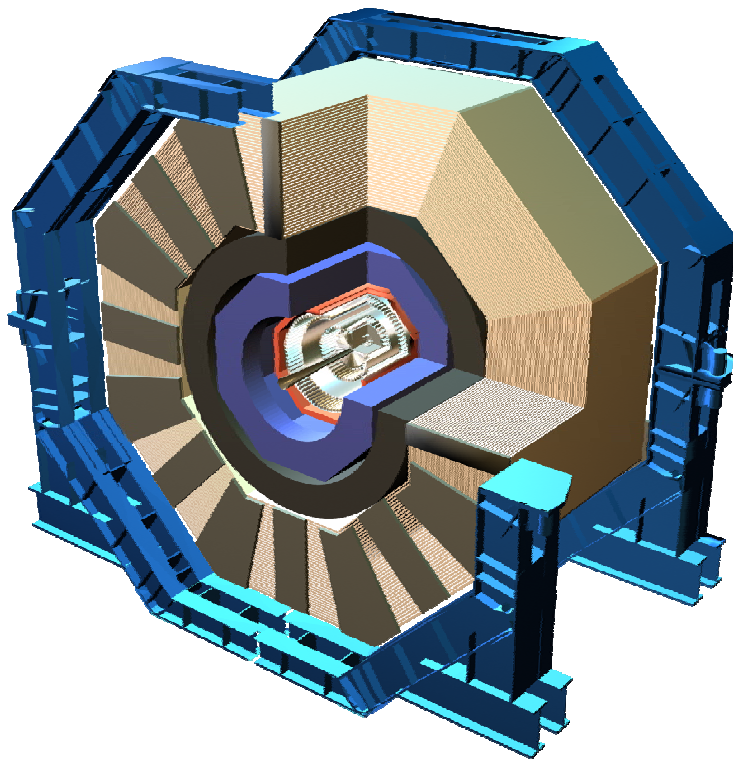
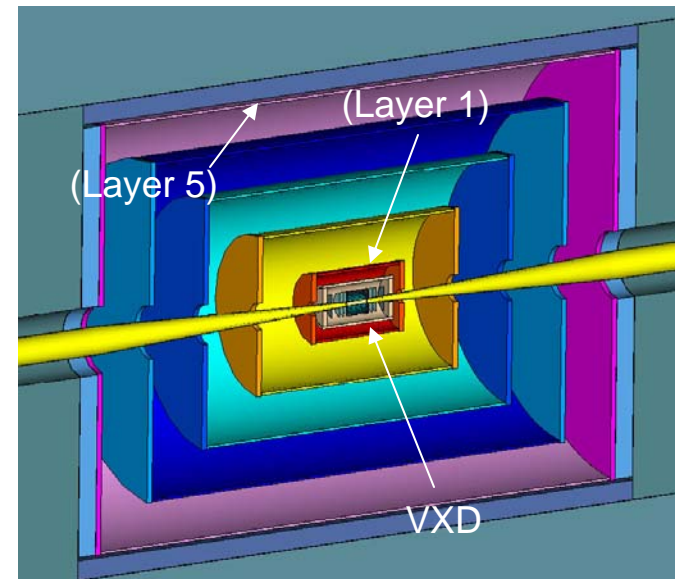




# Vertex Detector Mechanical Design: Status and Issues



Bill Cooper  
Fermilab





## Proposed VXD Barrel Changes

- Changes are proposed to address two comments made in the December SiD meeting.
  - The December geometry was too open.
  - Passing ladders through up to 4 openings could be difficult.
- The idea of gluing, rather than using fasteners, to build sub-assemblies would be retained.
  - Extensive use of fasteners appears to contribute too much material.
  - Fasteners would still be used to join sub-assemblies.
- Operation at  $T > -10^{\circ} \text{C}$  has been suggested for the design concept document.
  - A consequence is that the effects of the small CTE mismatch between silicon and carbon fiber are reduced.
  - That allows greater freedom in the ways in which CF can be used.
- VXD still clam-shells as left-right (top-bottom?) halves.



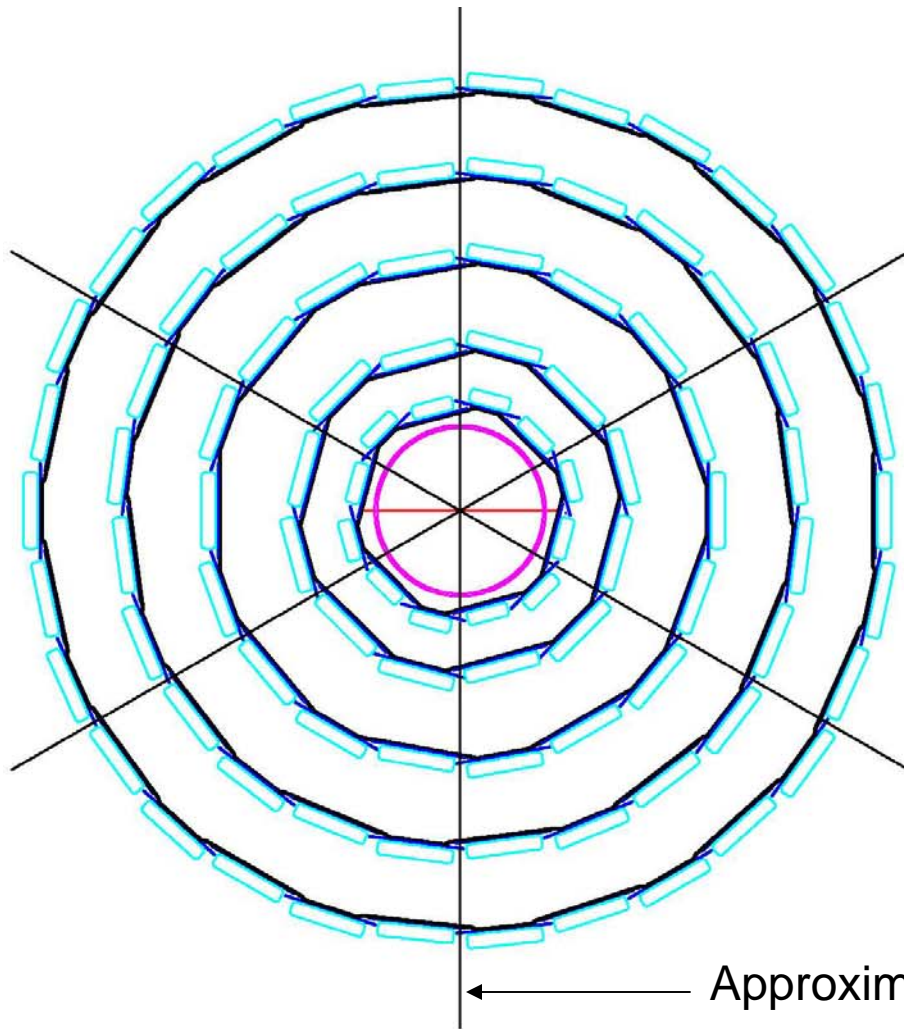
# Proposed Changes

- Build CF polygonal support cylinders which cover 180°.
  - Cylinders would be single-walled with 3 or 4 plies.
  - 180° annular rings at each end would control out-of-round.
  - Openings in those rings would be large enough to pass a cable and its connector, but not the full width of a sensor.
  - To control material (~0.11% RL for 4 plies of solid CF), openings would be cut into CF leaving lattice-work.
    - It may be feasible to remove ~75% of material.
  - Sensors would be glued to the CF with required electrical insulation / connections.
  - Up to 15 sensors would be in a cylinder sub-assembly.
- CF end membranes spanning all cylinder radii would form the set of 5 (6?) cylinders into a 180° half-barrel.
  - ~3 fasteners at each end of a cylinder
  - End membranes would have openings to reduce material and provide cable and cooling gas passages.



