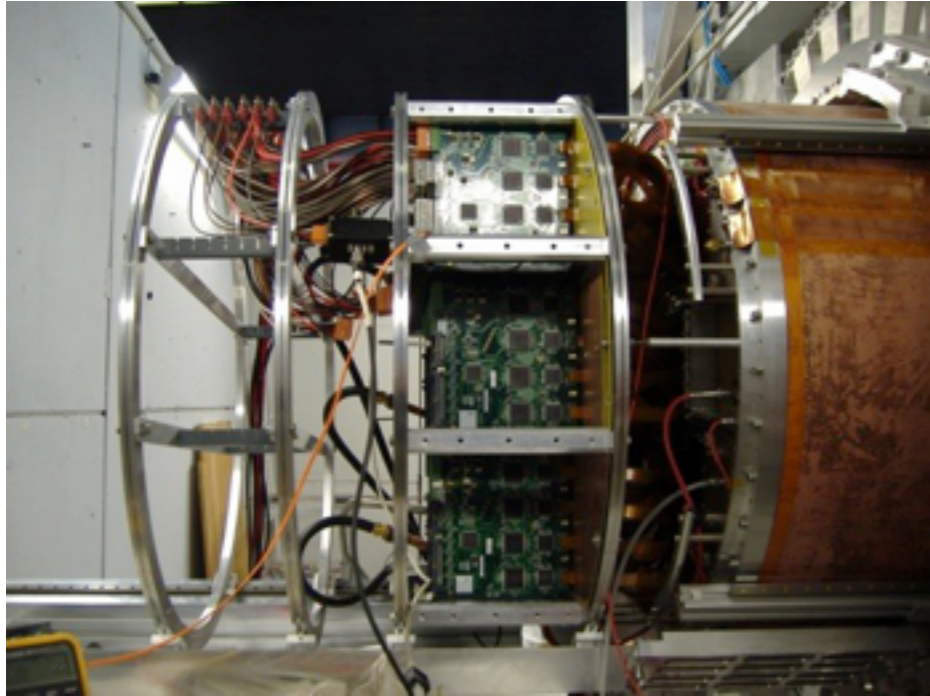


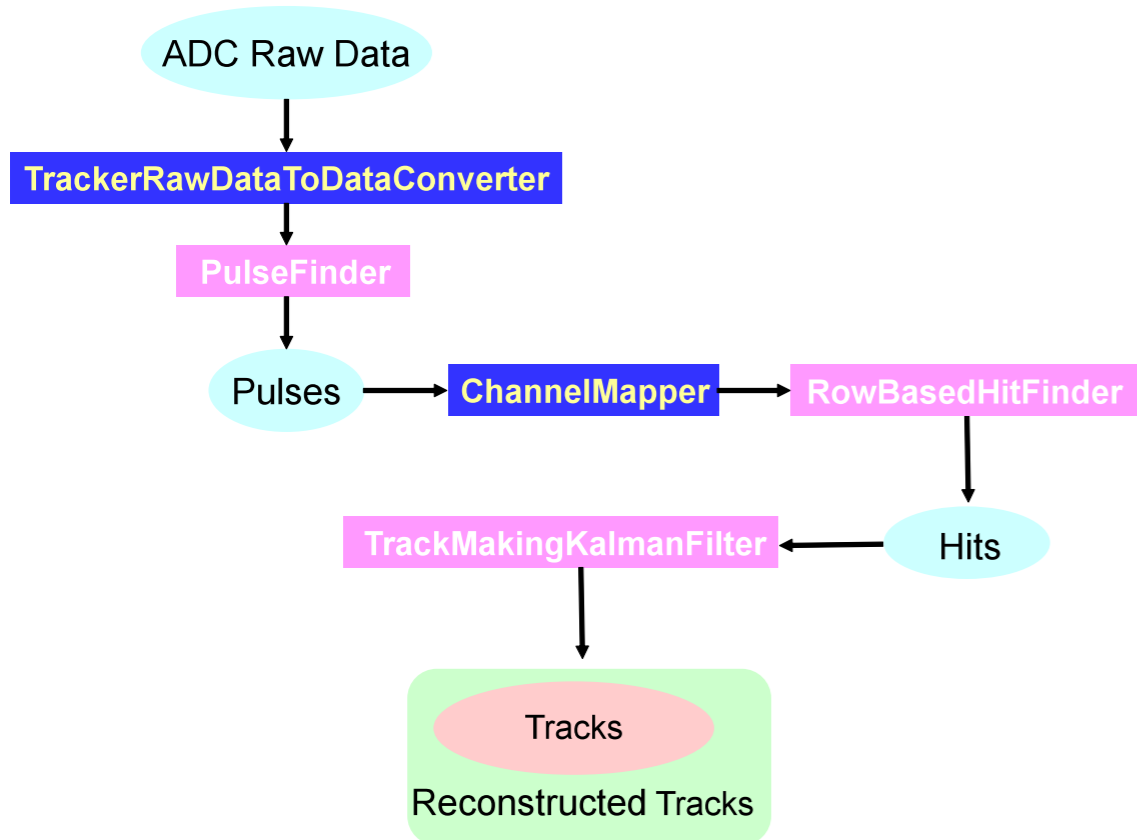
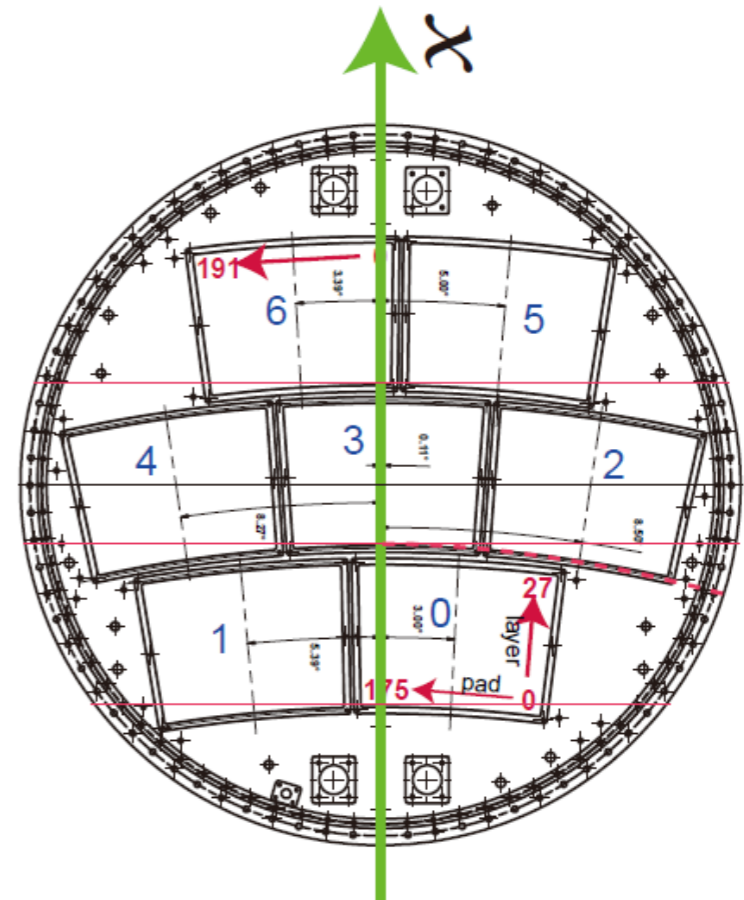
LP1 beam test data analysis by MarlinTPC

Li Bo

LP1 beam test and MarlinTPC



- LP1 beam test: Sep. 2010, at DESY;
- B field: 1T electron beam: 5GeV;
- drift distance: 5, 10, ..., 55cm;
- 3 modules were used.

