

ILD

Seismic design for ILD Detectors

ILD WebEx Integration Meeting – March 2nd 2012

Seismic Design

- ❖ **Installing the ILC and the associated detector(s) in Japan requires to take into account seismic hazard when designing the instruments**
 - Systems should be designed not to suffer any damage from minor earthquake, which are likely to occur during the lifespan of the instruments
 - Moderate earthquake should result in minor damages only
 - Recovery from a major earthquake should be possible

- ❖ **Systems should be design to resist vertically applied load (gravity) but also horizontal seismic loading**
 - Seismic load is dynamic and can induce forces with the same order of magnitude or higher than gravity in the horizontal direction
 - Even structures with high eigenfrequencies will have to withstand quasi-static loading

- ❖ **Any equipment, whether it is light or heavy, should have proper restrains, able to withstand loading in any direction**
 - Applies to subdetectors but also to ancillary systems: cables, services, electronic racks, tanks

Flexible vs. Rigid design

- ❖ **Two approaches: Rigid structure / Flexible structure**
 - Rigid design
 - Structure with high eigenfrequencies
 - Stiff connections able to withstand high stress levels
 - Limited displacements
 - Flexible design
 - Structure with low eigenfrequencies
 - Large displacements due to flexible connections to avoid stress concentration
 - Favored approach for buildings

- ❖ **Rigid design probably better suited for a HEP detector: small displacements are desirable**
 - Detector needs to be compact, with limited clearance between sub-detectors
 - Gaps are usually filled with cables and services

Design to Standards

- ❖ **Standards provides useful information to evaluate the seismic actions and design seismic resistant structures**
 - Mainly developed for buildings but cover also any equipment installed inside
- ❖ **ISO 3010 – Bases for Design of Structures - Seismic Actions on Structures**
- ❖ **EUROCODE 8 – Design of Structures for Earthquake Resistance**
- ❖ **National Standards or Building Codes**
- ❖ **In Japan**
 - Reference is the Building Standard Law
 - Non official documents but still acceptable: Recommendations from Architectural Institute of Japan (more frequently revised)
 - Released in 1993 updated in 2004
 - Specifications for T2K Neutrino experiment were based on AIJ 1993

Analysis Procedure

❖ **Response spectrum analysis for linear structures**

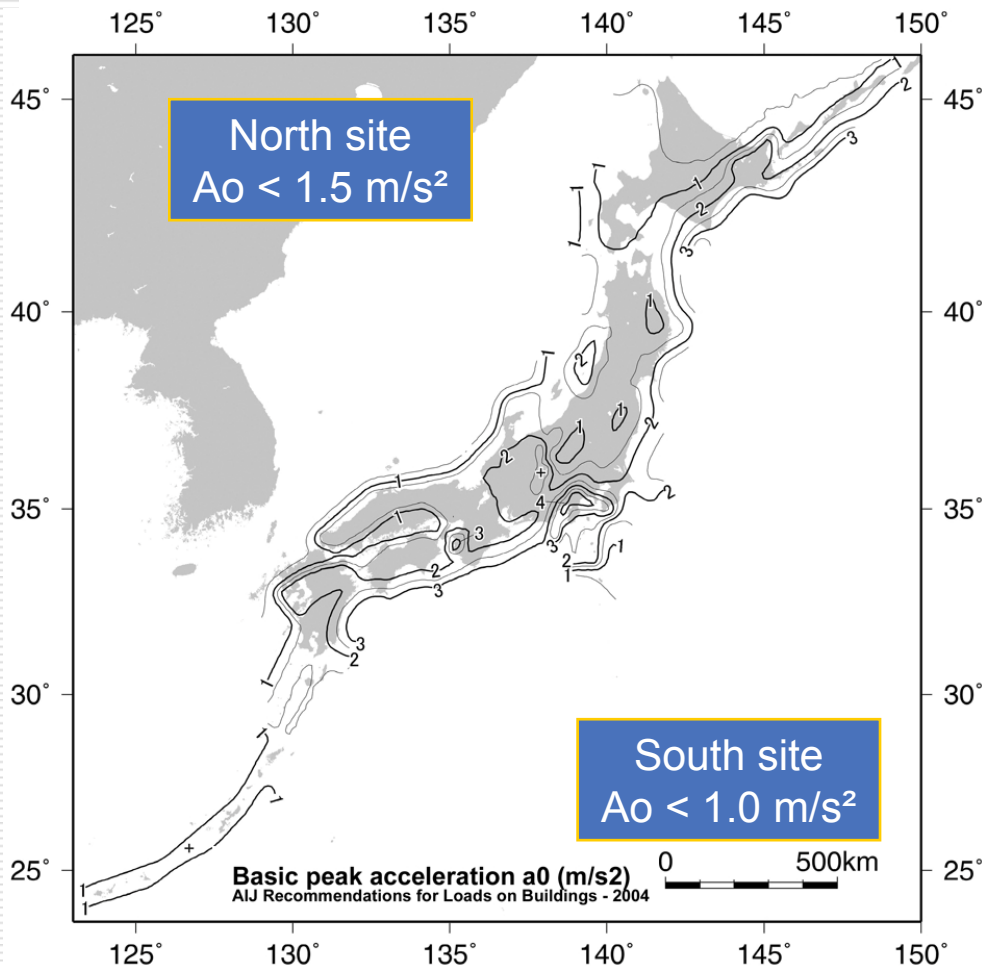
- Define a site specific acceleration response spectrum
- Calculate the eigenfrequencies, enough to account for at least 90% of the participating mass of the structure
- Combine the modal contributions with CQC method
- Combine spatial components (X, Y, Z) with SRSS method

