

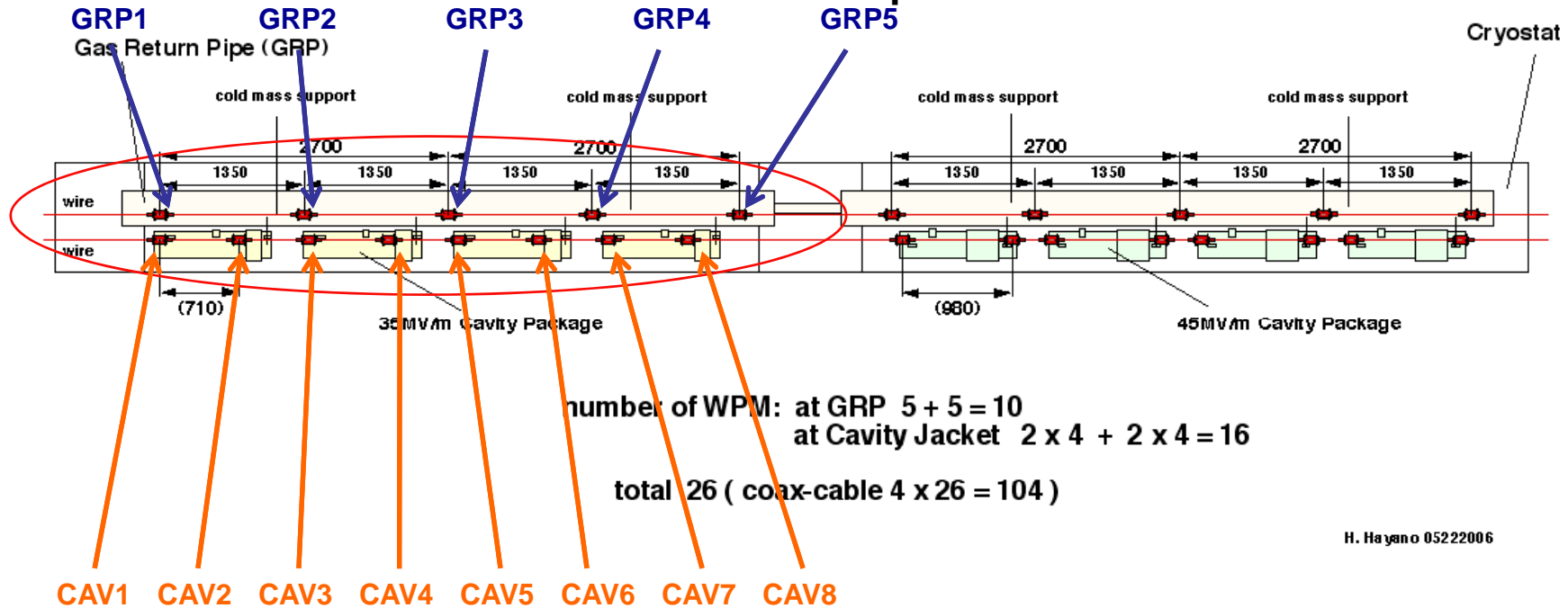
STF

Wire Position Monitor

12.09.2008 H. Hayano

WPM system overall

WPM installation position

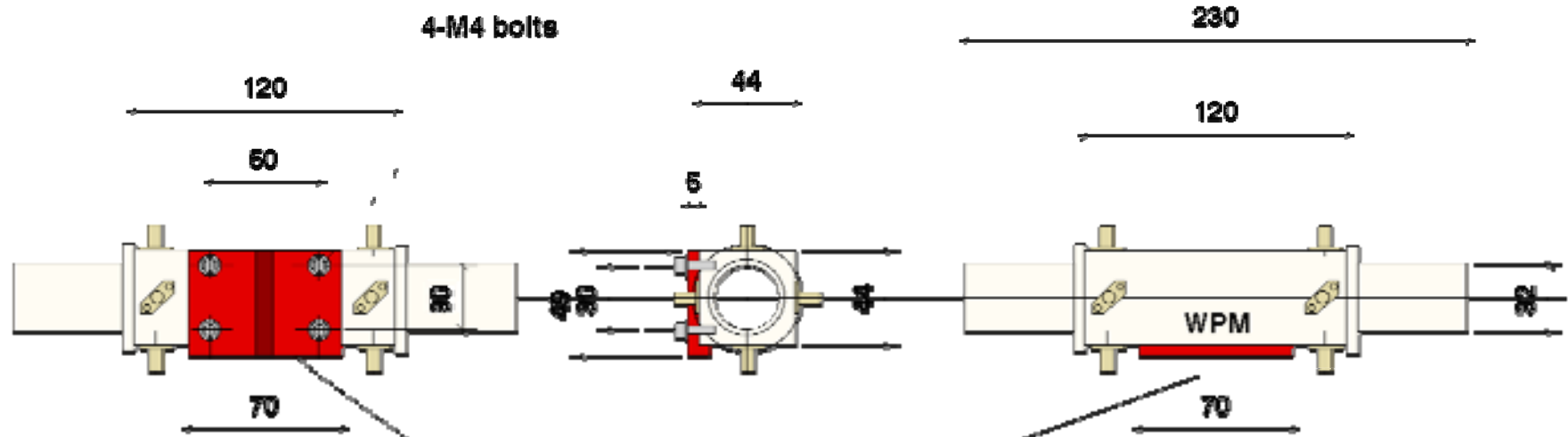


names on the reading software

	Module A		Module A		Module B		Module B
ch1	GRP1	ch9	CAV1	ch17	GRP6	ch25	CAV9
ch2	GRP2	ch10	CAV2	ch18	GRP7	ch26	CAV10
ch3	GRP3	ch11	CAV3	ch19	GRP8	ch27	CAV11
ch4	GRP4	ch12	CAV4	ch20	GRP9	ch28	CAV12
ch5	GRP5	ch13	CAV5	ch21	GRP10	ch29	CAV13
ch6	no connection	ch14	CAV6	ch22	no connection	ch30	CAV14
ch7	no connection	ch15	CAV7	ch23	no connection	ch31	CAV15
ch8	no connection	ch16	CAV8	ch24	no connection	ch32	CAV16

