

Some Plots from RootFileProcessor (& GeometryChecker)

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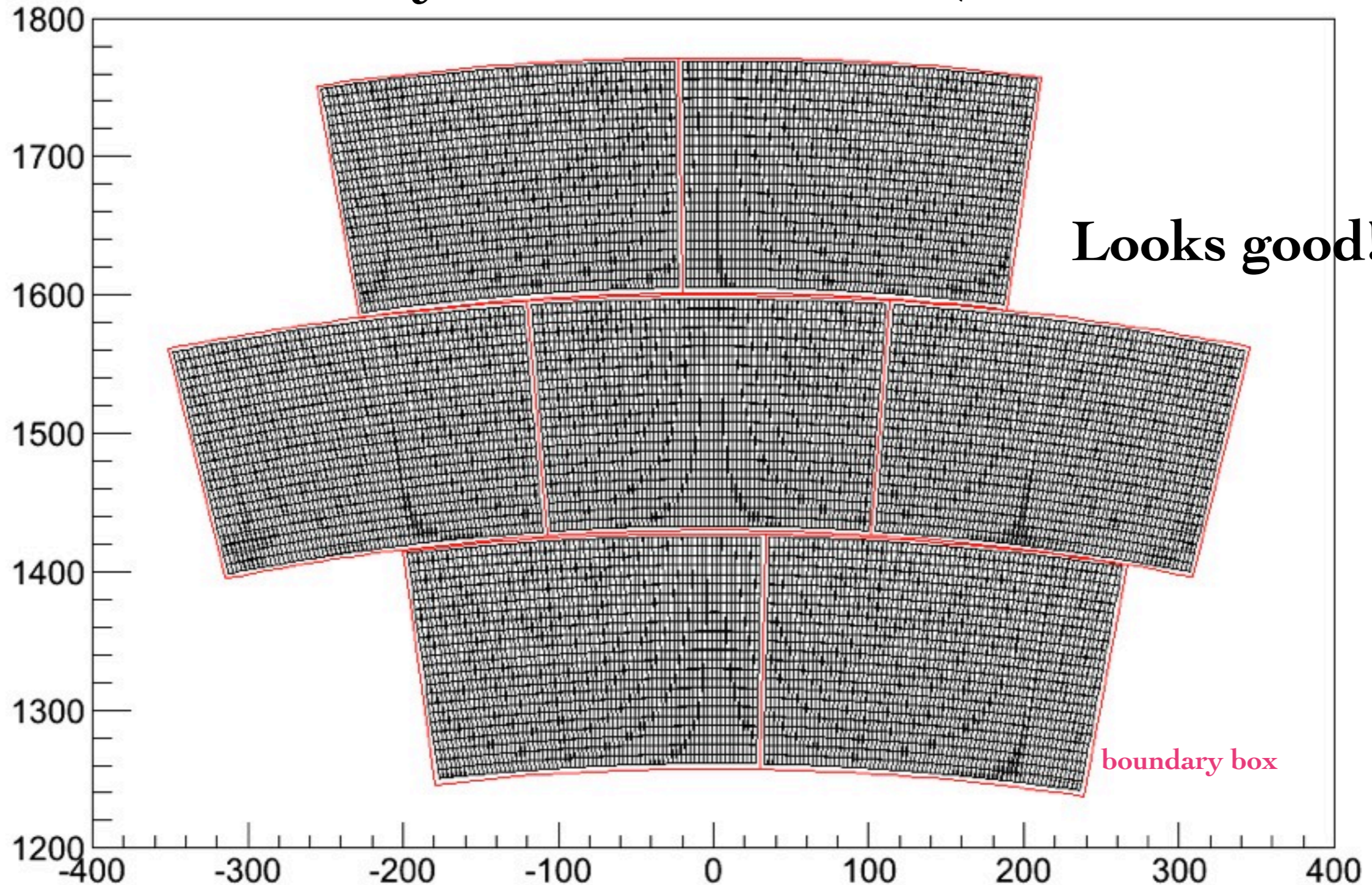
22nd. Jan. 2013

