# ML-SCRF: Monthly WebEx Meeting August 22, 2012

- 1. Reports from PMs
  - GDE activity and meeting plan
  - LCWS2012: Arlignton Texas
- 2. Reports from TA Group Leaders (very briefly, if any?)
  - Cavity, Cavity Integration, Cryomodule, Cryogenics, HLRF, ML
- 3. Special Discussions on TDR
  - TDR Status J. Carwardine
  - TDR1-SCRF E. Elsen and A. Yamamoto
  - TDR2-ML-SCRF N. Walker and A. Yamamoto
  - Comments K. Yokoya
- 4. LCWS preparation
  - TDR finalization session
     M. Ross, N. Walker, and A. Yamamoto
  - SCRF parallel session
     H. Hayano and A. Yamamoto

# ML & SCRF Action/Meeting Plan (2012)

Month	Day	Place	Meeting
July	4-11 12-13 25		36 <sup>th</sup> ICHEP (Melbourne) GDE-EC face-to-face Meeting (TDR draft discussed) ML-SCRF Meeting
Aug.	22		ML-SCRF Meeting
Sept.	10-14	Telaviv	Linac-2012
Oct.	3 22-26 29-30	Texas Anaheim	ML-SCRF meeting LCWS (TDR draft to be finalized) IEEE-NS (LC event)
Nov.	5-8 13-14	JLab	TTC ILC-GDE internal cost review
Dec.	13-14	KEK	ILC-PAC (@ KEK)

### **LCWS 2012**

- LCWS12: International Workshop on Future Linear Colliders 2012
- Dates: Oct. 22 ~ 26
- Held at: Arlington, Texas
  - http://www.uta.edu/physics/lcws12/
  - Accommodation
    - http://www.uta.edu/physics/lcws12/pages/accomodation.html
- Program
  - 22(Mon): Joint plenary, Accelerator plenary
  - 23(Tue): ILC-CLIC Common issues
    - am: Emittance preservation, Power consumption
    - Pm1: System tests, and cost & schedule
    - Pm2: Higgs Factory session (Joint session of accelerator and physics)
  - 24(Wed): Accelerator: CLIC & ILC separate programs
    - Finalizing TDR
  - 25(Thu): Working Groups: Parallel Sessions
    - SCRF/NCRF >> Convener H. Hayano
  - 26(Fri): Accelerator plenary, Joint plenary (~ 13:00)



# **IEEE -NSS Symposium:**

**Nuclear Science Symposium** 

Institute of Electrical and Electronics Engineers **2012 IEEE NSS/MIC/RTSD Anaheim, California** 27 October - 3 November 2012

#### Conference Information

#### **Special Linear Collider Event** 29-30 October 2012

Introduction & Motivation

Agenda for the "SPECIAL LINEAR COLLIDER EVENT"

LC 6 Session:

Accelerator Technologies for Industrial Applications (Invitation to Industrial Partners)

#### Registration

register over <u>IEEE NSS and MIC</u>
web site. Pre- registration is
available online over IEEE
registration

All participants are required to

#### Accommodation

Hotel reservation information can be found under <u>IEEE NSS web</u> As part of the NSS Symposium, a special Linear Collider (LC) event is organized, which will include presentations on:

International Linear Collider (ILC) and the Compact Linear Collider (CLIC) accelerator

**Detector concepts** 

Impact of LC technologies for industrial applications

Forum discussion about LC perspectives

James Brau, University of Oregon, USA
Juan Fuster, IFIC Valencia, Spain
Michael Harrison, BNL, USA
Steinar Stapnes, CERN, Switzerland
Hitoshi Yamamoto, Tohoku University, Japan
Maxim Titov, IRFU/CEA Saclay, France (ex of
Ingrid-Maria Gregor, DESY Hamburg, German

SCRE^121003

**SERF WebEx Meeting** 

### ILC Special Event: Agenda

**Session 1: Introduction** Welcome: R. Heier (CERN) ILC: B. Barish (Caltech CLIC S. Steinar (CERN) H. Murayama (IPMU-Tokyo, LBNL) Physic of LC: Session 2: ILC/CLIC accelerator and Detector Concept SCRF acceleration and ILC: N. Walker (DESY) X-band, two-beam acceleration and CLIC D. Schulte (CERN) Vertec Detector LC: M. Winter (IPHC, CNRS/IN2P3) Silicon Tracking for LC T. Nelson (SLAC) Session 3: ILC/CLIC Detector Concept and Summary of Detector Spin-offs Gaseous tracking for LC T. Matsuda EM Calorimetry for LC J-C Brient (Ecole Polytechniques, CNRS/IN2P3) Hadron Alorimetery for LC J. Repond (ANL) Forward calorimetry and ... S. Kulis (AGH Univ. ST Cracow) Spin-off Document "ILC Detector R&D" M. Demarteau (ANL) Session 4: ILC/CLIC detector spin-off and ILC/CLIC Accelerator Instrumentation From ILC imaging calorimeter to a PET E. Grautti (U. Hamburg) LC Spin-offs outside Medial Imaging C. de la Taille (IN2P3/CNRS) LC instrumentation T. Lefevre (CERN) Linear Collider module control and stabil. A Jeremie (LAPP, CNRS/IN2P3) Session 5: ILC/CLIC Accelerator Technologiew for Industrial Applications I Opportunties for applications of LC technology M. Ross (SLAC) Overview of industrial, medical, energy, and ... N. Holtkamp (SLAC) Application of SCRF LC J. Rathke (AES) Application of NCRF LC W. Wuensch (CERN) Aplication of LC supporting RF Technology S. Lenci (Communications & Power Industries, LLC) Session 6: ILC/CLIC Accelerator Technologies for Industrial Applications II Application of LC supporting instrumentation M. Ross (SLAC) The Status of AAA M. Matsuoka (AAA, Japan) **Session 7: Forum Discussion about LC perspetives** 



### **TDR Publication and Review**

First-draft sections	* 23 April *
Complete edited draft	22 October (LCWS 12)
Final draft (for PAC)	15 November
PAC review	15-16 December

Formal publication at Lepton Photon Conf. (SF, June 2013)



Expect international reviews:

Both technical and cost (Q1-22 2013)

