ILC Coordinate Reference System

Or: how to do Design Integration for a 30km long building

Benno List DESY



LINEAR COLLIDER COLLABORATION

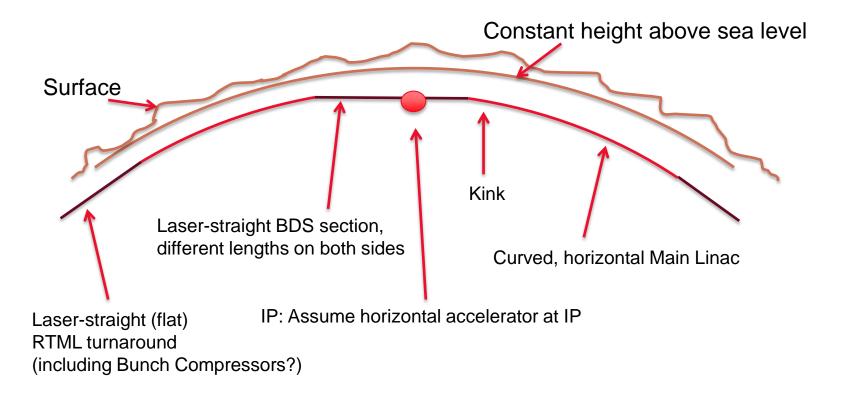
Designing the world's next great particle accelerator



LINEAR COLLIDER COLLABORATION



Schematic ILC Side View

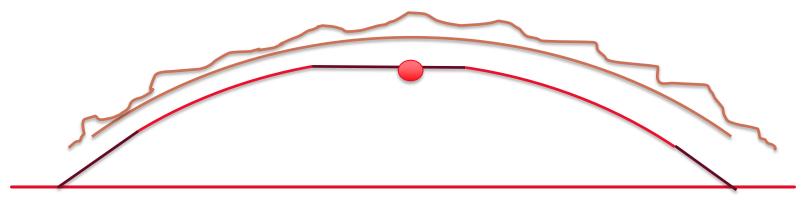






The Problem: How to model a 30km long building

- The earth's surface is curved
- "Up" is a different direction everywhere on earth
- A horizontal "straight" tunnel is curved in reality
- GIS systems understand this
- CAD systems do not understand this!

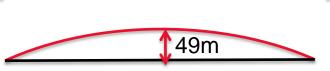


LINEAR COLLIDER COLLABORATION Size of curvature for ILC



Over a length of L= 50km, earth curvature corresponds to a sagitta

of $L^2/(8R_F) = 49m$ 30km->18m; 10km->2m; 5km->0.5m



L=50km

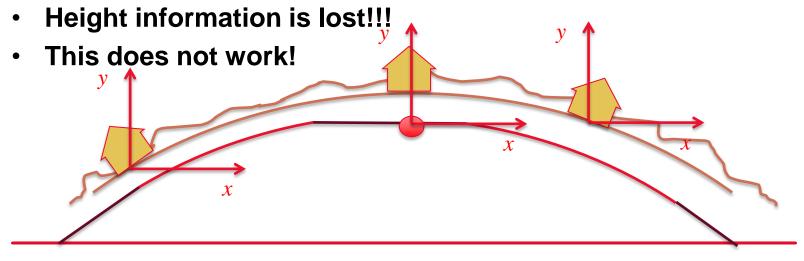
- For accurate planning of shaft geometry (depth, length, slope) a definition is needed which parts of the machine (if any!) follow the earth's curvature and which ones are laser-straight
- My understanding:
 - Main Linac sections follow earth's curvature
 - Central region (undulator section and BDS) are laser-straight (means that tunnel floor is slightly sloped in central region, and kink between ML and central region); main reason: helium lines should not be sloped
 - Damping rungs are flat (do not follow earth curvature) -> negligible effect
 - RTML turnaround sections (the "ears") are laser straight (small effect).
- At some point, we need to write a formal document that specifies this





The naïve approach: not a solution!

