

# Studies on GEM modules for a Large Prototype TPC for the ILC.

Dimitra Tsiou

On behalf of the LCTPC Collaboration

VCI 2016 - Vienna, 19-Feb-2016



- > A time projection chamber for the ILC
- > Performance
- > Ongoing optimisation studies



> A time projection chamber for the ILC

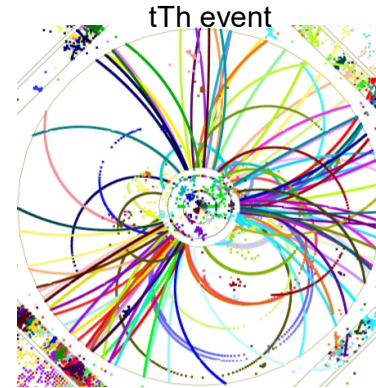
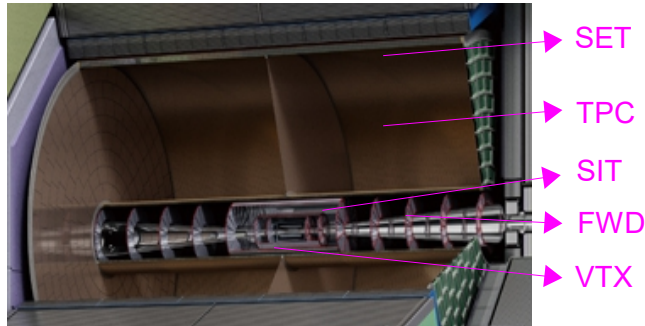
Performance

Ongoing optimisation studies



# International Large Detector – Tracking Requirements

- > The International Large Detector (ILD) is one detector concept for the International Linear Collider (ILC)



- > Momentum resolution:

- $\sigma(\Delta p_T/p_T^2) = 2 \cdot 10^{-5} \text{ GeV}^{-1}$
- TPC alone:  $10^{-4} \text{ GeV}^{-1}$

- > Tracking efficiency

- close to 100% down to low momenta for Particle Flow

- > Minimum material

- > Full angular coverage and high hermeticity

- > TPC dimensions

- $\pm 2.35 \text{ m}$  in  $z$ ,  $1.8 \text{ m}$  outer radius

- > The TPC provides

- $\sim 200$  space points along the track
- $\sigma \sim 100 \mu\text{m}$  in the  $r\phi$  plane (full drift)
- $\sigma \sim 400 \mu\text{m}$  in the  $z$  direction at zero drift and  $1.4 \text{ mm}$  at full drift
- $dE/dx$  measurement for PID
- $5\% X_0$  for barrel &  $25\% X_0$  for endcaps

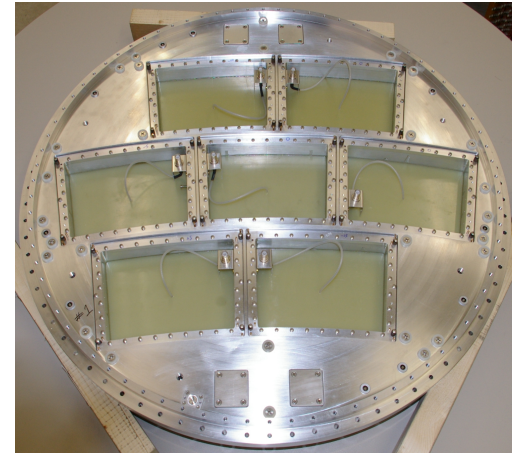
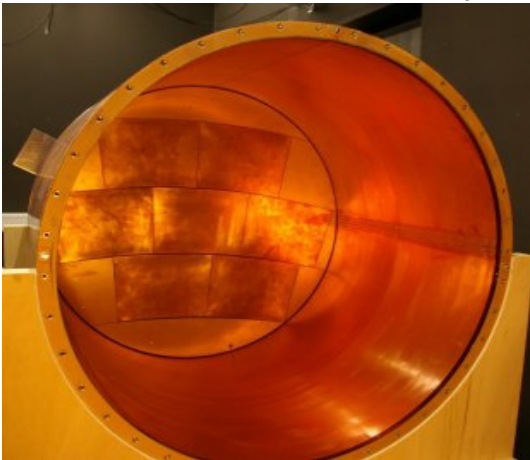




# Large Prototype TPC

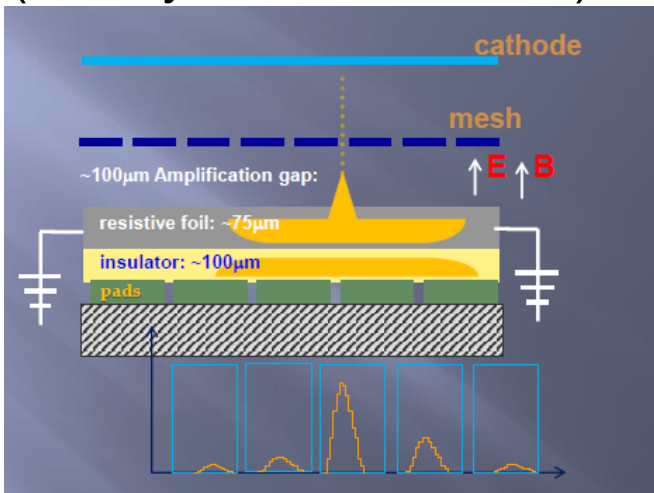
- Large Prototype TPC built and installed by the LCTPC collaboration in order to test different readout technologies and scale up to dimensions relevant to the ILD
- Technologies under investigation: GEMs, InGrid, Micromegas
- LP field cage parameters:
  - Length: 61 cm, Diameter: 72 cm
  - Up to 25 kV →  $E_{\text{drift}}$  up to 350 V/cm
  - Wall material budget: 1.3%  $X_0$

- The endplate is able to host 7 readout modules (dimensions  $\sim 22 \times 17 \text{ cm}^2$ )



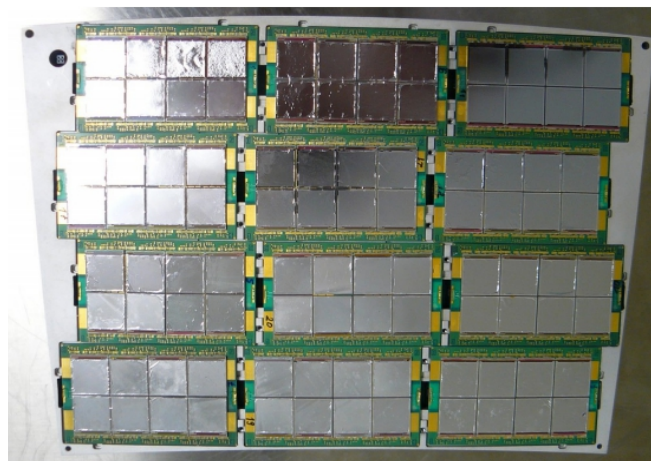
# ILD TPC – MPGD Readout Technologies Overview