## End View

- 2 types of sensors —> some adjustments to radii.

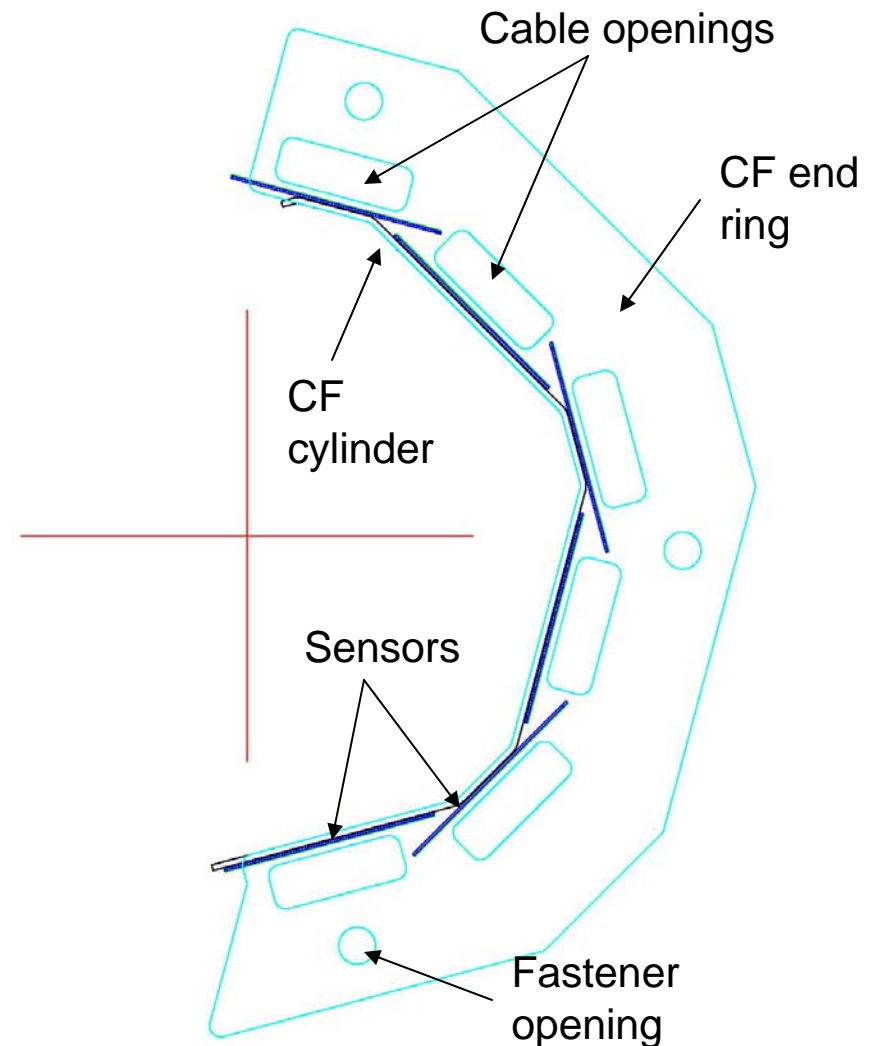


Sensors:  
IR\_A = 14, 22, 35, 47.6, 60 mm  
IR\_B = 15.154, 23.132, 35.890, 48.409, 60.770 mm  
Active widths: 8.549, 13.3 mm  
Cut widths: 10.149, 13.8 mm  
Beam pipe IR: 12 mm  
Beam pipe OR: 12.4 mm  
January 18, 2006

← Approximate clam-shell split line

# Comments

- All sensors are on the outer surface of CF.
- A & B layer 1 geometry is shown.
  - Spiral geometry will be checked, also.
- A & B layers have been placed leaving 0.5 mm gaps between sensors.
- Other openings would be added in end rings, but their geometry has not been calculated yet.
  - Reduce mass
  - Allow air flow