- Use a orthogonal coordinate system pinned to one point of the earth
- Upright buildings will be inclined
- Horizontal tunnels will be curved

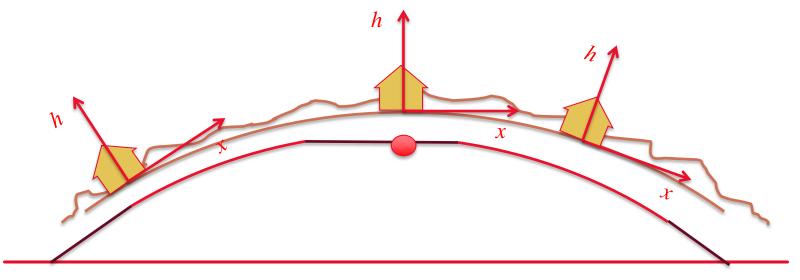






The real solution

- Use coordinates that are locally orthogonal
- One axis is height: always points "up" everywhere
- The other axes are orthogonal

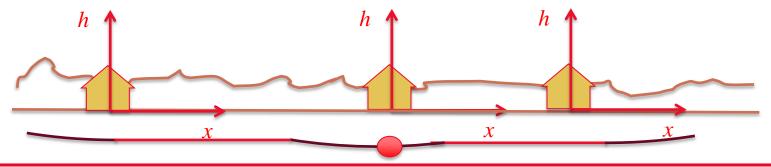






The real solution: A projection

- Use coordinates that are locally orthogonal
- One axis is height: always points "up" everywhere
- The other axes are orthogonal
- All buildings are "upright"
- Horizontal tunnels are straight
- But: laser-straight tunnels are curved!

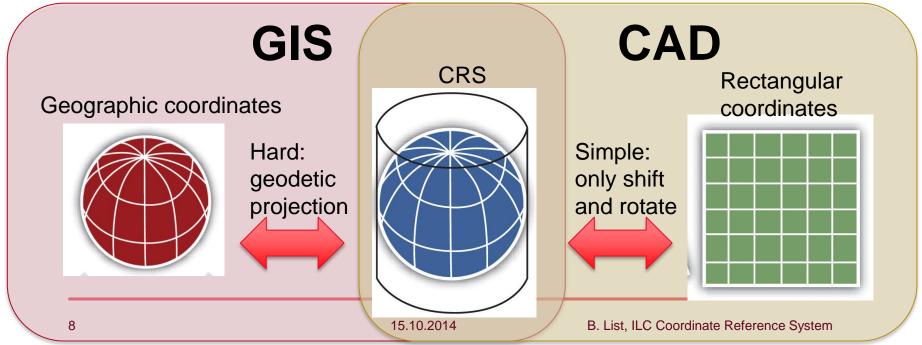






The role of the Coordinate Reference System

 CRS is a locally orthogonal system, into/from which coordinates from GIS and CAD systems can be transformed

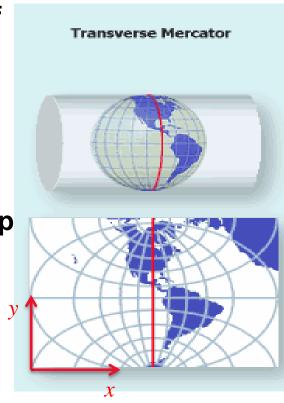


LINEAR COLLIDER COLLABORATION Coordinate Reference Systems



A Coordinate Reference System consists of

- A geodetic datum: Parameter set of the earth's shape, plus definition of a reference meridian
- A projection: Relates longitude/latitude(+height) to x/y (+z) coordinates suitable for plotting on a map
- A CRS defines a coordinate grid on the earth's surface

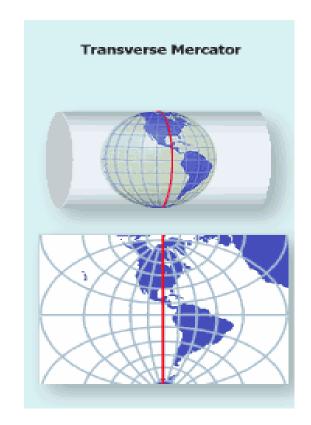


LINEAR COLLIDER COLLABORATION Requirements for ILC CRS



- Minimal scale distortions in the interesting region: Main Linac tunnels and a few km to the side
- Projection should conserve angles (circles) on surface are circles on the map, small rectangles stay rectangles)
 - -> "conformal" projection
- Solution: Use a Mercator projection (conformal), with a center line following roughly the Kitakami site strip
- -> This is a "oblique" Mercator projection

