

Pion Energy Reconstruction with Deep Neural Networks

Erik Buhmann¹, Gregor Kasieczka, Erika Garutti



Universität Hamburg

DER FORSCHUNG | DER LEHRE | DER BILDUNG



Bundesministerium
für Bildung
und Forschung



Friedrich Naumann
STIFTUNG

FÜR DIE FREIHEIT

¹ eMail: erik.buhmann@desy.de

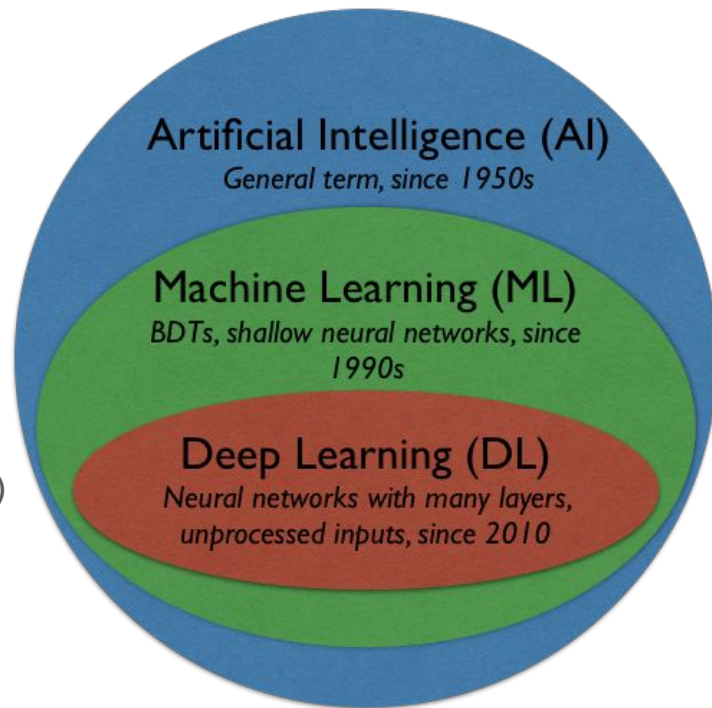
Overview

- Introduction
 - Neural Networks Basics
 - Network Architectures
- Preliminary Studies
 - Regression with 3D Convolutional Layer
 - Regression with Locally Connected Layer
- Summary & Outlook

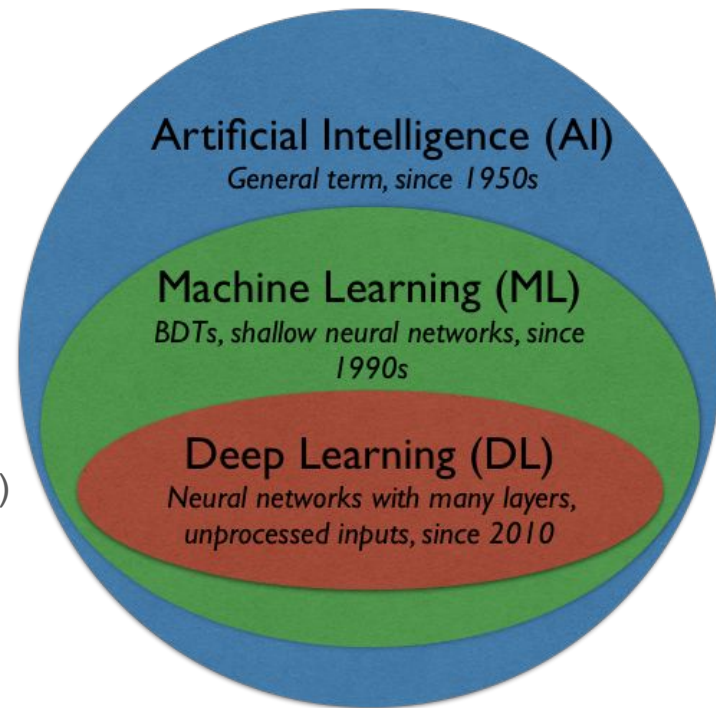
Overview

- Introduction
 - Neural Networks Basics
 - Network Architectures
- Preliminary Studies
 - Regression with 3D Convolutional Layer
 - Regression with Locally Connected Layer
- Summary & Outlook

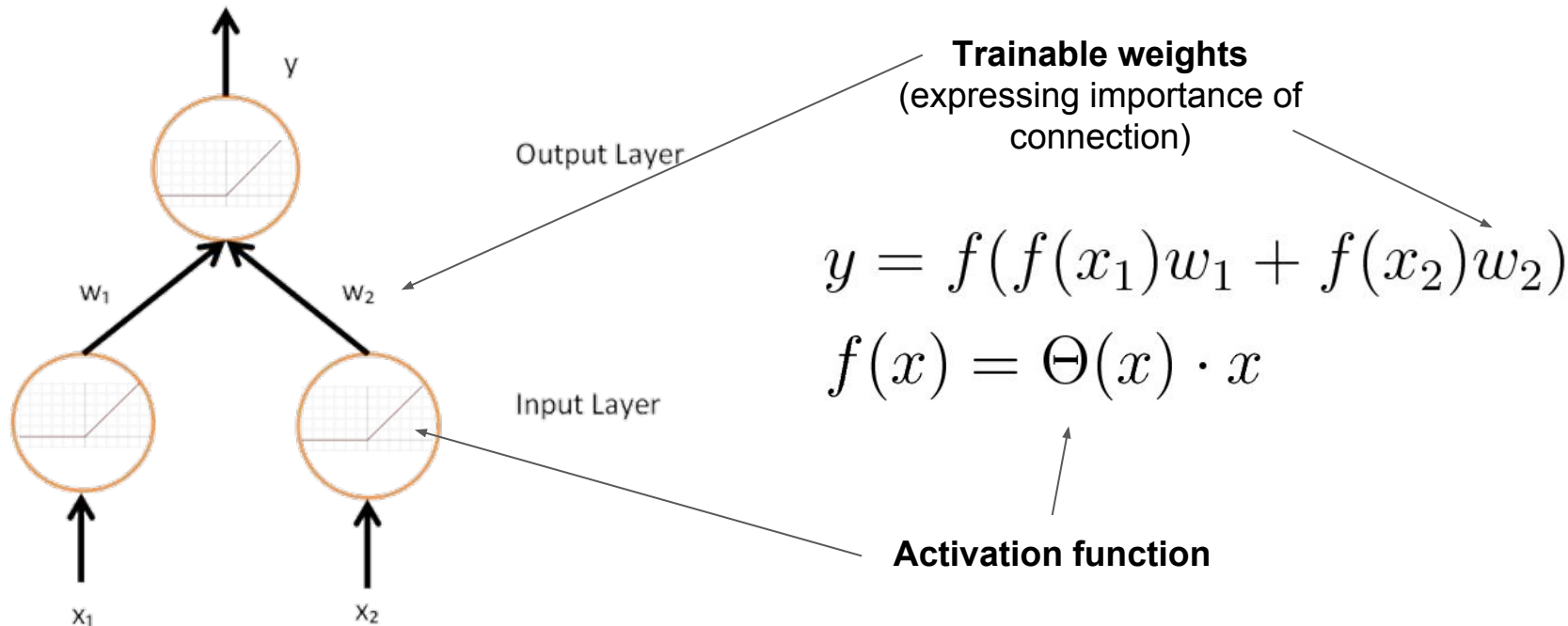
- What do we want to learn?
 - Classification (Cat or dog?)
 - Generation (New pictures of cats)
 - Regression (How old is the cat?)
 - Compression (Smaller cats)
 - ?
- What do we have available?
 - Labelled examples (supervised learning)
 - Limited labelled examples (weakly supervised training)
 - No examples (unsupervised training)



- What do we want to learn?
 - Classification (Cat or dog?)
 - Generation (New pictures of cats)
 - **Regression (How old is the cat?)**
 - Compression (Smaller cats)
 - ?
- What do we have available?
 - **Labelled examples (supervised learning)**
 - Limited labelled examples (weakly supervised training)
 - No examples (unsupervised training)



A Basic Neural Network

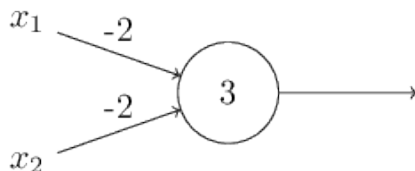


Simple NN as logic circuit

NAND logic function with “neuron”:

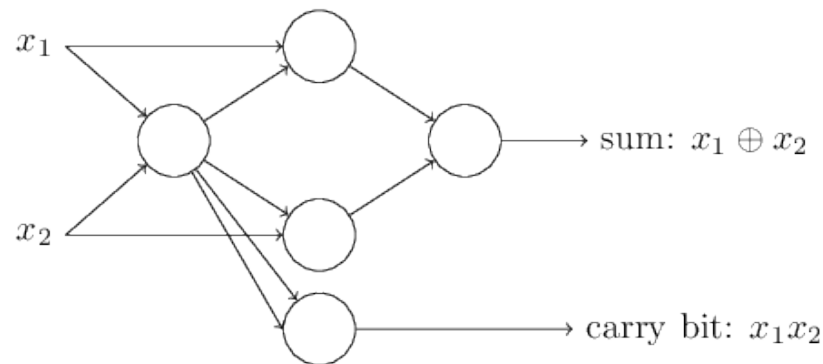
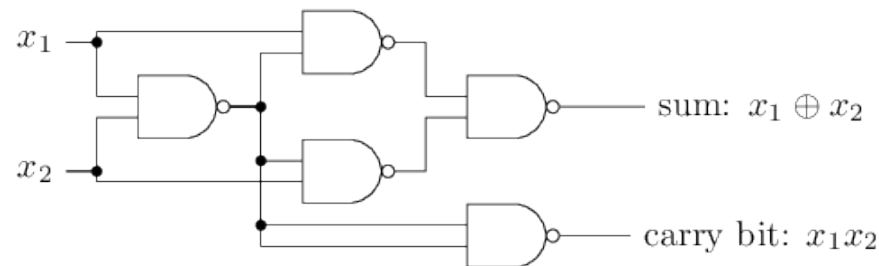
Weights $w_1, w_2 = -2$

Bias $b = 3$



Assuming
binary input:

x1	x2	$(x_1 w_1 + x_2 w_2) + b$	Out
0	0	3	1
0	1	1	1
1	0	1	1
1	1	-1	0



→ A large enough neural network with correctly tuned (trained!) weights can model any decision making process

[1] <http://neuralnetworksanddeeplearning.com>

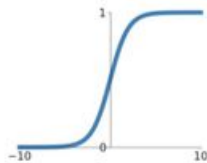
Computation performed in each neuron - Examples:

Activation Functions

Historical:

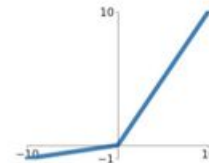
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



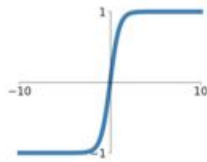
Leaky ReLU

$$\max(0.1x, x)$$



tanh

$$\tanh(x)$$



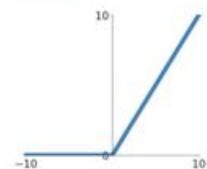
Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

Currently popular:

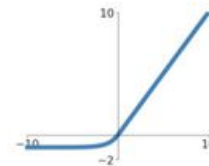
ReLU

$$\max(0, x)$$



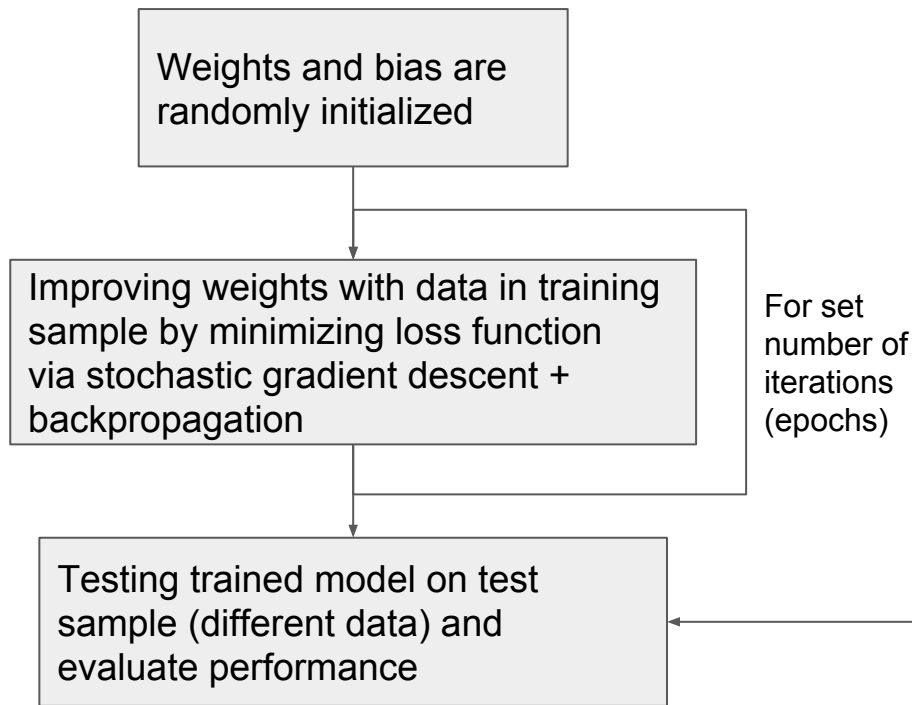
ELU

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$

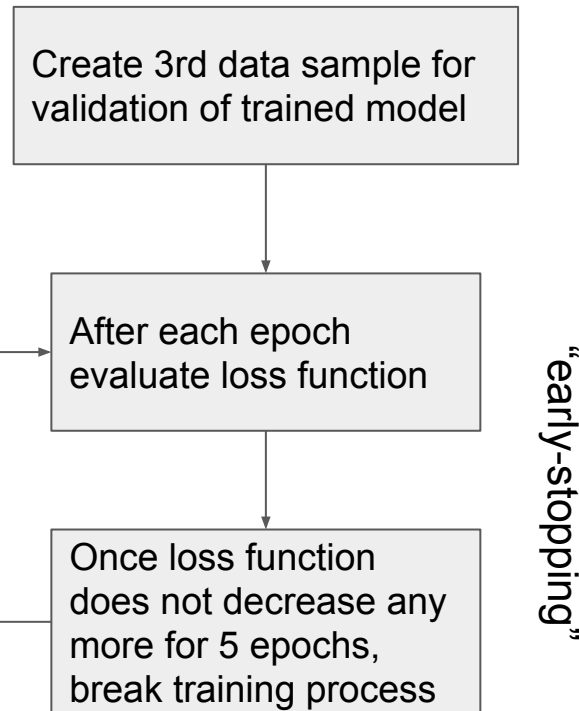


Learning Process

General process:



To avoid overfitting:



Loss function

Training by minimizing of loss function through adjusting weights and biases in every training step

Example 1) Mean Squared Error:

$$L(E_{i,true}, E_{i,pred}) = \frac{1}{N} \sum_i (E_{i,pred} - E_{i,true})^2$$

Example 2) Mean Squared Relative Error:

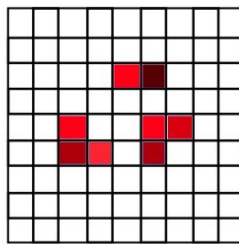
$$L(E_{i,true}, E_{i,pred}) = \frac{1}{N} \sum_i \left(\frac{E_{i,pred} - E_{i,true}}{E_{i,true}} \right)^2$$

- Network based on connection of different layers and layer types
- Layer types we used so far:
 - Fully Connected layer
 - Locally Connected layer
 - Convolutional layer

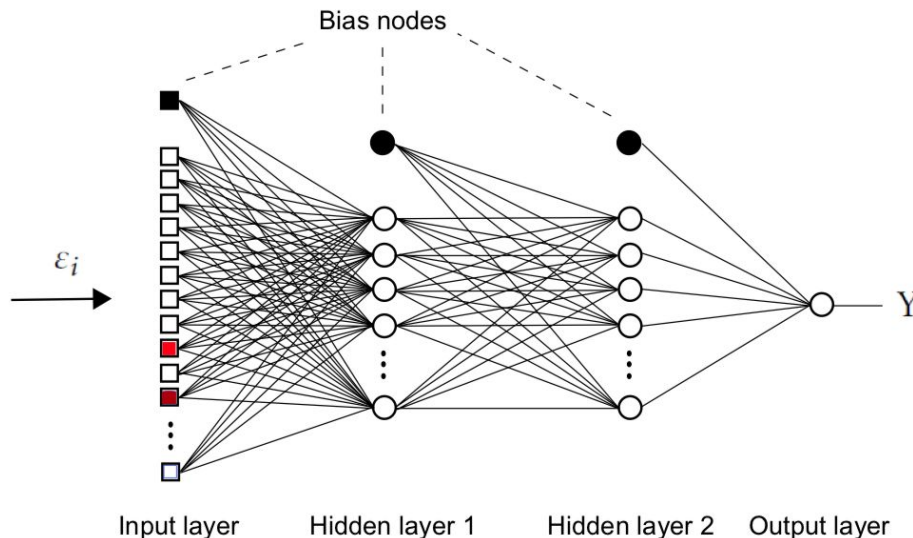


Fully Connected Layer

- “Classical” Artificial Neural Network (ANN)
- Every node of each layer connected to every node of neighboring layers
- Many trainable weights
 - During training connections are strengthened or weakened



Calorimeter image



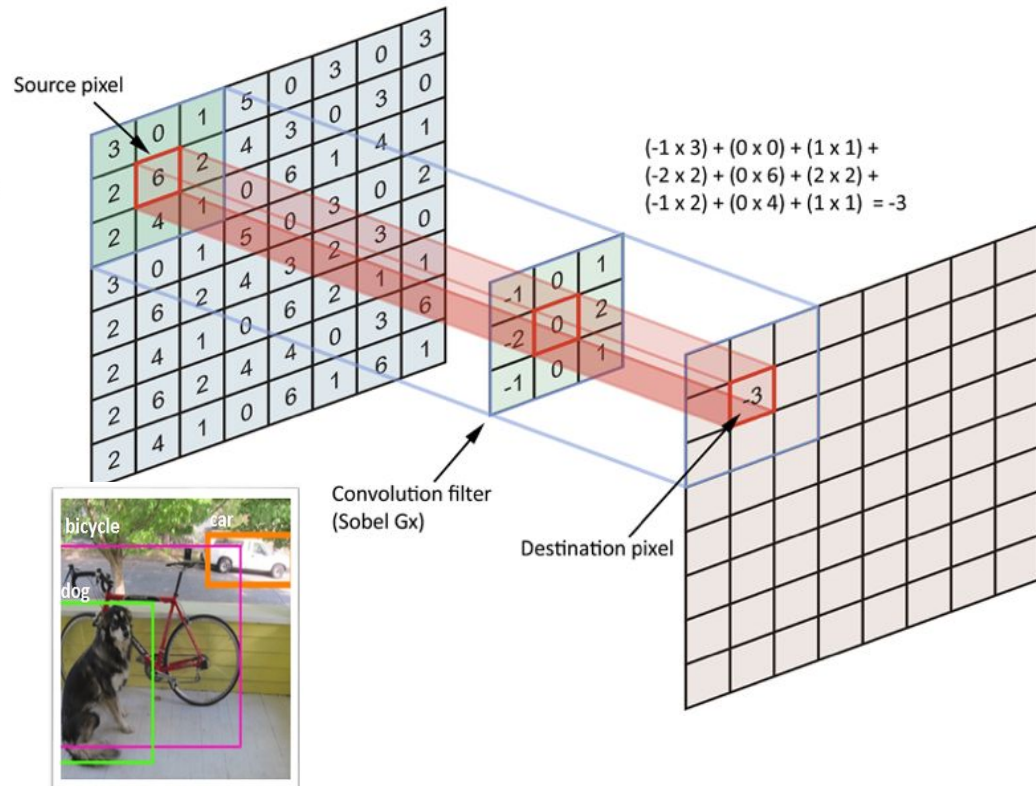
[1] Almeida et al, Playing Tag with ANN: Boosted Top Identification with Pattern Recognition, *arXiv:1501.05968*

Locally Connected Layer

- Output value of convolutional kernel:

$$O_{conv} = (w_1 E_1 + w_2 E_2 + w_3 E_3 + \dots) + b$$

- Unshared weights
 - New kernel (here 3 x 3) is used at every position
 - Multiple kernels used to learn different features of the image
 - Could a (1 x 1) kernel be used to learn single calorimeter channel calibration?



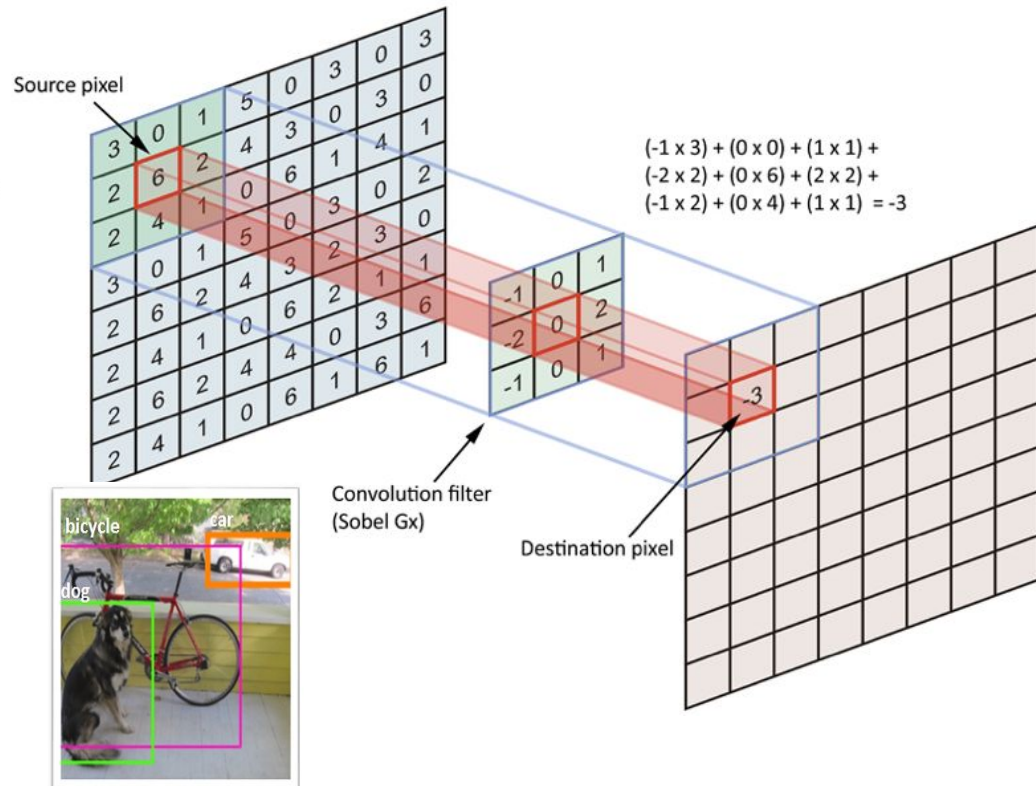
Convolutional Layer

- Output value of convolutional kernel:

$$O_{conv} = (w_1 E_1 + w_2 E_2 + w_3 E_3 + \dots) + b$$

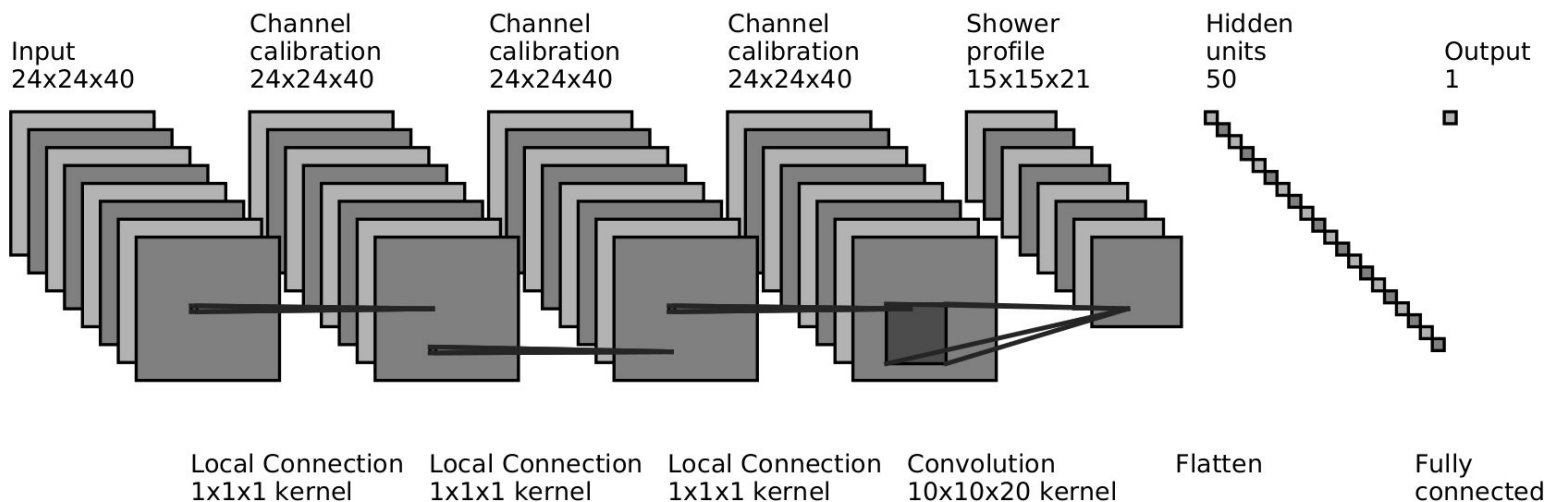
- Shared weights

- Same kernel (here 3 x 3) is used at every position
 - Less trainable weights
- Multiple kernels used to learn different features of the image
- Could a convolutional kernel be used to learn particle shower features in calorimeter?



Goal: Deep Neural Network

- Connecting multiple locally connected, convolutional and fully connected layer
- Physics based approach:
 - Locally Connected layer to find channel calibration
 - Convolutional filter to identify shower profile



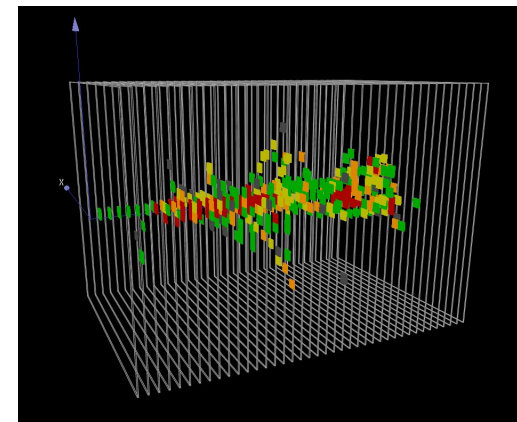
- Introduction
 - Neural Networks Basics
 - Network Architectures
- Preliminary Studies
 - Regression with 3D Convolutional Layer
 - Regression with Locally Connected Layer
- Summary & Outlook

- Network programmed in Python
 - Keras as high-level neural network API
 - Theano or tensorflow as back-end
- Training on Maxwell Cluster at DESY
 - Nodes with NVIDIA Tesla P100 GPU, 16GB RAM



Input data for network:

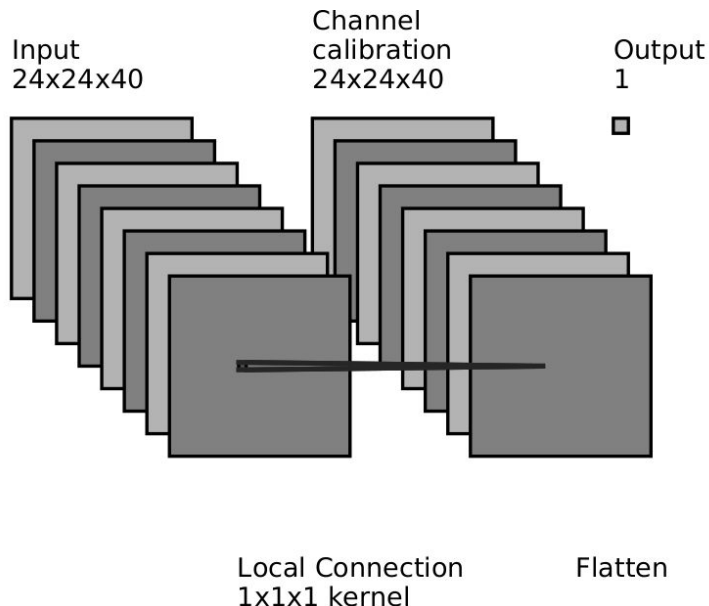
- Pion data from May testbeam @ SPS
- “Event display images” as (24,24,40) arrays
 - With hit energies at (I,J,K) coordinates
- $E_{\text{sum}} > 200$ MIP to cut Muon contamination



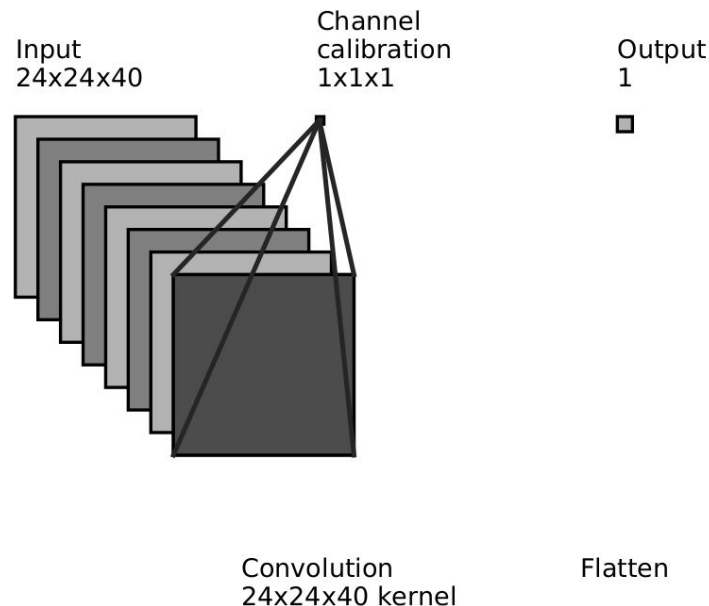
Regression task

Pion energy [GeV]	Events in training sample	Events in validation sample	Events in test sample
10	12,000	4,000	4,000
15	0	0	4,000
20	12,000	4,000	4,000
30	0	0	4,000
40	12,000	4,000	4,000
50	0	0	4,000
60	12,000	4,000	4,000
80	0	0	4,000
100	12,000	4,000	4,000
120	0	0	4,000
160	12,000	4,000	4,000

