DOOCS framework for CALICE DAQ software

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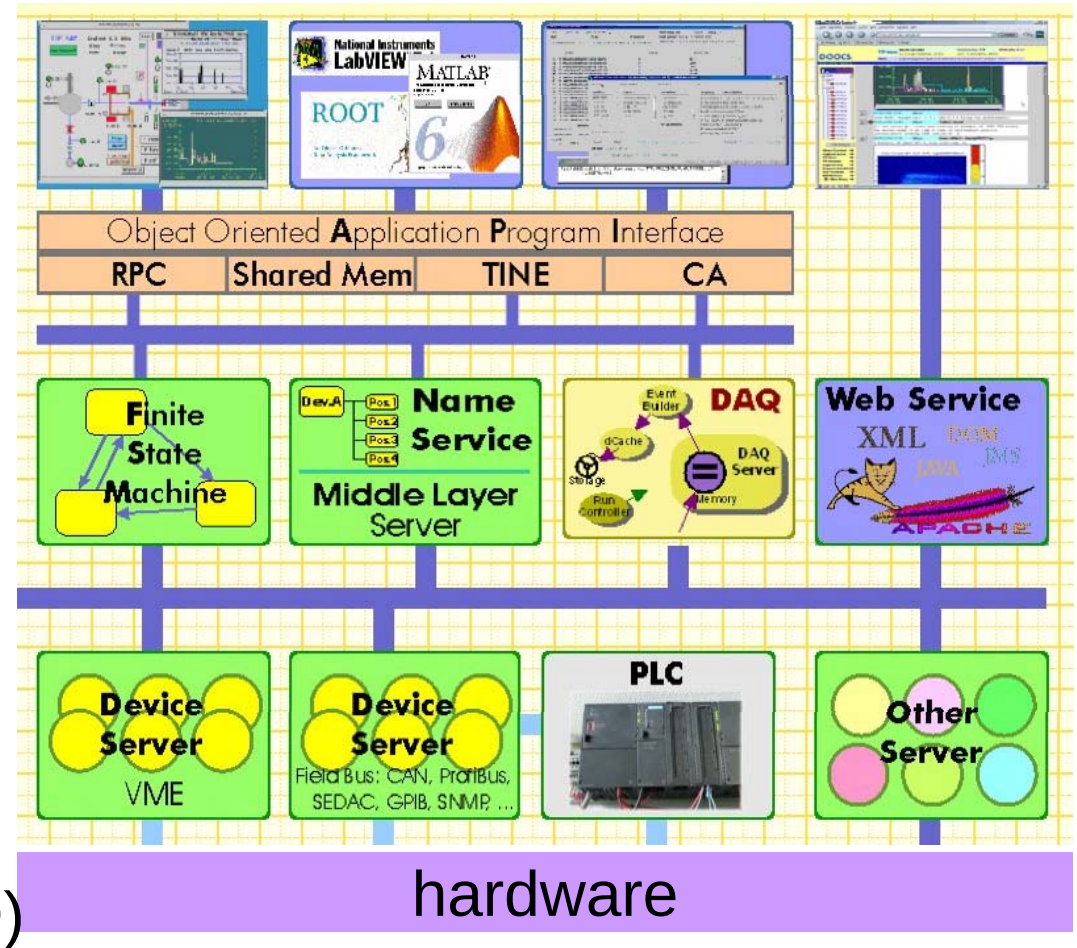
DOOCS overview

- 3 layers
- common APIs
- modular design
- multi protocol (RPC, TINE, EPICS, shared memory)
- device level (~200 server types)
- middle layer (FSM, FB, DAQ)