## > Micro-Mesh Gaseous Detectors (Saclay, Carleton, SINP)



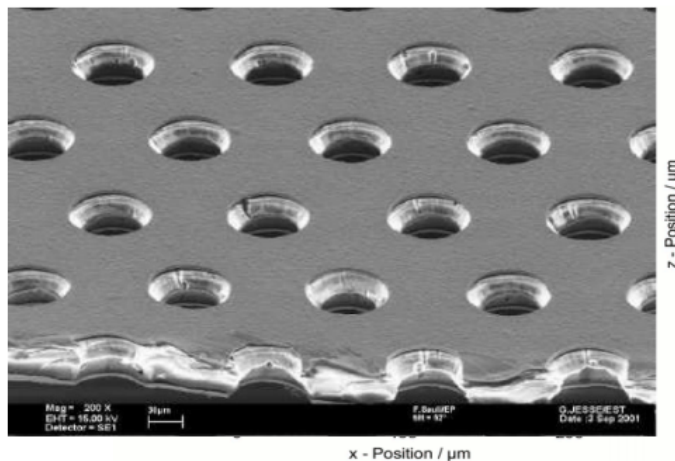
## > GridPix (Bonn, Nikhef, Saclay, Siegen)

- Micromegas with pixel readout



Talk by J. Kaminski on Thursday

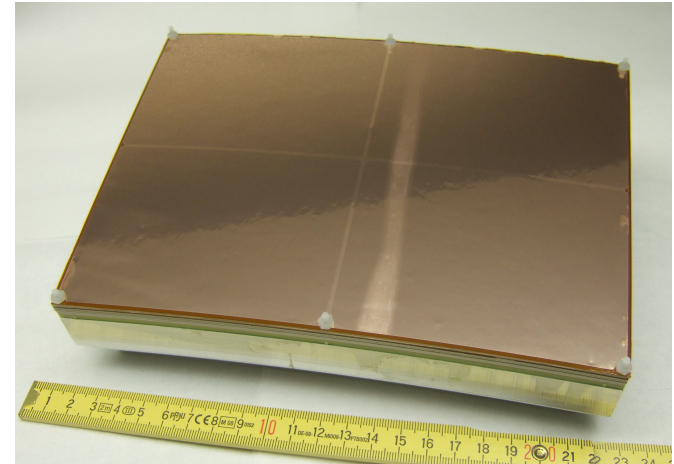
## > Gas Electron Multipliers (DESY, Japan, Bonn, Lund)



# DESY GEM module

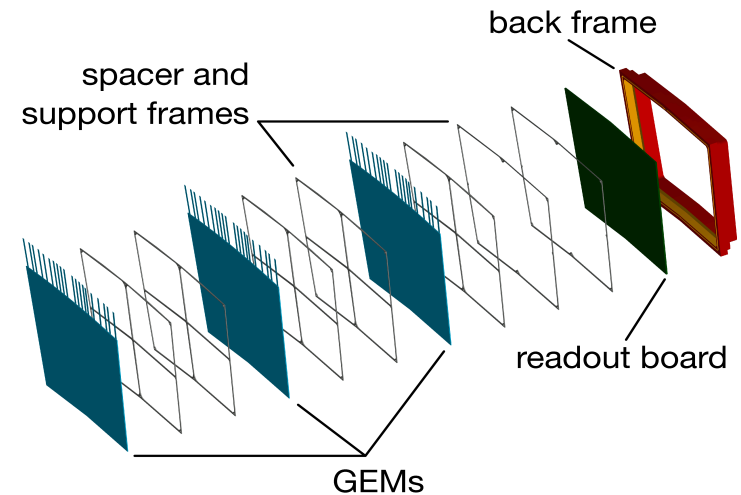
## > Goals

- Maximum active area
- Minimum material budget
- Field and high gain homogeneity
  - Flatness of GEMs
- Minimal field distortions (field shaping wire/strips)



## > GEM module design and characteristics

- Ceramic grid frame (integrated support structure)
- Anode divided into 4 sectors
- No division on cathode side
- Triple GEM stack (→ stable operation at high gain and flexibility)
- Pad size  $1.26 \times 5.85 \text{ mm}^2$  (~5k pads per module)



A time projection chamber for the ILC

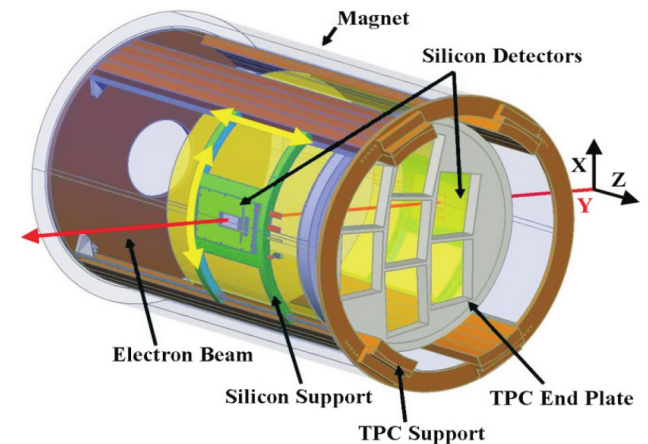
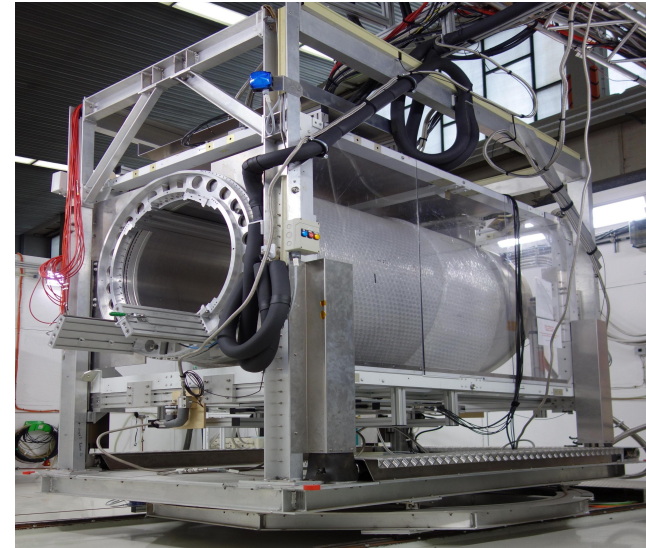
## > Performance

Ongoing optimisation studies



# Test beam infrastructure

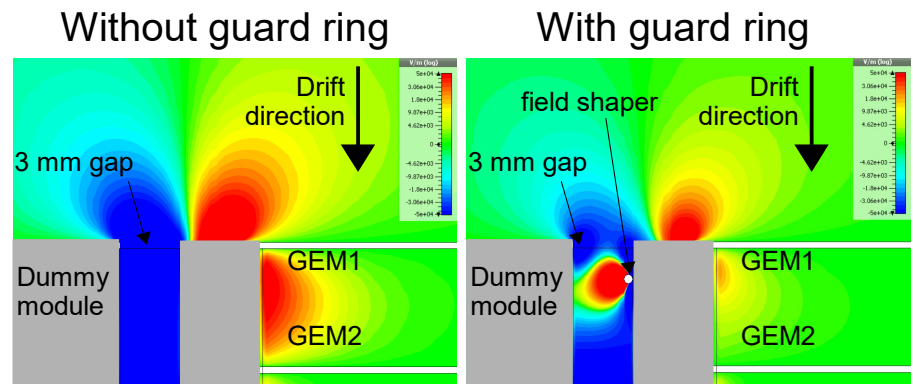
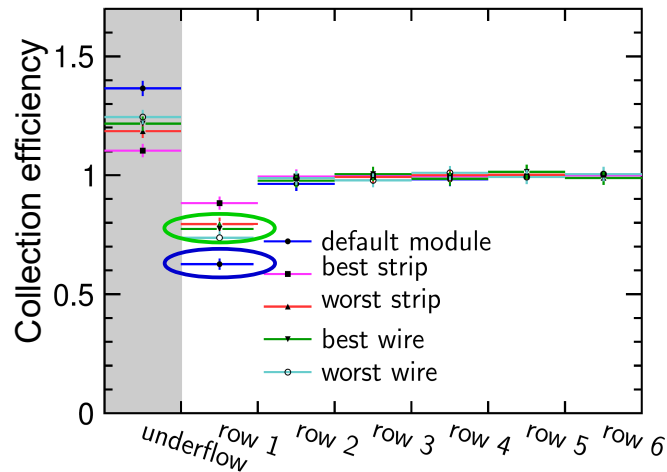
- Infrastructure includes a large bore 1T magnet
  - 20%  $X_0$  material budget
- Ongoing effort to build an external Silicon tracker to provide reference tracks for the TPC
- Motivation: ability to study field distortions and alignment and measure the momentum resolution during combined test beams with the TPC system
- Challenge: Si tracker needs to fit in the existing TPC infrastructure (3.5 cm gap)
  - Stringent requirement on sensor spatial resolution: better than 10  $\mu\text{m}$