With locally connected layer:

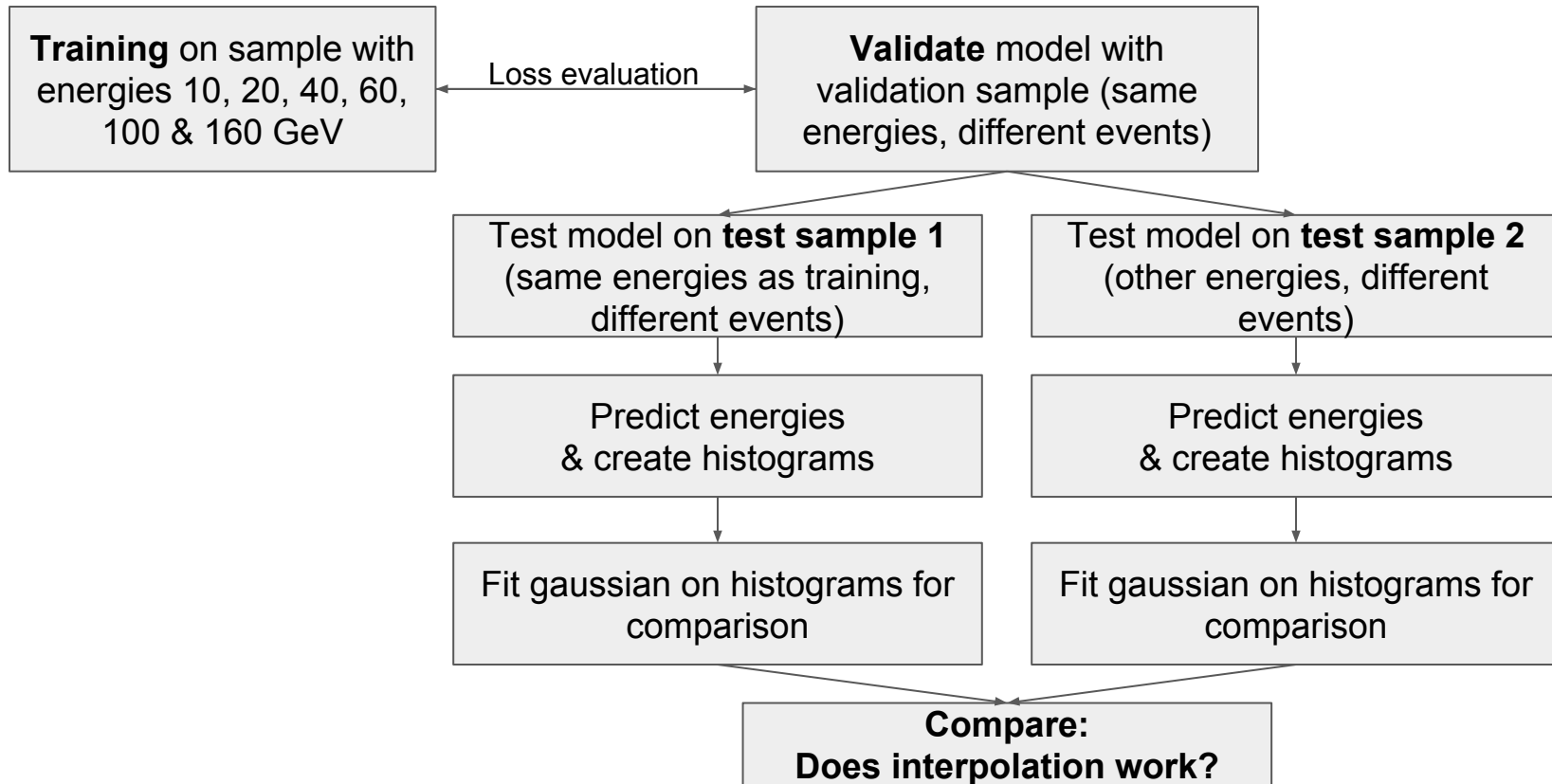


With 3D convolutional layer:



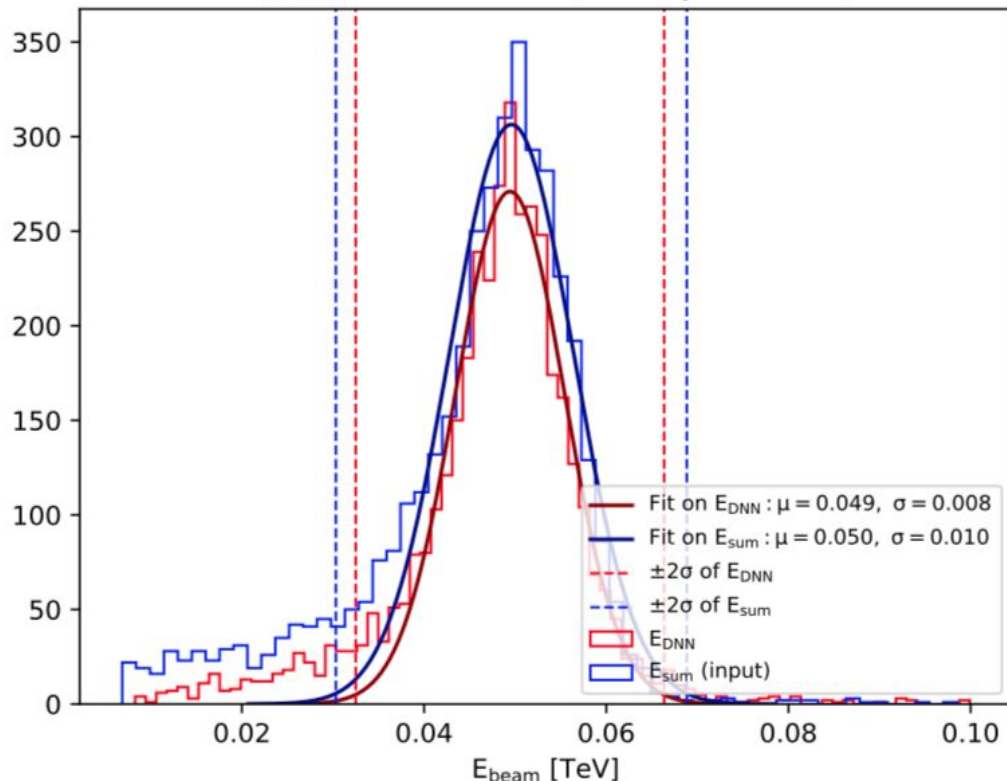
Both with loss function: Mean Squared Relative Error (MSRE)

Training & Testing Process



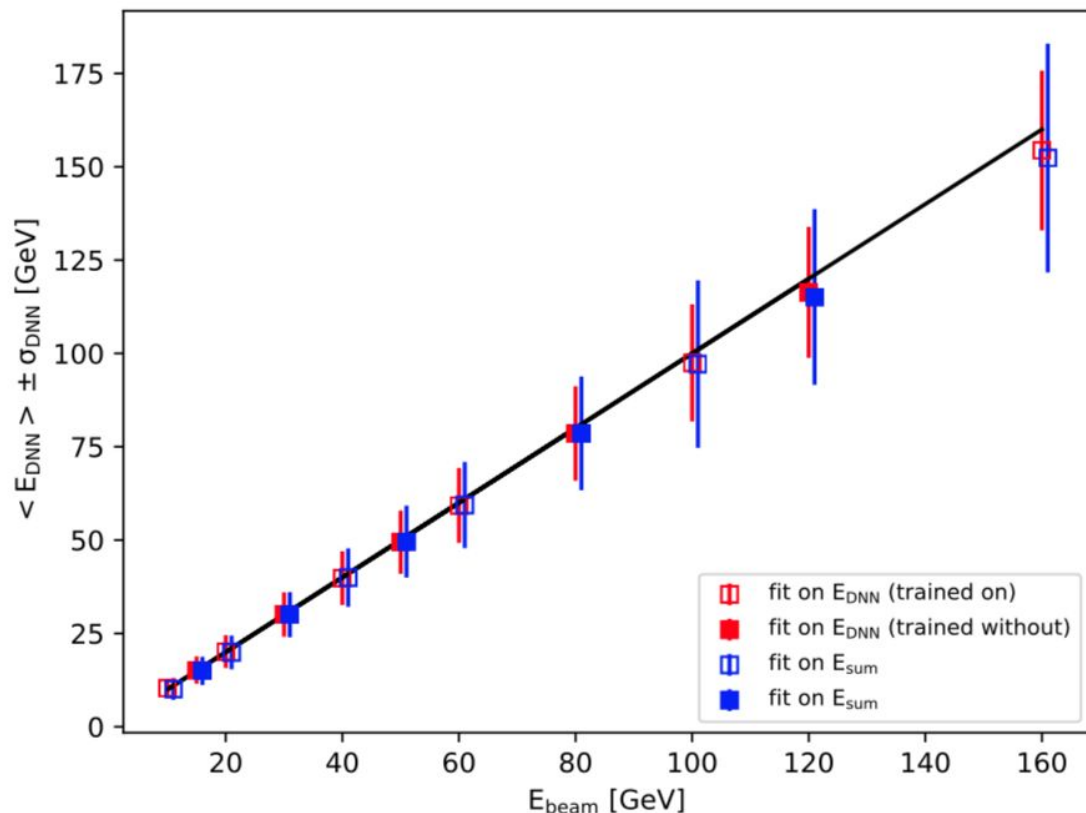
Reconstructed Energies

$E_{\text{beam}} = 50 \text{ GeV}$ (interpolated)



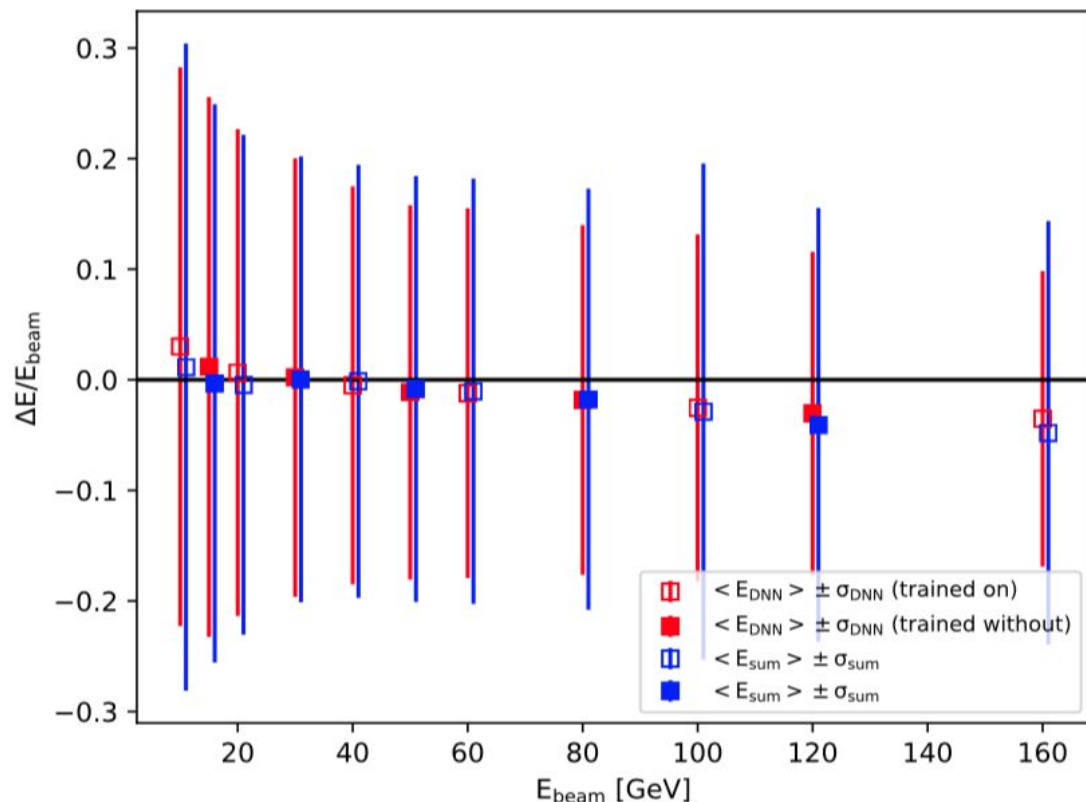
- Gaussian fit on histogram of reconstructed energy
- Comparison with original energy sum as “sanity check”
 - ◆ Based on a linear MIP-to-GeV factor of 29.7
- Histogram of reconstructed energy is always smaller than of energy sum
- Histograms and fits created for all energies of both test samples
- Tails through leakage (?)