### **ILC TDR public**

### https://forge.linearcollider.org/tdr

TDR – ILC TDR public – ILC Forge 12/06/26 20:09

#### Portal for Authors and Editors of the ILC Technical Design Report

#### TDR Editorial Team

Chair: John Carwardine (Argonne)

Editors, Part-I: Eckhard Elsen (DESY), Hitoshi Hayano (KEK)

Editors, Part-II: Phil Burrows (OXON), Nan Phinney (SLAC), Kaoru Yokoya (KEK), Nobu Toge (KEK)

Project Managers: Marc Ross (Fermilab), Nick Walker (DESY), Akira Yamomoto (KEK)

Technical Editors: Maura Barone (Fermilab), Benno List (DESY)

#### Reference material for the TDR Baseline Design

- Top-Level ILC Parameter Tables (EDMS)
- Technical Design Documentation Portal (linearcollider.org)

#### File uploader

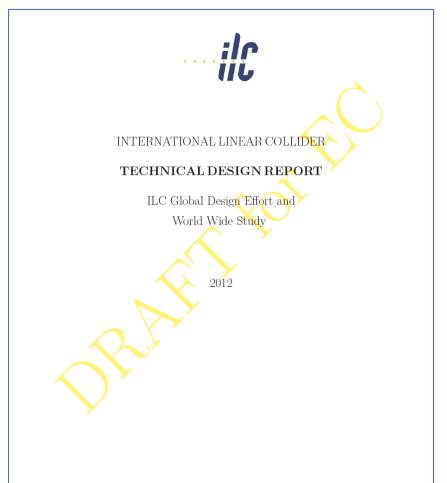
Select the 'Upload files' button below to start uploading your content (text and/or images). Please remind that figures should be uploaded as separate files from the text, possibly in original.

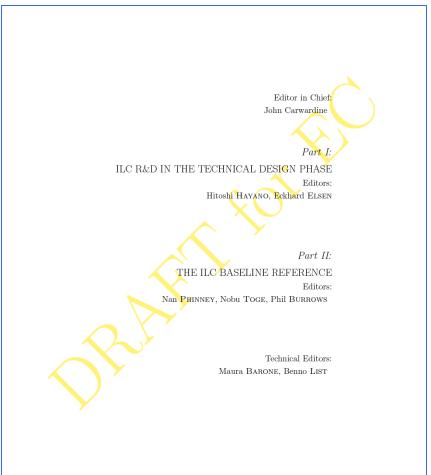
A pop-up window will open, from there:

- Enter your email address and the <u>common password</u> (ilctdr) note: that's a common password for all the TDR authors, valid for the file upload only, it's not your Forge password!
- Select the chapter using the drop-down menu
- . Add the files to upload using the 'Add files' button you can add up to 20 files at a time
- . Hit 'Start upload' (IMPORTANT: files will not be uploaded to the server until you hit 'start')
- The figures will be submitted to a staging area for printing quality check. You will be contacted if the image quality is unsatisfactory for printing.

Upload files

# ILC Technical Design Report status as of Oct. 1, 2012





# **TDR: Part 1 (1)**

#### Table of Contents

1	1 Introduction								
2	Suj	Superconducting RF technology							
	2.1	Overv	iew	5					
	2.2	Develo	opment of cavity infrastructure and R&D	9					
		2.2.1	Inspection infrastructure and capabilities	9					
		2.2.2	Cavity Tuning	11					
		2.2.3	Second sound quench detection and temperature mapping $\ .$ .	11					
		2.2.4	Production and test facilities	12					
		2.2.5	Test infrastructure and measurement techniques	16					
		2.2.6	Field emission	17					
		2.2.7	Remediation technique	18					
		2.2.8	Development of coupler R&D and production infrastructure .	19					
	2.3	High-g	gradient SCRF cavity R&D and yield evaluation	22					
		2.3.1	Baseline cavity	22					
		2.3.2	Results of ILC high-gradient cavity R&D program $\ \ldots \ \ldots$	27					
		2.3.3	Global cavity database and yield evaluation	35					
		2.3.4	Alternate cavity development	37					
		2.3.5	ILC 1 TeV upgrade	40					
	2.4	Cavity	y integration	42					
		2.4.1	The frequency tuners	42					
		2.4.2	The fundamental power couplers $\dots \dots \dots$ .	50					
		2.4.3	The magnetic shields R&D $\ \ldots \ \ldots \ \ldots \ \ldots$	54					
		2.4.4	Conclusion of cavity integration R&D $\ \ldots \ \ldots \ \ldots$	55					
	2.5	The S	1-Global experiment	56					
		2.5.1	Cavities and Couplers	58					

	2.5.2	Tuners	59
	2.5.3	Cryomodules and Cryogenics	59
	2.5.4	HLRF and LLRF	61
	2.5.5	Single cavity performance test	63
	2.5.6	The causes of the tuner failures. $\hdots$	63
	2.5.7	Cavity performance & issue	64
	2.5.8	Power coupler conditioning $\ldots \ldots \ldots \ldots$	66
	2.5.9	LFD measurement	66
	2.5.10	Compensation of LFD by piezo tuning	67
	2.5.11	Summary of single cavity operation	68
	2.5.12	Operation of Seven Cavities with Vector-sum Feedback Control $$	69
	2.5.13	Detuning Measurement during Long Time Operation	69
	2.5.14	Simultaneous operation of seven cavities	69
	2.5.15	Conclusion of S1-Global experiment	70
2.6	Cryom	odule, cryogenic thermal balance and quadrupole R&D	72
	2.6.1	Measurements of the thermal performances of the S1-Global modules	73
	2.6.2	Measurements of the thermal performances of the XFEL pro-	13
	2.0.2	totype modules	76
	2.6.3	Measurements of the thermal performances of the NML CM1	-
	0.0.4	(1-2 pg)	78
	2.6.4	Cryogenic thermal balance and Baseline TDR cryomodule	78
	2.6.5	R&D on the split quadrupole	79
2.7	-	wer generation and distribution	82
	2.7.1	Overview of HLRF R&D in the Technical Design Phase	82
	2.7.2	HLRF system in FLASH and European XFEL	83
	2.7.3	Test Station Development at STF in KEK	84
	2.7.4	Waveguide Components R&D	85
	2.7.5	R&D of the DRFS (Distributed RF Scheme)	88
	2.7.6	R&D of the Klystron Cluster RF Scheme	90
	2.7.7	Experimental program	93
	2.7.8	Sheet-beam klystrons	93
2.8		towards mass-production and design for manufacture	94
	2.8.1	R&D and Studies towards Industrialization of Cavities	94
	2.8.2	${\rm R\&D}$ and Studies towards Industrialization of Cryomodules .	96
	2.8.3	A production model for the ILC cold components	97

