Summary of ILD Stray Field Calculations

LSWC 2014 Belgrade

Uwe Schneekloth, DESY





Outline

- Stray field requirements
- Initial calculations
- Recent calculations
 - Motivation
 - Trying to reduce size of ILD yoke
 - Better understanding of uncertainties
- Conclusions

Main work done by:

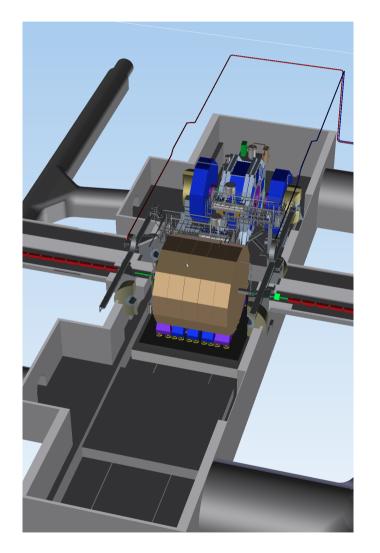
- A.Petrov, M.Lemke, B.Krause (DESY)
- E. Bondarchuk, B. Kitaev, E. Vyrva (Efremov Insitute, St.Petersburg)

Some involvement:

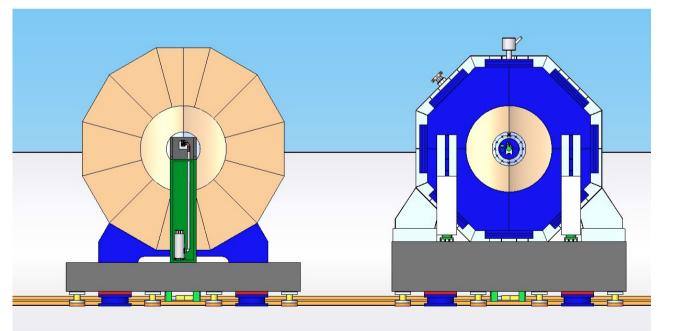
K.Büsser, K.Sinram, U.S.



Stray field requirements



- Two detectors in one experimental hall, in beam and in park position
- Requirements on stray field
 - 50G in 15m radial distance from detector center based on CMS experience

