

### Study of Higgs→invisible at ILC using kinematic fit applied jet energy resolution of ILD

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# Outline

#### **Motivation**

- $\succ$  BSM search using Higgs→invisible at ILC
- ➢ Kinematic fit

### Evaluate jet energy resolution

- ILD model: large/small
- > check jet energy &  $\cos \theta$  dependence

also evaluate jet angle resolution  $\rightarrow$  apply to kinematic fit

### Kinematic fit

fit variables :  $E_{j1}, \theta_{j1}, \phi_{j1}, E_{j2}, \theta_{j2}, \phi_{j2}$ constraint :  $m_{jj} = m_Z = 91.2 \text{ GeV}$ use MarlinKinfit - fitter engine : OPALFitter apply jet energy/angle resolution > check effect & accuracy of fit

#### Improve analysis performance

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# Motivation



"Search for Invisible Higgs Decays at the ILC" LCWS2014@Belgrade

2018/5/8

Signal





# Analysis Setup

Simulation

- ILCSoft: v01-19-05
- Samples: DBD sample + Signal sample (  $e^+e^- \rightarrow qqH, H \rightarrow ZZ^* \rightarrow 4\nu$  )
- Detector: ILD full simulation (ILD\_o1\_v05) "Left" "Right"

•  $\sqrt{s} = 250 \text{ GeV}, \quad \int Ldt = 250 \text{ fb}^{-1}, \quad (P_{e^{-}}, P_{e^{+}}) = (-0.8, +0.3), \quad (+0.8, -0.3)$ 

•Flow of analysis

- 1. Particle flow reconstruction (PandoraPFA)
- 2. Isolated lepton finder (veto)
- 3. Durham jet finder (forced 2 jets)
- 4. Kinematic fit with MarlinKinfit (OPALFitter)
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- Optimized assuming signal BR(H $\rightarrow$ invisible) = 10%
- 6. Estimate upper limit of BR (95% CL)

1<sup>st</sup>. result

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MVA	input	No.	Cut	No.	Cut
varia	ables	1	Isolated lepton veto	5	80 < di-jet invariant mass < 100
di-jet inv. mass	one jet polar angle	2	Loose Cut (Ptz,Mz,Mrecoil)	6	di-jet polar angle  < 0.9
di-jet polar angle	another jet polar angle	3	#pfo >15 & #all_track > 6 & # track_in_one_jet > 1	7	100 < recoil mass < 160
TMVA	v-4.2.0	4	20 GeV < di-jet Pt < 80 GeV	8	BDT cut

1<sup>st</sup>. result

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## Principle of kinematic fit



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# International Large Detector





#### □Concept of detector system at ILC

- high-performance vertex detector
- high-resolution trackers
- high-granularity calorimeters etc.
- □Main request
  - Reconstruct all the particles, especially hadron jets
- To achive high energy resolution,Particle Flow Algorithm

#### Particle Flow Algorithm

The energy(momentum) for each particle is extracted from the subdetector system in which we expect the measurement to be most accurate.

 $\begin{array}{ll} \mbox{Charged particles} \rightarrow \mbox{Tracker} \\ \mbox{Photon} & \rightarrow \mbox{E Cal.} \\ \mbox{Neutral particles} & \rightarrow \mbox{H Cal.} \end{array}$ 



#### 2018/5/8

# Setting of Evaluation JER

- •ILCSoft : v01-19-05 (gcc49)
- •ILDConfig : v01-19-05-p01
- •ILD models : ILD\_I5\_o1\_v02, (ILD\_s5\_o1\_v02)
- ●Samples : Z→uds (w/o overlay)

•				-							$\sim$	
√s [GeV]	30	40	60	91	120	160	200	240	300	350	400	500
l5 [events]	10k	9k	10k	9k	10k							
s5 [events]	10k	10k	10k	10k	9k	10k	10k	9k	10k	10k	10k	10k