iv

# **TDR: Part 1 (2)**

3	Bea	am Tes	t Facilities	99
	3.1	Overvi	iew	99
		3.1.1	Main Linac Technology $\ \ldots \ \ldots \ \ldots \ \ldots \ \ldots$	100
		3.1.2	Electron cloud R&D program	101
		3.1.3	Final Focus optics and stabilization R&D program	103
	3.2	FLASI	H 9 mA experiment	105
		3.2.1	Introduction	105
		3.2.2	FLASH Overview	105
		3.2.3	Preamble to 9 mA Experiment results	109
		3.2.4	High-power long-pulse studies	110
		3.2.5	HOM absorber studies	112
		3.2.6	Klystron saturation studies $\hdots$	112
		3.2.7	Gradient studies: beam operation close to quench $\ \ \ldots \ \ \ldots$	113
		3.2.8	Gradient tilts from beam loading: gradient flattening studies	114
		3.2.9	Lorentz-force detuning compensation studies $\ \ldots \ \ldots \ \ldots$	116
		3.2.10	Energy stability results	119
		3.2.11	Linac Operations	120
		3.2.12	Ramp-up to full beam power and maximum gradients $\ . \ . \ .$ .	123
		3.2.13	Conclusions	123
	3.3	STF b	eam test facility at KEK	125
		3.3.1	Introduction  .  .  .  .  .  .  .  .  .	125
		3.3.2	Quantum-Beam Accelerator as an injector for STF-2	125
		3.3.3	The STF-2 accelerator	129
	3.4	Fermil	ab Cryomodule 1 Test	130
		3.4.1	$Introduction/Goals \ . \ . \ . \ . \ . \ . \ . \ . \ . \ $	130
		3.4.2	Commissioning & Testing Protocol	130
		3.4.3	Cold coupler conditioning and performance $\ \ldots \ \ldots \ \ldots$	131
		3.4.4	Ancillary Systems and Findings	136
		3.4.5	9 millisecond Pulse Tests $\ \ldots \ \ldots \ \ldots \ \ldots$	137
		3.4.6	Future Prospects	137
		3.4.7	Summary	137
	3.5	CesrT	A and electron-cloud R&D	139
		3.5.1	Introduction to the Electron Cloud R&D Program $\ .\ .\ .\ .$ .	139
		3.5.2	The CesrTA R&D Programme $\ \ldots \ \ldots \ \ldots \ \ldots$	139
		3.5.3	Electron Cloud R&D at Other Laboratories	148

		3.5.4	Electron Cloud Mitigation Recommendations 150
	3.6	ATF2	Final Focus experiment
		3.6.1	Introduction
		3.6.2	Status of ATF2 systems
		3.6.3	Tuning Status Towards Achievement of Goal 1 $\ \ldots \ \ldots \ 156$
		3.6.4	Post TDR plan
4	Acc	celerat	or Systems R&D 163
	4.1	Overv	iew
	4.2	Polaria	zed electron source
		4.2.1	Beam Parameters
		4.2.2	System Description
	4.3	Positre	on Source
		4.3.1	Overview
		4.3.2	Undulator
		4.3.3	Conversion target
		4.3.4	OMD
		4.3.5	Photon collimator
		4.3.6	Normal conducting RF accelerating structure prototyping and RF breakdown Study $\dots\dots\dots\dots\dots\dots$ 176
		4.3.7	Performance simulation
		4.3.8	Lattice design
		4.3.9	Remote handling and radiation shielding 179
		4.3.10	Alternative source
	4.4	Damp	ing ring
		4.4.1	Electron cloud mitigation
		4.4.2	Ultra-low emittance operation
		4.4.3	Performance of fast injection/extraction kickers 185
	4.5	$\operatorname{Beam}$	Delivery System and MDI
	4.6	$\operatorname{Beam}$	dynamics (simulations)
		4.6.1	Overview
		4.6.2	Sources of Luminosity Degradation
		4.6.3	Impact of Static Imperfections
		4.6.4	Dynamic Effects
		4.6.5	Optics for the Upgrade to 1 TeV

vi

# **TDR: Part 1 (3)**

5	Co	nventic	onal Facilities and Siting Studies	205					
	5.1	Analy	sis of options	205					
	5.2	Descri	ption of studies	211					
		5.2.1	Americas Region	211					
		5.2.2	Asian Region	213					
		5.2.3	European Region	213					
6	Eve	olution	of the ILC design in the Technical Design Phase	217					
	6.1	The g	oals of the Technical Design Phase	217					
	6.2	Appro	ach to cost constraint and re-baselining the ILC	220					
	6.3	Propo	sed top-level design modifications and their impact	221					
	6.4	Impac	t of design modifications on CFS	224					
	6.5	Summ	ary	$^{224}$					
7	Do	or The	R R&D	225					
1	7.1		Program	225					
	7.2		erator Design and Integration	226					
	1.2	7.2.1	Physics Requirements	226					
		7.2.2	Projects using ILC-derived technology	227					
		7.2.3	Site Studies	228					
	7.3		Linac Technical Component R&D	228					
	1.3	7.3.1	Beam Test Facilities – Superconducting Linac Technology	229					
		7.3.2	Cavity gradient	230					
		7.3.3	Cryomodule	230					
		7.3.4	Industrialisation	230					
	7.4	Beam	Test Facilities	231					
		7.4.1	Electron Cloud – Cesr Test Accelerator (CesrTA)	231					
		7.4.2	Beam Delivery – Accelerator Test Facility (ATF / ATF2)	232					
	7.5	Remai	ining R&D at other facilities	233					
		7.5.1	Positron source	233					
		7.5.2	Beam-Delivery System (BDS) and Machine-Detector Interface (MDI)	233					
8	Sur	mmary 2							

#### Chapter 1

#### Introduction



Figure 1.1. A superconducting nine-cell 1.3 GHz resonator (cavity).