15.10.2014



Formal Definition





- Datum:

 Japanese geodetic Datum 2000 (JGD2000)
 as used for Japanese topographic maps
- Vertical Datum: GSIGEO2011
- Center point and middle line:
 λ_C=141.39°, φ_C=39.03°, α₀=-20.2°
 -> close to planned IP, but not exactly
 -> does not divulge IP location
- Center Point gets offset values
 x₀=5000m, y₀=50000m
 so all coordinate values are positive

The Geographic Coordinate Reference System ILC CRS 2014

Be nno List, DESY, and Tomovuki Sanuki, Tohoku University and KEK

Introduction

The overall length of the ILC is so big that the earth curvature needs to be taken into account in the design of the accelerator. The longest sections of the ILC, the two arms of the Main Lines, with a length of about 20 Skm each in the baseline configuration, will follow the curvature of the earth so that the cryomodules can be mounted horizontally and the liquid he lum inside them does not follow to no exist.

The sagitta for a 30km long tunnel that follows the earth curvature is 18 m, for a 50km long tunnel it amounts to 49 m. Thus, in a global 30 CAD model or lattice this effect is non-negigible.

A ratural but some what naïve, approach to the handling the earth cuvature would be to work in an orthonormal coordinate system, with origin at the line raction Point, y pointing upwards at the lip; pointing along the "me an" axis of the Main Linux in the electron flight direction, and x being perpendicular to x and z to form a right-handed orthonormal coordinate system.

Insuch a system, the Main Linac tunnels, and the Main Linac lattice, would be sloped considerably, and the γ coordinate of the beams in the Main Linac would deviate onsiderably fly up to 34 m from 0 for an earth-curvature following linac.

The IIC lattice approaches this problem in a different way: Implicitly, it treats the y coordinate (in the Main hare region) as corresponding to the boat vertical direction, so that the earth curan ture following beam has a corretant yvalue of 0. The necessary bending, and the dispersion introduced by that bending, it accounted for by applying "vertical kit is" to the beam at the locations of the corrector magnets, and using the correctors to "size or out" these kits, so that the beam stays at y=0.

If such a lattice is to be overhaid with a 3D tunnel model this means that the tunnel has to be constructed with the same convention, i.e., a "straight" tunnel following the earth's curvature has to follow a straight line in the CAD system, while in truth it follows a great circle (or the equivalent on the oblate ellipsoid of the earth).

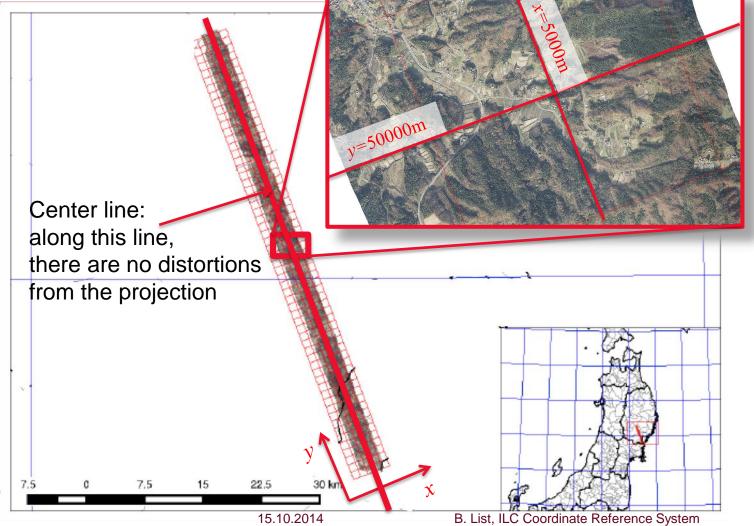
No w_i the transformation from the curved surface of the earth, which is described by latitude q_i longitude λ_i and heighth is above sea level), to a "flat" surface with coordinates x and z in the plane and y for the height is exactly what a map projection does. Or, turning the point of view around: A map projection defines a mapping between coordinates $\{y_i, k_i, k_i\}$ and $\{x_i, y_i, z_i\}$, where typically hey. Thus, $\{x_i, y_i, z_i\}$ form a curvilinear coordinate system, in which a [baser is traight line is not straight anymore. In the nor calculus, such a coordinate system would come with a metrix tensor that is not the identity anymore.

