



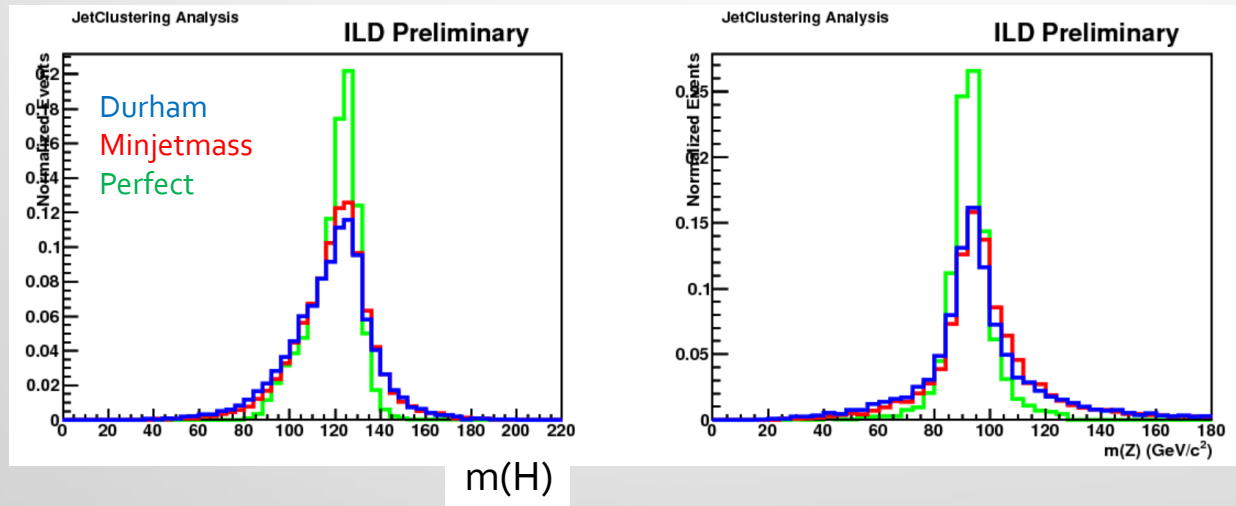
Construct Deep Jet Clustering

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Introduction

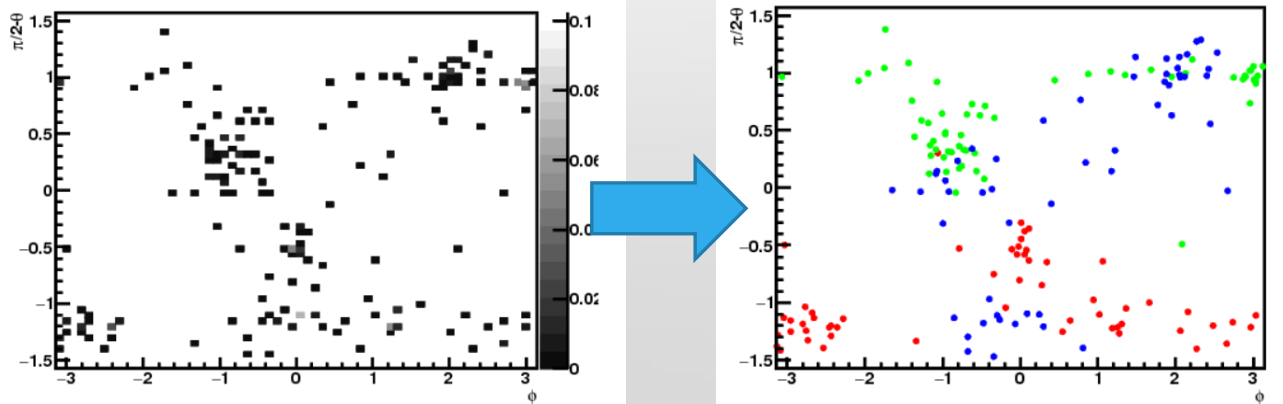
- Jet clustering is one of the main key to obtain better physics results
 - Physics results are strongly limited by mis-clustering
 - To obtain correct jets leads to improve the mass resolution of the resonances
- Present jet clustering is far from good tool for reconstructing jets
 - e.g. Higgs self-coupling@500GeV(ZHH): $\sim 40\%$ improvement if perfect!