Wire Position Monitor attachment plate Conceptual design

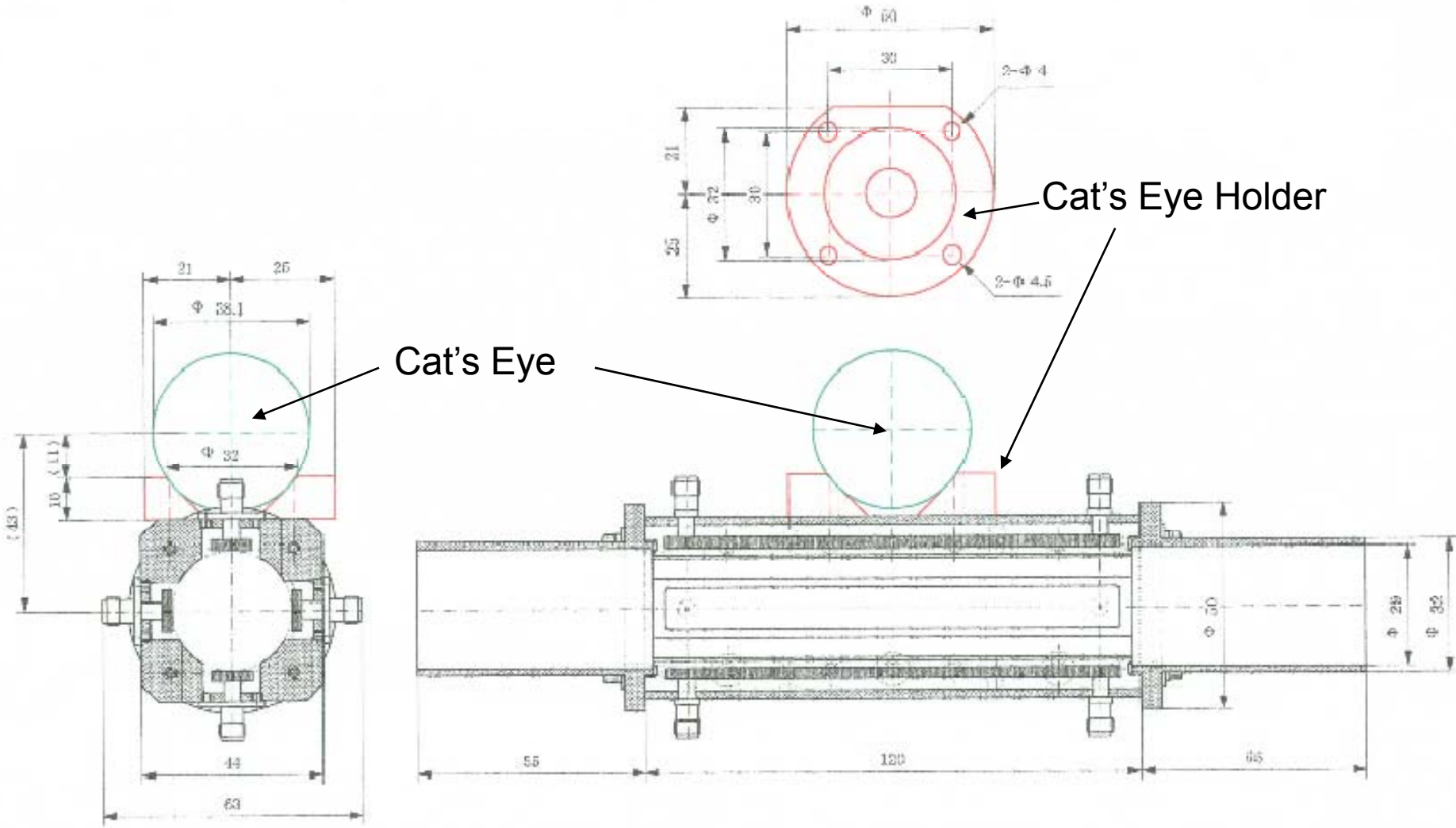
WPM attachment on the holder plate



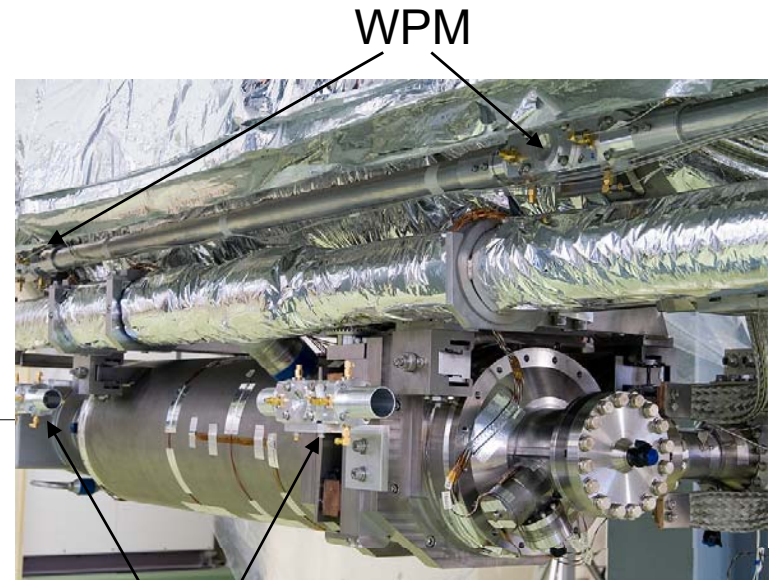
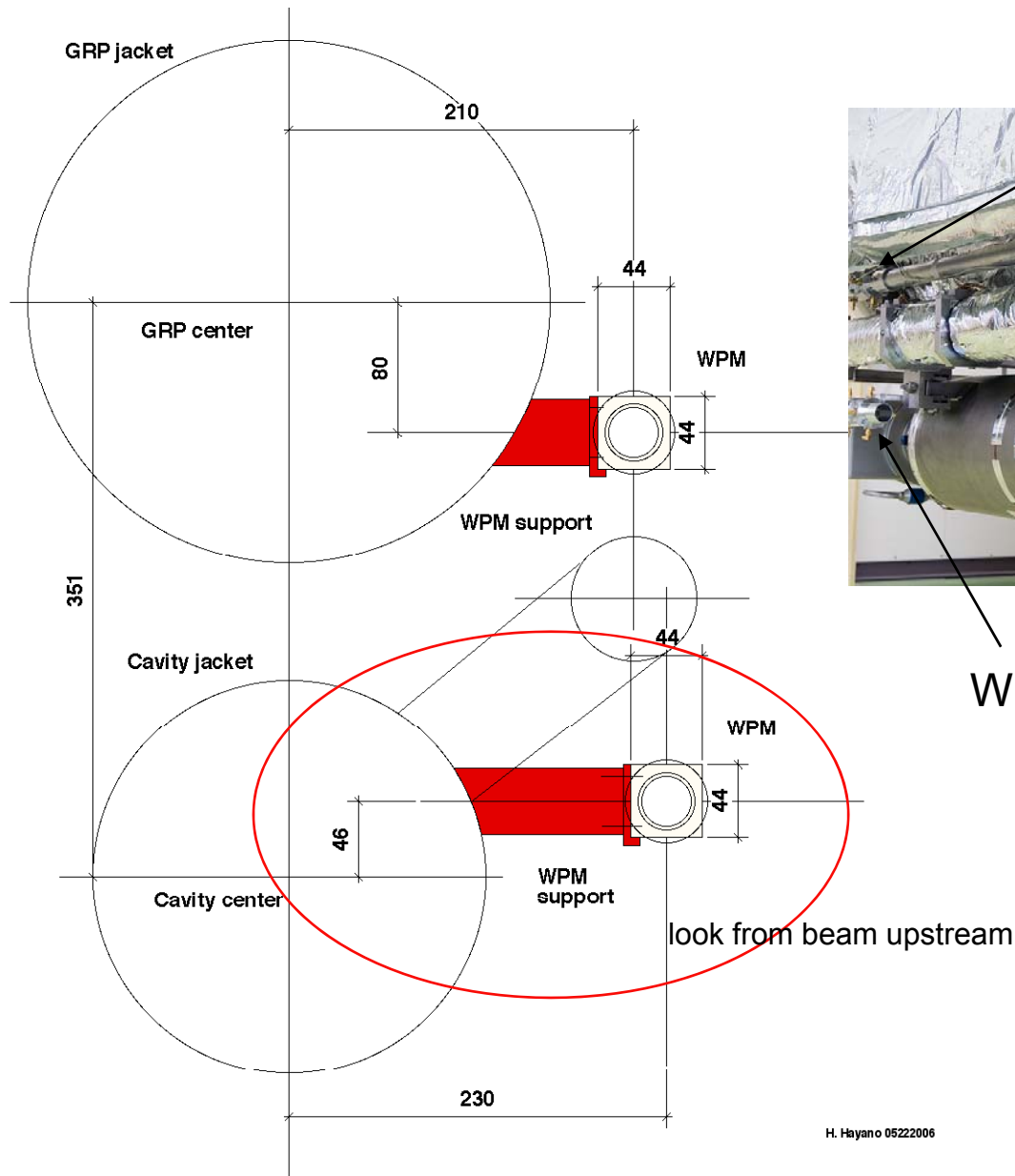
WPM attachment