Locally Connected Architecture



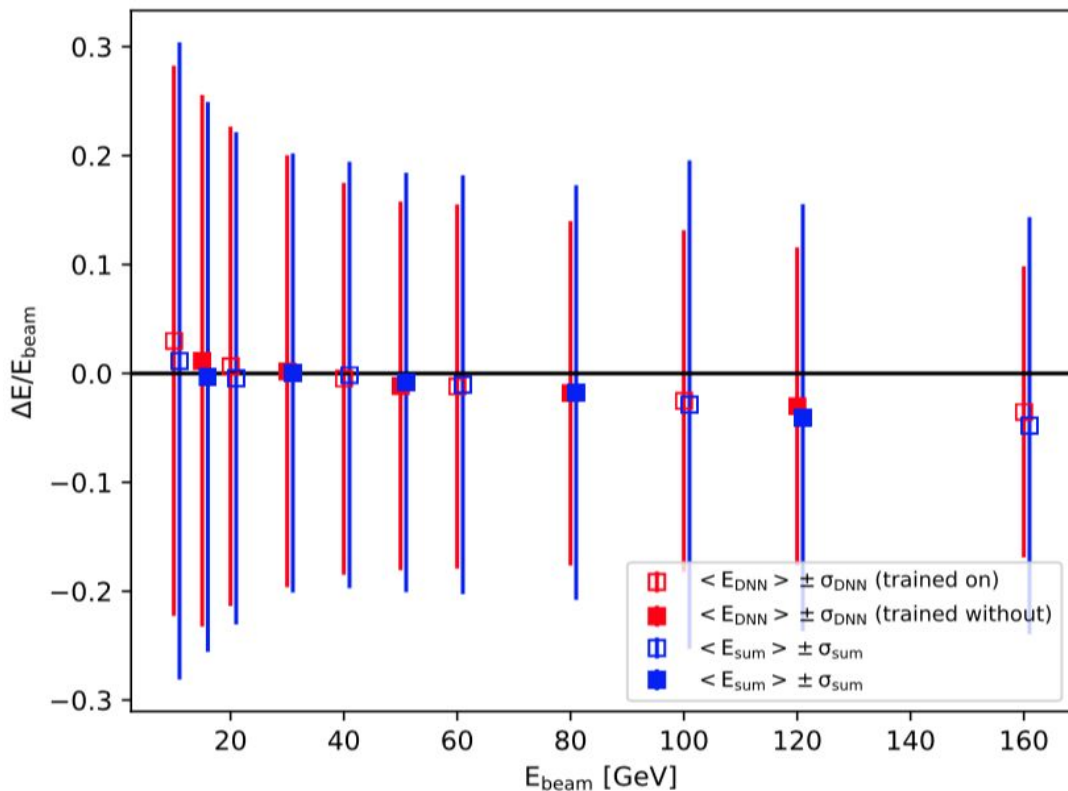
- Overview of fit parameters for all energies
- Error bars represent $\pm 1\sigma$ intervall
- Both training samples
 - ◆ No systematic difference observable

Locally Connected Architecture



- No systematic difference between trained on and interpolated reconstructed energies
- σ for E_{reco} overall smaller than for E_{sum}
 - ◆ Network performance better than simple energy fit
- Simple network learns MIP-to-GeV calibration
- Per channel linear calibration is learned

Convolutional Architecture



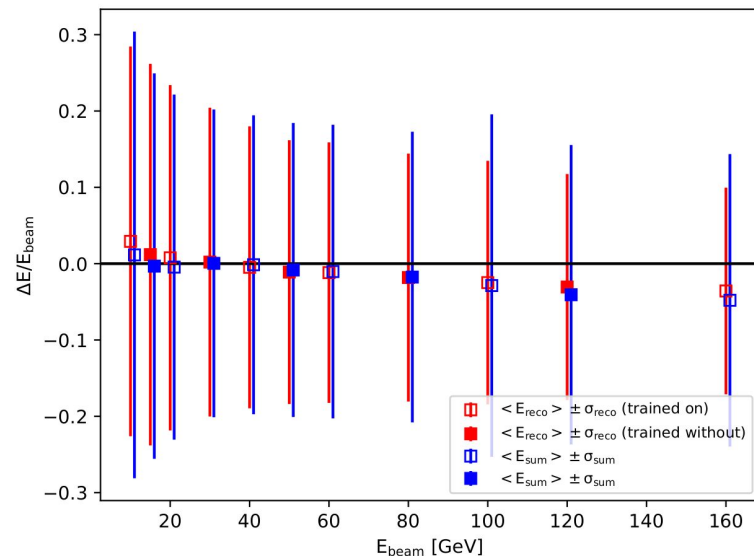
→ Similar performance to
 Locally Connected
 layer

- Introduction
 - Neural Networks Basics
 - Network Architectures
- Preliminary Studies
 - Regression with 3D Convolutional Layer
 - Regression with Locally Connected Layer
- Summary & Outlook

Summary

- Conversion of TB data into file format for ML works
- Preliminary studies with energy reconstruction
- Energy interpolation learned by network
- Trained solely on real data, no MC simulations used
- MIP-to-GeV conversion learned by network
- Shallow architecture for easy understanding of network output
 - 3D convolutional layer to learn shower features
 - Locally Connected layer to learn calibration values for single channels

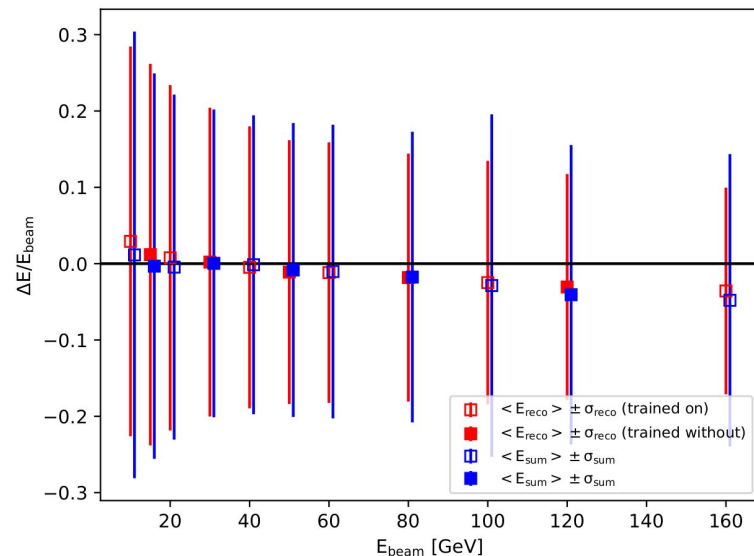
- Implementation of deeper network architecture
- Energy reconstruction + Particle ID
- Training with MC simulation
- Usage of time information
- Studies with uncalibrated ADC data



- Implementation of deeper network architecture
- Energy reconstruction + Particle ID
- Training with MC simulation
- Usage of time information
- Studies with uncalibrated ADC data

Thank you!

- And more ideas?



Bonus Slides



Universität Hamburg

DER FORSCHUNG | DER LEHRE | DER BILDUNG



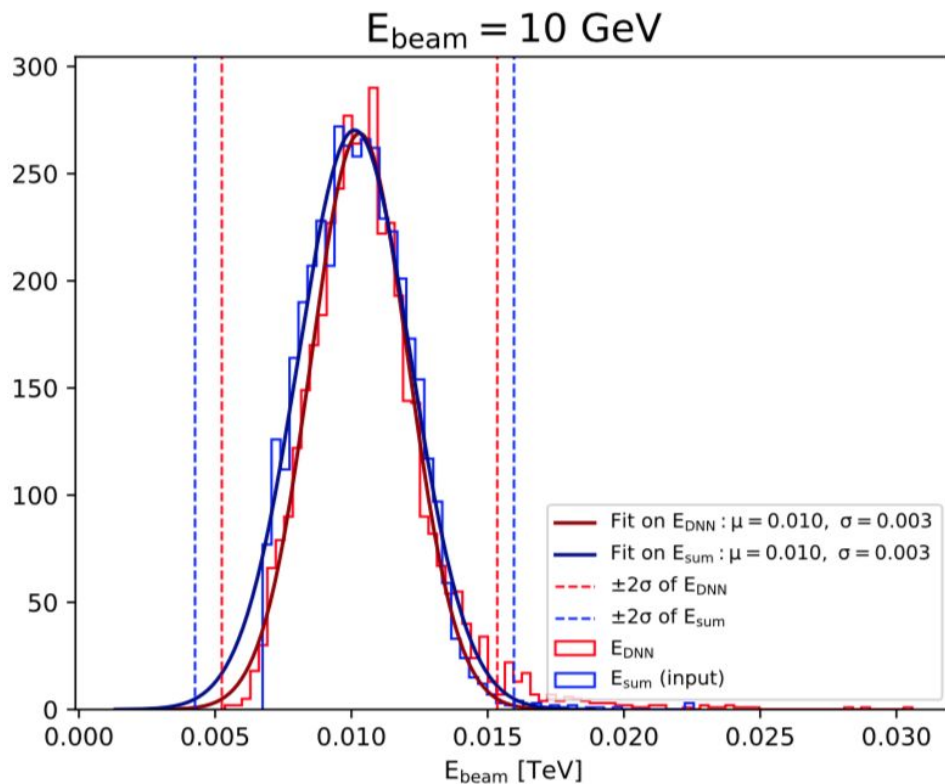
Bundesministerium
für Bildung
und Forschung

