# S1-Global study plan (HLRF/LLRF) Shin MICHIZONO KEK

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GDE meeting Beijing (Mar.29, 2010)

#### **Schedule**

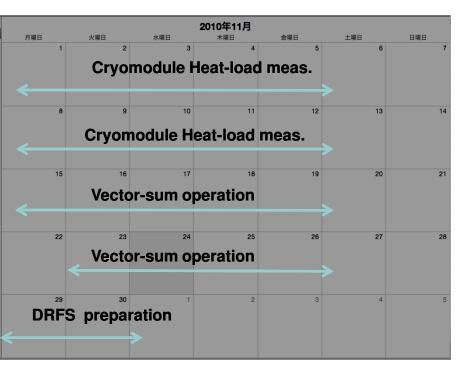
Total 5 weeks for LLRF/HLRF

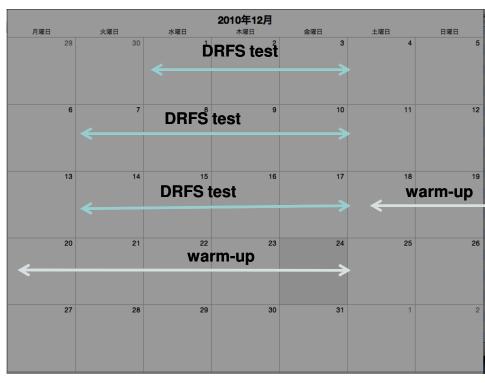
- Two weeks for 8 cavity rf control
  - Replacement and calibration
  - Fast interlock system using loaded-Q monitor
  - Vector sum FB control 8cav. under piezo compensation
  - Vector sum FB control IF-Mix
  - Feedback instability
- Three weeks for DRFS system evaluation
  - Replacement and calibration
  - Fast interlock performance
  - Field regulation
  - Sag compensation
  - Cavity filling procedure
  - Forward & reflection monitor without circulators
  - Klystron output characteristics under rf reflection

#### S1G schedule LLRF/HLRF

Nov. 2010

Dec. 2010



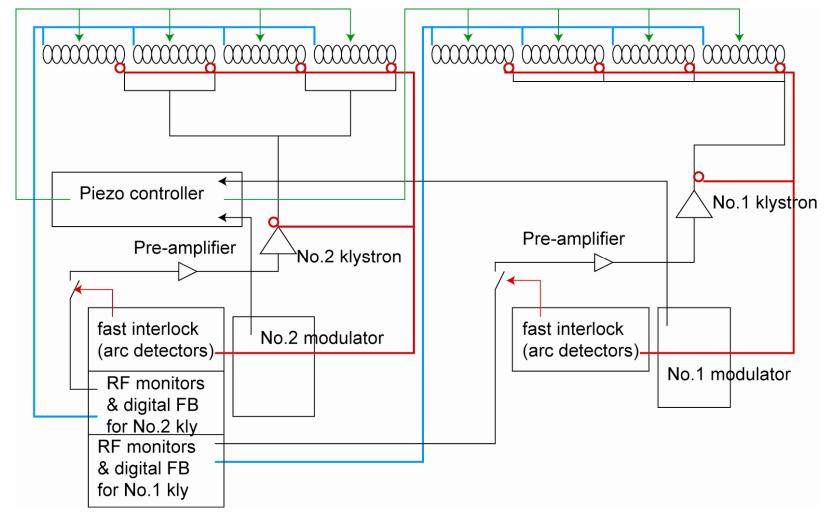


#### S1 Global

Both No.1 and No.2 klystrons will be used for conditioning of 8 cavities.