Although the ILC Reference Design Report published in 2007 [1] presented a relatively mature and low-risk design for a 200—500 GeV  $e^+e^-$  linear collider, it also clearly identified and prioritised several areas of risk in that design which required further R&D before such a challenging project could be proposed for construction. The highest-priority R&D items were:

- 1. SRF cavities capable of reproducibly achieving at least 35 MV/m.
- 2. A cryomodule consisting of eight or more cavities, operating at a gradient of  $31.5\,\mathrm{MV/m}$
- Linac string test (or integration test) of more than one cryomodule linac with beam.
- 4. Development of models and mitigation techniques for electron cloud effects in the positron damping ring.

Other R&D areas (for example in the beam delivery system and the sources) were also identified.

The first three priority R&D items all relate to the SCRF linear accelerator technology, the primary cost driver of the machine, and are discussed in Chapter 2.

1

1711

# **TDR: Part 2 (1)**

#### Table of Contents

1	Introduction								
2 General Parameters, Layout and Systems Overview									
	2.1 Introduction								
	2.2	2 Top-Level Parameters							
		2.2.1	Physics related machine parameters for 200–500 GeV centre-of-mass running	7					
		2.2.2	Special considerations for running at low centre-of-mass energy	9					
	2.3	Accele	rator Layout and Design	10					
		2.3.1	Superconducting RF Main Linacs	10					
		2.3.2	Electron Source	13					
		2.3.3	Positron Source	14					
		2.3.4	Damping Rings	15					
		2.3.5	Ring to Main Linac	17					
		2.3.6	Beam Delivery System	18					
	2.4	Site D	ependent Designs	20					
		2.4.1	Flat topography site-dependent design (Americas and European sample sites)	21					
		2.4.2	Mountainous-topography site-dependent design (Asian sample sites)	22					
	2.5	Lumin	osity and Energy Upgrade Options	25					
3	SC	RF Lir	nac Technology	27					
	3.1	Main	linac top-level parameters and general layout	27					
		3.1.1	Overview	27					
		3.1.2	Beam Parameters	27					
		3.1.3	System description	29					

	3.1.4	Accelerator Physics	3
	3.1.5	Operation and Upgrades	3
	3.1.6	Linac Systems	3
3.2	Cavity	performance and production specifications	3
	3.2.1	Overview	3
	3.2.2	Cavity Design	3
	3.2.3	Cavity fabrication and surface processing $\ \ldots \ \ldots \ \ldots$	3
	3.2.4	Procedure of cavity testing	3
3.3	Cavity	integration	4
	3.3.1	Fundamental-mode power coupler	4
	3.3.2	Frequency tuner	4
	3.3.3	HOM couplers	4
	3.3.4	Helium jacket and its interface	4
	3.3.5	Plug-compatible design	4
	3.3.6	Test procedure for input couplers	5
	3.3.7	Test procedure for cryomodules	5
3.4	Cryon	nodule design including quadrupole and cryogenic systems	5
	3.4.1	Overview	5
	3.4.2	Beamline Components in the Cryomodule and Slot Length $$ .	5
	3.4.3	Technical Description	5
	3.4.4	Cost Estimation	6
3.5	RF po	ower source	6
	3.5.1	Overview	6
	3.5.2	Modulator	6
	3.5.3	Multi-Beam Klystron	6
	3.5.4	Local power distribution system	7
	3.5.5	RF Power Requirements	7
3.6	Low-le	evel RF control concept	7
	3.6.1	Introduction and overview	7
	3.6.2	Vector-sum control of cavity fields	7
	3.6.3	Individual cavity control	7
	3.6.4	Control of cavity gradient flatness	8
	3.6.5	LLRF operation	8
	3.6.6	LLRF system implementation	8

iv

# **TDR: Part 2 (2)**

Ma	in linac	c layout for a flat topography	85
4.1	Introdu	action	85
4.2	Layout		85
4.3	Klystro	on cluster scheme RF power distribution system	86
4.4	LLRF	control for KCS	90
Ma	in linac	c layout for a mountain topography	93
5.1	Introdu	action	93
5.2	Layout		93
5.3	Distrib	outed Klystron Scheme Power Distribution System	94
	5.3.1	DKS	94
	5.3.2	RF Source	94
	5.3.3	Klystron power division	95
	5.3.4	Local power distribution system	95
5.4	LLRF	control for DKS	97
	5.4.1	Introduction	97
	5.4.2	Layout	97
Ele	ctron s	ource	99
6.1	Overvi	ew	99
6.2	Beam	Parameters	99
6.3	System	Description	99
	6.3.1	Photocathodes for Polarized Beams	100
	6.3.2	Polarized Electron Gun	101
	6.3.3	ILC Source Laser System	102
	6.3.4	Bunching and Pre-Acceleration	103
	6.3.5	Chicane, Emittance Measurement and Matching Sections	103
	6.3.6	The 5 GeV Superconducting Pre-Acceleration (Booster) Linac	103
	6.3.7	Linac to Damping Ring Beamline and Main e <sup>-</sup> Source Beam Dump	104
	A1	rator Physics Issues	104
6.4	Accelei		
6.4	6.4.1		104
6.4		DC Gun and Bunchers	104
	6.4.1 6.4.2	DC Gun and Bunchers	105
6.4	6.4.1 6.4.2	DC Gun and Bunchers	
	4.1 4.2 4.3 4.4 Ma 5.1 5.2 5.3	4.1 Introdu 4.2 Layout 4.3 Klystre 4.4 LLRF  5.1 Introdu 5.2 Layout 5.3 Distrib 5.3.2 5.3.3 5.3.4 5.4 LLRF 5.4.1 5.4.2  Electron s 6.3 System 6.3.1 6.3.2 6.3.3 6.3.4 6.3.5 6.3.6	4.2 Layout  4.3 Klystron cluster scheme RF power distribution system  4.4 LLRF control for KCS   Main linac layout for a mountain topography  5.1 Introduction  5.2 Layout  5.3 Distributed Klystron Scheme Power Distribution System  5.3.1 DKS  5.3.2 RF Source  5.3.3 Klystron power division  5.3.4 Local power distribution system  5.4 LLRF control for DKS  5.4.1 Introduction  5.4.2 Layout   Electron source  6.1 Overview  6.2 Beam Parameters  6.3 System Description  6.3.1 Photocathodes for Polarized Beams  6.3.2 Polarized Electron Gun  6.3.3 ILC Source Laser System  6.3.4 Bunching and Pre-Acceleration  6.3.5 Chicane, Emittance Measurement and Matching Sections  6.3.6 The 5 GeV Superconducting Pre-Acceleration (Booster) Linac  6.3.7 Linac to Damping Ring Beamline and Main e Source Beam

