# **Point 5:**  $\tilde{\chi}_1^{\pm}$  and  $\tilde{\chi}_2^{\ 0}$  Pair Production at the ILC

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**Point 5**

#### **"Point 5" benchmark : gaugino pair production at ILC**

 <http://arxiv.org/pdf/1006.3396.pdf> (ILD LoI) <http://arxiv.org/pdf/0911.0006v1.pdf> (SiD LoI)



## **Point 5 - motivation**

- > The "point 5" scenario is a good case for:
- > studying the detector and particle flow performance
	- 2 escaping LSP's  $\rightarrow$  missing energy
	- hadronic decay of gauge bosons
	- goal: clearly distinguish between W and Z pair events
- > **comparing and studying the performance of two versions of detector simulation (e.g. LOI and DBD)**





## **Data Samples:**

Signal: 40000  $\tilde{\chi}_1^{\pm}$  events and 9000  $\tilde{\chi}_2^{\,0}$  events



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#### > **LOI sample:**



> **DBD sample**:

## **Study case – Analysis Flow**

- > The **fully hadronic** decay modes of the on shell gauge bosons were chosen as **signal**
- **Signal topology:** 4 jets and missing energy
- > **Background**:
	- SM 4f background is dominant
	- Each signal channel acts as background to the other!
- Event **preselection** apply cuts on:
	- Number of tracks in event and per jet
	- $\blacksquare$  Minimum number of PFOs per jet = 3
	- Minimum jet energy and  $|cos(\theta)|_{\text{et}}$
	- $\blacksquare$   $|cos(\theta)_{\text{pmiss}}|$  < 0.99
	- $\blacksquare$  100 GeV <  $E_{visible}$  < 300 GeV
	- $M_{\text{missing}}$  > 220 GeV
- **Perform kinematic fit** using MarlinKinFit: equal mass constraint (determine best jet pairing and improve resolution)
	- Apply cut on converged kinematic fit





### **Dijet [Boson] Mass Comparison – LOI to DBD**



- The DBD and LOI distributions are similar.
- > Compatible σ, DBD distribution slightly narrower.
- The LOI sample has a jet energy increase of 1% while the DBD sample does not.
- The DBD  $\mu$  is shifted significantly to lower energies.



# ${\tilde{\chi}}_1^{\;\pm}$  and  ${\tilde{\chi}}_2^{\;0}$  Cross Section Measurement

#### > **Use dijet mass to separate χ <sup>1</sup> <sup>±</sup> and χ <sup>2</sup> <sup>0</sup> events** → **measure cross section**



> After selection cuts + kinematic fit:

> Perform fit to disentangle chargino and neutralino candidates





# ${\tilde{\chi}}_1^{\;\pm}$  and  ${\tilde{\chi}}_2^{\;0}$  Cross Section Measurement

After KinFit  $\rightarrow$  fit distribution with Voigt profile where  $\Gamma$  = boson natural width,  $\sigma$  = detector resolution:



- $\sigma$   $\sim$  norm W / Z  $\rightarrow$  check the statistical error on norm W/Z
- **For both LOI and DBD samples, the statistical errors are almost identical**:
	- In the case of  $\tilde{\chi}_1^{\pm}$ :  $\simeq 1\%$
	- In the case of  $\tilde{\chi}_2^0$ :  $\simeq 2.8\%$
- The same precision is obtained for the LOI sample as in the LOI analysis.

# ${\widetilde \chi_1}^\pm$  and  ${\widetilde \chi_2}^0$  Mass Measurement

- $\blacktriangleright$  Mass difference to LSP  $(\tilde{x}_+^{\delta})$  is **larger** than  $M_{\rm \scriptscriptstyle Z}$ 1  $\sim$ χ
- > Observe the decays of real gauge bosons
- $\geq 2$  body decay  $\rightarrow$  the edges of the energy spectrum are kinematically determined
- **> Use dijet energy spectrum ..end points" in order to calculate masses**

$$
\gamma = \frac{E_{beam}}{M_{\chi}}
$$
  

$$
E_{\pm} = \gamma \cdot EV^* \pm \gamma \cdot \beta \cdot \sqrt{E_V^*^2 - M_V^2}
$$

#### **Real [model] edge values [GeV]:**







# **Dijet [Boson] Energy Comparison LOI - DBD**

#### **>** Use dijet energy to measure  $\tilde{\chi}_{1}^{\pm}$  and  $\tilde{\chi}_{2}^{\phantom{\pm}0}$  mass



The DBD distribution appears slightly shifted towards lower energies. Nevertheless, the two distributions agree very well.



