



Engineering studies on calorimeter structures

A status

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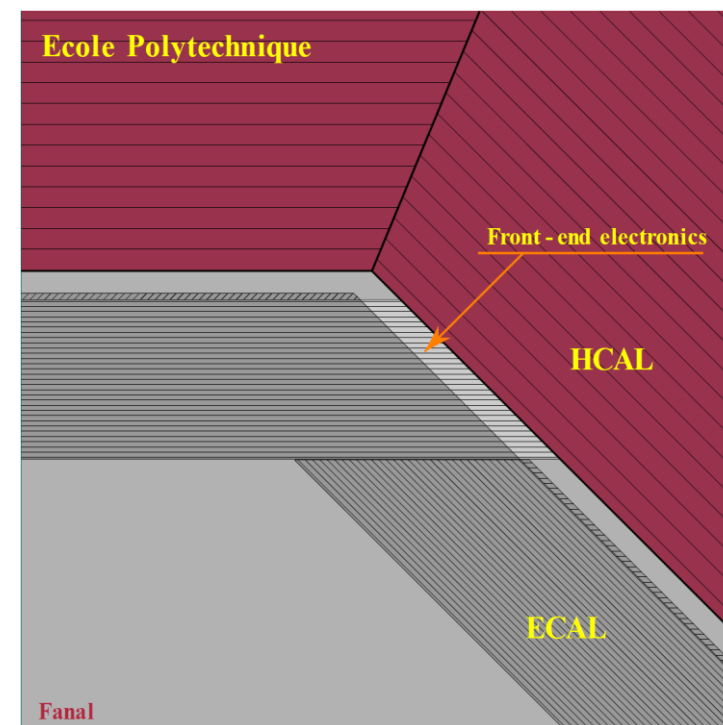


There exist two technologies proposed for the HCal, the scintillators and the RPC's.

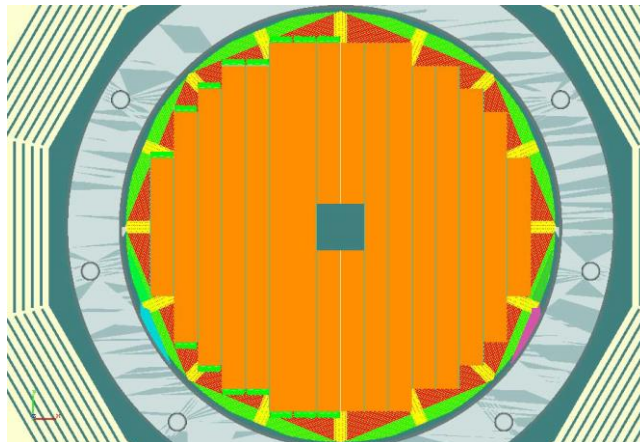
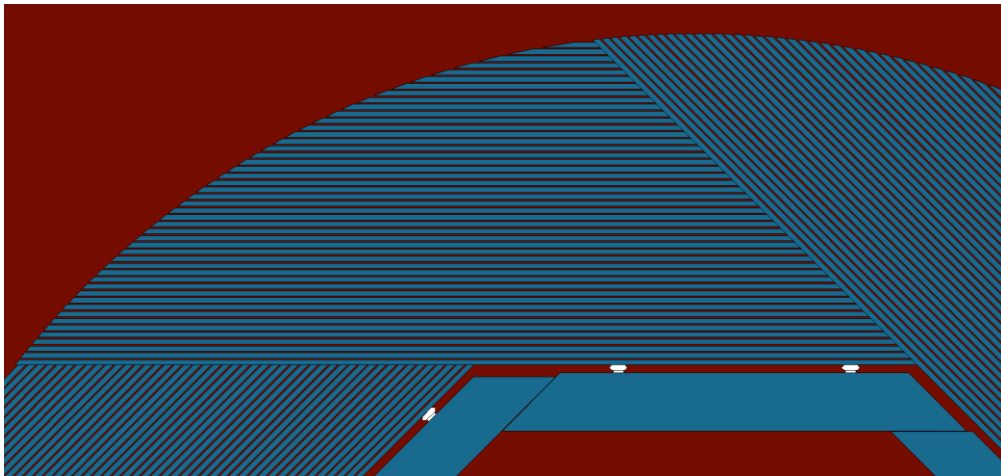
They have developed using different mechanical designs referred to as Tesla (this design was invented for the Tesla project 2000) and Videau (because one day your "serviteur" proposed it) but there are no strong correlations between sensors technology and mechanics.