			109
7.1	Overv		10
7.2		1	10
7.3			11
	7.3.1	F	11:
	7.3.2	1	113
	7.3.3		11
	7.3.4	5-GeV SC Booster Linac	11
	7.3.5	Linac to Damping Ring Beam Line	11
7.4	Optics	s parameters	11.
7.5	Accele	erator components	11
	7.5.1	Undulator	11
	7.5.2	Target	113
	7.5.3	Optical matching device	113
	7.5.4	Normal conducting RF accelerator system	119
	7.5.5	Magnets	12
	7.5.6	Diagnostics	12
	7.5.7	Electron & photon beam dumps	12
Da	mping	Rings	12
8.1	Top I	aval Danamatana and Lavout	10
0.1	TOP L	evel Parameters and Layout	12.
8.2	-	•	
	Lattic	ee description	12
8.2	Lattic	e description	12
8.2	Lattic Beam	e description  Dynamics  Emittance Tuning	12° 12° 12°
8.2	Lattic Beam 8.3.1	e description  Dynamics  Emittance Tuning  Dynamic aperture	12° 12° 12°
8.2	Beam 8.3.1 8.3.2	e description  Dynamics  Emittance Tuning  Dynamic aperture  Collective Effects	12° 12° 12° 12°
8.2	Lattic Beam 8.3.1 8.3.2 8.3.3	e description  Dynamics  Emittance Tuning  Dynamic aperture  Collective Effects  Electron Cloud	12° 12° 12° 12° 12°
8.2	Beam 8.3.1 8.3.2 8.3.3 8.3.4 8.3.5	e description  Dynamics  Emittance Tuning  Dynamic aperture  Collective Effects  Electron Cloud  Fast Ion Instability	12' 12' 12' 12' 12' 13'
8.2 8.3	Beam 8.3.1 8.3.2 8.3.3 8.3.4 8.3.5	ce description Dynamics Emittance Tuning Dynamic aperture Collective Effects Electron Cloud Fast Ion Instability um System	12' 12' 12' 12' 12' 13' 13'
8.2 8.3	Beam 8.3.1 8.3.2 8.3.3 8.3.4 8.3.5 Vacuu 8.4.1	ce description Dynamics Emittance Tuning Dynamic aperture Collective Effects Electron Cloud Fast Ion Instability um System RF systems	12' 12' 12' 12' 12' 13' 13' 13' 13'
8.2 8.3	Beam 8.3.1 8.3.2 8.3.3 8.3.4 8.3.5 Vacuu 8.4.1	ce description Dynamics Emittance Tuning Dynamic aperture Collective Effects Electron Cloud Fast Ion Instability um System RF systems ets and power supplies	12' 12' 12' 12' 13' 13' 13' 13'
8.2 8.3	Beam 8.3.1 8.3.2 8.3.3 8.3.4 8.3.5 Vacuu 8.4.1 Magne	ce description Dynamics Emittance Tuning Dynamic aperture Collective Effects Electron Cloud Fast Ion Instability um System RF systems ets and power supplies Superconducting Wigglers	12: 12: 12: 12: 12: 13: 13: 13: 14: 14: 14:
8.2 8.3	Beam 8.3.1 8.3.2 8.3.3 8.3.4 8.3.5 Vacuu 8.4.1 Magne 8.5.1	ce description Dynamics Emittance Tuning Dynamic aperture Collective Effects Electron Cloud Fast Ion Instability um System RF systems ets and power supplies Superconducting Wigglers Conventional Magnets	12° 12° 12° 12° 13° 13° 13° 13° 14° 14° 14° 14° 14° 12° 12° 13° 14° 14° 14° 14° 14° 14° 14° 14° 14° 14

Vì

# **TDR: Part 2 (3)**

		8.6.1	Diagnostics and Instrumentation	143
		8.6.2	Fast Feedback systems	143
	8.7	Injection	on and Extraction systems	144
9	Rin	g to M	ain Linac	147
	9.1	Overvi	ew	147
	9.2	Beam	Parameters	147
	9.3	System	Description	147
		9.3.1	Layout	147
		9.3.2	Geometry Match	149
		9.3.3	Sub-systems	150
		9.3.4	Collimation and diagnostics	154
		9.3.5	Tuning, Correction, and Operations	155
	9.4	Accele	rator Physics Issues	158
		9.4.1	Incoherent (ISR) and Coherent (CSR) Synchrotron Radiation	158
		9.4.2	Stray Fields	158
		9.4.3	Beam-Ion Instabilities	158
		9.4.4	Static Misalignments	158
		9.4.5	RF Phase and Amplitude Jitter	159
		9.4.6	Halo Formation from Scattering	160
		9.4.7	Space Charge effects	160
		9.4.8	Wake field in SRF cavities and collimators	160
		9.4.9	Emittance preservation	161
	9.5	Accele	rator Components	161
		9.5.1	Magnets, Pulsed elements	161
		9.5.2	Vacuum Systems	162
		9.5.3	Cryogenics	163
		9.5.4	Service tunnels and Alcoves	163
10	Bea	am Del	ivery System and Machine Detector Interface	165
	10.1	Top-le	vel parameters and layout	165
		10.1.1	Beam Parameters	165
		10.1.2	System Description	165
	10.2	Lattice	description	168
		10.2.1	Diagnostics, Tune-up dump, Machine Protection $\ \ldots \ \ldots \ \ldots$	168