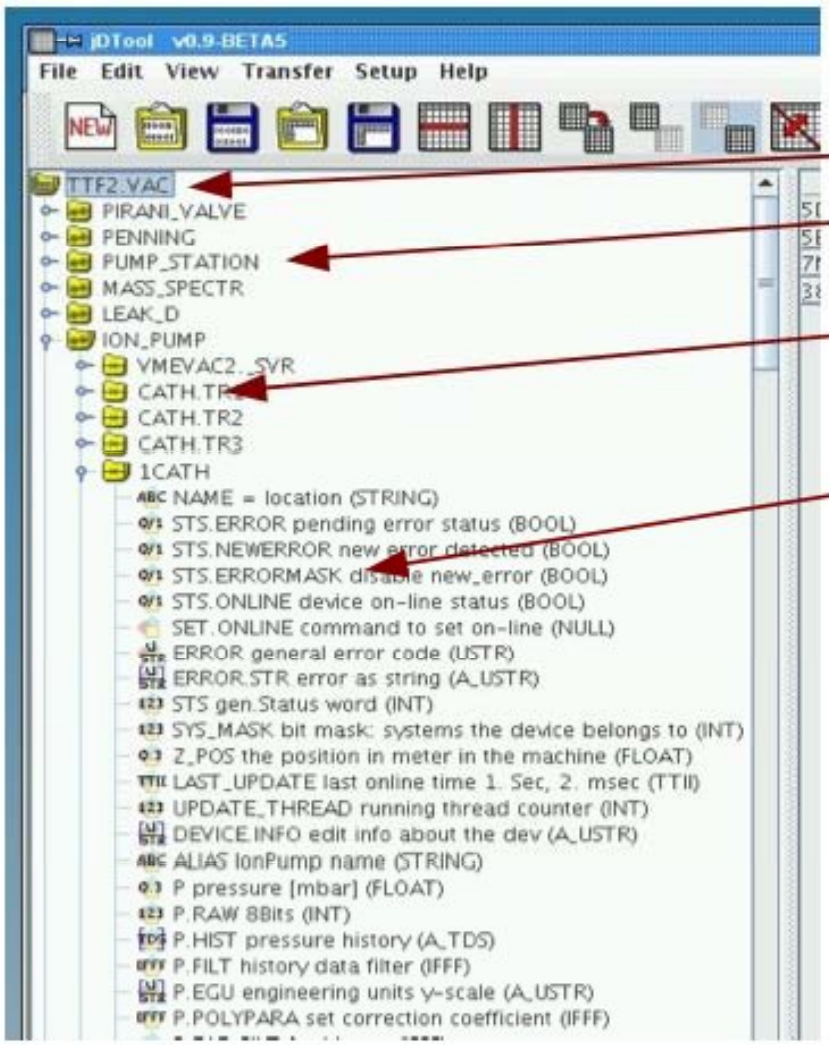
User Interface

Program Interface

Middle Layer

Hardware interface

ENS naming service



FACILITY == Accelerator

DEVICE == Type of a device

LOCATION == position inside the accelerator

PROPERTY == list of properties

Example:
CALICE.ECAL/ODR/ODR1/STATUS

ENS naming service: proposal for CALICE

Our proposal for the naming service:

FACILITY:	CALICE.ECAL, CALICE.AHCAL,
	CALICE.DHCAL
DEVICE:	ODR, LDA, DIF, ASIC1, ASIC2, ASIC3
LOCATION:	ODR1, ODR2, ODRX
	LDA1, LDA2, LDAX
	DIF1, DIF2, DIFX
PROPERTY:	????

$\Rightarrow$ need to get input from hardware colleagues about properties of the devices

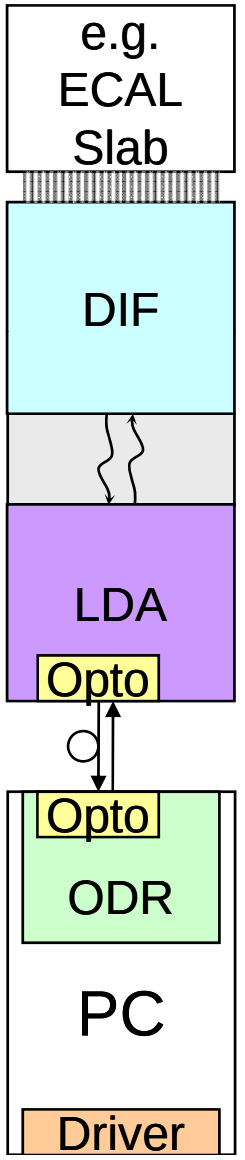
ENS naming service: hierachical DAQ system

- send data to DIF by wrapper through ODR and LDA (have switch to configure debugging modes which go directly to the LDA or DIF)
- ENS naming service can signal connections by additional properties, e.g. for device DIF:

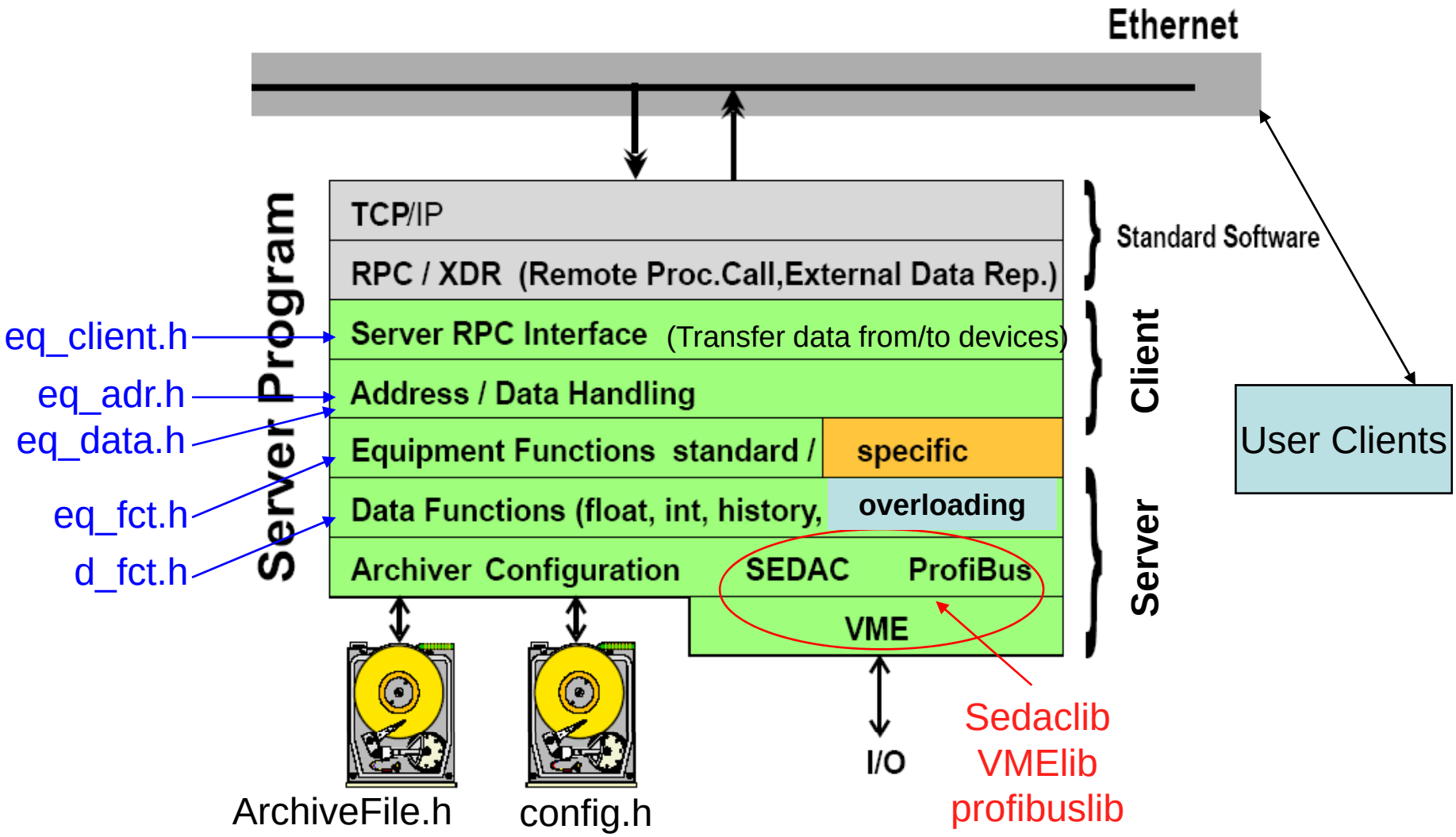
CALICE.ECAL/DIF/DIF1/ODR_CON

CALICE.ECAL/DIF/DIF1/LDA_CON

CALICE.ECAL/DIF/DIF1/DEBUG_MODE



Device Servers



Device Servers for CALICE

- servers will update/poll information every few seconds (property can be set in configuration)
$\Rightarrow$ can be used for monitoring & data taking

- data functions can be overloaded to set registers in hardware and to get registers
$\Rightarrow$ can be used for configuration & getting values which are typically not monitored (do not use it to read out too many values, because it directly accesses the memory)

- interfaces to hardware need to be communicated to and discussed with DAQ software group

Possible functions for ODR

```
class ODRCard  {
   ODRCard();
   virtual ~ODRCard();
   virtual void InitODR ();
   virtual void MappingODR();
   virtual void UnMappingODR();
   virtual void ReadODR();
   virtual void WriteODR();
   virtual void ODRIOCTL();
   virtual void ODRStatus();
   virtual void ODRCMD();
   virtual void ODRMonitor();
   virtual void ODRSetLocalVal();
   virtual void ODRReadLocalVal();
   virtual void GetLiveList();
}
// with arguments for each…
```