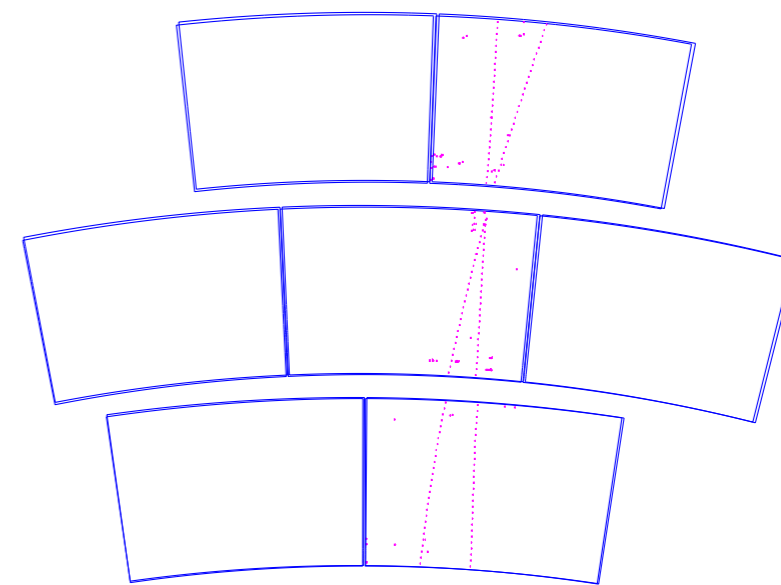
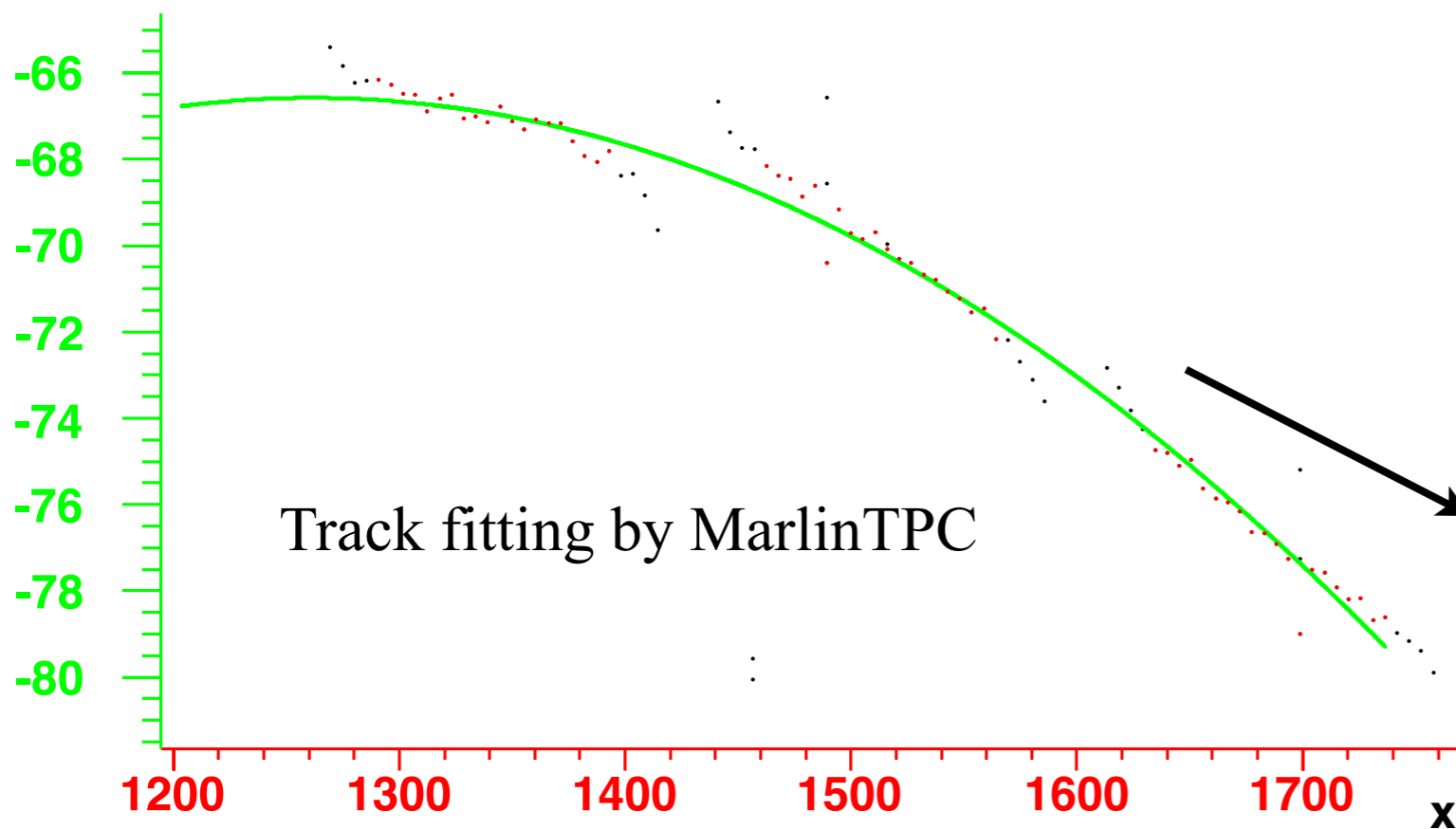


- MarlinTPC is as a tools for track reconstruction;
- The tracking algorithm is based on Kalman filter, and is tested by MC.

Track reconstruction

From the reconstructed tracks, we can see that:

- Detector has good tracking efficiency;
- Momenta of electrons are not the same;



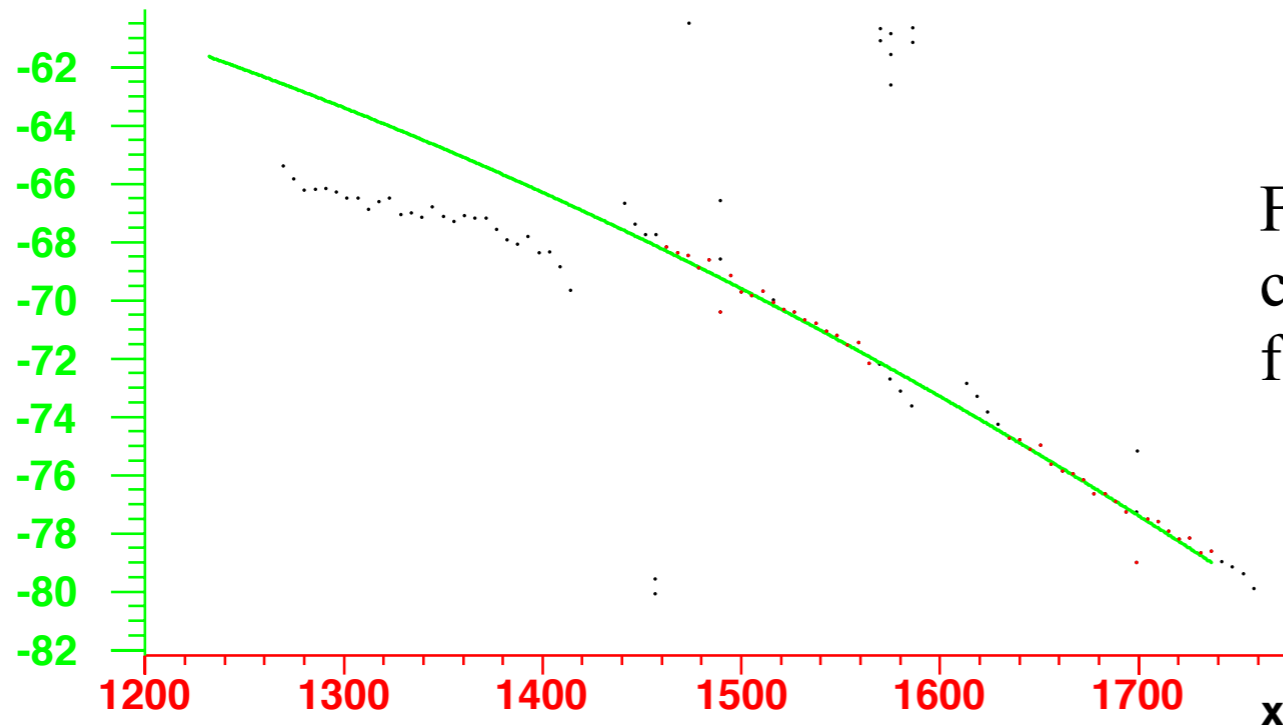
BBQ event display

Distortion:

