

Status of IP FB system design

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Outline

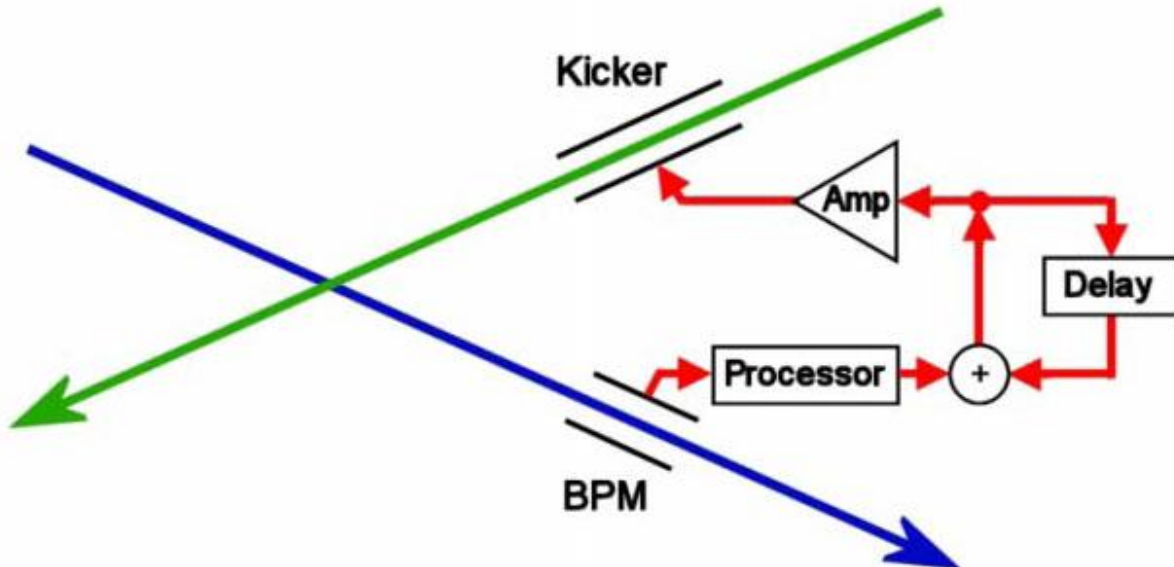
- **System concept**
- **ILC design status**
- **CLIC design status**
- **FONT prototype systems performance**
- **Remaining technical issues**
- **Recent progress at ATF2**

LC intra-train feedback system - concept

**Last line of defence
against relative
beam misalignment**

**Measure vertical
position of outgoing
beam and hence
beam-beam kick
angle**

**Use fast amplifier and
kicker to correct
vertical position of
beam incoming to IR**



FONT – Feedback On Nanosecond Timescales

IP FB Design Status: ILC

Conceptual design documented in ILC RDR (2007), fleshed out since:

1. IP position feedback:

provide IP beam position correction at ± 50 sigma_y level
i.e. ± 300 nm of vertical beam motion at IP

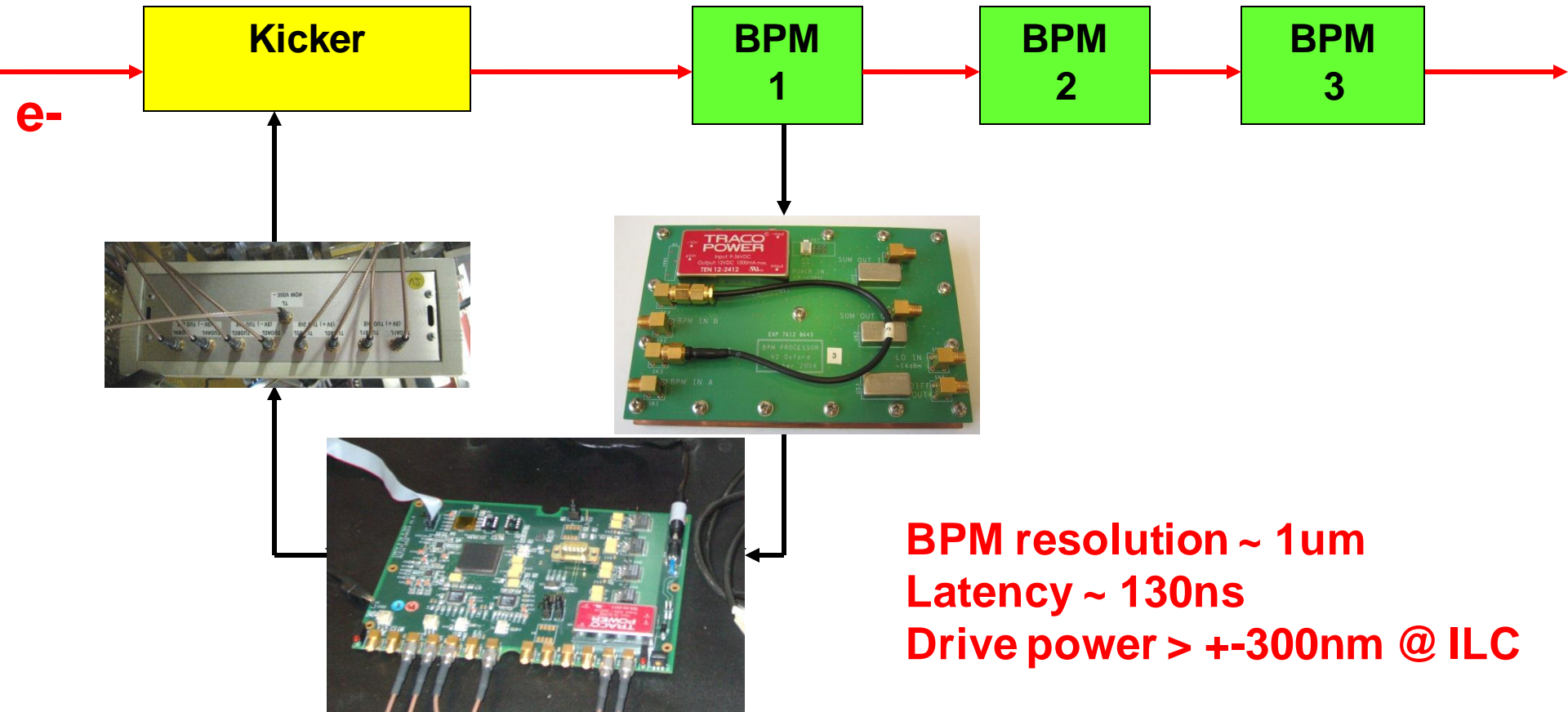
2. IP angle feedback: hardware located few 100 metres upstream
conceptually very similar to position FB, (arguably) less critical

3. Bunch-by-bunch luminosity signal (from BEAMCAL)

‘special’ systems requiring dedicated hardware + data links

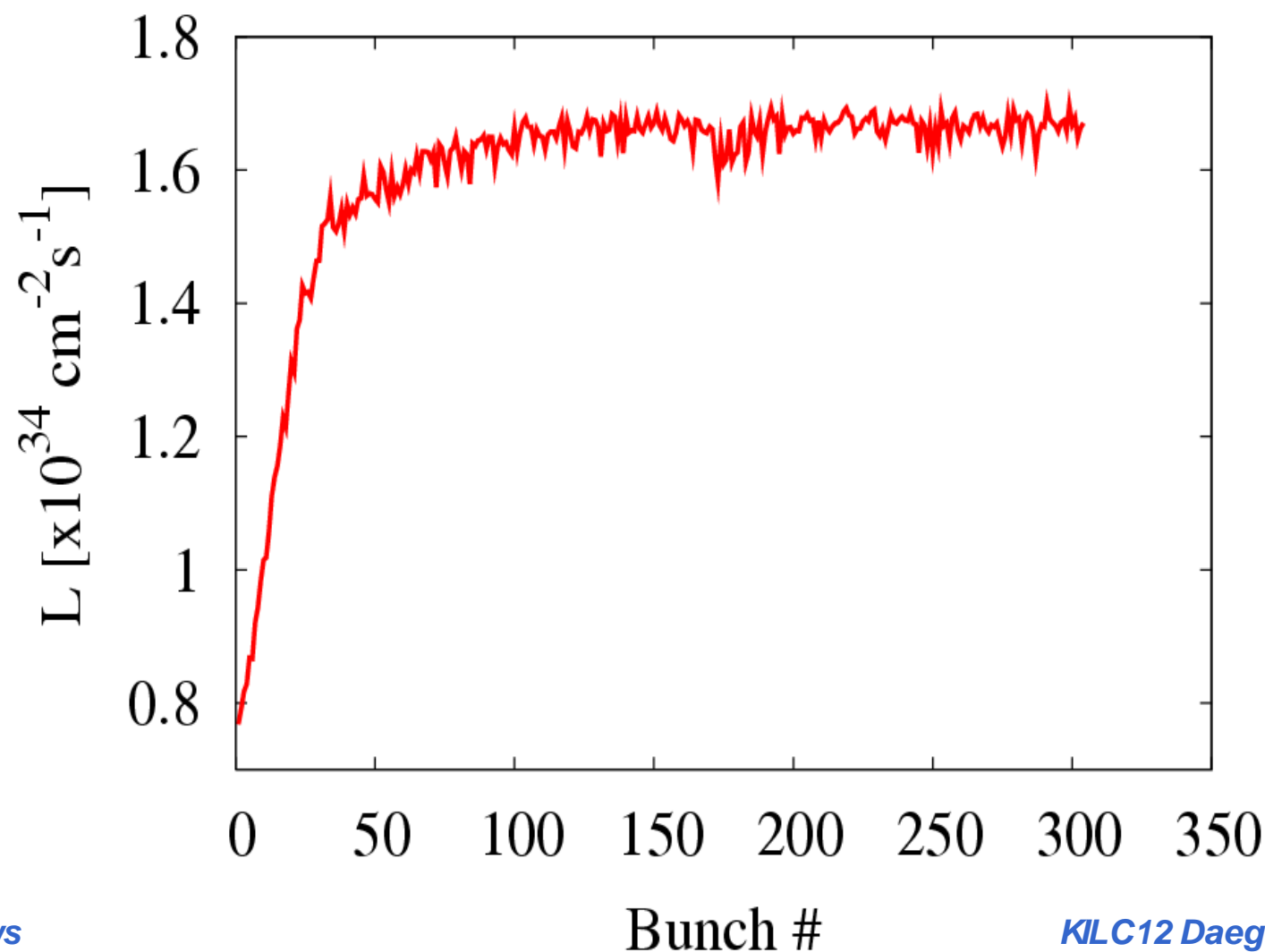
More realistic engineering design now in progress for TDP document (2012)

ILC prototype: FONT4 at KEK/ATF



BPM resolution ~ 1 μ m
Latency ~ 130ns
Drive power > +-300nm @ ILC

ILC IP intra-train FB performance



IP FB Design Status: CLIC

Conceptual design developed and documented in CLIC CDR (2011)

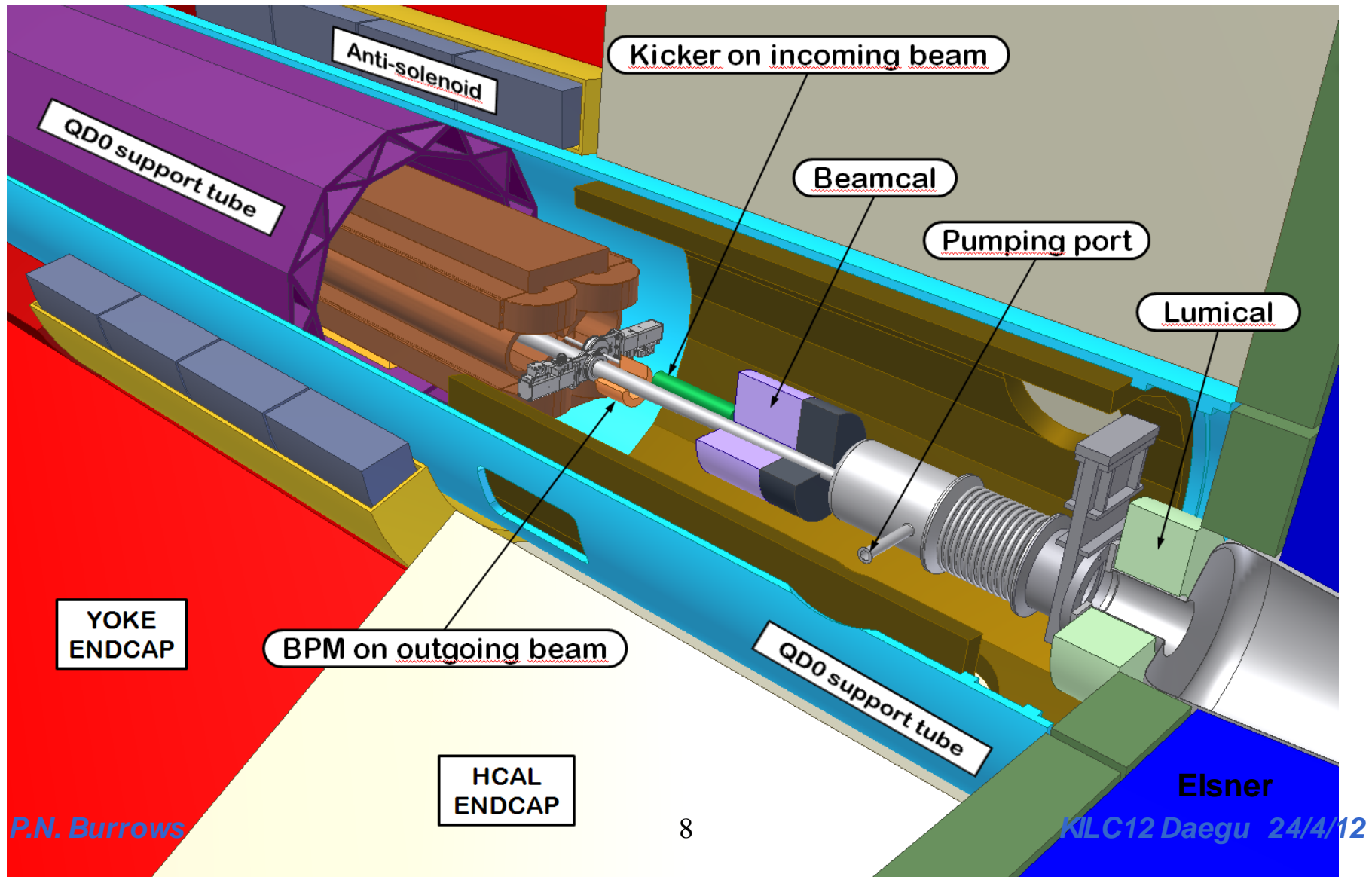
NB primary method for control of beam collision overlap is via vibration isolation of the FF magnets, and dynamic correction of residual component motions

IP position feedback:

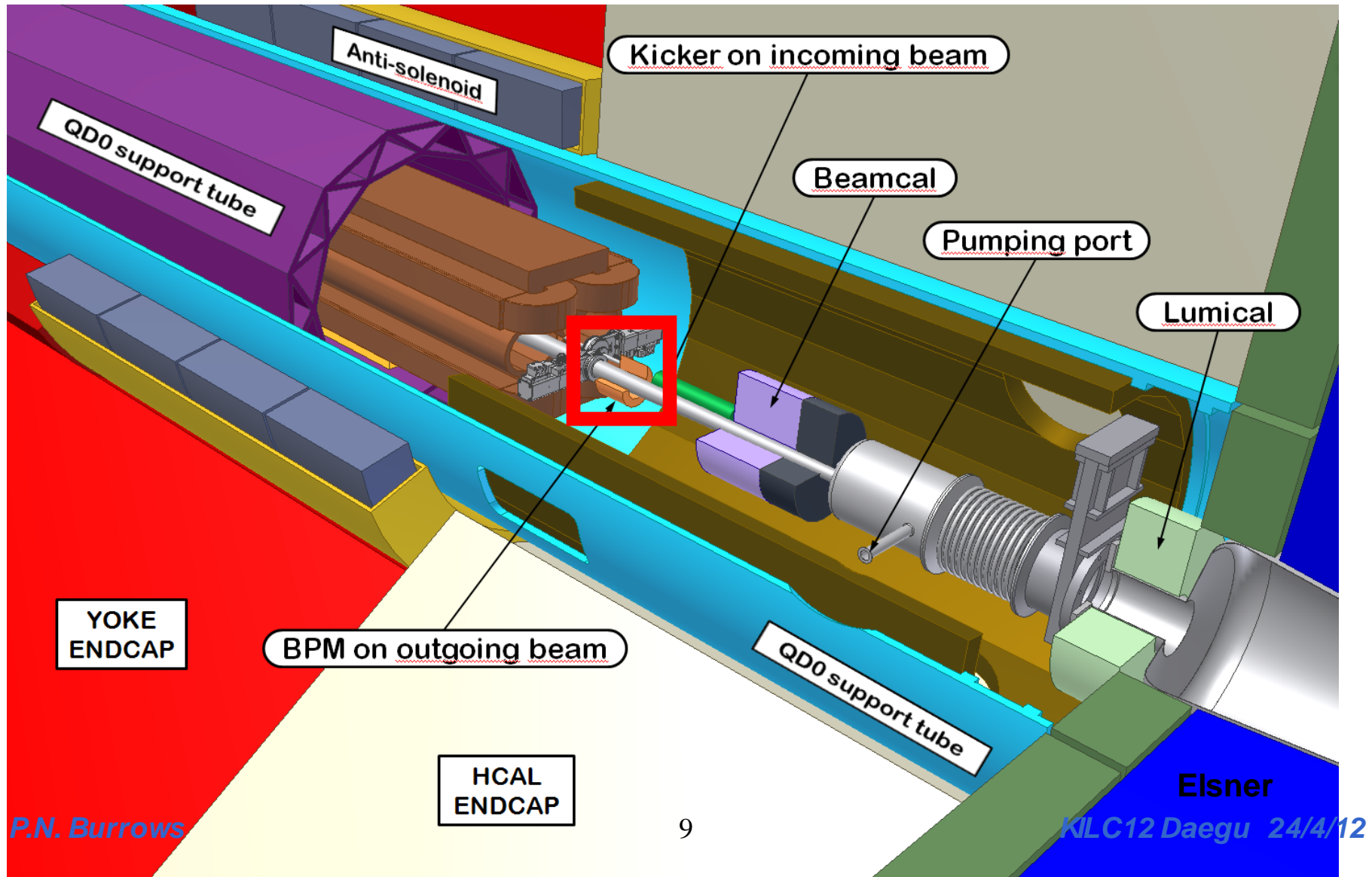
provide IP beam position correction of ± 50 nm of vertical beam motion

More realistic engineering design can be developed in next project phase

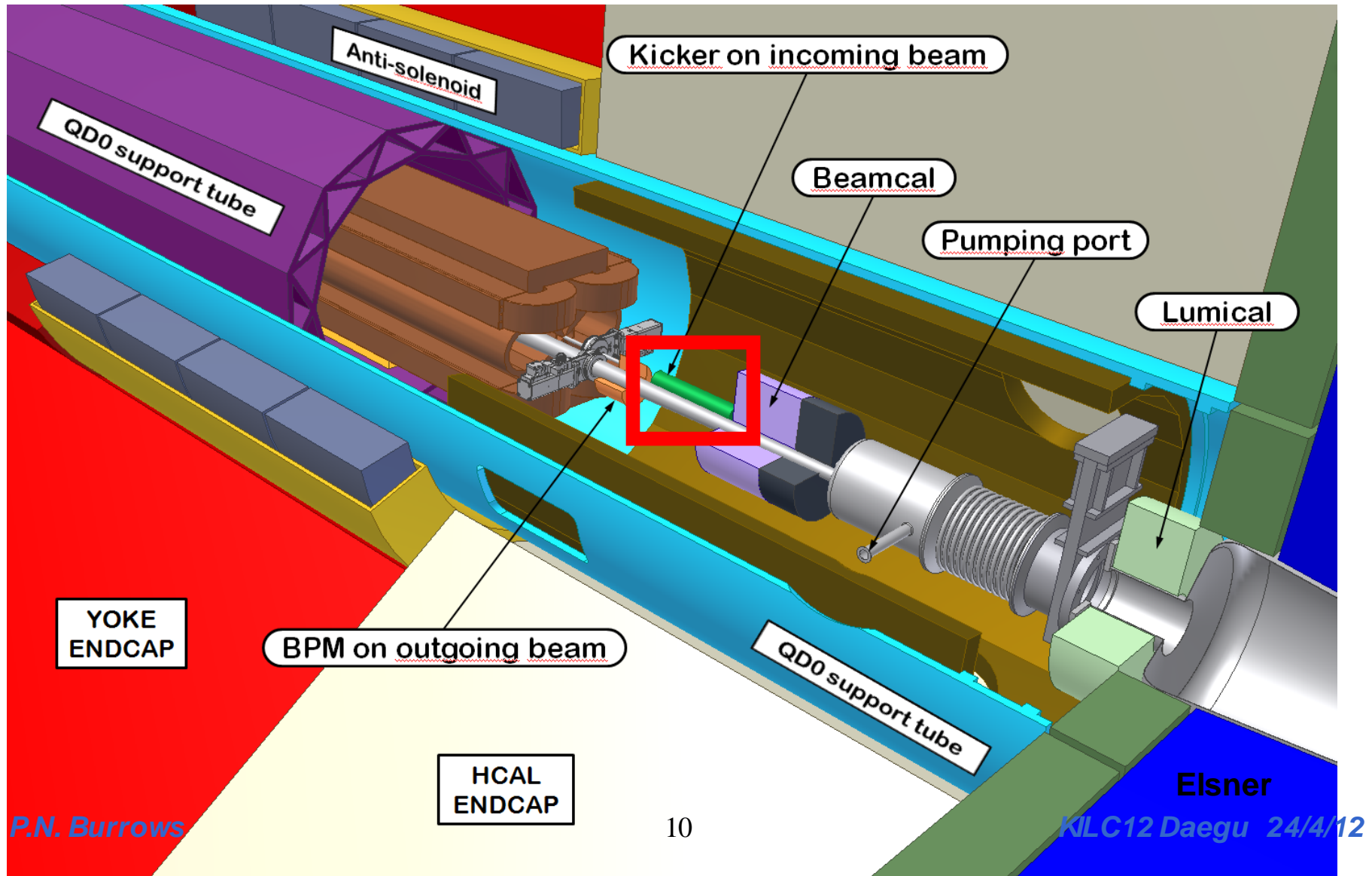
CLIC Final Doublet region



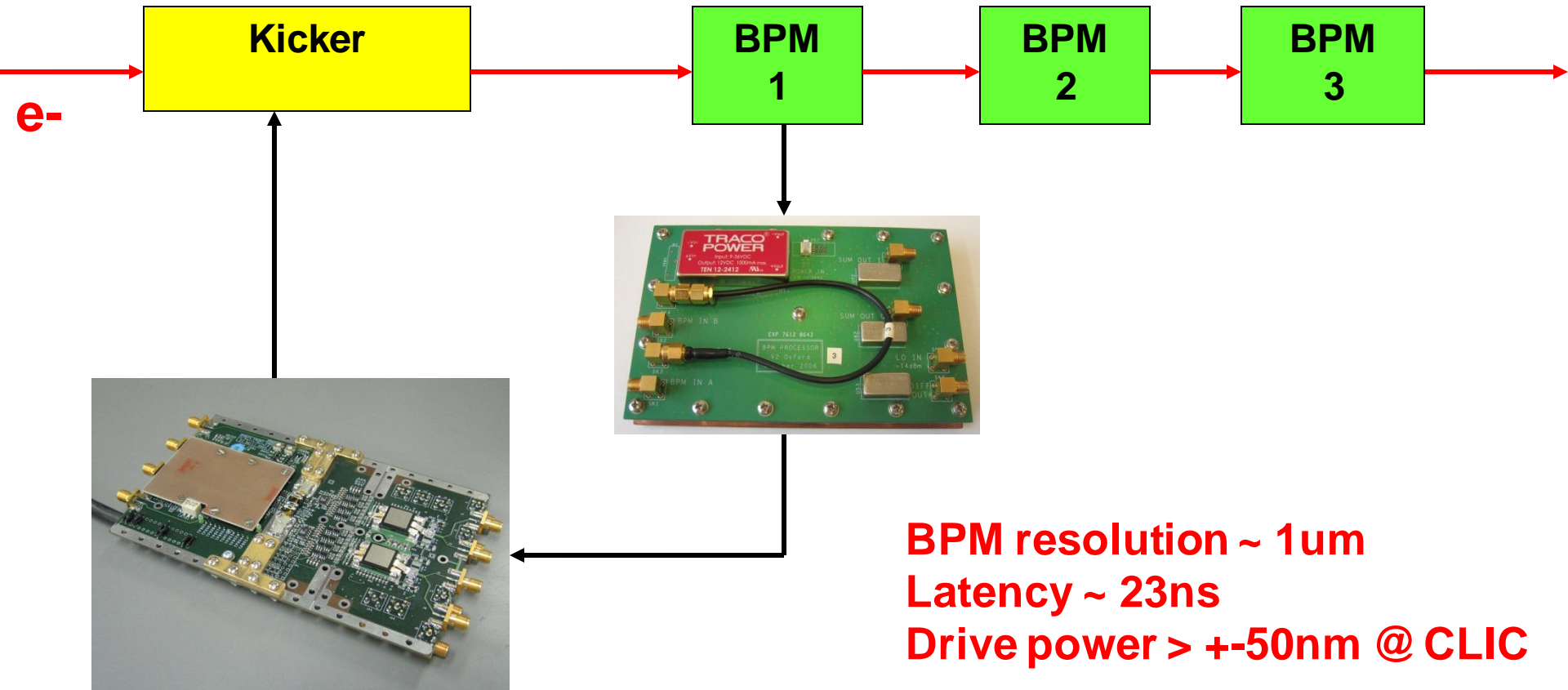
CLIC Final Doublet region



CLIC Final Doublet region



CLIC prototype: FONT3 at KEK/ATF

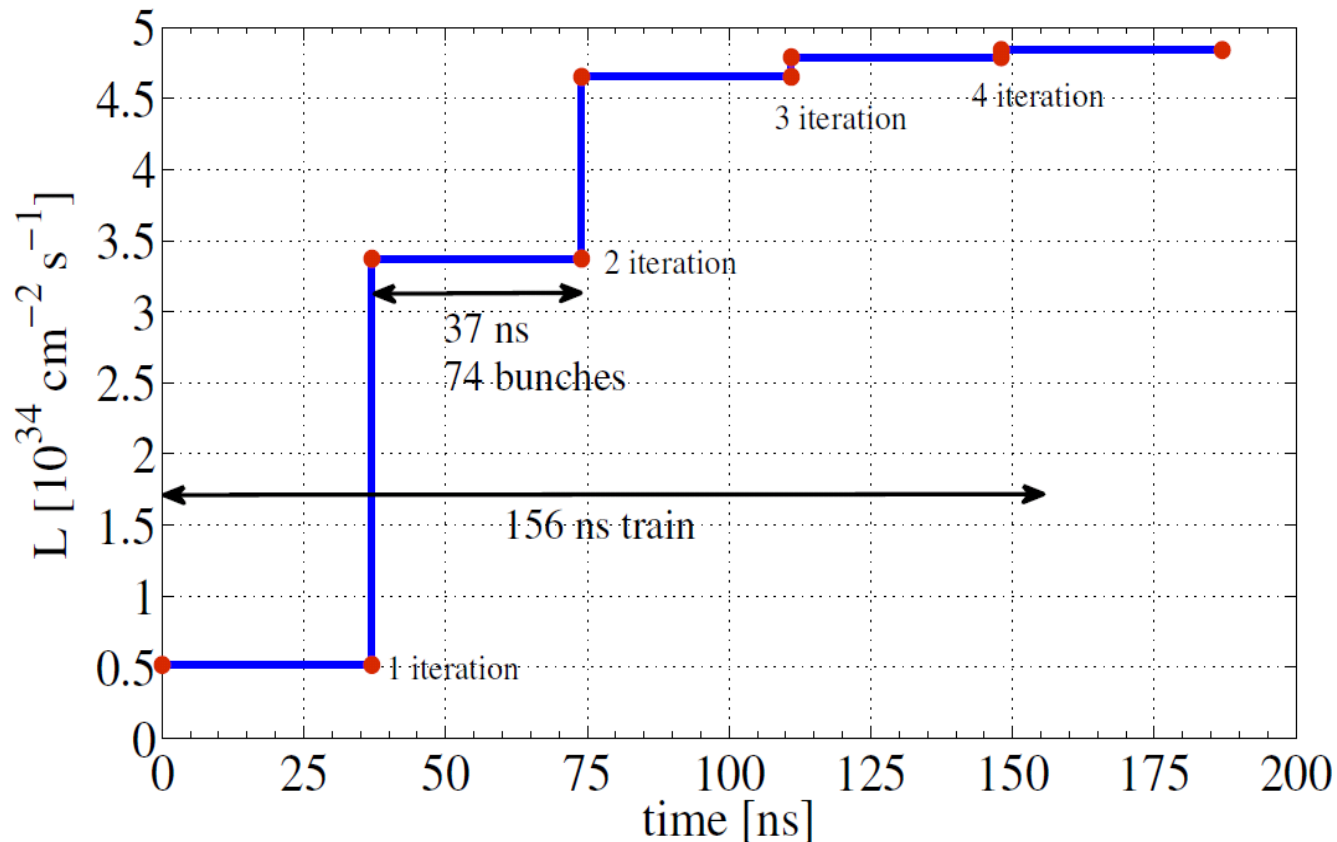


Luminosity performance with IP FB

Resta Lopez

Simulation time structure:

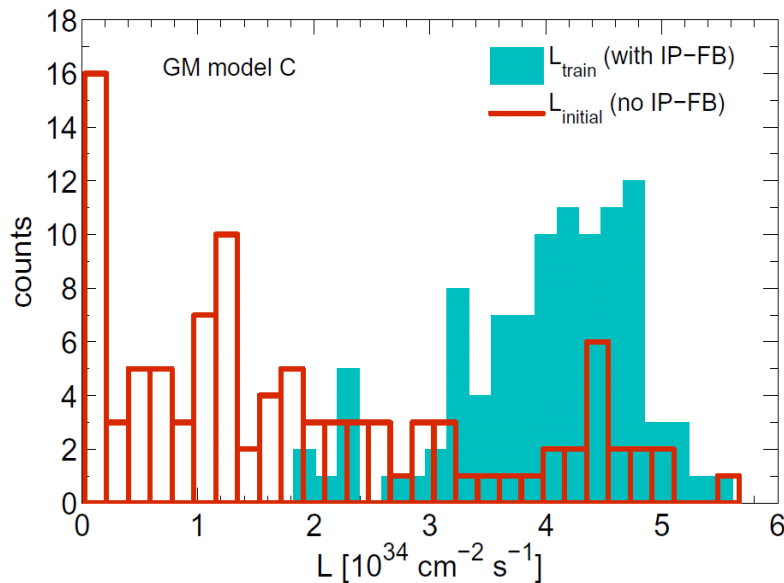
Example applying a single random seed of GM C



Luminosity performance with IP FB

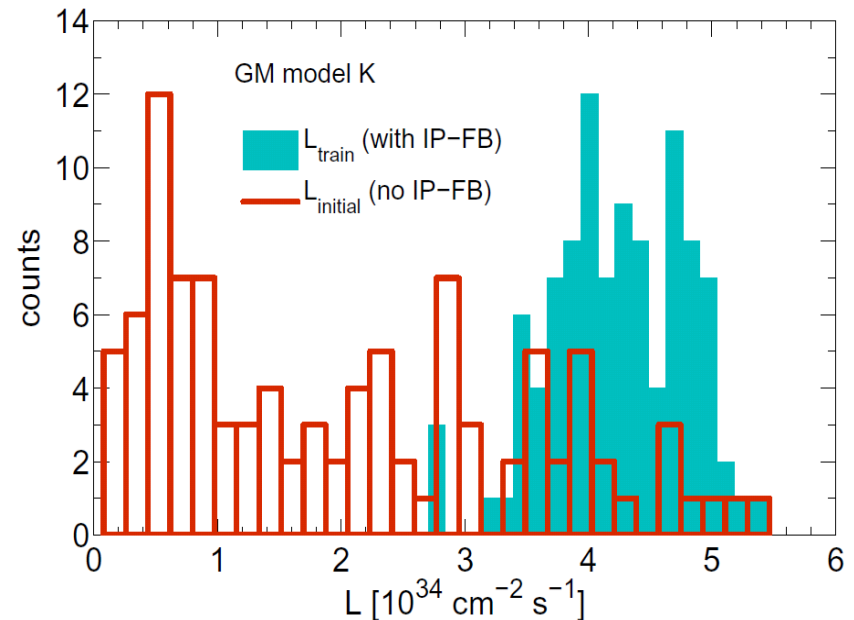
Resta Lopez

For noisy sites:



Model C:

- Without any correction: mean $\square L/L_0 \square_{\text{train}} = 30.52\%$
& High standard deviation!
- With IP-FB: mean $\square L/L_0 \square_{\text{train}} = 64.15\%$
std reduced by a factor 2



Model K:

- Without any correction: mean $\square L/L_0 \square_{\text{train}} = 32.53\%$
& High standard deviation!
- With IP-FB: mean $\square L/L_0 \square_{\text{train}} = 67.82\%$
std reduced by a factor 3

Remaining technical issues

- Engineering of real hardware optimised for tight spatial environment: BPM, kicker, cables ...
- Large (and spatially-varying) B-field → operation of ferrite components in kicker amplifier?!
- Further studies of radiation environment for FB system:
was studied for ILC, so far preliminary for CLIC;
where to put electronics?
need to be rad hard? shielded?
- RF interference: beam \leftrightarrow FB electronics
 kicker \leftrightarrow detector

FONT5 location

ATF2 extraction line

最終収束ビームライン
— ナノメートルビームの開発 —
Nano-meter beam R&D (ATF-FF)

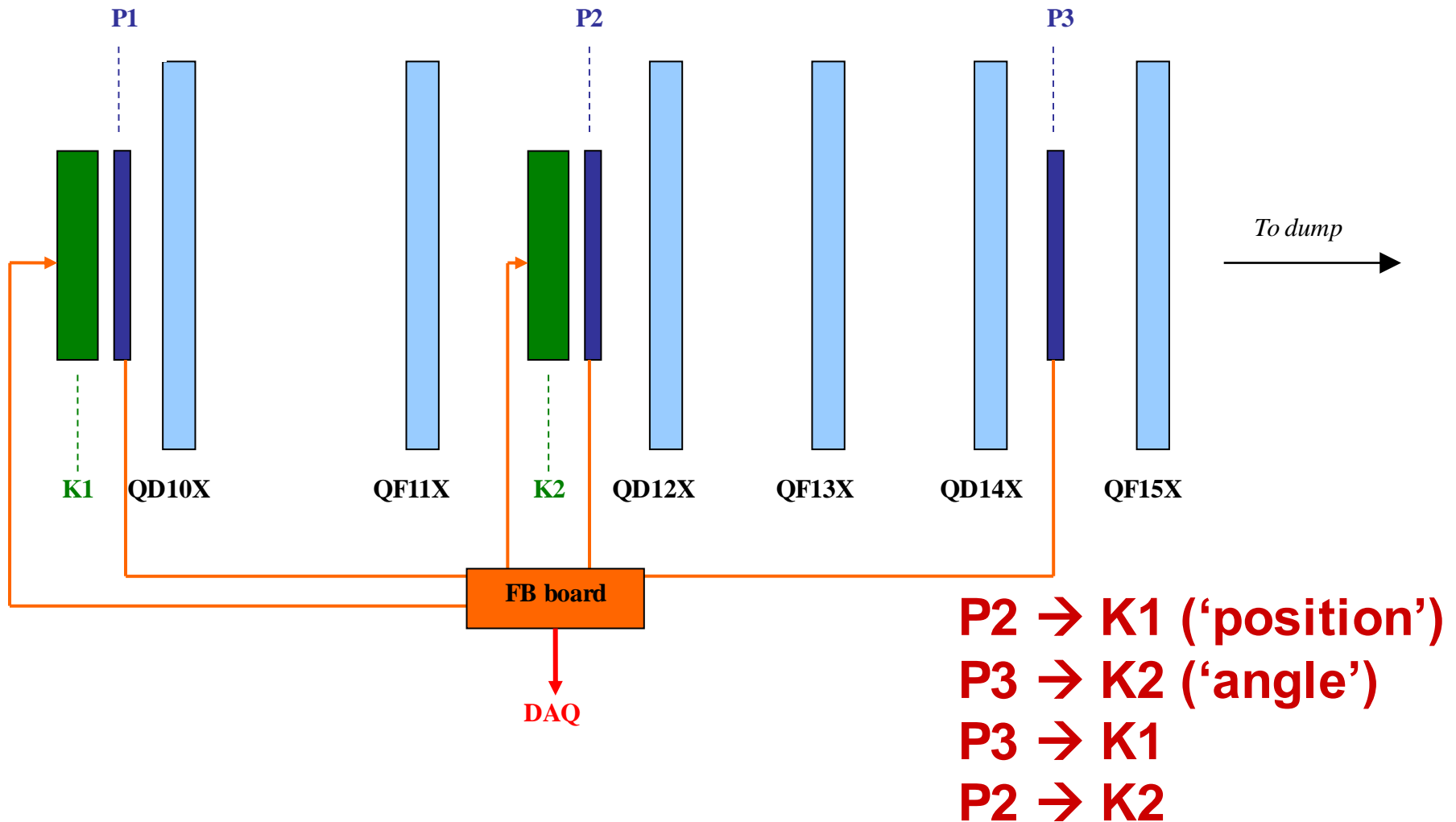
ビーム取り出しライン
— 世界最先端ビームモニタの開発 —
Extraction line

ダンピングリング
— 世界最高品質の電子ビームに変換する —
Damping Ring

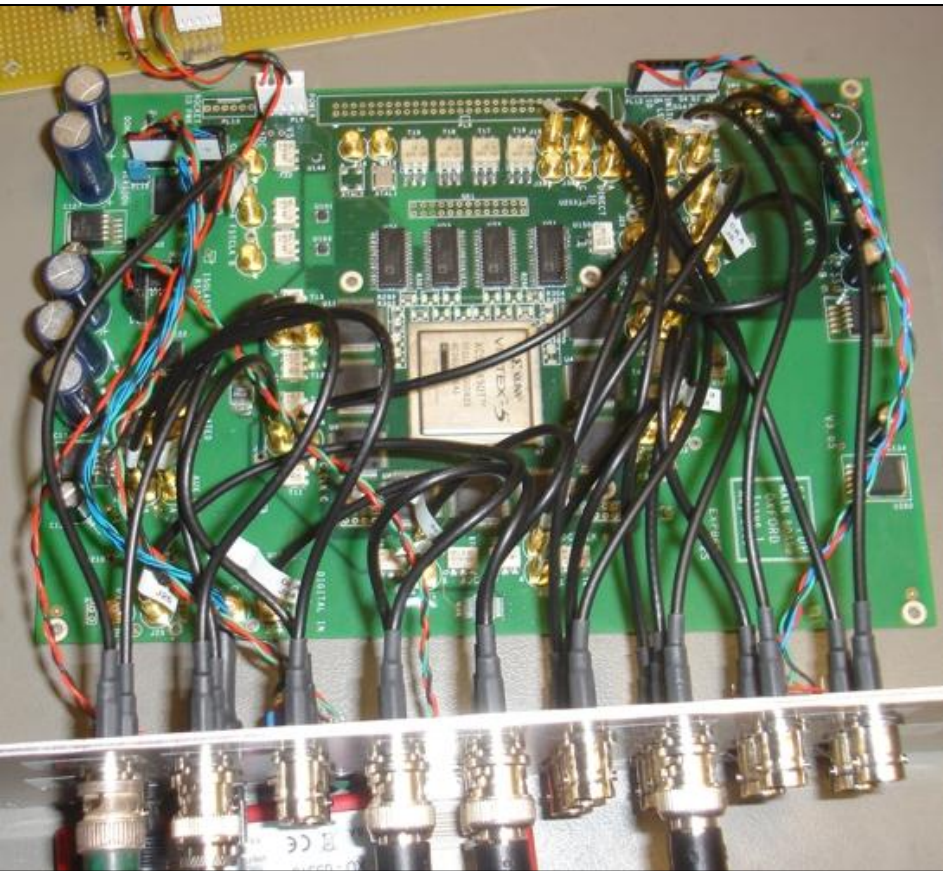
光陰極型高周波電子銃
— 電子ビームを生成する —
Photocathode RF Gun

電子線形加速器 (1.3GeV)
— 電子ビームを加速する —
S-band electron LINAC

FONT5 setup



FONT5 digital FB board



Xilinx Virtex5 FPGA

**9 ADC input channels
(TI ADS5474)**

**4 DAC output channels
(AD9744)**

**Clocked at 357 MHz
phase-locked to beam**

4x faster than FONT4

Ongoing R&D

- Improving BPM resolution:
Robert Apsimon PhD thesis
- Understanding/improving FB performance:
further DR extraction kicker timing studies
monitoring downstream BPMs + jitter tracking
Douglas Bett PhD thesis
- Design of an IP feedback system:
Michael Davis PhD thesis

Winter programme 2011-12

- **Nov/Dec: 2 dedicated shifts in each of 3 weeks**
- **March/April: 2 shifts in each of 2 weeks**
 - 1) setup, commissioning, BPM resolution,
DR extraction kicker timing studies w. 2 bunches**
 - 2) re-establish FB, loop/gain studies**
 - 3) FB optimisation,
downstream stripline BPM + OTR monitoring,
simultaneous logging of cavity BPM data**

BPM processor resolution tests

- 3 BPM processors (5,7,10) on BPM P2

25/10/11 8-hour shift:

0.55 0.56 0.60 μm

0.56 0.54 0.51 μm

0.53 0.40 0.35 μm

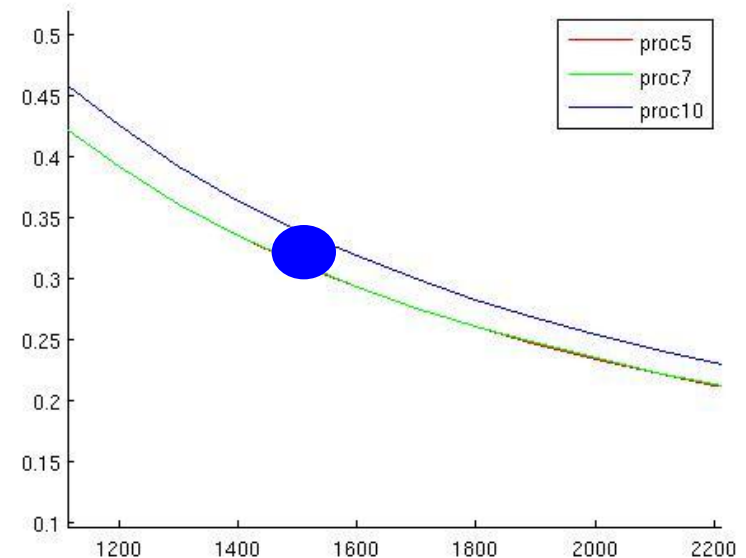
0.50 0.35 0.33 μm

0.45 0.44 0.35 μm

0.50 0.43 0.36 μm

Beam position jitter 3- 4 μm

expectation from
ADC noise alone:



Feedback Performance

(example FB Run 6 13/12)

bunch

1

2

FB off

FB off

Jitter P2

3.42

3.42

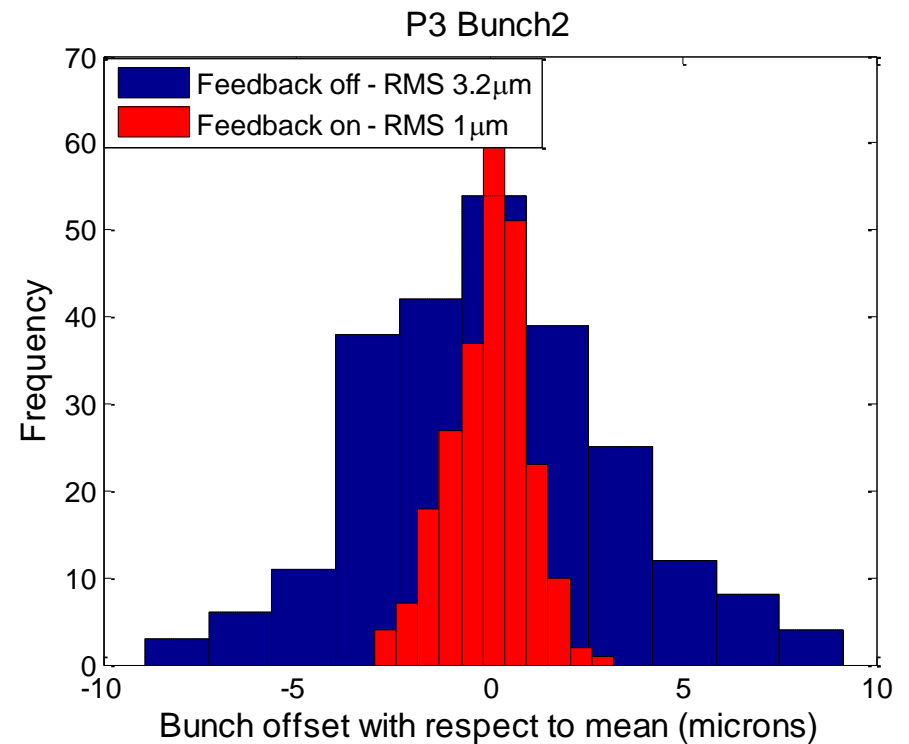
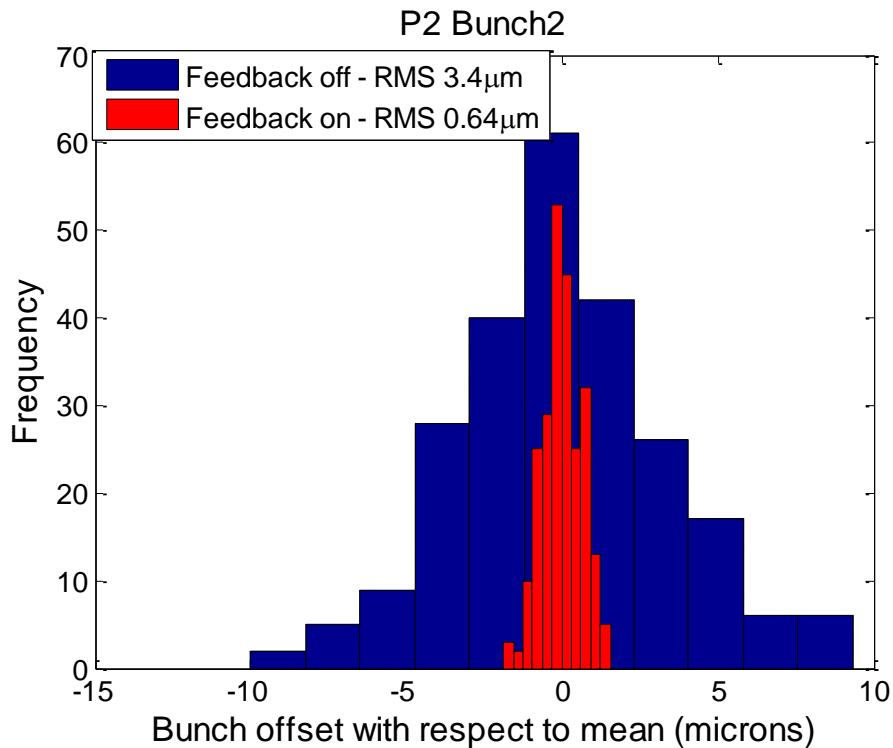
P3

3.24

3.21

Feedback Performance

(example FB Run 6 13/12)