❖ **Time history method for non linear structures**

- Requires sets of ground motion records to be used as load input

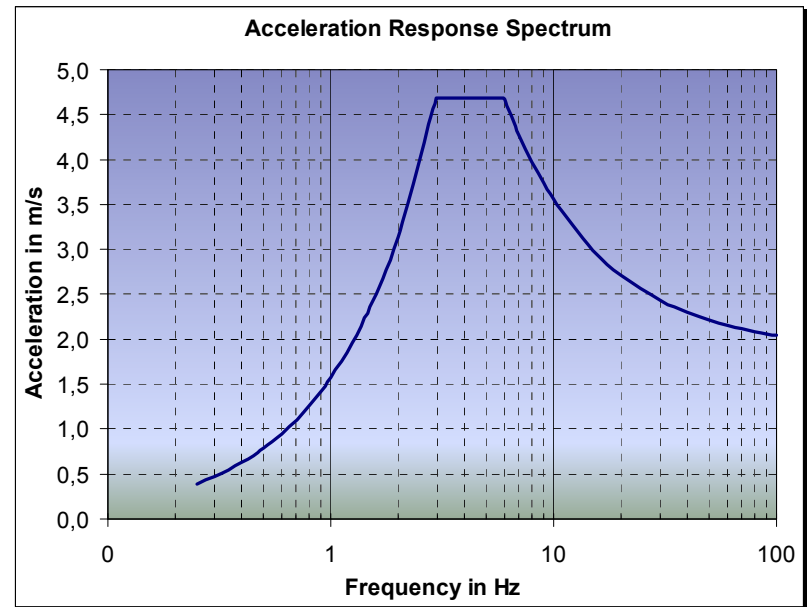
Response Spectrum

Spectrum based on AIJ - 1993



Parameters for acceleration spectrum

- Peak Ground Acceleration: 1.5 m/s^2
- Damping ratio for steel structure: 2%
- Soil type: hard soil



