Automation of SRF cavities optical inspection

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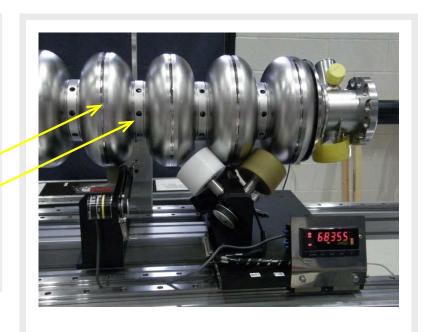
Optical inspection system

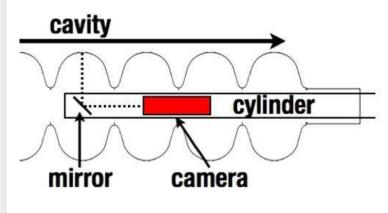
Optical inspection system is designed to study the inner surface of cavities for defects

This includes

- equator welds
- iris welds

Optical camera is used to inspect iris & equator welds





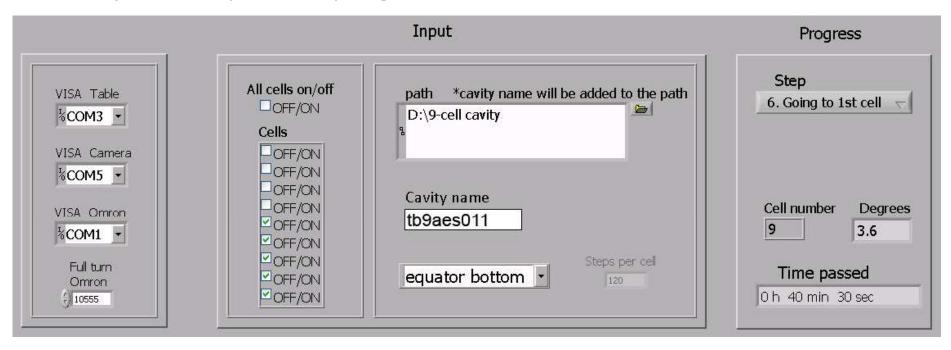
Automation system outline

At present:

- the system performs inspection in 3 hours
- can work **autonomously**
- still needs some manual adjustments