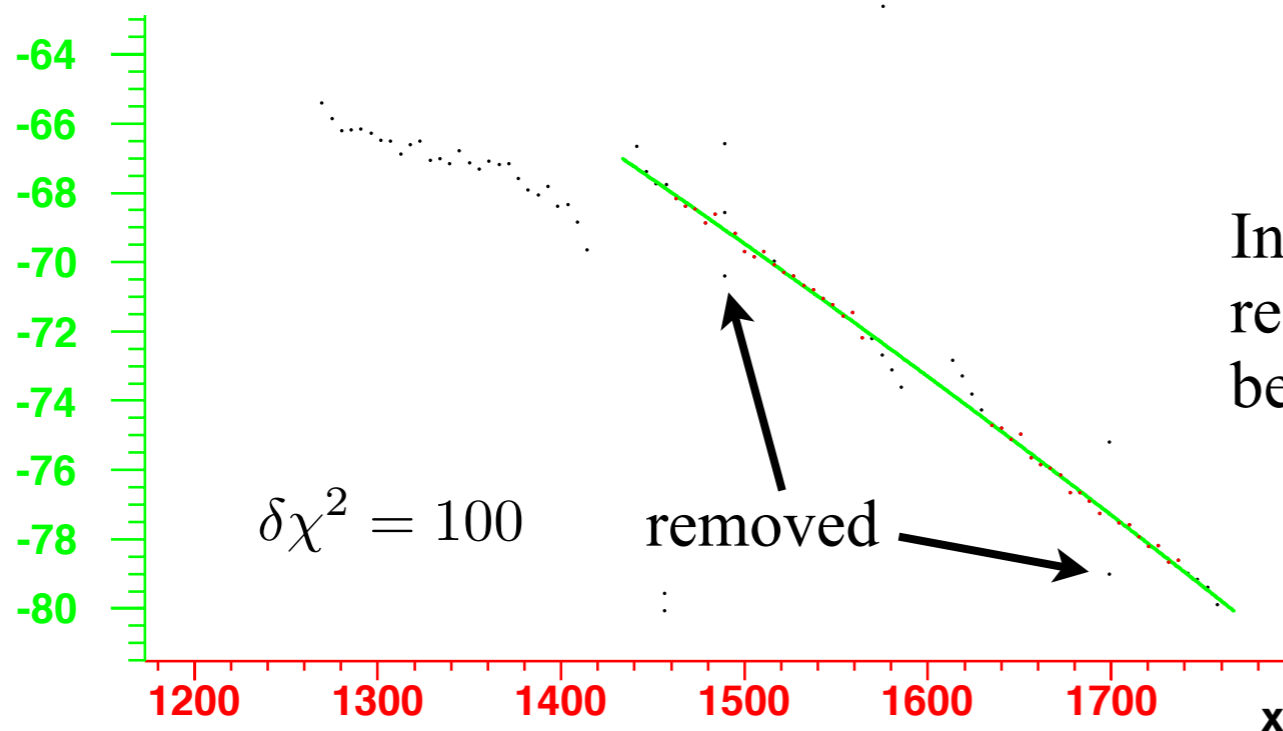
- The distortion at the boundary gives 'S shape' track in each module.
- 'Misalignment' between modules.

In order to take into account hits in 3 modules, a huge delta-chi2 is needed. It may affect the track quality.

Track reconstruction(cont.)



Fitting the track in module 3 and 5, we can see an obvious difference between the fitting line and track in module 0;