WPM detector body

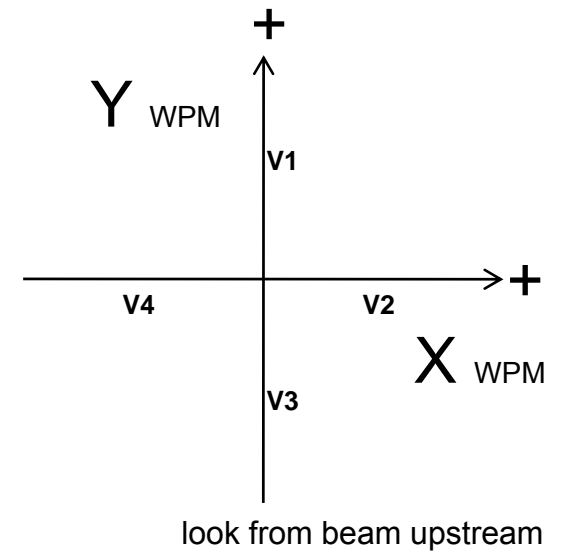


WPM mount and coordinate system

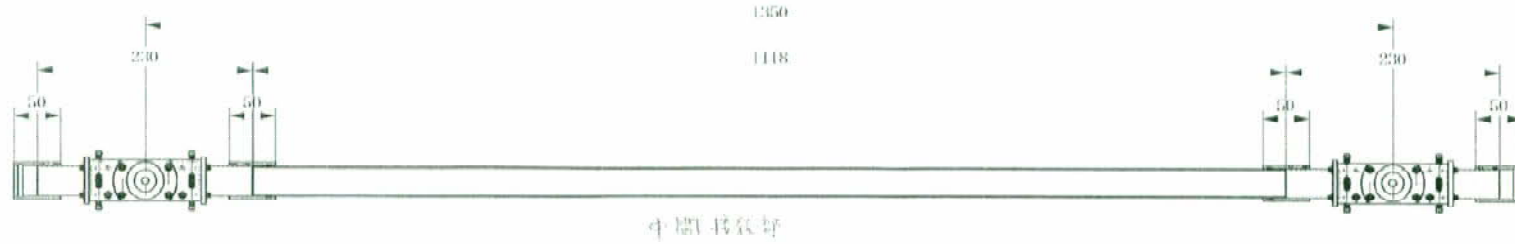


example of TESLA shape cavity

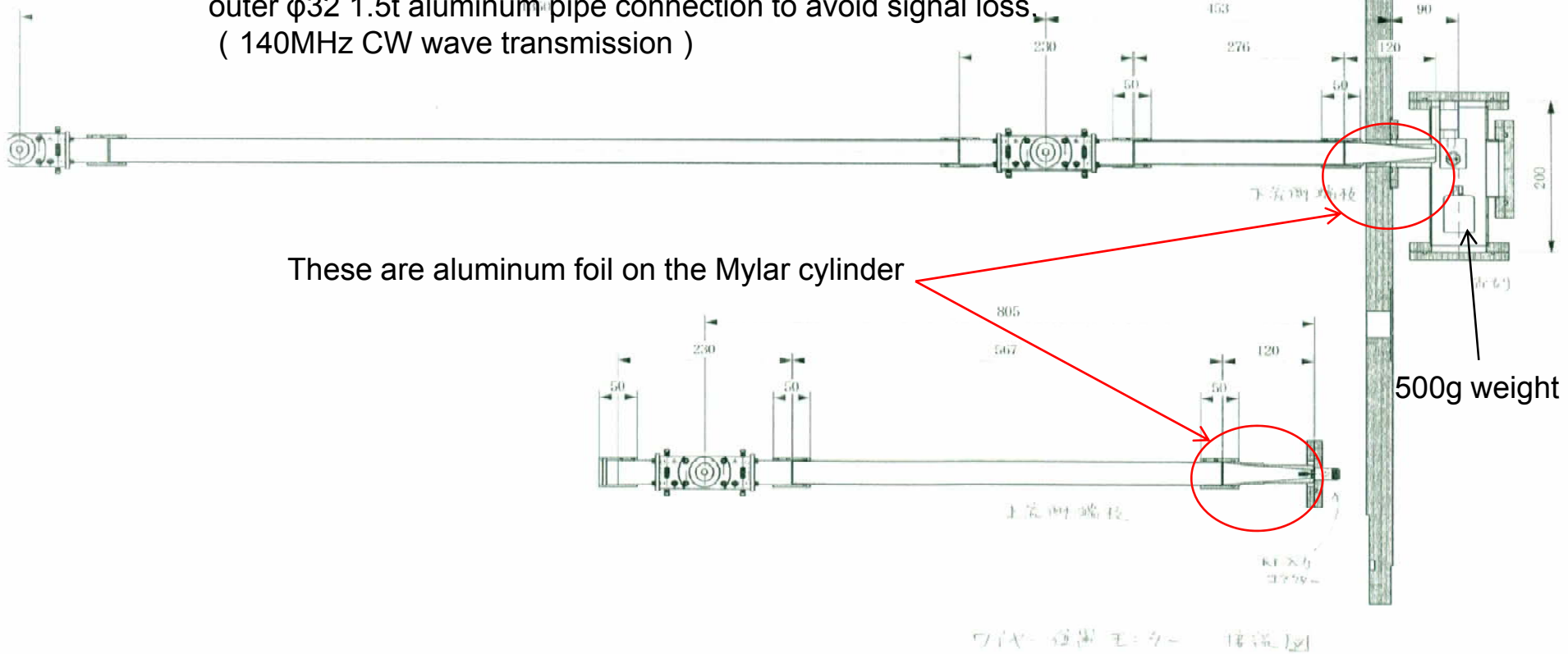
WPM



connection between WPM, and both end of wire



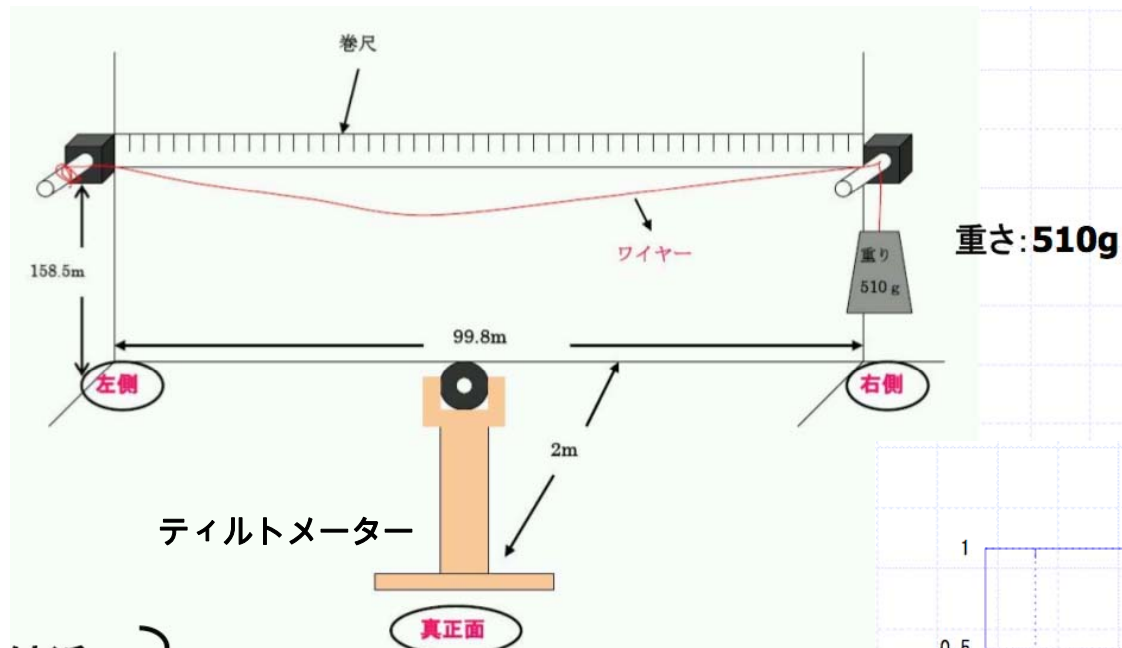
outer $\phi 32$ 1.5t aluminum pipe connection to avoid signal loss
(140MHz CW wave transmission)



