

Steering & On line Dispersion Measurement Software

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Principle

- ▶ Change corrector strength or quadrupole mover position.
- ▶ Fit BPM reading variation function of that change.
- ▶ Compare with On line mode prediction.

Improvements

- ▶ Can measure multiple correctors and movers.
- ▶ Faster measurements with movers.
- ▶ Estimate correctors strength scale errors.

Principle

- ▶ Measure beam position at each BPM (corrected by BBA).
- ▶ Use corrector or quadrupoles on movers to correct to a reference orbit.

Improvements

- ▶ Minimize corrector strength and mover displacements (no more saturation problems).
- ▶ Gain implemented.
- ▶ Cancellation works properly.
- ▶ Much less badly set correctors observed.

On Line Dispersion Measurement

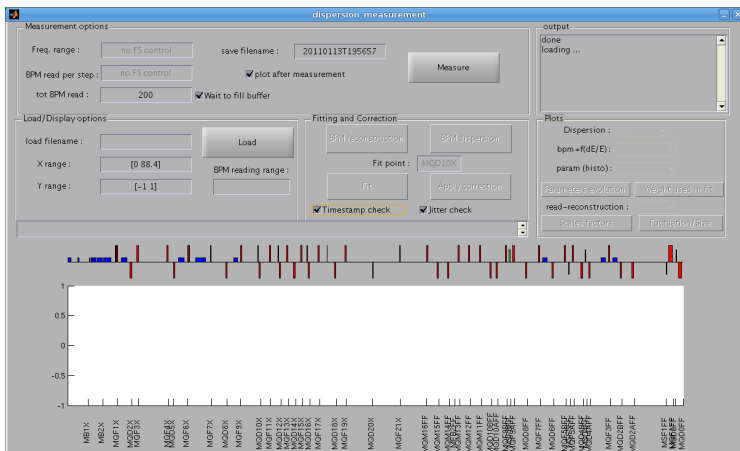
Principle

- ▶ Measure pulse to pulse beam position variation at each BPM.
- ▶ Reconstruct the parameter at injection :
 $x, x', y, y', \frac{\Delta E}{E}$ (weights $\propto \frac{1}{\text{BPM resolution}^2}$).
- ▶ Get the correlation the position measurements and $\frac{\Delta E}{E}$ to get dispersion at each BPM.
- ▶ Fit the dispersion.

Improvements

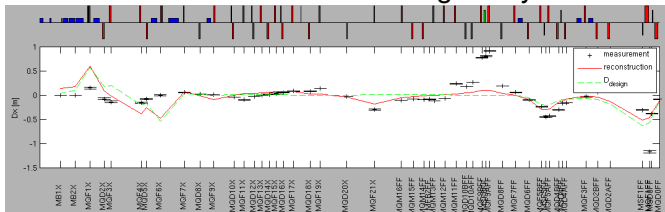
- ▶ Check the synchronization of the different BPMs systems.
- ▶ Detect bad pulses.

Interface

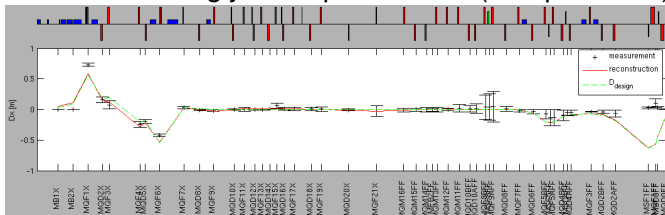


Experimental Problems

- ▶ Good measurement when the ramp is used.
- ▶ Bad measurement otherwise using cavity BPMs.



- ▶ Works well using just stripline BPMs (bad precision).



Problems (2)

Characterization

- ▶ Nominal optics produce very large beam size & fluctuations in FF.
- ▶ Energy reconstruction is much more sensitive to BPM scales errors and modeling errors.

Some Numbers (at QF5FF):

- ▶ horizontal jitter due to energy jitter :

$$D_x = 0.2m \frac{\Delta E}{E} \text{ jitter} = 5.10^{-5}$$

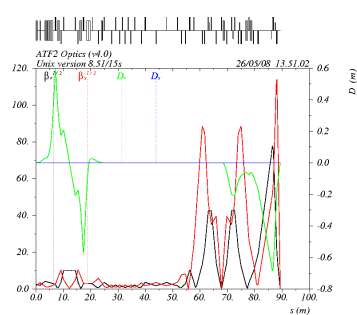
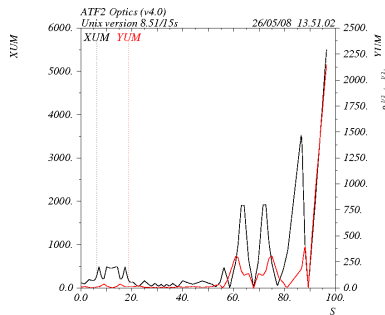
$$\Delta x_{E \text{ jitter}} = D_x \times \frac{\Delta E}{E} \text{ jitter} = 10\mu m$$

