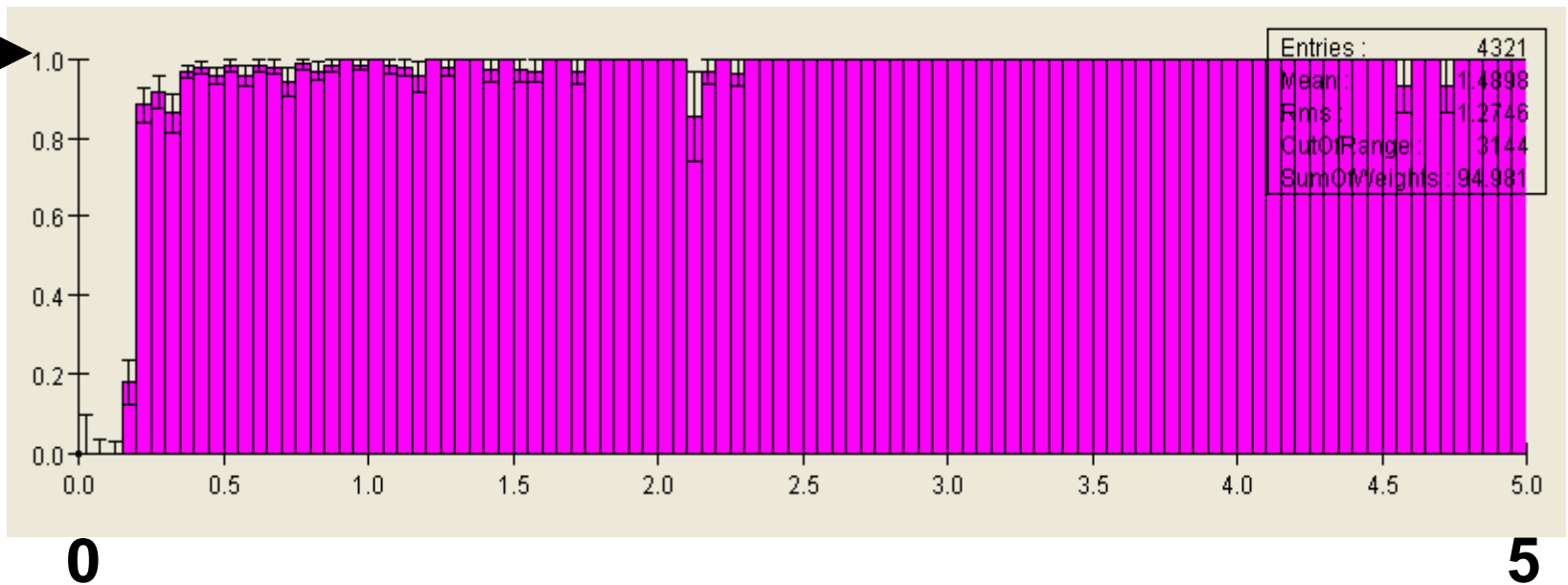




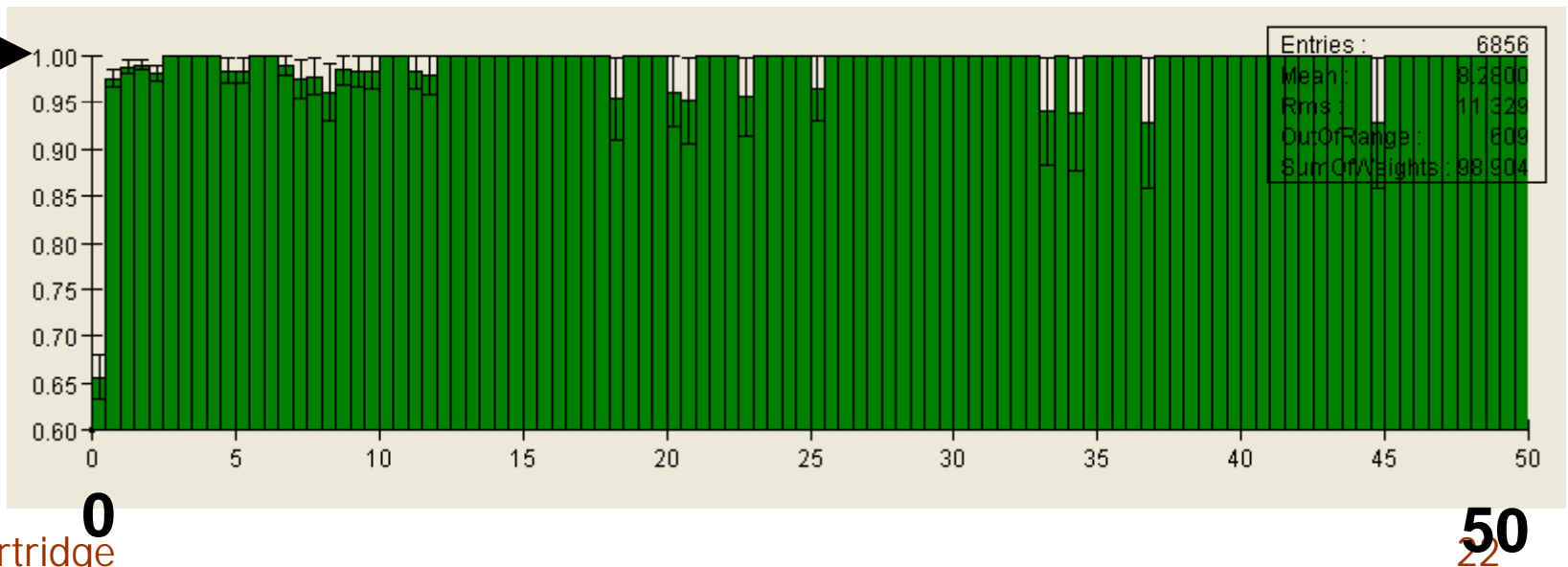
Efficiency vs p_T for 6-Jet $t\bar{t}$ Events