These are aluminum foil on the Mylar cylinder

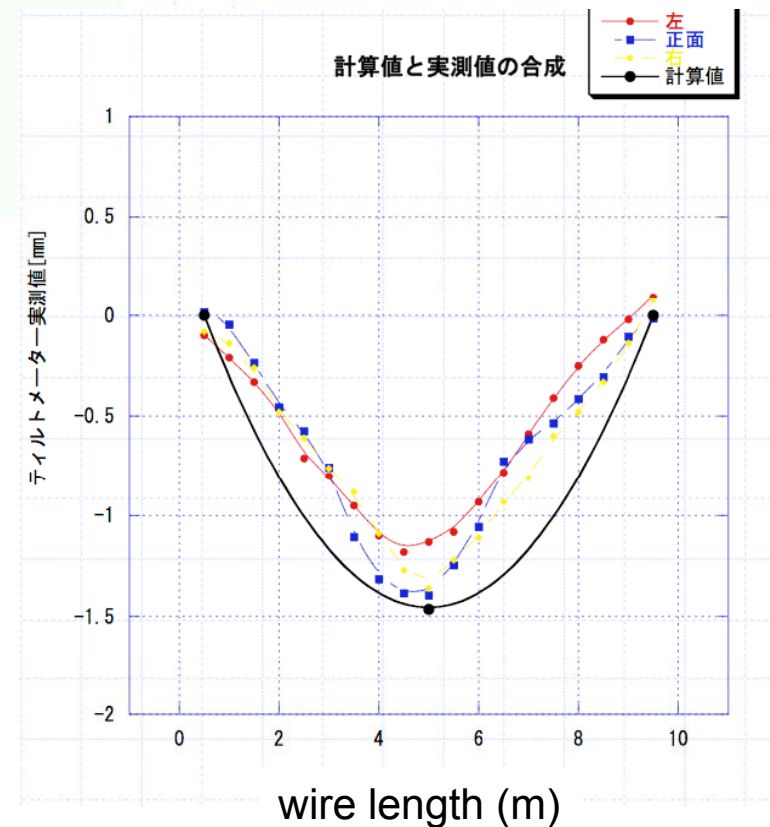


7 μ m diameter Tungsten Wire stretch for 10m

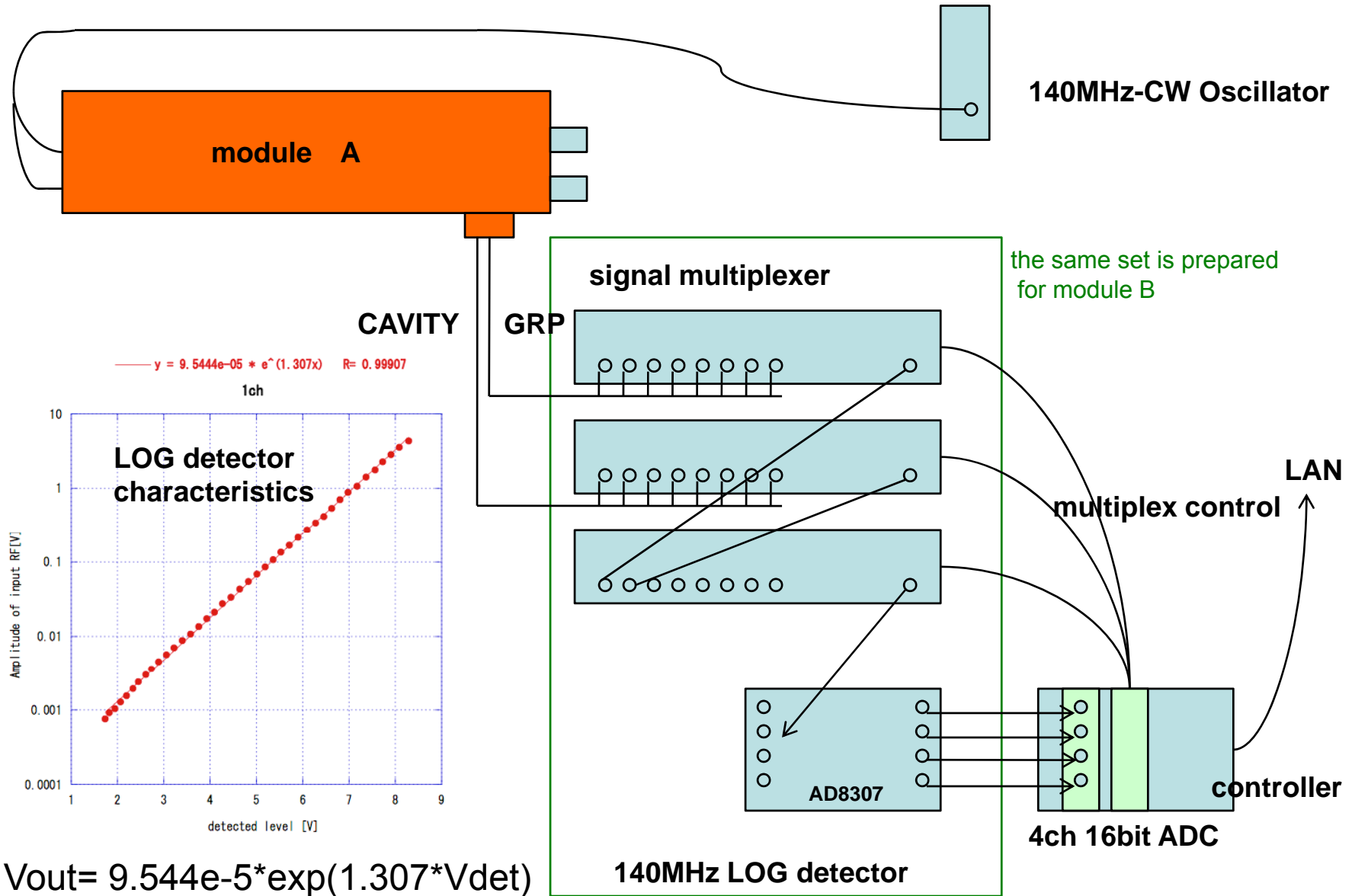


sag was 1.4mm
(estimation was 1.475mm)

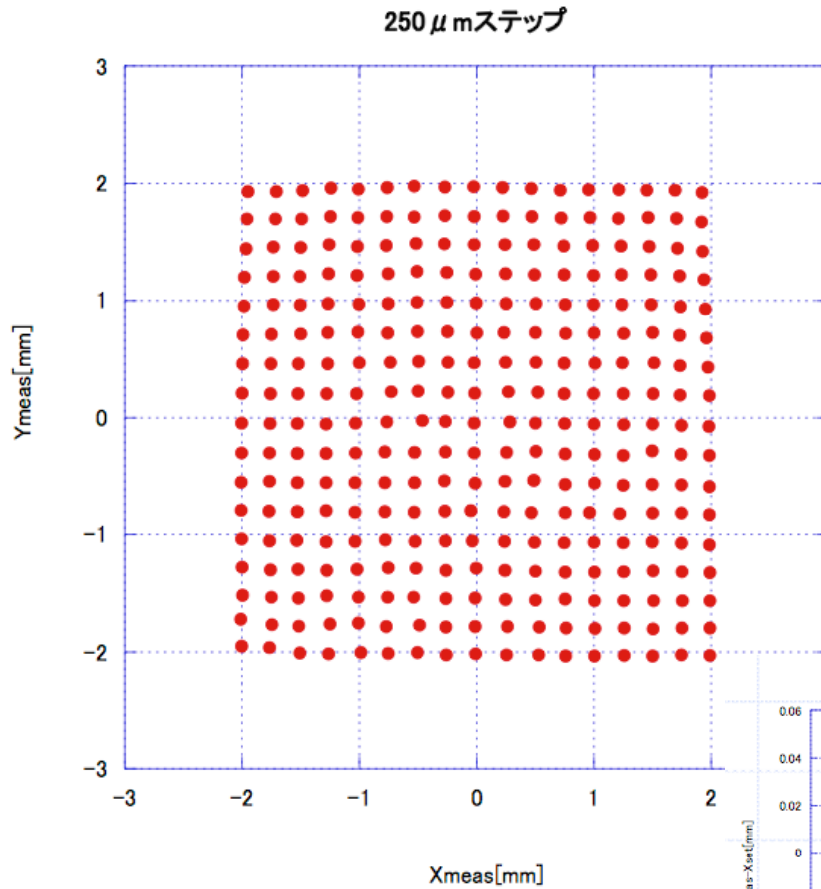
