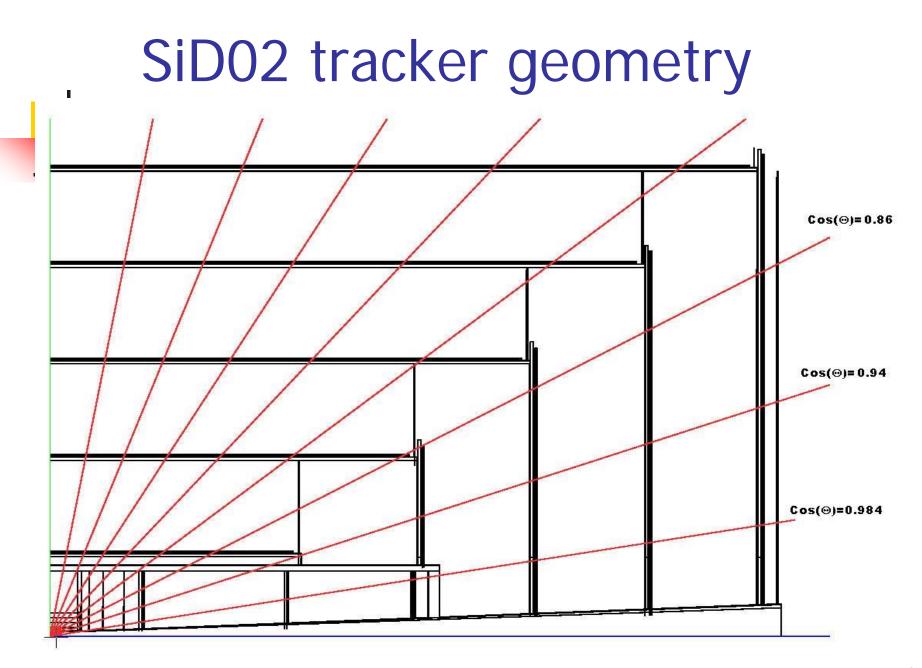
# SiD02 tracking resolutions with missing layers

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### What I did

- Using Weight Matrix Fitter I can get tracker resolution for any detector configuration. I can mask any layer in the tracker or vertex detector, which means that I consider it as dead.
- To get covariance matrix of track parameter errors, I don't need large statistics of tracks, as for given track parameters covariance matrix is not fluctuating. So I need just one track for any given set of track parameters passed through fitter to get it.
- So, I did this exercise for every possible missing layer for 8 different values of cos(Θ) 0, 0.5, 0.75, 0.8, 0.89, 0.95, 0.972, 0.986, varying particle total momentum from 0.2 to 1000 GeV
- I got 5(parameters) x 8(cos values) x 21 (layers) = 840 plots. However not all of 5 them are different, as not all layers are hit at all values of cos(Θ). Total number of different plots was 231

#### You can see it here:

#### <u>http://www.slac.stanford.edu/~sinev/sid02res.html</u>

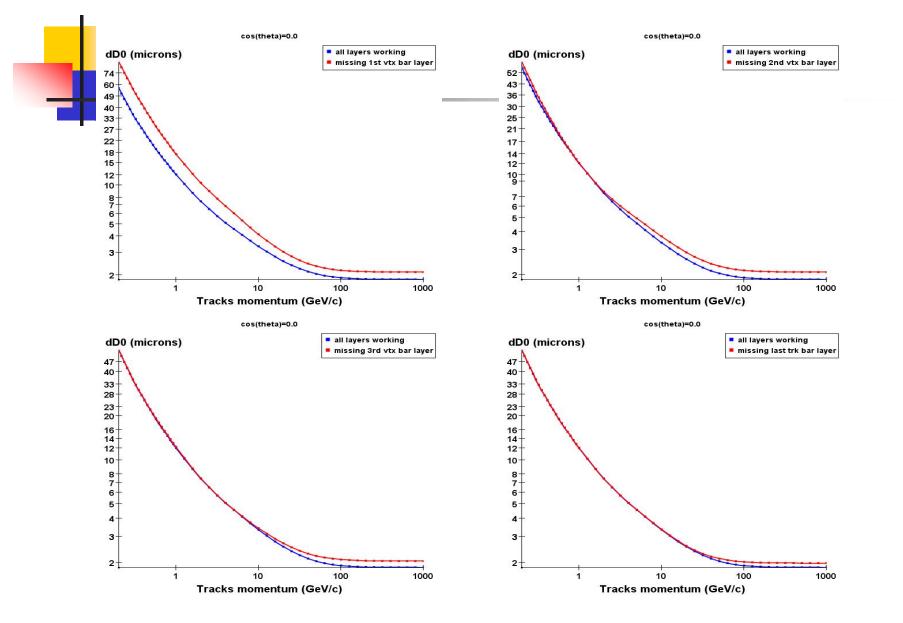
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#### Effect of missing layer in SiD tracker on fitted track parameters errors