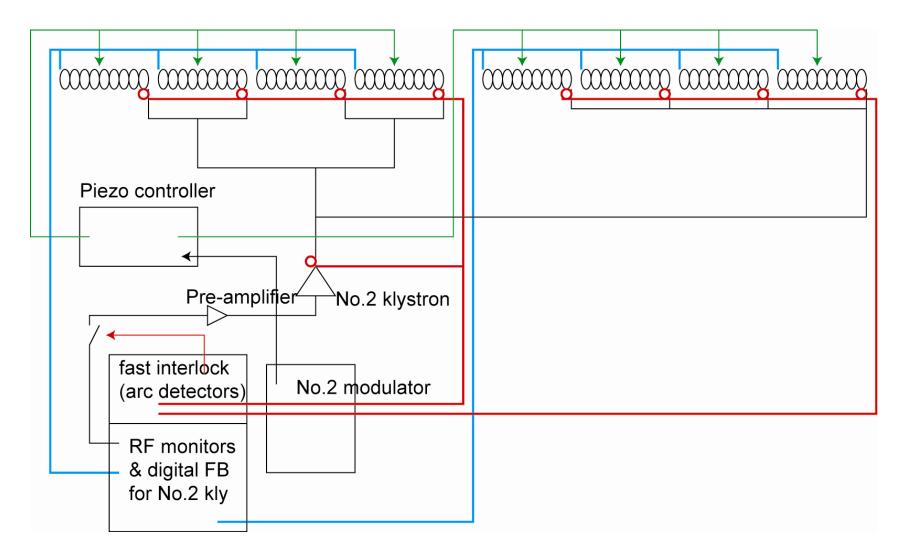
### S1 Global 1<sup>st</sup> stage

- Each 4-cavities is driven by a klystron (in order to reduce the conditioning time).
- Digital IIrf controls are located near No.2 klystron.
  Only fact interlock (MDS) cyclem will be located at No.4
- Only fast interlock (MPS) system will be located at No.1 klystron.

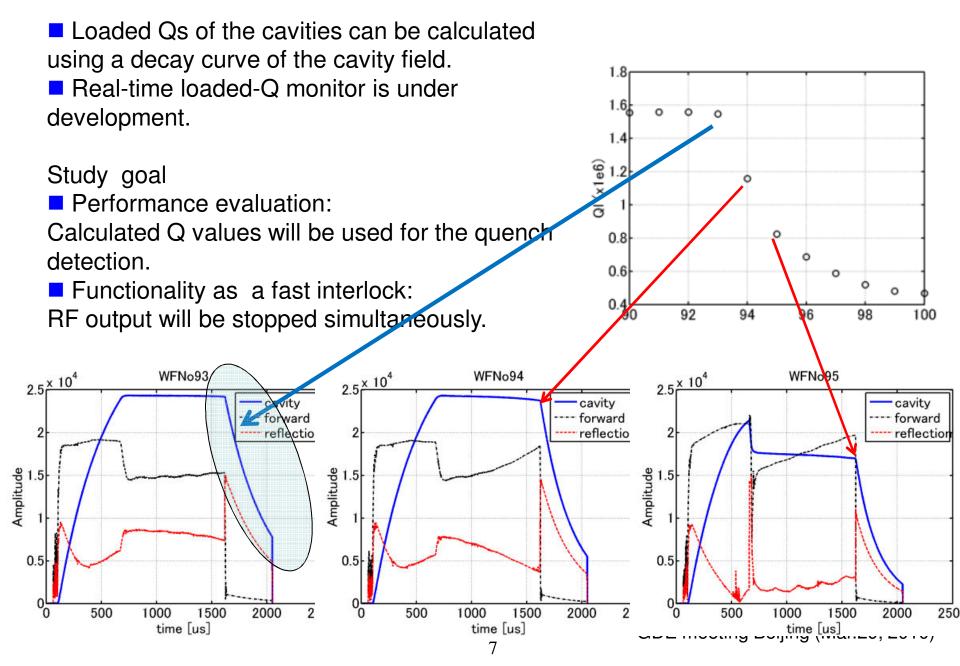


#### S1 Global 2<sup>nd</sup> stage

All the cavities are driven by No.2 klystron.



#### **loaded-Q monitor**



#### Vector sum FB control

Vector sum FB control 8cav. under piezo compensation...

