

The ILD vertex detector and its relation to the inner tracker

ILD integration meeting LAL, 2 february 2018

Marcel Vos IFIC (U. Valencia/CSIC), Spain With inputs from Auguste Besson, Akimasa Ishikawa, Miguel Angel Villarejo, Ivan Vila

CMOS proof-of-principle

STAR Heavy Flavour Tagger

Based on MIMOSA CMOS sensor Operated successfully 2014-2016 Multiple detectors built!

Air cooled!!

Note: positive experience with air cooling in STAR and Belle II; AIDA2020 air cooling setup at Oxford

ILD integration, LAL, feb 2018 Marcel.Vos@ific.uv.es

CMOS MAPs future

Starting point: CPS for ALICE

In-pixel ampl. \oplus shaping \oplus discr. ALPIDE: $5 \mu m$, $5 \mu s$

MAPS for CBM-MVD

MIMOSIS hit rate 10^8 hits/cm² Prototype to be tested Production in 2020/21

MAPS for ILC

PSIRA VXD: 4 μ m, 2/4 μ s SIT: $5 \mu m$, $1 \mu s$

HVCMOS/HRCMOS

High Voltage or High Resisitivity CMOS process adopted by HEP

- \rightarrow allows for a sizeable depleted region
- \rightarrow contained signal, fast collection
- \rightarrow multiple wells allow for in-pixel functionality

Fashionable at the LHC:

- \rightarrow ALICE ITS upgrade
- \rightarrow part of ATLAS upgrade plan

ILC/CLIC tracking

Strasbourg CMOS MAPs suited for silicon inner tracker SIT

CLICdp positively evaluated the possibility of all-pixel CMOS tracker (ALPIDE-based design)

DEPFET active pixel detectors All-silicon ladder Belle II/ILC

self-supporting signal and power lines read-out & steering electronics

The next generation is ready to take the stage

DEPFET vertex detector

One more milestone:

installation of DEPFET PXD + SVD ladders in Belle II commissioning detector

Come-back of a golden oldie

FPCCD: inspired by SLD vertex detector

Pixel size down to $5 \times 5 \mu m^2$

Radiation hardness (= charge transfer efficiency) significantly improved by charge injection

The next-to-next generation...

Double silicon-on-insulator (DSOI) solves main SOI problems:

back-gating, trapping and cross talk

SOFIST: in-pixel time-stamping with 25 x 25 m² pixels

...is anxious to take over

Mechanics – ladder design

 $\mathsf \Omega$ L \Box $\bf \Sigma$ $\mathsf{L}\mathsf{L}$ ರ o \beth

ble -sid

 Ξ e $\frac{a}{\theta}$

ರ $\bf\sigma$ ے
0

Aim for double ladders with very low material budget: 0.35 % X_0 Alternative: single ladders

- Si Carbon fiber
- Si 4% SiC foam kapton Si
- Si plastic + air Si

 \bigcap \sqcup $\mathsf \Omega$ \sqcup \sqcup \vdash $\frac{1}{\alpha}$ silic o $\mathbf \subset$ $\bf\overline{o}$ o \beth ble $\frac{a}{1}$ $\bf\sigma$ dے
0

- Plume collaboration (Bristol, DESY, IPHC)
	- Double sided ladders with minimized material budget
- Plume 01 prototype (fab. 2012)
	- 2x6 Mimosa-26 on 2 mm foam SiC
		- \triangleright <mat.budget> ~ 0.6 % X₀ + Air cooling
	- Successfully validated in test beam
		- \triangleright Mat. budget checked in test beam with kink angle in sensitive area: 0.47 ± 0.02 % X_o (0.45 expected) (B.Boitrelle PhD)
- Plume 02 prototype → Reduced mat. Budget
	- Cu flex cable (0.42 % X_0)
		- 2 modules functional, 2 more expected
	- $-$ Al flex cable (0.35 % X_0)
		- ≥ 4 modules. Connectors issue \Box fix in 2017
	- 6 ladders expected (2 fabricated)
		- \triangleright Modules functional. Tests ongoing in 2016

•

LCWS2016, Morioka **Auguste Bess** 2016, Morioka Auguste Besson 2016 **Ladders close to ILC mat.budget specifications**

Ultra-thin silicon, power pulsing and air cooling?

Keep the silicon cool without affecting the stability or compromising the integrity!

Experience with air cooling in STAR arXiv:1710.02176

Extensive studies in Belle II mock-up, arXiv:1607.00663

Aggressive plans for Mu3e! arXiv:1610.02021

Air cooling & mechanical stability

Ph.D. thesis Nacho Garcia, U. Valencia, 2016

Dummy petal in CERN wind tunnel

Vibrations remain acceptable for air speed up to several m/s

12 Marcel.Vos@ific.uv.es

Double-sided structures

Double-sided structures based on all-silicon ladders

Air cooling

C U

sided structures have considerably higher eigenfrequency

Air cooling

ු
CSIC

ū

Double-sided structures improve resilience against air-induced vibrations

Note: ladders supported on one side only to amplify effects Note: thick silicon (thinned assembly soon) Note: petal-shaped structure to follow later

MCC AIDA²⁰²⁰

Micro-manifold before (photograph) and After wafer bonding (X-ray image) Samples produced at HLL.