Preliminary Analysis Results

❖ Model: very limited engineering input

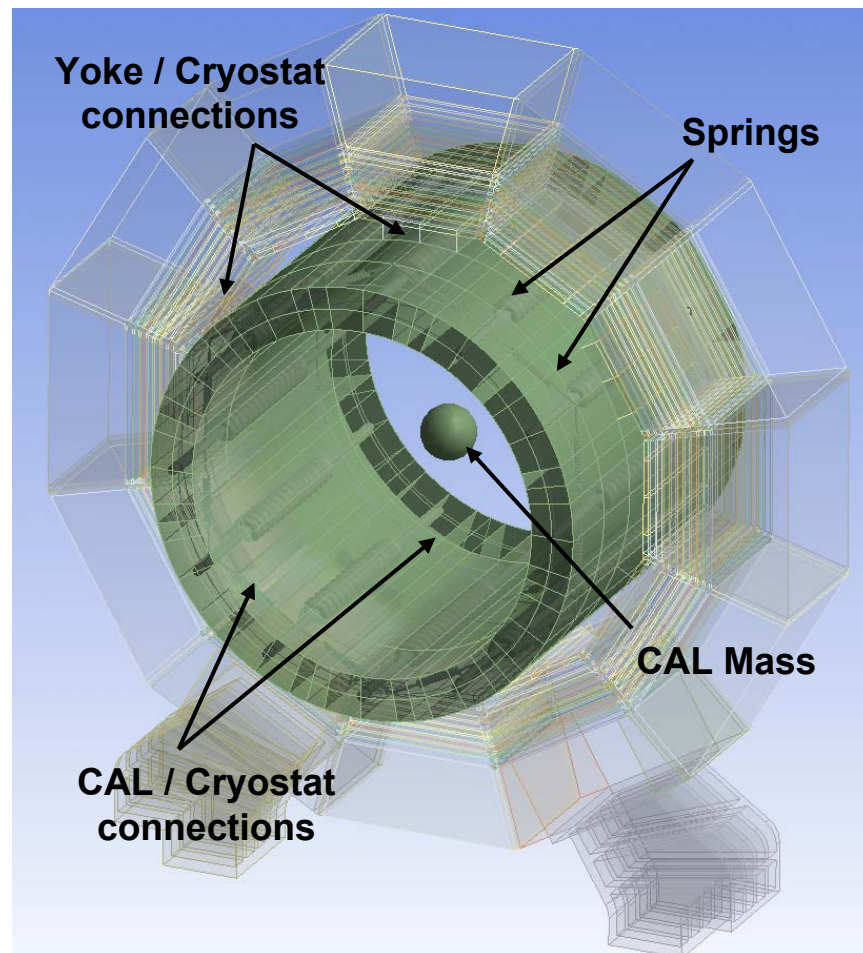
- Central yoke ring with supporting feet, cryostat with coil
- Calorimeters as nodal mass
- ILD dimensions and weights
- CMS type design

❖ Interfaces

- Coil attached to the cryostat with springs
- Radial connections between the cryostat and yoke at the front and the back
- Radial connections between the CAL mass and the inside shell of the cryostat

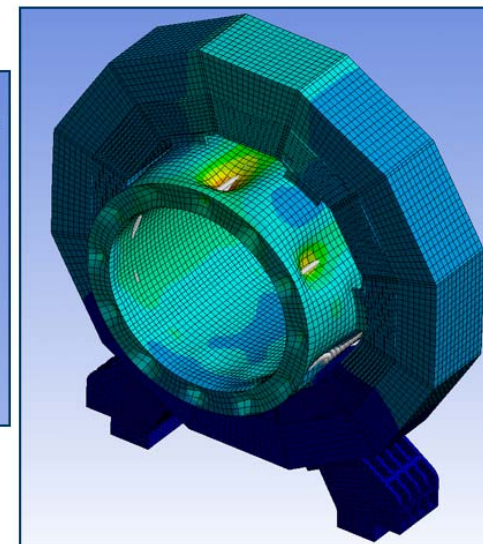
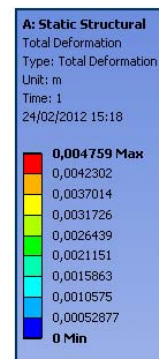
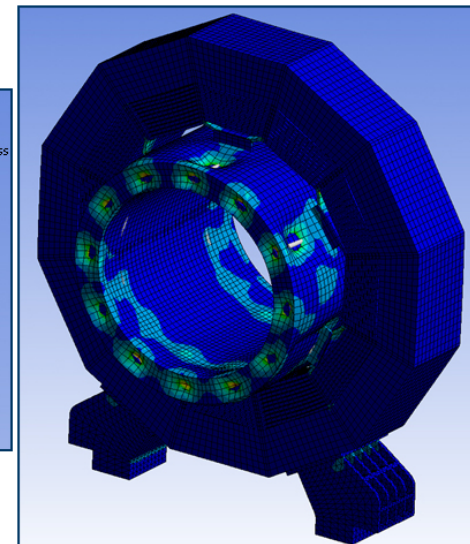
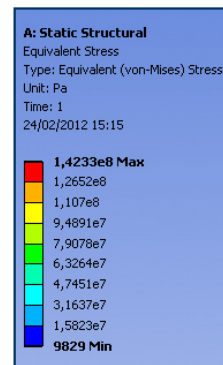
❖ Loads