Feedback Performance

(example FB Run 6 13/12)

bunch

1

2

FB off

on

FB off

on

Jitter P2

3.42

3.39

3.42

0.64

P3

3.24

3.16

3.21

1.04

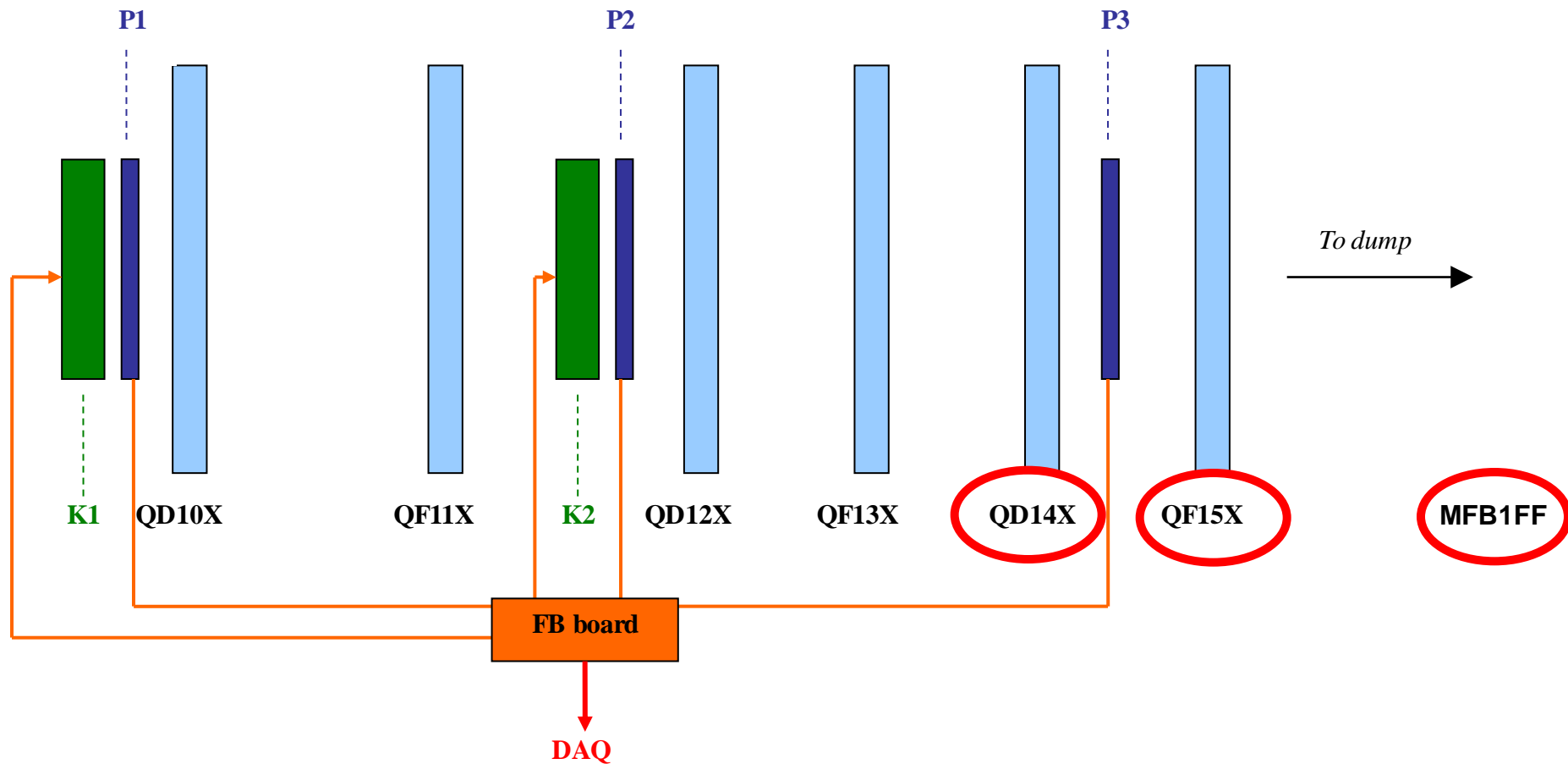
Feedback Performance

(example FB Run 6 13/12)

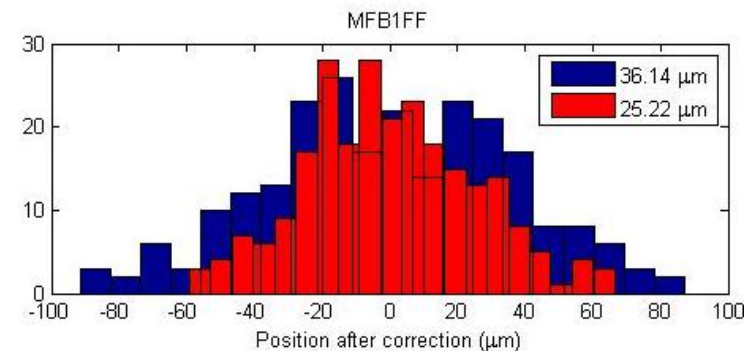
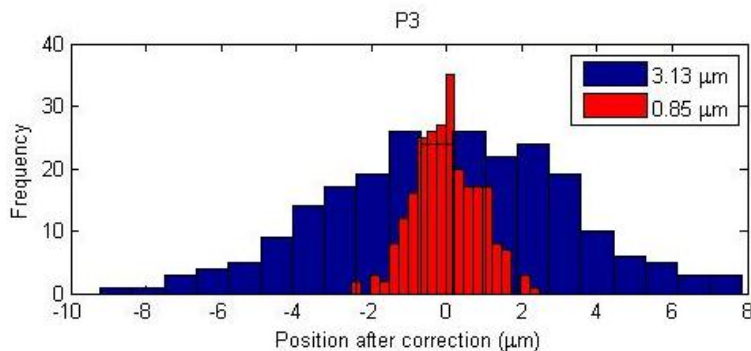
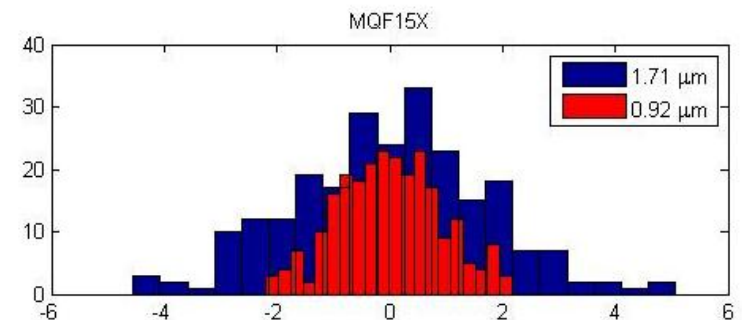
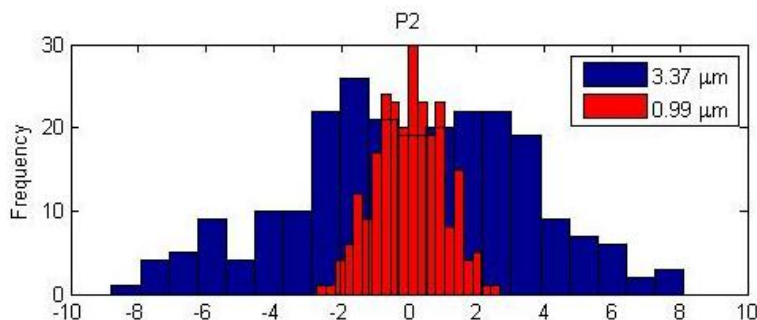
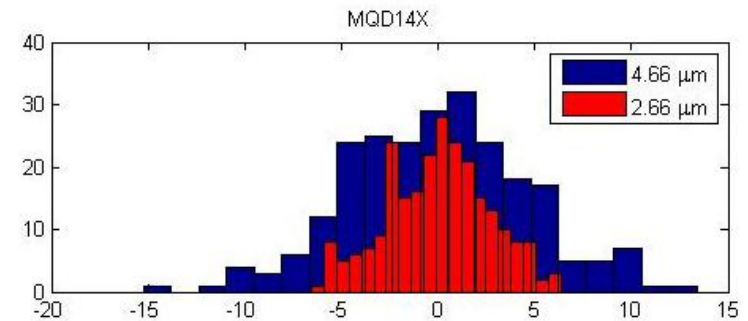
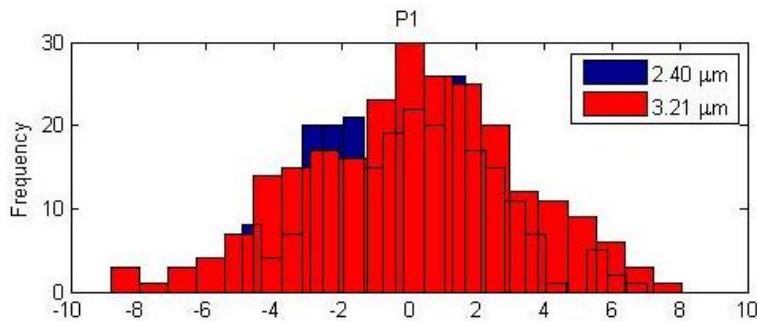
bunch	1		2		
	FB off	on	FB off	on	Pred.
Jitter P2	3.42	3.39	3.42	0.64	
1-2 correl 98%					0.67
P3	3.24	3.16	3.21	1.04	
1-2 correl 97%					0.83

$$\sigma_2'^2 = \sigma_1'^2 + \sigma_2'^2 - 2\sigma_1\sigma_2\rho_{12} \geq 2\sigma_r'^2$$

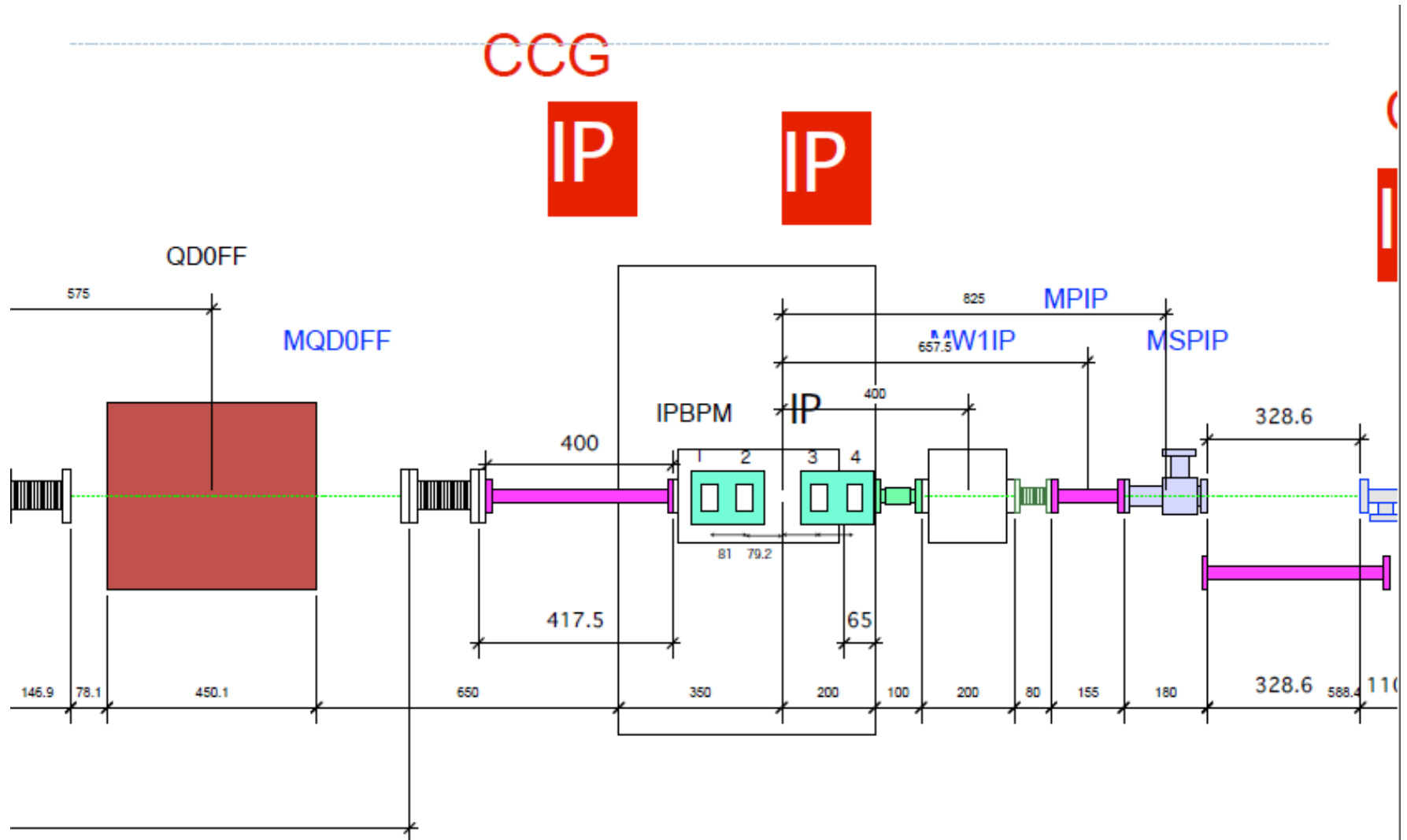
FONT5 setup Winter 2011-12



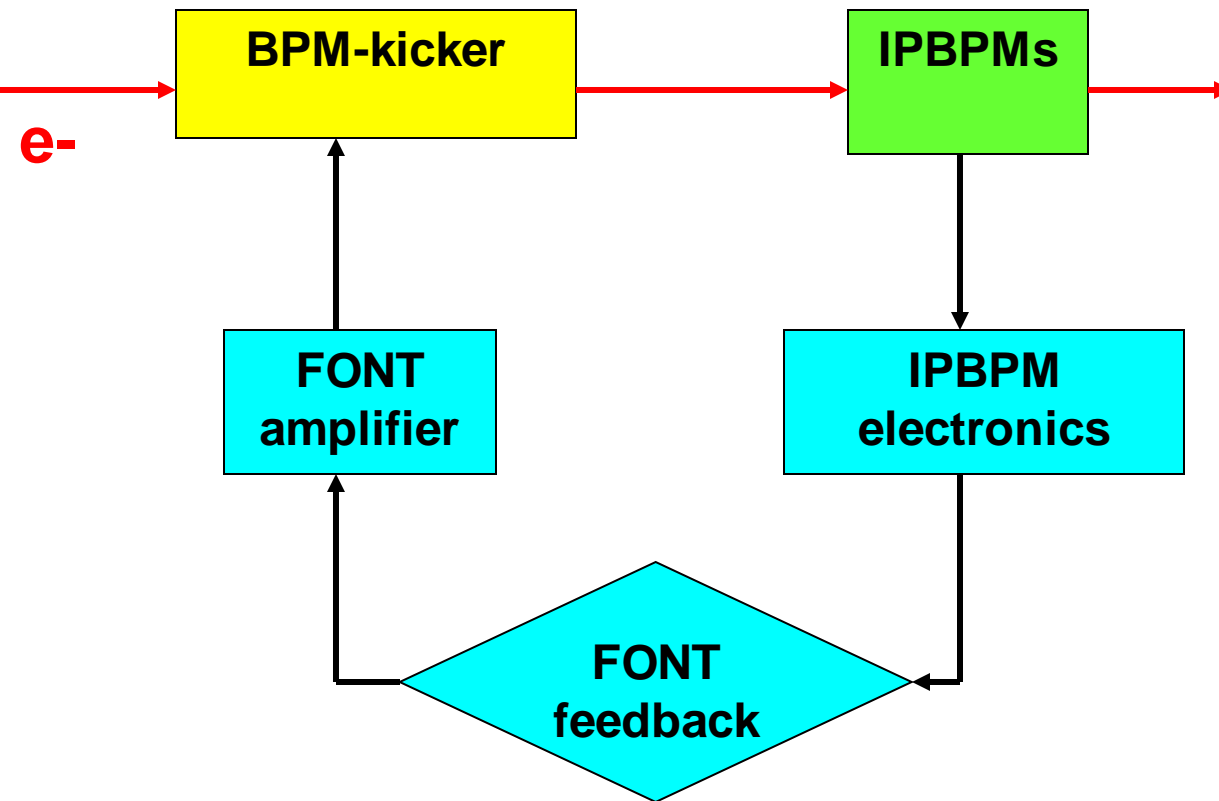
07/12 FB Run 23 (nom. optics)