Friedrich Naumann
STIFTUNG

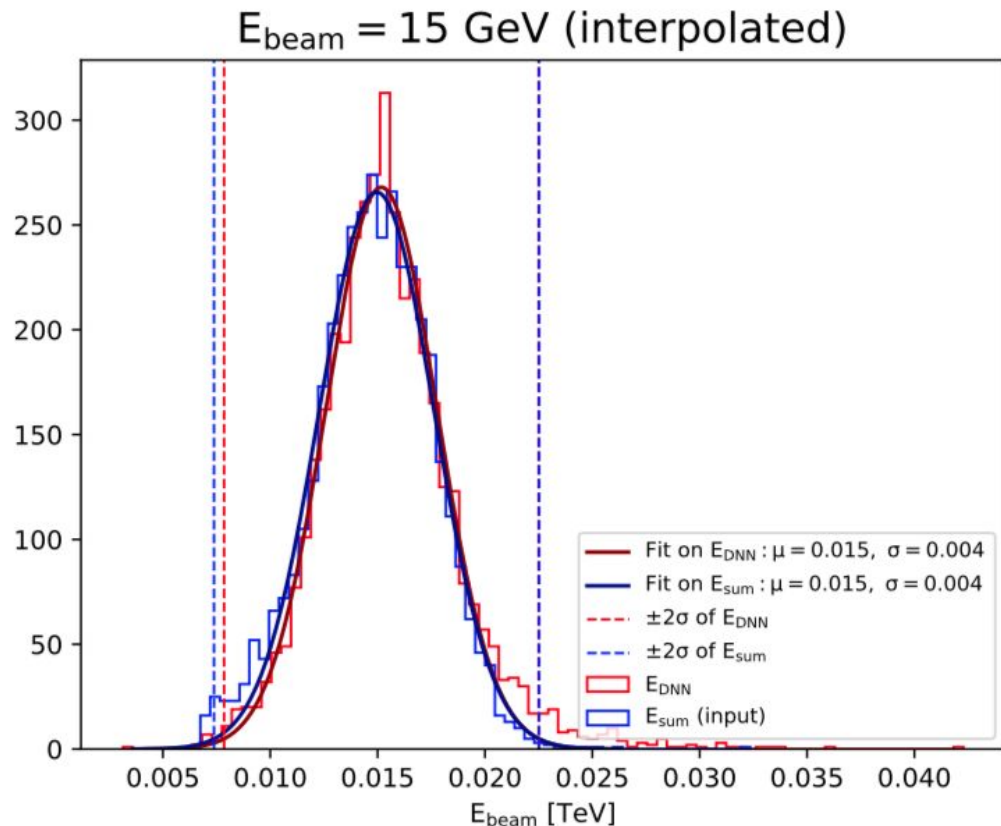
FÜR DIE FREIHEIT

ALL THE OTHER HISTOGRAMS FOR EVERY ENERGY
FOR BOTH ARCHITECTURES

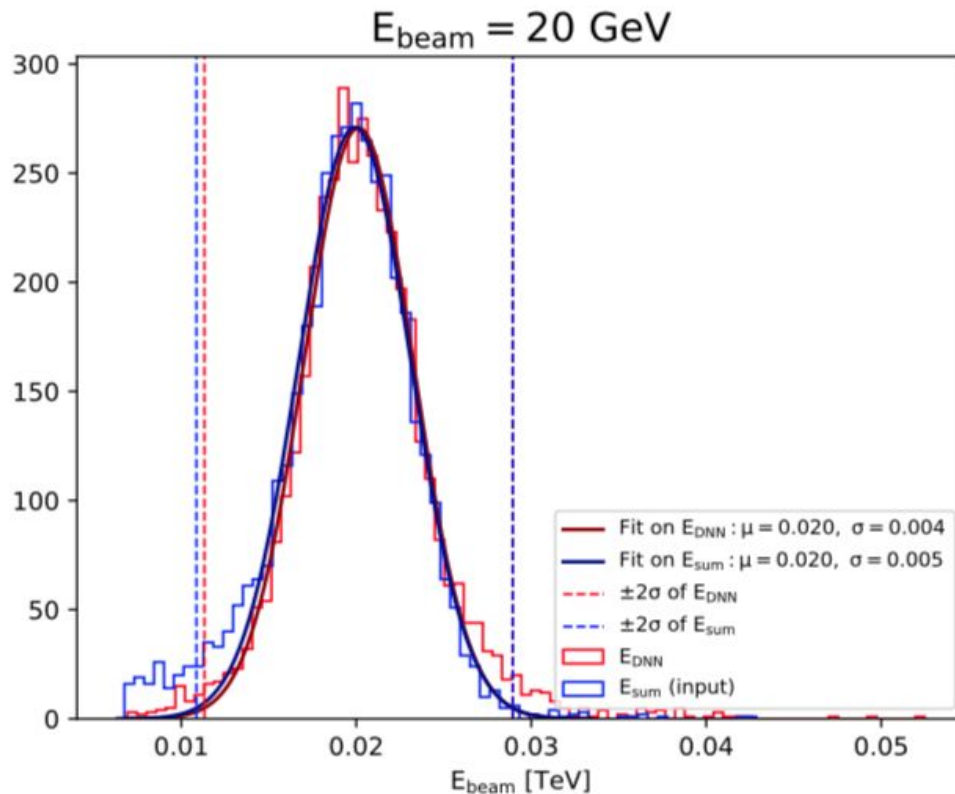
3D Conv



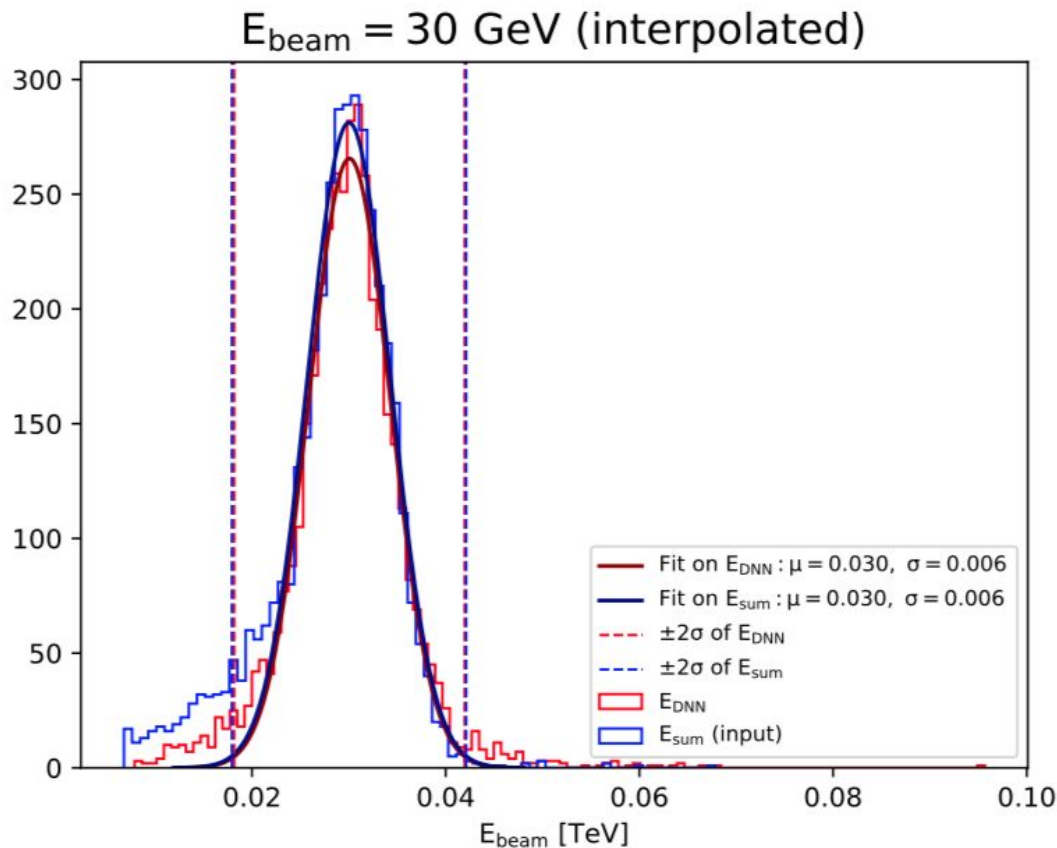
3D Conv



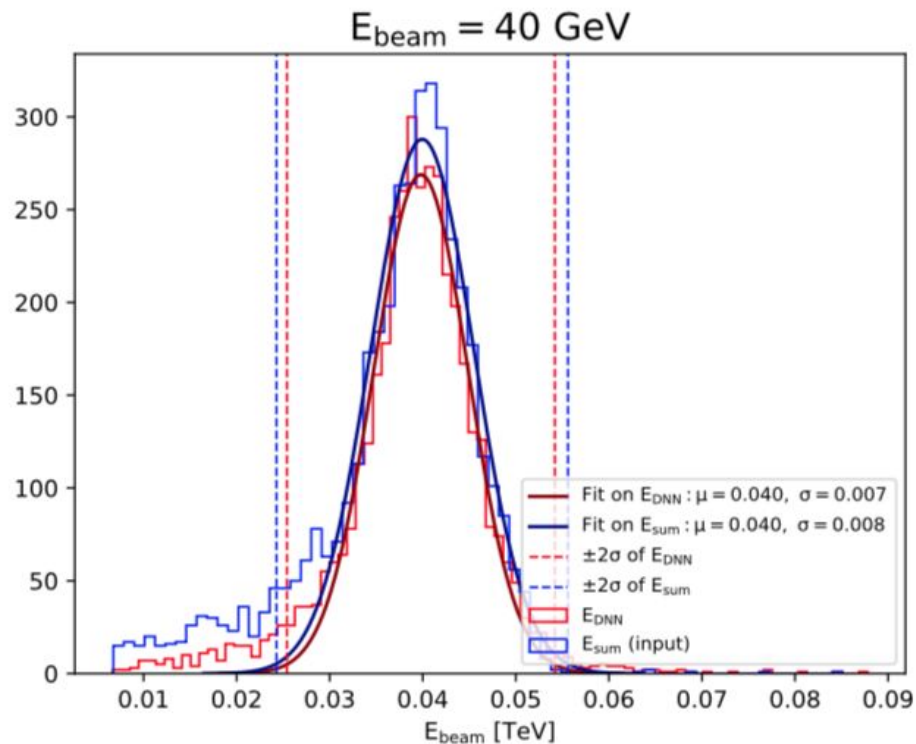
3D Conv



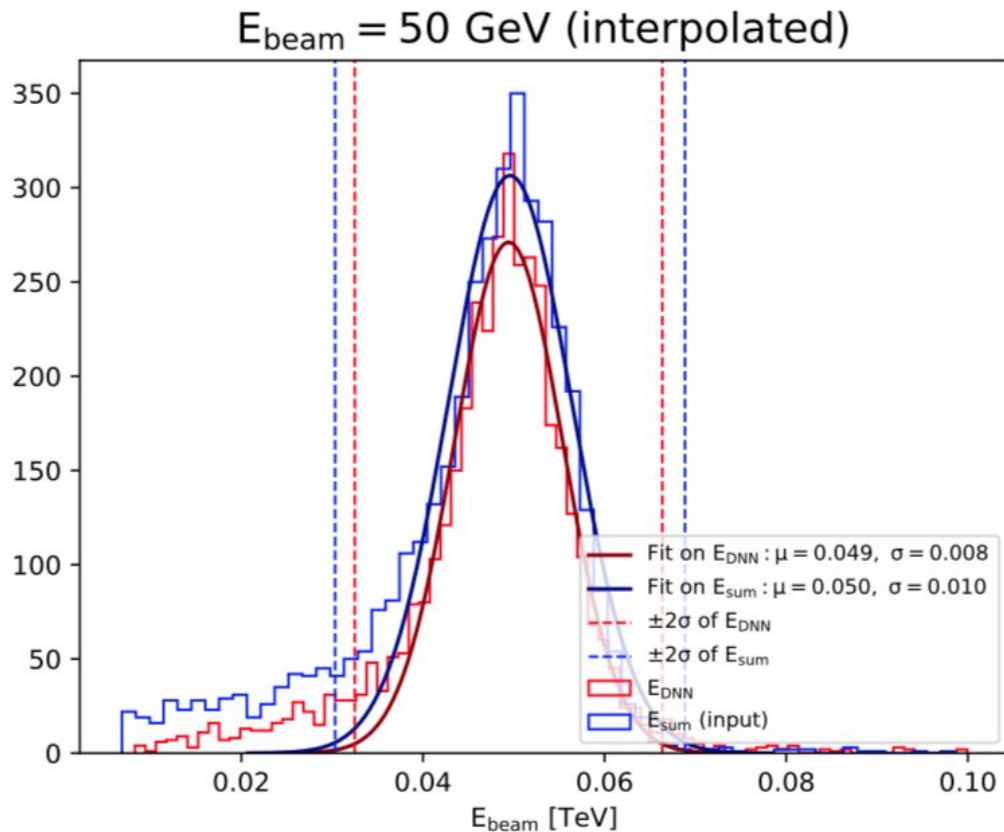
3D Conv



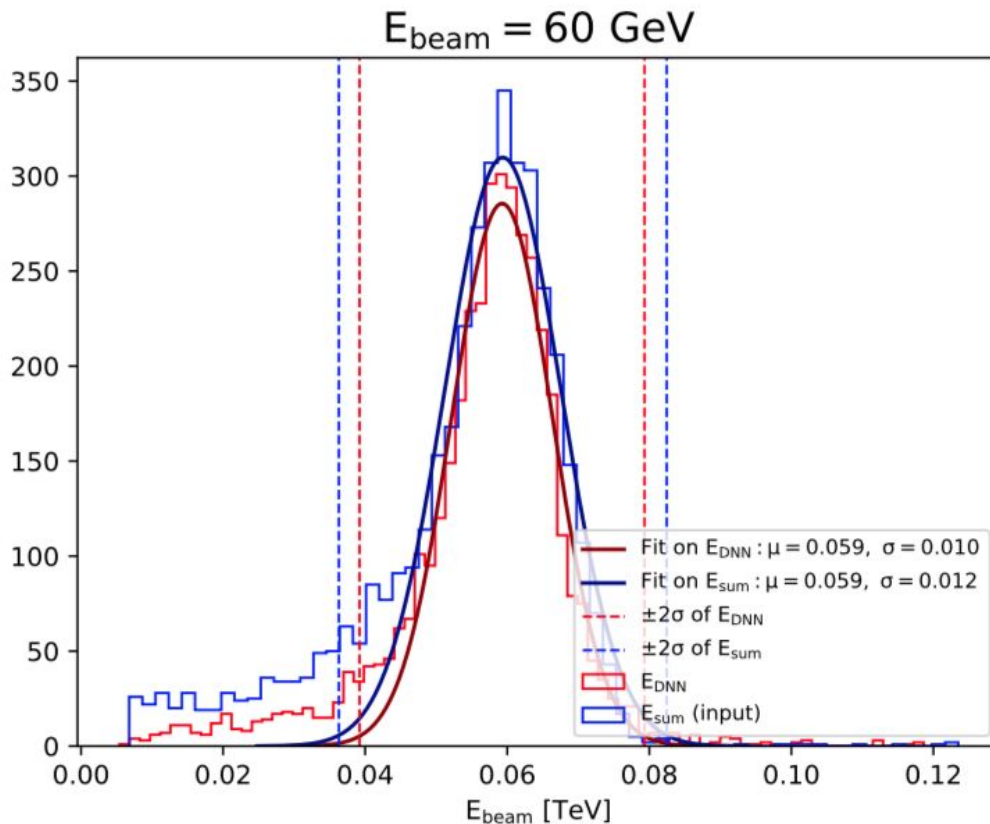
3D Conv