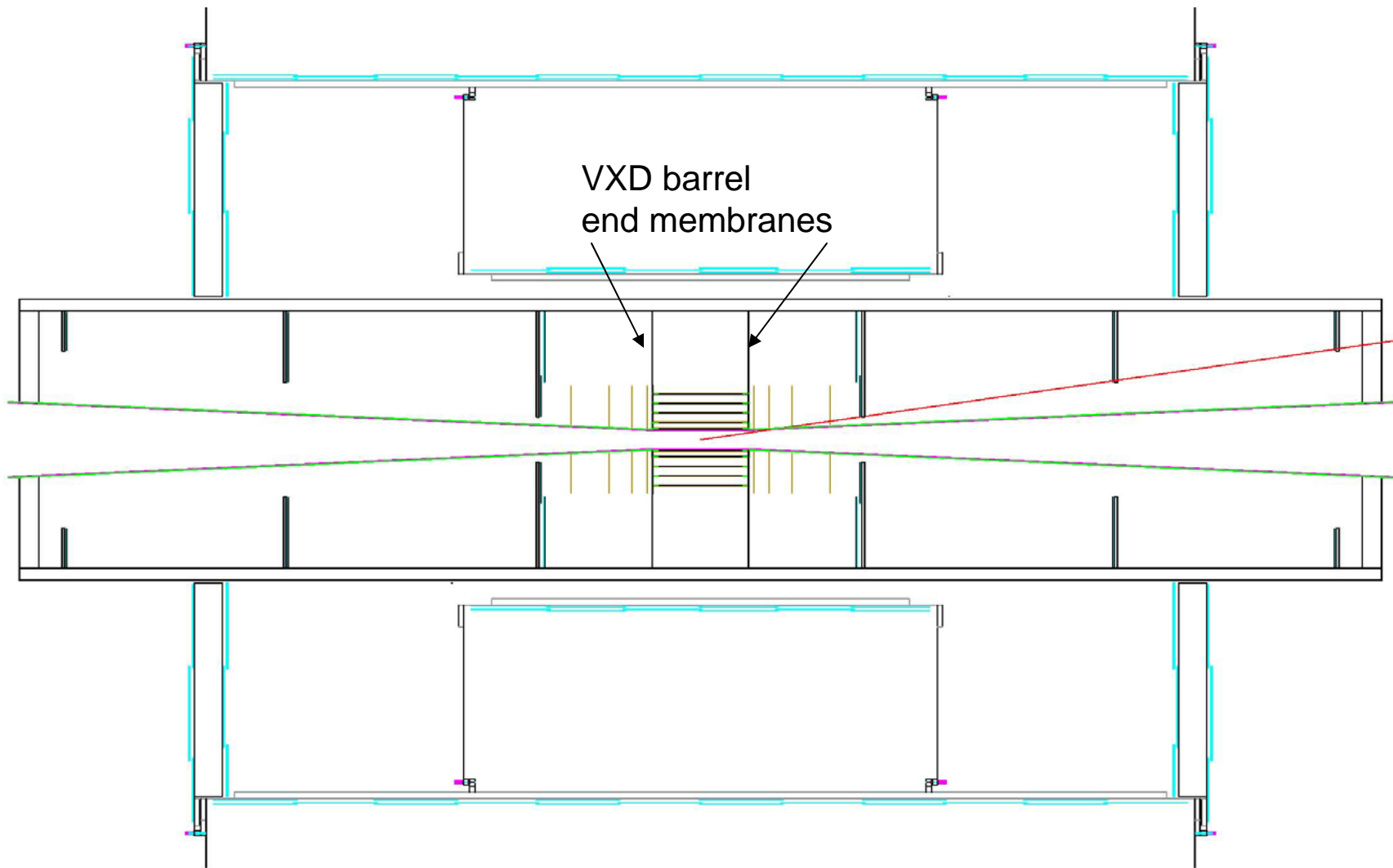


# Features

- CF cylinders address beam-like deflection, so sensor assemblies can be thinner.
  - For sensors which are adjacent in phi, that allows the delta R between the edge of one sensor and the surface of the next to be decreased (improves hermeticity).
  - Sensor – sensor gap is drawn as 0.5 mm.
- End rings would be glued to a cylinder while the cylinder is still on a support mandrel.
- We need to optimize the geometry of material which remains after openings have been cut.
  - The U. of Washington will begin FEA to do that.

# Elevation View

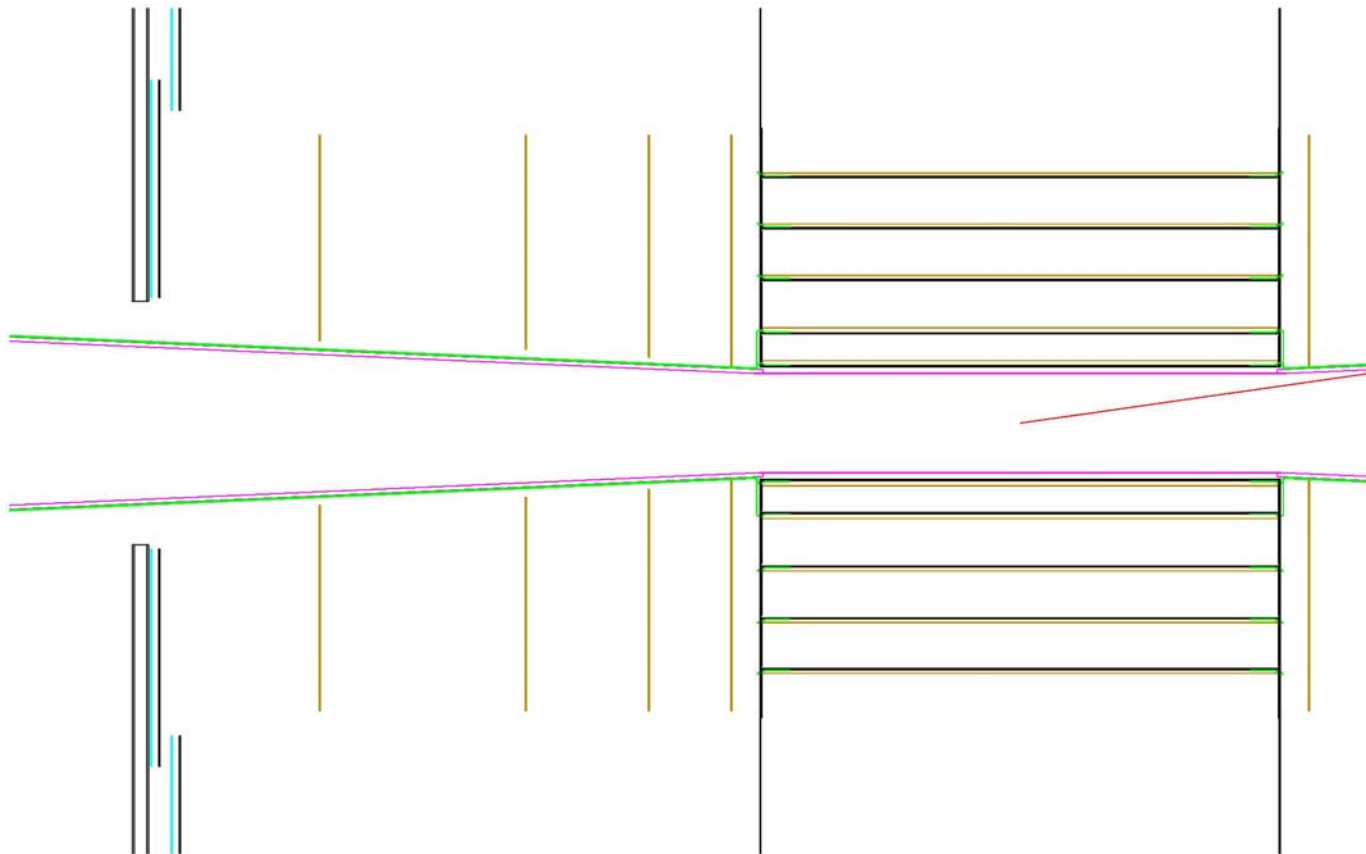
- Barrel sensors are drawn 125 mm long.





## Elevation View

- Longer barrels begin hitting beam pipe and VXD disks.
- Disks may move outward in Z to increase lever arm.
- Outer radii would be adjusted to maintain coverage.