- Jet resolution definition
  - use RMS<sub>90</sub> method
  - Energy

$$\frac{\sigma_E}{E} = \frac{\text{RMS}_{90}(E_j)}{mean_{90}(E_j)} = \sqrt{2} \frac{\text{RMS}_{90}(E_{jj})}{mean_{90}(E_{jj})}$$

(J. S. Marshall and M. A. Thomson, "Pandora Particle Flow Algorithm", <u>arXiv:1308.4537</u> [physics.ins-det])

Angle

use jet clustering: Durham  

$$\delta \phi = \text{RMS}_{90}(\phi_{rec} - \phi_{mc})$$
  
 $\delta \theta = \text{RMS}_{90}(\theta_{rec} - \theta_{mc})$ 

Study of Higgs->invisible using kinematic fit

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# JER: Comparison Barrel/Endcap

JER was evaluated separately for barrel and endcap regions.



sv01-19-05.mlLD\_l5\_o1\_v02\_nobg

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# JER: Comparison Large/Small

The two detector models (large/small) were evaluated for comparison. sv01-19-05 lcos0l<0.7



- Impact of small detector seen for large jet energy
- JER goal (ILC TDR) satisfied for both models

## Result : energy & angle dependence

sv01-19-05.mlLD\_l5\_o1\_v02\_nobg



## Angular resolution



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#### Improve analysis performance





 $E_{j1}, \theta_{j1}, \phi_{j1}, E_{j2}, \theta_{j2}, \phi_{j2}$ 

Z mass constraint

$$m_{jj} = m_Z = 91.2 \,\mathrm{GeV}$$

□Jet mass asumption

$$m_j^{before} = m_j^{after}$$

Implement of jet resolution

$$\sigma_E(E,\cos\theta), \sigma_\theta(E,\cos\theta), \sigma_\phi(E,\cos\theta)$$





lcosθl

## MarlinKinfit : OPALFitter



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## Result : Recoil mass



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 $significance = \frac{N_s}{\sqrt{N_s + N_b}}$ 

# Cut table $(P_{e^-}, P_{e^+}) = (-0.8, +0.3)$

cut condition	S/√S+B	signal	all bkg	ZZ	WW	$\nu\nu$ Z	other bkg
No Cut	0.84	5255	$3.93  imes 10^7$	214211	2748230	67952	$3.63 imes10^7$
$N_{lep}=0$	1.00	5249	$2.74  imes 10^7$	165399	1276030	67853	$2.59  imes 10^7$
Pre-Cut	7.54	5026	439363	35027	69535	33852	300949
$N_{pfo} > 15 \& N_{charged} > 6$	9.66	4947	256873	34332	67457	33236	121848
$p_{Tjj} \in (20, 80) \mathrm{GeV}$	12.48	4688	136149	30207	56149	29166	20627
$M_{jj} \in (80, 100) \mathrm{GeV}$	13.50	3919	80266	23533	29210	23675	3848
$ \cos  heta_{jj}  < 0.9$	13.94	3768	69199	20457	24817	21246	2679

#### w/o kinematic fit

cut condition	S/√S+B	signal	all bkg	ZZ	WW	$\nu\nu Z$	other bkg
common part	13.94	3768	69199	20457	24817	21246	2679
$M_{recoil} \in (100, 160) \text{GeV}$	13.95	3765	69002	20438	24748	21174	2642
$\mathrm{BDT} > -0.0718$	15.54	3388	44086	12604	14941	14676	1865

#### w/ kinematic fit

cut condition	S/√S+B	signal	all bkg	ZZ	WW	$\nu \nu Z$	other bkg
common part	13.94	3768	69199	20457	24817	21246	2679
$M_{recoil} \in (100, 160) \text{GeV}$	15.10	3766	58404	15873	21289	18665	2577
BDT > -0.0867	16.26	3425	40893	11086	14030	13903	1874