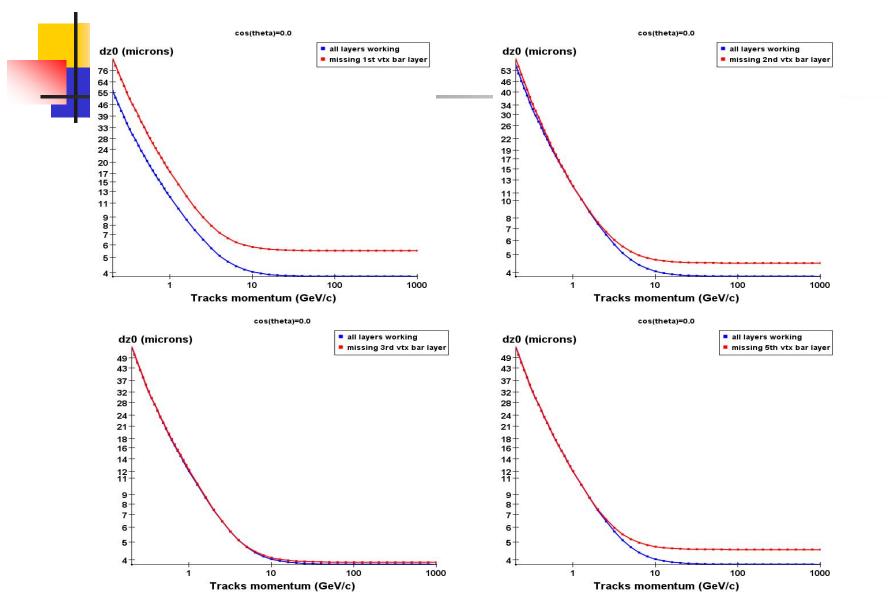
Errors are calculated by Weight Matrix Fitter, assuming following sensor resolutions: VTX - 3.5µ Tracker barrel 7µ in rφ and 100 mm in Z, Tracker endcap - 7µ in rphi and 35µ in r (12 degree stereo), Forward detector disks - same as VTX. Entries are shown in red if given layer does not affect given parameter.

Missing layer	$\cos(\theta)=0.0$	$\cos(\theta)=0.5$	Cos(θ)=0.75	Cos(θ)=0.80	Cos(θ)=0.89	Cos(θ)=0.95	Cos(θ)=0.97	Cos(θ)=0.986
First VTX barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
Second VTX barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
Third VTX barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
4th VTX barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
5th VTX barr.	d0 <b>q0</b> Pt z0 T1	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
First Tracker barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>			
Second Tracker barr.	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt <mark>z0 T1</mark></u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
Third Tracker barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>			
4th Tracker barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
Last Tracker barr.	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
First VTX endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>
Second VTX endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>			
Third VTX endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 </u> ]
4th VTX endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 </u>
First Tracker endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 </u> ]
Second Tracker endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>	<u>d0 φ0 Pt <b>z0 T1</b></u>	<u>d0 φ0 Pt z0 T</u>
Third Tracker endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T</u>			
4th Tracker endcap	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 Tl</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 </u> ]			
First Forward Disc	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 <b>T1</b></u>	<u>d0 φ0 Pt z0 </u>
Second Forward Disc	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 7</u>
Third Forward Disc	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 T1</u>	<u>d0 φ0 Pt z0 7</u>