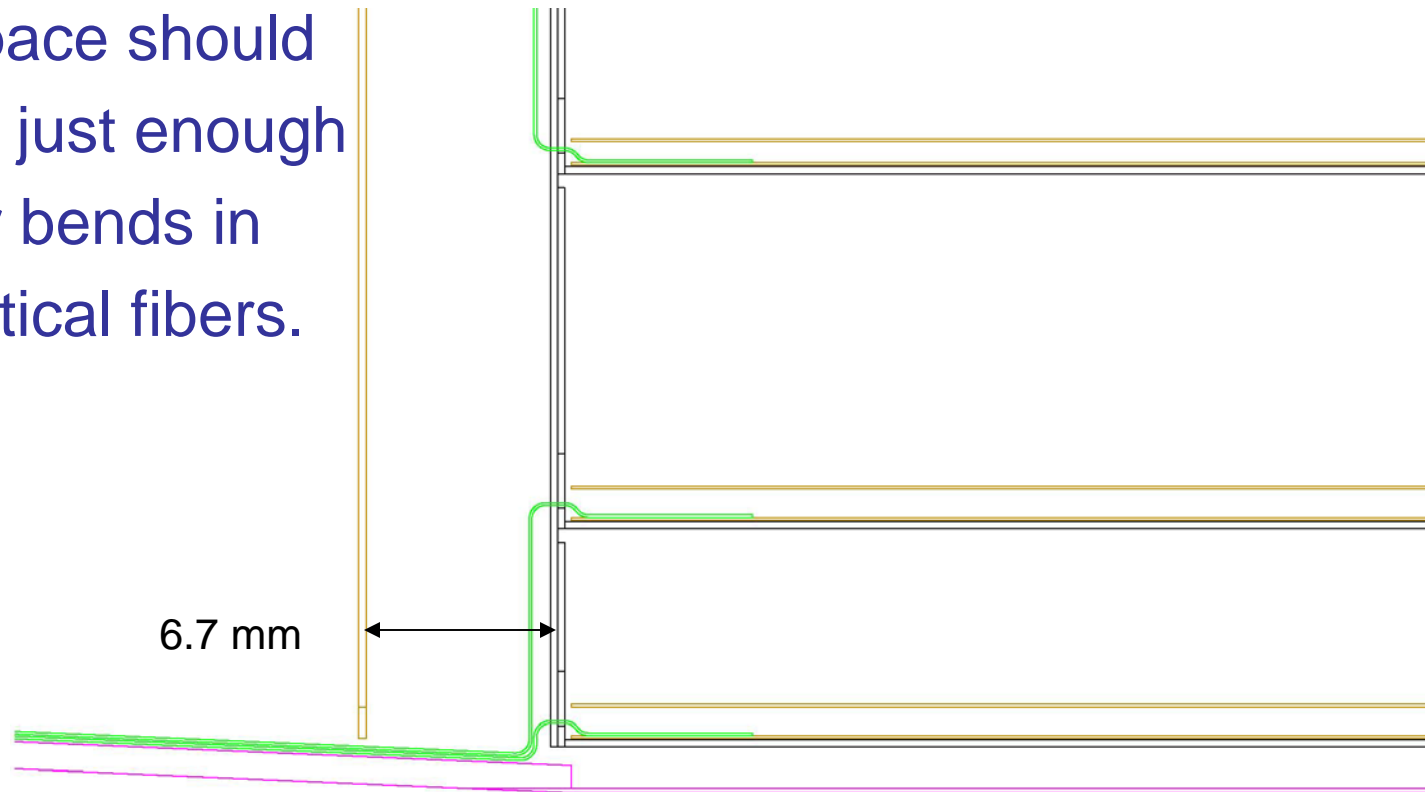






## Elevation View

- Only A-layer CF and cables are shown.
- Cables for layers 3 - 5 (& maybe 2) are thought to run outward.
- Space should be just enough for bends in optical fibers.





## Questions

- 6 mm x 2 mm openings for cables are shown in layer 1, and 11 mm x 2 mm in other layers.
  - Can opening sizes be reduced or are they already too small?
- A border of 0.25 mm has been drawn between active region and cut edge of each sensor.
  - Can that be reduced, or is it already too small?
- As noted, no extra length is presently drawn for readout.
  - Is that acceptable?
- How much power?
  - Total (could be difficult if > 20 watts)
  - Per location
  - Per unit area



# Disks

- A similar design philosophy is assumed, that is, sensors glued to 3 or 4 plies of a CF.
  - Openings would be cut to reduce CF material by a factor of  $\sim 1/4$ .
  - To provide overlap, sensors of a half-disk would be at 4 Z-locations.
  - Sensors at a given Z would all be attached to an individual CF membrane, so 4 membranes for a half-disk assembly.
  - Material left after openings are created would be non-aligned to the extent practical from one membrane to the next.
- The assumption is that disk readout connections would originate near the outer edge.
- What are the limitations (if any) on the shape of the active area of a disk sensor?
  - Can true wedges be made?
- Questions for barrels apply to disks.



# Back-up Slides Follow



## VXD Barrel Material

	SLD VXD3	SiD VXD
Beampipe liner	Ti 50 $\mu$ m 0.14%	Ti 25 $\mu$ m 0.07%
Beampipe	Be 760 $\mu$ m 0.22%	Be 400 $\mu$ m <b>0.07%</b>
Inner gas shell	Be 560 $\mu$ m 0.16%	(Note 1) 0
Ladder/layer	0.41%	<b>0.11%</b>
Outer gas shell	Be mesh 0.48%	0.28%
Cold N2 Gas	0.05%	0.05%
Cryostat coating	Al 500 $\mu$ m 0.58%	<b>0.22%</b>
Cryostat foam	Urethane 0.44%	NilFlam <b>0.12%</b>

Su Dong

**Note 1) Cooling gas can be brought in from two ends**

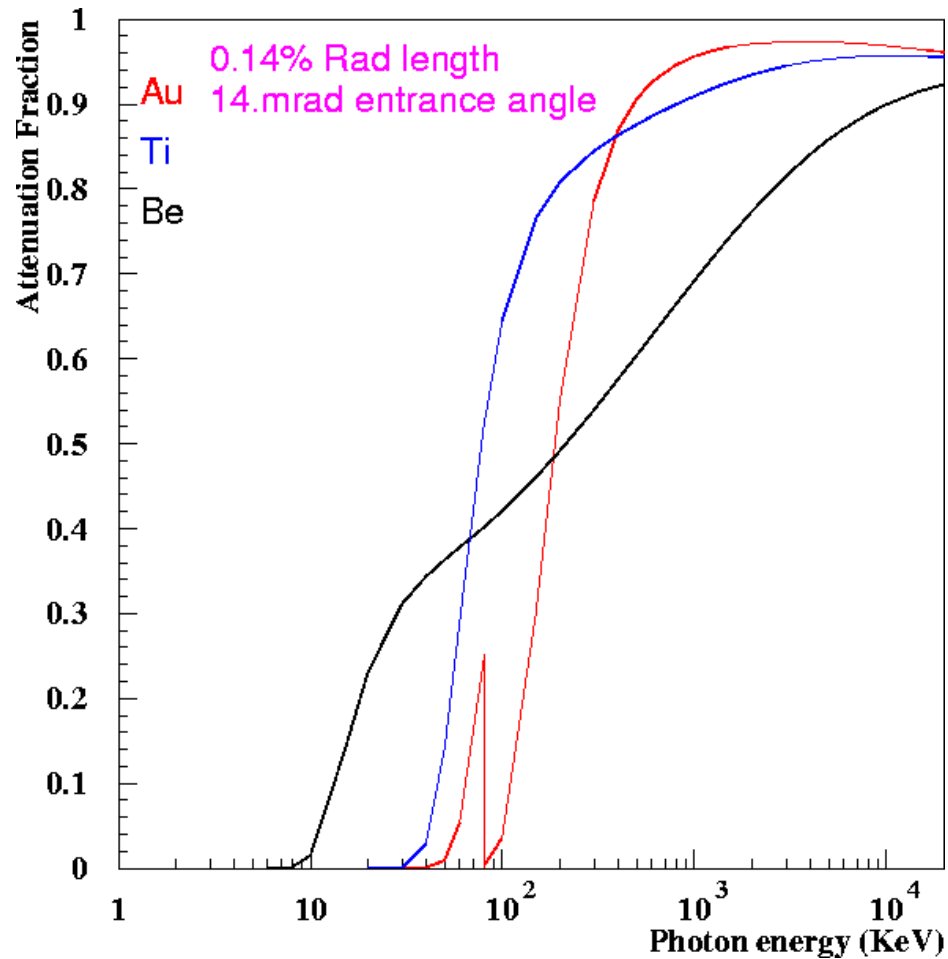


## Endcap Region Material

	SLD VXD3		SiD VXD
Barrel Endplate	Be/Fe/gap 3mm	1.5%	Composite ? 0.5%
Barrel support annulus	Be	~2.4%	1.0% ?
Ladder blocks	Al <sub>2</sub> O <sub>3</sub> (smeared)	3.0%	1.0% ?
Striplines	Kapton/Cu (face on)	0.5%	0.2%
Stripline clamp support	Be plate with holes	~1.0%	0
Stripline connectors	Hit it 0.4%; smear	0.14%	0
Cryostat	Foam	0.4%	0.4%