* 36m module \rightarrow 19.1mm sag



Detector circuit



+/- 2mm mapping example



formula :

$$X = k_x * (V_2 - V_4) / (V_2 + V_4)$$

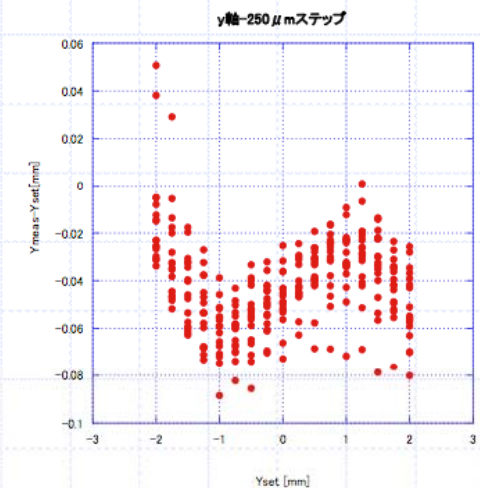
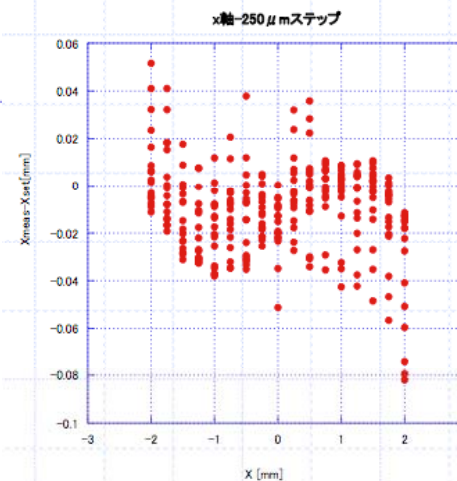
$$Y = k_y * (V_1 - V_3) / (V_1 + V_3)$$