This is true for barrel and for end caps in a totally independent way.

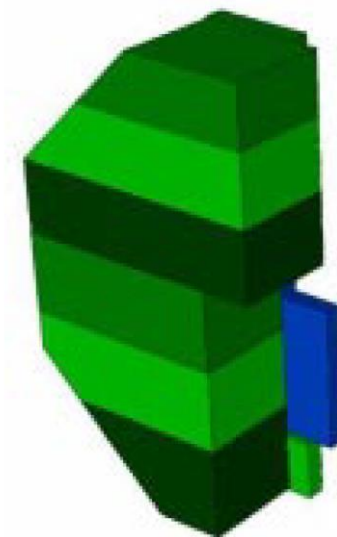
Notice that, following the eightfold way, the Ecal barrel existed with its actual structure chosen only to get signals and services out directly in the back of the Ecal in the gap left between Ecal and Hcal



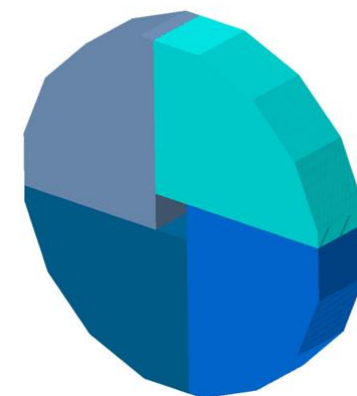
TESLA TDR



DBD



TESLA TDR



Icd sDHCaI

A sketchy history of the two designs for barrel and end caps according to me:

For the barrel the TESLA model gets back to the beginning of the TESLA project (TDR in 2000)

At a time, long ago, it was considered to get fibres from the calorimeter out of the yoke.

The model V was introduced much later to follow the same idea as the Ecal and get the services out in the back of the Hcal, in front of the coil.

For the end caps the earlier solution was “à la V”, made of four quadrants for an easy fastening to an FSP likely to bulge slightly when the field is turned on.

The T structure was proposed by Karsten Gadow later (DBD) for the simplicity of the fastening I guess.



The question



If really there is no strong correlation between technology and mechanical structure

why not solve first the mechanical structure choice which should be easier, and this independently for barrel and endcaps?

Answer:

Create a TV task force

DONE

The first approach was to look at the structure from a mechanical point of view: what is more stable against static load, under earthquake conditions? Is any structure better for its partners like Ecal or services?

Then we can also discuss cracks, cooling etc.

Only the first point has started to be looked at.

Here is the status.