100% →

Efficiency
for tracks
satisfying 1
cm IP cut



100% →

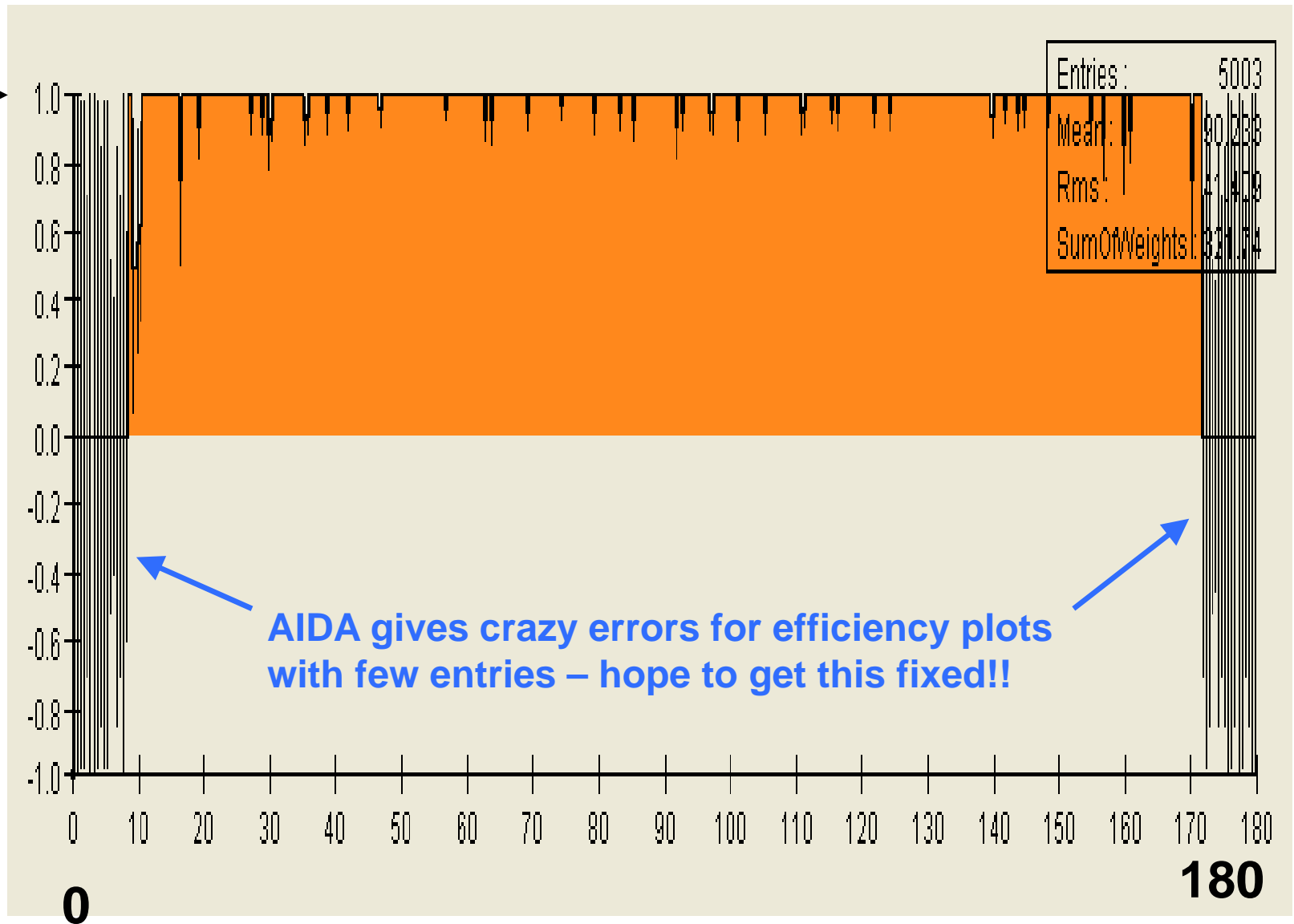