		10.2.2 Collimation System	69
		10.2.3 Final focus	72
		10.2.4 Extraction line	73
		10.2.5 Beam dynamics and emittance growth	75
	10.3	Interaction Region Layout and Machine-Detector Interface $1^{\circ}$	75
		10.3.1 Requirements and boundary conditions $\dots \dots \dots$	75
		10.3.2 The push-pull system $\dots \dots \dots$	75
		10.3.3 Final focus	77
		10.3.4 Experimental area layout and infrastructure	79
		10.3.5 Shielding	81
		10.3.6 Detector services	82
	10.4	Magnets and power supplies $\dots \dots \dots$	83
		10.4.1 Tail Folding Octupoles	84
	10.5	Vacuum system	84
	10.6	Instrumentation and feedback systems	85
		10.6.1 Feedback systems and Stability	85
		$10.6.2\;$ Energy, Luminosity and polarization measurements	87
		10.6.3 Diagnostic and Correction devices	89
	10.7	Beam dumps and Collimators	90
		10.7.1 Main Dumps	90
		10.7.2 Collimators	92
	10.8	Crab cavity system	92
	10.9	$  Accelerator \ Components \ \dots \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	93
11		bal Technical Systems 19	
			95
			95
	11.3		95
			95
			96
			98
			99
			04
			04
			05
		(	06
		11.3.9 Cost Estimation, Bases of Estimates	06

Vii

# **TDR: Part 2 (4)**

12 Availability, Commissioning and Operations	209
12.1 Overview	209
12.2 Availability	209
12.2.1 Importance of Availability	209
12.2.2 Methodology	210
12.2.3 High Availability Design Features	210
12.2.4 Availability Studies of RDR to TDR Design Changes	211
12.3 Commissioning	212
12.3.1 Phased Commissioning	213
12.4 Radiation shielding and PPS zones	214
12.4.1 Summary of Regions' Radiation Requirements	214
12.4.2 Summary of the Radiation Safety Design for the Main Linac	214
12.4.3 PPS Zones	215
12.4.4 Shielding between PPS Zones	216
12.5 Machine Protection System	217
12.5.1 Overview	217
12.5.2 Single Pulse Damage	218
12.5.3 Average Beam Loss Limiting System	219
12.5.4 Abort Kickers and Dumps	219
12.5.5 Restart Ramp Sequence	220
12.5.6 Fault Analysis Recorder System	220
12.5.7 Rapidly Changing Fields	220
12.5.8 Sequencing System Depending on Machine State	221
12.5.9 Protection Collimators	221
12.6 Operability	221
12.6.1 Feedback systems	222
13 Conventional Facilities and Siting	223
13.1 Introduction	223
13.2 Overall Layout	224
13.3 Common design criteria	225
13.4 General site requirements	225
13.5 Asian region (Mountain topography)	226
13.5.1 Siting studies	226
13.5.2 Civil construction	228

13.5.3 Mechanical	234
13.5.4 Electrical	238
13.5.5 Life safety and egress	241
13.6 European region (Flat topography)	242
13.6.1 Siting studies	242
13.6.2 Civil construction	247
13.6.3 Mechanical	251
13.6.4 Electrical	252
13.6.5 Life safety and egress	252
13.7 Americas region (Flat topography)	254
13.7.1 Siting studies	254
13.7.2 Civil construction	256
13.7.3 Mechanical	259
13.7.4 Electrical	264
13.7.5 Life safety and egress	267
13.8 Handling equipment	269
13.8.1 Introduction	269
13.8.2 Items to be transported	269
13.8.3 Transport operations	270
13.8.4 Installed handling equipment	270
13.8.5 Mobile handling equipment	271
13.9 Alignment and survey	274
13.9.1 Introduction	274
13.9.2 Reference and coordinate systems	275
13.9.3 Geodesy and networks	276
13.9.4 Component Metrology	276
13.9.5 Component Alignment	278
13.9.6 As-built measurements and integration	279
13.9.7 Metrology for the detectors and experimental area infrastructures	279
13.9.8 Software, database and informatics	280
13.10Installation	280
13.10.1 Scope	280
13.10.2 Methodology	280
13.10.3 Model of Main Linac installation	282

Х

# **TDR: Part 2 (5)**

14 Possible upgrade and staging options	285
14.1 Introduction	285
14.2 Parameters	286
14.2.1 Luminosity upgrade	286
14.2.2 Energy upgrade	288
14.3 Scope of the luminosity upgrade	288
14.3.1 Main linacs	289
14.3.2 Damping Rings	290
14.3.3 Electron and positron sources	291
14.3.4 RTML (bunch compressors)	292
14.3.5 Beam Delivery System	292
14.4 Scope of energy upgrade to 1 TeV centre-of-mass energy	292
14.4.1 Positron source	296
14.4.2 RTML	296
14.4.3 Beam Delivery System (BDS)	297
14.4.4 AC Power requirements	297
14.5 A possible staged approach to the baseline 500 GeV centre-of- mass-	
energy machine	297
14.6 Summary	299
15 Scope of post-TDR engineering	301
15.1 Maturity of design	301
15.2 Remaining R&D issues	301
15.3 Scope of remaining engineering	301
15.4 Technical risk assessment	302
16 Project Implementation Planning	303
17 Cost and Schedule	309
17.1 Value estimating methodology	309
17.2 Value estimate for the construction of the ILC	309
17.3 Construction schedule	309
17.3.1 Project Implementation Planning	309
17.3.2 Scope and assumptions	310
17.3.3 Accelerator complex	313
17.3.4 Detectors	316

18 Summary 319

#### Chapter 1

#### Introduction

The technical specifications and design presented in this reference report represent a mature and relative low-risk design for a linear collider. At the heart of the accelerator remains the two approximately 11-km long SCRF main linacs, based on the technology developed by the TESLA collaboration and proposed in 2001 for the TESLA linear collider [2]. The updated cost estimate reflects the significant worldwide developments in this technology, with the establishment of R&D infrastructure as well as a significant industrial base in the Americas, Asia and Europe. The GDE driven global high-gradient SCRF R&D has succeeded in routinely establishing the required 35 MV/m average performance, with every indication that this could be exceeded in future years. Integrated systems tests at the TTF2/FLASH accelerator in DESY, Hamburg have demonstrated many of the design and performance parameters for the ILC, and this currently unique facility will soon be joined by similar test accelerators in both KEK, Japan, and Fermilab, USA. Beyond the fundamental R&D, the on-going industrialisation of the technology has enabled the GDE to provide realistic industrial studies for globally mass producing the required approximately 18,000 SCRF nine-cell cavities and assembling them into 1750 cryomodules, resulting in a relatively robust and defendable cost estimate, as well as clear concepts as to how the machine could be constructed as an international project based on in-kind contributions, complete with a realistic construction and installation schedule. The design evolution since the original RDR reflects the results of this R&D, a re-evaluation of cost-performance trade-offs, and a more detailed considerations of site-specific cost-optimum design options. The system designs and associated cost estimates reported here are considered sufficiently complete as to form a sound basis for a "Proposal to Construct" soon after an International ILC Organisation has been formalised and a specific site has been selected.

