

# FTD Mokka Driver and Digitisation

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# Outline

## 1 FTD Mokka Driver

- Driver Description
- Driver Modifications

## 2 FTD Digitisation

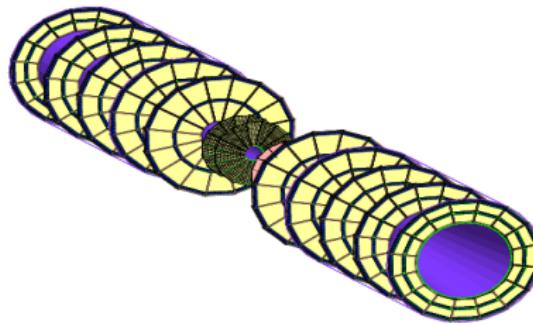
- Adapting to FTD

## 3 Summary

# *1. FTD Mokka Driver*

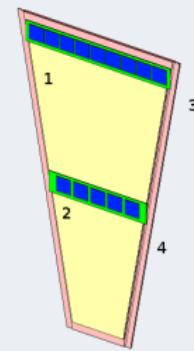
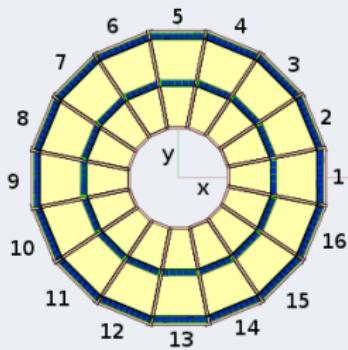
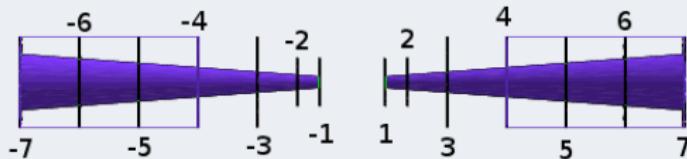
## SFtd06 driver

- Self-scaling driver: significant parameters and positioning defined w.r.t surrounding components (VTX, SIT, SET, beam pipe, ...) following the LOI specifications (see backup)
- Sensitive areas placed over petals generating a disk structures
  - Pixel disks: 1,2
  - Micro-strips disks: 3-7 (Included READ-OUT chips and hybrid)
- Supports:
  - Inner cylinder: supports the whole disks structure w.r.t beam tube
  - Outer cylinder: supports the micro-strips disks (4,5,6,7) w.r.t TPC
- Cables located in the inner cylinder as a cone. **CABLING TO BE UPDATED**



## Elements identification

- Disks (layers): Identified with 4 bits:  $\pm 1, \dots, \pm 7$ , in increasing order of (signed)  $z$ .
- Petals (ladders): Identified with 5 bits (could be 4), in increasing order of  $\phi$ . Disposed in a turbine-like design.
- Sensors: Identified with 3 bits (could be 2), facing the IP and from  $R$  great: 1,2,3,4



## Modifications

- Remove petal rotation around its plane. **Database parameters change**
  - `petal_inclination_angle_support`  $4^\circ \rightarrow 0^\circ$
- Within a disk, alternating petals displaced in z to get overlapping petal edges. **Driver to be modified and database new parameters inclusion**. As the modifications can be introduced in a compatible way with respect the rotated case, the driver is not going to change its name
- Improvement in the petals design including services; slightly change of petal geometry. **Driver changes and database new parameters inclusion**. Design is ongoing

Two equivalent versions of the subdetector in order to do optimisation and comparation studies (between rotated and non-rotated petals), plus a new future version as soon as the mechanical design including power network components would be ready

Subdetector	driver	database	description
SFtd09	SFtd06.cc	ftd08	Current implementation. Petals rotated around its plane
SFtd10	SFtd06.cc	ftd09	Petals non-rotated and displaced w.r.t. the z-disk position
SFtd11	SFtd07.cc	ftd10	As the previous one but with an improved design

# Mokka sub-detector SFtd09

## Database

Parameters from the *ftd08* database well documented in the driver. Table parameters are:

### common\_parameters :

- ftd1\_vtx3\_distance\_z
- ftd7\_ecal\_distance\_z
- ftd1\_sit1\_radial\_diff
- ftd2\_sit1\_radial\_diff
- ftd3\_sit2\_radial\_diff
- ftd4to7\_tpc\_radial\_gap
- beamtube\_clearance
- cables\_thickness
- cable\_shield\_thickness
- outer\_cylinder\_total\_thickness
- petal\_half\_angle\_support
- petal\_wings\_length
- petal\_wings\_thickness
- petal\_y\_ratio
- chip\_strips\_thickness
- chip\_strips\_width
- chip\_strips\_length

### disks table :

- disk\_number
- z\_position\_ReltoTPCLength
- petal\_cp\_support\_dxMax
- petal\_cp\_support\_thickness
- petal\_cp\_support\_holes\_separation
- petal\_cp\_support\_edges\_separation
- petal\_cp\_holes\_width\_support
- petal\_inclination\_angle\_support
- disk\_Si\_thickness
- padUp\_Si\_dxMax
- kapton\_petal\_thickness
- kapton\_petal\_interspace

Note that the units used in the database are:

distance mm

angular degree

## *2. FTD Digitisation*

- Code kindly provided by Zbynek Drásal (Charles University Prague)
- Code currently in use for the digitisation of the *SVD* subdetector in *Belle II* ⇒ Algorithms tested and validated.
- Incorporates (see <https://docs.google.com/viewer?a=v&pid=explorer&chrome=true&srcid=0Bxr58vjAs-zqM2EwZjk1NTEtYzkzYi00YTl5LTK3MWItNWE0MDBjMDA20WQ1&hl=ca>):
  - Digitisation of micro-strips:
    - adapted to barrel and forward geometries
    - drift in electric field
    - diffusion due to multiple collisions
    - Lorentz shift in magnetic field
    - mutual micro-strip crosstalks (dependent on AC/DC coupling)
    - electronics noise
  - Clustering: cluster finding algorithm based on COG (centre of gravity) method (cluster size is lower than 3) or on head-tail analog method (cluster-size is equal or higher than 3). Transform electric pulses into real hits
- Integrated in Marlin framework, two main processors:
  - SiStripDigi:
    - input processor parameters to change digitising algorithms
    - LCIO input collection: *SimTrackerHit*
    - LCIO output collection: *TrackerPulse*
  - SiStripClus
    - LCIO input collection: *TrackerPulse* (output of SiStripDigi processor)
    - LCIO output collection: *TrackerHit*

The geometry information required for data processing is accessed via a geometry interface: *SiStripGeom* which uses the information obtained from a given xml file (GEAR constructed). This class encapsulates the detector stuff and manage the methods related with it; the main processors (digitiser and clustering) use the interface to extract all the detector information needed.

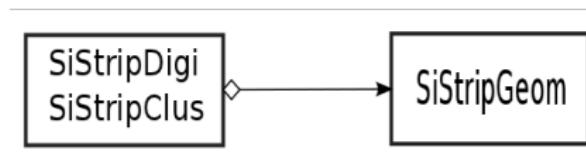
⇒ Potentially can be used for any micro-strip based subdetector: FTD, SIT, SET, ETD

- In order to adapt the processor to FTD (or others subdetectors), we have identified the next issues:
  - ① Decouple the geometry interface from the type of subdetector in order to re-use the digitising processor
  - ② Modify the geometry interface to the FTD geometry
  - ③ It will be easier to adapt if previously the FTD description is included in GEAR

# FTD Digitisation

Decoupling the geometry interface

The processors (*SiStripDigi* and *SiStripClus*) use an instance of *SiStripGeom* to deal with the geometry of some concrete detector



*SiStripDigi.cc*

```
void SiStripDigi::init()  
{  
    ...  
    _geometry = new SiStripGeom();  
    ...  
}  
  
void SiStripDigi::processEvent(LCEvent *evt)  
{  
    ...  
    // Uses the accesors of _geometry  
    ...  
}
```

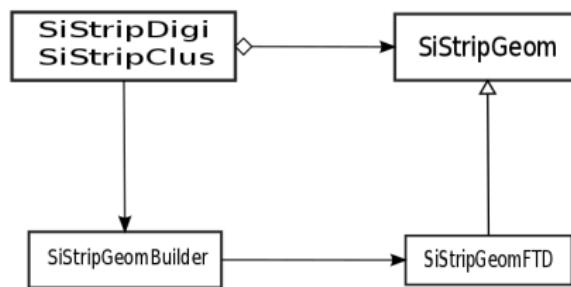
*SiStripDigi.h*

```
class SiStripDigi : public marlin::Processor  
{  
    ...  
protected:  
    SiStripGeom *_geometry;  
    ...  
}
```

# FTD Digitisation

## Decoupling the geometry interface (2)

Introduced a builder (*SiStripGeomBuilder*) used by the processors in order to instantiate the concrete *SiStripGeom* representation (FTD,SET,SIT or ETD).