Eventual IP configuration



IP FB loop



New kicker

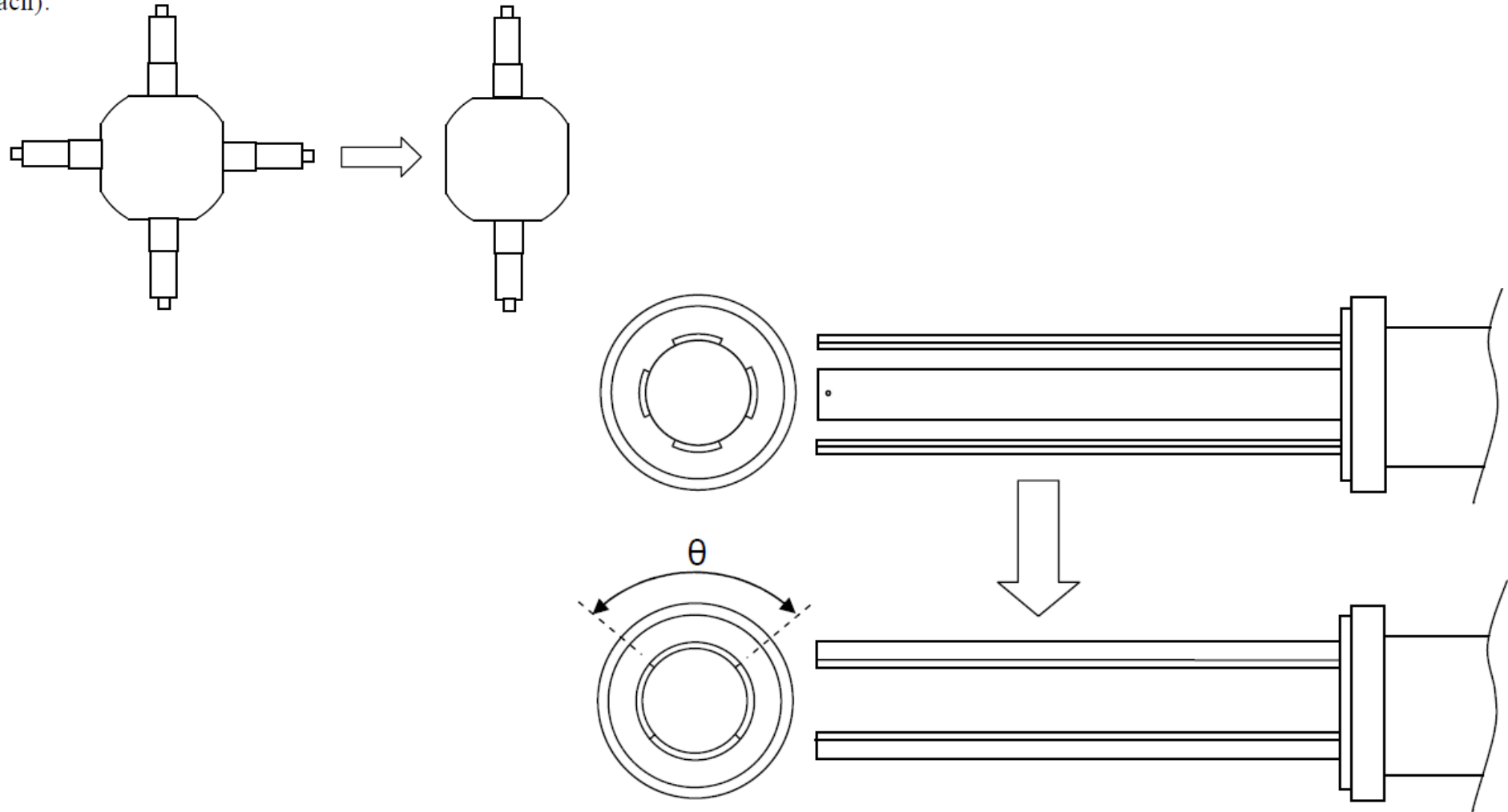
- Don't (in principle) need much drive for nm-level correction at IP
- Short kicker OK – necessitated by space available
- Simple proposal:
 modify stripline BPM design
 for driving as a kicker

 use FONT amplifier
 (plenty of drive)



BPM modified as kicker

ach):



New kicker



Working assumptions (1)

- **Kicker centre ~ 0.5m upstream of IPBPM**
- **Stripline aperture ~ 24 mm**
- **Stripline length ~ 12 cm**

Working assumptions (2)

Dynamic correction range:

- Beam y jitter ~ beam size (?)
- 3 sigma correction range:
 - 37nm beam → 100nm range → 200nrad kick
 - 100nm → 300nm → 600nrad kick
- FONT amplifier/kicker provides $\pm 50 \mu\text{rad}$
- Amplifier not matched to new BPM-kicker, but will be more than adequate!

Latency estimate

- Amplifier 35ns
- Kicker fill (12cm) 0.5ns
- Beam flight time amplifier → IPBPM 2ns
- Cables (3 x 1.5m?) 23ns
- **IPBPM electronics** X
- Digital FB processing 60ns

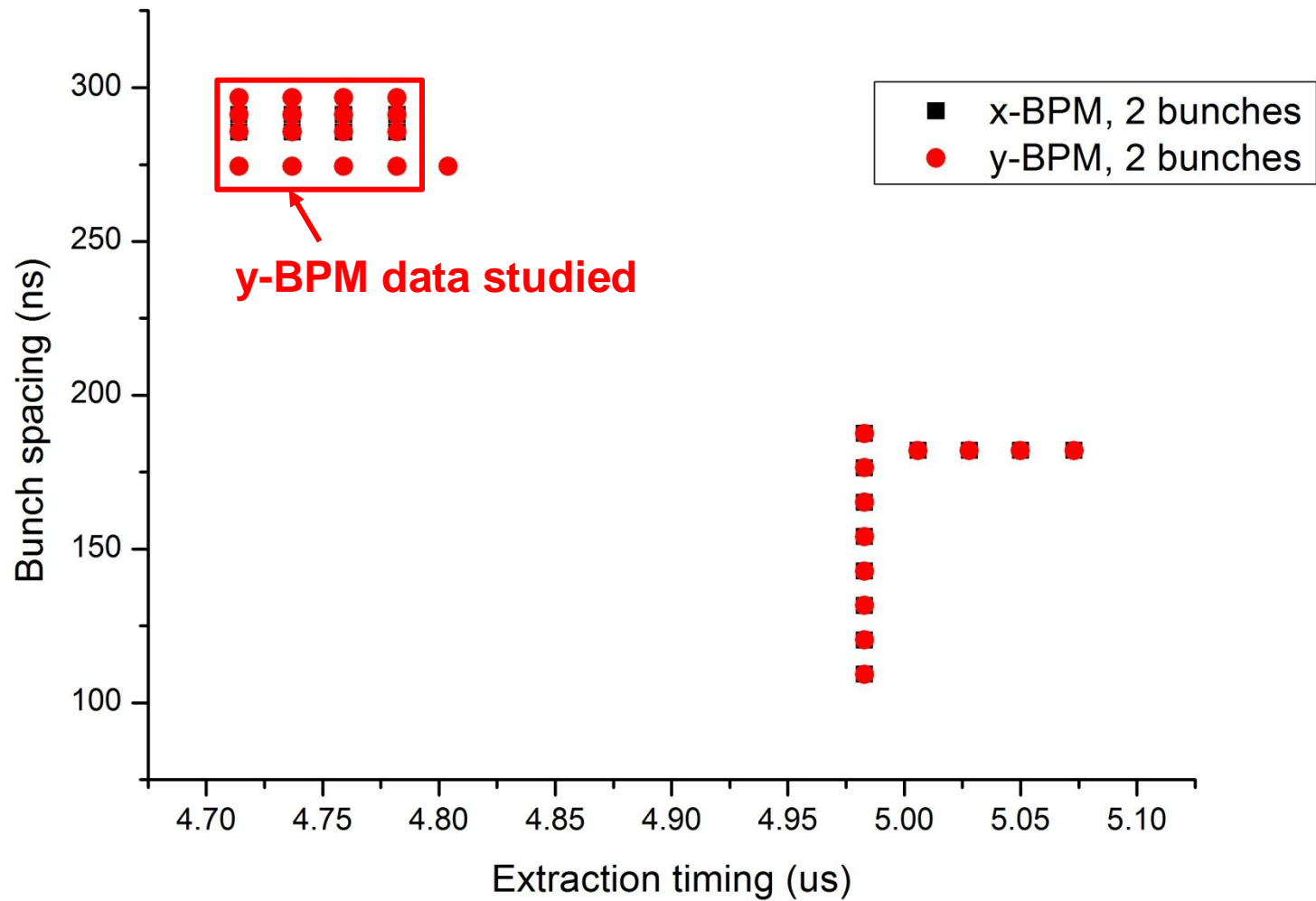
Total 120 + X ns

Bunch spacing < 300ns → **X < 180ns**

2-bunch train

- Intra-train beam feedback requires extremely high degree of spatial correlation between the bunches
- **Better off extracting just 2 bunches**
- Removes requirement for multibunch cavity BPM signal processing for input to FB
- Increases latency budget available for FB loop
- December FONT running investigated optimal extraction kicker parameters

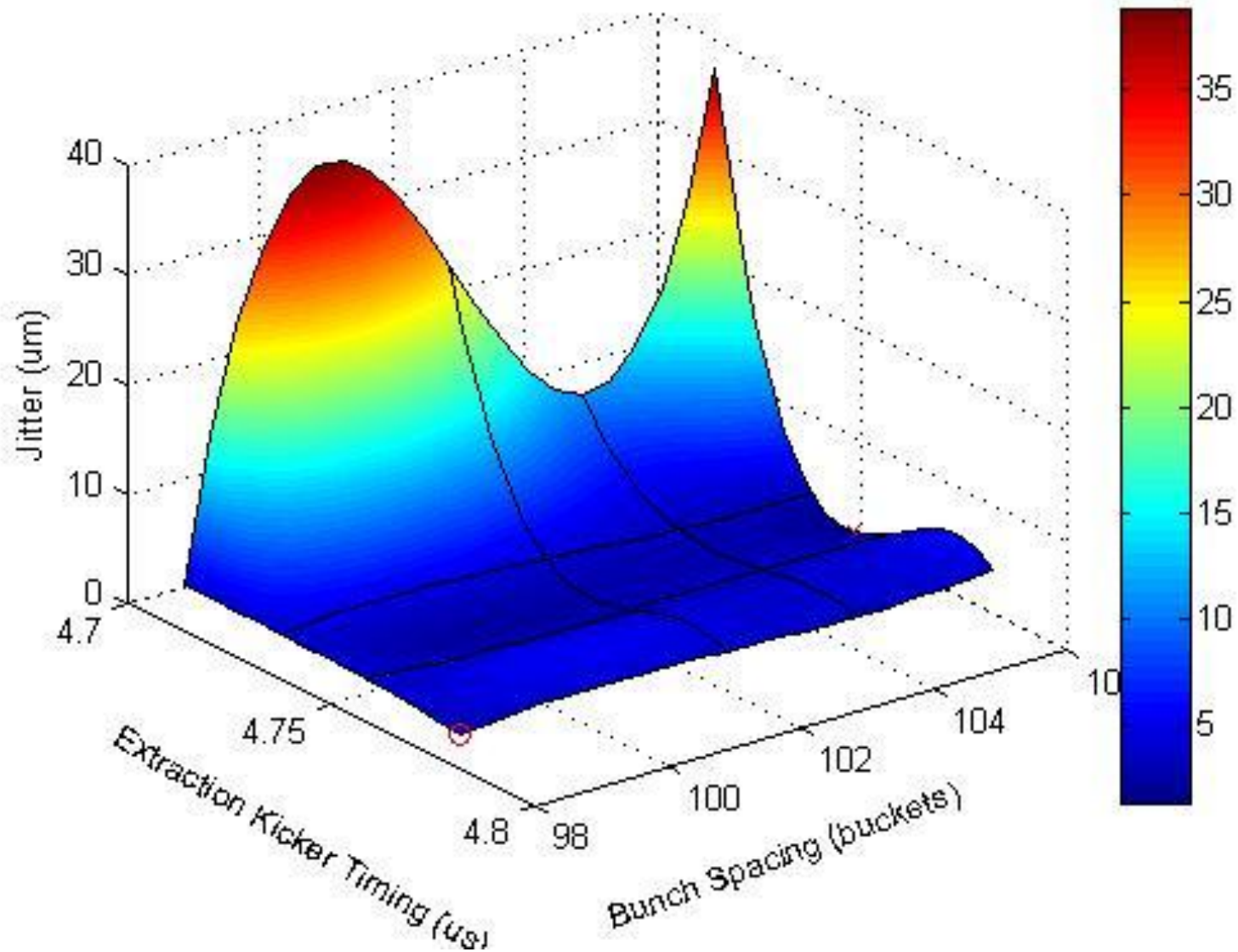
Setting map: bunch spacing vs. extraction timing (021211)



BPM P2 (021211)

o: raw min at (98, 4.782, 3.0806)

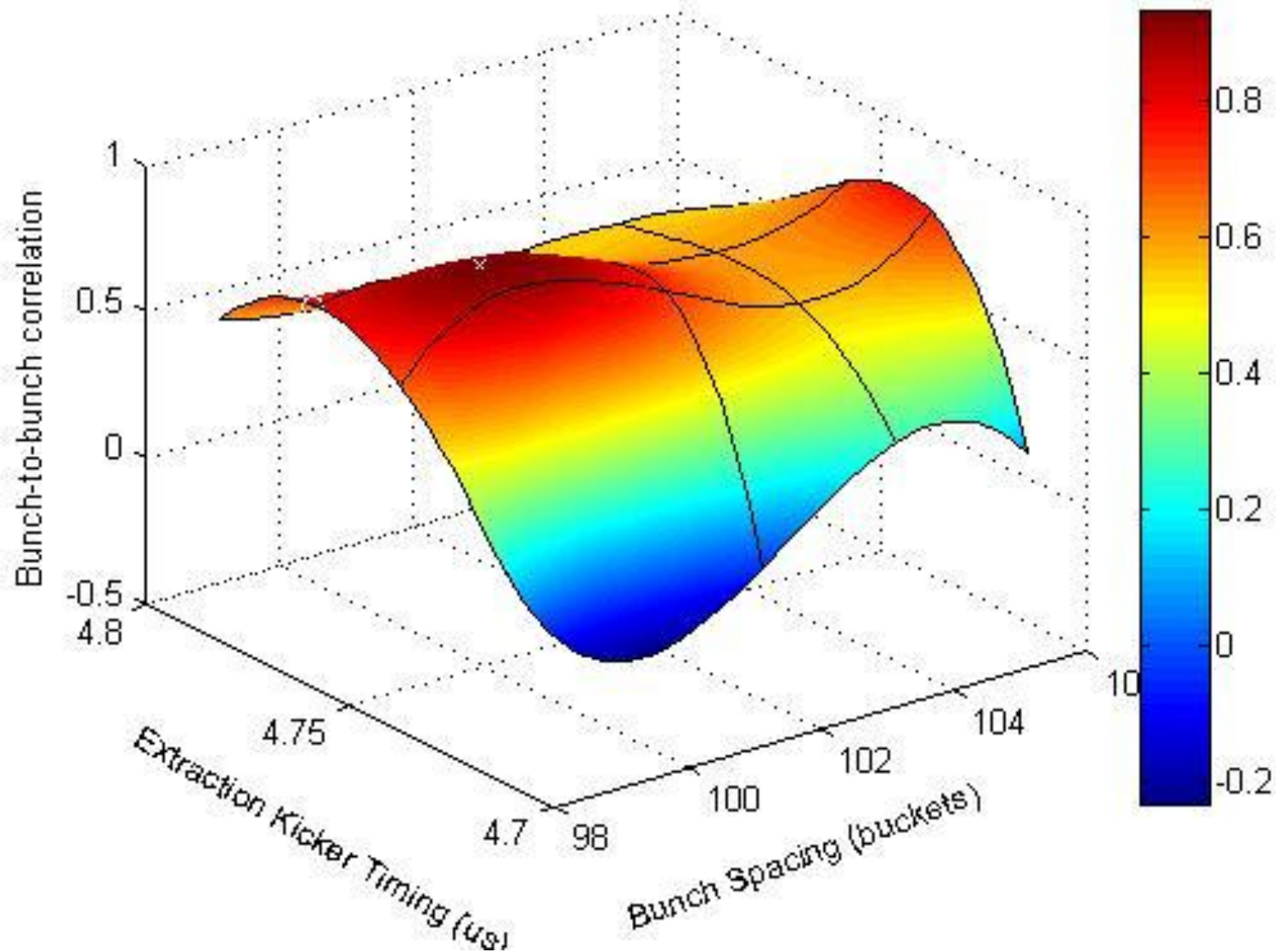
x: interpolated min at (106, 4.748, 1.2931)



BPM P1 (021211)

o: raw max at (98, 4.759, 0.8066)

x: interpolated max at (99.6, 4.7446, 0.93515)



Summary: LC FB design

- **Well developed IP FB system concept for both ILC and CLIC**
- **Simulations demonstrate luminosity recovery capability**
- **Demonstrated prototypes with required performance parameters**
- **Progress on designing customised beamline components for ILC case**

Summary: ATF2 IPFB

- **Conceptual IPFB design established**
- **New kicker has been fabricated**
- **Use FONT amplifier to drive kicker**
- **Use FONT5 FB board for digitisation + signal processing**
- **Measurements indicate good beam quality for 2-bunch mode with up to 300ns bunch spacing**

Extra material

General considerations (1)

Collision optimisation – based on beam-beam deflection:

1. Interaction point position feedback:

- hardware located near IP

- kicker at 90 degrees w.r.t. IP

2. Interaction point angle feedback:

- hardware ideally located near IP

- kicker in phase w.r.t. IP

3. Additional (feed-forward) inputs:

- information from alignment systems (eg. QD0 etc.)