Efficiency vs θ for 6-Jet $t\bar{t}$ Events

100% →

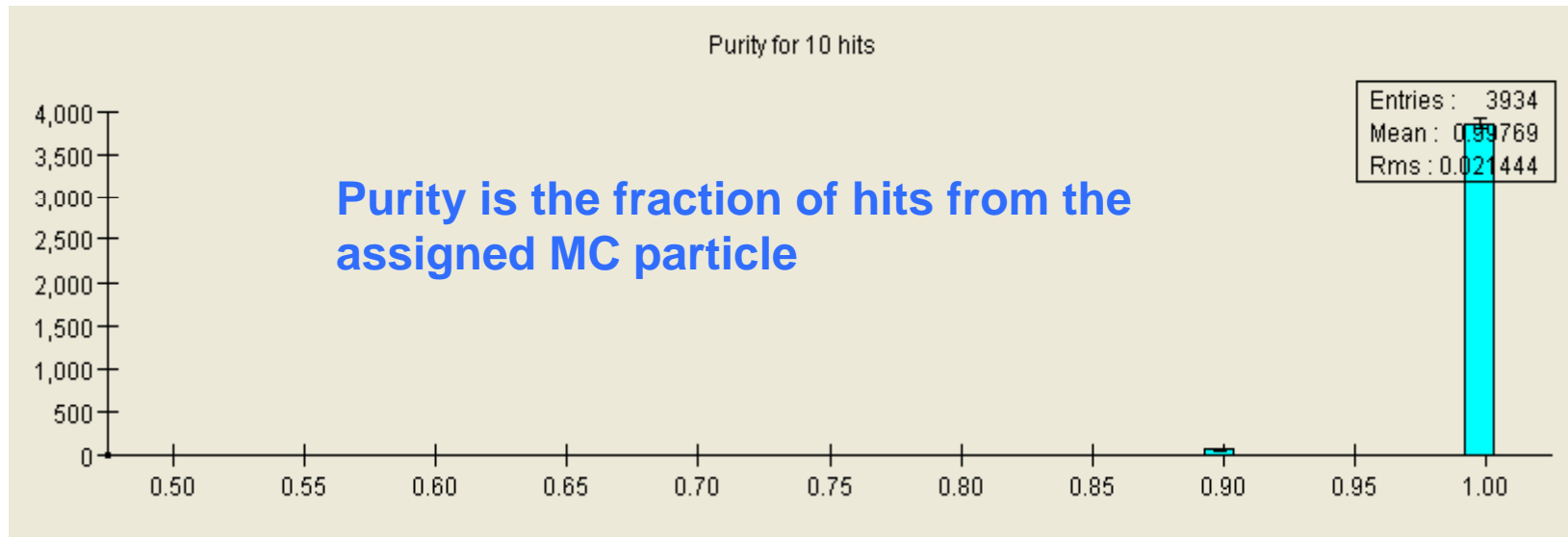
Efficiency
for tracks
satisfying 1
cm IP cut