The ILC design has been developed to achieve the following physics performance goals during the first years of operation:

- $\bullet$  A continuous centre-of-mass energy range between  $200\,\mathrm{GeV}$  and  $500\,\mathrm{GeV}$
- • A peak luminosity of approximately  $2 \times 10^{34} \ \mathrm{cm^{-2} \, s^{-1}}$  at 500 GeV centre-of-
- 80 % electron polarisation at the Interaction Point (IP)

1

# TDR Snapshot Review SCRF in TDR1 and TDR2

K. Yokoya

2012.9.27

### General

- Almost no description about X-ray (only as diagnostics in TDR1 2.2.6) TDR1
   2.3.3 cavity data base does not mention at all.
- HOM coupler
- Alignment within cryomodule
- Cryogenics
  - 2 pages in TDR2 3.4.1 overview
  - half page in TDR2 3.4.3.5
- TDR2 3.5.2 Marx modulator → mostly TDR1. Leave here only the final specs.
  - (3.5.2 cites TDR1 but no such section in TDR1)
- Chap4 & 5 (flat & mountain)
  - should be combined into one chapter,
  - or should be absorbed in Chap3 (3.5 RF Sources)
  - The latter seems to be more reasonable because
    - These 2 chapters concern only HLRF issues
    - The difference in the cryogenic system is described in 3.4
- TDR1 relatively in good shape.

### TDR1

- 2.1 Overview. Subheadings are needed
- 2.2.4 Production and test facilities. Peking university should be mentioned at least a little somewhere if not this section.
- 2.3.1.1 cavity shape. Table 2.3. Q factor. "installed quality factor  $>10^{10}$ " & "quality factor during qualification  $>0.8x10^{10}$ ".  $>10^{10}$  used to be  $>10^{10}$  at 31.5MV/m and  $>0.8x10^{10}$  at 35MV/m. Same meaning?
- 2.3.1.2 very long. Subheadings needed.
- 2.3.2 Results of cavity gradient. The present preamble fits more to the overview section.
- 2.3.3.1 Fig 2.21. Must be magnified. The legends in tiny letters are needed.
- 2.5 S1-Global. 16pages. A bit long.
- 2.6 Cryomodule etc. Deformation of cryomodule.
- 2.7 RF. Marx modulator to be included.
- 2.8.2 Fig 2.82.
  - What is vertical axis? Quantities for entire ILC?
  - Near the end. To give name "Toshiba" not appropriate.

# TDR2 Chap 3 to 5

- 3.1.1 Overview. Orbit control comes as the first sentence of SCRF.
   Bizarre.
- 3.1.3 System description
  - Schematic diagram of 1 RF unit is needed for understanding
  - 10Hz should be mentioned
- 3.1.4 Accelerator physics.
  - 1<sup>st</sup> line. Eliminate the word "weak focusing" (This is the word against alternating grad.)
  - 7<sup>th</sup> line. "Beta about 80m in both planes" True? Phase advance in x and y are different.
  - 2<sup>nd</sup> paragraph . IP vertical emittance 40nm  $\rightarrow$  35nm
- 3.1.5 Operation and Upgrades. Is it necessary to give upgrade scenario here.? Needed only when the upgradablility imposes constraint in the baseline design.
- 3.2.1 Table 3.7 Spec for HOM Qext. This sounds like HOM Qext is measured for every cavity.

# TDR2 Chap 3 to 5 (continued)

- 3.3.1 Table 3.9. Is this the plug-compatibility table mentioned in 3.3.5.1?
- 3.3.2 Frequency tuner. I could not find the reason why blade tuner has been adopted for TDR. (TDR1 2.2.4 describes the conclusion from S1-Global but does not say why blade tuner.) Same for couplers.
- Relation between Fig 3.12 in 3.3.6 and Fig 3.13 in 3.3.7.
   The latter and the right hand side of the former are the same process?
- 3.4.2 Fig 3.17 "longitudinal view" missing? Font pr oblem.
- 3.4.3.8 Quad package. Missing specs for quad, correction dipole, BPM. (TDR1 table 2.18 for quad?)

# TDR2 Chap 3 to 5 (continued)

- 3.5.1 power source overview
  - 1<sup>st</sup> paragraph. 8x10<sup>9</sup> should be 1x10<sup>10</sup>?
  - 3<sup>rd</sup> paragraph from the end. 200~300MW sounds too crude. Should give max value.
- 3.5.5. Power requirements. Hard to understand Fig 3.28 and sentences below. My problem only?
- 3.6.1 Table 3.17 field vector sum tolerance, check with Kubo table (revised)
- 3.6.4 Gradient flatness: give tolerance number and measured values at FLASH
- 4.1 end of first paragraph mentions about optics difference (`somewhat' large). True? This is not mentioned in Kubo chapter.
- Figures in 4.3 contains font problem
- Missing 4.2 & 5.2 (layout)

# TDR-2, ML-SCRF: Top Level Editing and Comments given by N. Walker Section 3.1: renamed "Overview of the ILC Main Linacs"

- This is where I have done by far the most editing. I have re-arranged the text and emphasise the technology upfront (rather than the beam dynamics). I removed section which repeatedly referenced chapter 2, to the extent of possibly repeating material from that chapter. However, once we are happy with this chapter (chapter 3), I would propose to return to chapter 2 and edit down that content. I would also move a couple of the tunnel cross-sections from chapter 2 to hear, but that must now wait.
- Section3.1.3 accelerator physics is still a little weak. In particular we should discuss what to do about the HOM issue here is the ednote in the text:
- Need to discuss what to include in this chapter on the HOM issue. Most of this work
- was done 10 years ago for TESLA. A table of the modes is given in the TESLA TDR, as well as
- results of multi-bunch simulations, but this never been reproduced in any document for the ILC.
- Effectively this field has been considered a ``solved problem'' for many years. What should we do
- for this TDR? Reproduce some of this? At the very least we should reference the work done for
- TESLA.
- I believe this chapter does need something on this.
- Section 3.1.5 Linac Systems has been greatly simplified, and now just briefly introduces the following sections.