Reconstruction and Making Plots

- ❖ I used MM standard(?) steering file (provided by Wenxin):
 - Peter's PulseFinderProcessor (use only peak adc as a pulse charge)
 - PRFBasedHitFinderProcessor (hit finder for MM)
 - BiasCorrectionProcessor
 - Peter's TrackMakingKalmanFilterProcessor (enable to use BiasCorrectionProcessr)
- ❖ For making plots, I used RootFileProcessor, which is also used in GEM analysis.
- ❖ Run : 2060, 2061, 2062, 2063, 2065, 2067, 2068, 2069, 2070

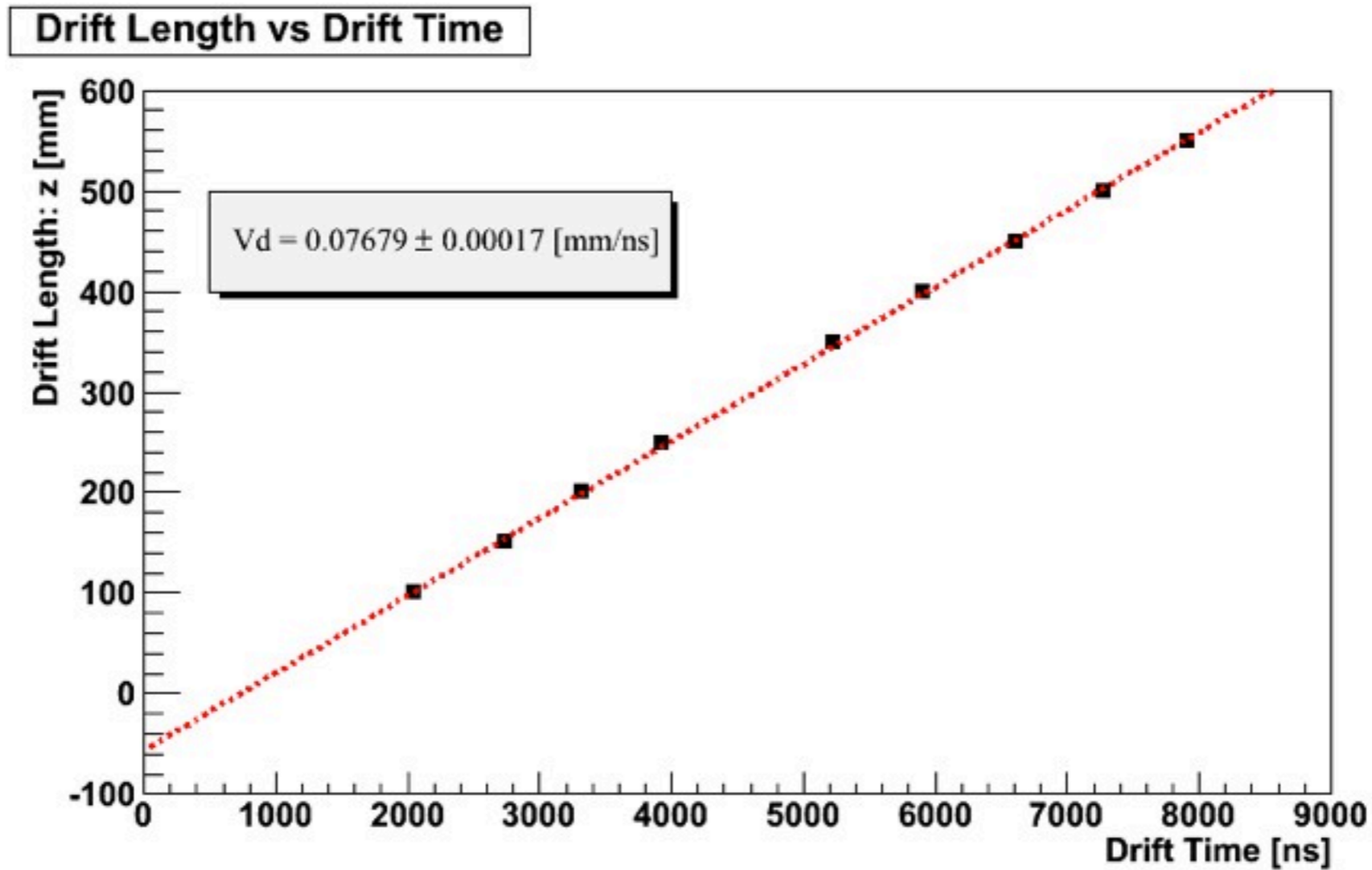
Drawing geometry from Gear File

Used PadGeometryChecker Processor (which is modified)