Study goal

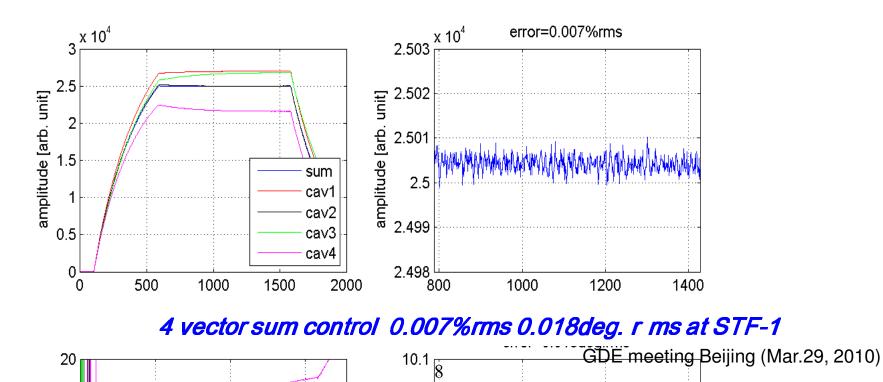
Performance evaluation:

Amplitude and phase stabilities during rf pulse

These number will be compared with the stabilities obtained at STF-0.5.

half day (~5hours max.) stability

Effects of microphonics, pieze compensation



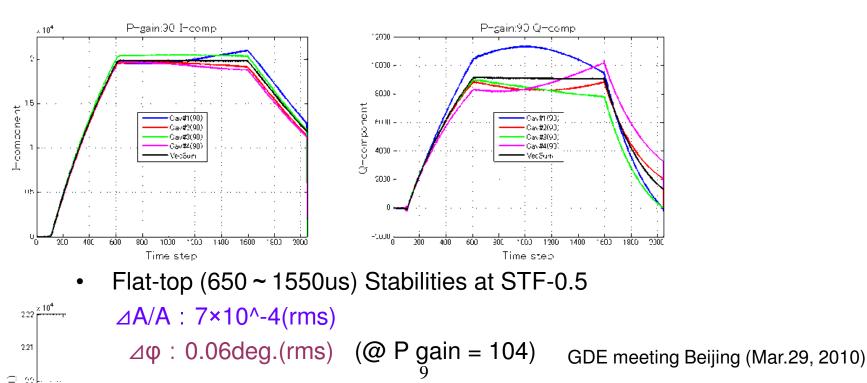
## Feedback with IF-Mix scheme

#### Vector sum FB control 8cav. under piezo compensation using IF-Mix.

Study goal
System demonstration
Eight ADCs will be used for 8 cav. Pick-up, forward, reflection signals.
First feedback demonstration using the IF-Mix scheme.
(Four-cavity vector sum was demonstrated at STF-0.5 with IF-Mix)

Performance evaluation:

Amplitude and phase stabilities during rf pulse.