# **χ 1 <sup>±</sup> and χ <sup>2</sup> <sup>0</sup> Signal Sample Further Separation**

S Calculate  $\chi^2$  with respect to nominal W / Z mass

$$
\chi^{2}(m_{j1}, m_{j2}) = \frac{(m_{j1} - m_V)^2 + (m_{j2} - m_V)^2}{\sqrt{2}}
$$

min  $\chi^2$   $\!\to$   $\!\tilde{\chi}_1^{\texttt{\texttt{+}}}$  and  $\tilde{\chi}_2^{\texttt{\texttt{0}}}$  separation

- Downside: lose statistics
	- Cut away 43% of  $\tilde{\chi}_1$ <sup>±</sup> surviving events
	- **Cut away 68% of**  $\tilde{\chi}_2^0$  **surviving events**
- $\blacktriangleright$  However, after the  $\chi^2$  cut, the separation is quite clear:







# **χ 1 <sup>±</sup> and χ <sup>2</sup> <sup>0</sup> Mass Measurement – "Endpoint" Method**

> Fit dijet energy spectrum and obtain edge positions:

$$
f(x; t_{0-1}, b_{0-2}, \sigma_{1-2}, \gamma) = fS_M + \int_{t_0}^{t_1} (b_2 t^2 + b_1 t + b_0) V(x - t, \sigma(t), \gamma) dt
$$



Where:

- The polynomial accounts for the slope of the initial spectrum
- The Voigt function accounts for the detector resolution and gauge boson width



#### **Issues of the "Endpoint Method"**





 **The fitting method appears to be highly dependent on small changes in the fitted distribution** → **it is clearly NOT appropriate for a comparing the simulation and reconstruction performance.**

**We need to apply a different edge extraction method!**



#### **Endpoint Extraction using an FIR Filter**

- > Finite Impulse Response (FIR) filters are digital filters used in signal processing.
- > FIR filters can operate both on discrete as well as continuous values.
- The concept of "finite impulse response"  $\leftrightarrow$  the filter output is computed as a finite, weighted sum of a finite number of values from the filter input.

$$
y[n] = \sum_{k=-M_1}^{M_2} \underbrace{b_k x[n-k]}_{\text{the filter coefficients (weights)}}
$$

- y is obtained by convolving the input signal with the (finite) weights
- FIR filters are used to detect edges in image processing techniques:



# **Testing the FDOG Filter**

- > J.F.Canny<sup>\*</sup> has suggested that an optimal filter is very similar to the first derivative of a Gaussian
- > There are two important filter characteristics that must be optimised: the bin size **Entries**

It is crucial to strike the right balance between the two:

the filter size

- If the bin size is too small  $\rightarrow$  the filter picks up a lot of statistical fluctuations
- If the filter size is too large  $\rightarrow$  the edge position cannot be localised anymore

#### **FDOGFilter**  $31$ Mean  $-9.456e + 16$  $0.02$ **RMS**  $9.456e + 16$ ا ۱۵۰۹  $-0.01$  $-0.02$  $-15$  $-10$ -5 0 5 10 15

#### A toy MC study is needed to optimise the filter and bin size!

\*) Canny's criteria: [J. F. Canny. **A computational approach to edge detection.** *IEEE Trans. Pattern Analysis and Machine Intelligence*, pages 679-698, 1986]



# **Testing the FDOG Filter**

> There are two important filter characteristics that must be optimised: the bin size and the filter size.



Filter response after applying the FDOG Filter to the  $\tilde{\chi}_1{}^\pm$  energy distribution:



#### **FIR Edge Extraction Comparison – LOI to DBD**



In the **LOI** case: the fitted and filter values are extremely close to the real model value. In the **DBD** case: the filter value is much closer to the model one than the fitted edge.



## **Toy MC for the Filter Edge Extraction**

- To estimate the statistical precision of the edge extraction  $\rightarrow$  toy MC
- > 10000  $\tilde{\chi}_1^{\pm}$  and  $\tilde{\chi}_2^0$  energy spectra have been produced
- The FDOG filter was then applied 10000 times
- S Example: for the  $\tilde{\chi}_1^{\pm}$  case:





# **Edge Extraction Comparison**



- The LOI uncertainties do not change much.
- The filter results are comparable between LOI and DBD in central value.
- The lower edges are much more precise with the filter method.

The filter extraction method is preferable:

- it is more stable
- provides smaller uncertainties in determining the edge position.



