

### ILD vertex detector: VXD Integration

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- **x** Overview
- **x** Mechanics
- **x** Cooling
- **x** Cabling
- **x** Material budget



- Mechanics
- Cooling
- Cabling
- Material budget

### Geometry - 1

#### Double sided ladders

- **x** Ladder is equipped with two layers of sensors
  - → ~2mm separation between two layers in one ladder
  - → Material budget [LOI target) 0.16% X0
- **x** 3 layers



#### Single sided ladders

- **x** Ladder is equipped with one layer of sensor
  - → Material budget (LOI target) 0.11% X0
- **x** 5 layers



### Geometry - 2

#### Geometry definition

- **x** Sensitive width of ladders is fixed, an additional 0.5 mm with is provisioned for electronics
- Number and orientation of ladders are computed to reach 100% coverage with some overlap

#### X

- Note: a module is a basic sensing element,
  ~125mm long, equipped with one readout cable
  - → A double sided ladder requires 2 modules, one one each side
  - → A 250 mm long ladder requires 2 modules for one length

layer	radius (mm)		width (mm)		length (mm)		# ladders		# modules	
	single	double	single	double	single	double	single	double	single	double
1	15	16/18	11	11	125	125	10	10	10	20
2	26		15		250		11		22	
3	37	37/39	22	22	250	250	11	11	22	44
4	48		22		250		14		28	
5	60	58/60	22	22	250	250	17	17	34	68
total							63	38	116	132

### **Sensor options**

#### CMOS pixel sensors

- **★** Power dissipation ~100mW/cm<sup>2</sup>
  - → Full detector O(1) KW while active
  - → Factor 1/50(100) for average
- **x** Servicing required

**→** ?

#### CCDs

- **x** FinePixelCCD, ISIS
- ✗ CCD to be kept at <u>low temp</u> Power dissipation ? mW/cm<sup>2</sup>
- **x** Servicing required

**→** ?

#### DEPFET sensors

- **x** Power dissipation ? mW/cm<sup>2</sup>
- **x** Servicing required
  - ➔ Read-out ASICs

#### ! INCOMPLETE SLIDE !

## Ladder prototypes



- **x** Bristol U. DESY, IPHC, Oxford U.
- **x** Running from 2009 to 2012
- ✗ Double sided ladder with 0.3% X0 goal
- Focus on CMOS sensors
  BUT should accommodate other technologies



#### SERWIETE project

- x IPHC, IKFrankfurt, IMEC Leuven
  - → EU-FP7, Hadron Physics 2 project
- Embedding the sensor inside kapton & metal layers
  - → Benefit from ultimate CMOS thickness (20-30µm)
  - $\rightarrow$  Allow very thin metal traces down to 1µm
  - → Material budget for 1 module O(0.1) % X0

#### Studies foreseen

- **x** Power pulsing
- Alignment (AIDA project in EU-FP7)
- x Lorentz force impact



### Mechanics

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## Mokka vs Mecha. model



### 🕒 Mokka (VXD03)

- Simplistic double-sided ladder
  = 2xsingle-sided ladder
  BUT radiation length match LOI target
- Cryostat larger R(+10mm) & z (+10mm)/ mecha. model

#### Mechanical model

- **x** Miss ladder fixtures on support
  - → Support z is -20mm / Mokka
- **x** Miss kapton cables from ladders to pipe
- x Support radius lower (-5mm) / Mokka

# Supporting the VXD

### Layer support

- **x** 1<sup>st</sup> layer is mounted on the beam pipe
- **x** 2<sup>nd</sup> & 3<sup>rd</sup> layers mounted on the Beryllium support
- **x** Beryllium support clamped on beam pipe
- **x** No study on the impact of beam pipe deformation
- **x** No technical drawing available (manpower)

#### Weight

- **x** Ladders:
- **x** Beryllium support:
- **x** Cryostat:
- **x** Cables (up to cryo.):

#### Mechanical alignment

- Initial survey (<100μm) should be good enough</li>
- ✗ <u>Note:</u> IR light go through CMOS sensors (both sides)

#### Mounting concept

x No detail work done



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### **Two options**

#### Room temperature operation

- **x** CMOS-like sensors
- **x** Passive cooling
  - Air flow  $\sim 1$  m/s (for mech. Stability)
  - ➔ Sensor Temp~10-30 °C
  - ➔ Air Temp. Under study
- **x** No real cryostat, nevertheless
  - ➔ Faraday cage needed
  - ➔ May require air separation / SIT
  - ➔ Some thickness of aluminium
- **x** Tubes required on beam pipe
  - ➔ Diameter ? mm

#### Negative temperature operation

- **x** FinePixel-CCD-like sensors
- **x** Active cooling required
  - $\rightarrow$  CO<sub>2</sub> evaporation in tubes
  - ➔ Sensor Temp~ -(5-15) °C
- **x** Real cryostat needed
  - → Backbone 0.5 mm aluminium
  - ➔ Isolation material = 10mm styropor
  - → 0.5(?) % X0
- **x** Tubes required on beam-pipe
  - **→** ?