EDMS: D*1084525







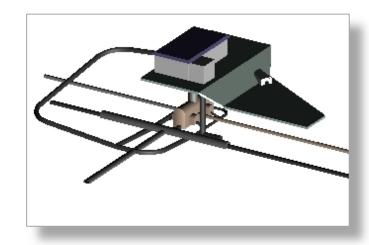




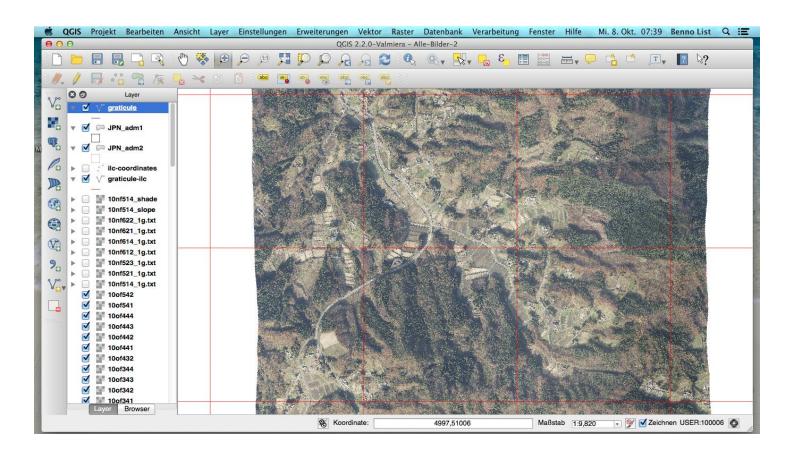


- ILC CRS allows to bring together
 - Geographic data: Elevation models, Aerial images, Map data
 - CAD data: Buildings, tunnels, shafts
- Combination of data can be done
 - In Geographic Information System: GIS
 - In CAD system