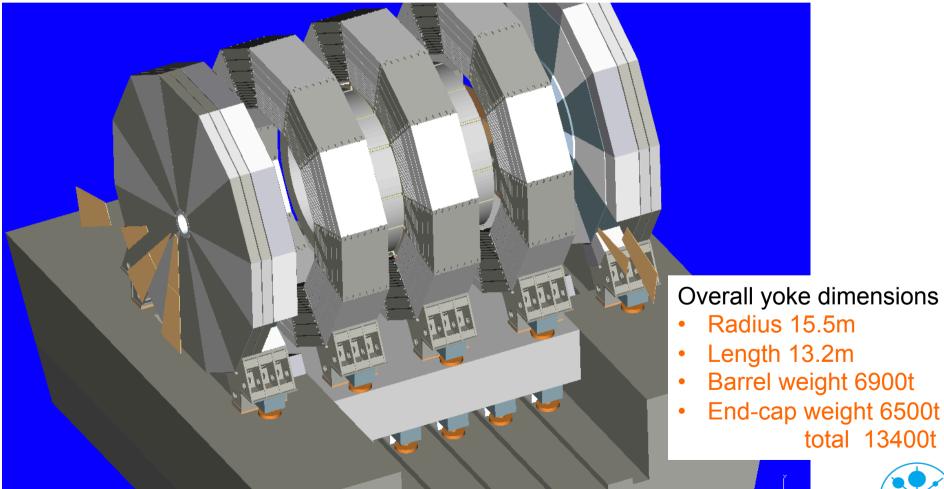




Yoke Design Overview

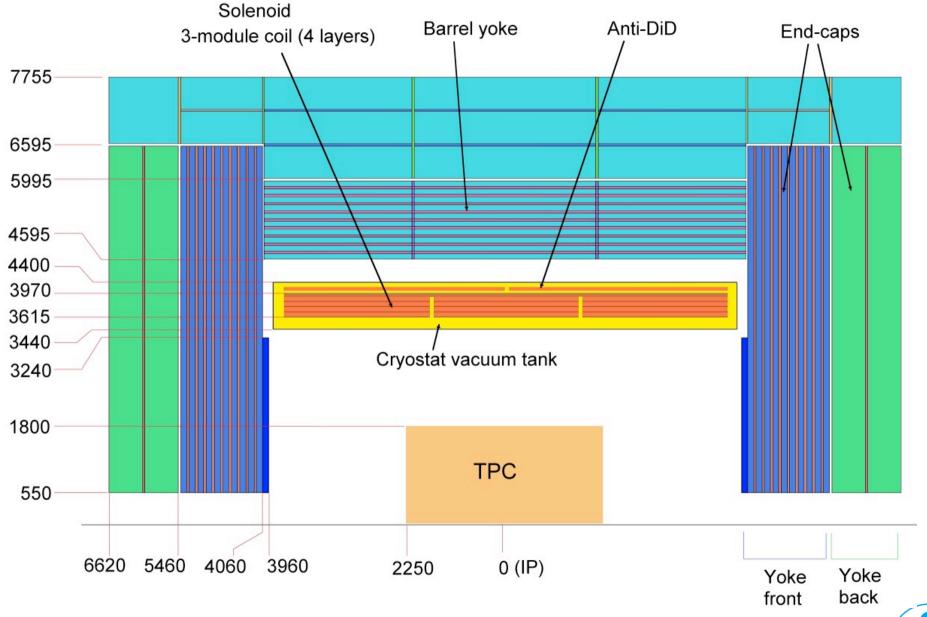
Design based on CMS

- Large volume magnet (similar to CMS)
 - Field: 4T (maximum), 3.5T (nominal operation)





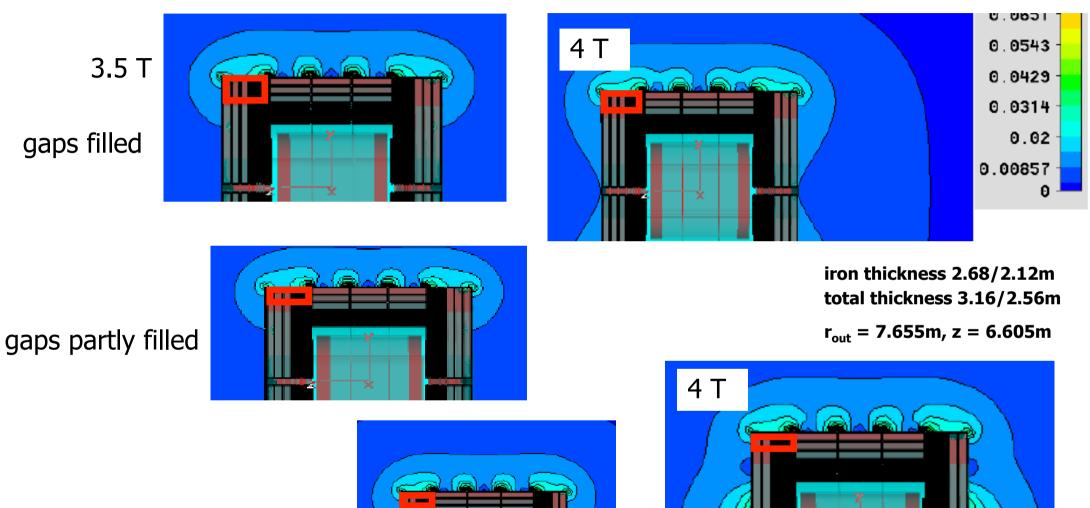
Yoke Cross-Section Overview





Stray Field Calculations

CST Studio 3D, A. Petrov, 2008



gaps partly filled, EC 2 plates

Uwe Schneekloth | ILD Stray Field, LCWS 2014 | Page 6

DESY

Stray Field Calculations

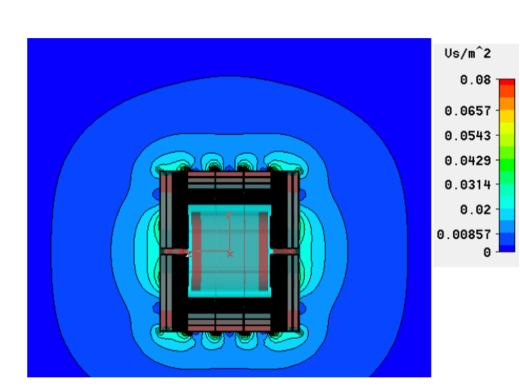
	central field 3.5 T								4 T	
									•	
	3 thick plates		3 thick plates		3/2 thick plates		3/2 thick plates			
iron yoke	3 thick plates		EC filled		EC partly filled		EC partly filled		EC partly filled	
B (T)	3.6		3.6		3.6		3.6		4	
z (m)	0	5.4	0	5.4	0	5.4	0	5.4	0	5.4
B stray (G)	y (m)	y (m)	y (m)	y (m)	y (m)	y (m)	y (m)	y (m)	y (m)	y (m)
200	7.7	11.3	7.6	7.9	7.6	7.9	7.6	8.2	7.6	8.4
100	13.4	13.9	10	10.3	10	10.3	10	10.3	10.5	10.6
50						<	13.2	12.6	13.7	13.2
	d (m)	d (m)	d (m)	d (m)	d (m)	d (m)	d (m)	d (m)		
200	0	3.6	0	0.3	0	0.2	0	0.5	0	0.7
100	5.7	6.2	2.3	2.6	2.3	2.6	2.3	2.6	2.8	2.9
50							5.5	4.9	6	5.5

