# Vertex-Detector R&D for CLIC

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### Outline

- •Requirements
- •Machine environment and backgrounds
- •Simulation layouts
- •Sensor- and readout-technology R&D
- •Power delivery / power pulsing and cooling

### Requirements

- Integral part of tracking systems (in particular for low  $p_T$ )
- Efficient tagging of heavy quarks + tau leptons through precise determination of displaced vertices:

$$\sigma(d_0) = \sqrt{a^2 + b^2 \cdot \operatorname{GeV}^2/(p^2 \sin^3 \theta)}$$

 $a \approx 5 \mu m$   $b \approx 15 \mu m$ 

- → Good single point resolution:  $\sigma_{SP}$ ~3 µm
- → Low material budget: X  $\leq$  0.2% X<sub>0</sub> / layer (incl. cooling)
- Full coverage down to low polar angles  $\theta_{min} \sim 7^{\circ}$
- Few % occupancy despite large background rates
- Time stamping with ~10 ns accuracy, to reject background
- To date: no technology option available fulfilling all requirements
- → Simulation studies: impact of layout on performance
- → Integration/Assembly + power-pulsing + cooling studies
- → R&D on sensors & readout

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# **CLIC** machine environment

	CLIC at 3 TeV		
L (cm <sup>-2</sup> s <sup>-1</sup> )	5.9×10 <sup>34</sup>		
BX separation	0.5 ns	K	Drives timina
#BX / train	312		requirements
Train duration (ns)	156	K	for CLIC detector
Rep. rate	50 Hz		
$\sigma_{\rm x}$ / $\sigma_{\rm y}$ (nm)	≈ 45 / 1	very small beam size	
σ <sub>z</sub> (μm)	44		



# Beam-induced backgrounds





Main backgrounds in detector:

- •Incoherent e\*e\* pairs: 60 particles / BX
- •yy→hadrons: 54 particles / BX
- → Need pile-up rejection
- → Need to include background in simulation

#### Backgrounds in inner tracking region



Occupancies per r/o cell and bunch train and radiation exposure, including clustering and safety factors:

Region	Readout granularity	Max. occup.	NIEL [n <sub>eq</sub> /cm²/y]	TID [Gy/y]
VXB	20 µm x 20 µm	1.9 %	4x10 <sup>10</sup>	200
VXEC	20 µm x 20 µm	2.8 %	5x10 <sup>10</sup>	180
FTD pixels	20 µm x 20 µm	0.6%	2.5x10 <sup>10</sup>	50
FTD strips	10 cm x 50 μm	290 %	1x10 <sup>10</sup>	7
SIT	9 cm x 50 μm	170 %	2x10 <sup>9</sup>	2
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# Beam pipe

Requirements for beam pipe:

- Provide good vacuum  $\rightarrow$  leak tightness
- Minimise multiple scattering  $\rightarrow$  small amount of material in central part
- Allow for placement of Si layers close to IP  $\rightarrow$  small radius
- Stay outside region of high background occupancy  $\rightarrow$  lower limit on radius
- Shield against back scatters from forward region  $\rightarrow$  thick conical part outside VTX acceptance

Implementation in simulations:

- Central Beryllium part:
  - CLIC\_ILD: d=0.6 mm, R=29.4 mm (B=4 T)
  - CLIC\_SiD: d=0.5 mm, R=24.5 mm (B=5 T)
  - Safe w.r.t. backgrounds, vacuum collapse, leak tightness (D0, CDF experience in run II)
  - Unlike ILC: no extra shielding, due to low expected levels of incoh. synchrotron radiation (t.b.c.)
- Forward conical part:
  - 4 mm iron, to shield against back scatters from forward region
  - Pointing to interaction point  $\rightarrow$  no extra material inside tracking acceptance



#### CLIC vertex detectors simulation layouts



### Modules and stave layout (post-CDR)

- First ideas for post-CDR CLIC\_ILD module + stave layouts (various options)
- Based on CLIC\_ILD\_CDR simulation design, taking into account constraints from hybrid sensor + readout concept
- Minimize cabling + active components through vertical integration (TSV) and stitching between neighboring chips
- Design has to take into account inactive regions and Lorentz-angle effect