- information about beam from upstream in machine (eg. DR)

Luminosity optimisation – based on measured luminosity:

- fast luminosity signal (from BEAMCAL)

General considerations (2)

Time structure of bunch train:

ILC (500 GeV):	c. 3000 bunches w. c. 300 ns separation
CLIC (3 TeV):	c. 300 bunches w. c. 0.5 ns separation

Feedback latency:

ILC: $O(100\text{ns})$ latency budget allows **digital** approach

CLIC: $O(10\text{ns})$ latency requires **analogue** approach

Recall speed of light: $c = 30 \text{ cm / ns}$:

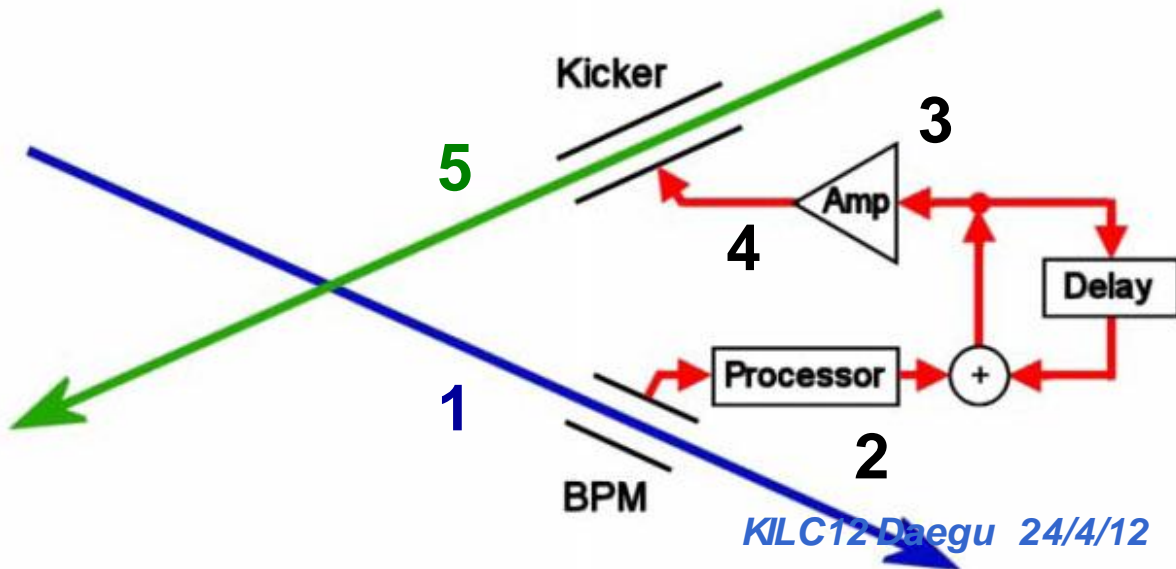
FB hardware should be close to IP (especially for CLIC!)

Two systems, one on each side of IP, allow for redundancy

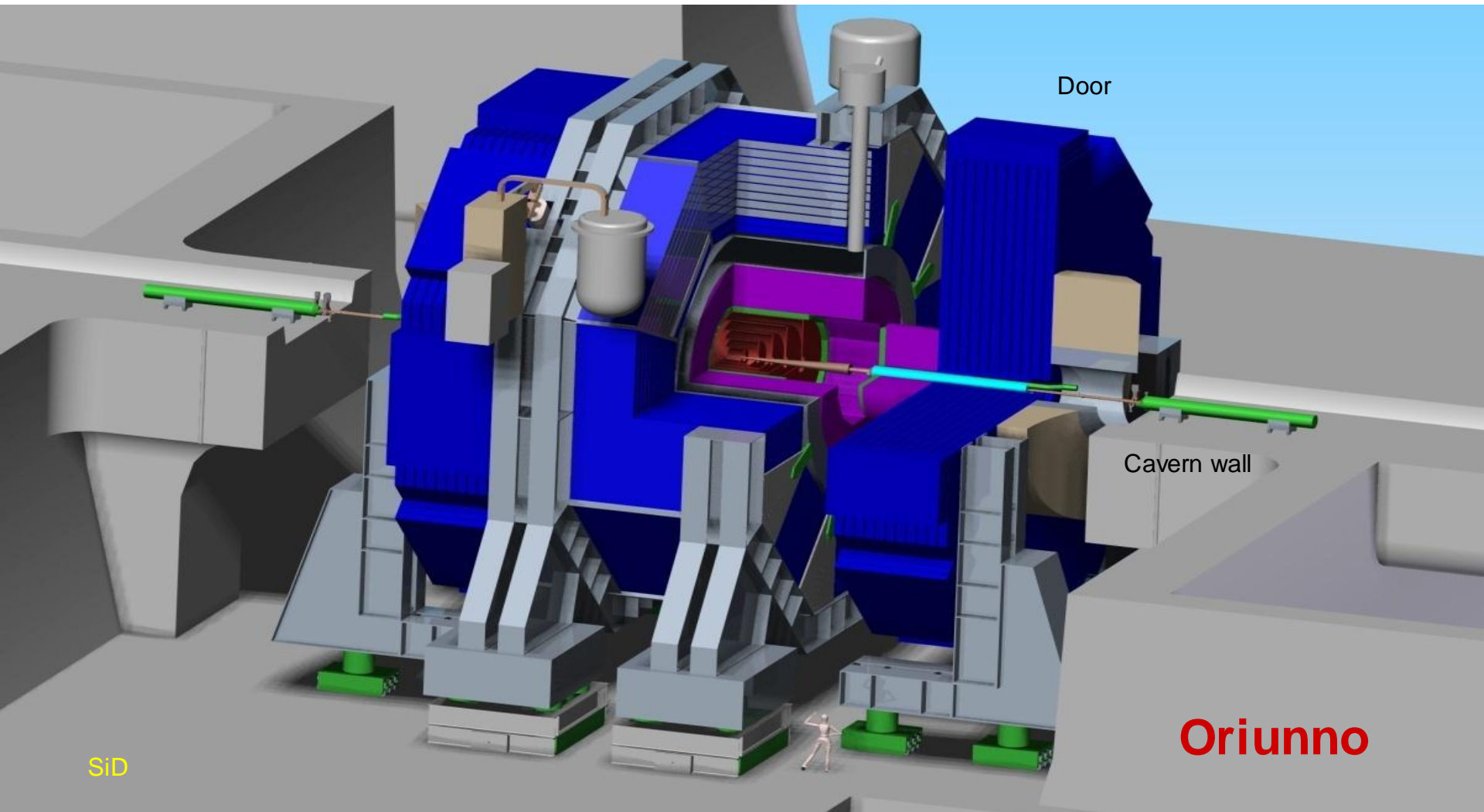
Interaction point FB latency

Latency:

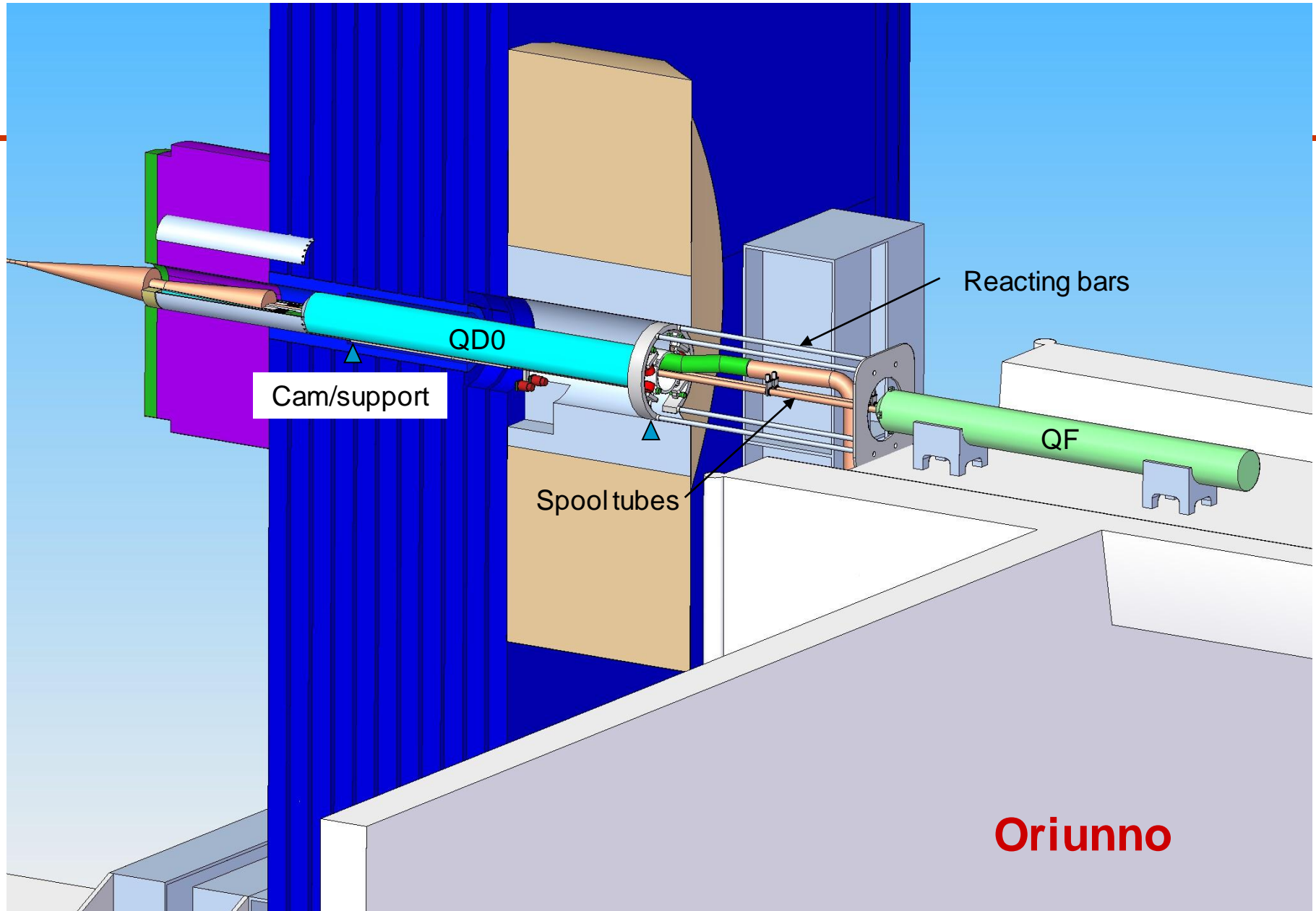
1. Beam flight time IP \rightarrow BPM
2. Signal processing, FB calculation
3. Amplifier + kicker response time
4. Cable delays
5. Beam flight time kicker \rightarrow IP



ILC IR: SiD for illustration

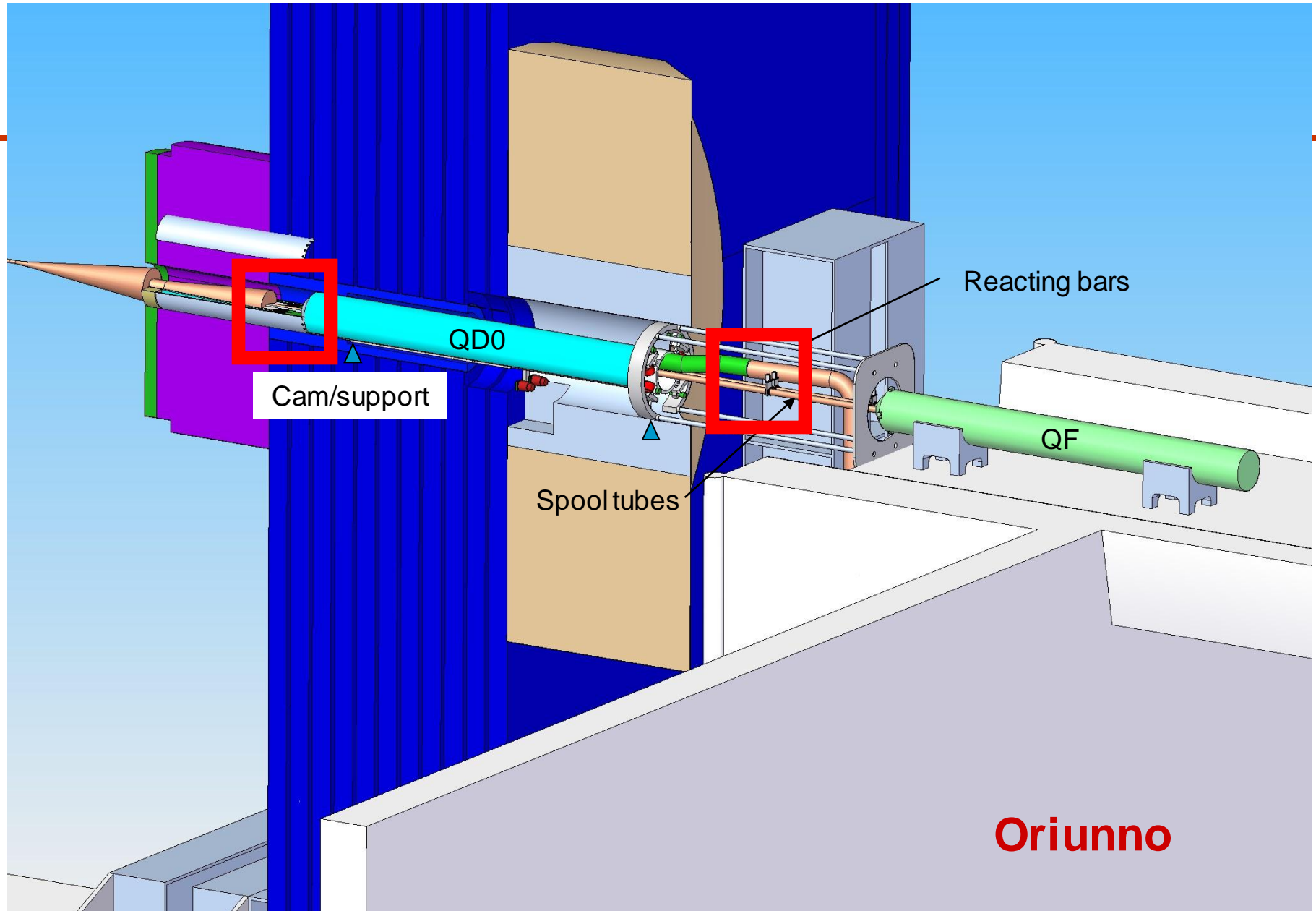


Final Doublet Region (SiD for illustration)