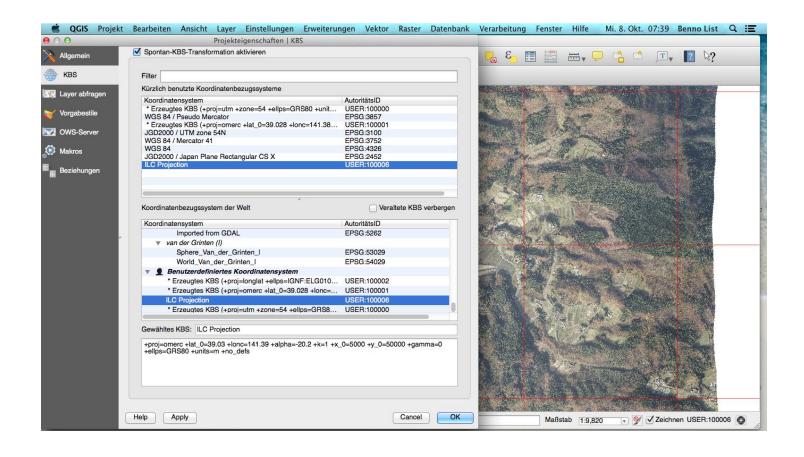






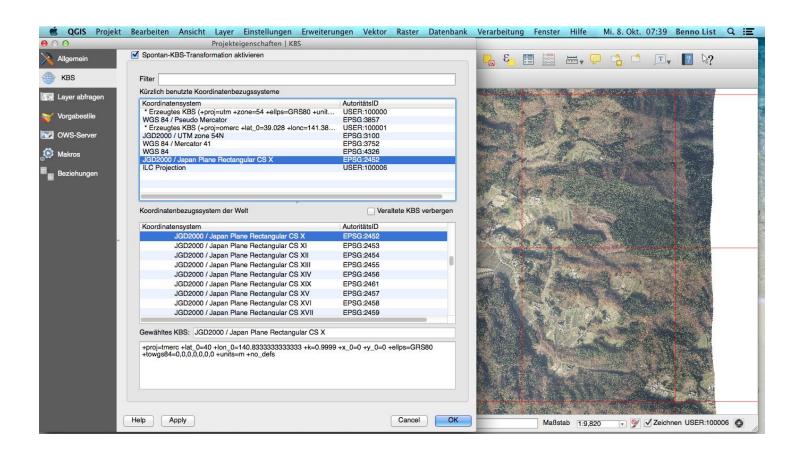




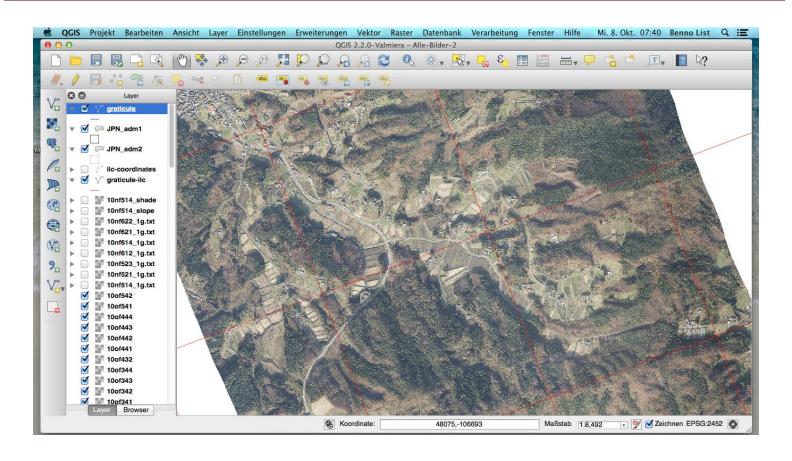






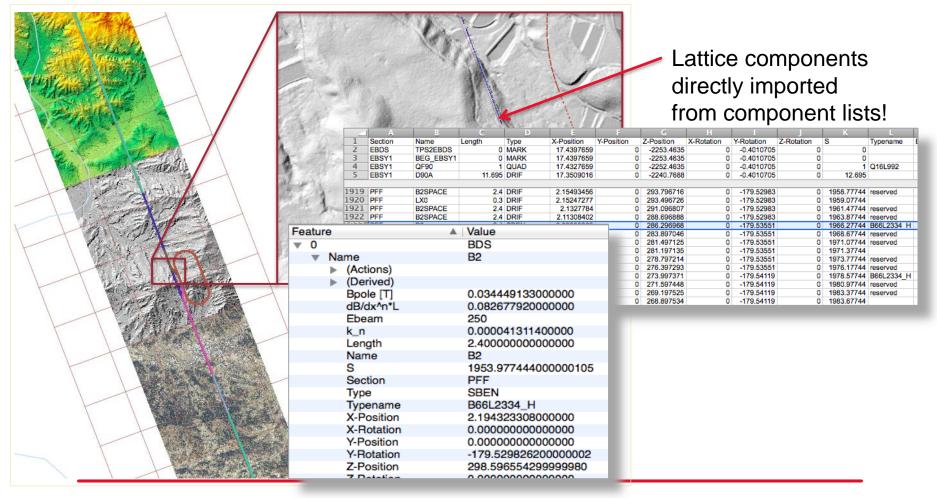






Showing the Accelerator in a GIS System

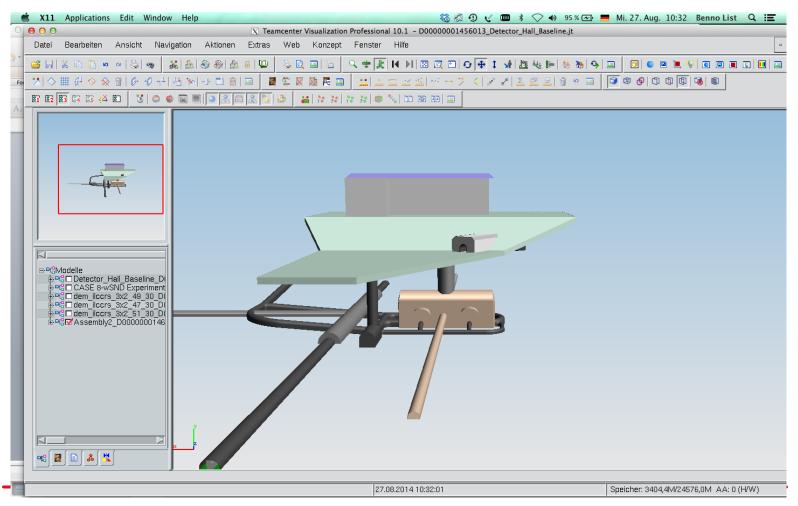






LINEAR COLLIDER COLLABORATION Example for CAD



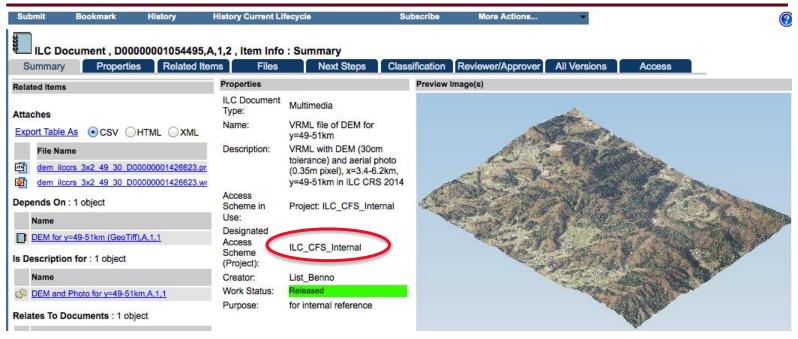




LINEAR COLLIDER COLLABORATION

Data based on ILC CRS in EDMS





Available: Elevation model (1m spacial resolution, 35cm height accuracy)

+ aerial view (35cm pixels)

Formats: 3D model as JT and VRML, aerial view as JPG

29 Tiles of size 2 x 2.8km, mapped to ILC CRS

Confidentiality: in ILC_CFS_Internal project







LINEAR COLLIDER COLLABORATION Combining CAD Data: Reference Points



intorn	ational linear d	hillo	o r				
_11111 & 1 1110	IIIVIIAI IIIICAI L	,UIIIU	;; —				
	ILC Reference Point	s for Civ	il Engin	eering			
	Version		2.95 06.05.1				
		KCS (America, Euro		rope)	DKS (Asia)		
Reference Point	Description	x [m]	y [m]	z [m]	x [m]	y [m]	z [m]
BEGEBC1	Begin Electron Bunch Compressor 1	112.896	0.000	-15667.757	113.228	0.000	-15715.104
TERTML2ML	Electron RTML to Main Linac	104.525	0.000	-14471.780	104.856	0.000	-14519.127