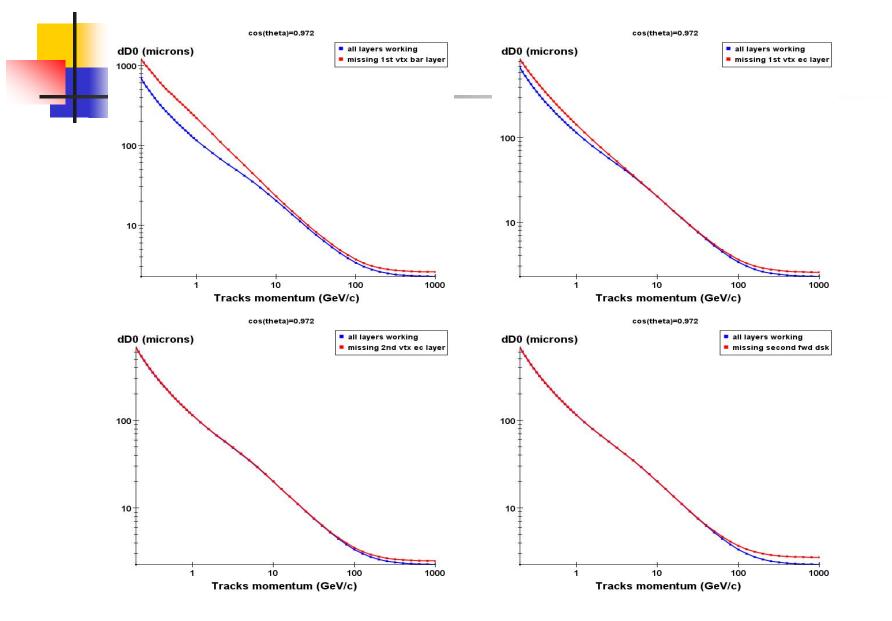
#### Some examples: d0 at $cos(\Theta)=0.0$



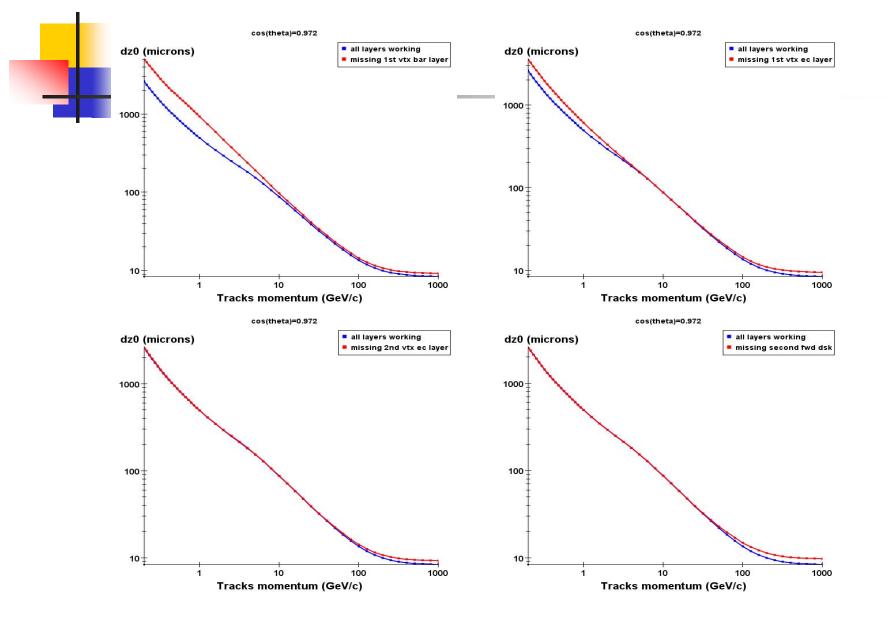
#### Some examples: z0 at $cos(\Theta)=0.0$