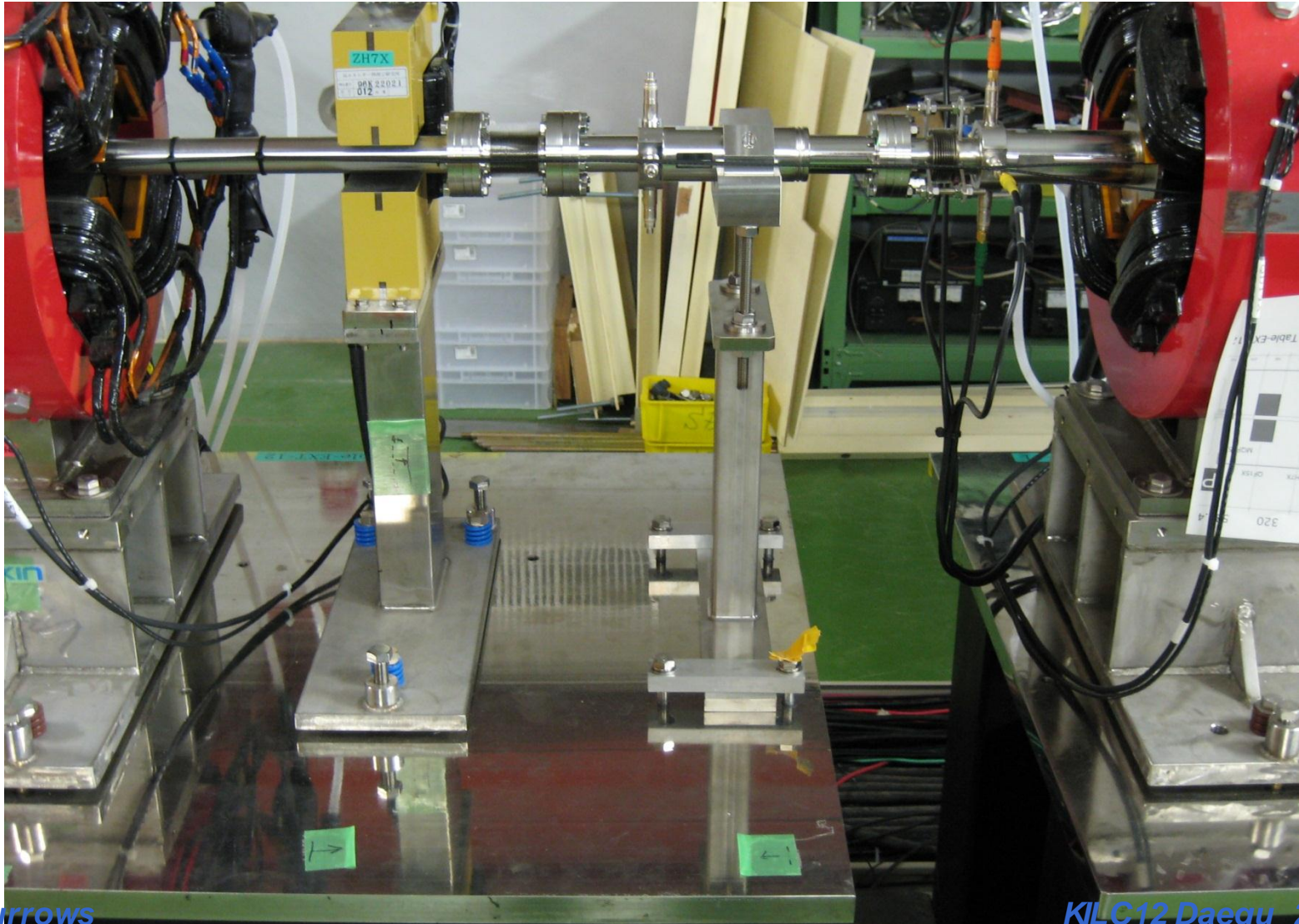


Oriunno

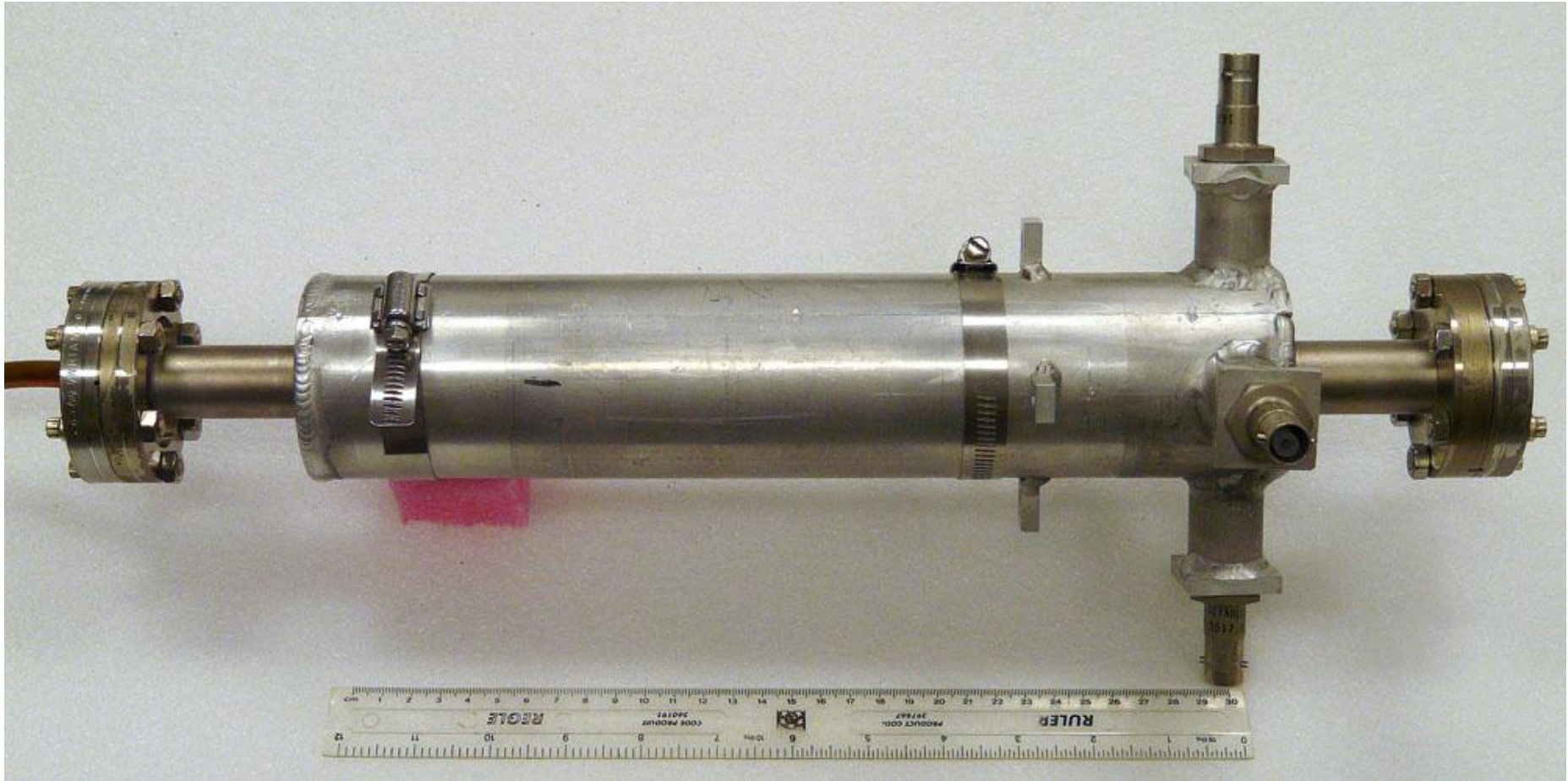
Final Doublet Region (SiD for illustration)