- Vacuum inside the cryostat
- Gravity
- Seismic load



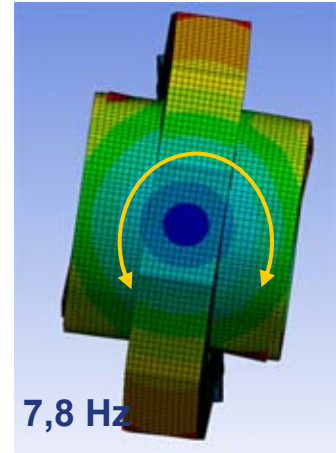
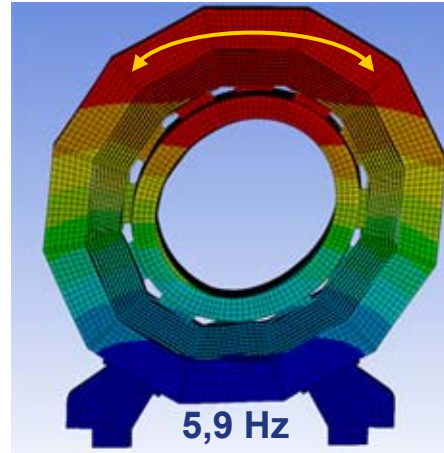
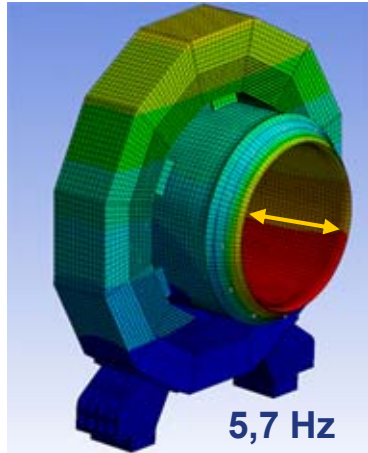
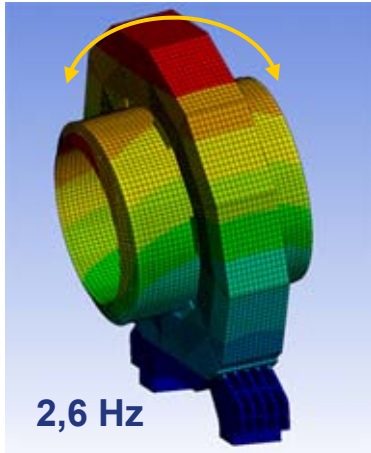
Preliminary results / Static

- ❖ **Static analysis to evaluate the effect of the gravity (vacuum inside cryostat included)**
- ❖ **Peak stress 142 MPa, but very local at the interface between the cryostat and the springs supporting the coil**
 - Not really relevant, better, more detailed model is required
- ❖ **Max displacement 4,7 mm, again at the interface between the coil and cryostat**