MSHAFTPMM12	Nominal Shaft PM-12 location	97.450	0.000	-13461.123	95.851	0.000	-13232.784
MSHAFTPMM11	Nominal Shaft PM-11 location	83.335	0.000	-11444.808	78.674	0.000	-10778.965
MSHAFTPMM10	Nominal Shaft PM-10 location	69.221	0.000	-9428.494	61.497	0.000	-8325.145
MSHAFTPMM9	Nominal Shaft PM-9 location	55.106	0.000	-7412.179	44.320	0.000	-5871.325
MSHAFTPMM8	Nominal Shaft PM-8 location	40.992	0.000	-5395.864	27.117	0.000	-3413.679
MSHAFTPMM7	Nominal Shaft PM-7 location	34.201	0.000	-4425.662			
TEML2PS	Electron Main Linac to Positron Source (Undulator Section)	26.540	0.000	-3331.319	26.540	0.000	-3331.319
PTARGET	Positron target	19.355	0.000	-2305.000	19.355	0.000	-2305.000
TPS2EBDS	Positron Source (Undulator Section) to Electron BDS	17.440	0.000	-2253.464	17.440	0.000	-2253.464
ETUDUMP	Electron Tuneup-Dump	8.293	0.000	-1376.513	8.293	0.000	-1376.513
EMUSP1	Electron Side Muon Spoiler 1 (res)	5.339	0.000	-647.950	5.339	0.000	-647.950
BEGPLTR	Positron source: start of transfer tunnel	6.221	0.000	-428.689	6.221	0.000	-428.689
PDUMP	Positron Main Dump	-2.104	0.000	-300.575	-2.104	0.000	-300.575
IP	Interaction Point	0.000	0.000	0.000	0.000	0.000	0.000