High-tech plumbing: custom, 3D-printed interfaces to commercial piping

First encouraging results: "cool 40 W with 3 I/h and $\Delta T = 10$ K" **Published in JINST (arXiv:1604.0877)**

New structures

AIDA2020 production: three wafers with 3x2 "sensors" each

First "sensor" sample bump-bonded to "chip" at NTC-UPV

Interface document

Sections divided among editors:

- Auguste Besson (electronics + dimensions + CMOS)
- M. V. (alignment + cooling + DEPFET)
- Akimasa Ishikawa (FPCCD)

Most sections have text, but none are final.

Interface document: references

Interface document: figures

A few figures and tables indicating (critical) dimensions are included in the interface document

Detailed, realistic design, VXD

Vertex detector design still very "generic"

Estimate technology-dependent performance

- detailed DEPFET/FPCCD/MAPs digitizers
	- Software exists, needs some effort
- realistic support structures
	- Double vs. Single layer
	- Refine as mock-ups evolve
- realistic end-of-ladder material for CLIC
	- M.A. Villarejo (now IFIC)
- realistic routing of services

Person-power: ?

ILD inner tracker engineering design

Sub-systems

Beam pipe

Vertex Detector

Silicon Intermediate Tracker

Forward Tracking Disks

Requires an integrated design of support and services

Mechanics + integration

Assembly in two halves

Primary support element = support cylinder at $R~30$ cm

SIT + Outer FTD connected directly

VTX + Inner FTD connected through SIT?

Beam pipe connected too (where?)

ILD vertex detector alignment

Positioning and alignment constraints

Marcel

The alignment of the vertex detector is critical to achieve the challenging requirements for the precision of the position measurements. The specifications on impact parameters resolution of the vertex detector require a spatial resolution of approximately $3 \mu m$. Some solutions can achieve even better resolution. This leads to a requirement that the position of the vertex detector elements must be known to approximately $1 \mu m$.

The alignment of the vertex detector will be determined using track-based techniques. A relatively modest data sample is sufficient to determine the six alignment parameters of the vertex detector as a whole. The internal alignment of the detector forms a hierarchy : double layers, ladders and sensors each have six degrees of freedom. Determination of all parameters at the lowest level of the alignment hierarchy represents a much more complex problem. Determination of all individual degrees of freedom requires a very large data set. The internal alignment at the lowest level of the hierarchy (i.e. individual sensors) can only be repeated on the time scale of weeks or months. Distortion of these internal degrees of freedom on shorter time scales must be avoided.

Monitoring of the alignment with hardware systems is complementary to the track-based alignment. Hardware systems can be useful to provide information on time scales inaccessible to track-based alignment and can monitor distortions that are not easily spotted with the track-based alignments (so-called weak modes that leave the residuals unchanged). Previous experiments have used laser alignment systems (AMS, CMS) and frequency scanning interferometry (ATLAS). Strain measurements using Bragg optical fibers can provide an interesting addition.

While the position of all detector elements must be known to the $1 \mu m$ level, the actual position of the vertex detector at the time of installation and during operation is much less constrained. To avoid clashes between adjacent detector elements, a positioning tolerance of $100 \mu m$ is typically sufficient. Movements during operation of the same order are readily corrected, as long as the distortions act on relatively long time scale and affect the highestlevel structure of the detector (i.e. the detector must move as one rigid entity). Experience from previous experiments shows that these requirements are met by modern silicon-based detector systems, at least to the at the level of 5-10 um required by these detectors. A detailed mock-up of the vertex detector in realistic conditions is needed to demonstrate that a much lighter detector can robustly maintain its internal alignment to the $1 \mu m$.

Forces acting on the vertex detector, from its own cables and services, from the beam pipe, transmitted by the service cylinder…. The system must be designed in such a way that the vertex detector will move under such forces, but that its internal structure will not be distorted.

Questions to overall ILD design and/or the machine interface: How stable is the beam pipe? How is it supported in the vicinity of the vertex detector? How will it deform in response to the passage of the beam? What beam pipe currents are induced in each bunch train?

Cooling, liquid requirements

Air cooling remains the baseline

- Present detailed numbers on gas flow rate
- Control of inner tracker gas conditions
	- (temperature stability to 1 degree C, humidity well below dew point)

MCC cooling may be an interesting alternative

FPCCD requires CO2 cooling + cryostat

Cryostat and Liquid $CO₂$ (and gas N₂) cooling system Should be cool down to -40degree Inter-train readout \Box Larger power consumption than CMOS/DEPFET About 50W inside the cryostat, about 200W junction box FPCCD 10mW/channel (heating is larger for readout side) ASIC 5mW/channel ASIC and FPCCD readout side can be directly cooled down via CFRP for doublet ladder $CO₂$: 1g/sec per side (note. cooling power 300J/g) 1×2 mm cable per side \Box in total 2 cables CO2 cable is attached to endcap and cool down the air inside N₂: 6litter/min (or less) If air flow is further needed to cool down the FPCCD for not-readout side, N_2 cooled down by CO_2 is flowed to cryostat. outer wall : 0.2mmt CFRP + 1cmt Styrofoam + 0.2mm Inner wall : similar one but styrofoam thinner

Conclusions

Vertex detector R&D is progressing mostly outside the LC, but with clear benefits for ILD

The integration document is being filled (primary responsibles: Auguste Besson, Akimasa Ishikawa, Marcel Vos)

Expect:

- detailed descriptions of technologies, ladder design
- discussion of alignment & testing requirements & strategy
- less detail on inner tracker integration (unless progress is made on global issues)
- very little on technology-dependent detail (cables, connectors etc.)