linear approximation

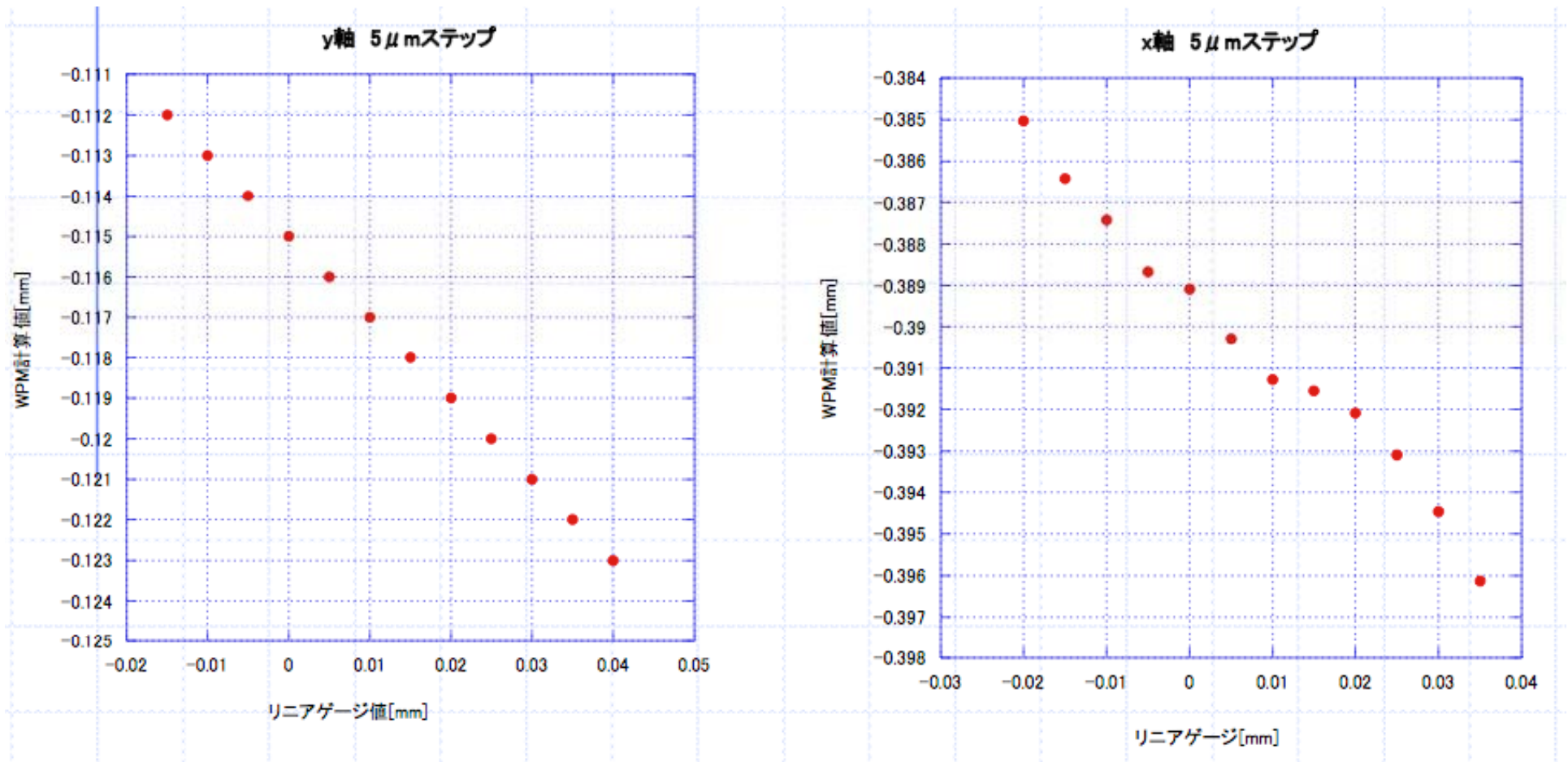
$$K_x = K_y = 7.262 \text{ mm}$$

difference from wire position set value

full width 140 μm error



Resolution in case 5 μ m step wire movement

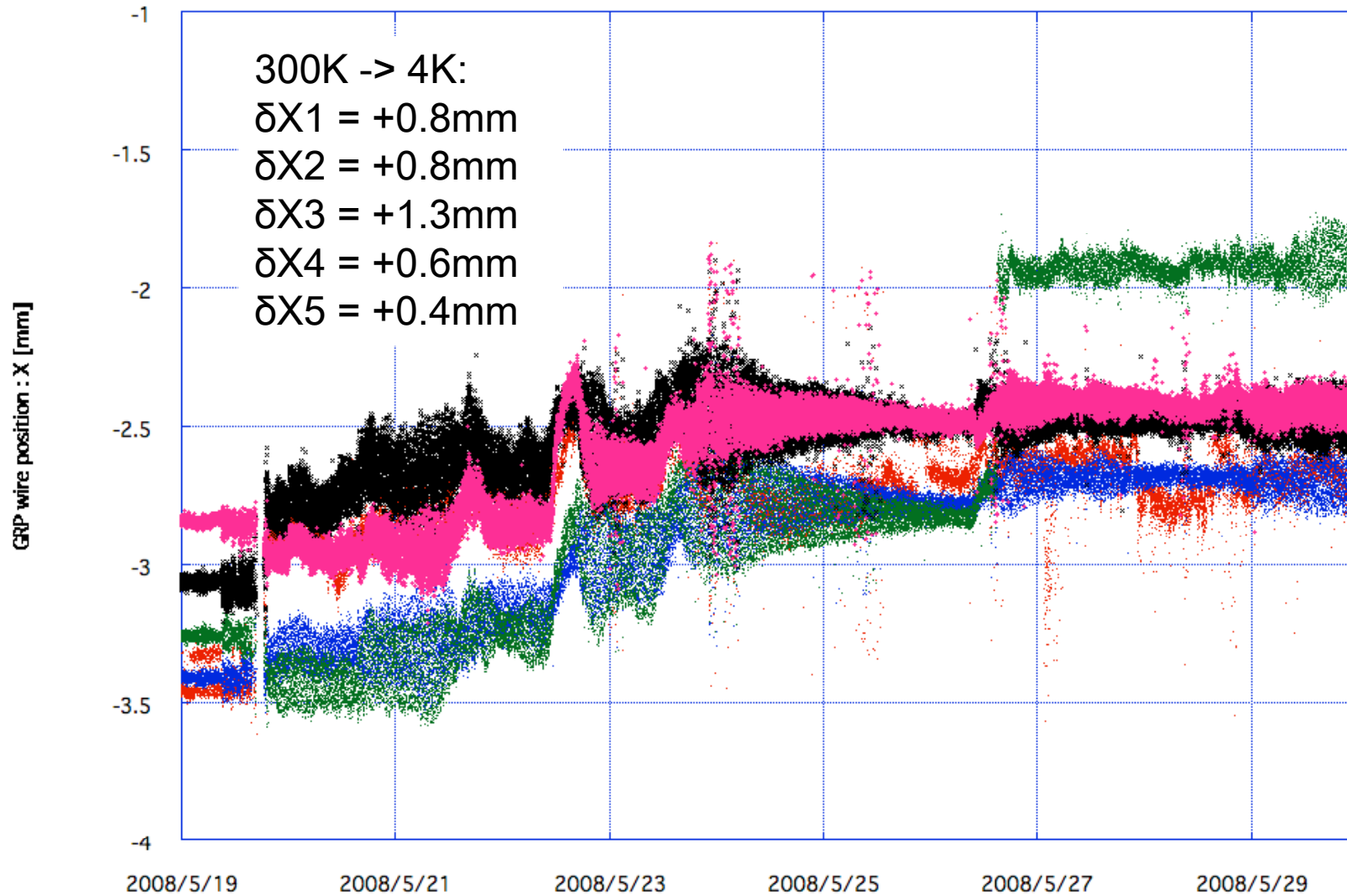


estimated resolution will be less than 5micron

- GRP X1 [mm]
