

Steering in the ATF2 Extraction Line

Y. Renier and P. Bambade (LAL)

A. Scarfe (UMAN)

G. White and M. Woodley (SLAC)

ATF2 Project Meeting

9 June 2009



Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - Anthony Scarfe's test
 - my test



Description of the measurement

Motivation

- Steering algorithm rely on transfer matrices.
- Sign problem evidences was found.
- It must be corrected before try any steering correction.

How was made the measurements

- BPM measurements are made for 11 corrector strengths.
- Linear fit of the displacement function of the angle.
- Slope : R12 or R34 between the corrector and BPMs.
- Compare with theoretical R12 and R34 from online model.
- If sign problems are found, they are corrected in FS.

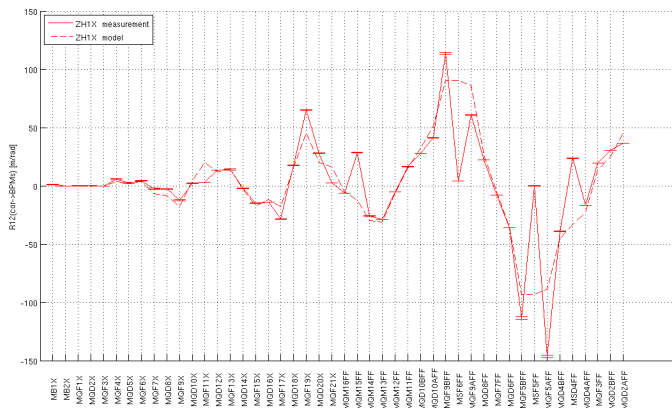


Outline

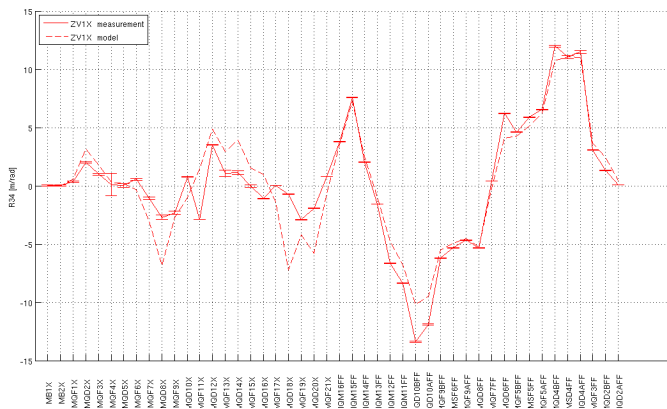
- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - Anthony Scarfe's test
 - my test



R12 from ZH1X to all BPMs



R34 from ZV1X to all BPMs



Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - **Parameters**
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - Anthony Scarfe's test
 - my test



Agreed errors (thanks to Glen)

Relevant Error Parameter for EXT section

Error Type	Level
x/y/z Post-Survey	200 μ m
Roll Post-Survey	300 μ rad
BPM - Magnet field center alignment (initial install) (x, y)	30 μ m
BPM - Magnet alignment (post-BBA, if BBA not simulated) (x, y)	10 μ m
Relative Magnetic field strength (dB/B) (systematic)	10 ⁻⁴
Relative Magnetic field strength (dB/B) (random)	10 ⁻⁴
C/S - band BPM nominal resolution (x, y)	100nm
Stripline BPM nominal resolution (x, y)	10 μ m
IP BPM nominal resolution (x, y)	2nm
EXT magnet power-supply resolution	11 – bit
FFS magnet power-supply resolution	20 – bit
Corrector magnet pulse-pulse relative field jitter	10 ⁻⁴



Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - **Results**
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - Anthony Scarfe's test
 - my test



Summary of EXT steering results

quantity	results	
	mine	Antony's
rms X (EXT) [mm]	0.2 ± 0.1	3 ± 2
rms Y (EXT) [mm]	0.3 ± 0.1	$.5 \pm .5$
rms X (EXT+FF) [mm]	$.5 \pm .5$	10 ± 10
rms Y (EXT+FF) [mm]	$.7 \pm .6$	2 ± 2
BPM measurements	10	60 ± 10

legend

- rms (EXT) : standard deviation of EXT BPM readings after EXT steering.
- rms (EXT+FF) : standard deviation of EXT+FF BPM readings after EXT steering.
- BPM measurements : number of measurements to obtain presented results.



Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - Anthony Scarfe's test
 - my test



Comparison simulation/true lattice

Difference from standard errors

Error Type	Nominal	observed
Relative Magnetic field strength (dB/B) (systematic)	10^{-4}	10^{-2} (rare standardization)
C/S - band BPM resolution (x, y)	100nm	5 μ m (no S-band)
Stripline BPM resolution (x, y)	10 μ m	50 μ m
Stripline BPM scale factor (x,y)	1	0.5 – 3

Remark

- My algorithm need then 3 iterations to obtain comparable results.
- Scale factor effect was not simulated => may have a large influence.



Comparison simulation/true lattice

Difference from standard errors

Error Type	Nominal	observed
Relative Magnetic field strength (dB/B) (systematic)	10^{-4}	10^{-2} (rare standardization)
C/S - band BPM resolution (x, y)	100nm	5 μ m (no S-band)
Stripline BPM resolution (x, y)	10 μ m	50 μ m
Stripline BPM scale factor (x,y)	1	0.5 – 3

Remark

- My algorithm need then 3 iterations to obtain comparable results.
- Scale factor effect was not simulated => may have a large influence.



Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - **General description**
 - Anthony Scarfe's test
 - my test



Description of the test

Description

- A reference orbit is taken.
- An angle is introduced with a corrector.
- Use the steering algorithm to find a correction.
- Check if the corrector strength is set back to its previous value.
- If it is not the case, check if the correction improves the orbit.



Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - **Anthony Scarfe's test**
 - my test



Anthony Scarfe's test

What was tested

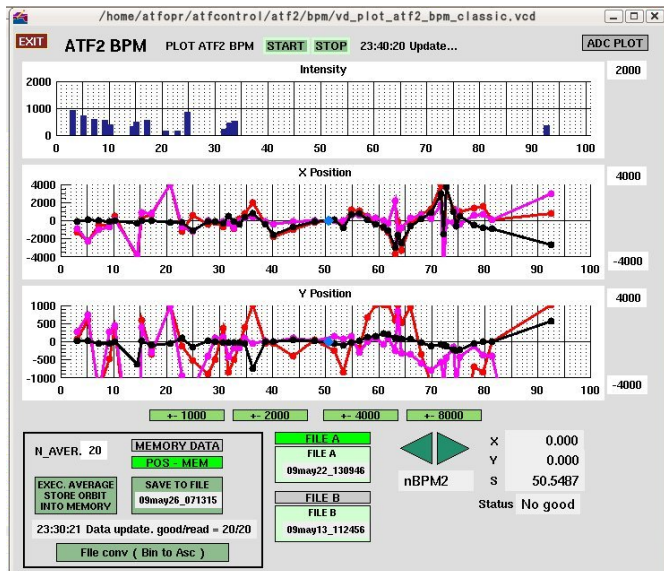
- Angle was introduced at ZH2X.
- Test using just ZH2X to correct.
- test using all horizontal correctors.
- test using all correctors (horizontal and vertical).

Result

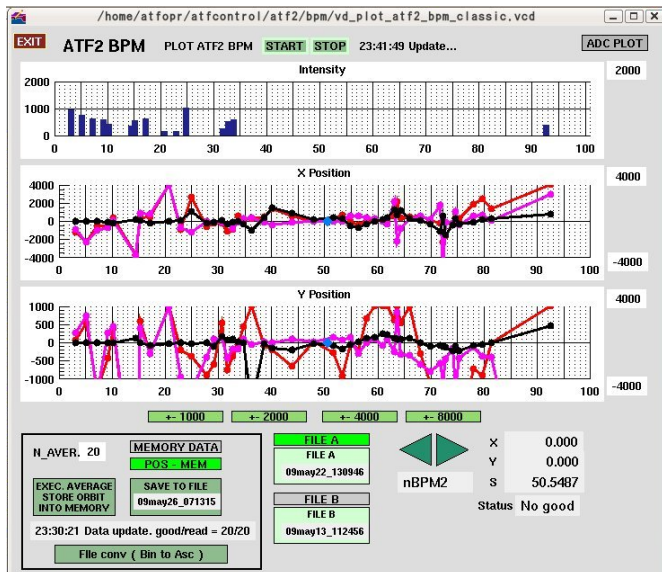
- The correction is 2x too large.
- Good correction with a gain of $\frac{1}{2}$.
- The good corrector is used to correct when all horizontal are used.
- Vertical and horizontal correction are separated, try to correct in vertical even if not needed.