- Even at 250GeV, clustering is very important
 - Separation of ZH/ZZ/WW in hadronic events

Use CNN for automatic colorization

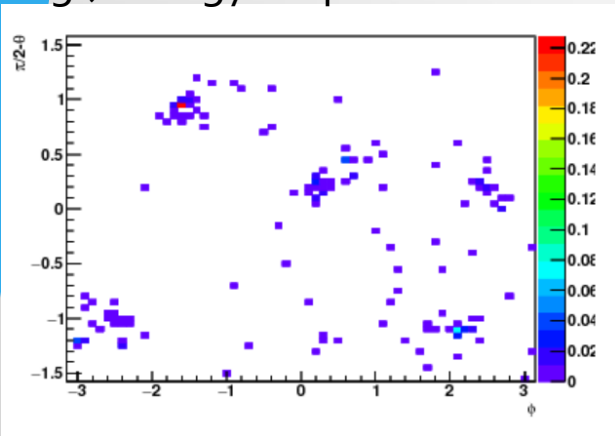
- For jet clustering, we need the global and local information for each event
 - Global: Where is the large energy located?
 - Local: Correlation between neighbors or large energy area?
- Using **Convolutional Neural Network**(CNN), we will extract both features
 - Encoder-Decoder type CNN is used (calls as u-network, mention later)
- Clustering is equivalent to “colorize” each particle in the same cluster
 - Grey scale \Rightarrow color
 - So, Automatic colorization is worth trying for jet clustering



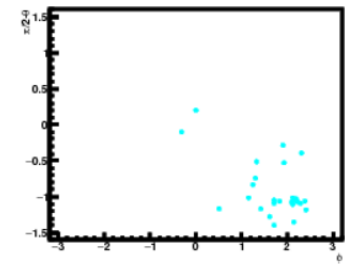
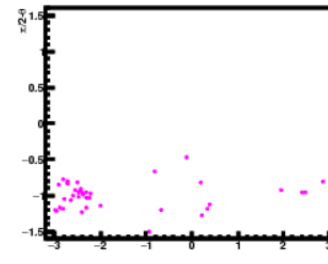
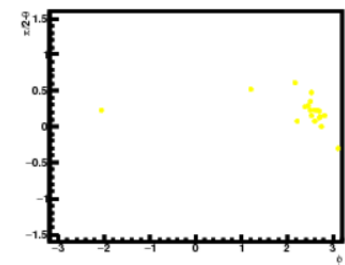
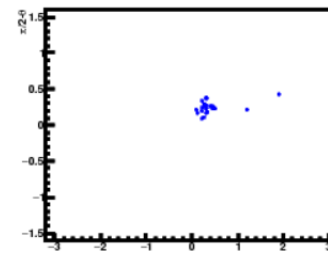
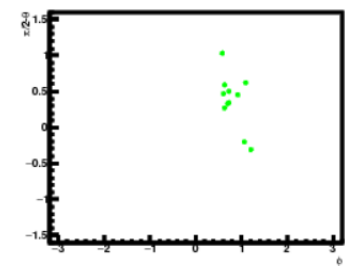
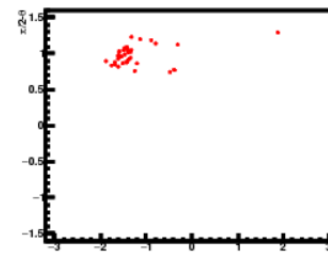
Trial

- Use Keras & tensorflow backend
- Using a certain map(s) of each event, estimate color of each track
 - Do not consider color-singlet state

Input(64×64 pixel figure)
e.g.) energy map



Output(64×64 pixel figure)