Drift Velocity

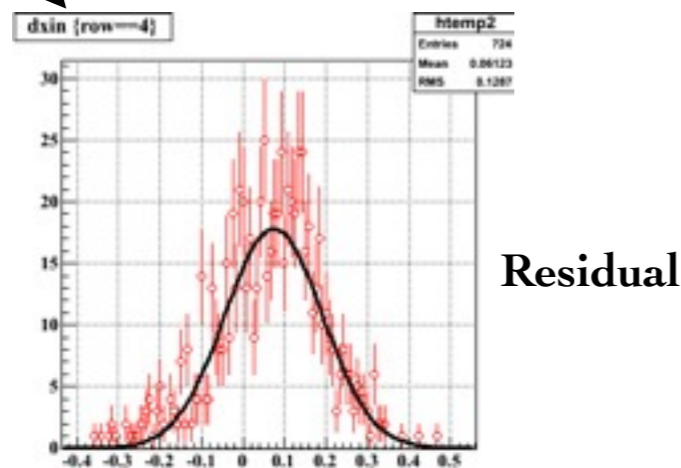
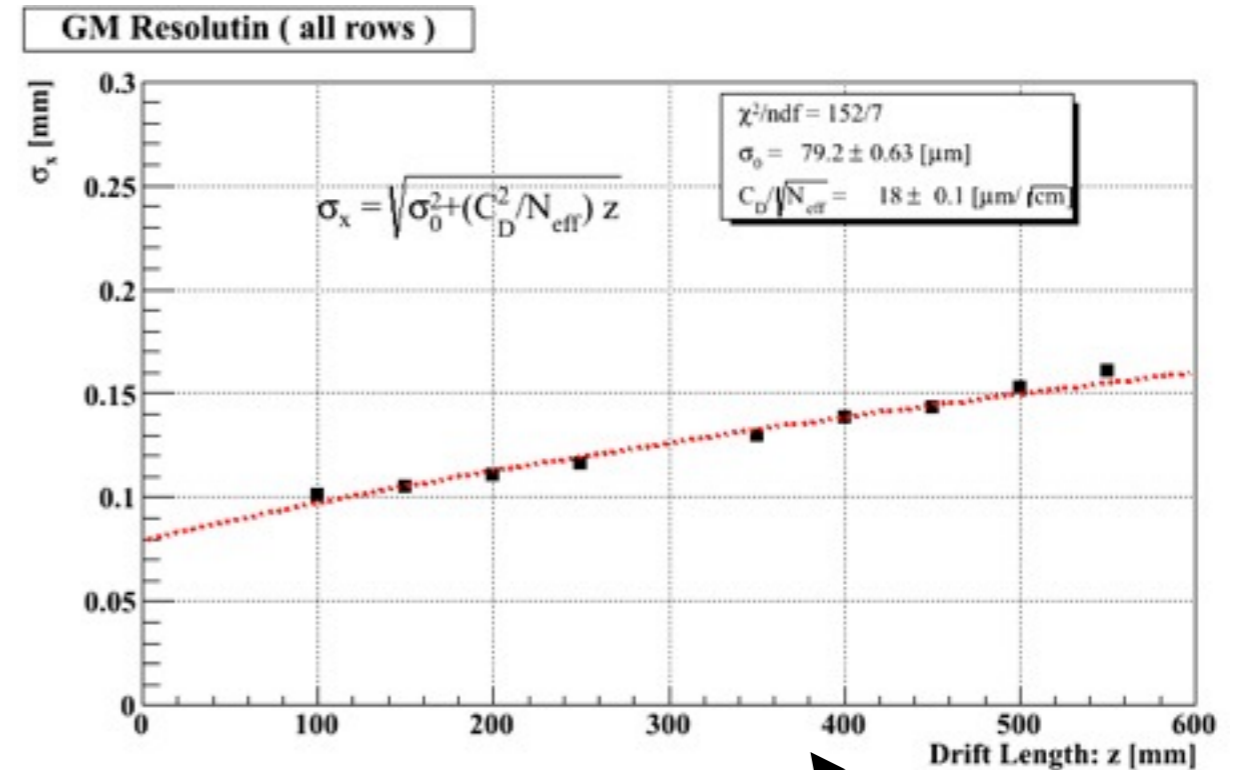
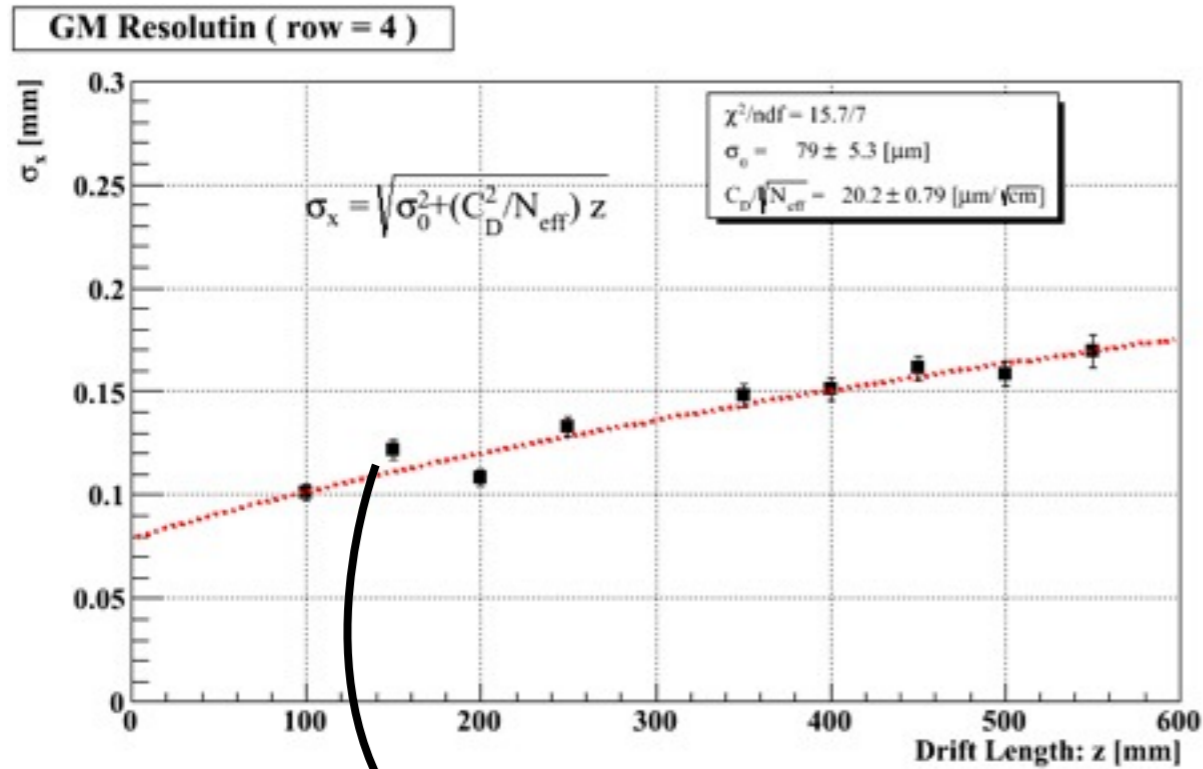
- Used only track associated pulses