# Field Distortions

- Inhomogeneities in the electric field can result in loss of signal and have an impact on the resolution
- Electric field distortions more pronounced at module edges
  - Guard ring introduced to minimise local field distortions at module borders



- Loss of signal close to module edge partially recovered when introducing a guard ring

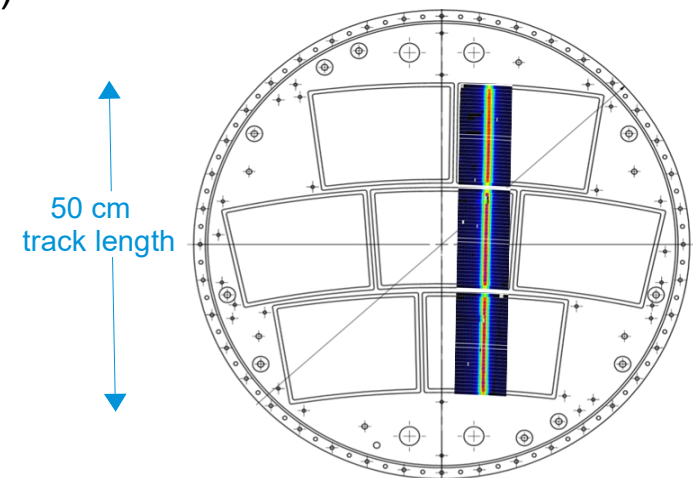
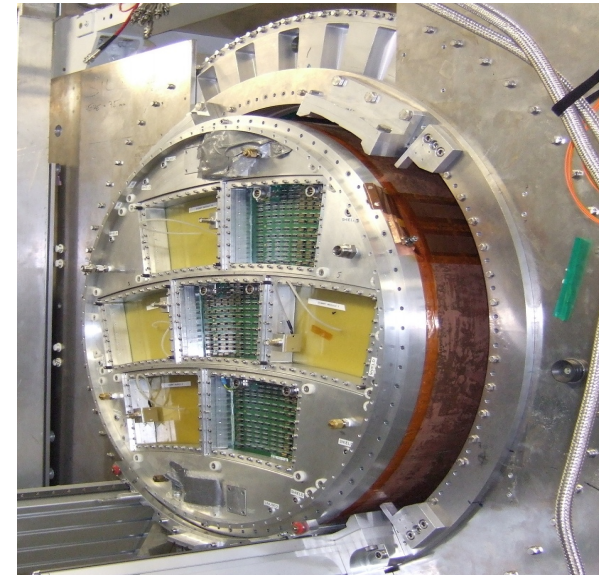
## > DESY GEM module test beam campaign 2013

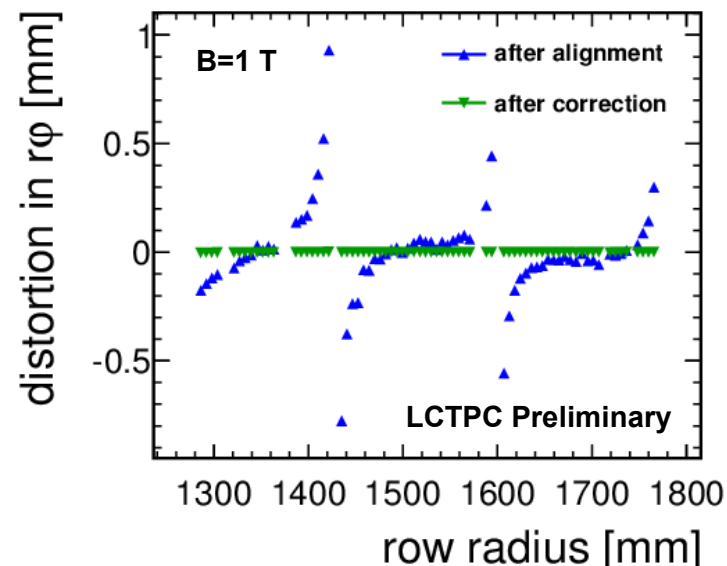
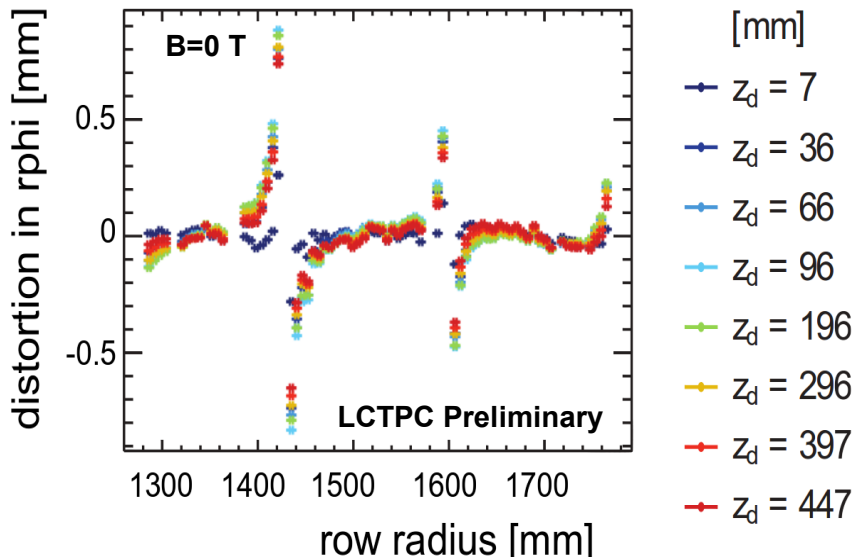
## > Experimental setup

- 3 GEM modules, partly equipped with readout electronics (~7k channels)
- 20 MHz sampling frequency
- Gas mixture: 95% Ar, 3% CF<sub>4</sub>, 2% iC<sub>4</sub>H<sub>10</sub>
- Default drift field 240 V/cm (maximum drift velocity) or 130 V/cm (minimal diffusion)

## > Goal

- Validation of module design and performance understanding
- Test of field shaping approach
- Calibration of alignment schemes





- > Displacement and rotation of GEM module
- > Use  $B=0$  T data where  $E \times B$  effects not present
- > Corrections up to 0.1 mm and a few mrad
- > Field distortion caused by inhomogeneities in magnetic and drift fields
  - $E \times B$  terms pronounced at module edges
- > Distortions derived from 10% of events and applied to the rest



# Analysis & Resolution

## > Selection requirements

- Track has at least 60 hits (out of 71 operational rows)
- Track is perpendicular to the pads
- Events with only one track are considered