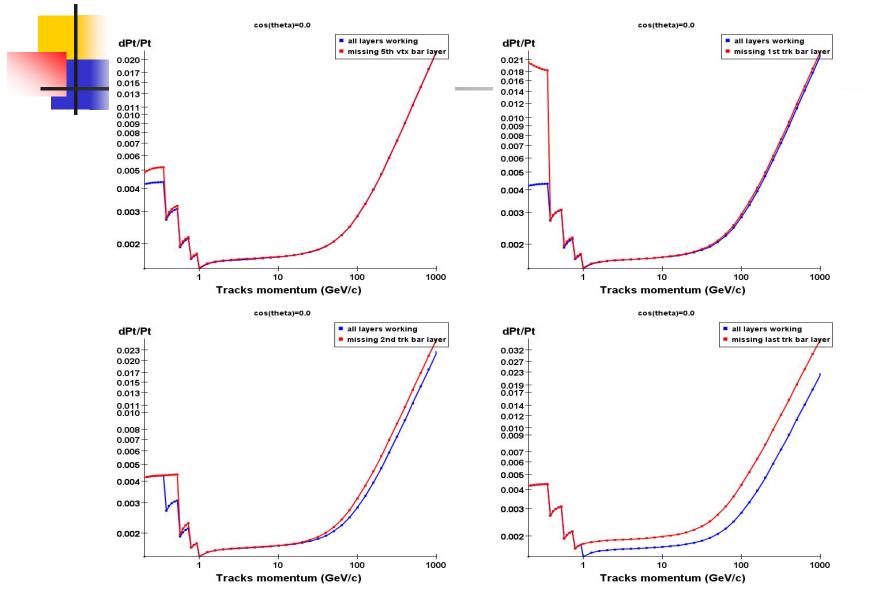
#### Some examples: d0 at $cos(\Theta)=0.972$



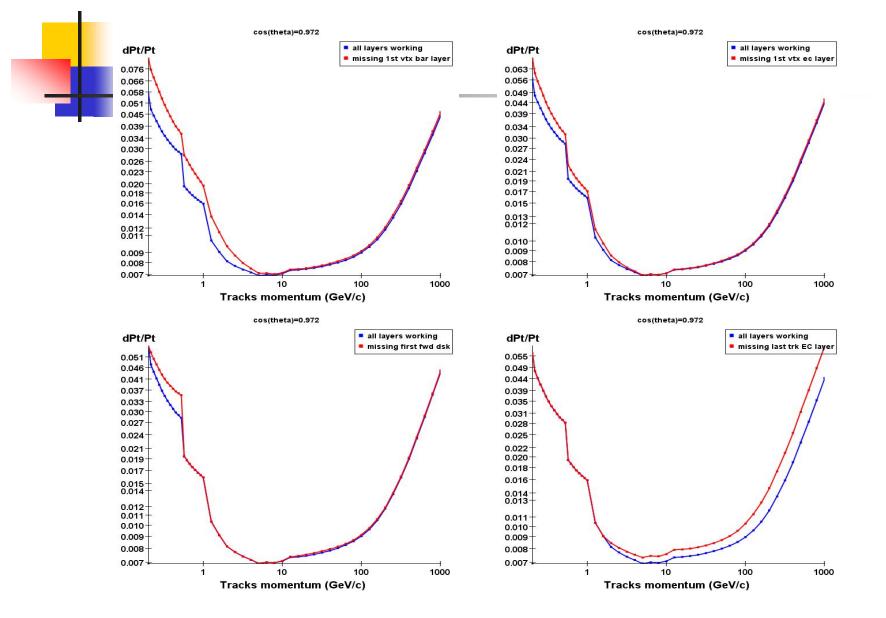
#### Some examples: z0 at $cos(\Theta)=0.972$



#### Some examples: dPt/Pt at $cos(\Theta) = 0.0$



#### Some examples: dPt/Pt at $cos(\Theta) = 0.972$



## How can it be used for benchmark studies ?

What I have available is the resolution tables, used for fast monte-carlo – in the same format as Bruce's tables. So, any physics parameter for benchmark processes can be extracted from fast monte-carlo simulation, using "layer deficient" table. I have 21 such tables and can provide them on request.

## Conclusions

- We can see, that no one single layer could ruin tracker performance. The track parameters resolution is sensitive to missing layer, but effect is not dramatic.
- From the other hand, we see, that there is no "unneeded" layers. Every layer plays a role in achieving maximum performance goal