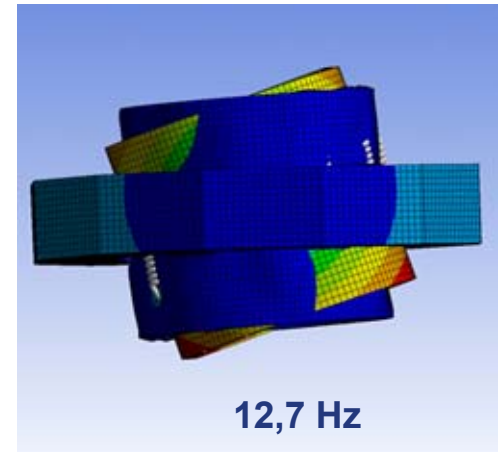
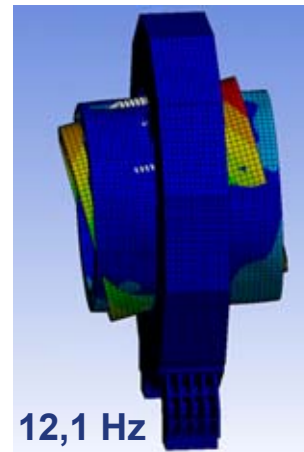
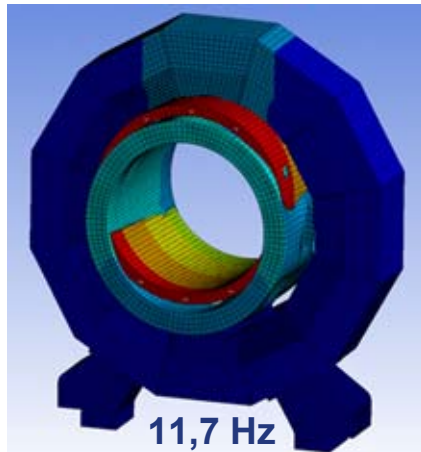
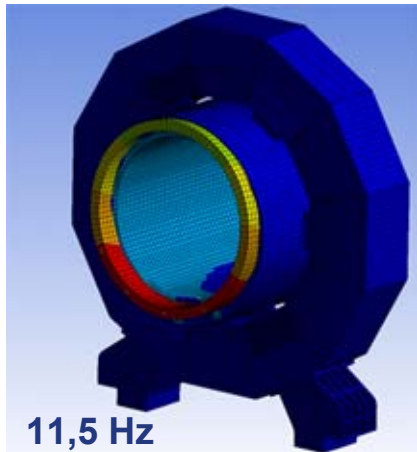


Preliminary results / Eigen Modes

Global modes

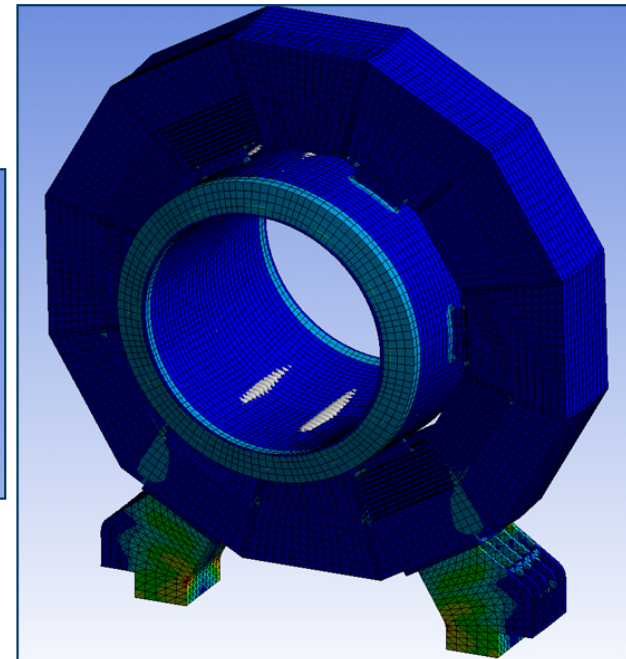
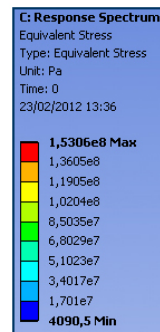
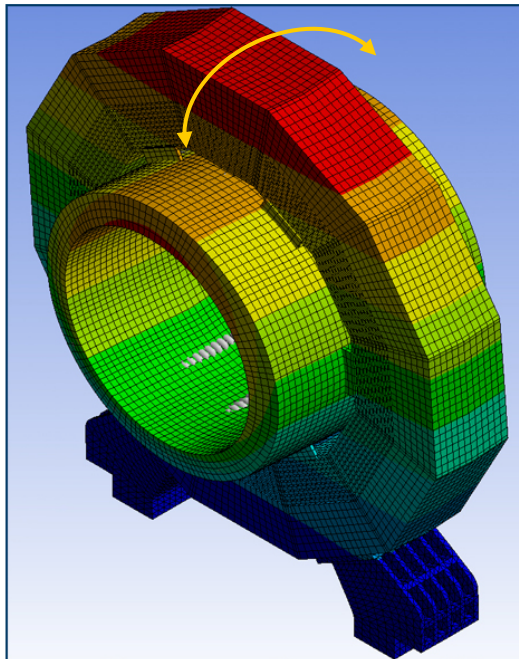