D0000000982315



LINEAR COLLIDER COLLABORATION Combining CAD Data: List of models

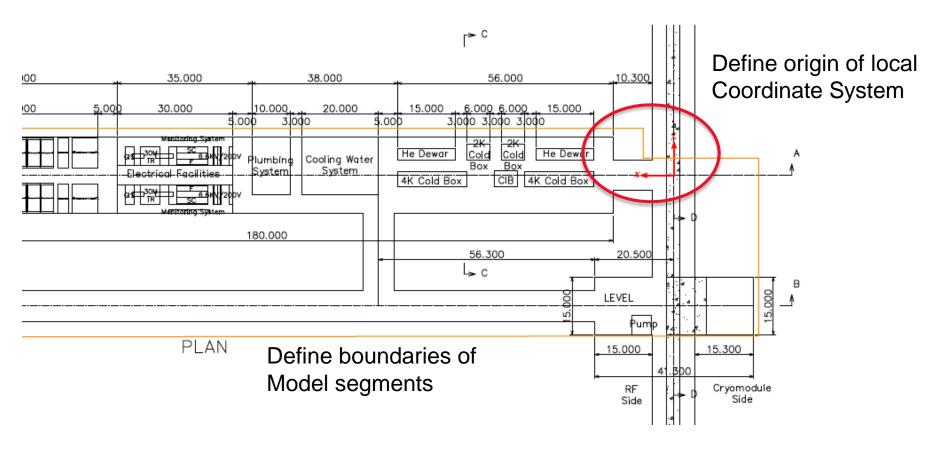


	A	В	· ·	D	F	E	G	н		- 1	K		M	N	0
2		_			-		u				IX.	-	141	14	
3	intoci	antional linear of	allidae												_
4		national linear cu	1111111141												
2 3 4 5	1111611	julivilui illivui vi	וטשוווע —												
		II C Boss Ornhan (BO) E													
6		ILC Base Orphan (BO) F													
7															
8		Version			2.95	06.05.14									
9															
10					Reference Point Coordinates			ocal Coordinates of Reference Poi			BO (Base Orphan) Coordinates				
				Reference											
11	Building	Description	EDMS ID	Point	x [m]	y [m]	z [m]	x [m]	y [m]	z [m]	x [m]	y [m]	z [m]	hor angle	vert ar
12	Exp_Hall_UXB0	Experimental hall	D00000001125663	IP	0.000	0.000	0.000	0.000	1.100	0.000	0.000	-1.100	0.000	0	
13	Cry_Hall_UH-12	Cryogenics Hall UH-12	D00000001424913	MSHAFTPMM12	95.851	0.000	-13232.784	-4.500	1.100	0.000	100.351	-1.100	-13232.784	-0.401	
14	Cry_Hall_UH-10	Cryogenics Hall UH-10	D00000001424923	MSHAFTPMM10	61.497	0.000	-8325.145	-4.500	1.100	0.000	65.997	-1.100	-8325.145	-0.401	
15	Cry_Hall_UH-8	Cryogenics Hall UH-8	D00000001424933	MSHAFTPMM8	27.117	0.000	-3413.679	-4.500	1.100	0.000	31.617	-1.100	-3413.679	-0.401	
16	Cry_Hall_UH+8	Cryogenics Hall UH+8	D00000001426393	MSHAFTPMP8	18.010	0.000	2334.874	-4.500	1.100	0.000	22.510	-1.100	2334.874	0.401	
17	Cry_Hall_UH+10	Cryogenics Hall UH+10	D00000001426413	MSHAFTPMP10	51.576	0.000	7129.974	-4.500	1.100	0.000	56.076	-1.100	7129.974	0.401	
18	Cry_Hall_UH+12	Cryogenics Hall UH+12	D00000001426423	MSHAFTPMP12	85.930	0.000	12037.614	-4.500	1.100	0.000	90.430	-1.100	12037.614	0.401	
19		Services Hall US-13	D00000001368993	BEGEBC1	113.228	0.000	-15715.104	-4.500	1.100	0.000	117.728	-1.100	-15715.104	-0.401	
20		Services Hall US+13	D00000001368993	BEGPBC1	101.574	0.000	14272.425	-4.500	1.100	0.000	106.074	-1.100	14272.425	-0.401	
21	Tum_R-13	Turnaround Tunnel R-13	D0000000xxxxxx3	BEGEBC1	113.228	0.000	-15715.104	-4.500	1.100	0.000	117.728	-1.100	-15715.104	0.401	
22	Tunnel_T-12	Tunnel T-12 (RTML, Bunch Compressor, e- ML)	D0000000xxxxxx3	MSHAFTPMM12	95.851	0.000	-13232.784	-4.500	1.100	2502.217	100.351	-1.100	-15735.001	-0.401	