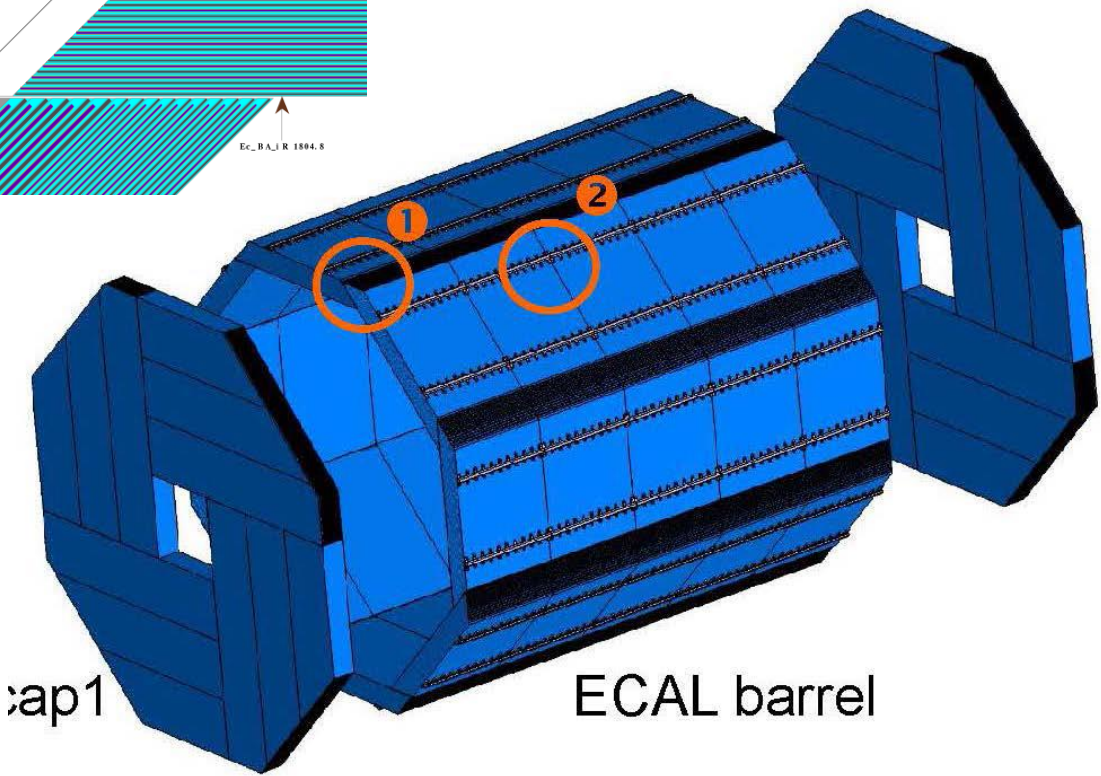
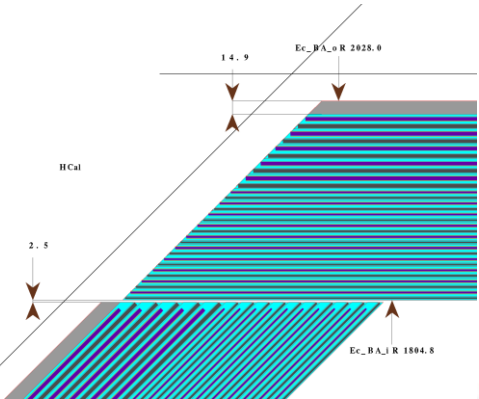
The ongoing study concerns the barrel and its way to behave under weight and earthquakes.

I take back the slides Claude had presented to summarise the status



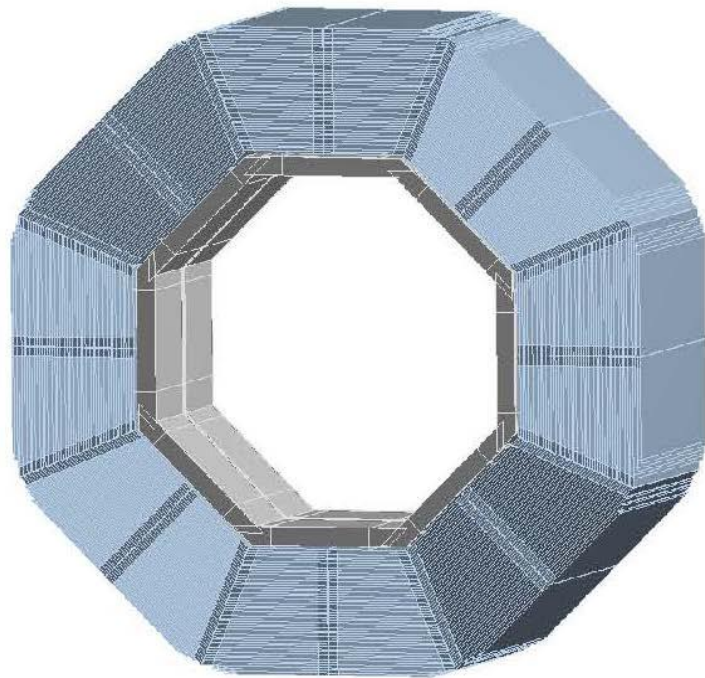
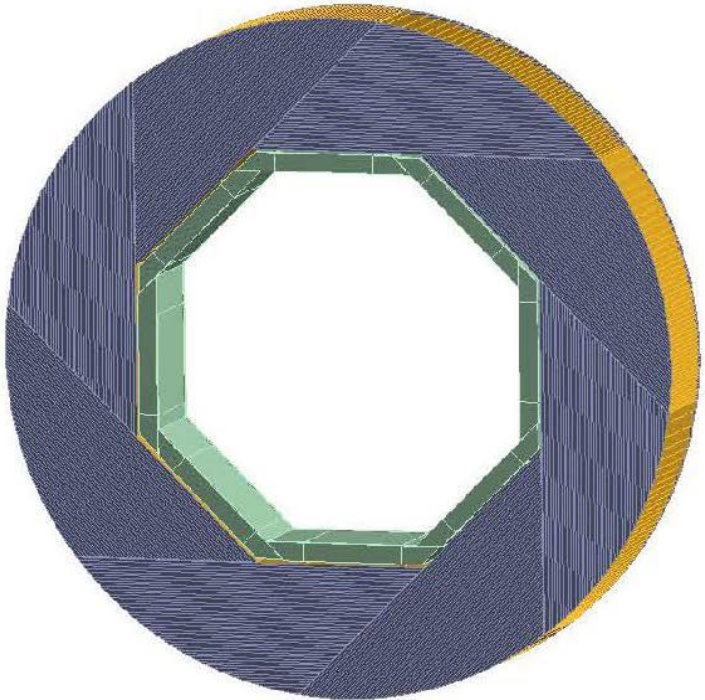
GLOBAL DESIGN: calorimeter mechanical simulations (LLR)