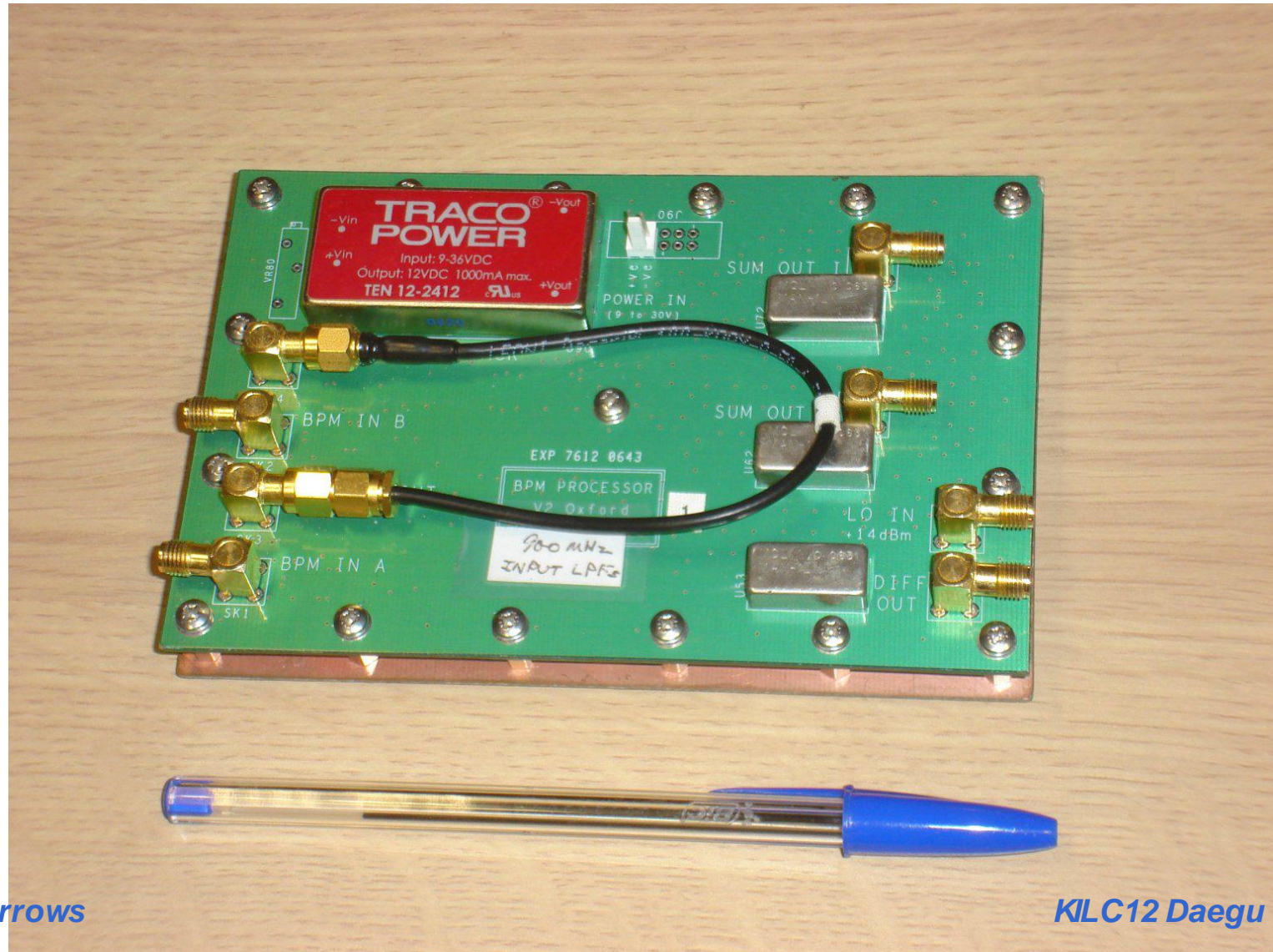
Off-shelf BPM



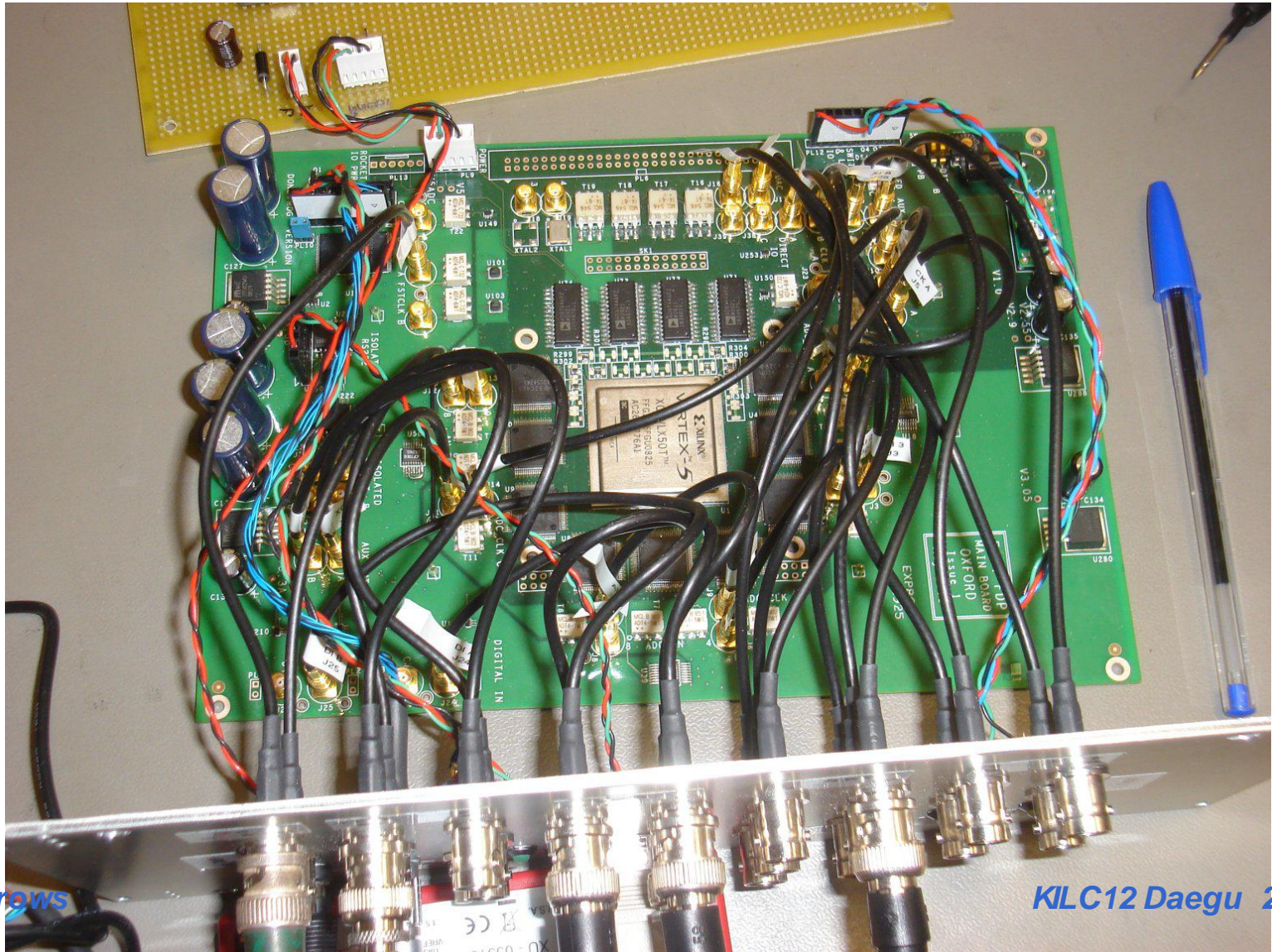
Off-shelf kicker



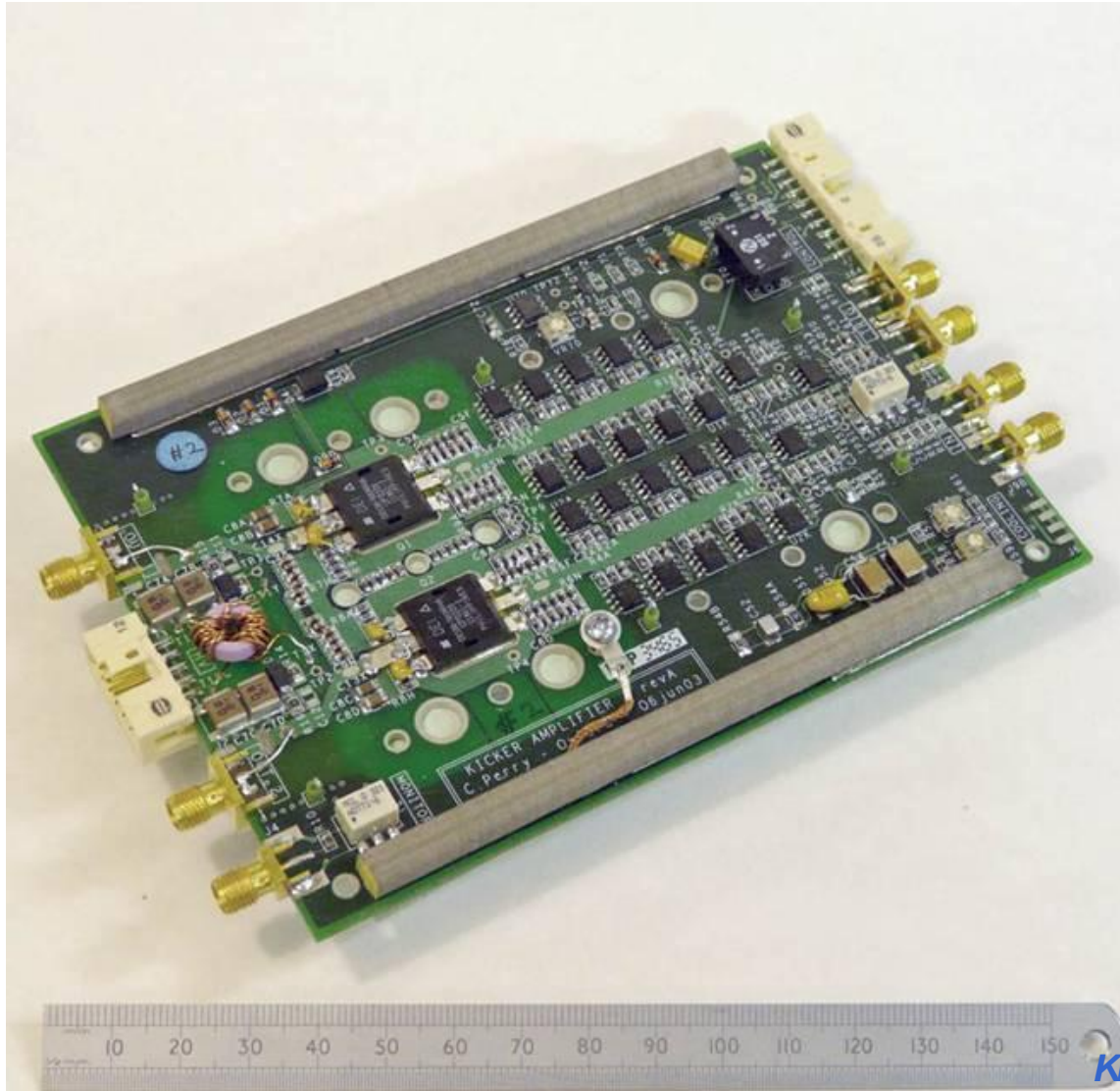
BPM processor



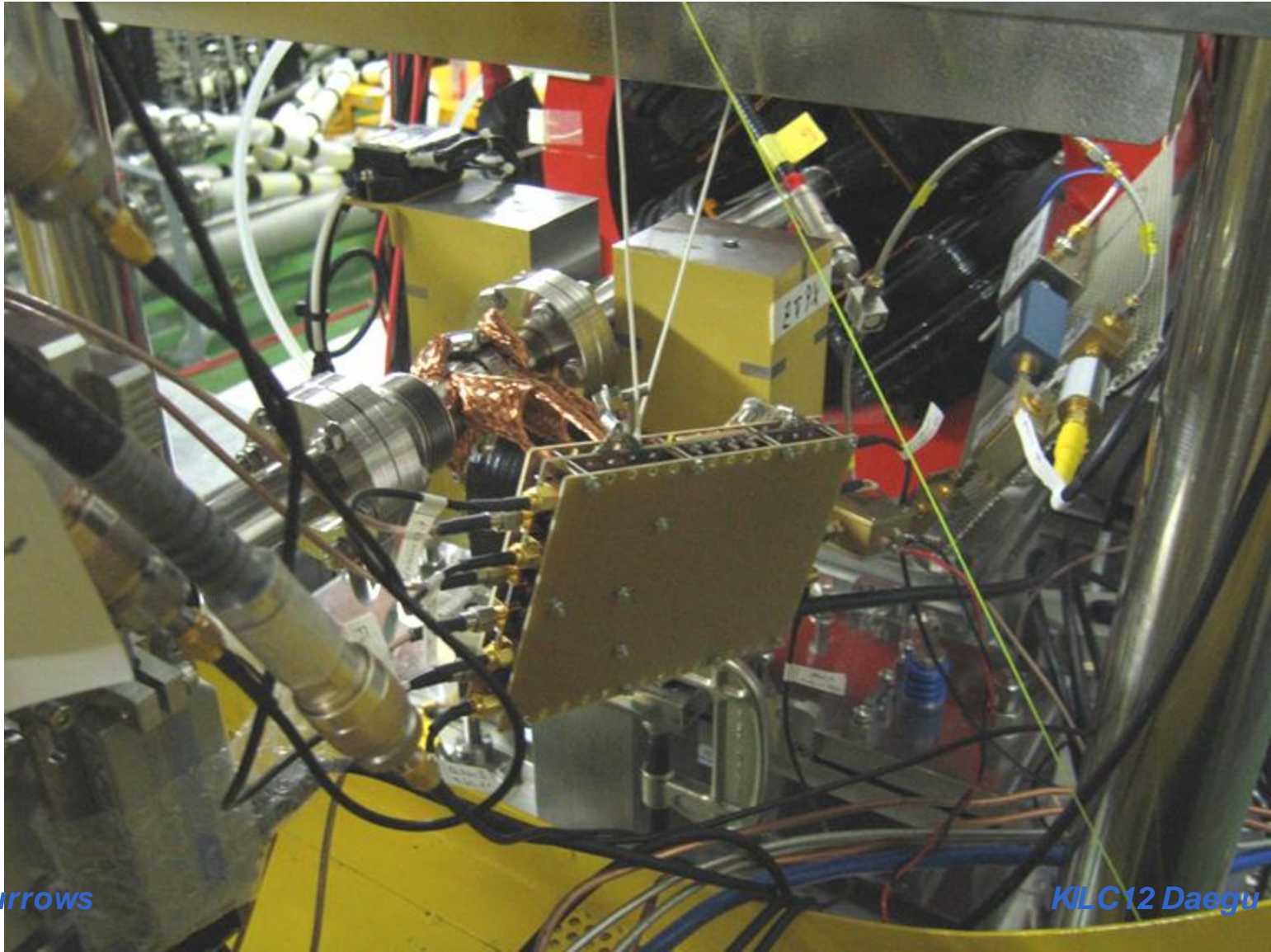
FB board



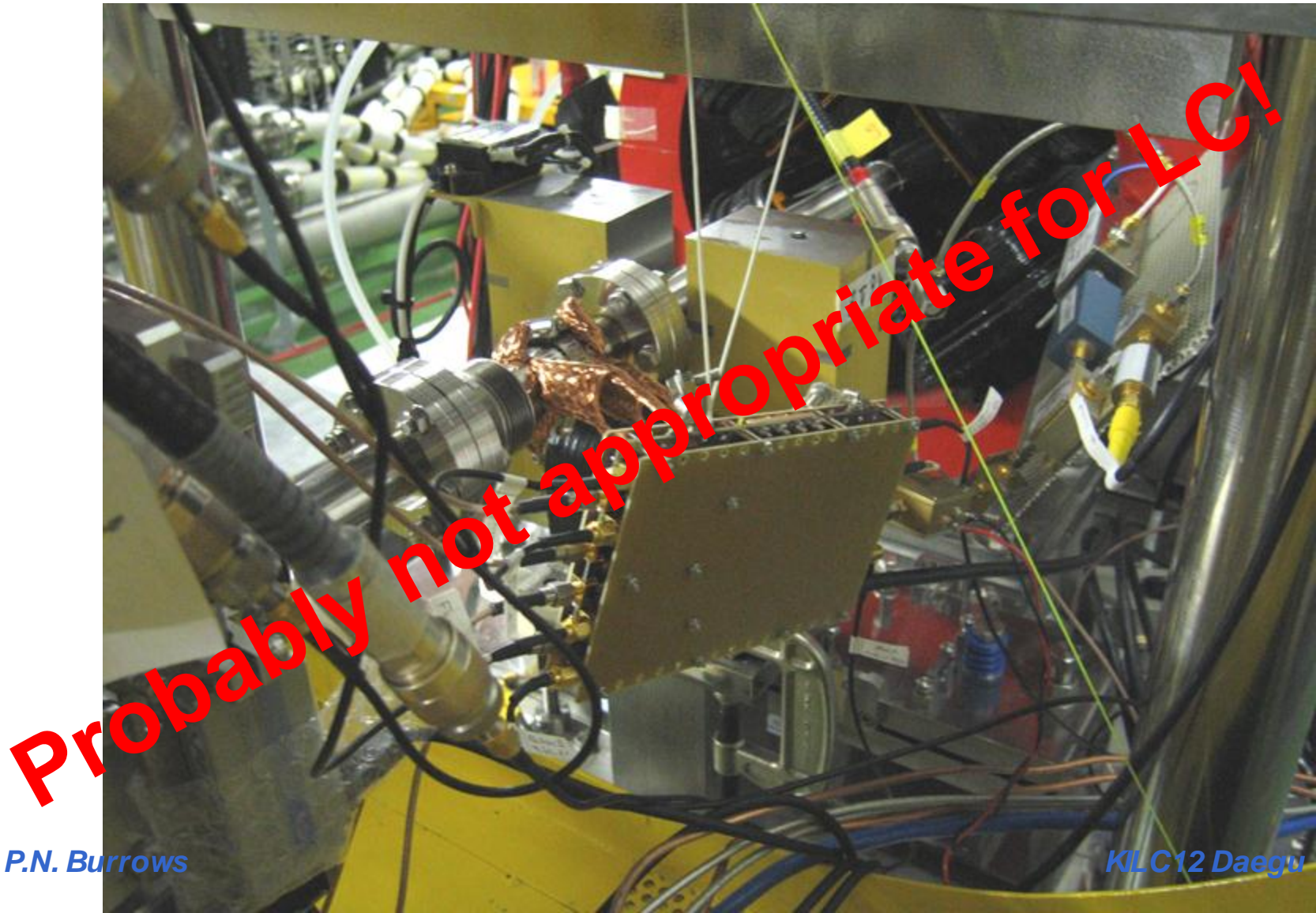
Drive amplifier



A pragmatic approach!



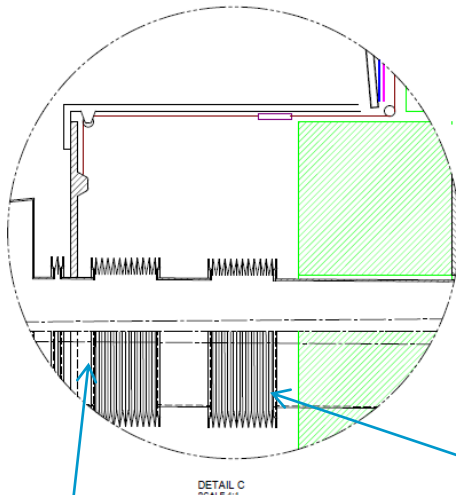
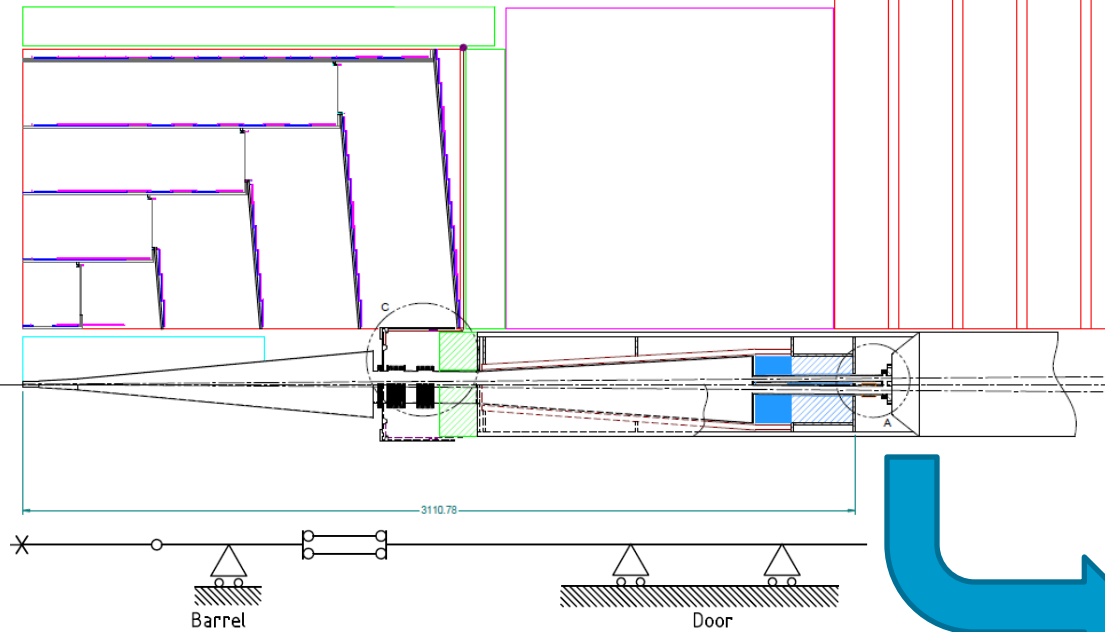
A pragmatic approach!



SiD - R20 region

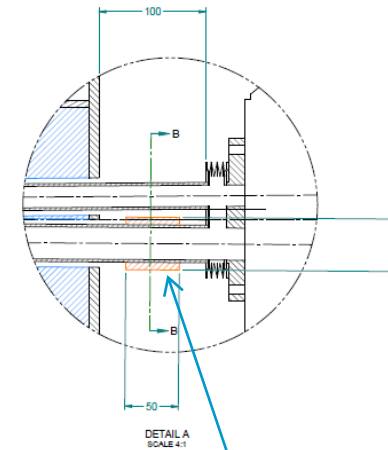
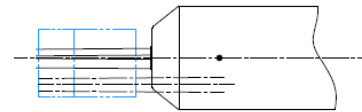
Marco Oriunno

**BPM arrangement,
under study**

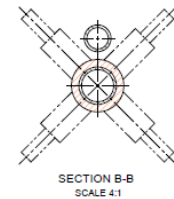


**Single convolution bellow
Kinematic Mount. VTX**

**Multi convolution bellows
Stress Relief QD0 vs. VTX**



**Gap Lumical vs. QD0
BPM for IP Lum. Feedback**



Custom BPM design

Table 1). Beam Position Monitor Transducer Parameters.			
Parameter	Symbol	Value	Comments
Distance to IP	Z_{bpm}	3.2 m	approximate
Duct radius	R	15 mm	
Stripline length	L_{strip}	100 mm	
Stripline roundtrip time	dt	0.67 ns	
Stripline Impedance	Z_{bpm}	50 Ohms	
Stripline Width		4.4 mm	

Steve Smith

Custom kicker design

Table 3. Kicker Parameters.

Parameter	Value	Comments
Distance to IP	8 m	
Duct diameter	2 cm	
Stripline length	1 m	
Stripline roundtrip time	6.7 ns	
Stripline radius	10 mm	
Stripline Impedance	50 Ohms	
Stripline azimuthal coverage	120 degrees	
Chamber inner diameter	34 mm	
Drive voltage needed	140 mV / nm or 28 V max	Per stripline
Drive power	0.4 mW / nm ² or 16 W max	Each amplifier
Maximum IP correction	200 nm	

Steve Smith