## > Single point resolution

$$\sigma_{r\varphi/z}(z) = \sqrt{\sigma_{0,r\varphi/z}^2 + \frac{D_{t/l}^2}{N_{\text{eff}} \cdot e^{-Az}} z}$$

Intrinsic resolution of the readout at zero drift distance in  $r\varphi/z$

Effective number of primary signal electrons

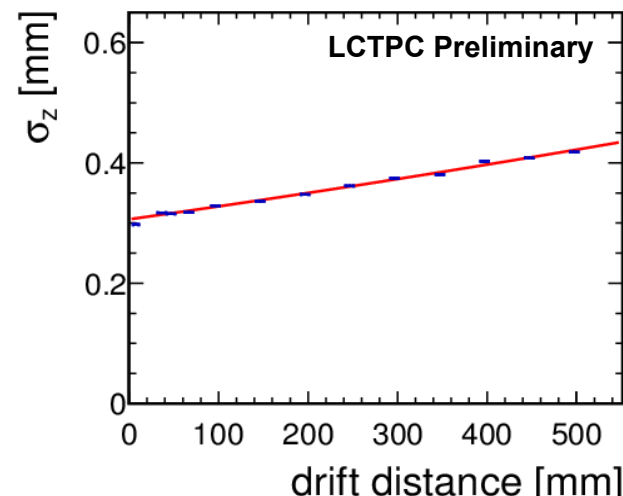
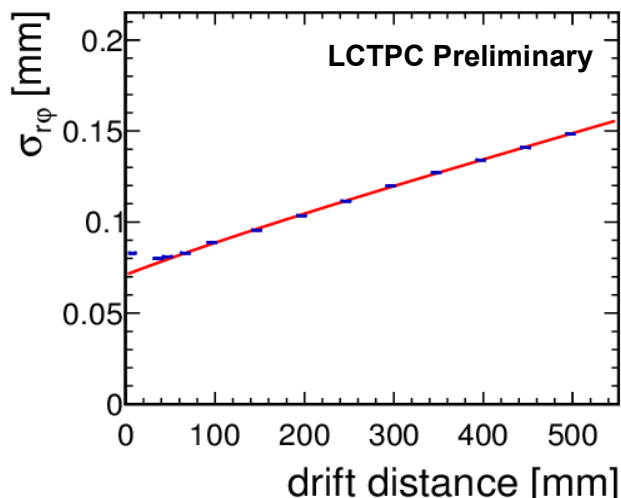
Attachment of primary electrons to gas molecules during drift

Transverse and longitudinal diffusion



## > Single point resolution

$$\sigma_{r\varphi/z}(z) = \sqrt{\sigma_{0,r\varphi/z}^2 + \frac{D_{t/l}^2}{N_{\text{eff}} \cdot e^{-Az}} z}$$



$\sigma$	$\sigma_{0,r\varphi/z} [\mu\text{m}]$	$N_{\text{eff}}$	$A [\text{m}^{-1}]$	$D_{t/l} [\text{mm}/\sqrt{\text{cm}}]$ (fixed)
$r\varphi$	$71.0 \pm 1.2$	$39.8 \pm 2.0$	$0.495 \pm 0.097$	0.103
$z$	$306.3 \pm 0.8$	$39.5 \pm 1.6$	$0.529 \pm 0.084$	0.226

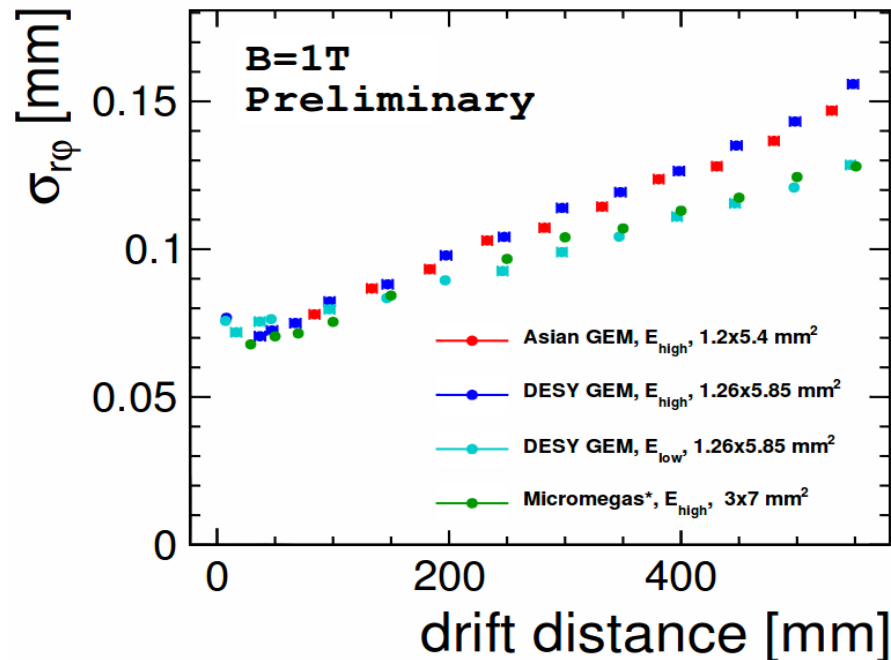
> The ILD TPC requirement of  $r\varphi$  resolution  $< 100 \mu\text{m}$  for full drift distance at 4T corresponds to an  $r\varphi$  resolution  $< 150 \mu\text{m}$  for the large prototype TPC at 1T

>  $z$  resolution  $\sim 300 \mu\text{m}$  at zero drift distance (ILD TPC requirement)



# Comparison between different MPGD technologies

- Different modules in the LP compared under similar conditions and reconstructed with the same tools



$E_{low} = 130\text{-}140 \text{ V/cm}$

→ minimal transverse diffusion

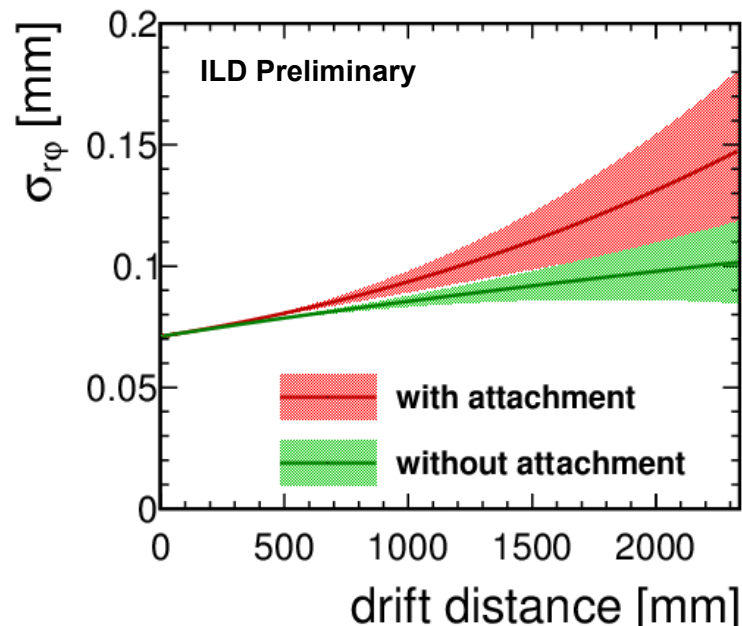
$E_{high} = 230\text{-}240 \text{ V/cm}$