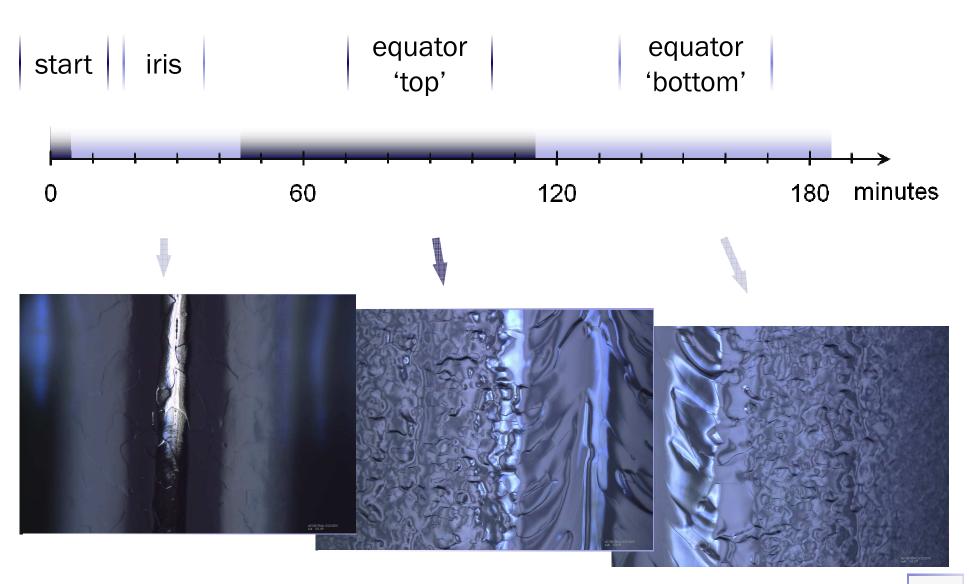
Automation system outline

Main optical inspection program window

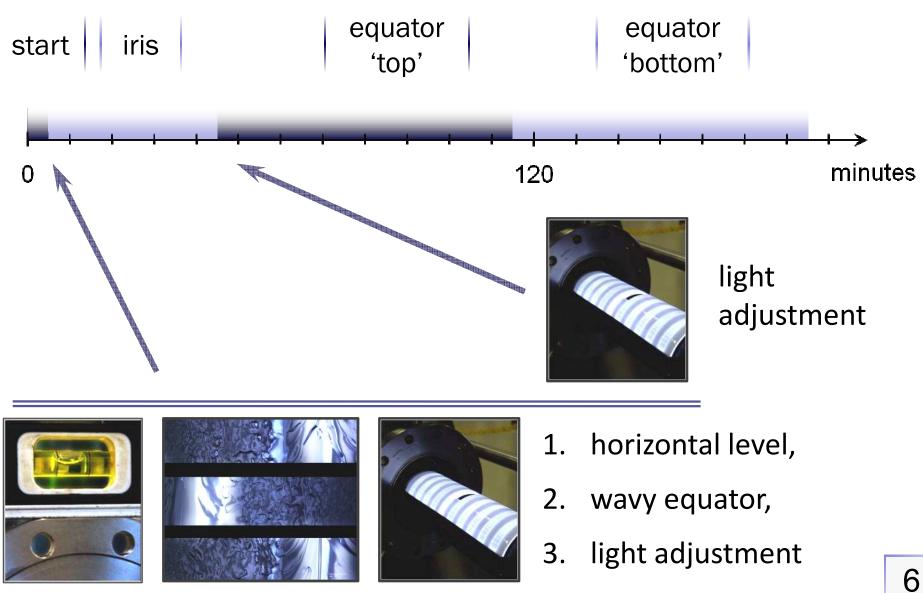


- Initial adjustments for lights, ...
- Various error handling
- Basic LabView functions library for further software development

Optical inspection is four-steps:



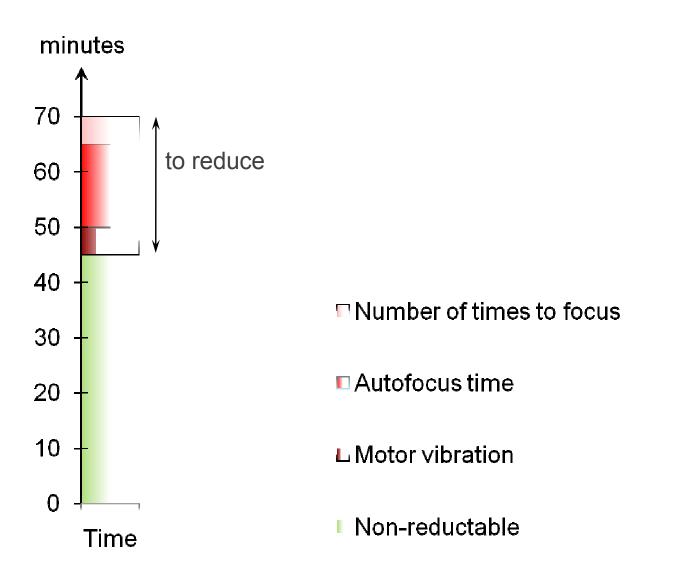
Manual adjustments are necessary



Next steps

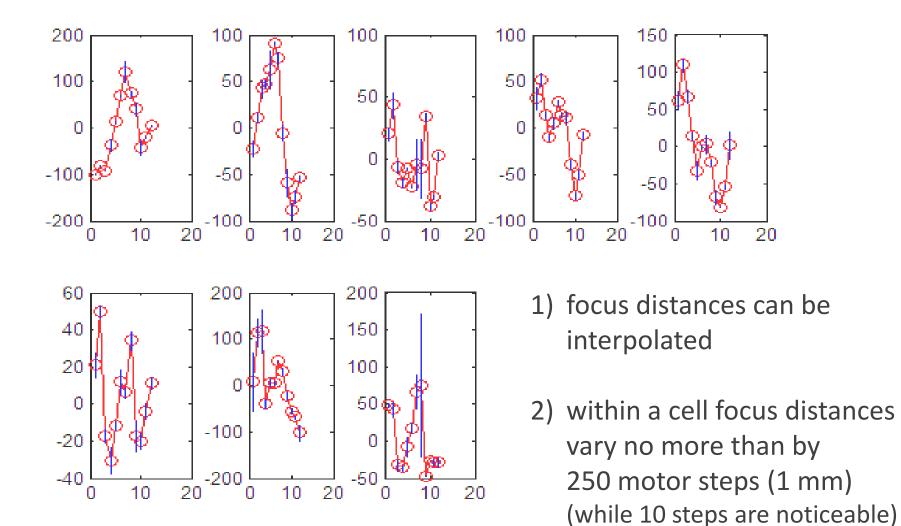
- 1. Time reduction (goal: ~2 hours)
- 2. Automation of light adjustment
- 3. Working on quality problems (horizontal level shift, ...)
- 4. Images processing