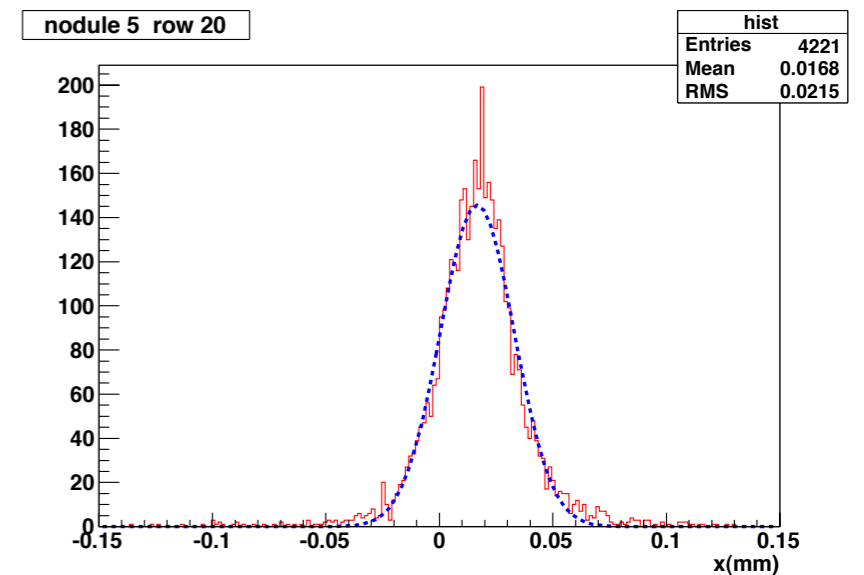
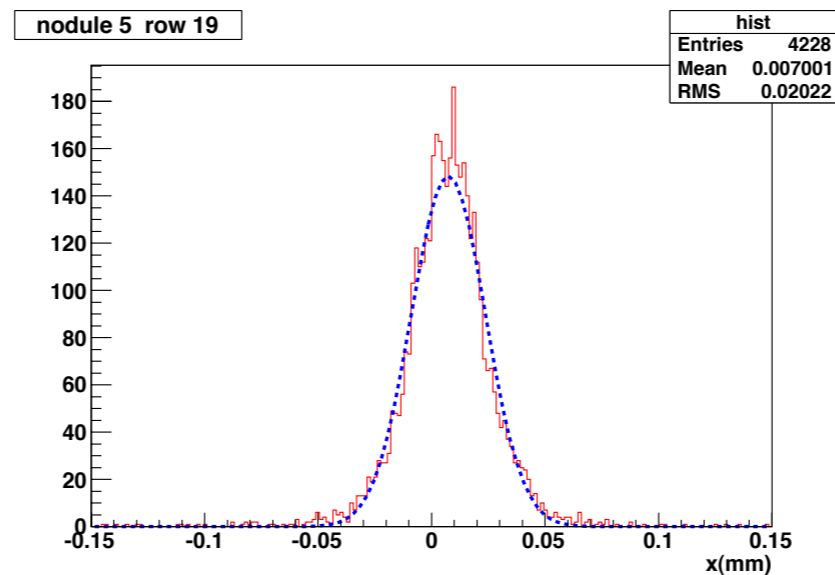
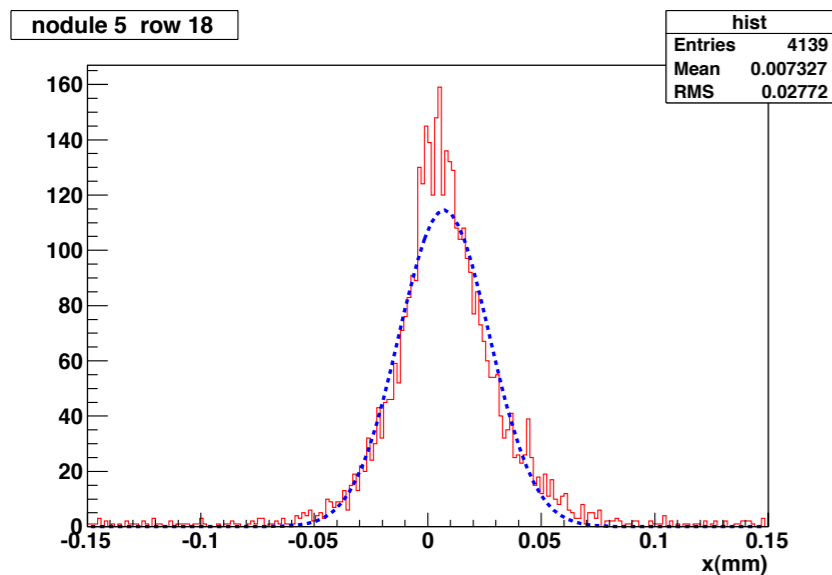
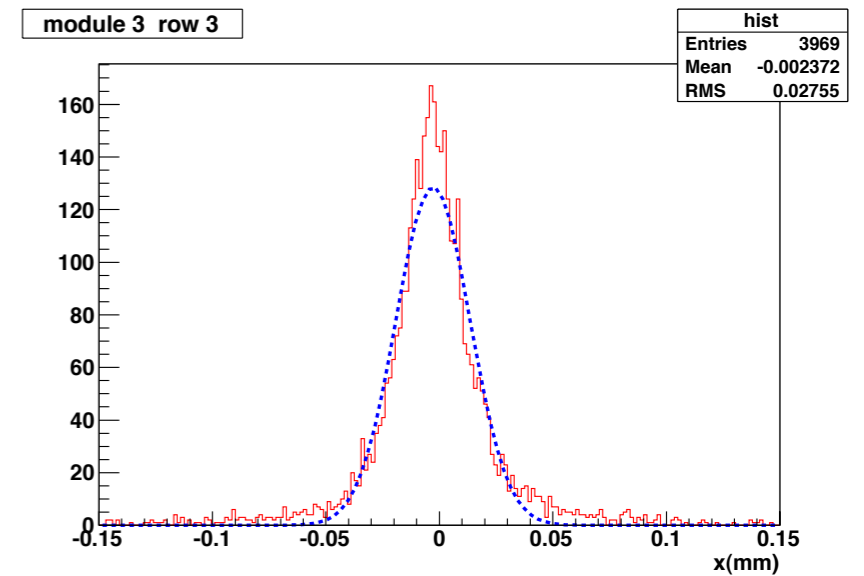
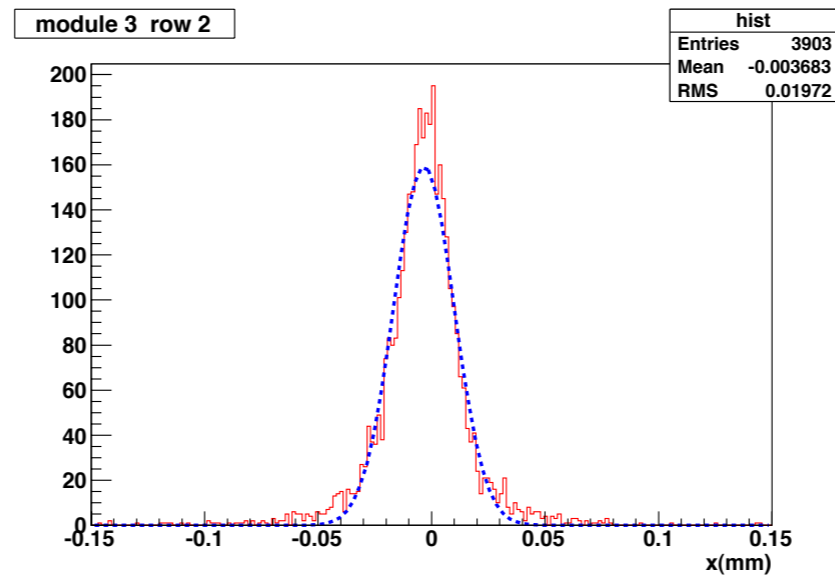
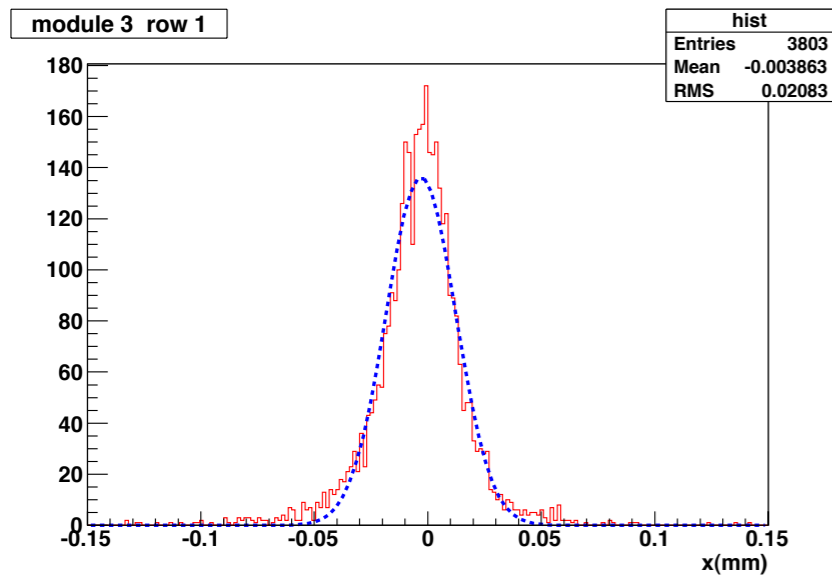


In this analysis, hits in module 3 and 5 are reconstructed. A proper delta-chi2 should be used.

Residual

To get the position resolution of TPC, we need to plot the residual of each row:

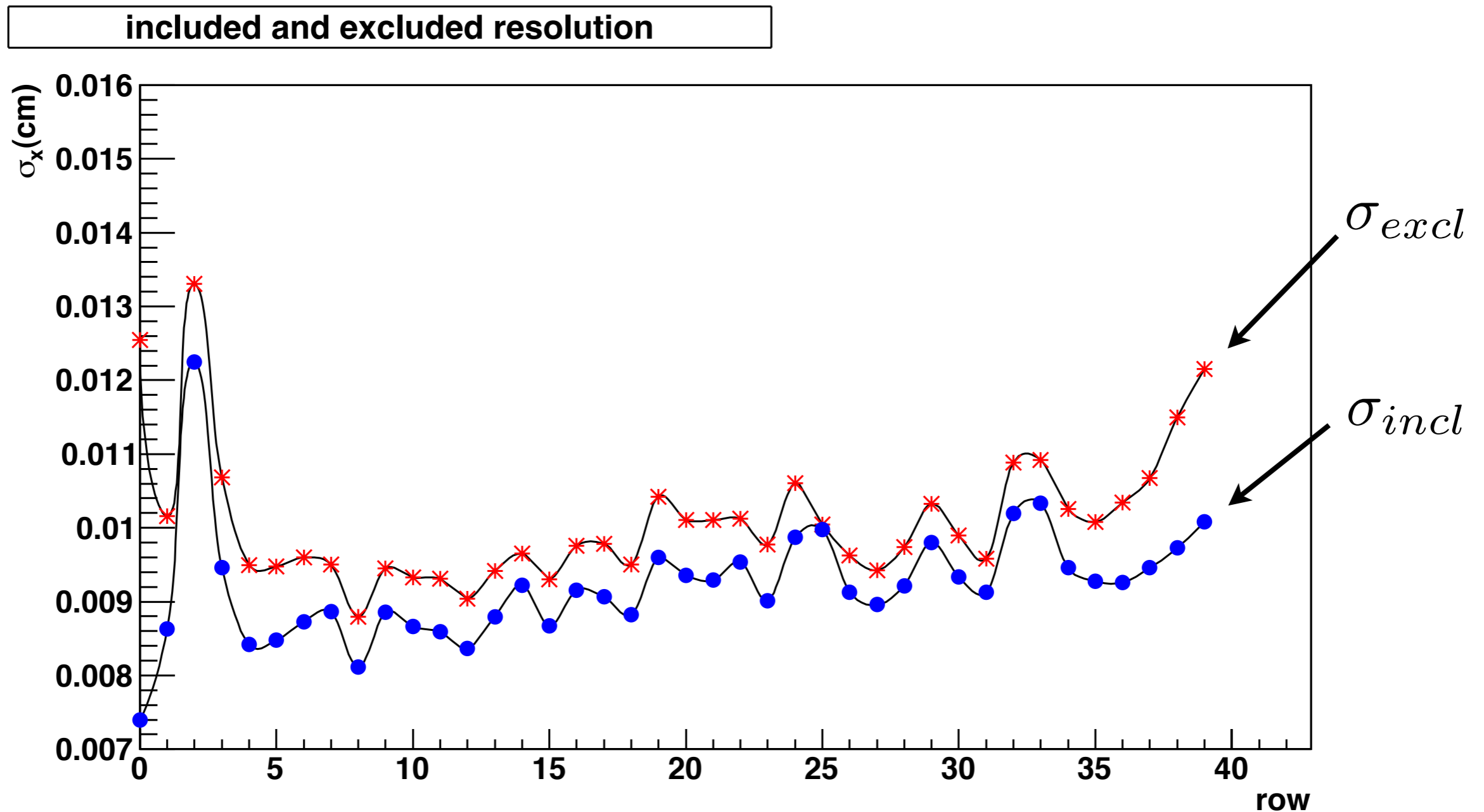
$$\text{residual} = x_{hit} - x_{track}$$



fitting will be improved...

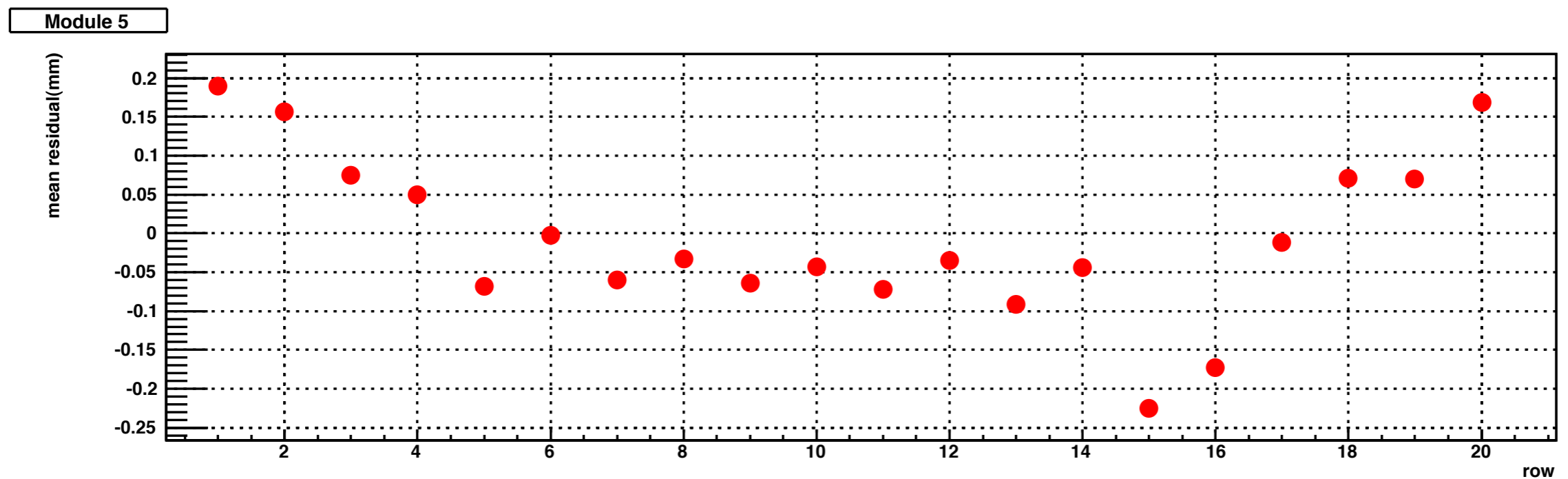
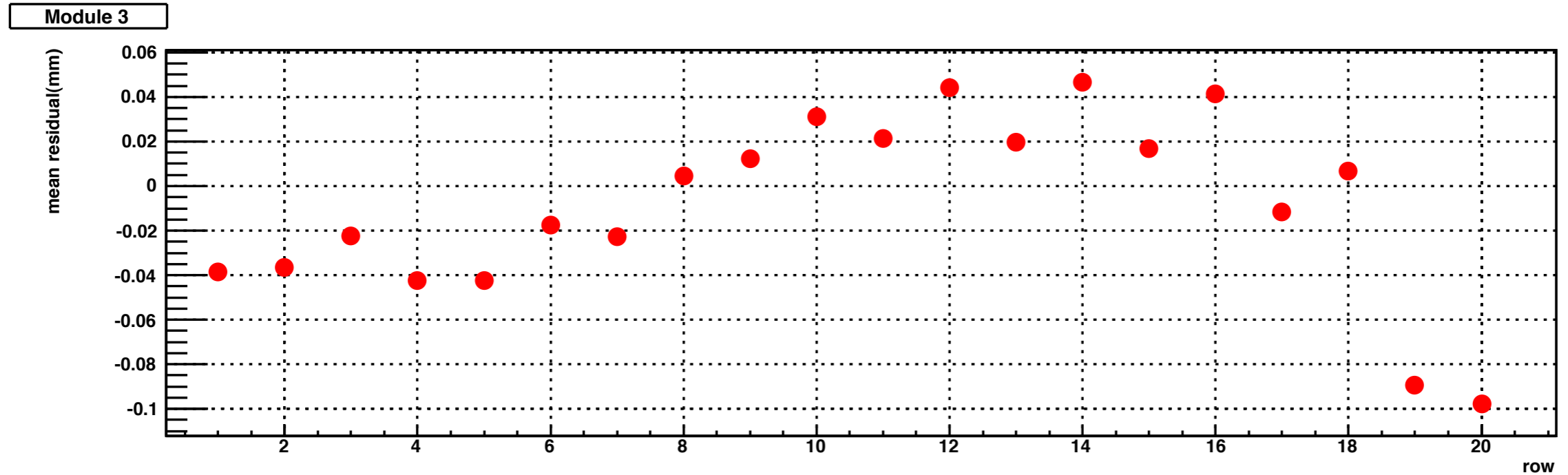
Resolution