23	Tunnel_T-11	Tunnel T-11 (e- ML)	D00000001425733	MSHAFTPMM12	95.851	0.000	-13232.784	-4.500	1.100	-10.300	100.351	-1.100	-13222.484	-0.401	
24	Tunnel_T-10	Tunnel T-10 (e- ML)	D00000001425743	MSHAFTPMM11	78.674	0.000	-10778.965	-4.500	1.100	0.000	83.174	-1.100	-10778.965	-0.401	
25	Tunnel_T-9	Tunnel T-9 (e- ML)	D00000001425713	MSHAFTPMM10	61.497	0.000	-8325.145	-4.500	1.100	-10.300	65.997	-1.100	-8314.845	-0.401	
26	Tunnel_T-8	Tunnel T-8 (e- ML)	D00000001425723	MSHAFTPMM9	44.320	0.000	-5871.325	-4.500	1.100	0.000	48.820	-1.100	-5871.325	-0.401	
27	Tunnel_T-7	Tunnel T-7 (Undulator)	D0000000xxxxxx3	MSHAFTPMM8	27.117	0.000	-3413.679	-3.000	1.100	0.000	30.117	-1.100	-3413.679	-0.401	
28 29	Tunnel_T-6	Tunnel T-6 (Electron dogleg)	D00000000xxxxxx3	MSHAFTPMM8	27.117	0.000	-3413.679	-3.000	1.100	0.000	30.117	-1.100	-3413.679	-0.401	
30	Tunnel T+8	Tunnel T+8 (e+ ML)	D00000001426443	MSHAFTPMP8	18.010	0.000	2334.874	-4.500	1,100	-92.8	22.510	-1,100	2427,674	0.401	
31	Tunnel T+9	Tunnel T+9 (e+ ML)	D00000001426433	MSHAFTPMP9	34.399	0.000	4676.155	-4.500	1.100	-52.0	38.899	-1.100	4676.155	0.401	
32	Tunnel T+10	Tunnel T+10 (e+ ML)	D00000001426463	MSHAFTPMP10	51.576	0.000	7129,974	-4.500	1.100	-92.8	56.076	-1.100	7222,774	0.401	
33	Tunnel T+11	Tunnel T+11 (e+ ML)	D00000001426453	MSHAFTPMP11	68.753	0.000	9583.794	-4.500	1.100	-92.6	73.253	-1.100	9583.794	0.401	
34	Tunnel_1711	Tullion 1 · 11 (o · ML)	D00000001420433	MOTINI TEMETI	00.755	0.000	3303.134	-4.500	1.100	U	73.233	-1.100	3303.134	0.401	

- Complete CAD model (buildings, lattices, detectors, surface) is assembled from JT files in a visview session (not in CAD system)
- -> result in EDMS: D00000001420943
- Method well established for XFEL project,
- independent from CAD native file format
- Requires agreed segmentation of 3D models, with local coordinate systems

Segmentation: Example for Cryo Hall









- Definition of an ILC CRS brings together geospacial data and CAD models, for use in GIS and CAD systems
- Enables modeling of the entire facility
- **Applications:**
 - Interface verification
 - Interactive reviews (also in Virtual Reality rooms)
 - Vision sharing
 - Public relations
- Design integration requires common CAD model conventions for coordinate systems, segmentation
- **Experience from XFEL: Establish standards and** conventions early, before the real work starts: Now