- GRP X2 [mm]
- GRP X3 [mm]
- × GRP X4 [mm]
- GRP X5 [mm]

Detected wire movement for GRP-WPM [X direction]

HH-WPM-V-052008-K



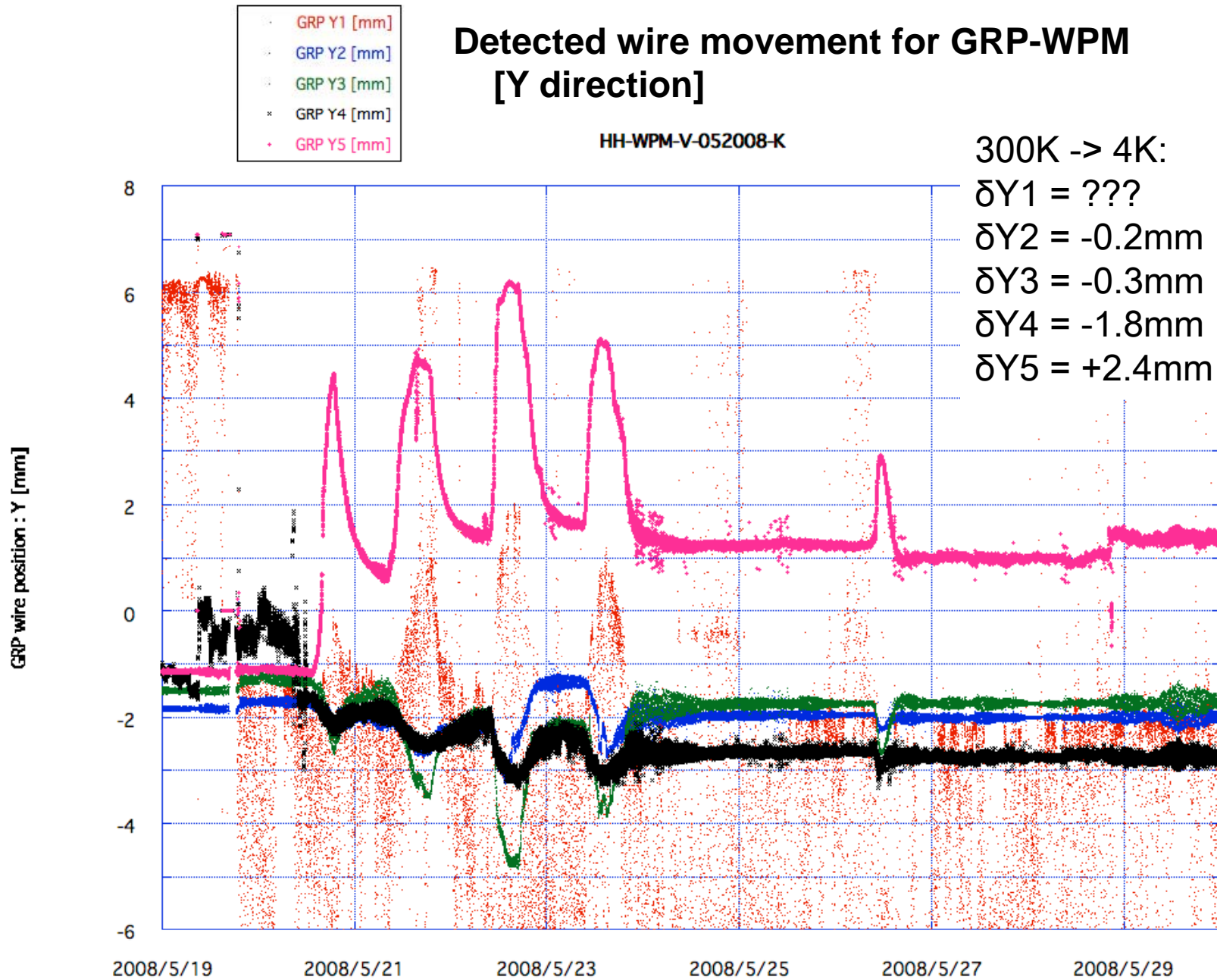
green data jump come from electrode-connector connection unstable.

date & time

Detected wire movement for GRP-WPM [Y direction]