→ maximum drift velocity

- All modules show comparable resolution



# Resolution – Extrapolation to ILD scale



- Extrapolation of the  $r\phi$  resolution from the Large Prototype conditions to the planned ILD detector
  - 3.5 T magnetic field and 2.35 m drift length
- To reach the ILD goal of 100  $\mu\text{m}$  at full drift distance, gas quality and purity need to be tightly controlled at ILD

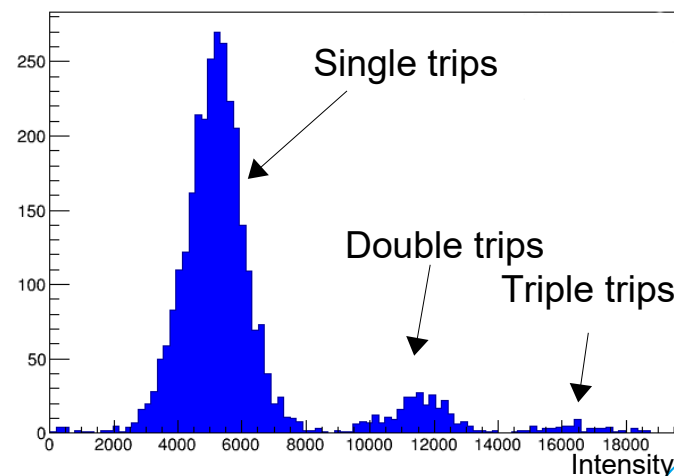
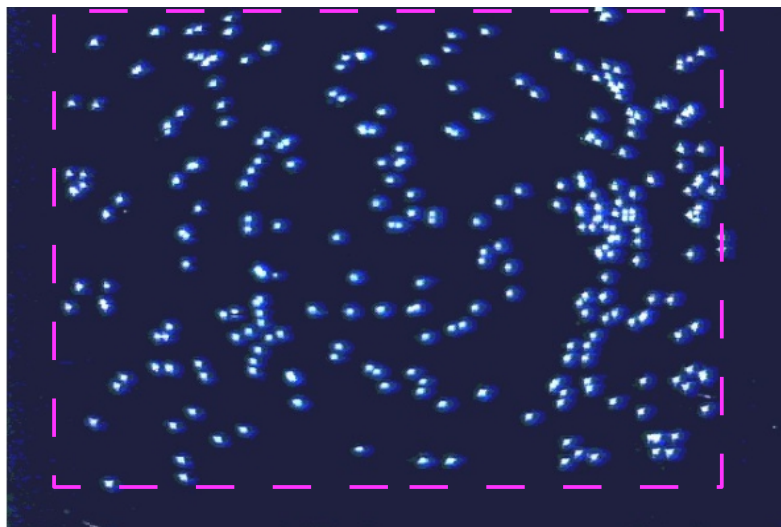
A time projection chamber for the ILC

Performance

> Ongoing optimisation studies

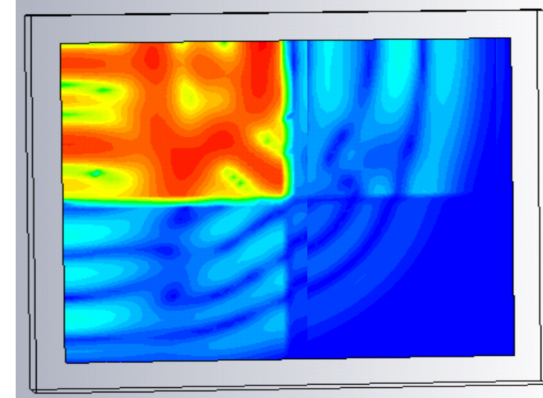
# GEM stability

- Observed discharges & destructive discharges during extreme conditions
- Investigate and improve long-term stability to demonstrate suitable performance for the ILD TPC
  - Optical and electrical observations of sparks of single GEMs in module-like setup
  - Simulations of the system to understand the behaviour
- Double and triple trips have been observed
  - No correlation with destructive charges observed

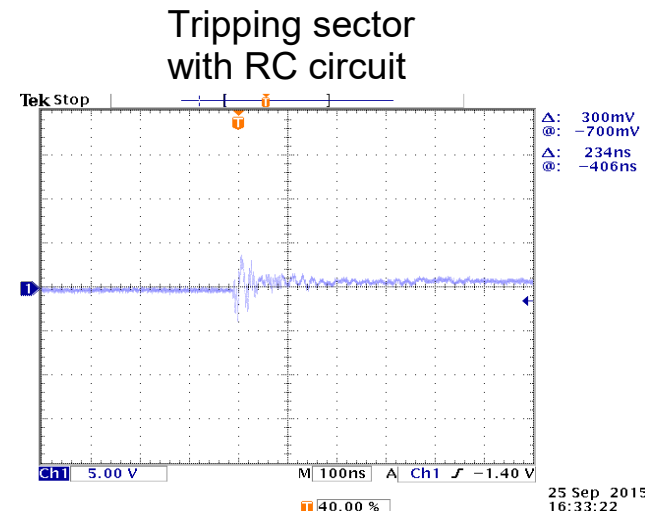
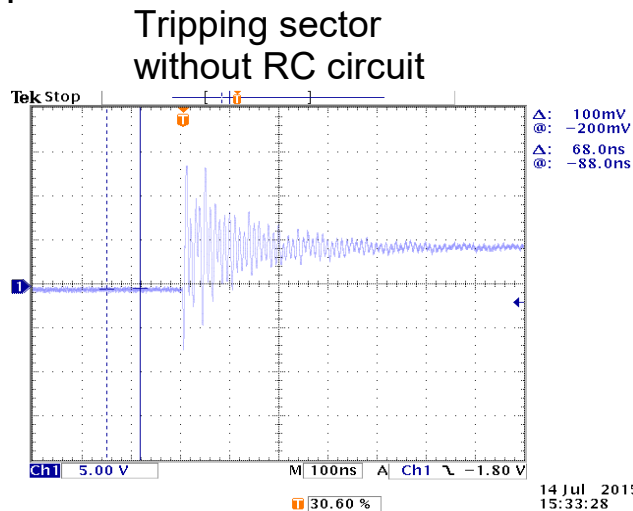


# GEM stability (2)

- Discharge causes current oscillations on GEM surface in different sectors (CST<sup>®</sup> simulations)

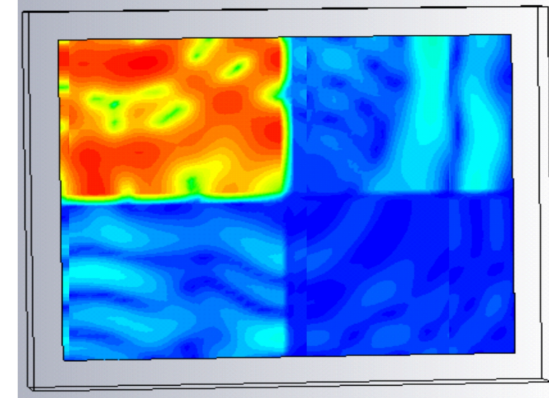


- Test setup using an R-C circuit to damp the oscillations and reduce the number of double discharges
  - Further ongoing studies to decide whether this will be included in the next module iteration