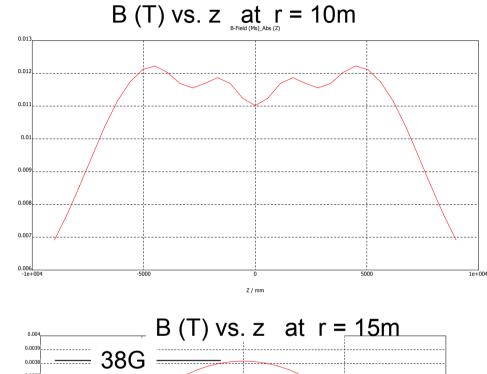
Stray field < 50G at 15m horizontal distance from beam line for 4 T. Limit as discussed in Chicago MDI meeting.

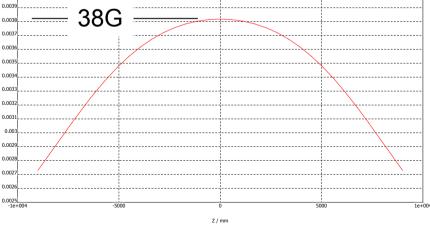


Stray Field Calculations

CST Studio 3D, A. Petrov, 2008







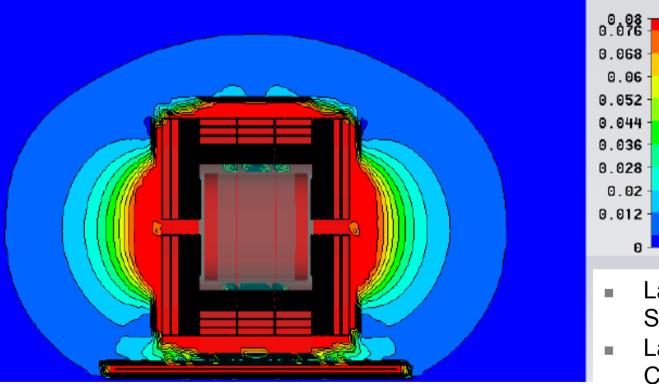


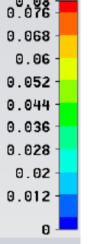
Stray Field with Floor Steel Plate

Simplified iron support feet, 4 T field >

A. Petrov, 2009

- Floor with steel plate (20m x 20m 60mm thick) >
- Increased end-cap hole to 1.1m diameter for rectangular support tube



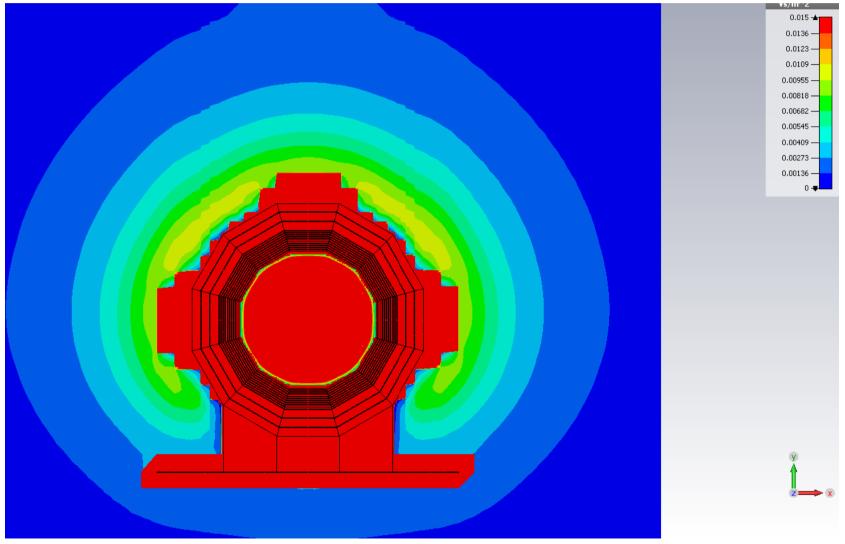


- Large field in steel floor 1.6T Similar with non-magnetic feet
- Larger EC hole increases stray field in z Cylindrical support tube would be better