## **Pixel-detector technology options**

- <~  $25x25 \ \mu\text{m}^2$  pixel sizes  $\rightarrow$  need small feature sizes
- Time-stamping ~10 ns → need high-resistivity sensor
- ~0.2% material/layer  $\rightarrow$  corresponds to ~200 µm silicon (incl. support + cables)
- 156 ns bunch train every 20 ms  $\rightarrow$  trigger-less readout, power pulsing
- Radiation exposure <10<sup>11</sup>  $n_{eq}/cm^2/yr \rightarrow radiation hardness not a major concern$

#### Possible technology development paths:

#### 1) Hybrid or multi-tier technologies

- Thinned high-resistivity fully depleted sensors, ~50  $\mu$ m thick
- Fast, low-power highly integrated readout chip,  $\sim$ 50  $\mu$ m thick
- Low mass interconnects
- Pros: factorization of sensor + readout R&D;
   r/o chips profit fully from advancing industry standards
- Cons: interconnect difficult/expensive; harder to reduce material

#### 2) Integrated technologies

- Sensor and readout combined in one chip or 3D integration of multiple tiers
- Charge collection in epitaxial layer (typically < 1  $\mu$ m)
- Pros: allows for very low material solutions; synergy with R&D for ILC detectors
- Cons: harder to achieve good time resolution and sufficient S/N

# Hybrid approach: R&D examples

- Thinned high-resistivity fully depleted sensors
  - Several producers can make ~50  $\mu m$  thick silicon sensors (e.g. IZM, Micron, CNM)
  - Handling + flip-chip bonding is a concern, in particular for larger structures
- Fast, low-power readout ASICs in Very-Deep-Sub-Micron (VDSM) technology
  - Timepix3 ~2013: 130 nm IBM CMOS, 55  $\mu$ m<sup>2</sup> pitch
  - SmallPix ~2013: 130 nm IBM CMOS, ~40 μm<sup>2</sup> pitch (medical applications)
  - CLICPix ~2015: 65 nm, 25  $\mu$ m<sup>2</sup> pitch
  - $\rightarrow$  CLICPix demonstrator prototypes ~2013: 64x64 pixel array
- Low-mass interconnects and pixel connectivity
  - Through Silicon Vias (TSV):
    - fan out ASIC contacts to backside through vertical conducting channel
    - avoids dead areas from wire-bonding pads around the chips
    - Example: CEA-Leti via-last process with Medipix 3, prototypes under test
  - Lateral interconnectivity
    - Edgeless sensors
    - Stitching of neighboring chips

### Silicon device simulation with TCAD

- Thin sensors (~50  $\mu$ m) + small pitch (20-25  $\mu$ m<sup>2</sup>) + fast shaping + digitization
- $\rightarrow$  Need to investigate:
  - Charge rise time, collection efficiency, sharing between pixels, signal/noise
  - Dependence on momentum, angle, electric field
  - Lorentz-angle effects from magnetic field •
- Use TCAD process and device simulation •
- Results to be validated with prototypes in test beam



Over-depletion reduces effect

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# Charge sharing



- Over-depletion increases E-field, thereby reduces charge spread and charge sharing
- Charge sharing can improve resolution
   through interpolation (with analog readout)
- However: signals below threshold are lost





(**m**n) X∆

# Signal rise time

- Need time-stamping precision of ~10 ns, to suppress beam-induced backgrounds
- $\rightarrow$  Peaking time in sensor should be <<10 ns, to optimize S/N and reduce effect of time walk
- electron collection faster than holes  $\rightarrow$  favors n-in-p sensors

Example:

- 55 x 55 μm<sup>2</sup> pixels
- 50  $\mu$ m thinned n-in-p sensor,  $\rho$ =10 kOhm cm
- ~2 ns peaking time with weak dependence on  $V_{\rm bias}$
- For higher V<sub>bias</sub> better S/N expected after shaping, due to higher peak value; also less time walk due to reduced dispersion



# Background simulation with realistic clustering

- Incoherent pairs in post-CDR CLIC\_ILD vertex detector model
- 50 µm sensor n-in-p
- Timepix-like readout
- AllPix + MAFALDA framework for digitization + reconstruction
- EM Liverpool physics list, for low-energy, delta rays
- Uses parameterized input from TCAD + Testbeam results



- Observed cluster sizes for 20x20 μm pixels in innermost vertex barrel layer:
  - 5-10 hits per cluster, depending on theta (for CDR studies: assumed 5 hits)
  - Resulting train occupancies ~ 0.5%-1% (excluding safety factors)
- Next step: include  $\gamma\gamma \rightarrow$  hadrons
- Results can be used to improve full-detector simulation with overlay of backgrounds