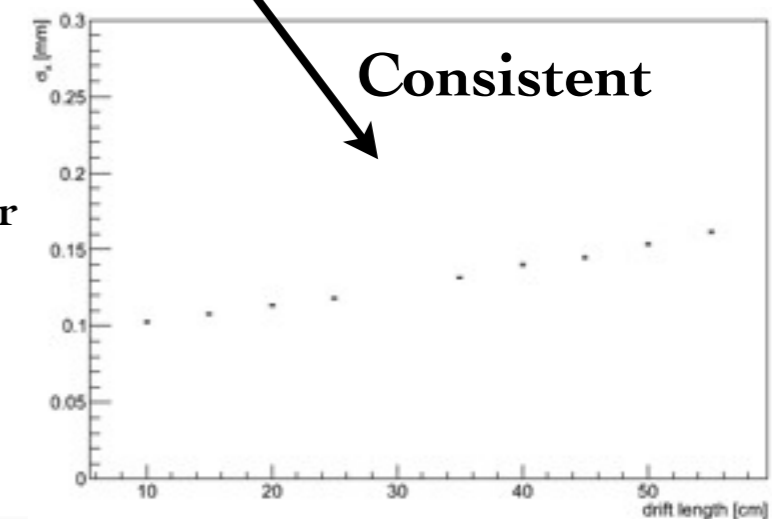
Point Resolution

Used the bias-corrected data
Used only row 4

Combined all rows



Consistent with the results
from
TrackMakingKalmanProcessor
+ Resolution.C provided by
Wenxin.