Address issue of tolerances at ECAL boundaries



cap1

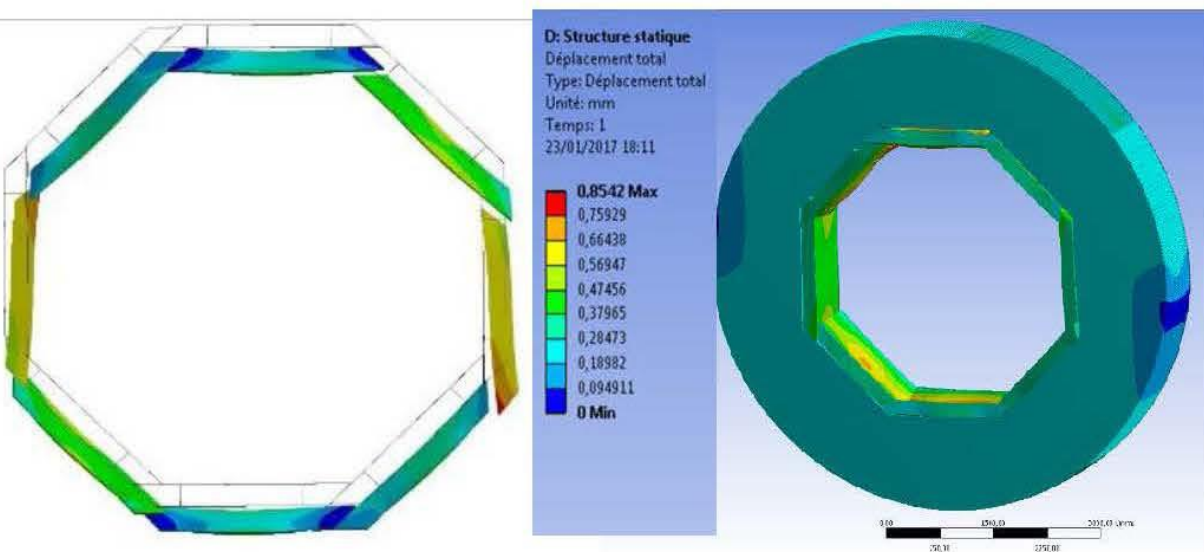
ECAL barrel



VIDEAU

TESLA

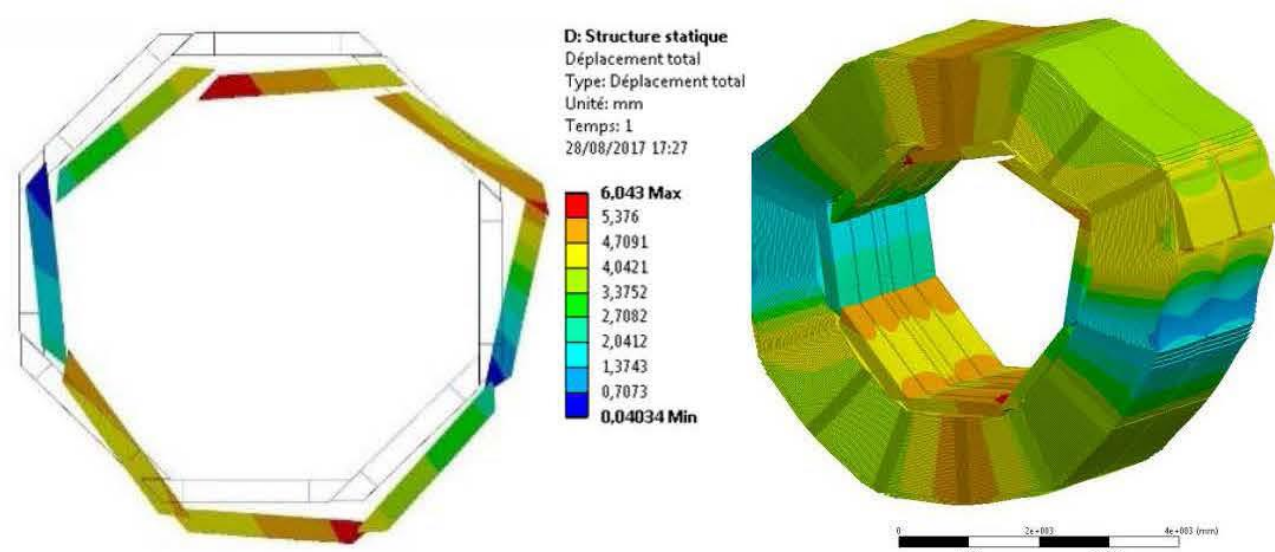
*NB: old model
Not
corresponding to
the actual (DBD)
dimensions,
The Ecal has then
been
adapted by LLR
for these
computations*



VIDEAU model :

For a nominal gap of 2.5mm

Total displacement **0,9 mm**
Smallest gap between ECAL
modules in phi : **2,31mm**



Roman TESLA model :

Total displacement **6 mm**
Smallest gap between ECAL
modules in phi : **0,95 mm**

Both models within specifications *VIDEAU more rigid, allows for tighter stack adjustment*