Stray Field with Floor Steel Plate

- Simplified iron support feet, 4 T field
- Floor with steel plate (20m x 20m 60mm thick)

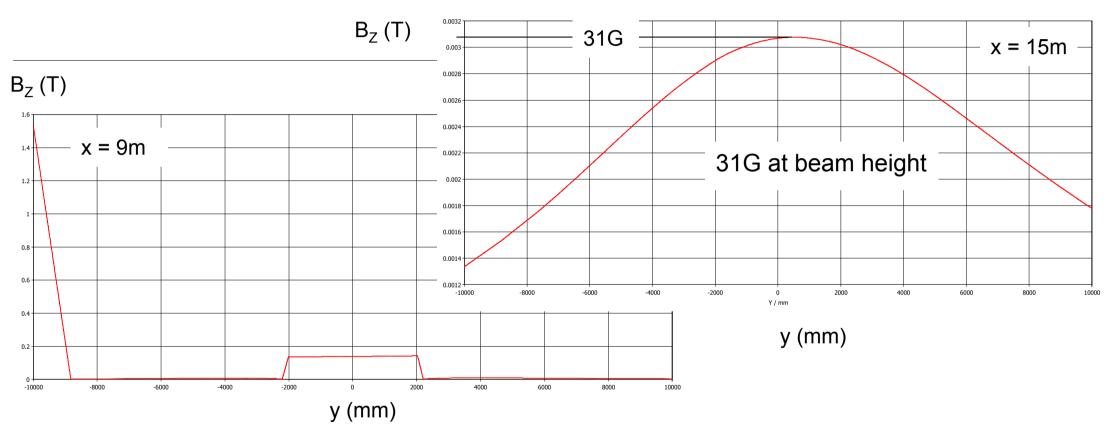




A. Petrov, 2009

Stray Field with Floor Steel Plate

Field at z = 0, x = 9m (on platform) and 15m as function of y (-10 to 10m)



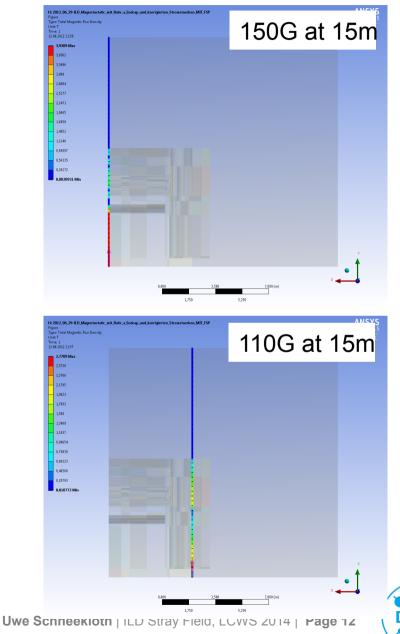
- Large field in steel floor, 1.6T
- Field obviously asymmetric
- Achieve <50G at 15m</p>



More Recent Field Calculations

Motivation

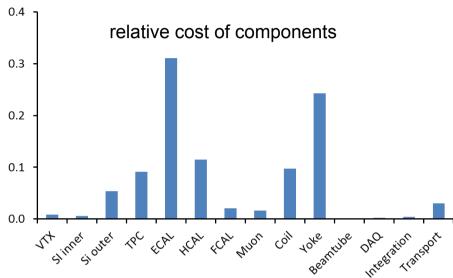
- FEM calculations of yoke deformation and stress due to magnetic forces using Ansys 3D code
- Used updated coil configuration (minor change)
- Looked at stray fields as well
- Quite a bit a higher: 150G
- Recently, checked calculations again. Found some issues. No conclusion yet. Work in progress.



M. Lemke 2012

Yoke Discussion

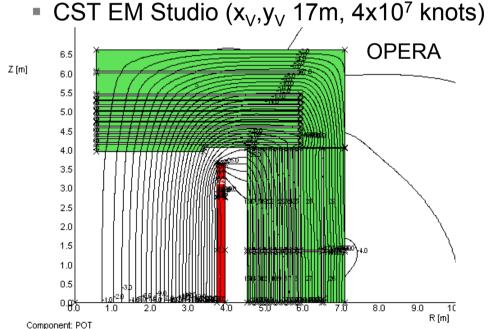
- > Thickness and cost of yoke is determined by stray field requirements
- > Reduce iron (cost saving)?
 - Coil Geometry (2nd large solenoid): No
 - Additional end cap coils (CLIC detector): No, power consumption too expensive
 - Add shielding iron at distance: No
 - Reduce iron thickness ???
- Need good understanding of field calculations
 - Uncertainties and limits of FEM code
 - Different code, mesh size, mesh, ...
- Realistic simulation/description of detector in real hall
 - Additional iron (infrastructure, services, scaffolding,...)?
 - Platform/floor, hall walls, …