Modes associated with the coil



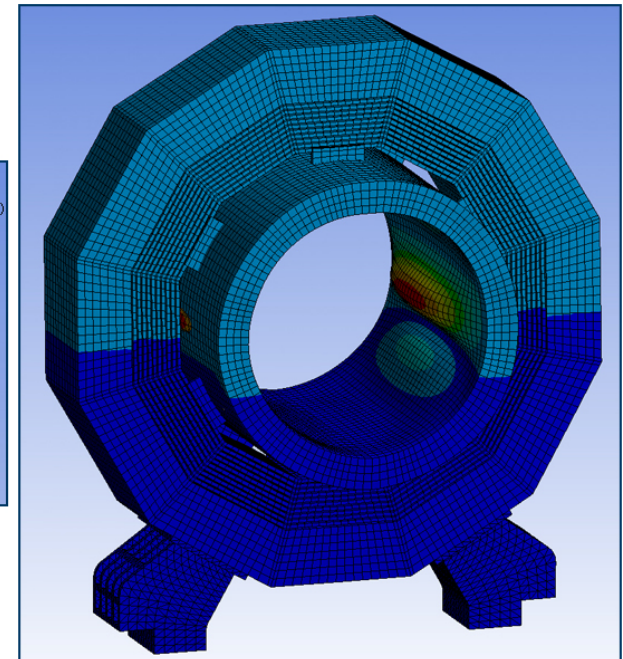
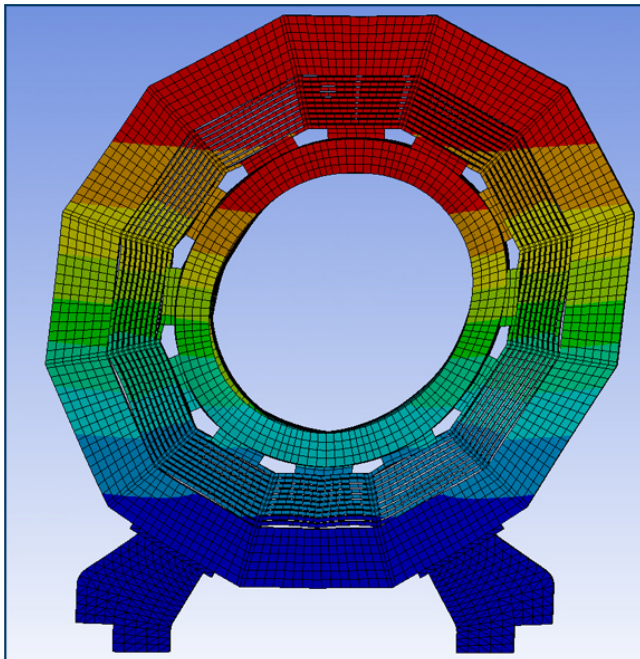
RS Analysis Results

- ❖ With the acceleration response spectrum applied along the detector axis, the fundamental mode of the structure dominates: back and forth motion of the yoke ring
- ❖ The max displacement is around 23mm, which is quite high
- ❖ The peak stress is located in the feet. The level seems acceptable but the results need to be checked with a proper design and model
- ❖ Attaching the 3 rings together is probably the way to go to increase the overall stiffness and reduce the peak displacement



RS Analysis Results

- ❖ **With the acceleration spectrum applied perpendicular to the detector axis, the displacement are significantly lower (less than 5 mm).**
 - Due to its geometry, the yoke ring offers a good resistance to side loading
 - The effect is still not negligible
- ❖ **With a rail type support, the effect is local: it affects only the calorimeters. The peak displacement increased to around 15 mm**



Conclusion

- ❖ **Seismic load is a major load case that needs to be taken into account when designing instruments to be installed in Japan**
- ❖ **Detectors and ancillary systems should be designed to be seismic resistant**
- ❖ **It is desirable to take into account those aspects as soon as possible in the design phase of the instruments**
- ❖ **Additional and stronger mechanical connections are needed to resist loading from various direction, which significantly impacts the assembly procedure of the detector**