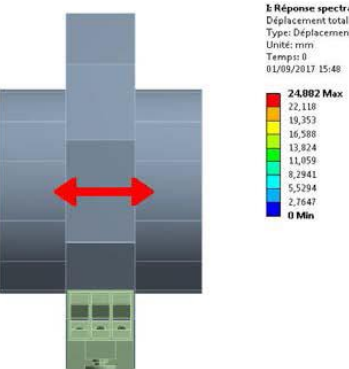
The smallest gap is the clearance left for sliding in the staves.



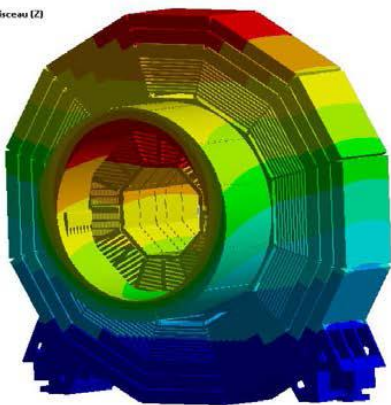
COMPONENT INTERFACES: dynamic simulation of TESLA
option (LLR)



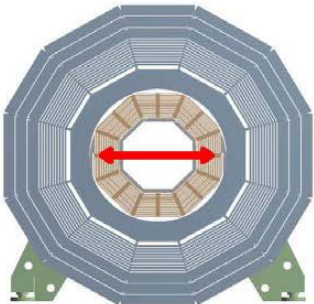
Since V is more rigid



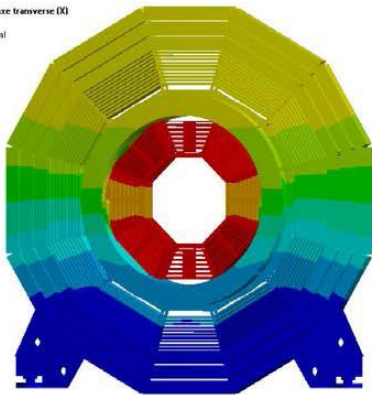
Réponse spectrale axe faisceau (Z)
Déplacement total
Type: Déplacement total
Unité: mm
Temps: 0
01/09/2017 15:48
24,082 Max
22,118
19,353
16,588
13,824
11,059
8,2941
5,5294
2,7647
0 Min



Maximum displacement:
24,9 mm
Smallest gap between ECAL
rings along z: **0,98 mm**
Smallest gap between ECAL
module along phi: **2,29mm**