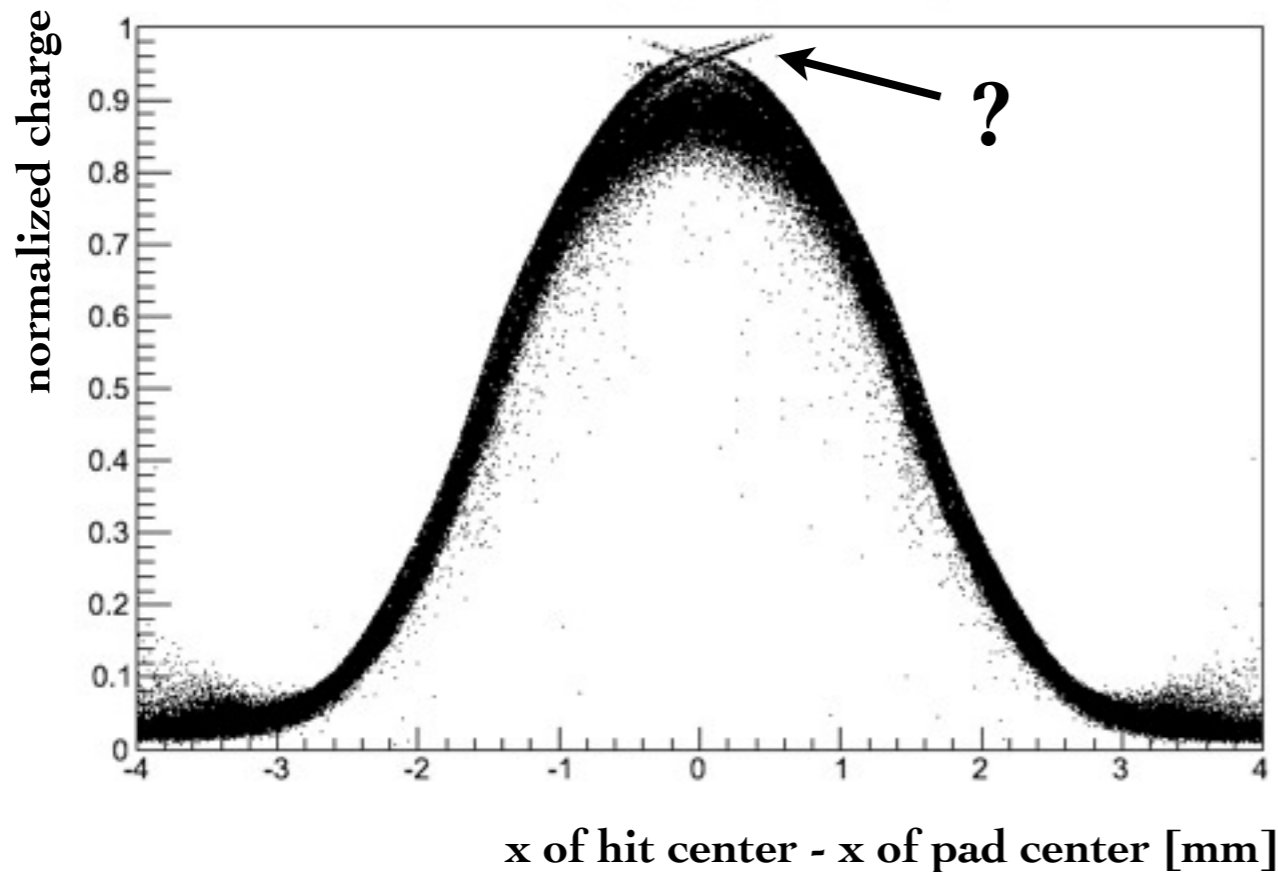


Pad Response

- Used only track associated hits
- All rows are combined

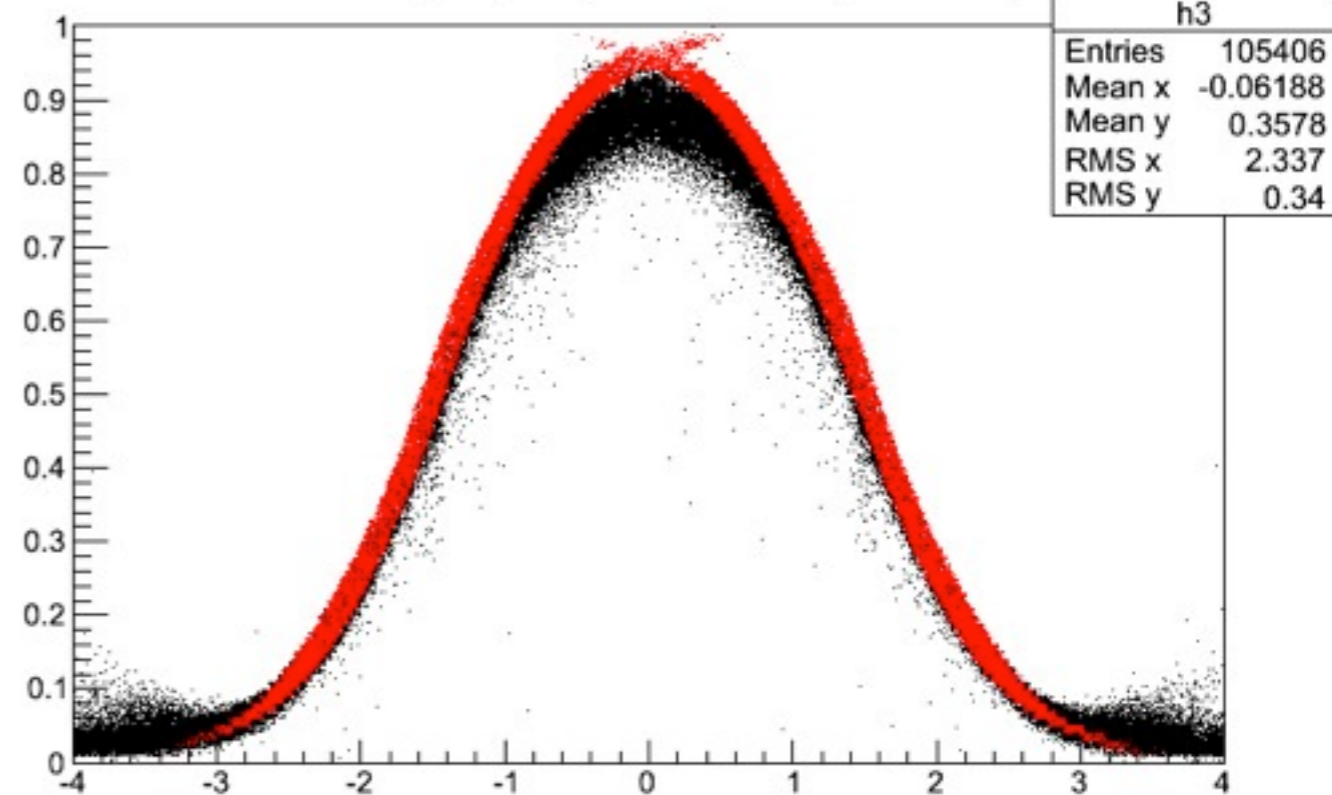
w/o requiring for # of hit pads

normchg:drphi {ndf>100}



Found that red points corresponds to 2-pad hit cases

normchg:drphi {ndf>100&&npadhit>2}



x of hit center - x of pad center [mm]