- Position resolution is the sigma of residual;
- Because the track is unknown, there are two kinds of resolution:



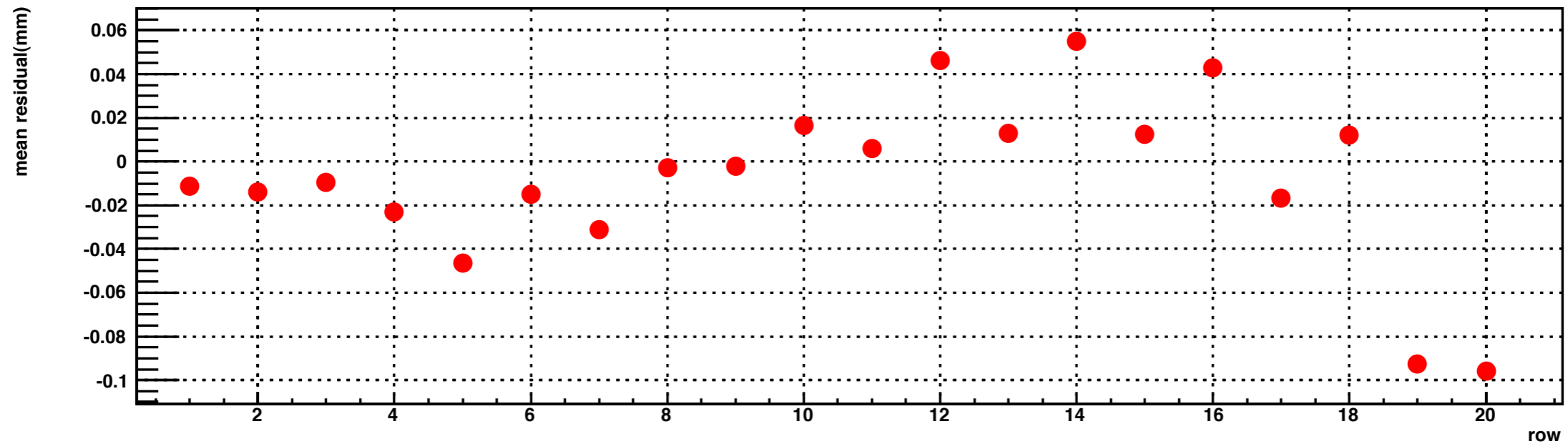
Distortion at 5cm

The mean of residual is the distortion:

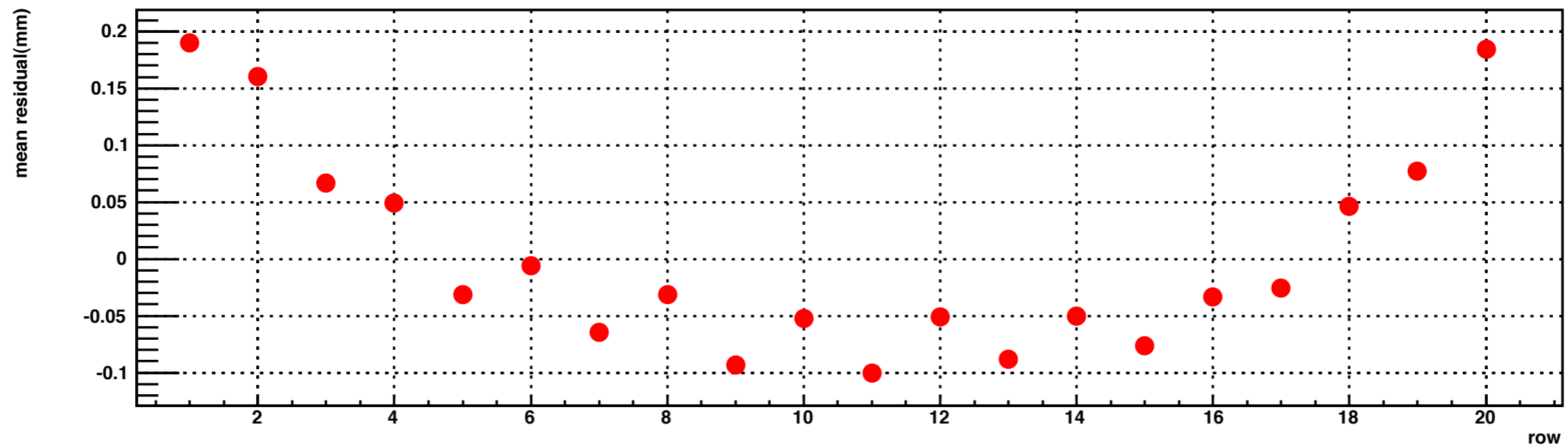


Distortion at 50cm

Module 3



Module 5

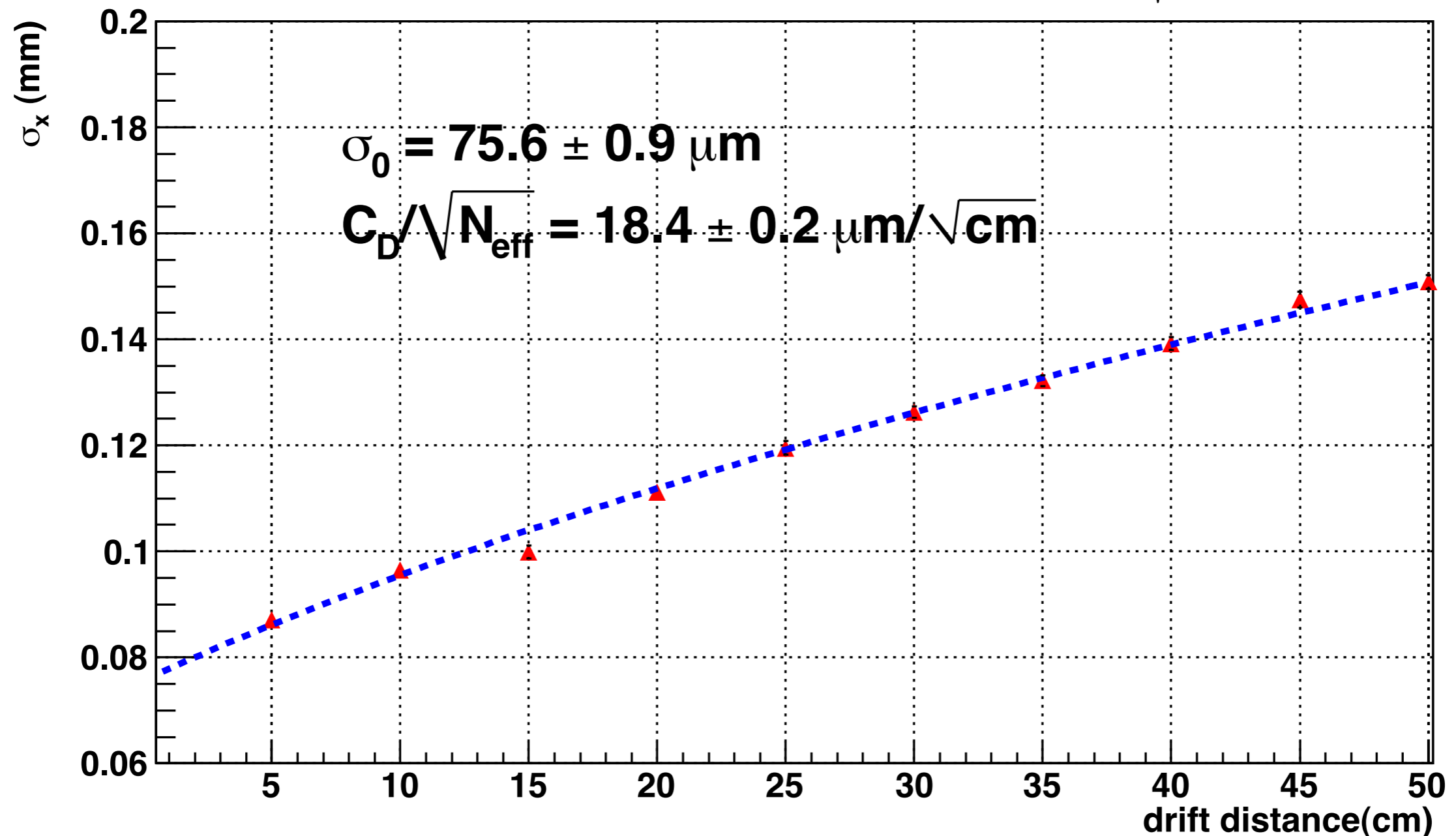


The distortion is not dependent drift distance significantly.

