

TPC Testbeam Software

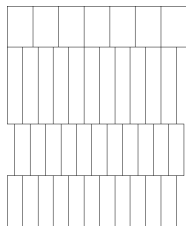
Martin Killenberg

Physikalisches Institut

universität  **bonn**



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Orsay, 04.11.2009

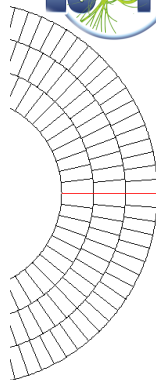


• RectangularPadRowLayout

- Cartesian Geometry
- All pads in one row are equal
- Pad size and number of pads may vary from row to row

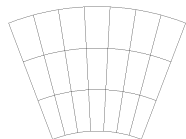
• FixedPadSizeDiskLayout

- Polar Geometry
- Complete circle
- All pads have the same size



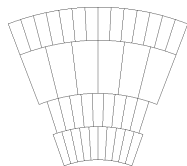
• New: FixedPadAngleDiskLayout

- Polar Geometry
- Segment of a circle
- All pads have the same angle



• New: VersatileDiskRowLayout

- Polar Geometry
- Segment of a circle
- All pads in one row are equal
- Pad size and number of pads may vary from row to row



Multiple Modules in GEAR

A realistic TPC end plate (EUDET LP) consists of multiple modules
⇒ introduce TPCModule in GEAR

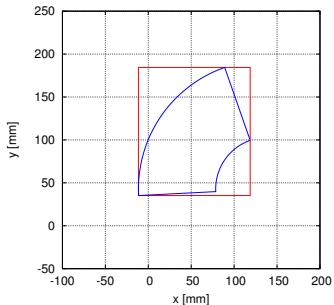
TPCModule

- derived from PadRowLayout2D
 - contains a pad layout implementation
- ⇒ full backward compatibility and transparency in user code

Coordinates:

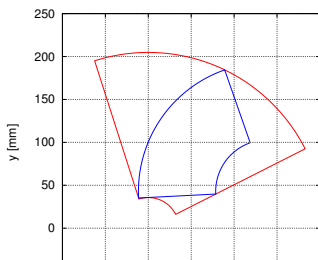
- Pad plane implementation provides local coordinates
- Module has offset and angle to global coordinate system
- Accessing the pad plane through the module automatically provides correct global coordinates

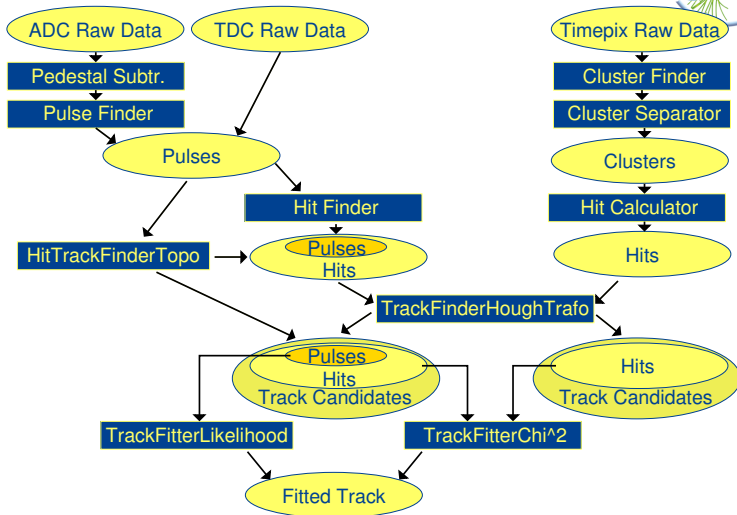
Example: Plane extent



↑ global Cartesian coordinates

↓ global polar coordinates







Status last year:

- Chain is ready for non-modular version, but only tested with toy MC

Requirements for LP test beam:

- Multiple modules
 - Include gear multiple modules in processors (✓)
 - Add ModuleID to conditions data classes (e. g. pedestals) (✓)
 - Alignment (✓)
- Data taking with magnetic field
 - Helical track fit (✓)¹
- Calibration (✗)
 - Toy MC does not need calibration
 - Has to be developed with real data

¹only simple fit without correct treatment of covariance matrix

Alignment is possible:

- Calculate offsets manually
- Hard-code offsets in GEAR XML files

Goal: Apply alignment at run time using LCCD

- Should be transparent to existing reconstruction code
 - Independency on pad plane implementation should not be broken
- ⇒ Keep the PadRowLayout2D interface

How to implement it?

- Store calibrated XML files in database?
- Extend functionality of TPCModule?
- Write a wrapper class?
 - Inherit from TPCModule?
 - Have an instance of TPCModule?

- Linear Collider Conditions Data toolkit
- TPCCondData: LCIO / LCCD classes for the TPC

Data needed	TPCCondData	Available for test beam run				
		Japanese ALTRO	GEM TDC	Micro-megas	Std. GEM	Timepix + GEM
Channel mapping	✓	✓	✓	✓	✓	
Channel quality	✓	×	×	×	×	×
Pedestals	✓	×	×	×	×	×
v_{drift} + Diffusion	✓	×	×	×	×	×
Gas conditions	✓	✓	✓	✓	✓	✓
E-field settings	✓	×	×	×	×	×
B-field settings	×					
HV settings	×					
Field maps	✓			×		
Electronics	×					
Calibration	×					

- Linear Collider Conditions Data toolkit
- TPCCondData: LCIO / LCCD classes for the TPC

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v_{drift} + Diffusion	✓	✗	✗	✗	✗	✗
Gas conditions	✓	✓	✓	✓	✓	✓
E-field settings	✓	✗	✗	✗	✗	✗
B-field settings	✗					
HV settings	✗					
Field maps	✓					
Electronics	✗					
Calibration	✗					

We have to get a working data base and conditions data bookkeeping

Two types of conditions data:

- Calibration data

- Pedestals, mappings, gain factors
- Collections / maps of many identical objects
- Possibly large amount of data
- Usually no DB access to individual data members

⇒ Store as binary objects

Current functionality of LCCD

- Meta data

- Gas mixture, beam energy, particle type, position of detector
- No collection, individual data objects
- Only few integer / float (/ string?) values
- Query DB to search for runs / data sets

⇒ Store data members directly in DB table

For development of geometry descriptions and fist checks during data taking a graphical viewer is needed.

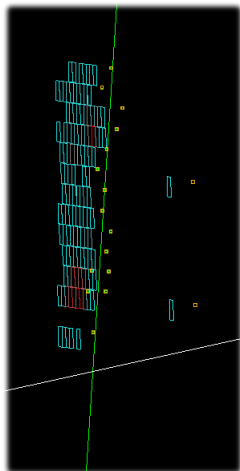
HepRepOutputProcessor produces HepRep XML file which can be displayed e. g. with Wired/JAS3

Event display shows

- TPC
- GEAR pad plane
- Charge on pads
- 3D hits
- Tracks

Disadvantages

- MarlinProcessor is offline software
- Events not browsable
- Graphical display has errors (depth)
- **Very bad** performance



- GEAR
 - New pad layout classes for existing prototypes
 - Multiple modules incl. coordinate transformations
 - **Implement alignment from conditions data**
- MarlinTPC
 - All reconstruction processors are multi module capable
 - Performance has to be improved
 - Develop calibration tools with real data
 - EventDisplay: HepRepOutputProcessor + Wired/JAS3
- Conditions data
 - Define missing data classes for calibration
 - Set up a data base
 - **Queryable conditons data**