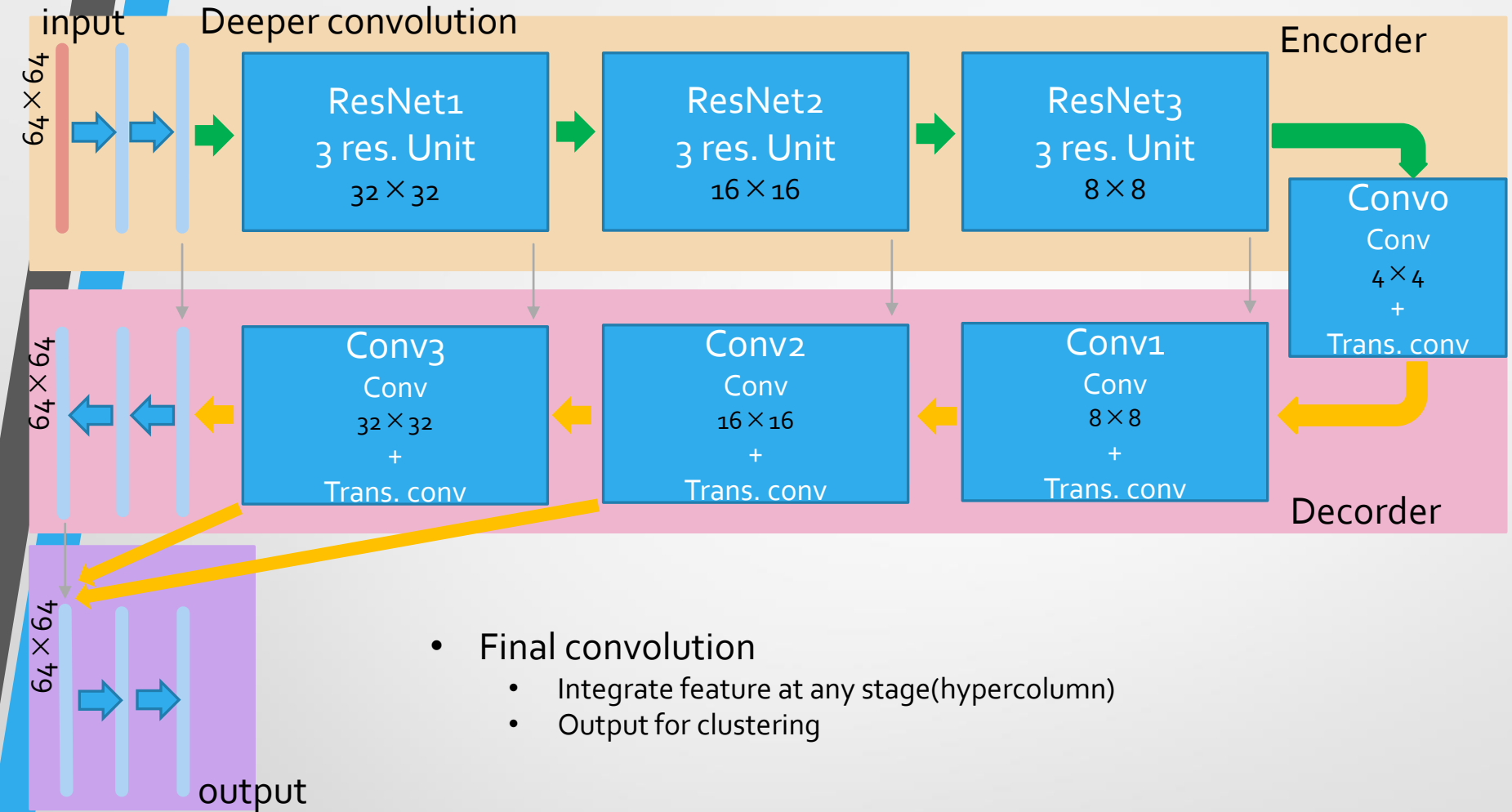


9 input images
Energy map
Charge map
Dosig map
Zosig map
Ecal map
Hcal map

+ direction vector(x, y, z)

