

ILD Vertex Detector

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ILD Workshop @Fukuoka

Outline

- Performance goal
- Baseline design
 - Design parameters
 - Pixel technology options
 - Ladders
 - Support structure
 - Cooling system
 - Installation and alignment
- Future prospects
 - Detector upgrade with beam energy
 - R&D needed

Performance goal

- Excellent impact parameter resolution
 $\sigma_{IP} < 5 \oplus 10/p\sin^{3/2}\theta$ [μm]
- Large acceptance
 $\max |\cos\theta| \cong 0.96$ (L1–L3)
 $\cong 0.9$ (outermost layer)
- Low pixel occupancy: $\lesssim \text{few}\%$

Design parameters

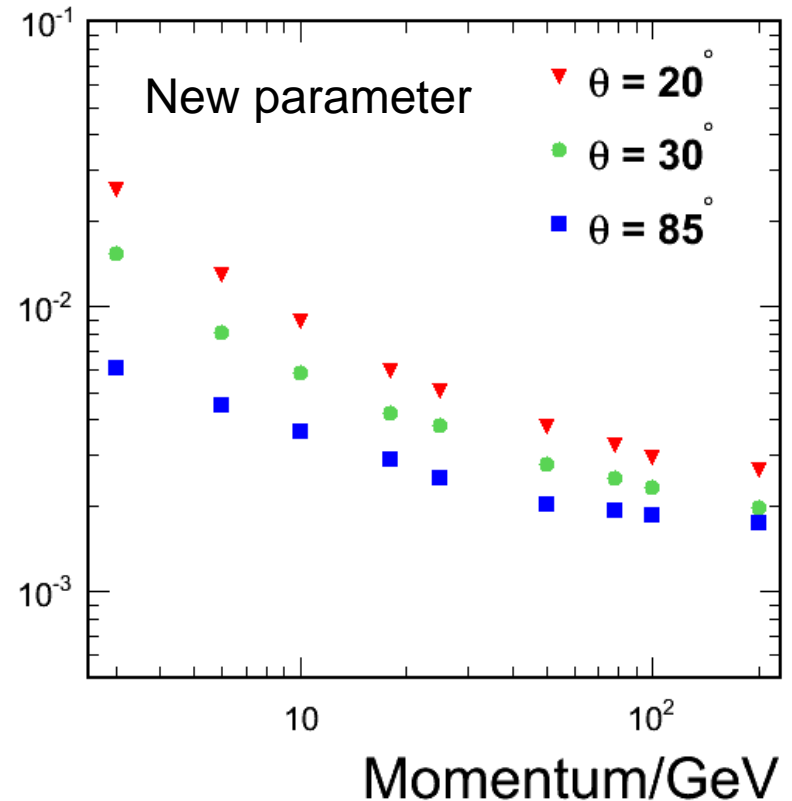
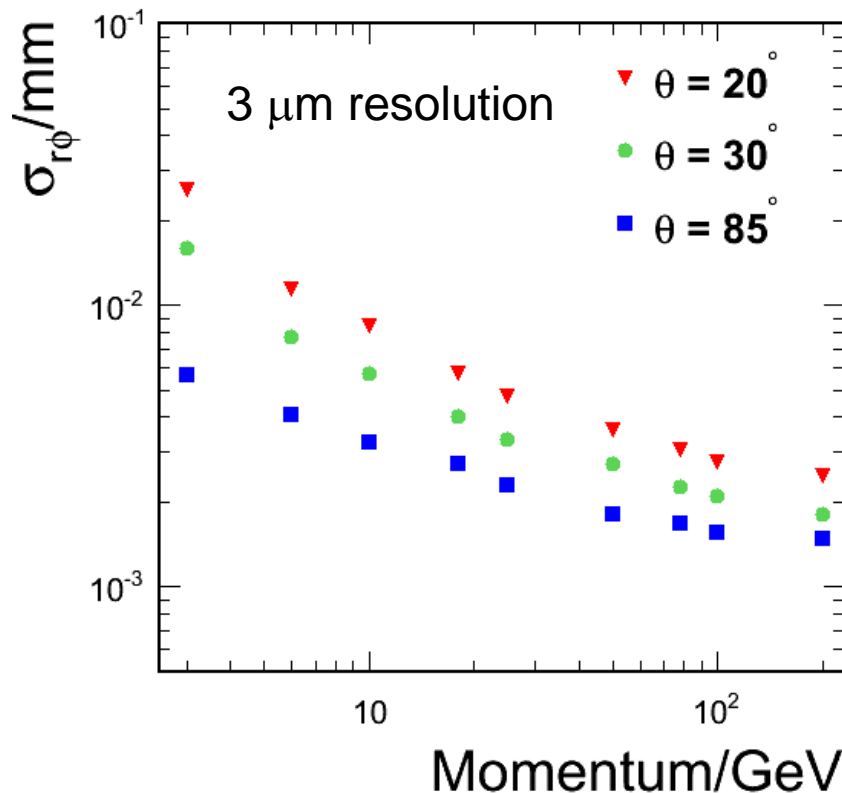
- Overall design
 - Each ladder has sensors on both sides ~2 mm apart
 - Three layers of the double-sided ladders make the vertex detector
 - $R_{in} = 16 \text{ mm}$, $R_{out} = 60 \text{ mm}$
 - Material budget $\sim 0.3\%X_0/\text{ladder} = 0.15\%X_0/\text{layer}$
- Software baseline parameters
 - Conservative parameters which have been demonstrated or seem within our reach will be used
 - It should be noted that the MOKKA simulation model is independent of sensor technology option
 - Difference in sensor technologies (point resolution, etc.) matters only in digitization and reconstruction phase, or in the background study