# **Section 3.2: Cavity**

- Removed the introductory material and the big table of CM counts (former is integrated into 3.1). Now just starts with 3.2.1 cavity design.
- New graphic 3.4 (this gets referred to quite a lot, and I may consider to repeat sub parts of it in the later text).
- 3.2.2 cavity fabrication process
- Bullet list of the process steps unchanged but I'm still not sure this is sufficient. Need to see what's in P1. Note that alcohol rinse appears to be explicitly missing here.
- Text that follows should be read carefully as I've modified it. In particular I have integrated
  Hitoshi's "Cavity test procedure" figure directly into this text, and attempted to describe it in
  words. We have already discussed the "fractions" stated in this flow chart and the various
  loops. I have attempted to make references to P1 where I feel these points should be justified
  by the R&D and this must be checked.
- This goes to the heart of our discussion of the cost estimate and whether or not the optical inspection and mechanical repair is a justified cost-effective approach for mass production on this scale or just a belief.

# **Section 3.3 Cavity integration**

- Quite some editing work but I think the content remains more or less the same for the various sub-assemblies. (I have a better figure of the coupler coming.)
- I have now included the coupler processing/test text/graphic directly into the coupler section, at least up to the assembly in the module. The figure should be edited to match the text accordingly, since the RHS really refers to the cryomodule testing which comes later.
- I've added many references to various places in this section (thanks to Benno); they need to be ordered a bit better and just checked they are really relevant.
- Better graphic of tuner coming also, without the side cartoon.
- I have left (as Nobu did) an empty Section 3.3.3 HOM couplers. There are plenty of references and history here, so in principle it is straightforward to add some text (much like the HOM in the accelerator physics section). The real problem is identifying somebody to write it. I could do it but I would need a couple of days to research it. What needs to be included here that's critical? This will come up again in the cryomodule section when the absorber is briefly discussed (see later).
- 3.3.5 Plug Compatibility: the first paragraph strikes me as being out of place here, and would be better suited to somewhere in Part I or even in the PIP. Only the interface specifications are really needed here, with a couple of sentences introducing them.

# Section 3.4: Cryomodule

- I found the original approach here rather awkward as it first introduced the big picture (string, unit etc) and ended up with the CM. I understand Paulo's logic here but at the end of the day I don't think it worked, since we are so focused on the CM as being our most visible piece of hi-tech and our cost driver. So now this chapter deals only with the CM.
- Not much different here except English.
- Page 31: I'm still confused by the HPC issue. I have now put 3 bar for the "maximum pressure for the cavities and magnets" (although I just realise that the latter may no longer be relevant given its now conduction cooled?). You should just correct this. (AY. Design Pressure to be 2 bar)
- HOM absorber I added a placeholder for a reference on these calculations (Martin Dohlus presumably) but I need to find one. We could add a picture of the latest XFEL absorber if you like.
- Section 3.4.2.8 on the quad. Just referencing part I is not enough here. I have copied over some of the text and the figure and parameter table. However there also needs to be something here (specs at least) for the corrector dipoles and BPM. Who could add this?
- Also there may be a (beam dynamics) technical issue with not being able to fiducialise the BPM and quadrupole together. Should
  check with Kubo on the tolerances.
- Section 3.4.3 is now for the module testing.
- I did my best here but there is really more work to do, especially considering it's a potential cost driver for the module. Here's the ed note:
- This section is too weak in my opinion and needs much more detailed work. Especially when we consider the
- cost impact on the CM. We can certainly look
- to the XFEL test procedures for more details of exactly what tests are done and in what order. Also there needs
- to be some time-line showing how long it all takes (I think the XFEL currently takes 2 weeks total time).
- Also there needs to be some discussion here concerning the testing rate and the ramifications thereof. I believe our current
- approach is similar to the TESLA TDR, in that testing every module before installation in the tunnel is cost prohibitive,
- and therefore after some initial ramp up we drop to something like 1 in 3. This is more in keeping with the concept of
- `production quality control'. The right thing to do is to keep a buffer of 3 CM's and if one fails, the other two must also be tested
- (before installation in the tunnel). If all three (or even 2/3) fail then there is a problem with the production line which needs to be
- remedied. We have not discussed this enough and need to do so.

# Section 3.5 Cryogenic cooling scheme

 NEW! I thought this was missing in the original draft. I have simple cut and paste the RDR text and edited it to fit (including the new graphic).

 THE TABLES AND NUMBERS MUST BE UPDATED! (I guess a job for Tom P.)

# Section 3.6 RF power source

- Mostly language. Removed intro stuff as repetitive. Removed (most) references to upgrade (covered in upgrade chapter).
- Despite Kaoru's EC comments, I think modulator is OK -- not overly R&D and the info is relevant. Can stay as is.
- Klystron section only English.
- LPDS quite some re-work. Again removed superfluous intro material. Re-wrote description of power division so I could understand it. Cut out some stuff I didn't think was overly relevant.
- Still need reference to S1 global report (see ednotes).
- RF power requirements
- Major re-write. Removed the tortuous explanation of the 'few %' OH for gradient spread.
   Attempted to explain meaning of entires in table better (at least to me). I have an email in to Chris N. and this might get one last iteration before we're done. Need to provide a back-up report on calculation of gradient spread OH could also be the one needed for LLRF section on PkQl

### Section 3.7: LLRF

- Mostly english and style. Removed some detail concerning methods for LFD compensation (too much detail). Same for Klys linearisation.
- Punted on explanation of PkQl can't do this simply so decided not to do it at all. Again, could review once I'm back.
- In general quite a long section for this. Perhaps somebody good at reducing word count could make it a little terser.