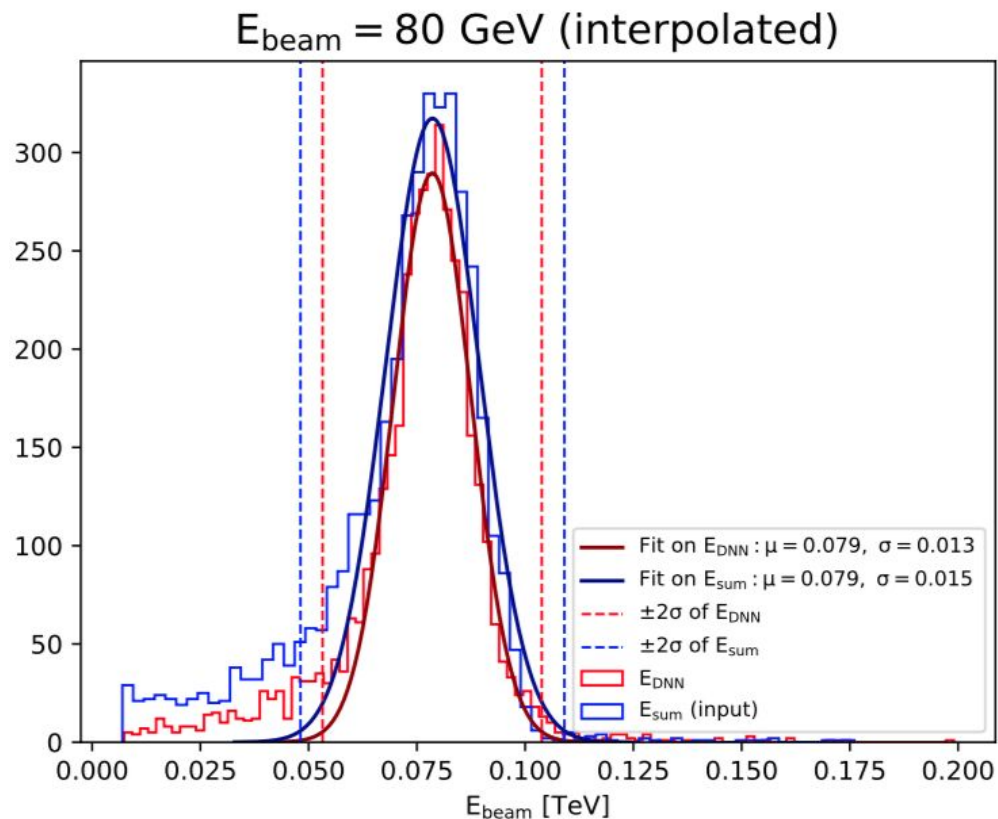
3D Conv



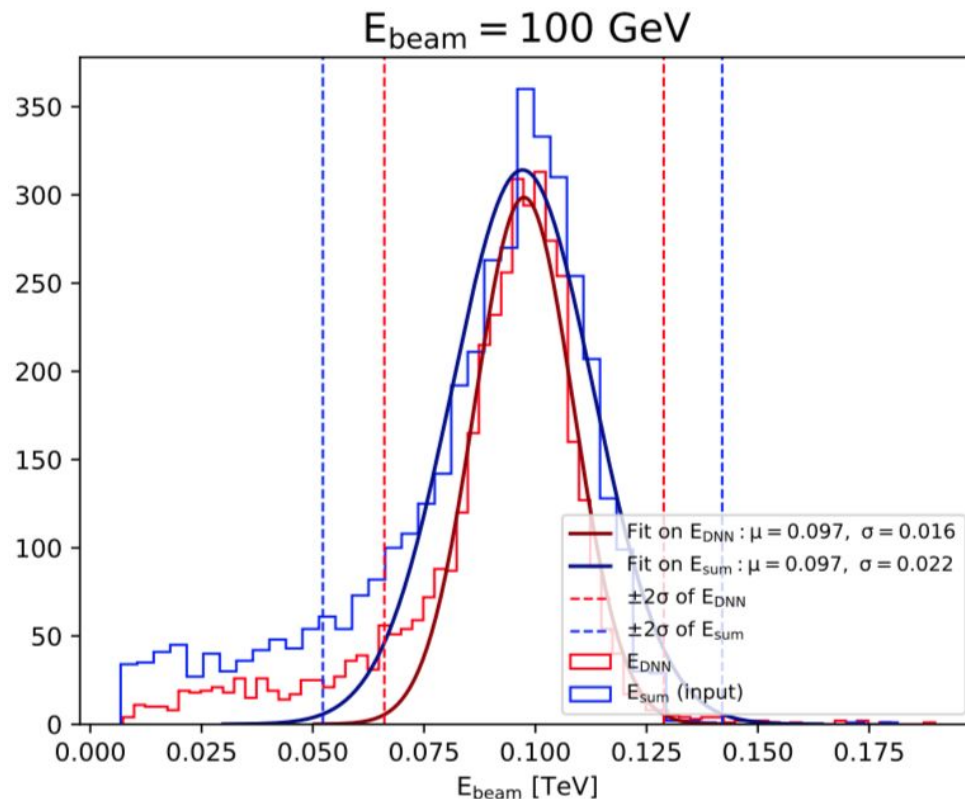
3D Conv



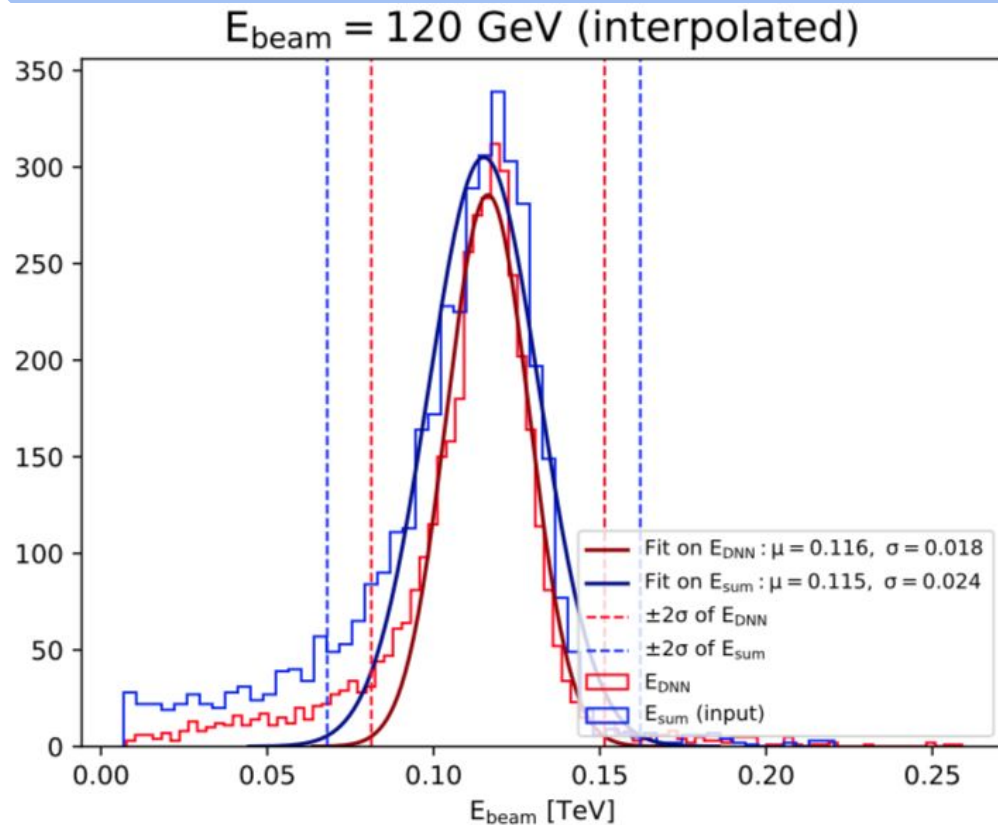
3D Conv



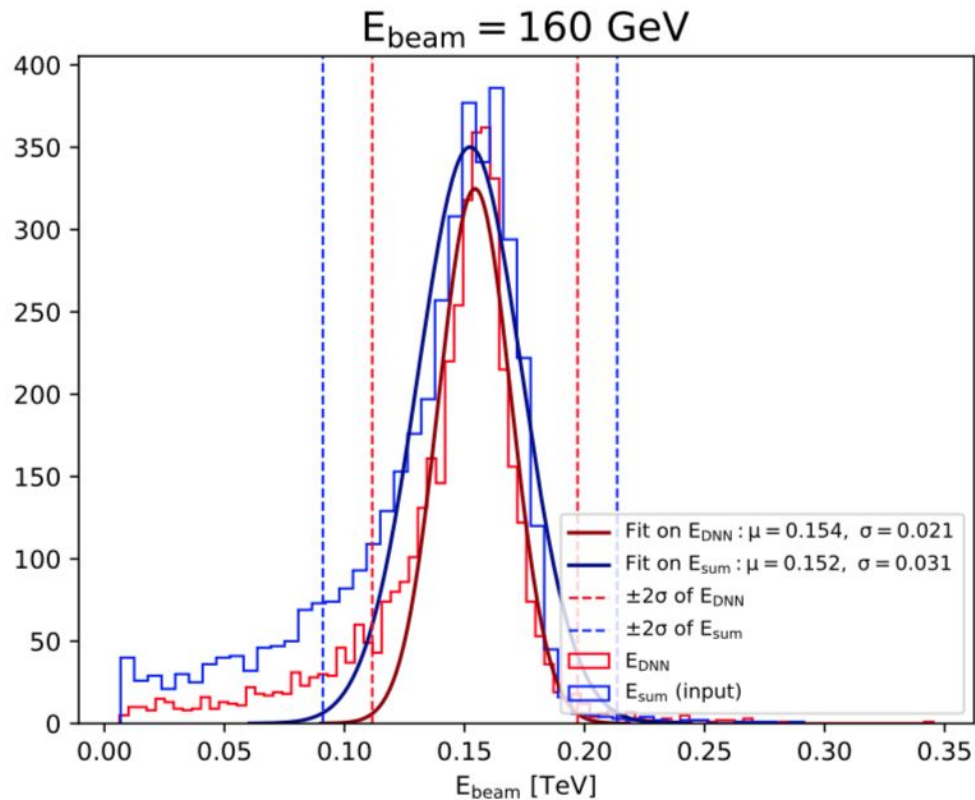
3D Conv



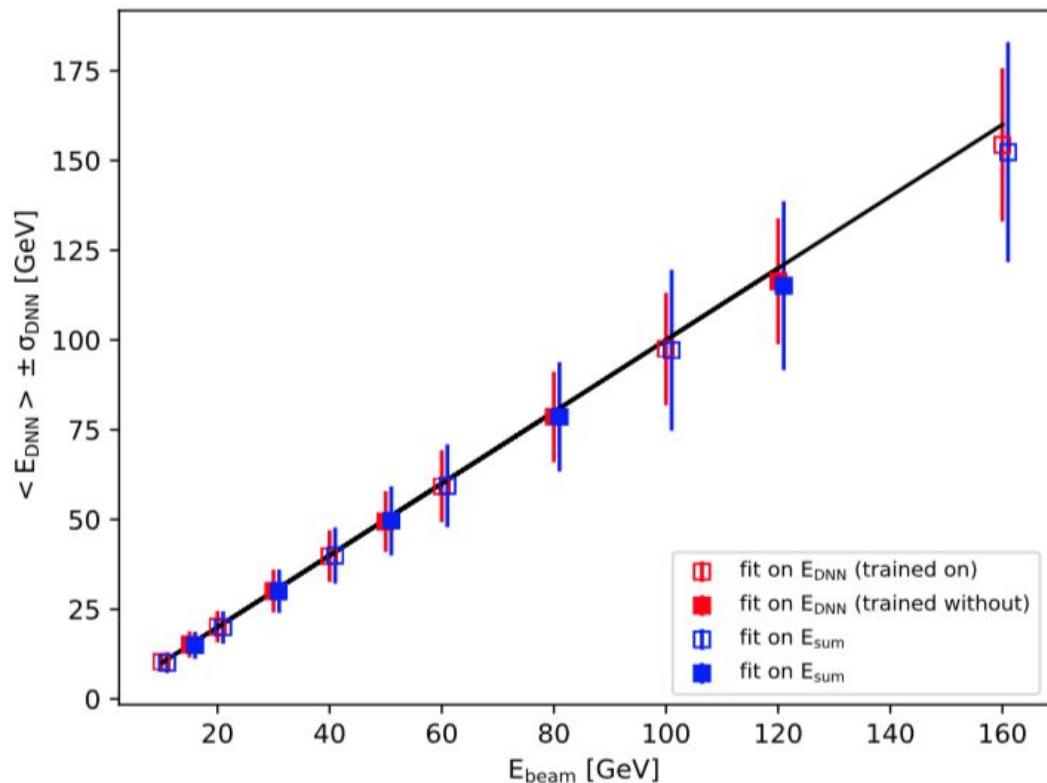
3D Conv



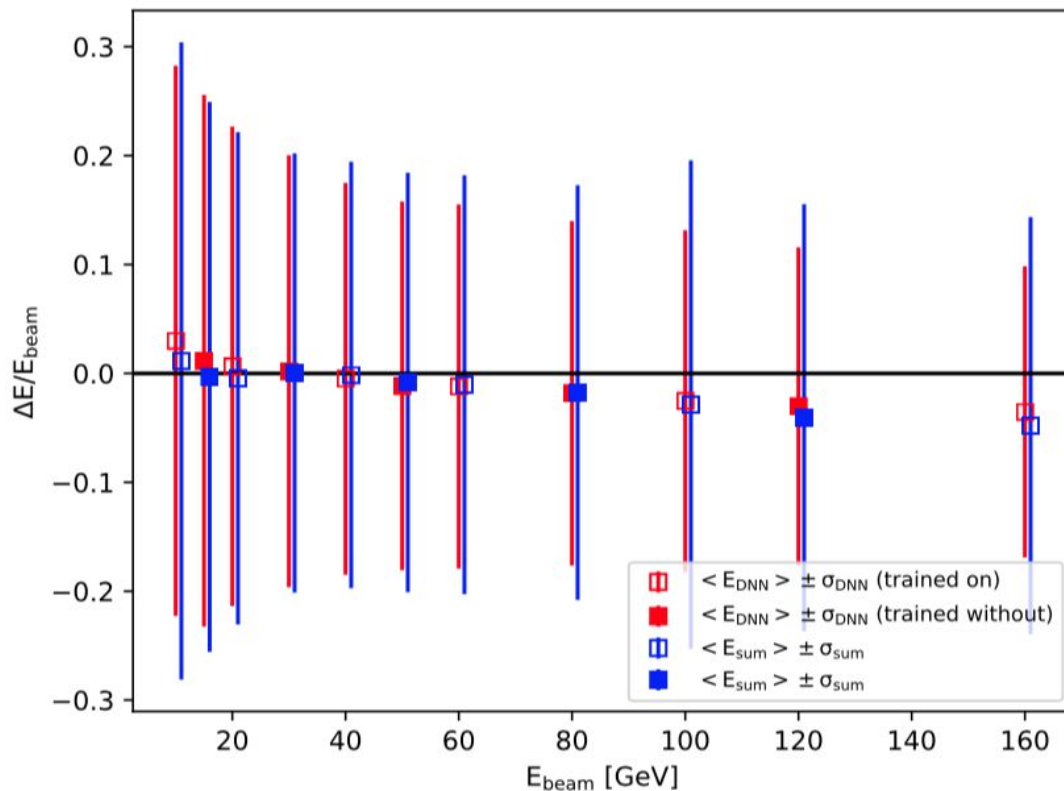
3D Conv



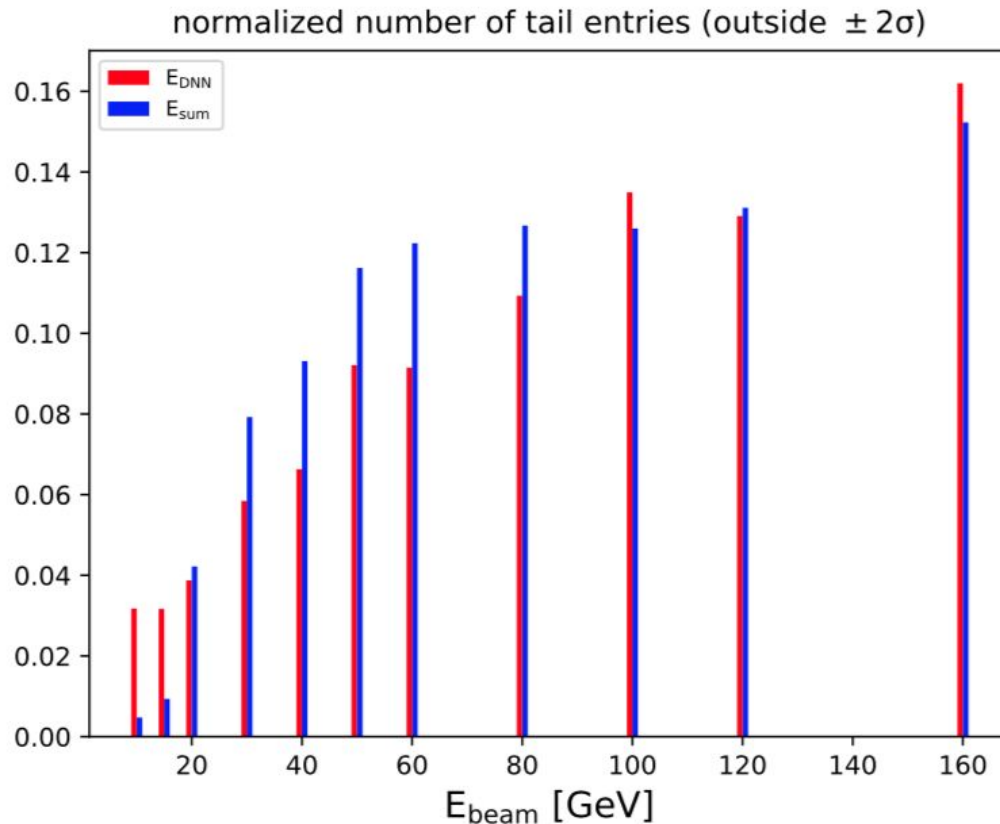
3D Conv



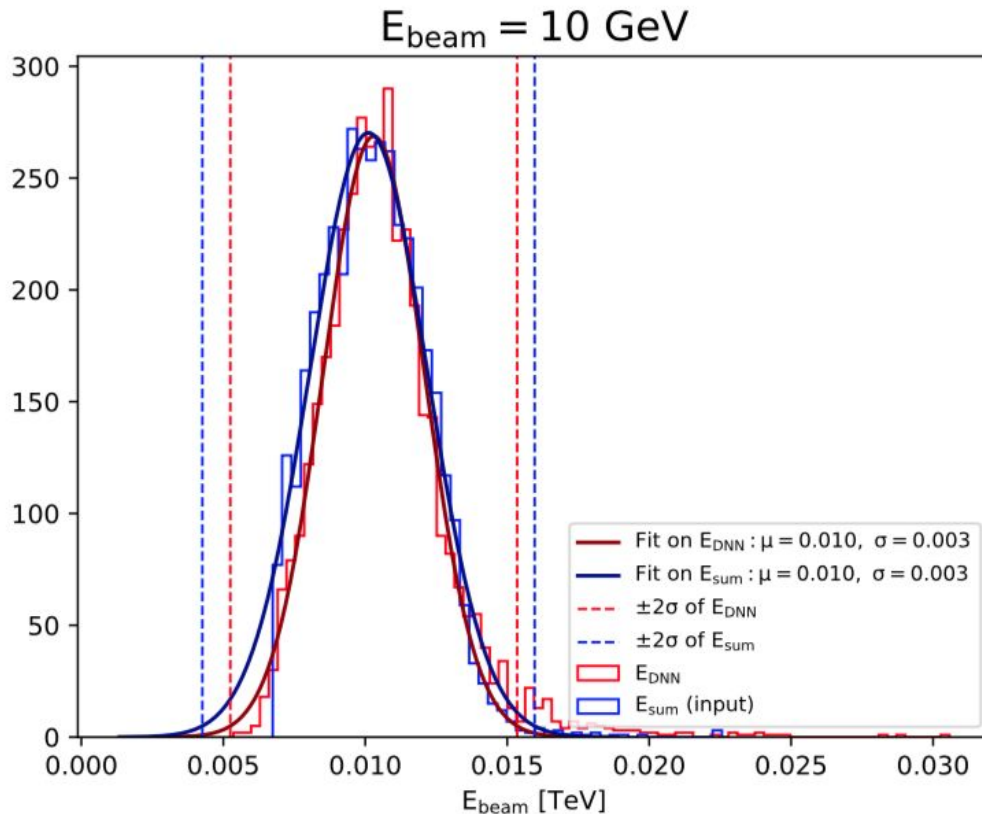
3D Conv



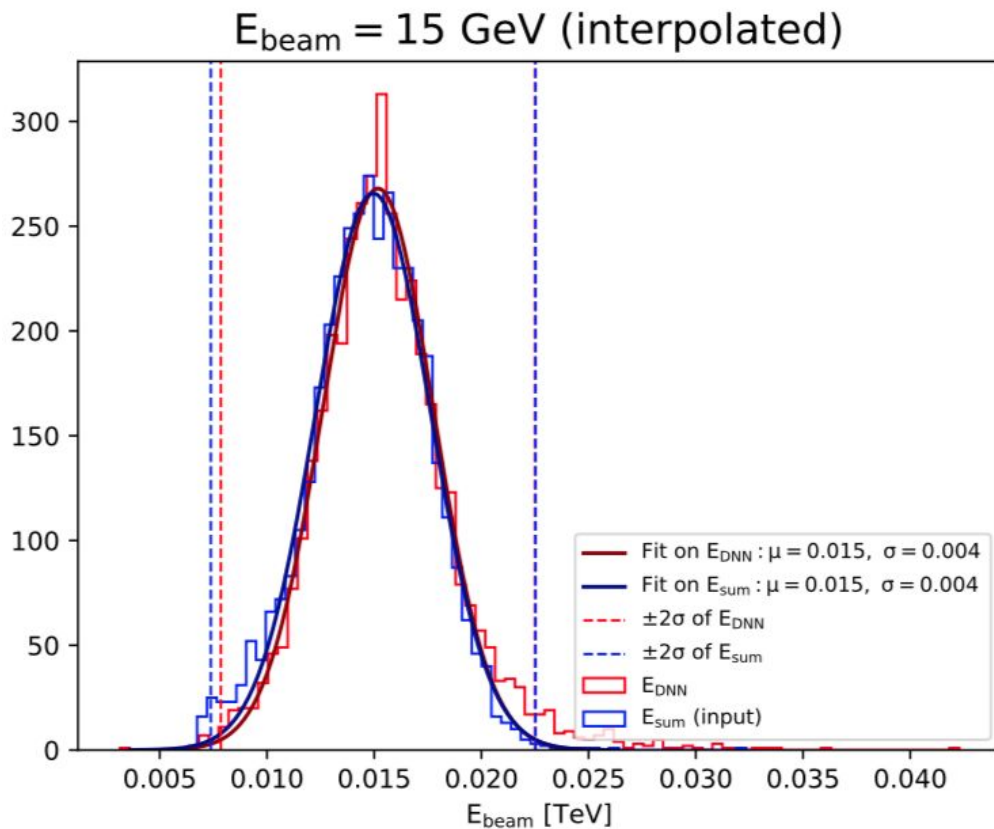