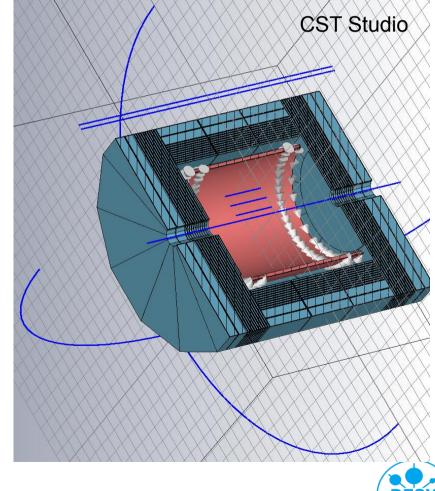


New Field Calculations

- Spring/summer 2014 study at Efremov Institute (St.Petersburg)
 - Motivation: field for reduced yoke, compare FEM codes
- Slightly reduced radius, 2 instead of 3 thick iron plates (60cm less in radius)
- Study dependence on FEM codes
 - ANSYS Maxwell 2D and 3D (x_V,y_V 30 40m)
 - OPERA 2D and 3D (x_V,y_V 30 40m)



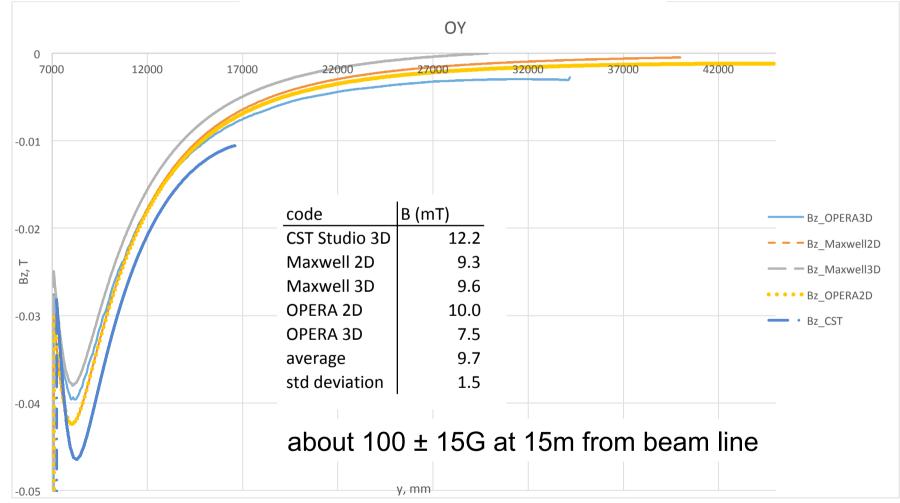
Minimum: -30.0, Maximum: 0.0, Interval: 1.0



New Field Calculations: Reduced Radius

Comparison of different FEM codes

Efremov, 2014



 B_z (T) as function of y for x=0, z=0



New Field Calculations: Reduced Radius

- > CST EM Studio volume size x_V, y_V 17m, limited by memory
- Repeated simulation at DESY, varying volume size

CST Studio 3D							
volume size r (m)	B (mT)						
17 (Efremov)	12.2						
30 (DESY)	9.9						
40 (DESY)	10.8						
60 (DESY)	8						

all ~ 100G



Conclusions

Present design

- Achieved goal of < 50G at 15m distance from beam line for 4 T</p>
 - Still have to understand ANSYS calculations
- > Thickness and cost of yoke (and size of detector) determined by stray field requirements
- Important to close gaps as much as possible
- Preliminary study of influence of steel plate floor (platform)
 - Small change of field in air, large field in floor
- \rightarrow Large size makes yoke very expensive, would like to reduce size

Smaller yoke

- Set 100G for slightly smaller barrel (60cm less in radius)
- Independent FEM calculations very consistent

However,

- > At limit of FEM codes, required accuracy ~0.1% of max. field
- Need realistic description of hall
 - Steel in platform, wall, any other magnetic materials
- > Avoid magnetic material between detectors



Proposal

- > Stray field only important on one side of detector in operation
 - No major work on detector in operation (accept replacing some electronics,...)
 - Do not disturb work on detector in park position

Proposal

- > No electronics and infrastructure (which requires maintenance) on side facing other detector
- > Avoid magnetic material between detectors as much as possible
- Restricted access between detectors when magnet on
- Agree on increasing stray field to reasonable level