- ▶ horizontal jitter due to position and angle jitter :

$$\sigma_x = 2mm \frac{\Delta x_{\text{jitter}}}{\sigma_x} = 20\%$$

$$\Delta x_{\text{jitter}} = \frac{\Delta x_{\text{jitter}}}{\sigma_x} \times \sigma_x = 400\mu m$$

Problems (3)

Transfer Matrix
Measurements

Trajectory Steering

On Line Dispersion
MeasurementConclusion and
Prospects

Explanation

- ▶ Final Doublet BPMs not used
 $\Rightarrow \frac{\Delta E}{E} \propto X(MQF9FF) - X(MQF5FF)$.
- ▶ reason : same β_x and ϕ_x but different D_x values.
- ▶ Subtraction of 2 large numbers to get a small one ...

Planned Solutions

Better model & scales factor determination

- ▶ $\simeq 1\%$ scales factor uniformity required.
- ▶ Same for uncertainty on transfer matrices.
- ▶ **Not realistic.**

Using Ring's BPMs

- ▶ Lots of dispersive regions, small fluctuations.
- ▶ Last turn readings needed.
- ▶ **Not available yet.**

Using Extraction line Chicane

- ▶ Large dispersion, small beam sizes.
- ▶ Not very precise BPMs.
- ▶ Scales factors are not very goods.

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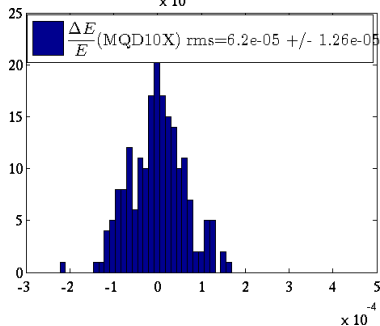
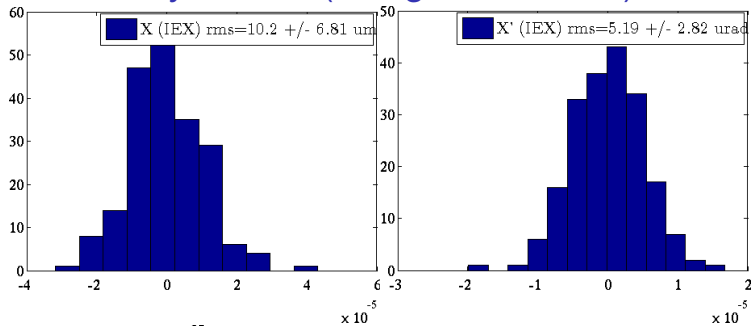
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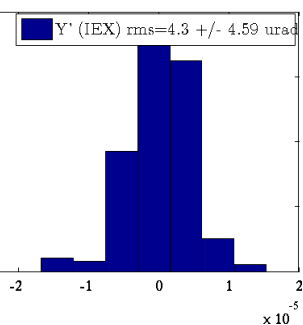
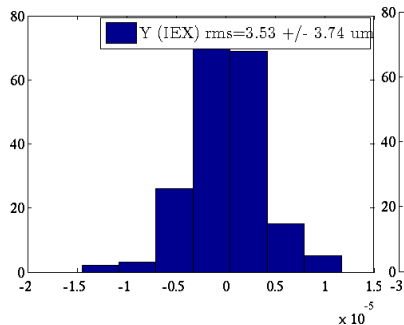
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Preliminary results (using EXT BPMs)



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Conclusion

- ▶ Transfer matrices check application available for all.
 - ▶ Extensively checked.
 - ▶ Has already been used successfully by various people.
- ▶ Trajectory steering application available for all.
 - ▶ Still sometimes need to repeat corrections.
 - ▶ Has already been used successfully by Glen.
- ▶ On line dispersion measurement still under development.

Prospects on the On-line dispersion Measurement

- ▶ Separate energy reconstruction from positions and angles.
- ▶ Will use extraction line BPMs for energy reconstruction.
- ▶ Would benefit from availability of turn by turn DR BPMs ?
- ▶ Any suggestions / remarks ?