#### CLICPix 65 nm test structures

- 65 nm technology allows for performance improvements w.r.t. 130 nm:
  - Smaller pixel sizes (10-30% less area for analog part, 60% less for digital part)
  - More functionality in each pixel
  - Lower noise (due to lower capacitances)
- Test structures produced in 65 nm multi-project wafer run:
  - Radiation and functional tests
  - Total size: 3x4 mm
  - Divided in three sub-chips:
  - 1 chip for analog structures and test devices
    - 1 pad per multiple gates
    - Analog structures
  - 1 chip w/ test structure/devices
    - 1 pad per gate
    - 142 total pins
  - 1 chip for digital logic
    - 64 kbit Shift-register
    - 56kbit Memory
    - Ring oscillator (1025 gates)



#### CLICPix 65 nm test structures: results

- Measurements on Test pixels
- Results according to simulations
- Improved radiation tolerance w.r.t. 130 nm observed (TID up 200 Mrad and SEU)
- Results allow for projections to CLICPix performance (e.g. power consumption digital part)

	Simulations	Measurements
Rise time	50ns	65ns
Gain	30mV/ke <sup>-</sup>	29.1mV/ke-
Linearity	5% at 16ke-	5% at 15ke <sup>-</sup>
Noise	55e <sup>-</sup>	60e <sup>-</sup> (70e <sup>-</sup> for ELT channel)



Preamp measurements:

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### CLICPix 65 nm demonstrator chip

Demonstrator chip for next 65 nm MPWR

- First prototype with full pixel-readout functionality
- Submission 2<sup>nd</sup> half of 2012
- Includes 64 x 64 pixel array with 25  $\mu$ m pitch
- Will try to bond to sensor

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- simultaneous 4-bits TOA and 4-bits TOT measurements per pixel (100 MHz reference clock)
- Compression logic allows for sparse readout; Cluster-based compression is being evaluated
- Power saving techniques include clock gating when the pixel is not being read out and power gating (with an external signal) for the analog part when the chip is not acquiring data

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## **CLICPix power-pulsing requirements**

- Overall power budget (driven by air-flow cooling): P<sub>avg</sub> ~ 50 mW / cm<sup>2</sup>
- Estimation of power consumption for analog and digital blocks of CLICPix readout chip
- Based on measurements with 65 nm test-chip and projections from current TimePix
- Power pulsing with On/Idle/Off states, to reduce average power consumption
- Very small duty cycle for analog power is major challenge for design of power delivery/pulsing
- → Requires local energy storage



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# Power delivery concept

- DC/DC converters outside pixel-sensor area
- Power pulsing, to reduce average power consumption
- Flexible Kapton cables for power delivery, controls, readout
- Cabling along ladders integrated in chips (stitching across modules)



HighTec<sup>™</sup> flex Kapton



- Cu on Polyimide
- ~20-50 μm total thickness
- Aim: replace Cu with Al
   → x3.7 less rad. length for same conductivity



Main challenges:

- Cabling has to cope with large and short current peaks in chips (small duty cycle of CLIC machine)
- Combine DC/DC with power pulsing (possibly including local energy storage on the staves)
- Has to work in magnetic field: B = 4-5 T
- Large currents along ladders: stitching technology not established yet

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## Power delivery simulations



Decoupling capacitor close to load helps to reduce spikes + drop in load voltage and to level cable currents
Realistic simulation of transient behavior needs to take into account details of chip response

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# Cooling

- P~500 W in vertex detectors (50 mW/cm<sup>2</sup>)
- Need efficient cooling, meeting material budget requirements
- Several options considered:

#### Forced (dry) air flow

- baseline for barrel region
- no extra material
- $\rightarrow$  following talk by Hubert Gerwig in this session:

http://ilcagenda.linearcollider.org/contributionDisplay.py?sessionId=20&contribId=57&confId=5414

#### **Evaporative CO<sub>2</sub> cooling**

- Option for supplementary cooling in forward disks
- High pressure up to ~70 bar, requires rather thick tubing
- $\sim 2.7 \% X_0$  per tube (incl. coolant)

#### Water cooling

- Option for supplementary cooling in forward disks
- Sub-atmospheric pressure
- Can use thin PEEK pipes  $\rightarrow$  lower material budget than CO<sub>2</sub>, ~0.4% X<sub>0</sub> per tube