3D Conv



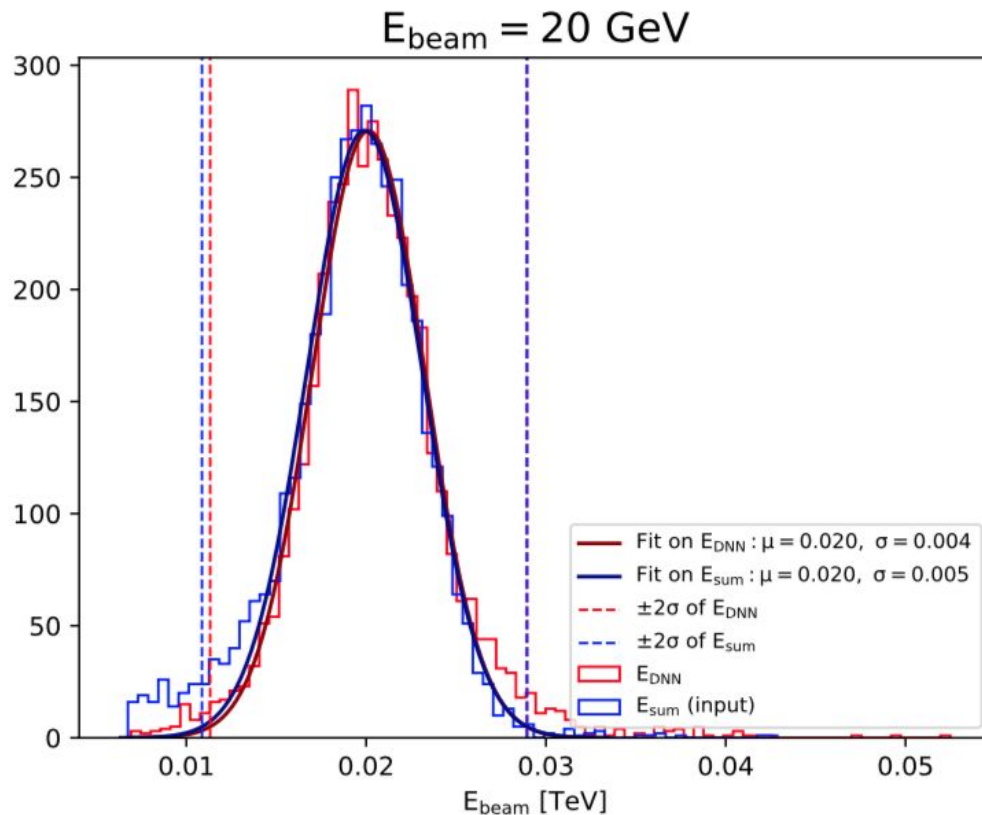
Locally Connected



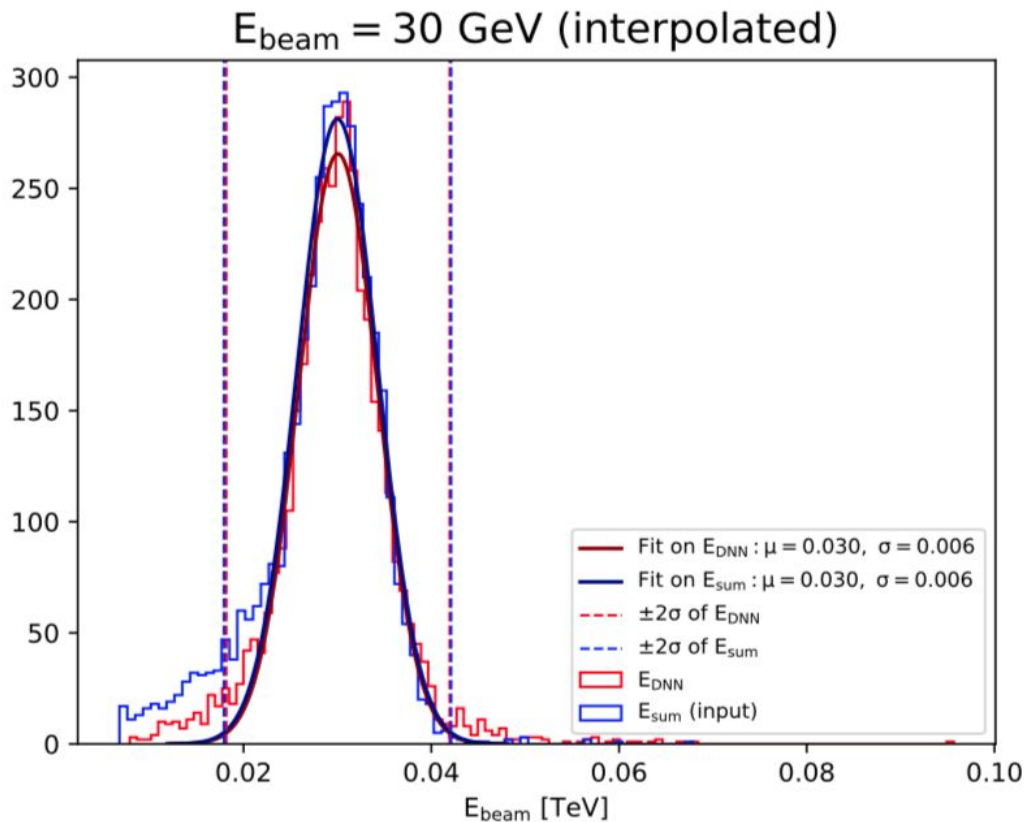
Locally Connected



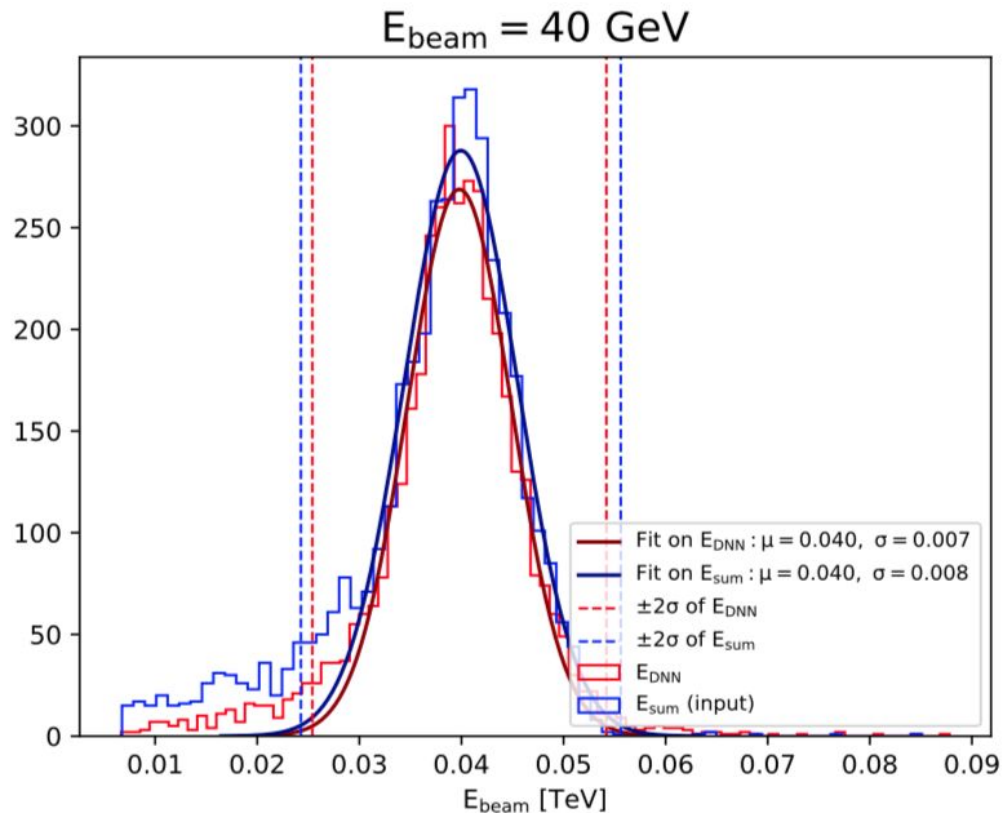
Locally Connected



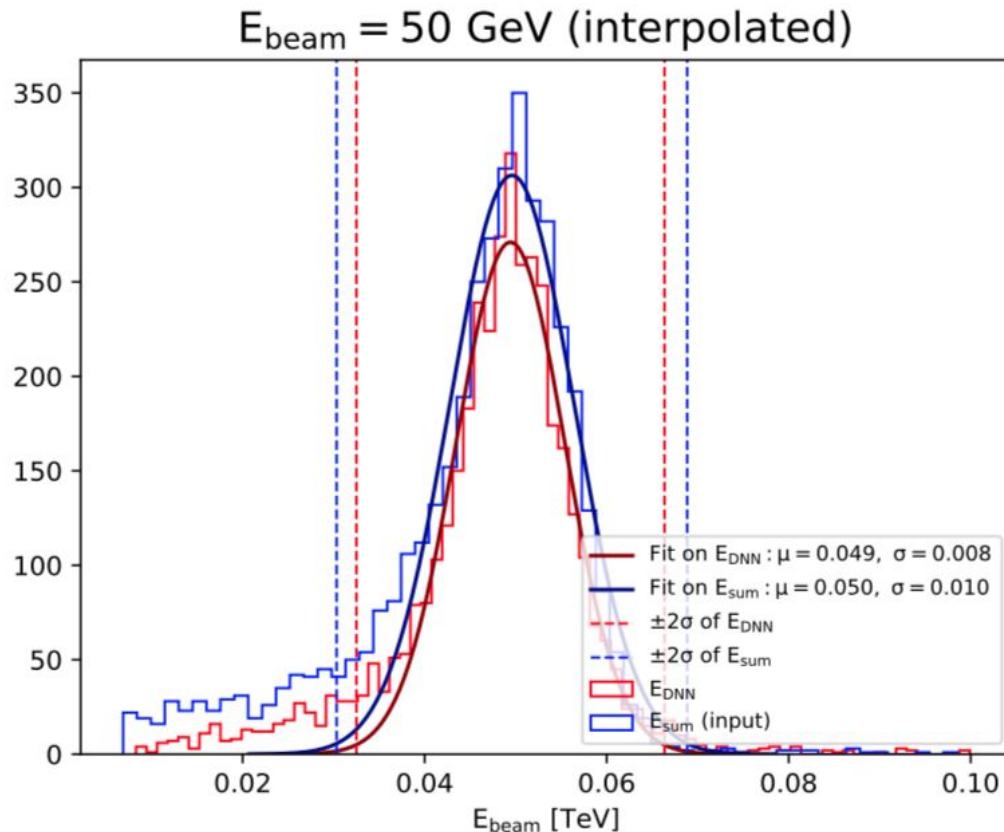
Locally Connected



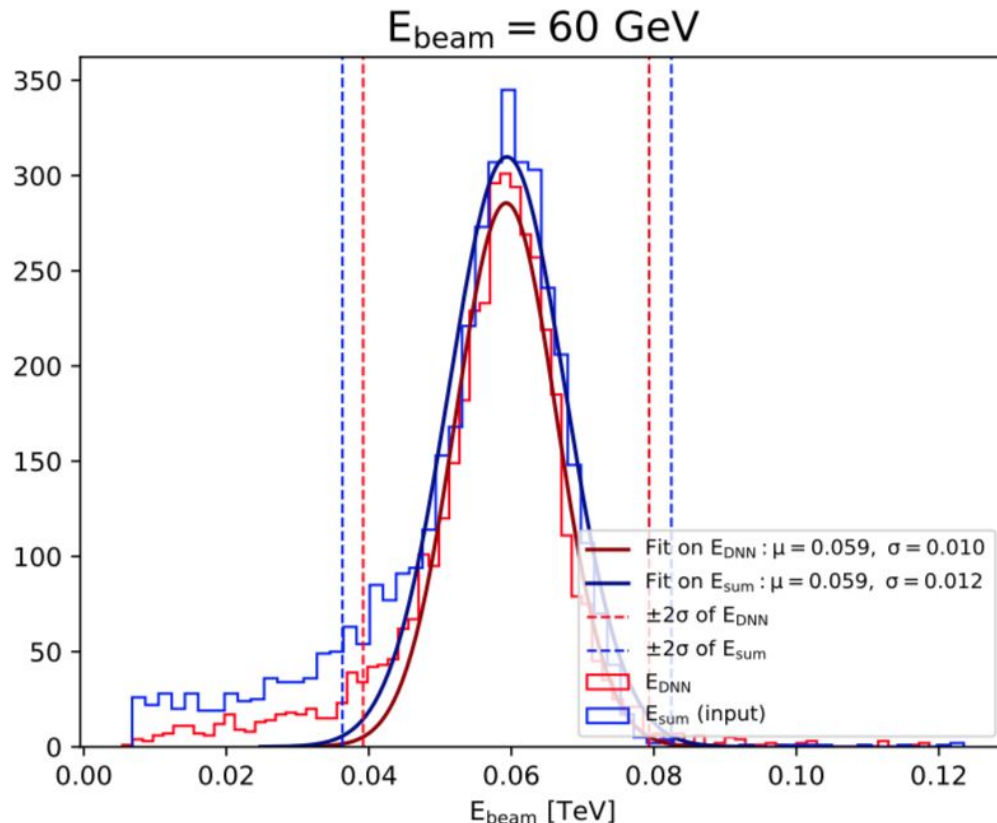
Locally Connected



Locally Connected

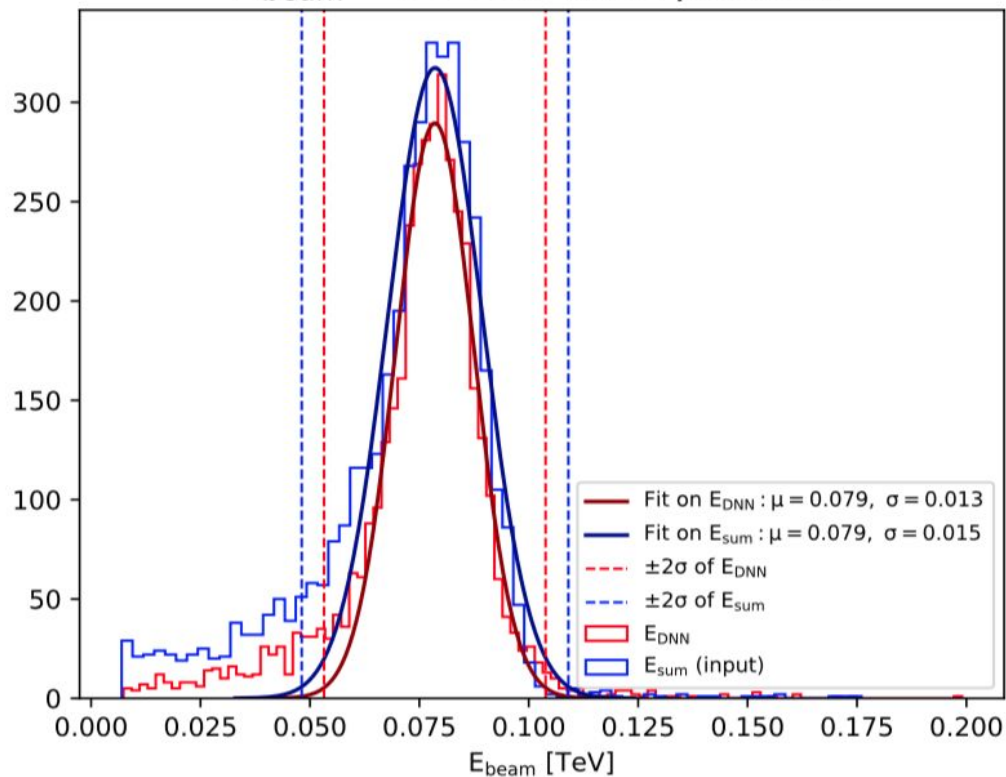


Locally Connected

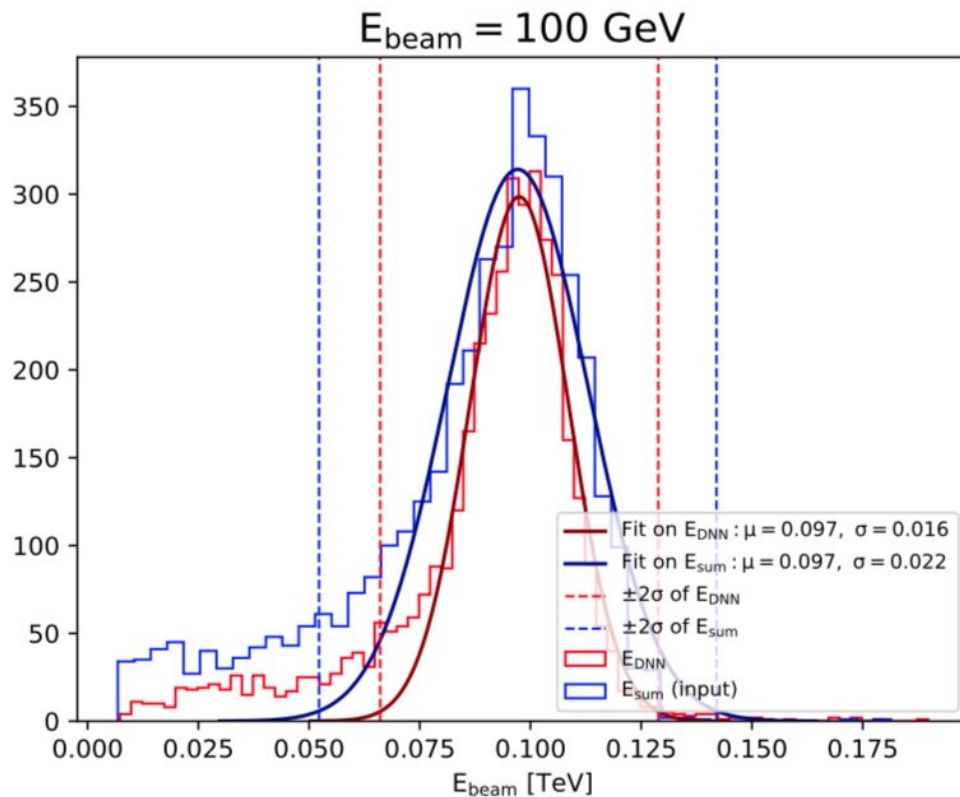