#### **Conclusions**

- A preliminary comparison between the LOI and DBD simulation and reconstruction has been made;
	- The DBD reconstructed dijet masses and boson energies are compatible to the LOI analysis.
	- The fitting method for the mass determination appears very sensitive to small changes. A more robust method is needed.
	- Applying a finite impulse response (FIR) filter in order to extract the edge information instead of the fitting method is:
		- $\triangleright$  More robust (i.e. independent on distribution shape)
		- $\triangleright$  Provides just as good if not better statistical precision
- Outlook:
	- Perform comparison on Full LOI and Full DBD data (update soon)
	- Perform mass calibration (to determine systematics).
	- Perform 2D fit on dijet masses to improve the x-section measurement







# Back up slides

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# ${\tilde{\chi}}_1^{\;\pm}$  and  ${\tilde{\chi}}_2^{\;0}$  Cross Section Measurement

- > Separating W and Z pairs candidates:
- SM background fitted with polynomial
- Signal distributions fitted with Voigt profile
	- Width (Γ) set to boson's natural width (2.11 GeV for W and 2.5 GeV for Z
	- Voigt  $\sigma \approx 3.5$  GeV detector resolution, deduced from a SM sample. The  $\sigma$  from the signal only sample is in the same ballpark!
- Determine relative W/Z fractions from fit





#### **Endpoint Extraction Comparison – LOI to DBD**



The DBD distribution appears slightly shifted towards lower energies. Nevertheless, the two distributions agree very well.



- > The changes of a function can be described by the derivative  $\rightarrow$  interpret the histogram as a 1D function
- > The points that lie on the edge of the distribution  $\rightarrow$  detected by local maxima and minima of the first derivative

$$
f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h} \approx f(x+1) - f(x) \quad (h = 1)
$$

> The first derivative is approximated by using the **kernel [-1, 0, 1]**





- entries The changes of a function can be described by the derivative  $\rightarrow$  interpret the histogram as  $\sum_{\frac{1}{2} \atop \frac{1}{2}}^{\infty}$ a 1D function
- > The points that lie on the edge of the distribution  $\rightarrow$  detected by local maxima and minima of the first derivative

$$
f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h} \approx f(x+1) - f(x) \quad (h = 1)
$$

- The first derivative is approximated by using the **kernel [-1, 0, 1]**
- The kernel is convoluted with the histogram:

 $response_i = -1 \times bin_{i-1} + 0 \times bin_i + 1 \times bin_{i+1}$ 





# **Applying an FIR Filter**

- > Goal: find edge positions in spectrum
- > Strategy: use weighted sums of bin content values to find patterns in distribution





# **Applying an FIR Filter**

- > Goal: find edge positions in spectrum
- > Strategy: use weighted sums of bin content values to find patterns in distribution
- > Consider the histogram as an array of bin content values





# **Applying an FIR Filter**

- Goal: find edge positions in spectrum
- Strategy: use weighted sums of bin content values to find patterns in distribution
- Consider the histogram as an array of bin content values
- Consider an array of chosen weights (smaller than the histogram!)
- Create new array of the same size:
	- $\blacksquare$  Each entry in the new array is the weighted sum of the bin content values from the bins surrounding the corresponding bin in the original array.
	- The array is filled using the **same** (finite) weights each time.
- The value of the output depends on the pattern in the neighbourhood of the considered bin and NOT on the position of the bin
- The pattern of weights = kernel
- The filter application = convolution





# **Testing the FDOG Filter**

Studied the effect of the filter size on a smeared step edge monte carlo data.



 $35\frac{1}{2}$ 

The FDOG filter does indeed perform best.

The filter size should be comparable to the size of the edge feature. We chose  $\sigma = 5$  bins.



## **Choosing the Appropriate Filter**

- The first derivative as kernel works
- It is however a high pass filter  $\rightarrow$  may be rather noisy
- In order to choose an apropriate filter one can apply the following criteria:

- Good detection: probability of obtaining a peak in the response must be high
- Localisation: standard deviation of the peak position must be small
- Multiple response minimisation: probability of false postive detection must be small
- Canny has suggested that an optimal filter is very similar to the first derivative<br>FROGETITER of a Gaussian





Canny's criteria: [J. F. Canny. **A computational approach to edge detection.** *IEEE Trans. Pattern Analysis and Machine Intelligence*, pages 679-698, 1986]

# **χ 1 <sup>±</sup> and χ <sup>2</sup> <sup>0</sup> Separation as Study case for Particle Flow**

- Signal topolgy: 4 jets and missing energy
- Event preselection (kinematics, etc.)
- Perform kinematic fit: equal mass constraint (determine best jet pairing)

Kinematic fit  $\chi^2$ 





#### **3.2. χ <sup>1</sup> <sup>±</sup> and χ <sup>2</sup> <sup>0</sup> Cross Section Measurement 3.2.2. 2D dijet mass fit**