#### **Micro-channel cooling**

- Ongoing R&D (e.g. NA62 Gigatracker upgrade)
- Integrate cooling channels in Silicon
- Connectors pose major challenge

# Summary / conclusions

- CLIC environment + physics requirements pose challenging demands on vertex-detector systems
- Presented initial layout proposals meeting those demands
- Examples for active R&D on:
  - sensor + readout technologies
  - Mechanics, cooling
  - Power-delivery and power pulsing
- More details in CLIC vertex-detector working group presentations: <u>http://indico.cern.ch/categoryDisplay.py?categId=2843</u> and in CDR: <u>http://lcd.web.cern.ch/LCD/CDR/CDR.html</u>

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#### Backup slides

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## Material budget vertex region



- Integrated amount of material seen by particles originating from the IP: X/X<sub>0</sub> ~ 1% (at θ=90°, averaged over φ)
- Good agreement full / fast simulation (fast simulation has only ideal cylinders and disks, no module overlaps)

#### Transverse impact-parameter resolution

d₀: distance of closest approach to interaction point in R-phi plane → main benchmark parameter for vertex detector performance Fast simulation: LiC detector toy tool, used for design optimization Full simulation: Geant4-based ILD/SiD frameworks, used for physics studies



#### CLIC\_ILD:

- Both full and fast simulation perform simple Gaussian hit smearing
- Very good agreement between full/fast simulations

#### σ(d<sub>0</sub>) [μm] CLIC\_SiD full sim. p=1 GeV fast sim. p=1 GeV full sim. p=10 GeV fast sim. p=10 GeV full sim. p=100 GeV $10^{2}$ fast sim. p=100 GeV 10 90 80 70 60 50 40 30 20 θ [°]

#### CLIC\_SiD:

 Full simulation models clustering according to parametrization of KPiX readout chip → added realism leads to worse resolution in full simulation, as expected

# Dependence on single-point resolution



- Varied single-point resolution by +- 50% (~ pixel sizes 10x10, 20x20, 30x30 μm<sup>2</sup>)
- Observed change in d<sub>0</sub>-resolution:
  - +- 40% for p = 100 GeV
  - +- 15% for p = 1 GeV
- Resolution close to or better than target values for all cases
- Pixel size is also constrained by:
  - Expected background occupancy
  - Ability to separate adjacent tracks in dense jets

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# Dependence on distance to IP



- Varied distance to interaction point, by changing radii of beam pipe and barrel vertex layers in CLIC\_ILD model
- Observed change in d<sub>0</sub>-resolution:
  - 3.2% / mm for high momenta (parameter 'a')
  - 0.8% / mm for low momenta (parameter 'b')
- Distance to interaction point is constrained by direct hits from incoherent pairs

### Dependence on material



- Very small amount of material in baseline designs
- Realistic models for supports, cabling, cooling not available yet
- Studied sensitivity of d<sub>0</sub> resolution for low momenta on material in beampipe and silicon pixel layers of CLIC\_ILD
- Doubling beam-pipe thickness  $\rightarrow$  ~20% worse resolution at 90°
- Doubling material in silicon layers  $\rightarrow \sim 20\%$  worse resolution at 90°
- Steeper slope in forward region

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### Examples for Integrated Approach

- Active R&D programs for integrated technologies, targeted to ILC requirements
- Attempts to reach faster signal collection and ~ns time-stamping capability, compatible with CLIC requirements:
  - MIMOSA CMOS chip family (currently 350 nm) in STAR, EUDET Telescope
     → developing high-resistivity epitaxial layers, smaller feature sizes
  - Chronopixel CMOS sensors with fully depleted epitaxial layer
  - INMAPS technology: deep p-well barrier protects n-well charge collector, improves charge collection, allows for high-resistivity epitaxial layer and full-featured CMOS MAPS technology
  - High-voltage CMOS: CMOS signal processing electronics embedded in reverse-biased deep n-well that acts as signal collecting electrode
  - Silicon-On-Insulator (SOI): ~200 nm SiO<sub>2</sub> isolation layer separates charge collection and readout functionality
  - Full 3D-integrated pixel solutions: Thinned high-resistivity sensitive tier coupled to additional tiers with advanced analog+digital functionality
- Concerns for CLIC:
  - Long-term availability of processes
  - Suitability for large-scale systems
  - $\rightarrow$  prefer staged developments and synergy with industrial trends