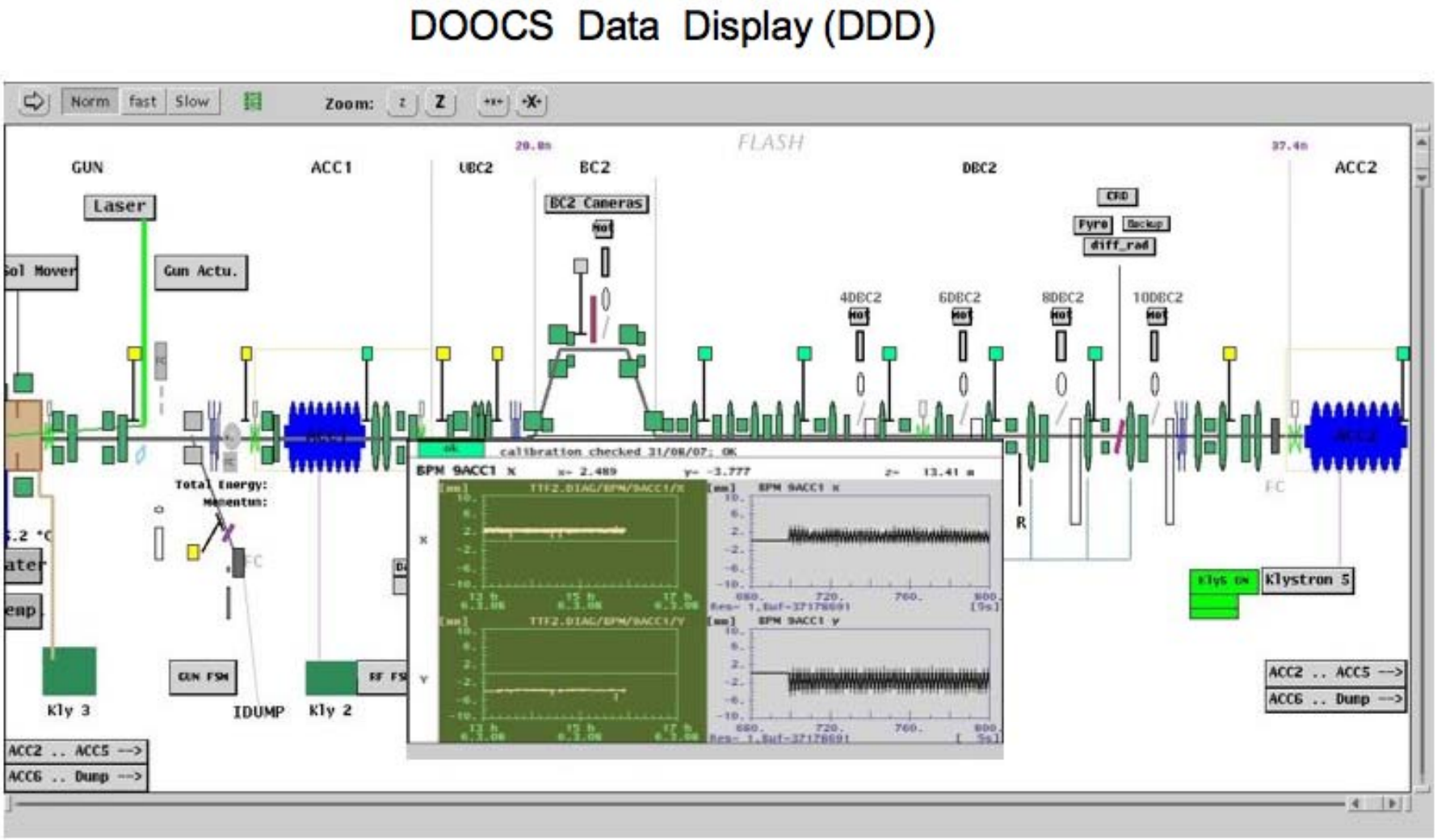
open (“/dev/odr3”, O_RDWR);

Initialize some parameters, and Mapping ODR device involved, ioctl(… , INIT); etc.

