To implement Lycoris for TPC distortion measurements

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TPC Distortion

In need of a reference tracker

- A broad energy spectra due to the energy loss in the magnet
 - to determine the momentum resolution
 - —> a **reference momentum measurement** is **in favor**;
- Distortions caused by non-perfect electric fields in particular close to ulletboundaries between modules
 - displaced hits —> impact on momentum measurements
 - —> a **reference position measurement** is **in favor**.

==> Guide us to an external silicon tracker









Lycoris in PCMAG with a LP-TPC

Funded by AIDA2020, in collaboration w/ SLAC

- A new large area strip telescope (Lycoris) in DESY beam area 24/1:
 - Status: R&D currently;
- Design comparible for LP-TPC
 - Suitable for a large prototype TPC in PCMAG;
 - Strip Silicon with pitch of 25 μm
 == ~7 μm spatial resultion;
 - Large active area (10 x 10 cm²) \rightarrow 90 - 96% particles (1 - 6 GeV);





Determine LP-TPC momentum resolution

Preliminary simulation study based on a 4-layer setup

- Simulated TPC momentum resolution
 - ▶ ~4.584 x 10⁻⁶ [1/MeV]
- To achieve a better resolution as a reference, and limited by space (<3.5 cm) to fit LP-TPC in PCMAG,
 —> Lycoris needs:
 - spatial resolution > 10 μm along bending direction Y;
 - Resolution along field direction Z less important: $\sigma_z > 1 \text{ mm}$

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Discussion

Measure TPC distortion with the Lycoris

- Lycoris, Software working status:
 - Reconstruction with Alignment software under development;
 - TBD: how to work with data from TPC
- TPC distortion measurements: ullet
 - Simulation study?
 - method?

Material based-on

- Felix Mueller: thesis doi:10.3204/PUBDB-2016-02659
- Dimitra Tsionou : internal note "Simulation Studies for a Silicon telescope in Test Beam area T24/1 accompanying the LCTPC prototype"



Thank you for your attention!









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- **KPiX** sync to **DESY** via a shutter signal generated by **TLU** to start the KPiX acq. cycle:
 - Status: tested/validated by feeding a manipulated shutter signal to KPiX.
- **KPiX** synced to **TLU** via a common TLU clock: <u>Status:</u> to test, new TLU exp. mid-June.
- **TPC** synced to TLU by counting triggers, so sync **TPC & KPiX** by a common start T 0 <u>Status:</u> to test, testbeam

exp. this fall.

Data Acquisition Overview

External trigger mode, used for TPC use case

- KPiX runs in pulse cycles, max. 4 evts/channel/cycle;
- Run control by EUDAQ2, implemented via a DAQ board; •
- Data Acquisition: \bullet
 - In each cycle, once a particle passing through:
 - PMT triggered —> TLU sent trigger to DAQ board
 - Trigger sent to all connected KPiX: ADC count on all activated channels recorded by KPiX;
 - End of a cycle:
 - <u>digitize</u> recorded KPiX data and send to DAQ board,
 - DAQ board <u>pack & send</u> to <u>EUDAQ2</u> via optic fibre.

Data Analyzing: EuTelescope

one analysis software candidate

Current status

- no tracker data available to prepare code for the test beam campaign forseen this fall;
- need to prepare analysis code in parallel to catch up the scheduled delivery 01/2019;
- Flow chart based on EuTelescope of lacksquareATLAS ITk version
 - binary readout, no pedestal DB used;
 - only one strip layer as DUT w/ Mimosa;
 - Raw to LCIO converter: <u>done</u> in EUDAQ side;
 - Other modules: to be tuned;
 - 11/05/2018: successfully installed under ILC NAF condition (finally).

Data Analyzing: EuTelescope

one analysis software candidate

Strategy

- 1st step target: analyzing data w/ Mimosa. ●
- <u>Todo</u> list: \bullet
 - Try out with ATLAS data for ideas to <u>tune</u> data converter, as well as other modules;
 - pedestal DB: noise suppression development w/ ECal data.

Data Analyzing: EuTelescope

one analysis software candidate

A comprehensive set of MARLIN processors. Each reconstruction step has a steering file containing multiple processors

– converter(noisypixel): converter (determine noisy pixels/strips)

- **clustering**: retrieve the geometry of the sensor and give the coordinate of the strips/pixels center; group nearby strips/pixels together with noise pixel/ strips removed

- hitmaker : find the cluster center to give the hit position

– **patternRecognition** : attach hits from planes together to form a track

– **GBLAlign** : determination of transformation from global frame to each local plane frame

- **GBLTrackFit** : fit of the track using hits attached together from pattern recognition

Project Overview

Milestones to achieve before delivery

- Key target: convey a 1st user analysis —> testbeam w/ TPC forseen in fall 2018:
- Hardware to be ready: ullet
 - **Mechanics** for final system: well track to be on time (see Uwe talk);
 - Make assembled Lycoris sensor **module** work (see talks from Uwe & Sebas);
 - **New DAQ board** exp. 18/06/2018: 1-2 weeks to SLAC to learn & test;
 - **New** AIDA2020 **TLU** exp. 06/2018: both hardware & software to test, and w/ new DAQ board;
- Software to be ready: •
 - Lycoris module works w/ TLU + mimosa on simple e-lab tests: EUDAQ2 to be ready;
 - Alignment, characterize module w/ mimosa: beam time needed
 - event definition and EuTelescope to be ready.

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in progress

TBD

TLU integration: KPiX sync to DUTs DUT syn to TLU

In general, DUTs can be categorized: sync to TLU or not

- 1. a DUT sync to the TLU:
 - The **TLU** common **global clock** to sync all devices;
 - Activation (shutter) issued by TLU
 - Busy signals (TLU state idle) to TLU: either global or local
 - <u>Global</u>: no trigger when any device is busy;
 - Local: trigger continuously issuing though some device busy

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Shutter: activation signal T0_sync: 1 per run, common start signal

TLU integration: KPiX sync to DUTs DUT unsync to TLU

In general, DUTs can be categorized:	clk			
sync to TLU or not;	T0-sync			
1 a DUT sync to the TIU.	Timestamp Emin	<u> </u>	_X_	
$2 \rightarrow DUT$ upconcite the TUU	Shutter			
z. a DUT unsync to the TLU:	Particles	 		
 Synchronization by trigger 	TLU state			
counting,				
Global busy used: no trigger sent	, clk	<u> </u>		
when either device is busy;	Timestamp	, (0	\ γ	1
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Add-on TLU func: configurable **delayed** TLU active period

Status:

- TLU state • new TLU will be issued by end of this month;
- a first use case needed to test.

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	-				
Trigger					
TLU state					
clk			1		
T0-sync	1 1 1 1 1				
mestamp			0		1
Emin	1 1 1 1 1 1			1 1 1 1 1	
Shutter	- - - - - - -	-		- - - - - -	
Particles	1 1 1 1 1 1	1		1 1 1 1 1 1 1	
Trigger	1 1 1 1			1 1 1 1	

Shutter: activation signal T0_sync: 1 per run, common start signal