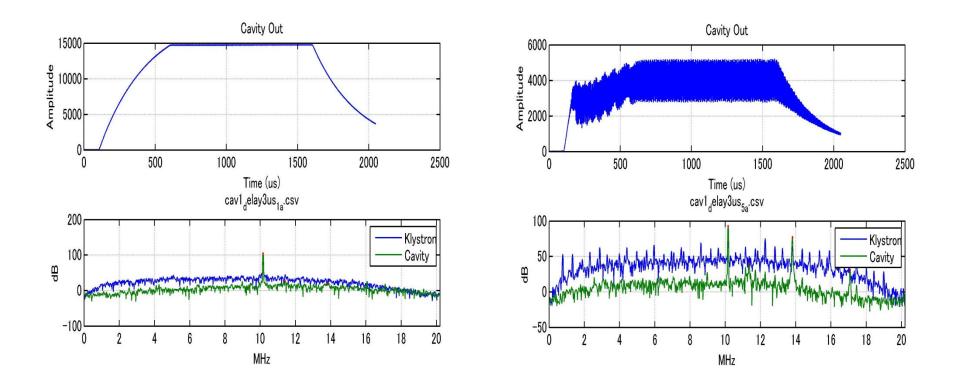
#### Feedback instability

Instability suppression using analog/digital filters

Study goal

Performance using digital or analog filters to eliminate the instablilities

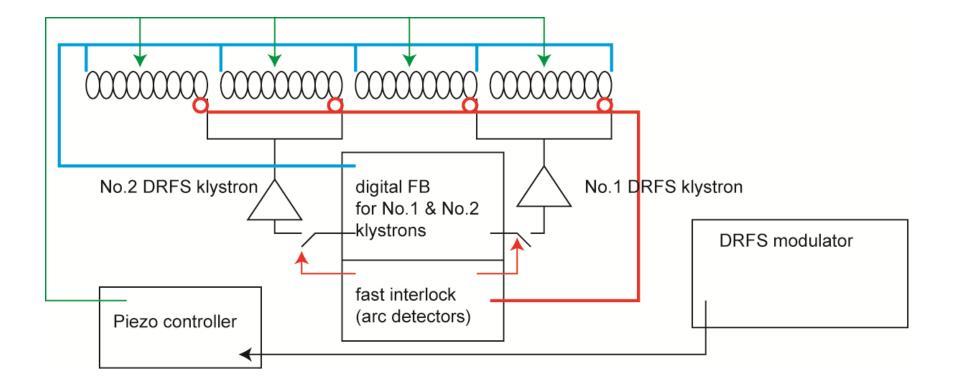
Comparison between these filters and latency optimization



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# S1 Global 3<sup>rd</sup> stage (DRFS)

- New digital LLRF systems (uTCA) will be installed to the tunnel.
- Fast interlock will be also located at the tunnel.
- Piezo compensation from the ground level



#### Fastinterlock performance

ILC-aimed compact fast-interlock system will be installed to DRFS units.
 This was developed for J-PARC and was also installed to cERL rf test stand.

#### Study goal

Performance evaluation

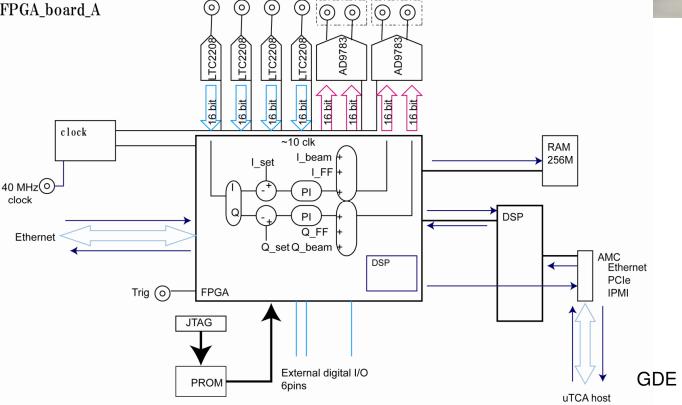


#### Field regulationField regulation

cERL like uTCA FPGA system will be installed.