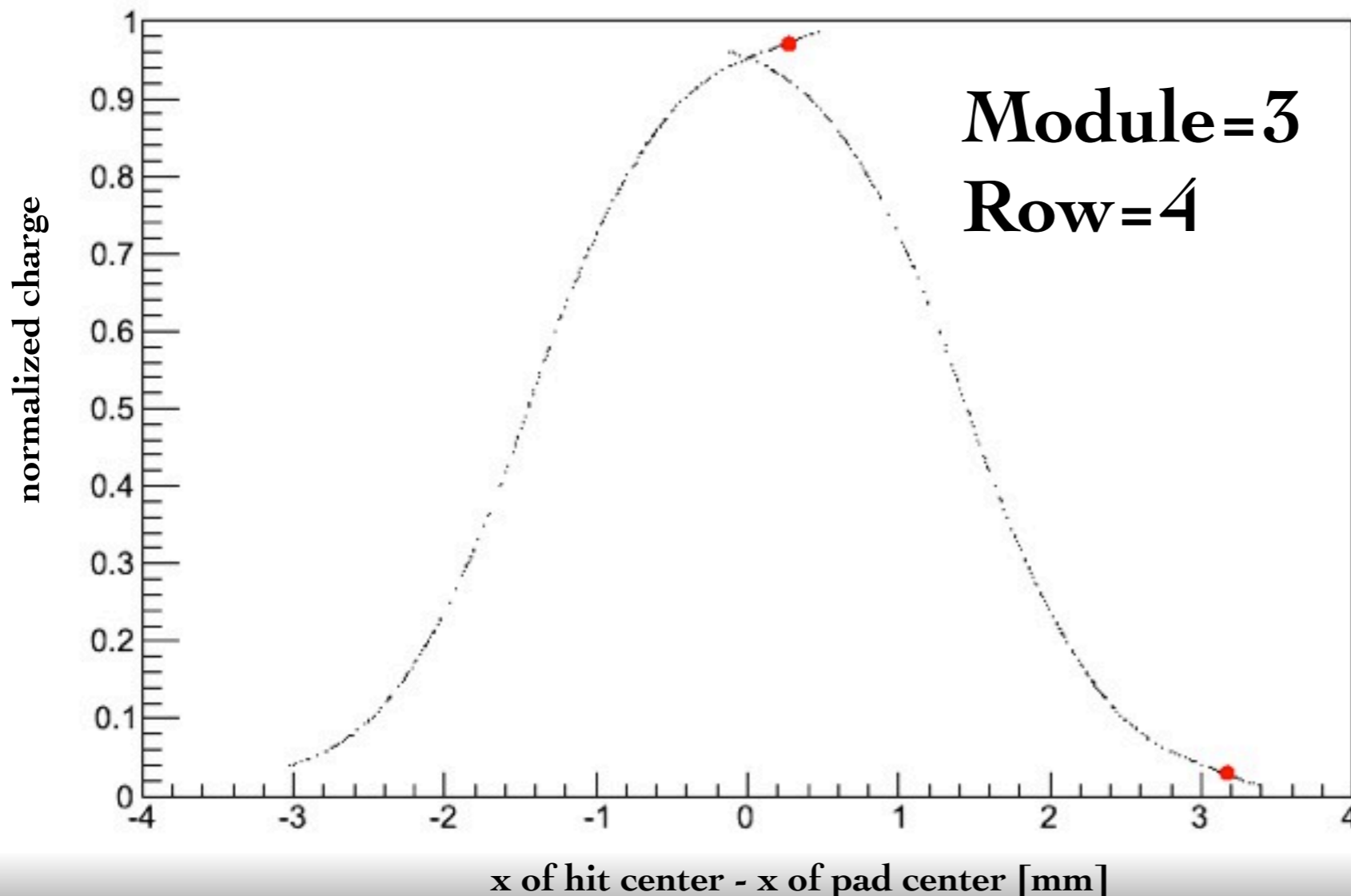
What I try to understand

Strange Behavior

In order to understand the detail, I checked PR at each row one by one.

I found that there are some strange behavior shown as red points in the figure.

`normchg:drphi {module==3&&row==4&&npadhit<3&&ndf>100}`



The red points correspond to a hit in a event. By definition, the weighted mean for these points should be zero, but it's not the case.

Possibilities :

- just bug in my code
- any problem in PRF fitting

(How many parameters do we need to fit for the PRF?
2-or3-pad hit may not provide enough information for the fitting.)

Others

One suggestion

For the convenience and common analysis codes as much as possible :

To create new TrackerHit collection, in which hits are already corrected, in the BiasCorrectionProcessor.

then I think

- we can use default TrackMakingKalmaFilterProcessor (and RootFileProcessor)
- it is easy for other groups to use BiasCorrectionProcessor
- convenient to compare the data before/after correction.

Summary & Plan

- I have learned how to analyze MM data.
(confirmed that the basic analysis had been prepared.)
- Now I am more interested in PRF fitting.
- I will continue MM analysis with Gilles in this week.