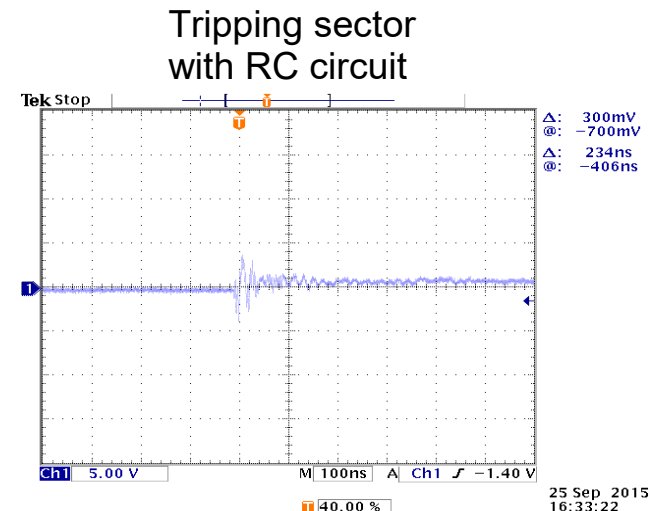
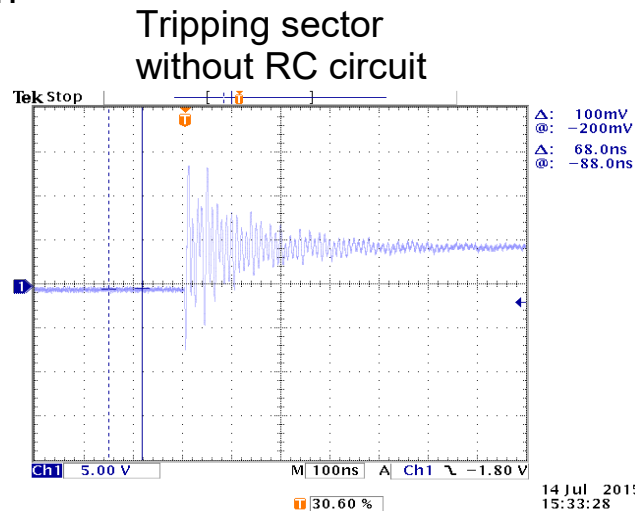


# GEM stability (2)

- Discharge causes current oscillations on GEM surface in different sectors (CST<sup>®</sup> simulations)



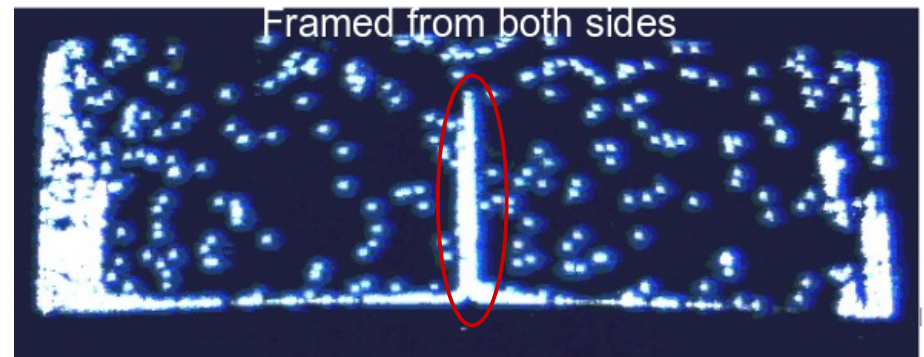
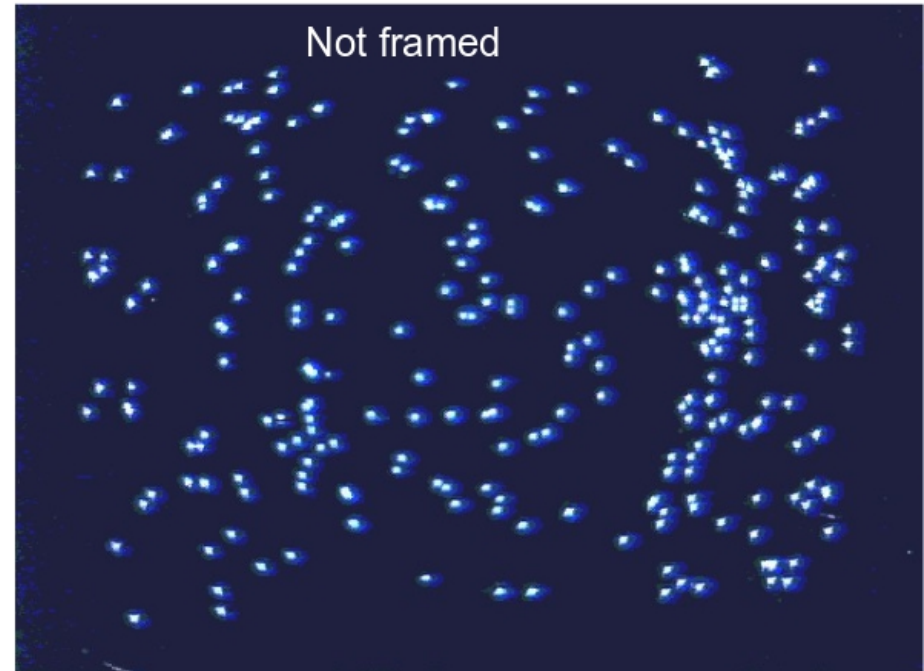
- Test setup using an R-C circuit to damp the oscillations and reduce the number of double discharges
  - Further ongoing studies to decide whether this will be included in the next module iteration





# GEM stability (3)

- > Trips concentrated close to the frame
- > Glueing/frame/stretching effects?
- > Ongoing optimisation of glueing procedure for the next module iteration



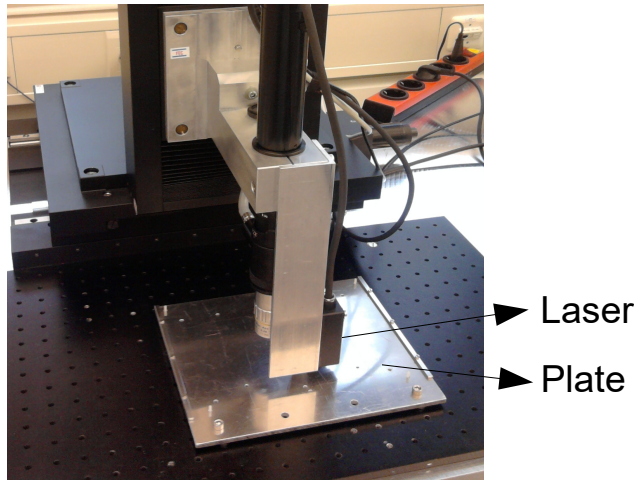
# GEM flatness

## > Flatness of GEMs guarantees

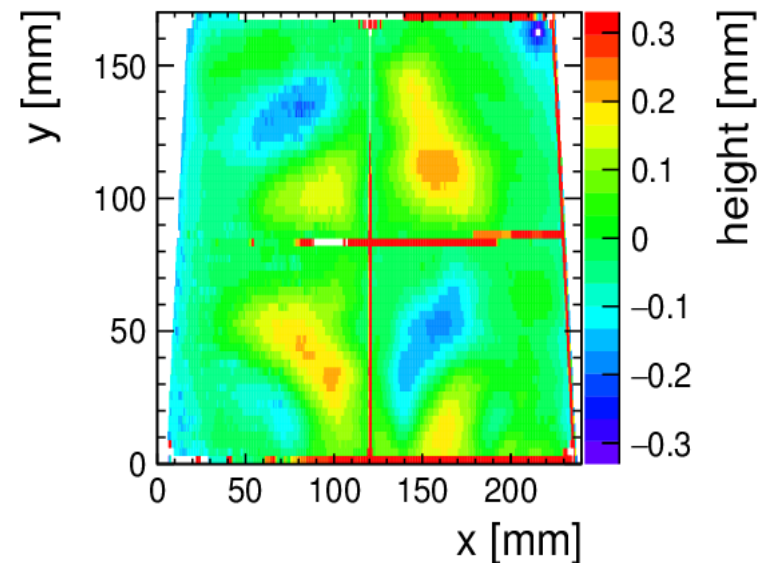
- a uniform gain distribution → precise  $dE/dx$  measurements
- electric field homogeneity between the GEMs and in the field cage