 $significance = \frac{N_s}{\sqrt{N_s + N_b}}$ 

# Cut table $(P_{e^-}, P_{e^+}) = (+0.8, -0.3)$

cut condition	S/√S+B	signal	all bkg	ZZ	WW	$\nu\nu Z$	other bkg
No Cut	0.76	3549	$2.16 imes10^7$	116792	189591	23127	$2.13  imes 10^7$
$N_{lep}=0$	0.95	3545	$1.39  imes 10^7$	89111	88065	23092	$1.37  imes 10^7$
Pre-Cut	7.33	3391	210605	16373	4918	8970	180344
$N_{pfo} > 15 \& N_{charged} > 6$	10.03	3331	106837	16028	4773	8786	77250
$p_{Tjj} \in (20, 80) \mathrm{GeV}$	15.59	3144	37369	14018	4022	7793	11536
$M_{jj} \in (80, 100) { m GeV}$	17.17	2632	20815	10828	2087	6121	1779
$ \cos  heta_{jj}  < 0.9$	17.81	2535	17670	9387	1806	5373	1104

#### w/o kinematic fit

cut condition	S/√S+B	signal	all bkg	ZZ	WW	$\nu\nu Z$	other bkg
– common part	17.81	2535	17670	9387	1806	5373	1104
$M_{recoil} \in (100, 160) { m GeV}$	17.83	2532	17598	9376	1800	5366	1056
BDT > -0.0840	19.72	2298	11231	5800	1170	3463	798

#### w/ kinematic fit

cut condition	S/√S+B	signal	all bkg	ZZ	WW	$\nu\nu Z$	other bkg
common part	17.81	2535	17670	9387	1806	5373	1104
$M_{recoil} \in (100, 160) \text{GeV}$	19.61	2533	14104	7196	1549	4274	1085
BDT > -0.1162	20.81	2395	10806	5431	1187	3318	870

## Result : Recoil mass distribution



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## How to set Upper Limit



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Result : Upper limit of BR (95% CL)



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# Summary

#### Evaluate jet energy resolution

ILD model : ILD\_I(s)5\_v02  $\triangleright$  jet energy & cos  $\theta$  dependence evaluate jet angle resolution also  $\rightarrow$  apply to kinematic fit

#### Kinematic fit

fit variables :  $E_{j1}, \theta_{j1}, \phi_{j1}, E_{j2}, \theta_{j2}, \phi_{j2}$ constraint :  $m_{jj} = m_Z = 91.2 \text{ GeV}$ MarlinKinfit : OPALFitter apply jet resolution

#### <u>Higgs→invisible</u>

Previous study

w/o kinematic fit

kinematic fit

Estimated upper limit of BR( $H \rightarrow inv$ .) Improvement by kinematic fit UL of BR [%] (95%CL) Left polarization



sv01-19-05.mILD 15 o1 v02 noba

Achieve best sensitivity in the results so far!

0.95

0.73

0.69

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w/

Study of Higgs->invisible using kinematic fit

0.69

0.52

0.49

29

## Plans

### Evaluate jet energy resolution

- More detailed evaluation of the end cap part : more statistics
- Add c-jet & b-jet information
- Use jet clustering :  $E_{j1} \neq E_{j2}$
- Add jet mass dependence

### kinematic fit

- Improve fit accuracy : check underestimation of JER
- Implement soft constraint : Γ<sub>Z</sub>
- Apply to other processes

### <u>Higgs→invisible</u>

- Use variables after fit for event selection
- Optimize recoil mass range used for estimation
- Set upper limit using profile likelihood ratio

# backup

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### Preliminary : Soft Constraint Test



### The Mathematics of the NewtonFitter



N parameters  $a_i,\,i=1...N$  Measured values  $\vec{y},$  covariance matrix V K constraint functions  $\vec{f}\left(\vec{a}\right)$ 

The total  $\chi^2$ :  $\chi^2_T(\vec{a},\vec{\lambda}) = \chi^2(\vec{a},\vec{y}) + \vec{\lambda}^T \cdot \vec{f}(\vec{a}).$ 

Seek stationary point, where all derivatives vanish:

 $\begin{aligned} \nabla_a \chi_T^2 &= \nabla_a \chi^2 + \vec{\lambda}^T \cdot \nabla_a \vec{f} (\vec{a}) = \vec{0}, \\ \nabla_\lambda \chi_T^2 &= \vec{f} (\vec{a}) = \vec{0}, \end{aligned} \qquad (N \text{ equations}) \quad \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\partial \chi_T^2}{\partial \vec{a}} \\ \frac{\partial \chi_T^2}{\partial \vec{\lambda}} \end{pmatrix} = \begin{pmatrix} \frac{\partial \chi^2}{\partial a_i} + \sum_k \lambda_k \cdot \frac{\partial f_k}{\partial a_i} \\ f_k \end{pmatrix} \end{aligned}$ 

Newton-Raphson iterative method to solve y(x)=0:

$$x^{\nu+1} = x^{\nu} - \frac{y(x^{\nu})}{y'(x^{\nu})} \quad \Rightarrow \text{ solve } \quad y'(x^{\nu}) \cdot (x^{\nu} - x^{\nu+1}) = y(x^{\nu})$$

Here: Solve this system of equations in each step:

$$\begin{pmatrix} \frac{\partial^2 \chi^2}{\partial a_1 \partial a_1} + \lambda_{\mathbf{k}} \cdot \frac{\partial^2 f_{\mathbf{k}}}{\partial a_1 \partial a_1} & \dots & \frac{\partial^2 \chi^2}{\partial a_1 \partial a_N} + \lambda_{\mathbf{k}} \cdot \frac{\partial^2 f_{\mathbf{k}}}{\partial a_1 \partial a_N} & \begin{vmatrix} \frac{\partial f_1}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_1} \\ \dots & \dots & \dots \\ \frac{\partial \chi^2}{\partial a_N \partial a_1} + \lambda_{\mathbf{k}} \cdot \frac{\partial^2 f_{\mathbf{k}}}{\partial a_N \partial a_1} & \dots & \frac{\partial^2 \chi^2}{\partial a_N \partial a_N} + \lambda_{\mathbf{k}} \cdot \frac{\partial^2 f_{\mathbf{k}}}{\partial a_N \partial a_N} & \begin{vmatrix} \frac{\partial f_1}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_N} \\ \frac{\partial f_1}{\partial a_1} & \dots & \frac{\partial f_1}{\partial a_N} \\ \dots & \dots & \dots \\ \frac{\partial f_K}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_N} \\ \frac{\partial f_K}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_N} & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ \frac{\partial f_K}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_1} & \dots & 0 \\ \end{pmatrix} \cdot \begin{pmatrix} a_1^{\nu} - a_1^{\nu+1} \\ \dots \\ a_N^{\nu} - a_N^{\nu+1} \\ \frac{\partial \chi^2}{\partial a_N} + \lambda_{\mathbf{k}}^{\nu} \cdot \frac{\partial f_k}{\partial a_N} \\ \frac{\partial f_1}{\partial a_N} & 0 & \dots & 0 \\ \dots & \dots & \dots \\ \frac{\partial f_K}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_N} & 0 & \dots & 0 \\ \end{pmatrix} \cdot \begin{pmatrix} a_1^{\nu} - a_1^{\nu+1} \\ \dots \\ a_N^{\nu} - a_N^{\nu+1} \\ \frac{\partial \chi^2}{\partial a_N} + \lambda_{\mathbf{k}}^{\nu} \cdot \frac{\partial f_k}{\partial a_N} \\ \frac{\partial f_1}{\partial a_N} & 0 & \dots & 0 \\ \dots & \dots & \dots \\ \frac{\partial f_K}{\partial a_1} & \dots & \frac{\partial f_K}{\partial a_N} \end{pmatrix} = \begin{pmatrix} \frac{\partial \chi^2}{\partial a_1} + \lambda_{\mathbf{k}}^{\nu} \cdot \frac{\partial f_k}{\partial a_1} \\ \dots \\ \frac{\partial \chi^2}{\partial a_N} + \lambda_{\mathbf{k}}^{\nu} \cdot \frac{\partial f_k}{\partial a_N} \\ \frac{\partial f_1}{\partial a_N} & \dots & 0 \\ \dots & \dots \\ \frac{\partial f_K}{\partial a_1} + \lambda_{\mathbf{k}}^{\nu} - \lambda_{\mathbf{k}}^{\nu+1} \end{pmatrix} = \begin{pmatrix} \frac{\partial \chi^2}{\partial a_1} + \lambda_{\mathbf{k}}^{\nu} \cdot \frac{\partial f_k}{\partial a_1} \\ \dots \\ \frac{\partial \chi^2}{\partial a_N} + \lambda_{\mathbf{k}}^{\nu} \cdot \frac{\partial f_k}{\partial a_N} \\ \frac{\partial f_1}{\partial a_N} & \dots & 0 \\ \end{pmatrix}$$