Resolution function

resolution-drift distance

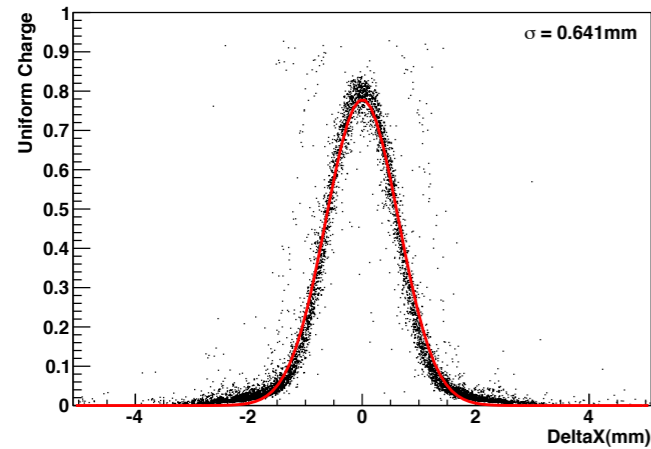
$$\sigma = \sqrt{\sigma_i \cdot \sigma_e} \quad \sigma_x = \sqrt{\sigma_0 + \frac{C_D}{N_{eff}} z}$$



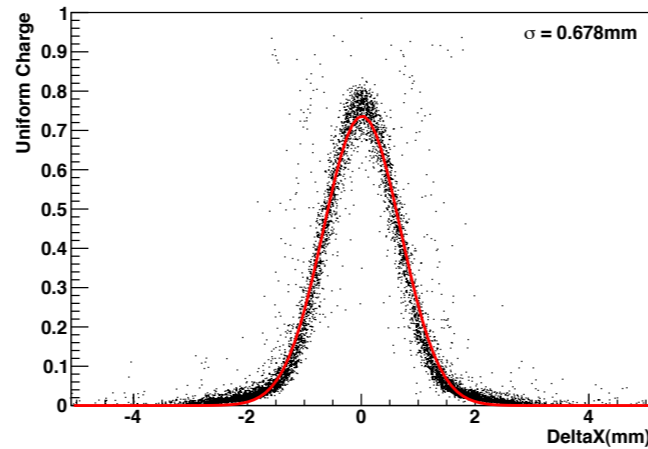
Pad response

Pad response: $Q \sim (x_{puslecenter} - x_{track})$

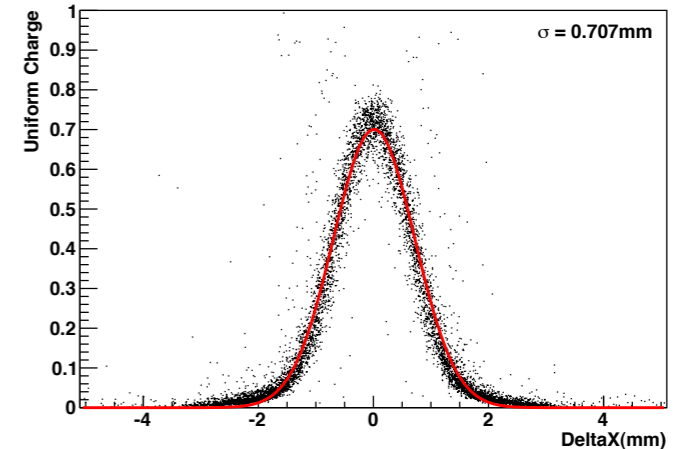
PadResponse at module3 row16, drift distance 5cm



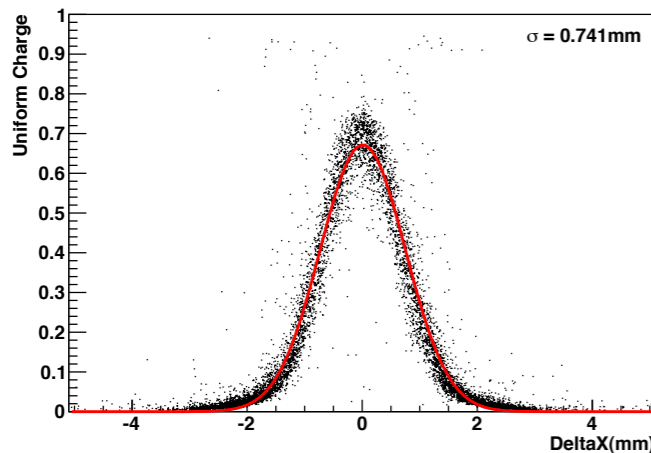
PadResponse at module3 row16, drift distance 10cm



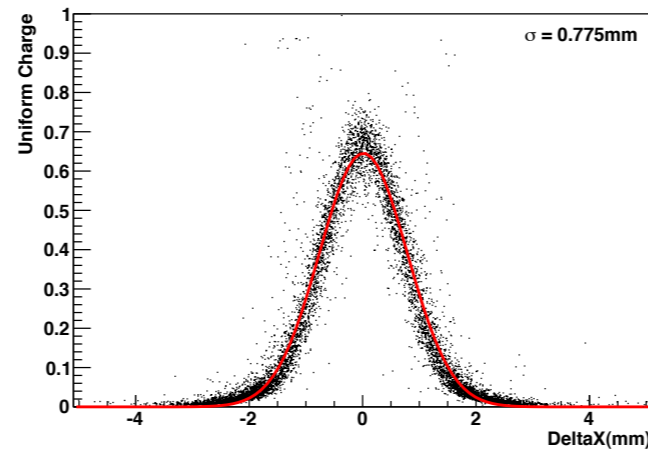
PadResponse at module3 row16, drift distance 15cm



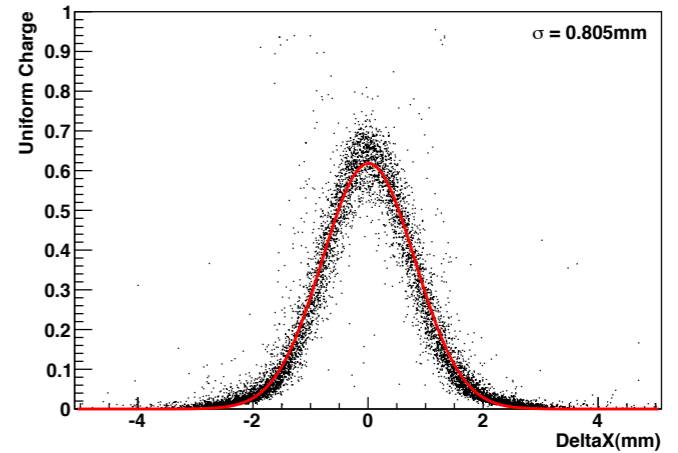
PadResponse at module3 row16, drift distance 20cm