## > Measurements performed on XYZ table using a laser measurement head

- GEM mounted on a precise plate

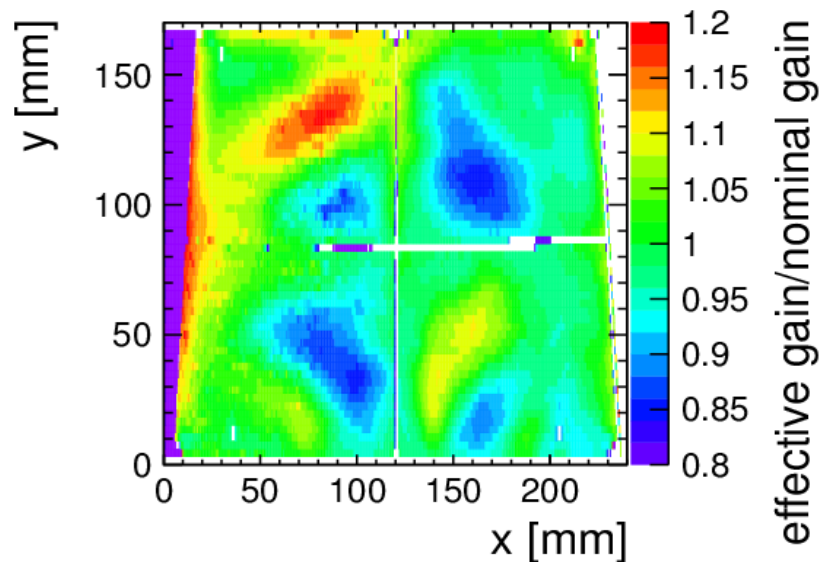


## > Flatness of current GEM structure is at the level of 150 $\mu\text{m}$ (rms)



## GEM flatness (2)

- 3 GEM profiles used to simulate an operating GEM module
- RMS of effective/nominal gain ~6%



- Considering new ceramic frame design
- Developing optimised tools and procedures & reproducible mounting and glueing process



# Conclusions

- Successful previous test beam campaign
  - Showing excellent performance of the LPTPC and GEM modules
  - Understanding of the system
  - Extrapolation shows we can achieve the resolution requirements of the ILD TPC
- Ongoing optimisation process for Large Prototype TPC and GEMs
  - Long-term stability of GEMs: Detailed ongoing simulation studies and measurements
  - Investigating optimised ceramic frame design and mounting procedure to improve flatness of GEMs
- These topics are under investigation in order to be included in the next TPC test beam campaign at DESY (2016)
- Infrastructure at DESY is constantly improved

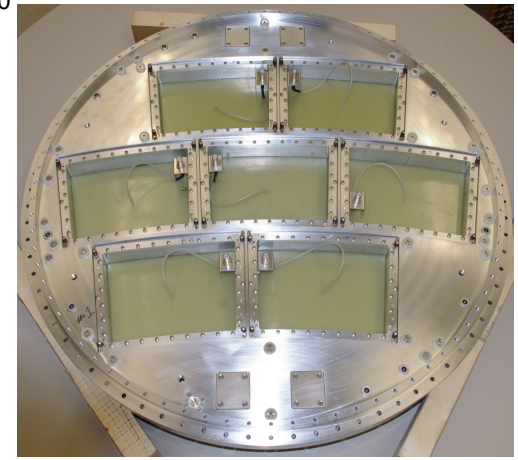
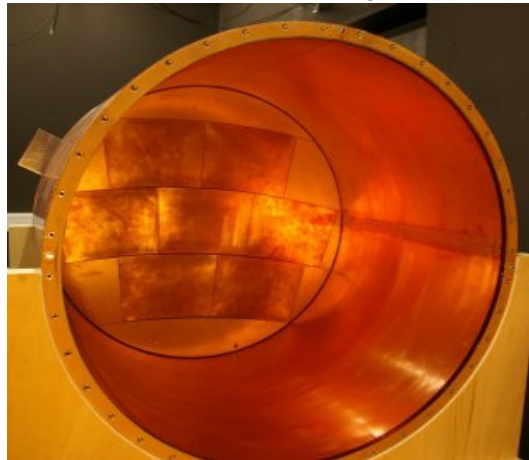
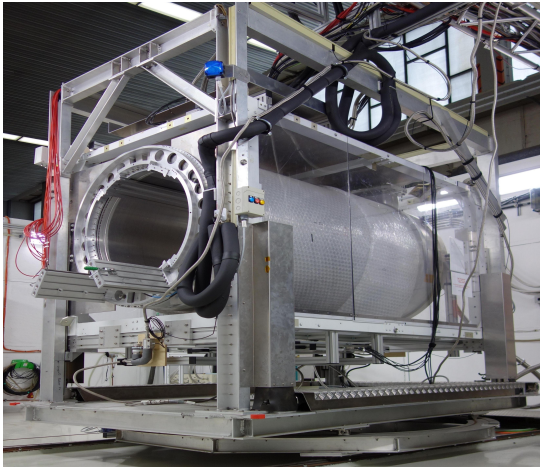


# BackUp



# Large Prototype TPC

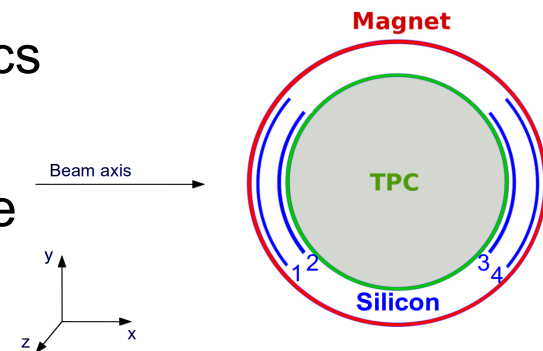
- > Large Prototype TPC built and installed by the LCTPC collaboration in order to test different readout technologies and scale up to dimensions relevant to the ILD
  - > Infrastructure includes a large bore 1T magnet
    - 20%  $X_0$  material budget
  - > LP field cage parameters:
    - Length: 61 cm, Diameter: 72 cm
    - Up to 25 kV  $\rightarrow E_{\text{drift}}$  up to 350 V/cm
    - Wall material budget: 1.3%  $X_0$
  - > The endplate is able to host 7 readout modules (dimensions  $\sim 22 \times 17 \text{ cm}^2$ )