There are options for time reduction



1. Reduction of number of times to focus

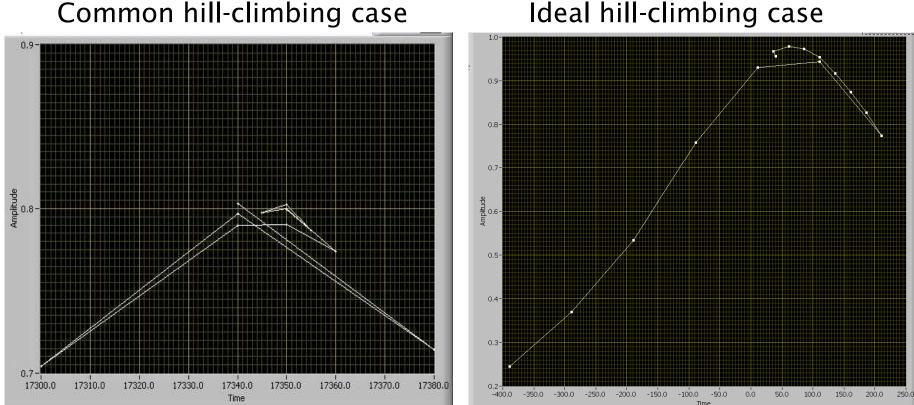
Focus distances for 8 irises for angles 0-360:



9

2. Autofocus time reduction

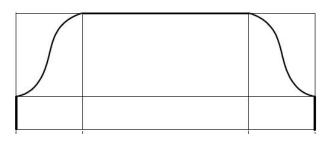
In many cases simple hill-climbing algorithm is too time-consuming because a new focus distance is close to the previous one (left image)



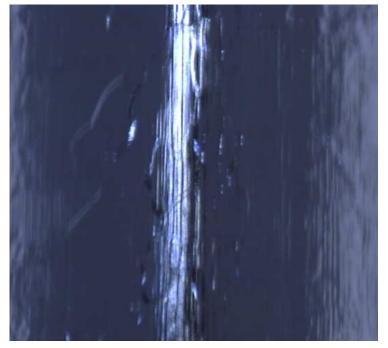
Ideal hill-climbing case

In other cases rough focus adjusting can be made with less steps than at present (right image)

3. Motor vibration effect



Sharp and smooth speed changes result in blurred and clear images respectively



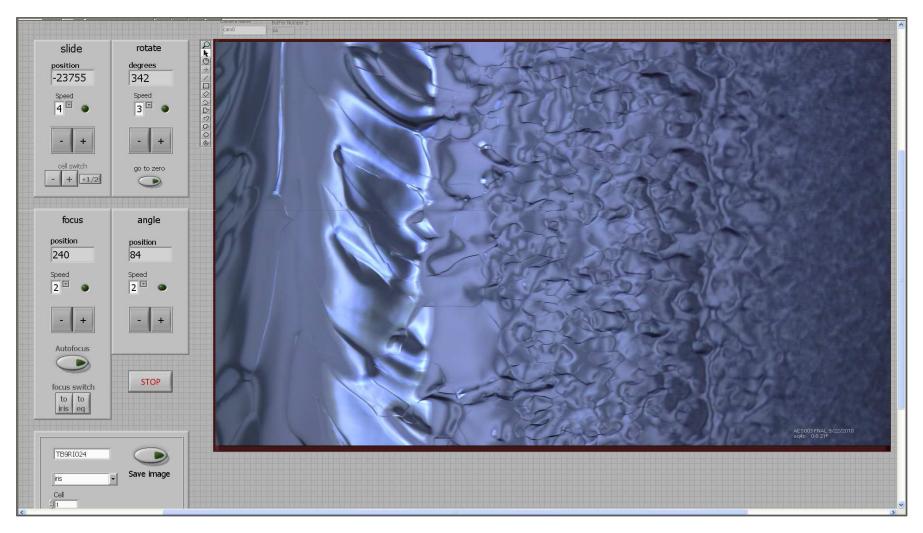


Hence, for the sharp speed function it is necessary to wait 600-1000 ms before taking picture

Q & A

Appendix-1

Control tool - basic



Appendix-2

Control tool - 2

CAMERA CON	TROL	TABLE CONTROL	Save Image
2 # pulses / step 2 Make step 2 500	osition focus focusing 75 Autofocus	Speed 0 GO position slide 2 T # pulses / step Make step 500 STEP Set to ZERO	TB9R1024
Step Set to ZERO 2 UP/DOWN 2	Focus	UP/DOWN ZERO Slide	path B ^{D: Images}
position to go 3 Move to 3 Speed 3 0 GO PO 2 4 pulses / step 3 Make step 3 0 100 STEP UP/DO3 Set to ZERO 3 ZERO	osition angle angle Angle	Speed 3 ♥ pulses / step uP/DOWN position to go Move to GO position rotate 0 position rotate 0 Precise turn Precise turn CERO Precise turn CERO Precise turn CERO Rotate	Omron position Omron -1 10505 Save image
cam0 706	Camera motor	Table motor Omron	