+ no particle

Network Architecture



- **Final convolution**

- Integrate feature at any stage(hypercolumn)
- Output for clustering

- **Encoder**

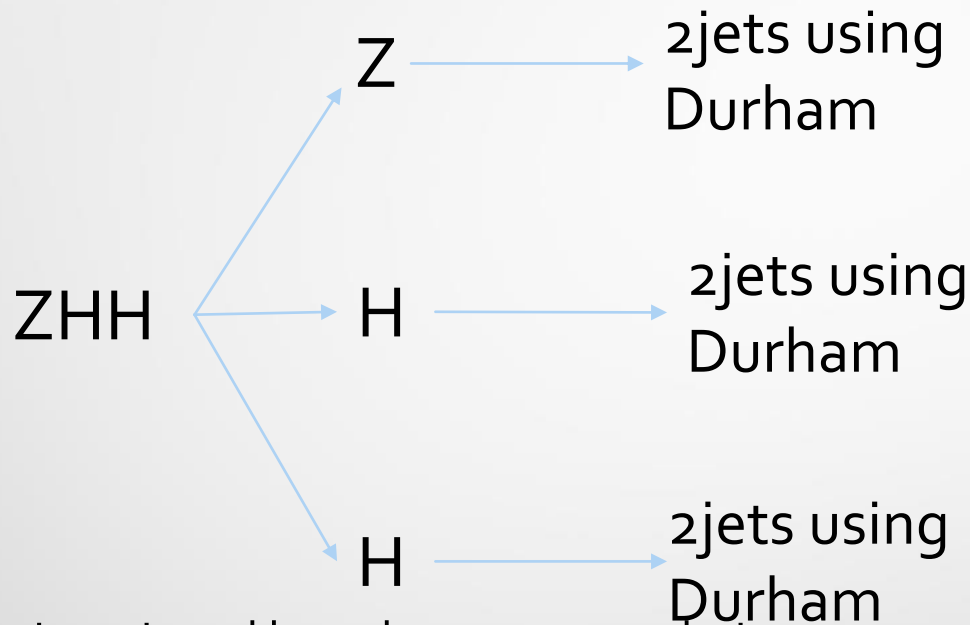
- Extract global & higher order feature
- Downsample to make network robust for distortion & shift effect
- Lost position information

- **Decoder**

- Propagate obtained feature to local
- Upsample to recover position information
- Merge encoder nodes to get precise position information

Create answer

- Supervised learning - Create "answer" jets: perfect Durham jet clustering



- Number is assigned based on energy ordering
 - Highest energy jet number is 0, lowest energy jet number is 5

So far, do not consider color singlet state: number of jets is 6

$ZHH \rightarrow (qq)(bb)(bb) \rightarrow 6\text{jets}$

Basics: How to train a network

- A network is trained to minimize **loss function**
- If output of the network is probability, cross-entropy is a popular loss function

$$L = -\frac{1}{n} \sum_n \sum_i t_i \log y_i$$

- Answer is zero(data does not belong to this node) or one(data is belong to this node)
- Only one node is 1, the other nodes are 0 (one-hot vector)
- Smaller value of L means better performance
- Considering better loss function is one of the important points to obtain better performance

Output

$$\sum_i y_i = 1$$



Answer

0 or 1



Pseudo-labelling

- Output: inference of the probability of the color to be assigned
 - $\sum y_i = 1.0$

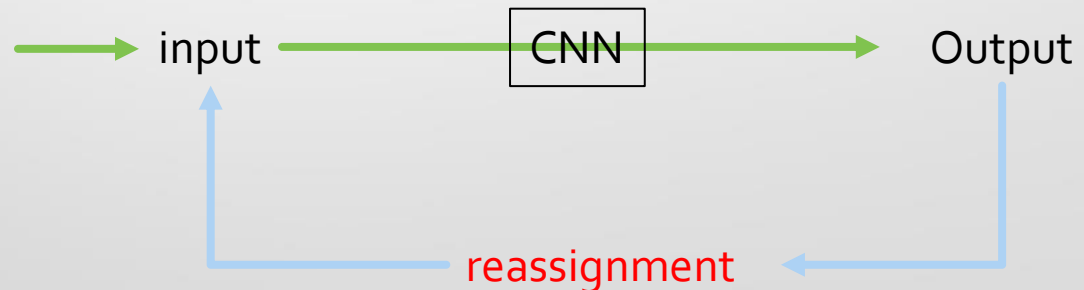
output



- The combination of color assignments is arbitrary, so assign them so that the loss function is minimized.
 - Using preliminary results after a training, re-assign the color combination
 - Minimize cross entropy $L = \frac{1}{n} \sum t_i \log y_j$