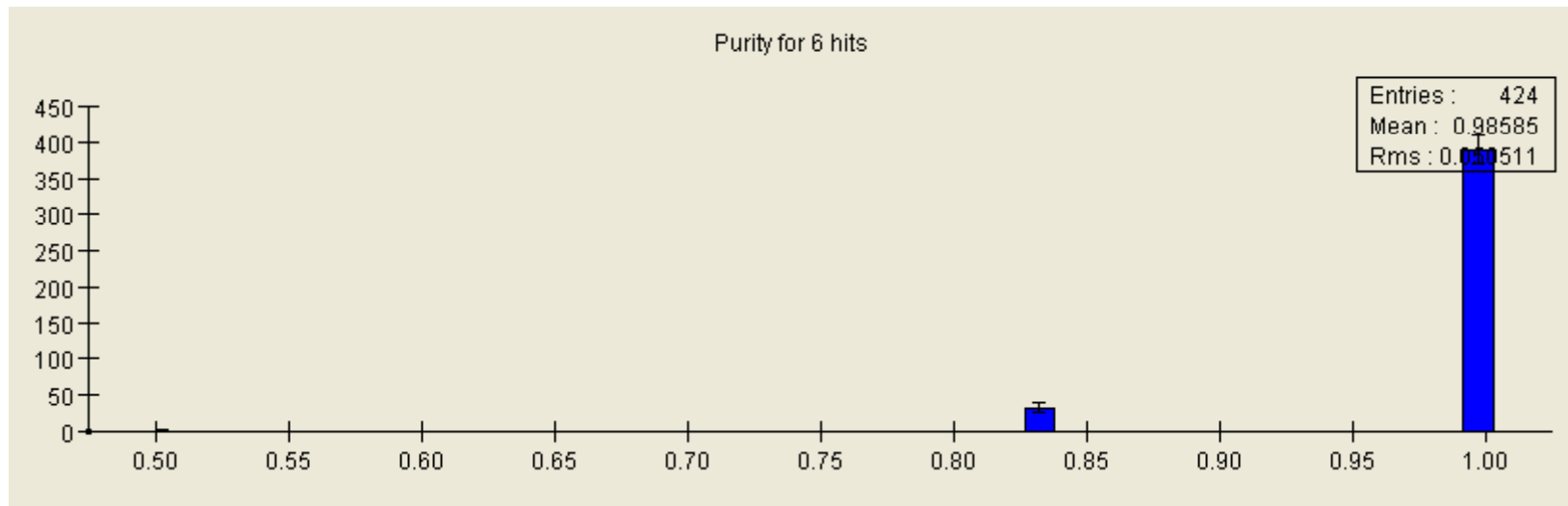


Purity for for 6-Jet $t\bar{t}$ Events

10 Hit Tracks



6 Hit Tracks





Summary

- ◆ SiD has developed a new track reconstruction code in the org.lcsim framework with a number of innovative features
 - Algorithm expressly developed for silicon tracker design studies
 - New (?) algorithm for performing full helix fit for set of axial hits
 - 3D stereo hit positions / covariance matrix calculated including dependence on track angle and helix uncertainties (new?)
 - All decision based on χ^2 cut – no internal tuning parameters
 - User controls track finding controlled through xml strategy file
 - Strategy builder automates generation of strategies
- ◆ Code has been used to characterize SiD tracker performance
 - Outstanding resolution over full solid angle
 - Full coverage with high efficiency for findable tracks
 - Tracks have high purity with very small fake rate