Possible Properties for ODR

// Intrinsic Properties
Channels 1010 // Channel activation/selection
Mode Send // Send or Receive mode
ExtractWord ID // Selected Word can be extracted from data
Debug 0 // 0 or 1 for debugging
DataGen 0 // 0 or 1 for external data generator
DataBuf 10 // number of data buffers
EventGroup ??? // grouping of events

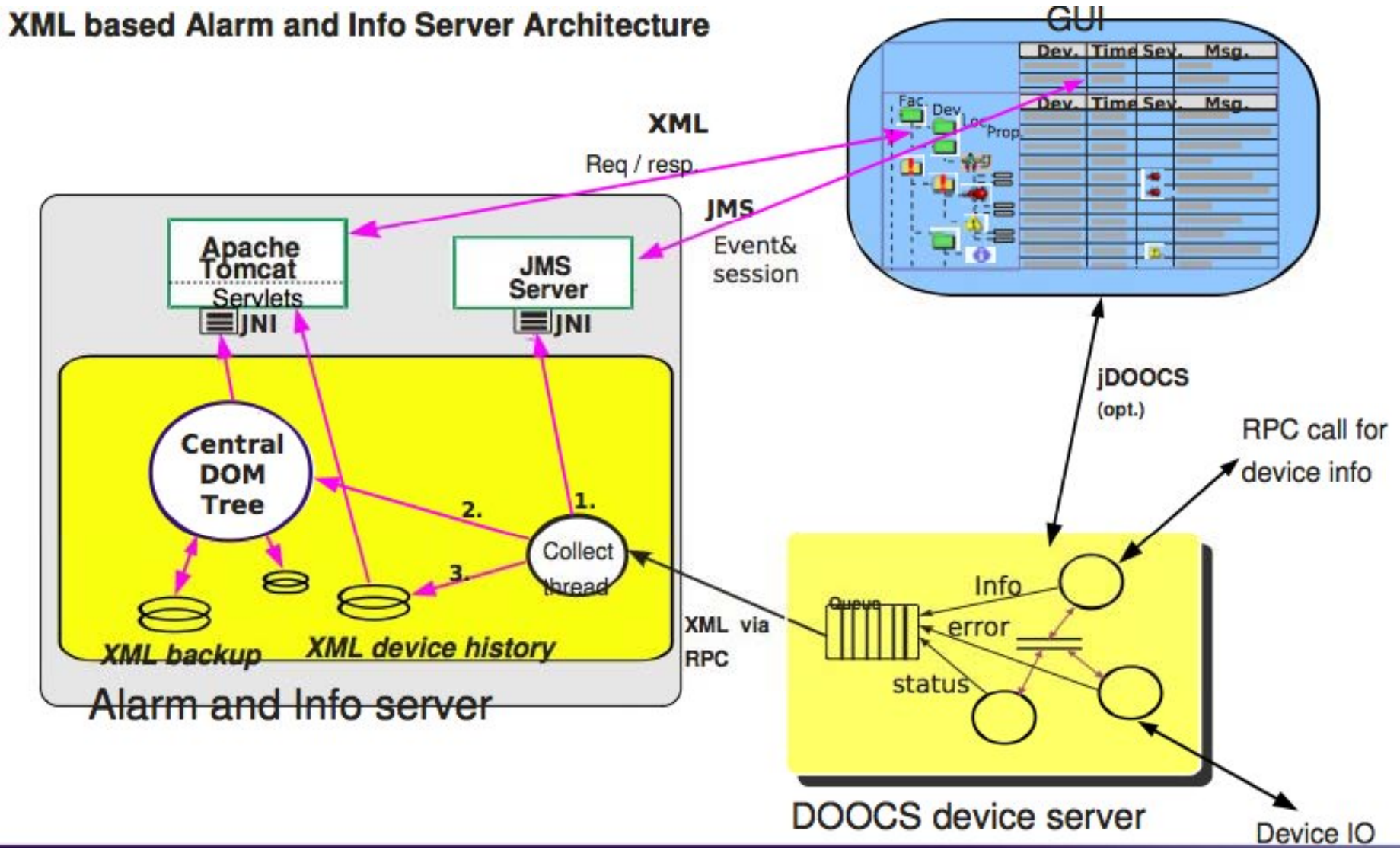
Example of monitoring GUI



Example of monitoring GUI

- monitoring can be drawn by special program
- easy to use, can be even handed to shifters
- many nice features:
    - click to get to histos,
    - display of broken links, etc.
- for CALICE application nothing done yet, will be added at a later stage