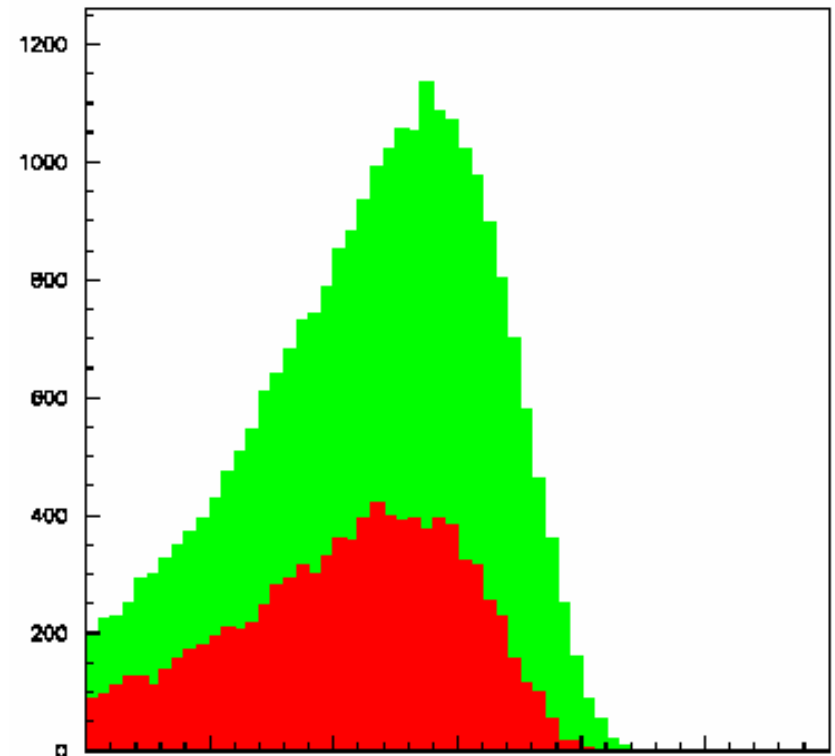
- What to replace the sliding blocks ?
- Readout can be replaced by optical system similar to ATLAS (T>-10C)  
with a very small transceiver and very thin fibers.
- Still needs power strips
- No need of clamp and connectors in active fiducial volume.

## Beampipe Liner



## Direct synchrotron

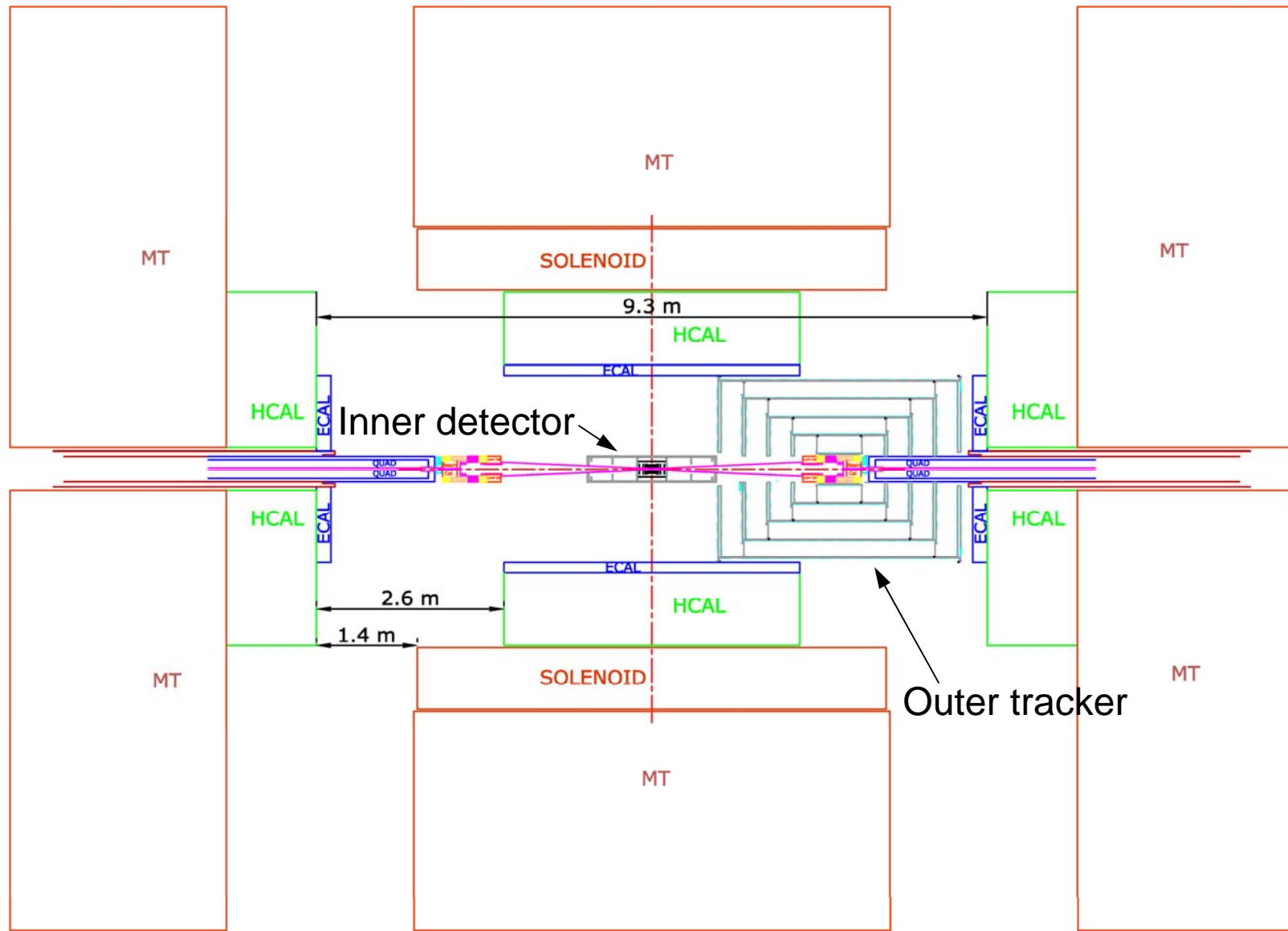
(backscatter spectrum to be calculated)