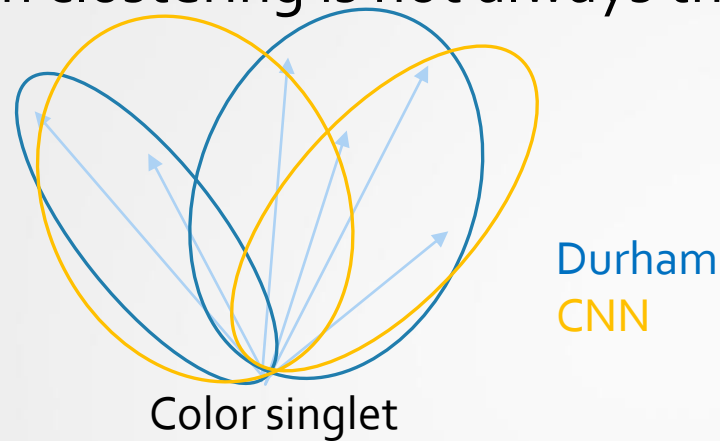
Start:

Energy ordering
Of jets



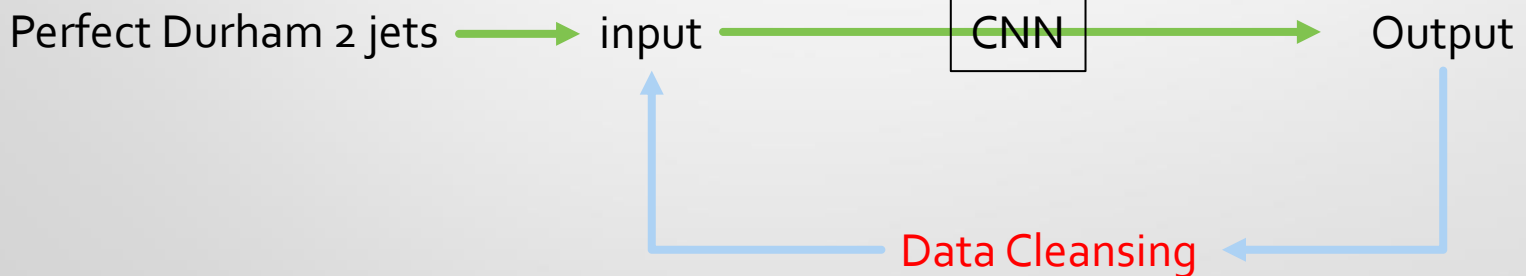
Data Cleansing

- Perfect Durham clustering is not always the best clustering into 2 jets for CNN



- By using the preliminary training weights, clustering into 2 jets is performed

Start:



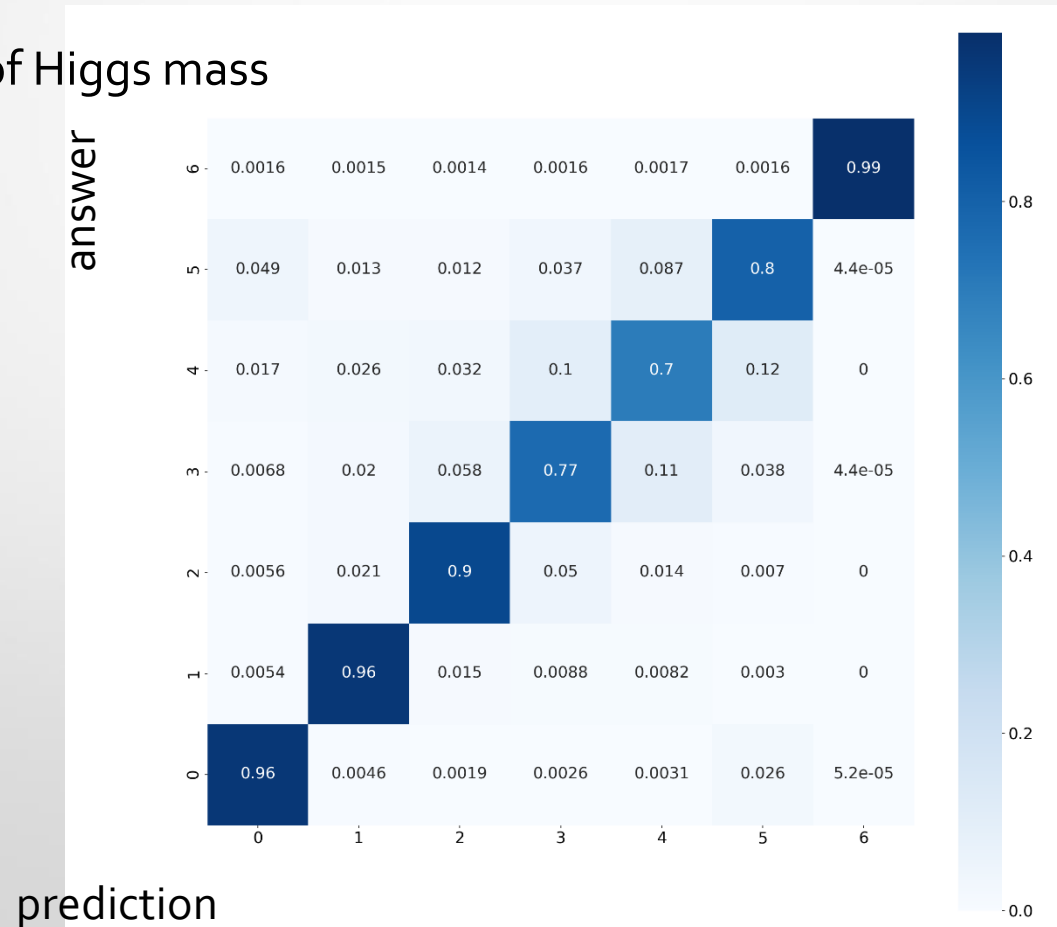
Clustering particles to make loss function minimum