B. List 20.2.2008

(Marlin)Kinfit: Kinematic Fitting for the ILC

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		List of enve	elope parameters for IL	D_I5_v02	
detector	inner radius	outer radius	half length min z, max z	additional parameters	
VXD	15.0	101.0	177.6	VXD_cone_min_z VXD_cone_max_z VXD_inner_radius_1	80.0 150.0 25.1
FTD	37.0	309.0	2350.0	FTD_outer_radius_1 FTD_outer_radius_2 FTD_min_z_0 FTD_min_z_1 FTD_min_z_2 FTD_cone_min_z FTD_cone_radius	152.8 299.7 177.7 368.2 644.2 230.0 192.0
SIT	152.9	324.6	644.1	SIT_outer_radius_1 SIT_half_length_1	299.8 368.1
ТРС	329.0	1769.8	2350.0		
SET	1769.9	1804.3	2350.0		
Ecal	1804.8	2028.0	2350.0	Ecal_Hcal_symmetry Ecal_symmetry	8 8
EcalEndcap	400.0	2095.84	2411.8, 2635.0	EcalEndcap_symmetry	8
EcalEndcapRing	250.0	390.0	2411.8, 2635.0		
Hcal	2058.0	3395.5	2350.0	Hcal_inner_symmetry	8
HcalEndcap	350.0	3225.5	2650.0, 3937.0		
HcalEndcapRing	2145.84	2980.0	2411.8, 2635.0	HcalEndcapRing_symmetry	8
Coil	3425.0	4175.0	3872.0		
Yoke	4475.0	7776.0	4047.0	Yoke_symmetry	12
YokeEndcap	300.0	7776.0	4072.0, 7373.0	YokeEndcap_symmetry	12
YokeEndcapPlug	300.0	3395.54	3937.2, 4072.0	YokeEndcapPlug_symmetry	12
BeamCal	17.8	140.0	3115.0, 3315.0	BeamCal_thickness	200.0
LHCal	130.0	315.0	2680.0, 3160.0	LHCal_thickness	480.0
LumiCal	80.0	202.1	2411.8, 2540.5	LumiCal_thickness	128.7

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detector	inner radius	outer radius	half length min z, max z	additional parameters	
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SIT	152.9	324.61	644.1	SIT_outer_radius_1 SIT_half_length_1	299.8 368.1
ТРС	329.0	1426.8	2350.0		
SET	1426.9	1461.3	2350.0		
Ecal	1461.8	1685.0	2350.0	Ecal_Hcal_symmetry Ecal_symmetry	8 8
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HcalEndcapRing	1767.92	2656.92	2411.8, 2635.0	HcalEndcapRing_symmetry	8
Coil	3075.33	3825.33	3872.0		
Yoke	4125.33	7426.33	4047.0	Yoke_symmetry	12
YokeEndcap	300.0	7426.33	4072.0, 7373.0	YokeEndcap_symmetry	12
YokeEndcapPlug	300.0	3045.83	3937.2, 4072.0	YokeEndcapPlug_symmetry	12
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