From Takashi Maruyama

**Liners help taking out low energy synchrotrons, but is the attenuation adequate for high energy synchrotrons ?**

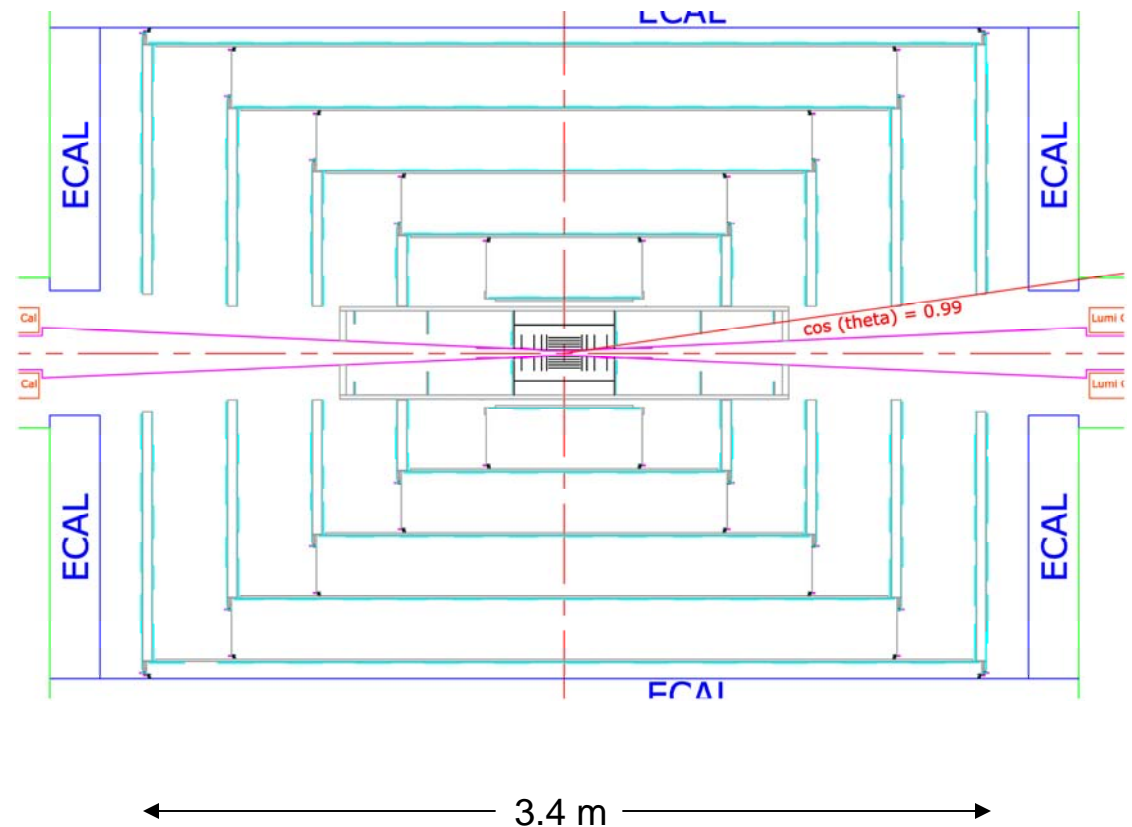
# SiD Detector Open with Full Access to Inner Detector





# Silicon Tracking Layout

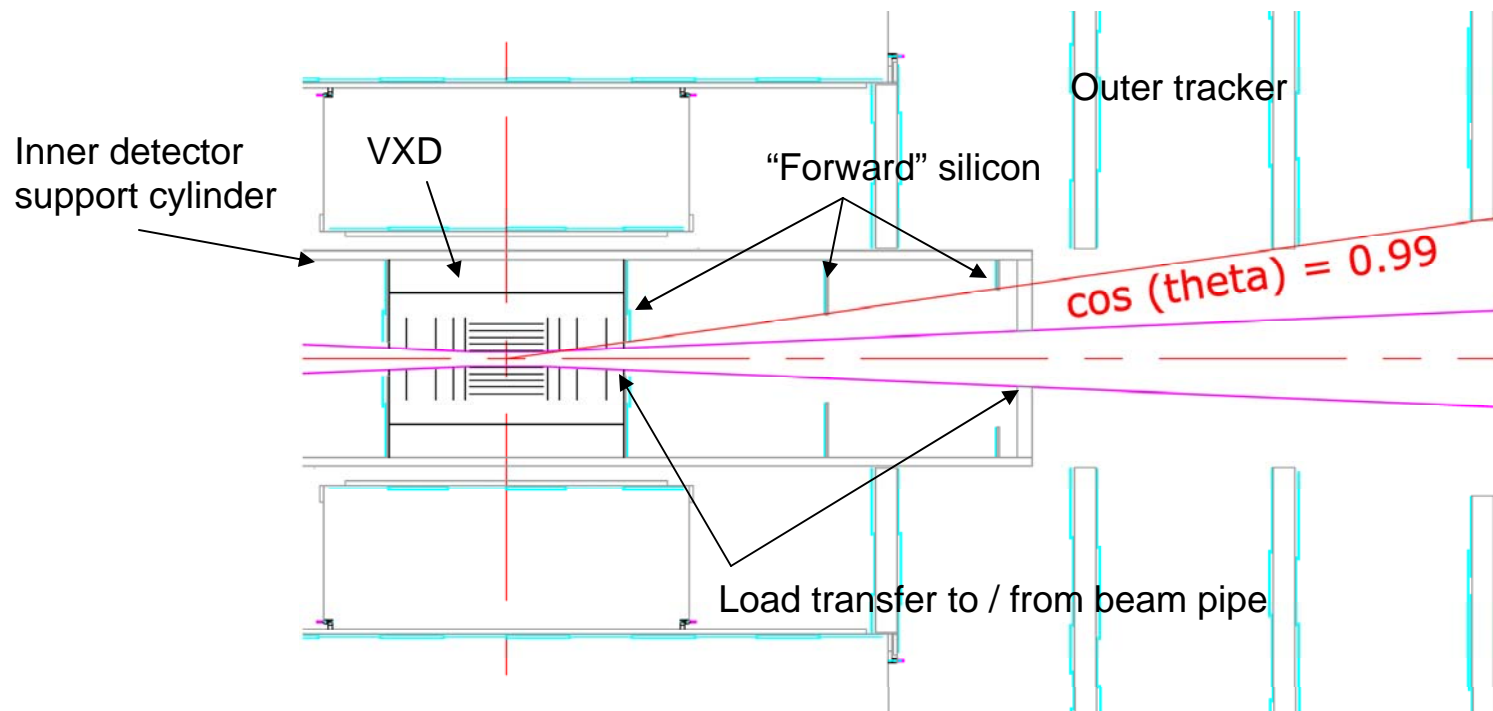
- Outer tracker (microstrips)
  - 5 barrel layers
  - 5 disks per end
  - OR = 1.25 m
  - IR = 0.2 m
    - May need to adjust inner radius to match beam-line elements
  - Supported from ECAL
- Inner detector (pixels)
  - VXD
    - 5 barrel layers (may increase to 6)
    - 4 disks per end
  - Additional “forward” disks
  - Supported from conical portions of beam pipe





# Concept of Inner Detector (VXD) Support

- To allow installation on the beam pipe, the inner detector and its support structures are based upon half-cylinders.
- Outer support half-cylinders could be thermally insulating
  - Detector elements are supported from those half-cylinders.
- Support half-disks couple to the beam pipe at approximately  $Z = \pm 0.2$  m and  $Z = \pm 0.9$  m and aid in maintaining beam pipe straightness.
- To reduce material, many of the support structures could be lattice-like.