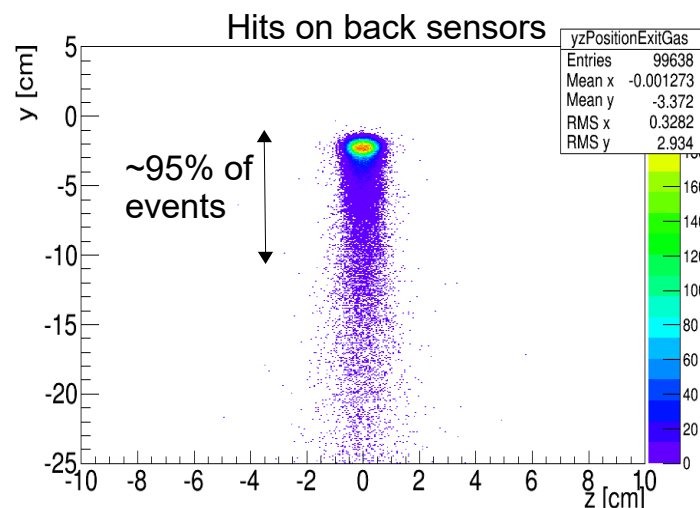
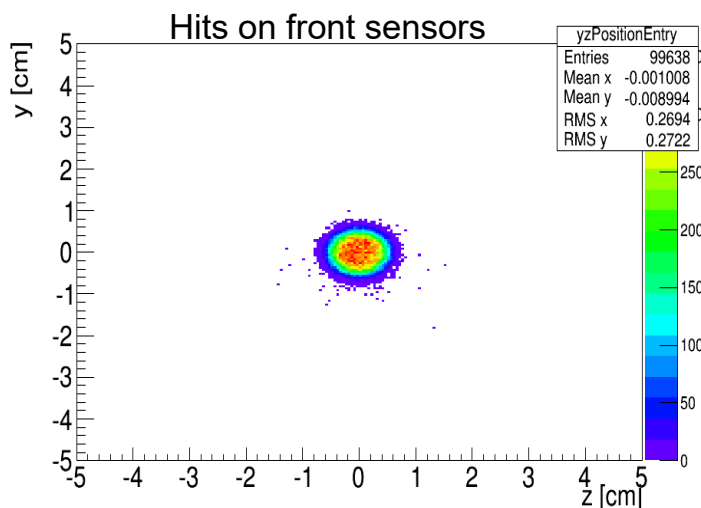
# Silicon telescope – Requirements

- > Simulation studies to decide on sensor characteristics and system geometry
- > Sensors with spatial resolution better than 10  $\mu\text{m}$  are needed
  - Driven mainly by the limited available space



- > Coverage area of the system (simulation)

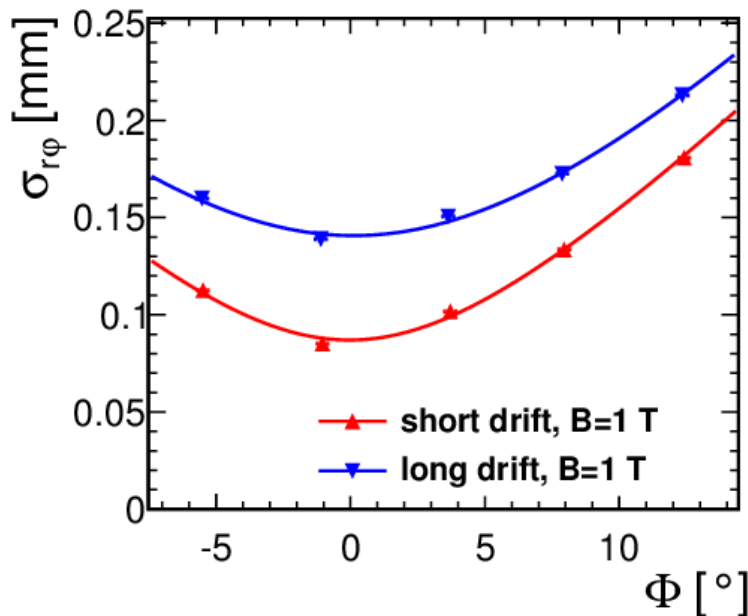
- Minimum area  $2 \times 2 \text{ cm}^2$  for the front and  $4 \times 10 \text{ cm}^2$  for the back sensors



# Resolution – $\Phi$ dependence

- For inclined tracks, a dependence of the resolution on the azimuthal angle  $\Phi$  is expected

$$\sigma_{r\phi}(\Phi) = \sqrt{\sigma_{0r\phi}^2(z) + \frac{L^2}{12\hat{N}_{\text{eff}}} \tan^2(\Phi)}$$



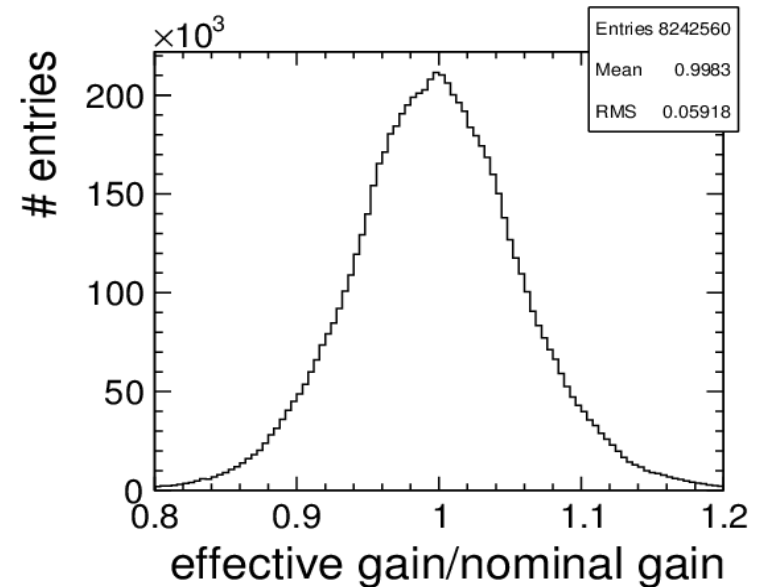
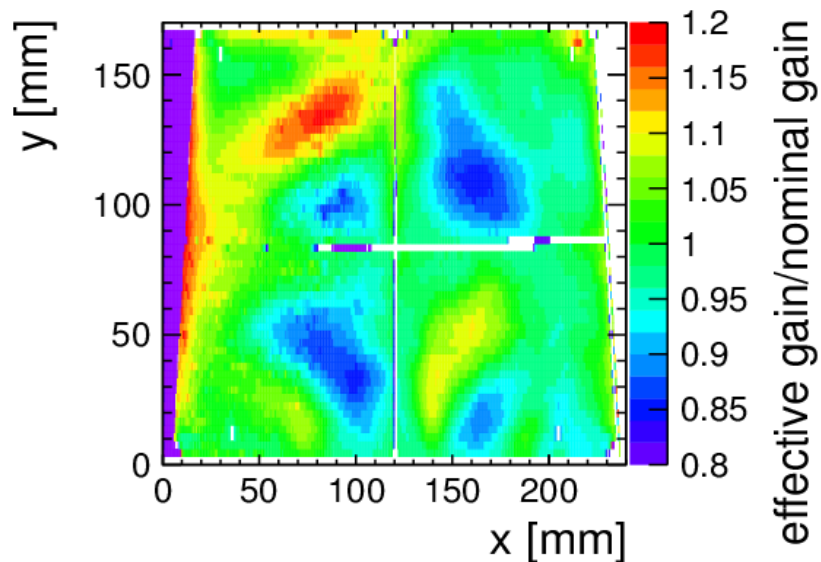
- Tracks for short (10 cm) and long (40 cm) drift distances are shown
- $\tan(\Phi)$  behaviour as expected





## GEM flatness (2)

- 3 GEM profiles used to simulate an operating GEM module
- RMS of effective/nominal gain  $\sim 6\%$



- Considering new ceramic frame design
- Developing optimised tools and procedures & reproducible mounting process