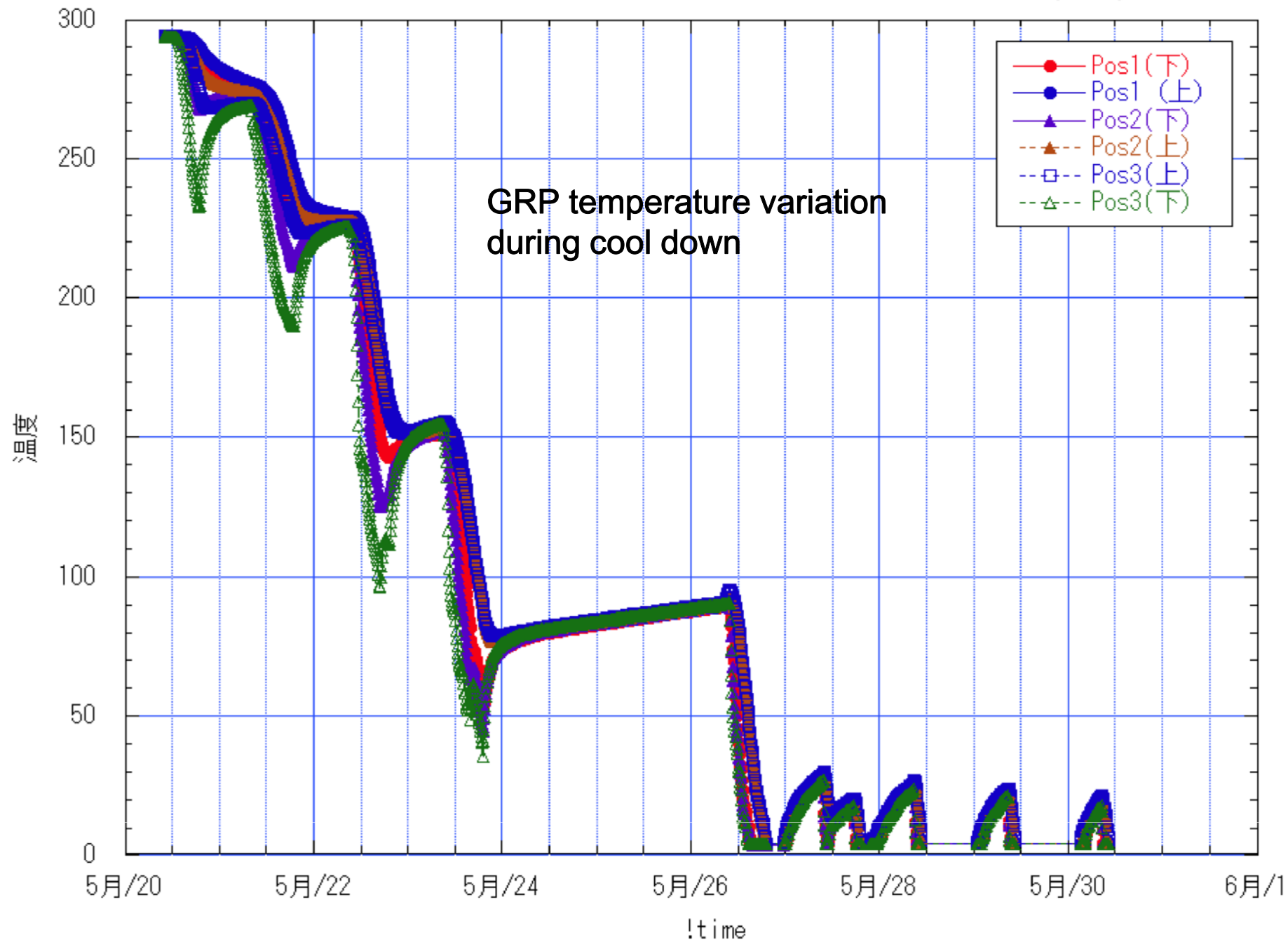
HH-WPM-V-052008-K

300K -> 4K:
 $\delta Y1 = ???$
 $\delta Y2 = -0.2\text{mm}$
 $\delta Y3 = -0.3\text{mm}$
 $\delta Y4 = -1.8\text{mm}$
 $\delta Y5 = +2.4\text{mm}$



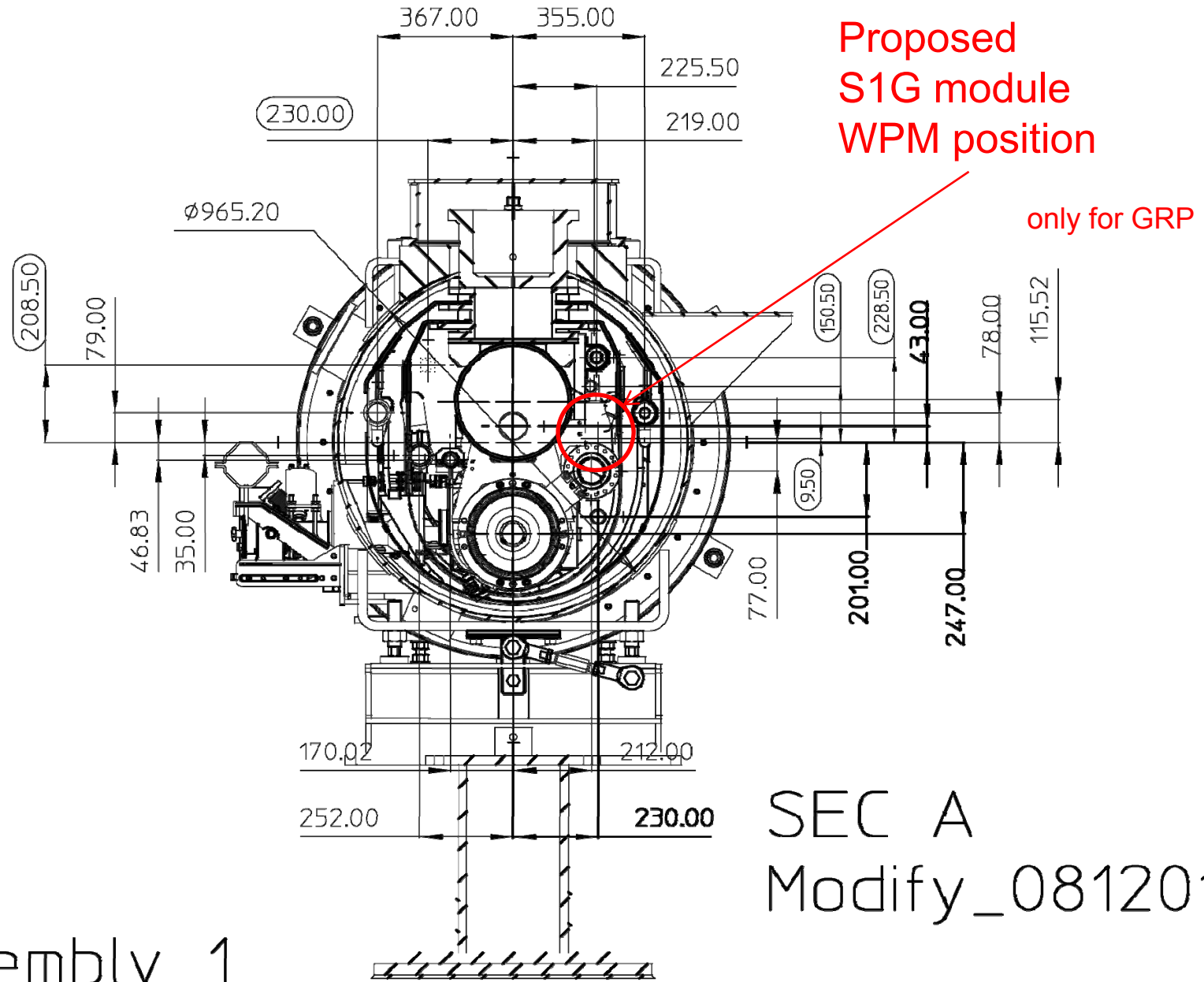
scattered data come from electrode-connector connection unstable.

date & time



Upgrade of WPM

- (1) Electrode – connector connection change from solder to spot welding (next month).
- (2) signal cable change to more strong one (next month).
- (3) SMA feed-through will be checked for the connection (next month).
- (4) WPM will be calibrated by optical telescope method in April 2008 cool down test.
- (5) study to use more narrow-band detection to resolve noisy (scattered) detected position.
(in future, maybe in S1G)



SEC A
 Modify_081201

S1_Assembly_1
 Date : 081111 Rev.8