Design parameters

	R (mm)	Z (mm)	cos θ	σ (μm)	Readout time (μs) (for CMOS)
Layer 1	16	62.5	0.97	2.8	50
Layer 2	18	62.5	0.96	6	10
Layer 3	37	125	0.96	4	100
Layer 4	39	125	0.95	4	100
Layer 5	58	125	0.91	4	100
Layer 6	60	125	0.90	4	100

Design parameters

- Impact parameter resolution
 - Difference is very small



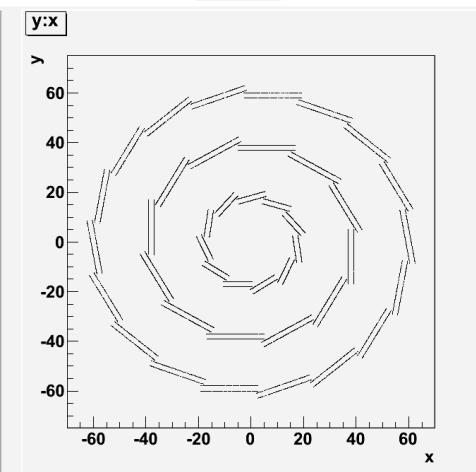
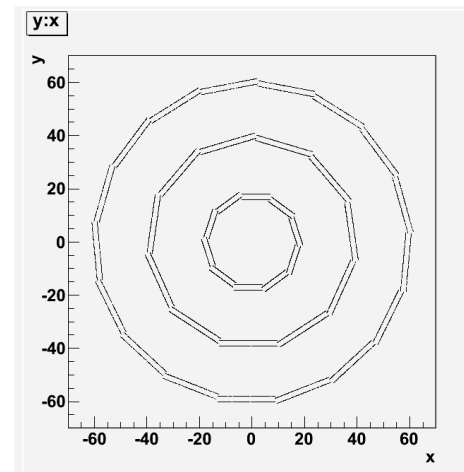
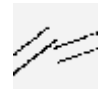
Pixel technology options

- Three sensor technology options seem to satisfy the requirements and are studied actively
 - CMOS
 - FPCCD
 - DEPFET
- Details of each sensor technologies will be presented in different talks later
- Each technology has pros and cons
 - Hybrid design using different sensor options in one vertex detector is not excluded
- Alternative technology options for future upgrade
 - ISIS
 - 3D sensors

Ladders

- Baseline design
 - Rigid foam (SiC or C) core sandwiched by thin ($50\mu\text{m}$) Si sensors
 - SiC core option is actively studied by PLUME collaboration
 - Carbon core option is proposed by FPCCD group
- Alternative design
 - Single sided ladders (5 layers) with or without (DEPFET) support
- Ladder overlapping in the baseline design
 - Two possible ways: layer by layer or ladder by ladder
 - Layer by layer overlapping will be used in the simulation