Locally Connected

$E_{\text{beam}} = 80 \text{ GeV}$ (interpolated)

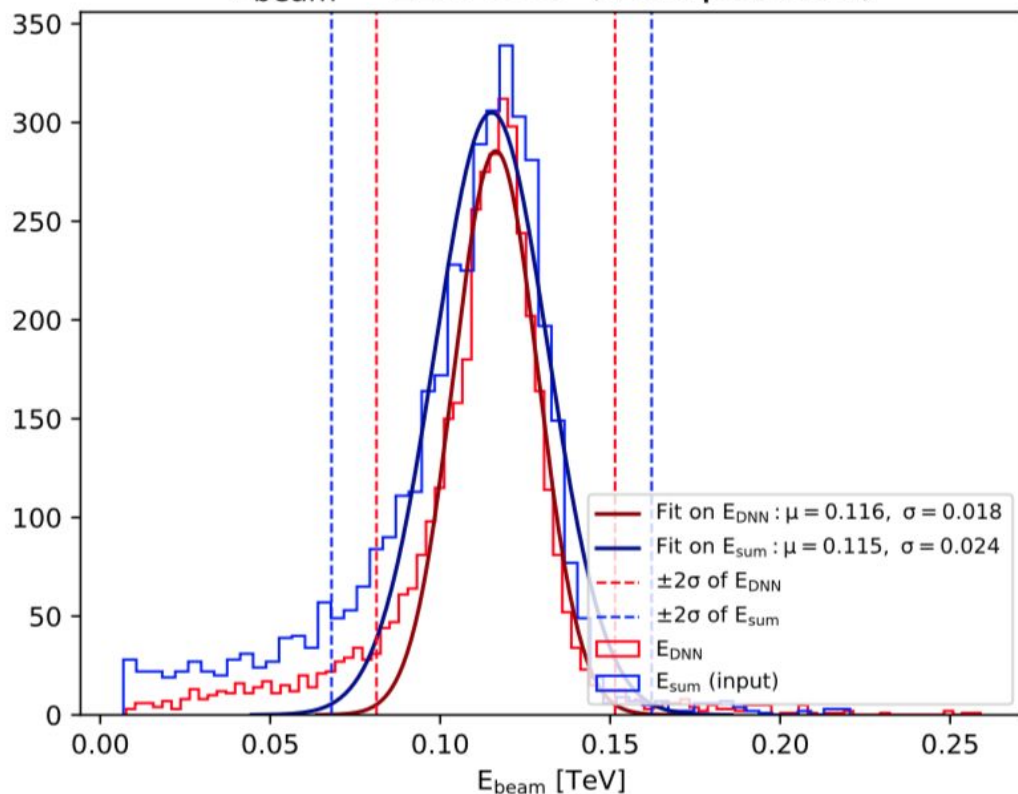


Locally Connected

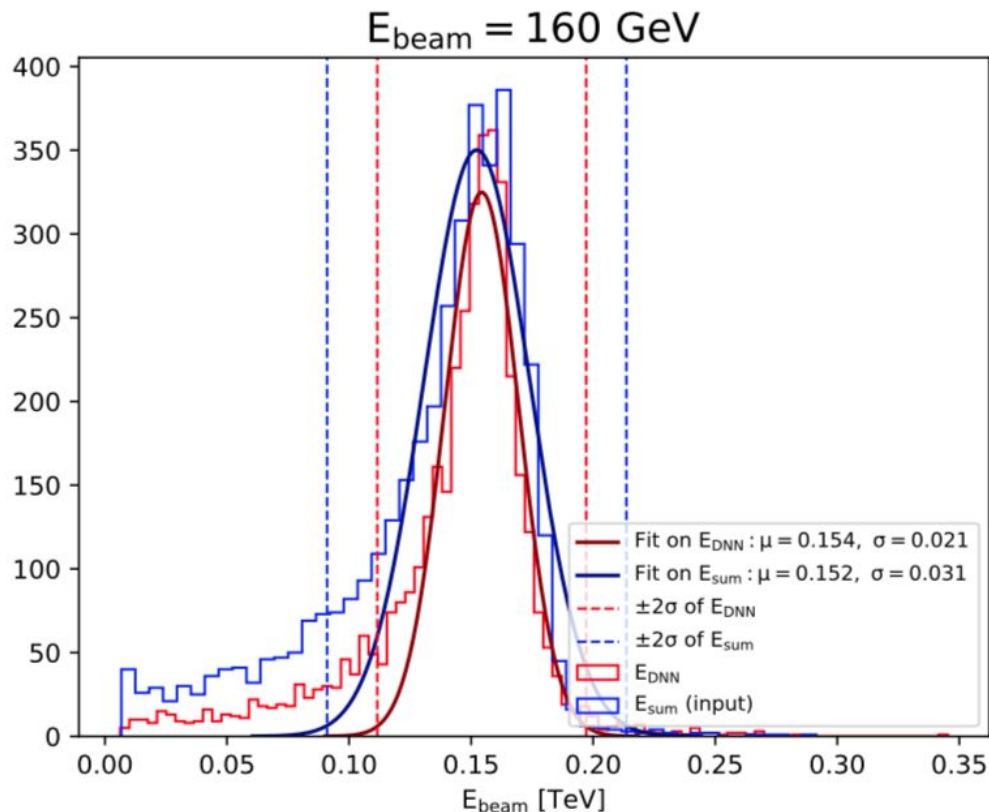


Locally Connected

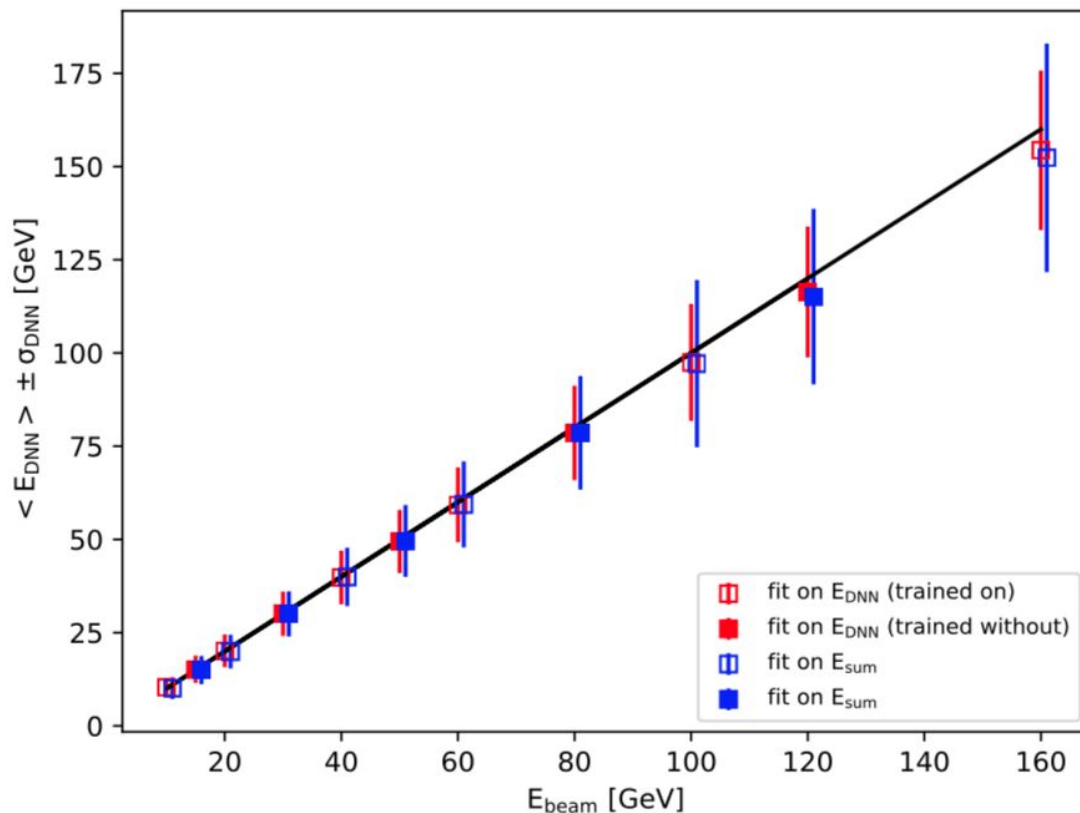
$E_{\text{beam}} = 120 \text{ GeV (interpolated)}$



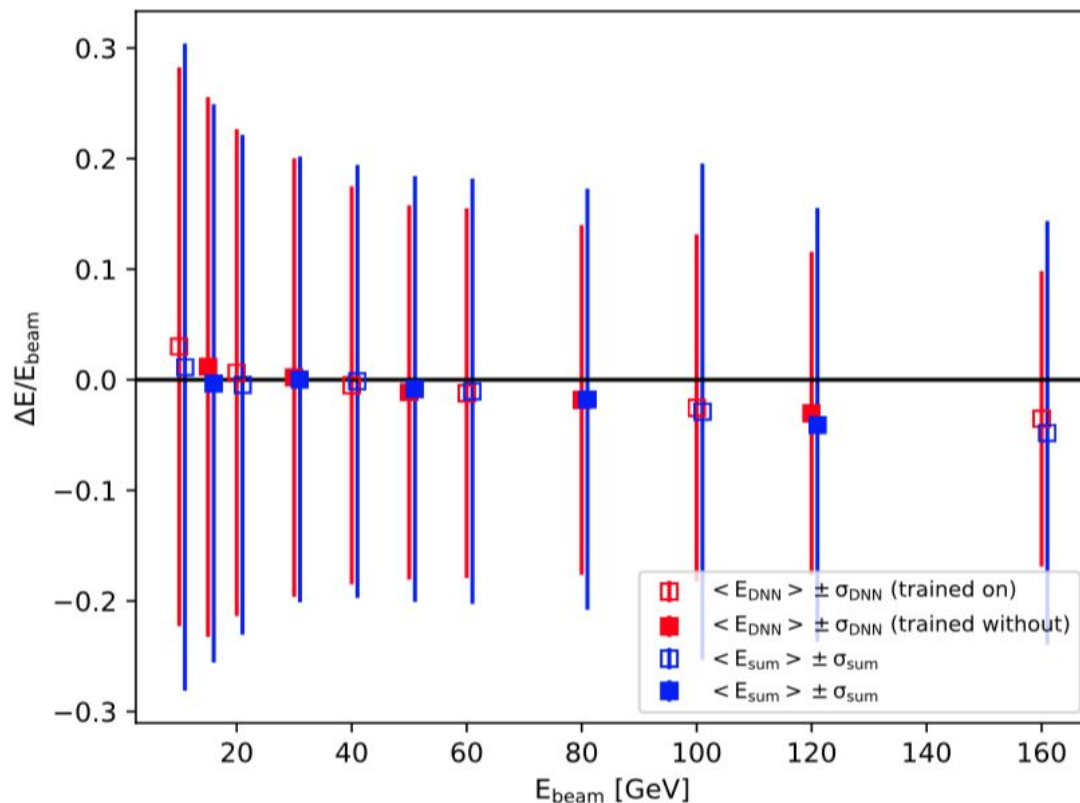
Locally Connected



Locally Connected



Locally Connected



Locally Connected