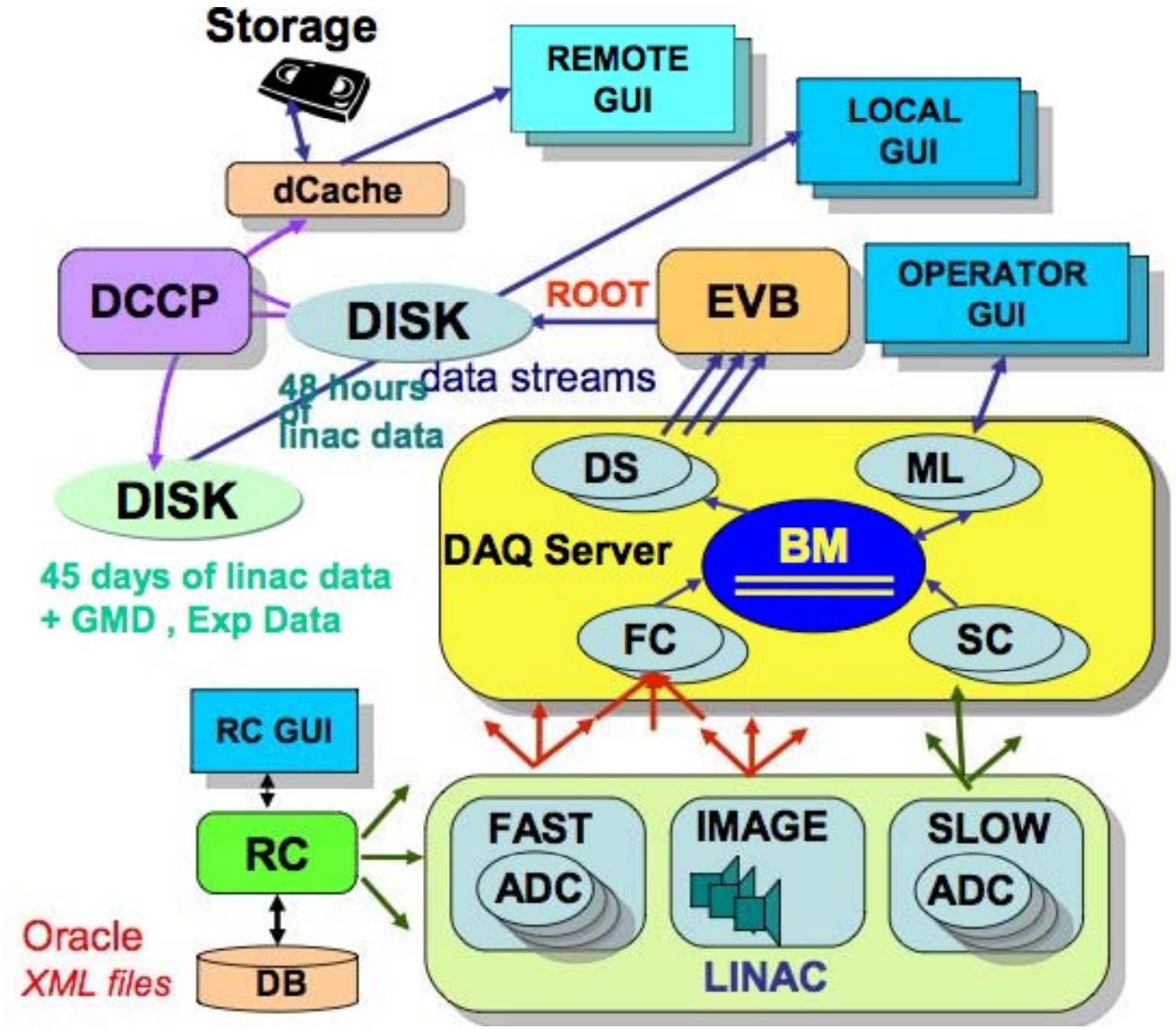
Alarm handling



Alarm handling - CALICE

- implementation of alarm handling within CALICE application will be added at a more mature state of the software
- however configuration considers alarm handling already at this stage

DAQ software



FC/SC:
Fast/Slow
Collector

BM:
Buffer Manager

EVB:
Event Builder

Example with dummy data has been successfully tested

Conclusion & Outlook

- how to apply DOOCS for the CALICE technical prototype is well understood
- the basic design for the CALICE application is ready
- interface to the hardware is the starting point of the implementation of the CALICE project within DOOCS

$\Rightarrow$ next step is to get feedback from the hardware guys to build the hardware interfaces and settle on the naming conventions