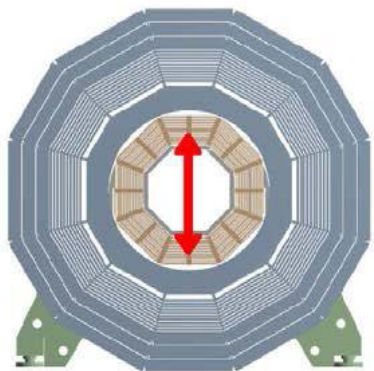
Réponse spectrale axe transverse (X)
Déplacement total
Type: Déplacement total
Unité: mm
Temps: 0
04/09/2017 10:31
17,25 Max
15,333
13,416
11,5
9,5931
7,6665
5,7499
3,8333
1,9166
0 Min



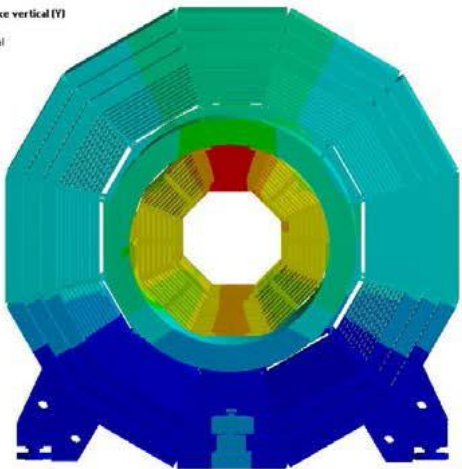
Maximum displacement:
17,3 mm
Smallest gap between ECAL
rings along z: **0,98 mm**
Smallest gap between ECAL
module along phi: **1,89mm**

Along the axis -> TPC -> ISS!!!

Horizontal transverse



Réponse spectrale axe vertical (Y)
Déplacement total
Type: Déplacement total
Unité: mm
Temps: 0
07/09/2017 14:18
2,8399 Max
2,5344
2,2088
1,8933
1,5777
1,2622
0,94664
0,6311
0,31555
0 Min



Maximum displacement:
2,9 mm
Smallest gap between ECAL
rings along z: **0,98 mm**
Smallest gap between ECAL
module along phi: **2,05 mm**

Input: spectrum provided by Tauchi-san

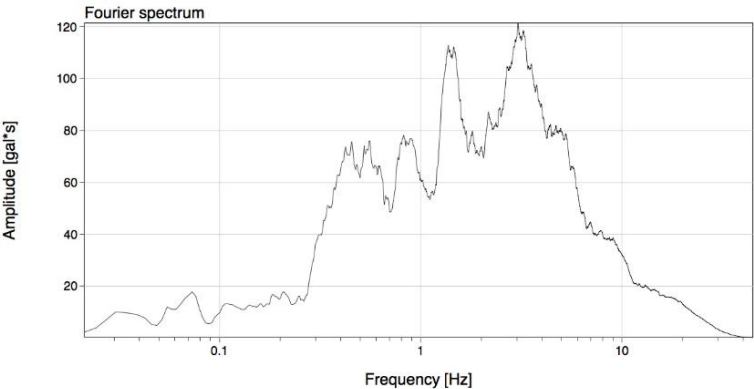
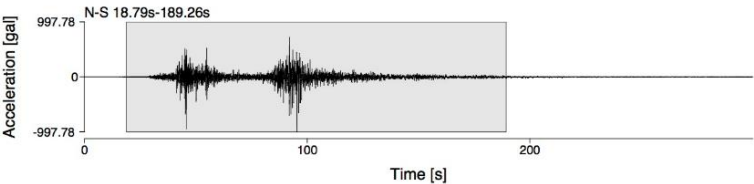
Overall ILD reacts as a ~stiff block
But breakable
to dynamical stimulations ??