## VXD Barrel Concepts (1)

- Ladders are designed taking into account support from two or four CF membranes.
  - Thickness of each membrane ~ 0.26 to 0.39 mm (0.11% to 0.16% of a radiation length for membranes with no holes).
- Ladders pass through openings in the membranes.
  - 1.8 mm of material is retained at nearest membrane openings.
  - We know that is sufficient to allow membrane fabrication.
- Flexibility of the membranes is tuned to provide good x and y positioning and to allow a difference between ladder thermal contraction and thermal contraction of an outer support cylinder.
  - CF thickness and geometry of openings determine flexibility.
  - Between the outermost ladders and the inner surface of that support cylinder, membranes can be mostly holes.



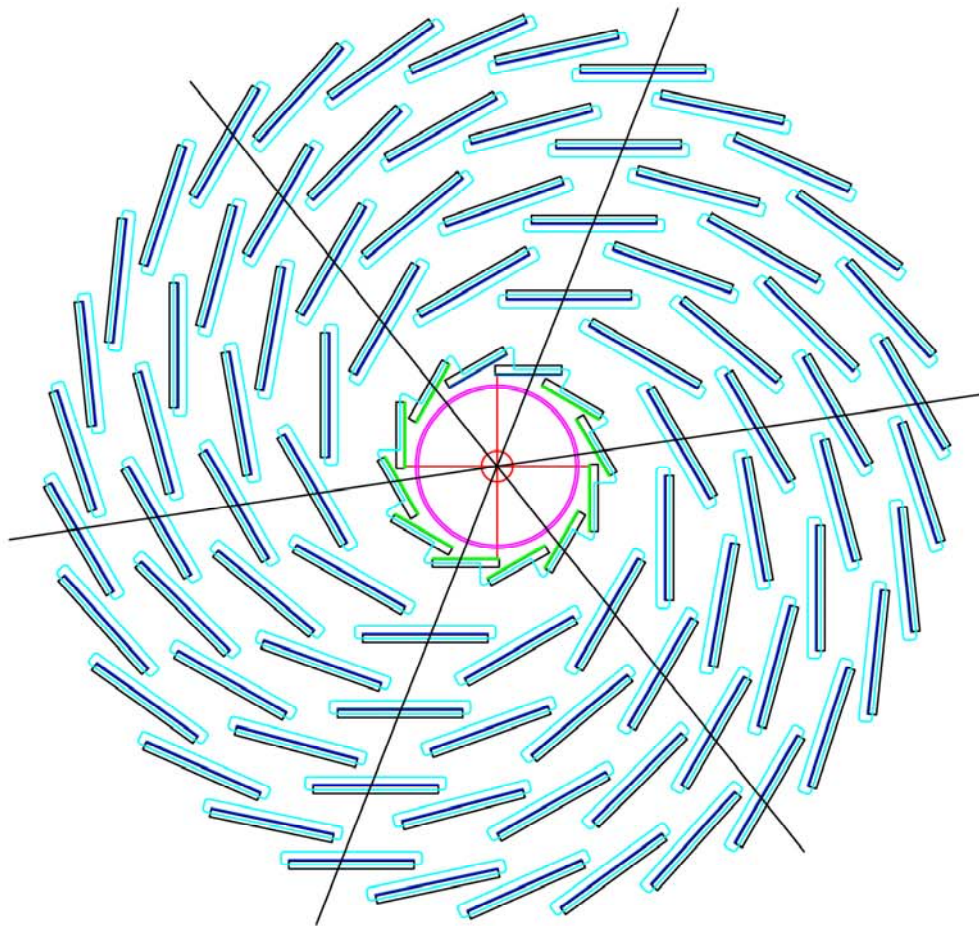
## VXD Barrel Concepts (2)

- There are clear advantages in being able to remove ladders from a completed barrel, but:
  - Pin a socket or equivalent connections are likely to be needed.
    - They do not appear to be needed to accommodate thermal contraction.
    - They add significant material.
- An alternative which reduces material would be to glue ladders into place.
  - For that option, a barrel could be divided in phi into six mating pieces.
    - Must split into two halves in any case to allow assembly on beam pipe.
  - For the geometry drawn, each piece would include 16 ladders
    - D0 has recently assembled a L0 silicon detector with 48 sensors glued into place. ~0.025% channels damaged during assembly



## Dec. 2005 End View of the VXD Barrel Array

- Ladders with inward facing sensors are shown.
- Sensors could equally well face outward.
- Note that 6-fold symmetry is shown.