Study goal Performance evaluation

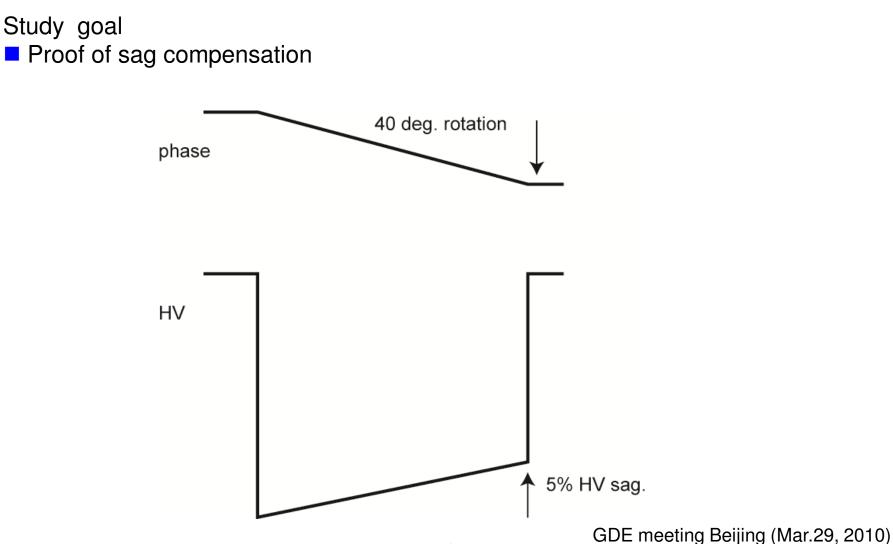




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## Sag compensation

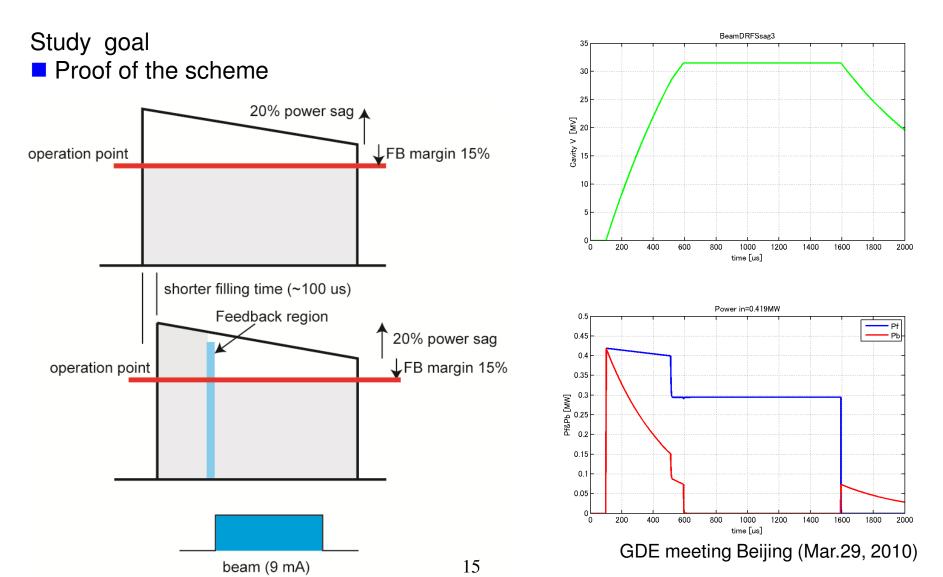
HV sag (~5%) will cause 40deg. Rotation. (8deg./%)
 This will degenerate the feedback stability and compensation is the essential for high feedback gain.



### Full power filling scheme

In order to use the rf power under sag efficiently, full-power filling scheme is proposed.

By using the full-power filling, shorter rf pulse will be enabled.

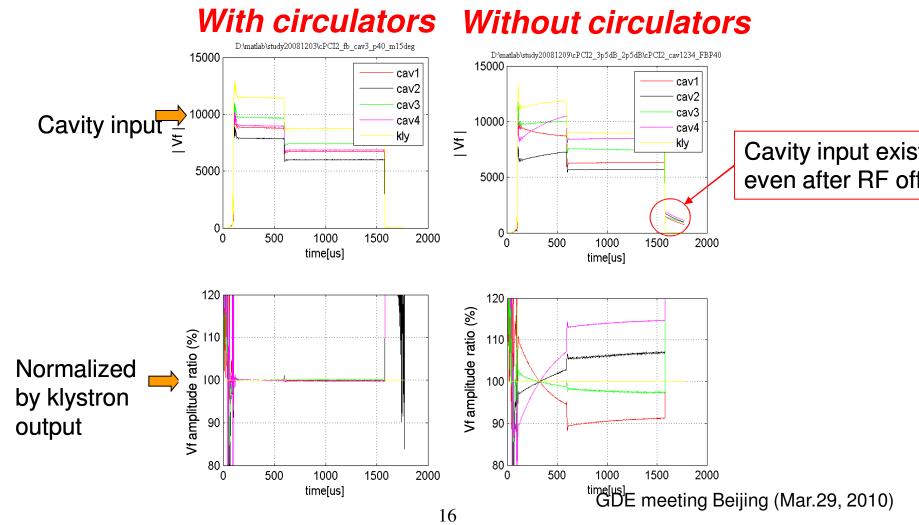


#### **Circulator effects**

The previous study (STF-1) indicate high isolation will be required at hybrid in order to estimate the cavity parameters (such as QI and detuning).

Study goal

Study of the rf isolation with new hybrid system suitable for DRFS



### **Circulator effects (2)**

Klystron output depends on the reflection to the klystron itself.

In case of the unbalanced operation (or different cavity detuning each other), the refections cannot be canceled.

Study goal: Evaluation of the effect of the reflection signal to the klystron