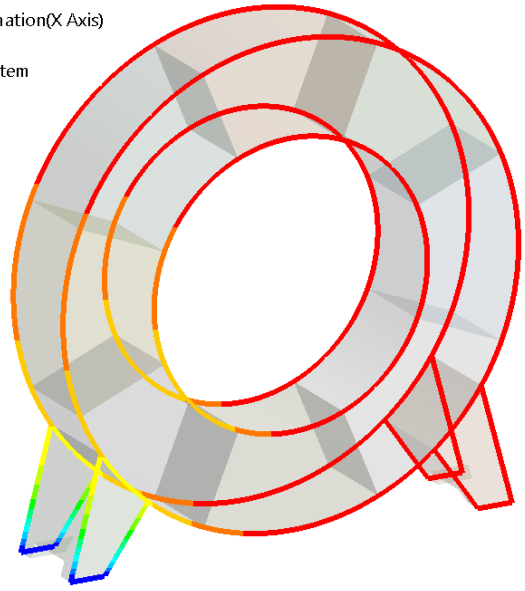
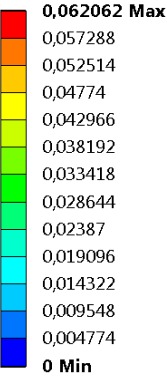
Fast simulation method “Component Mode Synthesis”
validated on simplified wheel model with real earthquakes

*Updated TESLA model needed from DESY to allow
cross-comparison and check of both static and dynamic
simulations between DESY and LLR*

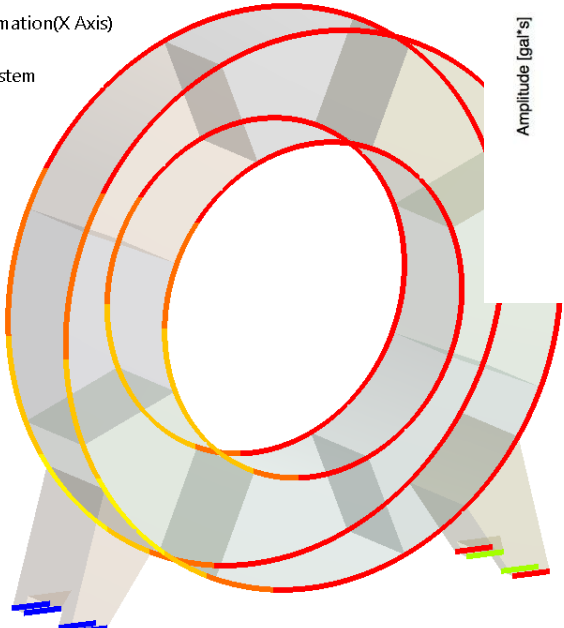
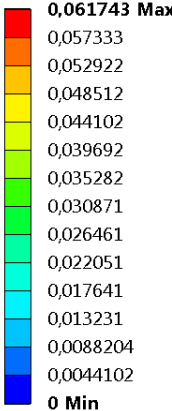
IWT010 2011/03/11 14:46:37



H: Response Spectrum
Figure
Type: Directional Deformation(X Axis)
Unit: mm
Solution Coordinate System
Time: 0