### Sensors:

IR = 14, 25.5, 37, 48.5, 60 mm

Active widths: 8.549, 17.443 mm

Cut widths: 10.149, 19.043 mm

Tilt angles: 18.8, 23.2, 21.7, 20.9, 20.3 degrees

Beam pipe IR: 12 mm

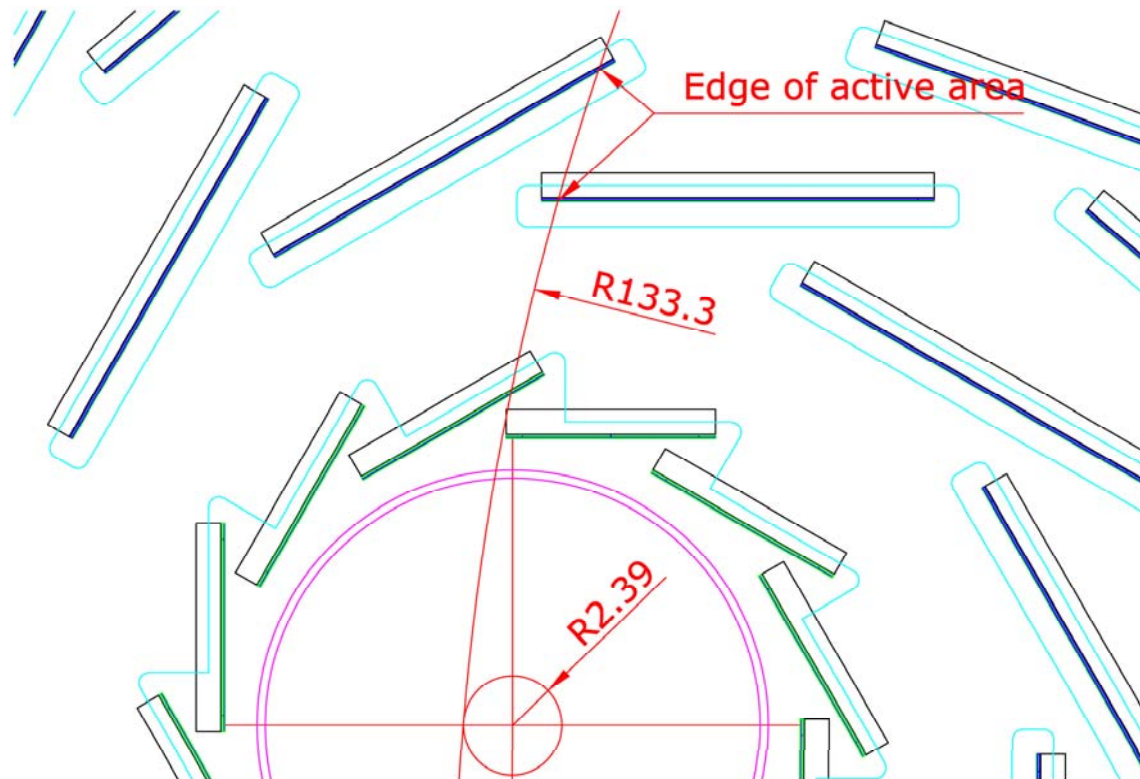
Beam pipe OR: 12.4 mm

December 7, 2005



## Example of Sensor Overlap

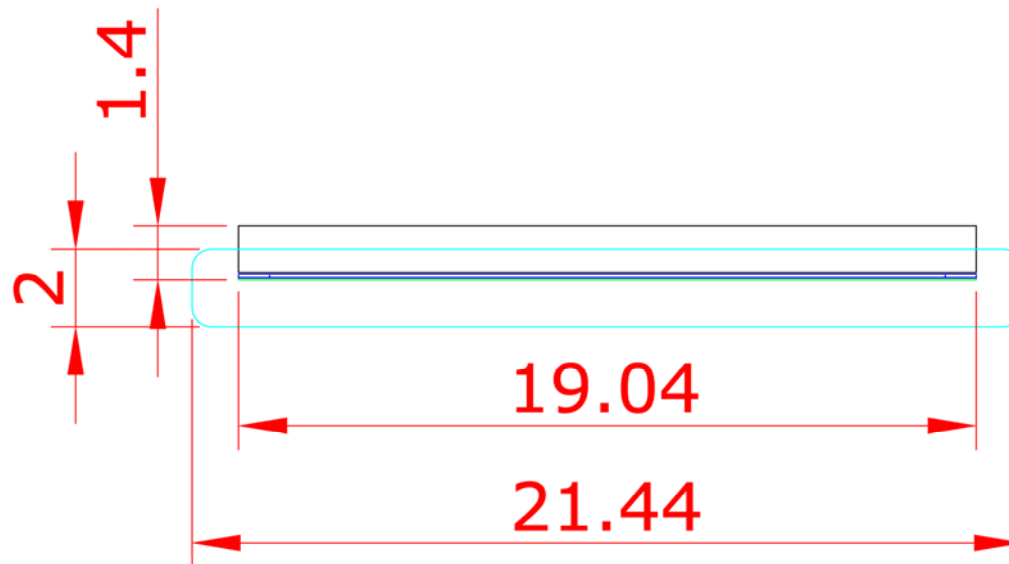
- Considerations:
  - Pt below which a trajectory can pass between sensor active areas (0.2 GeV/c shown for  $B = 5$  T)
  - Closest approach of trajectory to  $x = y = 0$  (2.388 mm shown)





## Basic Ladder Dimensions

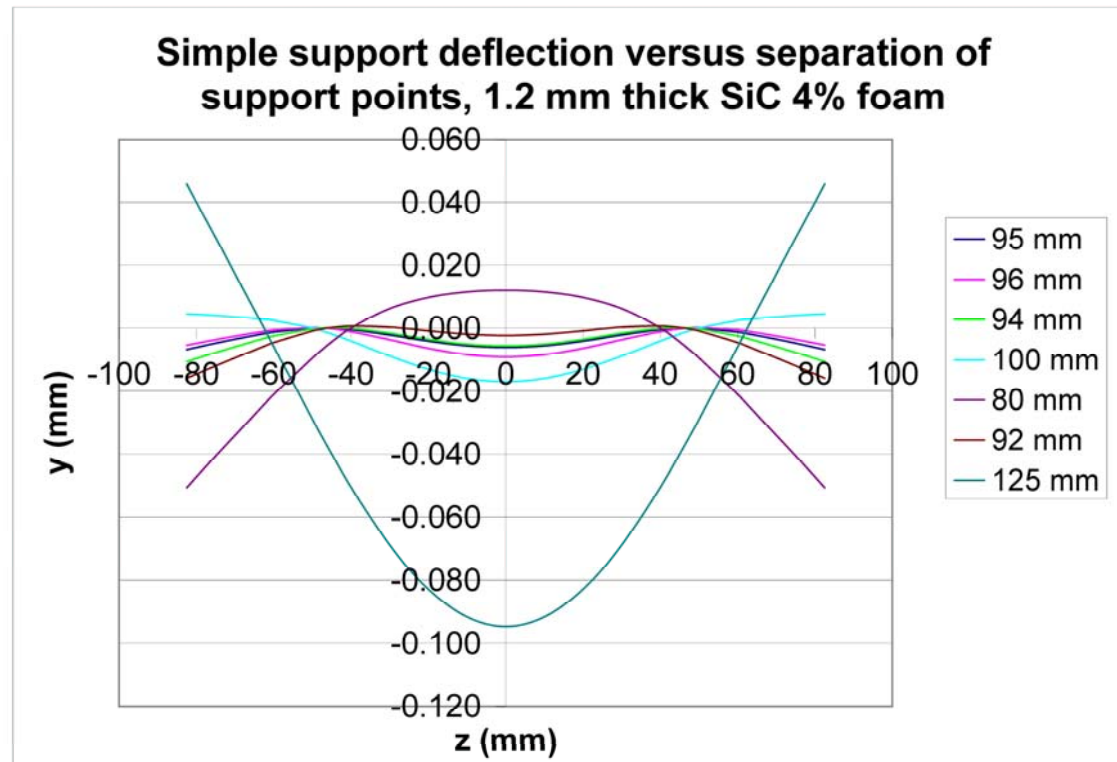
- 0.1 mm thick x 125 mm long sensors
- 0.15 mm thick x 20 mm long readout regions
- 0.05 mm glue thickness
- 1.2 mm thick x 165 mm long foam (SiC foam presently assumed)
- Ladder and membrane opening dimensions are shown below





## Deflections under Gravity (1)

- Assumes simple support of ladder by two membranes
- Deflection OK with support points moved inward
- Forces from cables are an issue which could argue for four, rather than two, membranes.







## Deflections under Gravity (2)

- Assumes support of ladder by four membranes
  - Inserting through holes would require good fixturing.
- Deflections are forced to 0 at the support points.
- Inner membranes would be floated from ladders.
  - Only the outer membranes would tie to an outer support cylinder.