Mechanics

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## Cables inside the cryostat

 Flat kapton cables running from each ladder to the cryostat at the beam pipe level where they are connected to a small patch panel (cannot go through the cryostat due to faraday cage spec.)

25 deg

16 deg

10 deg

Beam pipe

FTD 0

cables

#### Electrical spec.

- **x** Kapton cable:  $\sim$  50  $\mu$ m thick,  $\sim$ 2cm wide
  - ➔ Realistic mat. budget including metal traces ~0.02 to 0.03 %X0
  - → In Mokka, only 50  $\mu$ m of kapton = 0.018 % X0
- **x** One such cable per module, so PER SIDE
  - ➔ 5 cables running at 10 deg along the beam pipe
  - ➔ 60 cables crossing acceptance between 10-25 deg

Taking into account overlaps: [10, 16] deg : ~0.15% X0 [16, 25] deg : ~0.05% X0

Micro patch panel

**VXD** arrangement

Aluminium Faraday cage+cryostat

Beryllium support

Laver 2

Layer 1

Layer 0

Interaction Point





# Cable outside the cryostat - 1

#### Cables running on the beam pipe, outside the cryostat, ~4m

#### Powers

- **x** Assumptions are:
  - → Sensors are active only during a period of few ms (around the train)
  - → Total instantaneous power between 300 to 600 W (300 Mpixels with 1 to 2  $\mu$ W/pixel)
    - This power range should cover all technologies and geometry (3 double or 5 single layers)
  - → Neglecting the power required from potential additional boards located on the cryostat
  - ➔ Powering voltage is 3 V
  - → Cable length is 4 m
  - → Allowed voltage drop < 0.1V
  - → Powering from both side of the detector, so current load (100 to 200 Amps) is divided by 2/side
- **x** Copper cables:
  - → Section: 0.4 to 0.8 cm<sup>2</sup>
  - → Weight: 4 to 8 g/cm
- **x** <u>Note:</u> the cables dissipate an instantaneous power of  $(0.1 \text{ V} \times 100 \text{ to } 200 \text{ A} = 10 \text{ to } 20 \text{ W})$  only during the ms when the sensors are functional. So, considering power pulsing, the average power dissipated by these cables is at most 5% of the instantaneous power.



# Cable outside the cryostat - 3

Cables running on the beam pipe, outside the cryostat,  $\sim 4m$ 

### Control signals

- *★* ~15 lines with ~15 Amps total <u>per side</u>
- **x** To limit voltage drop to 100 mV with copper cables
  - → Cable copper section ~ 5mm<sup>2</sup>
  - → equivalent to a weight load ~0.5 g/cm



# Cable outside the cryostat - 3

#### Cables running on the beam pipe, outside the cryostat, ~4m

#### Data

- **x** Remember that the data rate is dominated by the e<sup>±</sup> from beamstrahlung
  - → Total hits expected in average per train ~  $3.3 \times 10^6$  (for 5 single-layers) or  $4.7 \times 10^6$  (for 3 double-layers)
  - → Taking into account Poisson fluctuation requires a factor x3
  - ➔ Security factor wrt simulations requires another factor x3
  - → Maximum expected hits overall the detector  $\sim$  45x10<sup>6</sup> hits/train
- **x** Assuming 100 bits to encode one hit (based on an average of 5 pixels per hit)
  - → Total detector information is 4 Gbits for one train (1ms) (this includes security factors)
  - → Non-uniform distribution of ladders: at r~15mm: 130 Mbits/ladder/train, at r~37mm: 30 Mbits/ladder/train, at r~48mm: 7 Mbits/ladder/train
- **x** Assuming we can use optic fibers featuring <u>10 Gbits/s</u>:
  - → OPTION with instantaneous (during 1 ms) readout: data rate ~ 4 Tbits/s → 200 fibers per side clearly, this option requires either a serialization at the support and/or fibers with higher rate
  - → OPTION with delayed readout (during 200 ms): data rate ~ 20 Gbits/s  $\rightarrow$  1 fiber per side
- **x** Difficult yet to estimate the material budget from fibers (assuming 1g/cm for glass):
  - → Probably inner layers will have 1 fiber at each ladder end -> 20 fibers per side
  - → The rest of the layers can be read-out with about 10 fibers
  - ➔ A LOT OF QUESTIONS STILL TO BE ANSWERED THERE



### **Cables for cooling**

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