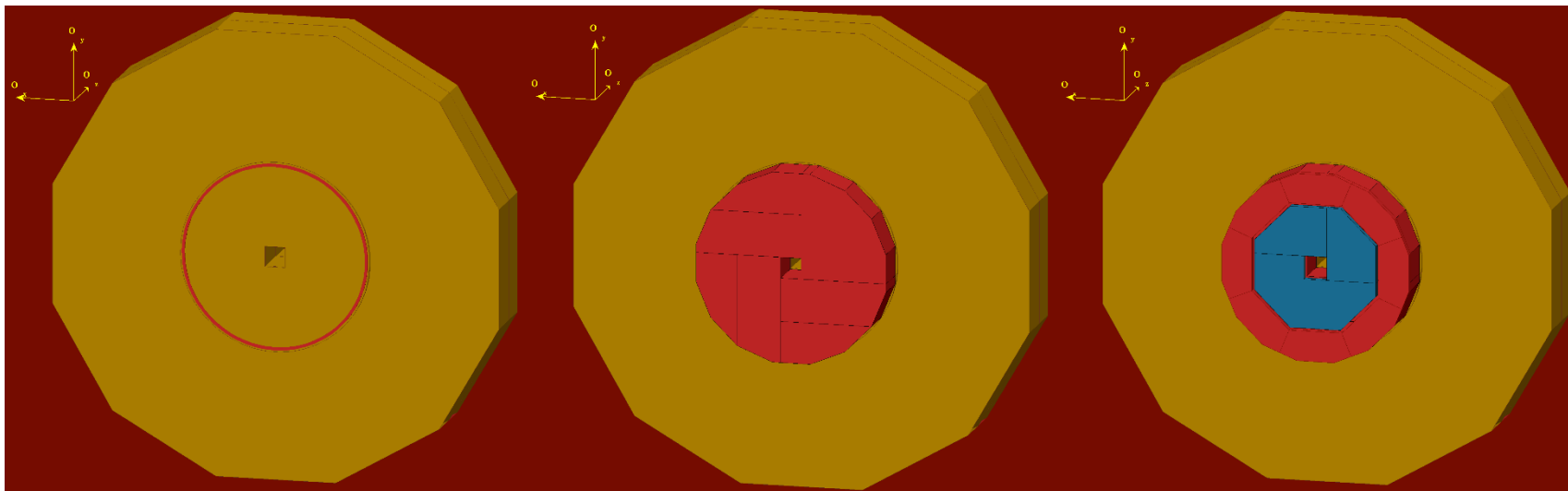


Y: Standard_mesh_CMS - Response Spectrum
Figure
Type: Directional Deformation(X Axis)
Unit: mm
Solution Coordinate System
Time: 0



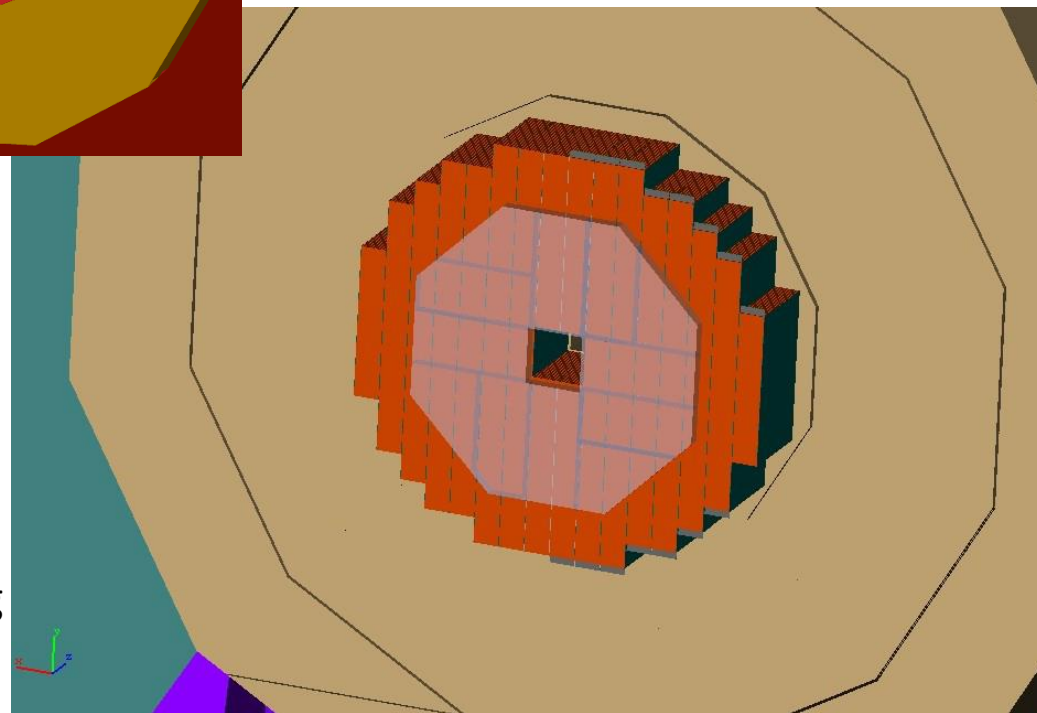


Hcal end caps



Plot de la version V (but from TESLA):
yoke and FSP with a fastening ring
Hcal end cap mounted in a two modules version
Ecal and Hcal ring installed

From Felix presentation
The bookshelf according
to Karsten Gadow





To follow up

The comparison needs to be done with an updated model, dimensions, thicknesses, but
what more studies have to be done to choose a structure for the barrel
A structure for the end caps?

The interference with the services path, therefore with the other sub-detectors
The interference with the TPC (support)
Etc.

End caps

The question on hanging on a slightly bulging FSP
The question of the dead zones.
Do really both technologies accept these two models?

Still not so much done but little drawings.
To be really started by the task-force



We have started the work

We have to move on as quickly as possible

LM