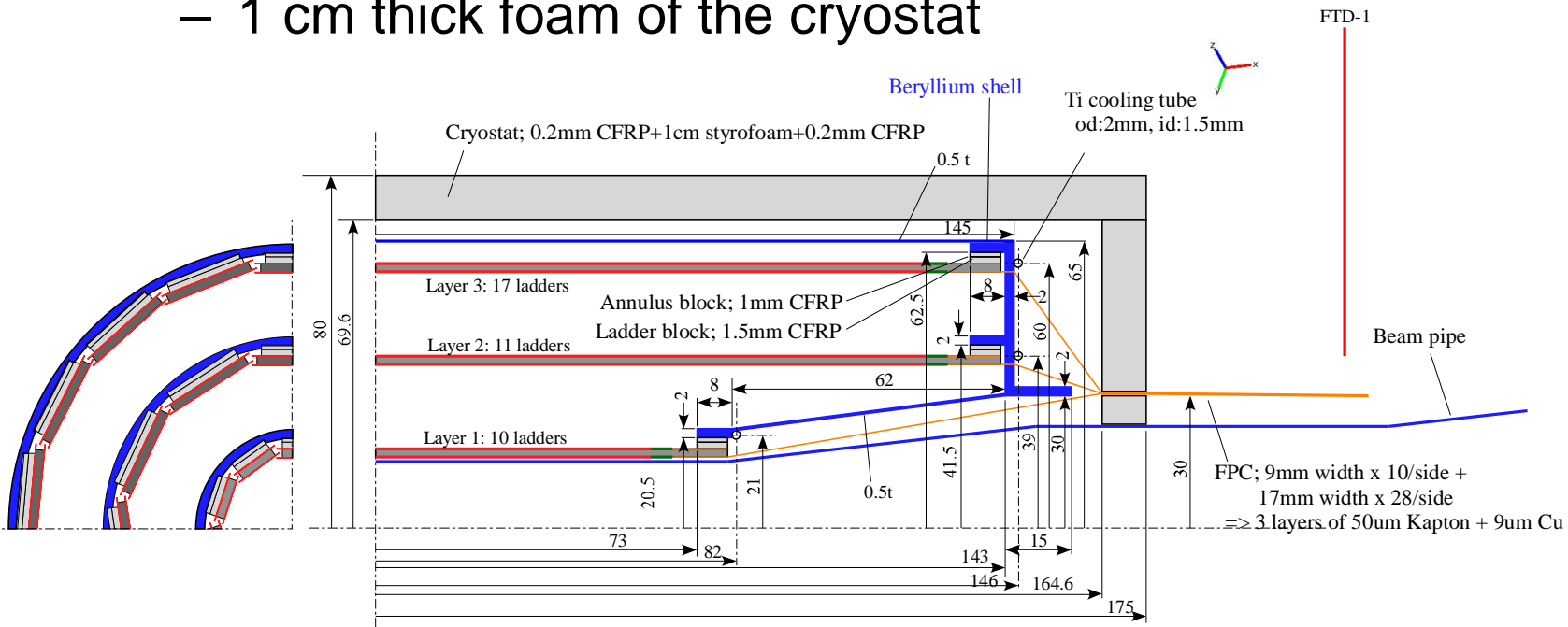
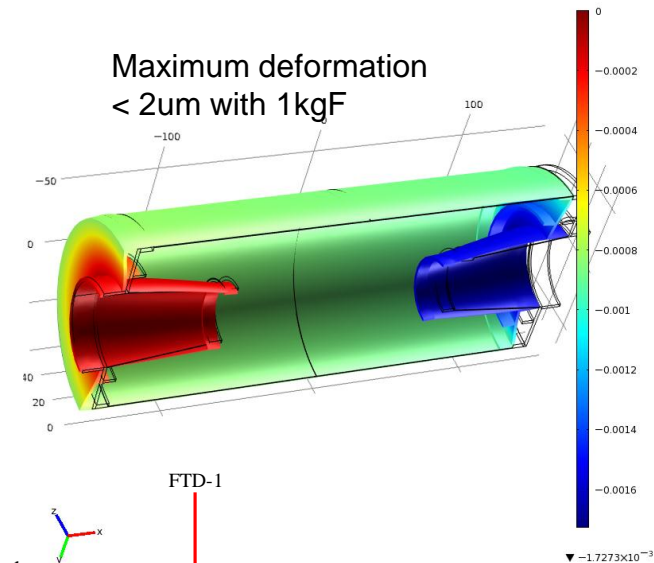
	Width (mm)	# of ladders
Layer 1,2	11	10
Layer 3,4	22	11
Layer 5,6	22	17



Support structure

- Design in ILD simulation model
 - Similar to SLD vertex detector
 - 2 mm thick Be end plate, 0.5 mm thick Be support shell
 - Kapton+Cu flexible cables
 - Ladders
 - 1 cm thick foam of the cryostat

Surface: Displacement field, X component (mm) Surface Deformation: Displacement field



Cooling system

- Two-phase CO₂ cooling system
 - Cooling power of ~300J/g
 - Thin (OD~2mm) cooling tube on the end plate
 - Studied by FPCCD group (P>50W inside the cryostat): target temperature = -40°C
- Gas cooling system
 - Applicable for low power consumption sensors

Installation and alignment

- Installation
 - ILD vertex detector is supported by the beam pipe, and the beam pipe is supported by the inner support tube
 - Integrated to ILD detector as a part of the “inner Si trackers” inside the inner support tube
- Alignment
 - Pre-alignment by optical survey during assembly
 - Precise alignment is achieved by beam-base alignment

Detector upgrade with energy

- Vertex detector is relatively easy to replace
- Detector upgrade with energy upgrade is reasonable
- Particularly at 1TeV where beam background is expected to increase by factor 5, new sensor technologies with much shorter readout time could be used
→ R&D should be continued

R&D needed

- R&D towards the baseline design
- R&D for better performance
- What R&D should be put in the common chapter?

- Detail will be discussed in each option talk