- *SiStripGeomFTD* is a derived class of *SiStripGeom*
- *SiStripGeom* contains pure virtual method which have to be implemented in the concrete classes: methods which are subdetector dependent
- Each subdetector responsible can focussed in the concrete class implementation (*SiStripGeomFTD*, *SiStripGeomSIT*, ...)
- The builder decides which concrete class to instance via an input parameter

# FTD Digitisation

## Decoupling the geometry interface (3)

### SiStripDigi.h

```
class SiStripDigi : public marlin::Processor
{
    ...
protected:
    SiStripGeom * _geometry;
    ...
}
```

### SiStripDigi.cc

```
void SiStripDigi::init()
{
    ...
    _geometry = SiStripGeomBuilder::Build(subdetector);
    ...
}
```

### SiStripGeomBuilder.cc

```
SiStripGeom *SiStripGeomBuilder::Build(const
                                         std::string & detector )
{
    SiStripGeom *p = 0;

    // Building the concrete SiStripGeom
    if( detector == "FTD" )
    {
        p = new SiStripGeomFTD("FTD");
    }
    //else if( detector == "VXD" )
    //{
    //    p = new SiStripGeomVXD();
    //}
    // Add another type here and codify a new concrete
    // class derived from SiStripGeom
    else
    {
        streamlog_out(ERROR) <<
            "Detector_type_unknown:_" <<
            detector << std::endl;
        exit(-1);
    }
    return p;
}
```

- FTD Mokka Driver

- Shown a brief description of the subdetector
- Decided some modifications:
  - Change the turbine-like design to petals positioned perpendicular to Z-axis
  - Some improvements in the mechanical design are planned, this will include service cabling (DC/DC convertors, opto-links,...)

- FTD Digitisation

- Code provided by Zbnynek Drásal, used in Belle collaboration for the SVD detector
- Trying to adapt to our subdetector requirements:
  - Introduced a builder mechanism to allow use this code with all micro-strips subdetector
  - Working on the adaptation of the geometric interface
  - Working on implementation of FTD in GEAR

(auto) **Deadline: 2nd week of August**

# BACKUP

## Parameters set passed to Mokka to load the FTD stand-alone

```
/Mokka/init/globalModelParameter SIT1_Half_Length_Z 371.309
/Mokka/init/globalModelParameter SIT2_Half_Length_Z 644.906
/Mokka/init/globalModelParameter SIT1_Radius 165
/Mokka/init/globalModelParameter SIT2_Radius 309
/Mokka/init/globalModelParameter TUBE_IPOOuterTube_end_z 230
/Mokka/init/globalModelParameter TUBE_IPOOuterTube_end_radius 24
/Mokka/init/globalModelParameter TUBE_IPOOuterBulge_end_z 2364.5
/Mokka/init/globalModelParameter TUBE_IPOOuterBulge_end_radius 184
/Mokka/init/globalModelParameter Ecal_endcap_zmin 2450
/Mokka/init/globalModelParameter TPC_Ecal_Hcal_barrel_halfZ 2350
/Mokka/init/globalModelParameter TPC_inner_radius 329
/Mokka/init/globalModelParameter TUBE_IPOOuterBulge_start_z 150
/Mokka/init/globalModelParameter TUBE_IPOOuterBulge_start_radius 24
/Mokka/init/globalModelParameter VXD_length_r3 125
```

# LOI specifications for FTD

Disk Number	$z_{pos}$ (mm)	$R_{inner}$ (mm)	$R_{outer}$ (mm)
1	220	39	164
2	371.3	49.6	164
3	644.9	70.1	308
4	1046.1	108.3	309
5	1447.3	130.	309
6	1848.5	160.5	309
7	2250	190.5	309