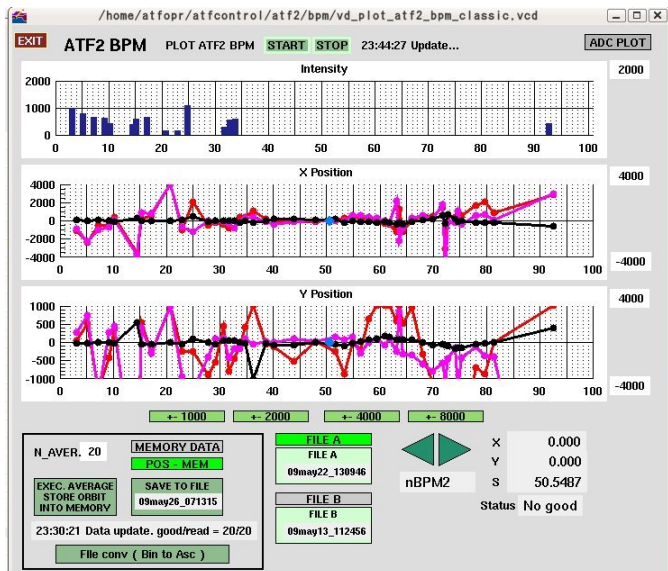


BPM reading before correction



BPM reading after correction



BPM reading after correction (gain of $\frac{1}{2}$)

Outline

- 1 Measurement of the transfer matrices between correctors and BPMs
 - Description
 - Results
- 2 Simulation of steering correction in EXT
 - Parameters
 - Results
 - Observed parameters
- 3 Experimental steering correction in EXT
 - General description
 - Anthony Scarfe's test
 - my test



my test

What was tested

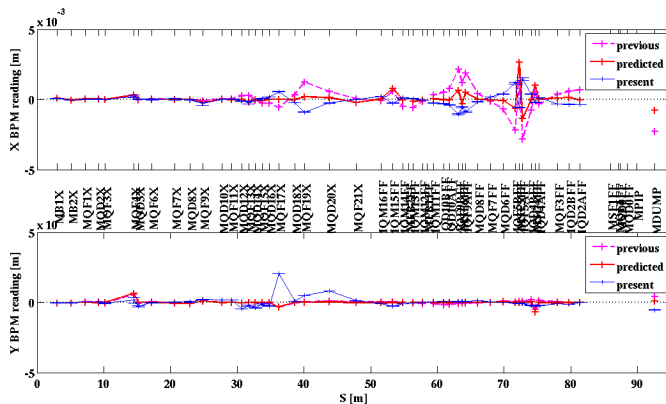
- Angle was introduced at ZH2X.
- test using all correctors (horizontal and vertical).
- Angle was introduced at ZV2X.
- test using all correctors (horizontal and vertical).

Result

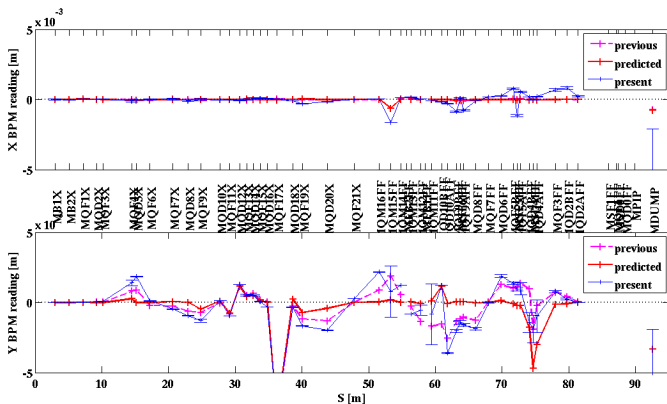
- The correction is 2x too large in horizontal (same as Anthony).
- The good corrector is used to correct.
- Correction seems to have the bad sign in vertical.
- After that results, transfer matrices check has been performed using ZH2X and ZV2X, strange results, analysing on-going.



horizontal correction



vertical correction



Conclusion and prospects

Conclusion

- Tools for check transfer matrices ready and working.
- Transfer matrices were checked from ZH1X and ZV1X.
- Very good agreement for the cavity BPMS.
- Non-constant scale factor for stripline BPMs.
- All sign are now correct. Thanks a lots to Glen and Mark !
- Steering works well in simulation, need to test effects of scale factors.
- Still problems with experimental steering, but getting close.

Prospect

- We would like to make a complete transfer matrices check.