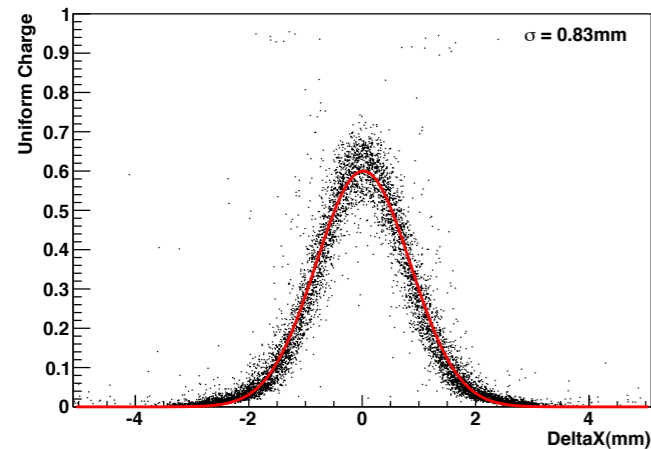
PadResponse at module3 row16, drift distance 25cm



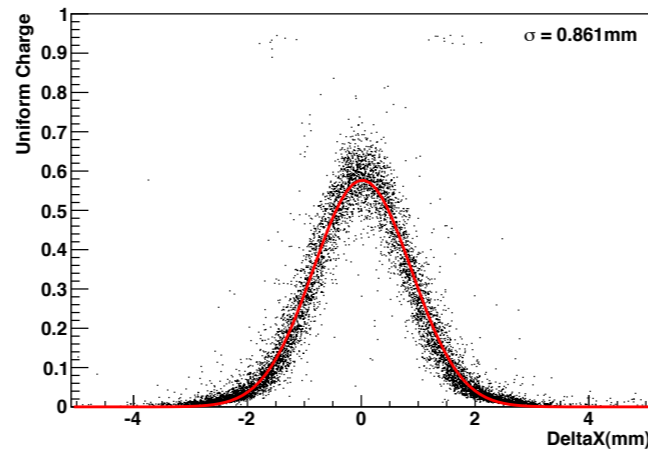
PadResponse at module3 row16, drift distance 30cm



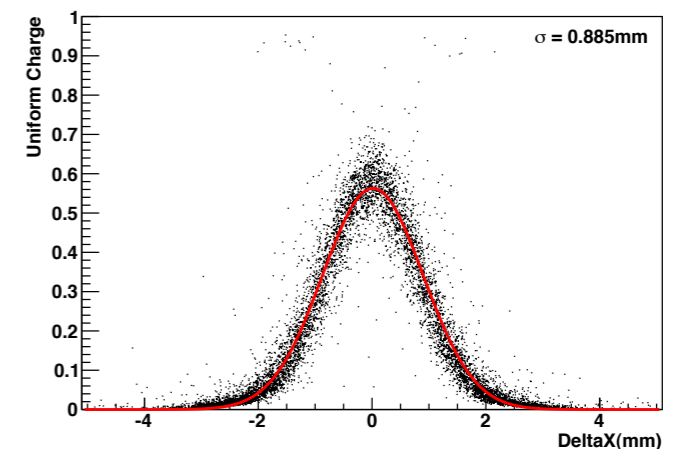
PadResponse at module3 row16, drift distance 35cm



PadResponse at module3 row16, drift distance 40cm

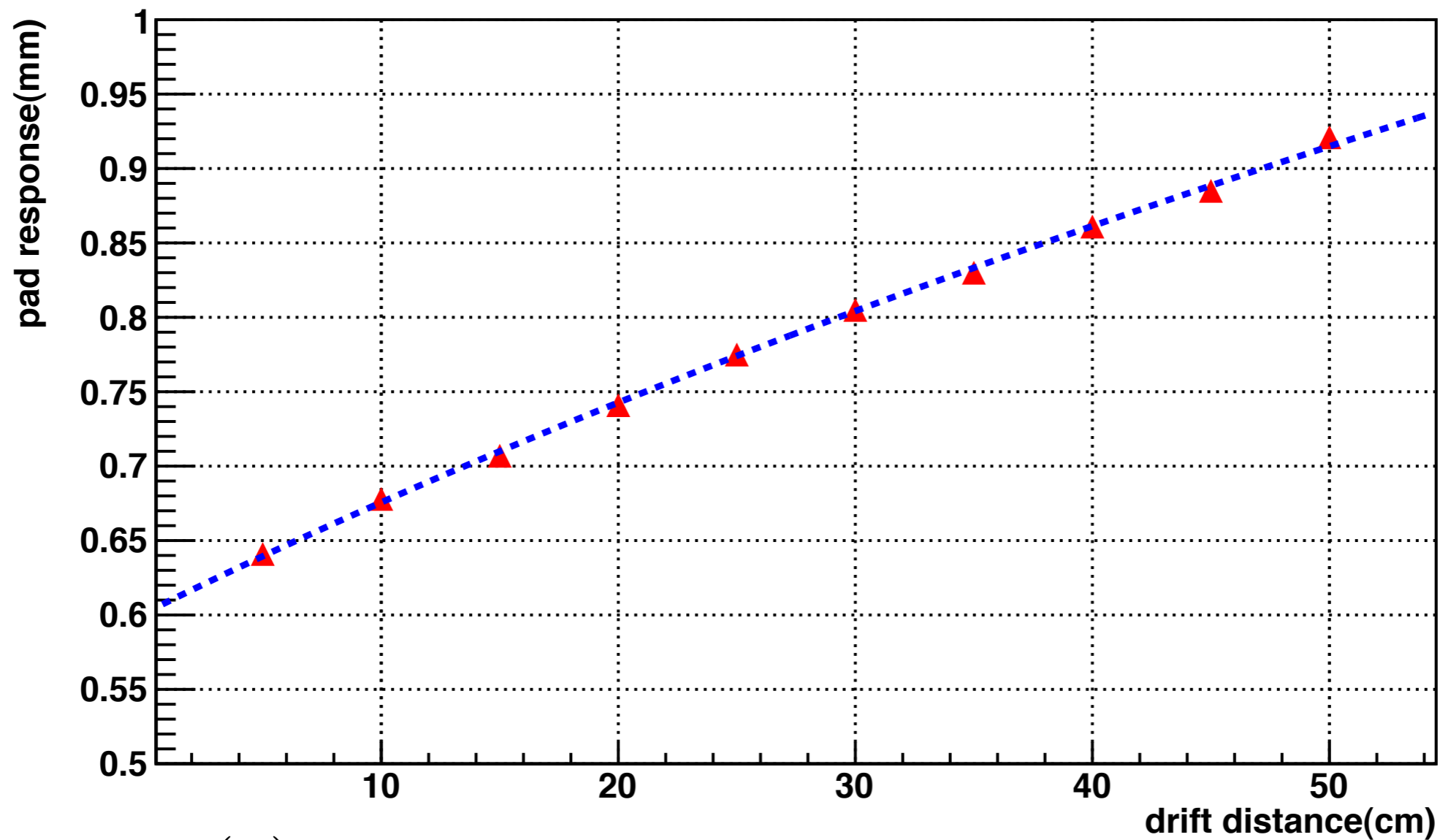


PadResponse at module3 row16, drift distance 45cm



Pad response and drift distance

pad response - drift distance



$$\sigma_{PR}(0) = 601 \mu m$$

$$C_D = 97.5 \mu m / \sqrt{cm}$$

Summary

- Now MarlinTPC can reconstruct tracks for LP1 beam test;
- Almost all information we need can be obtained from MarlinTPC;
- The preliminary result is consistent with that given by YokaRowMon;
- Future work is to check and improve the result.