status

- Use $ZHH \rightarrow (qq)(bb)(bb)$: 6jets clustering
 - q: uds + c + b ratio: 9:9:5 need to consider the effect of flavor ratio
 - If a network can really feel flavor
- Use 230000 events for training(207000 train, 23000 validation)
 - Very weak or no over fitting can be seen between train vs. validation
- Don't consider color singlet state for network training
- Input: 6 + 3 images output: 6 + 1 images

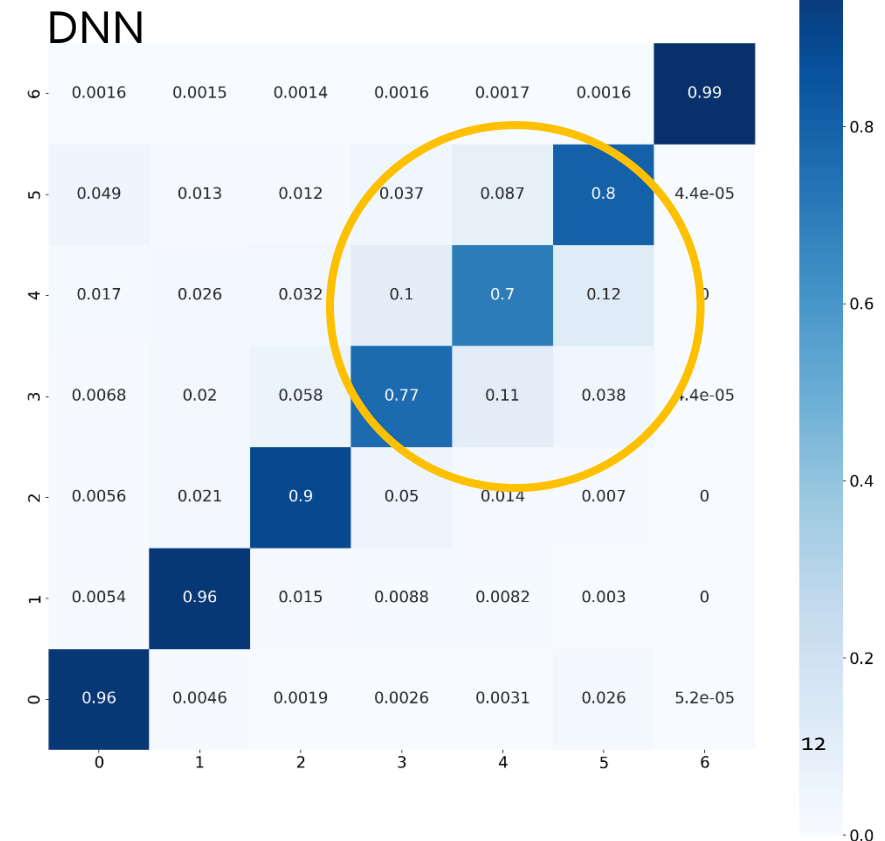
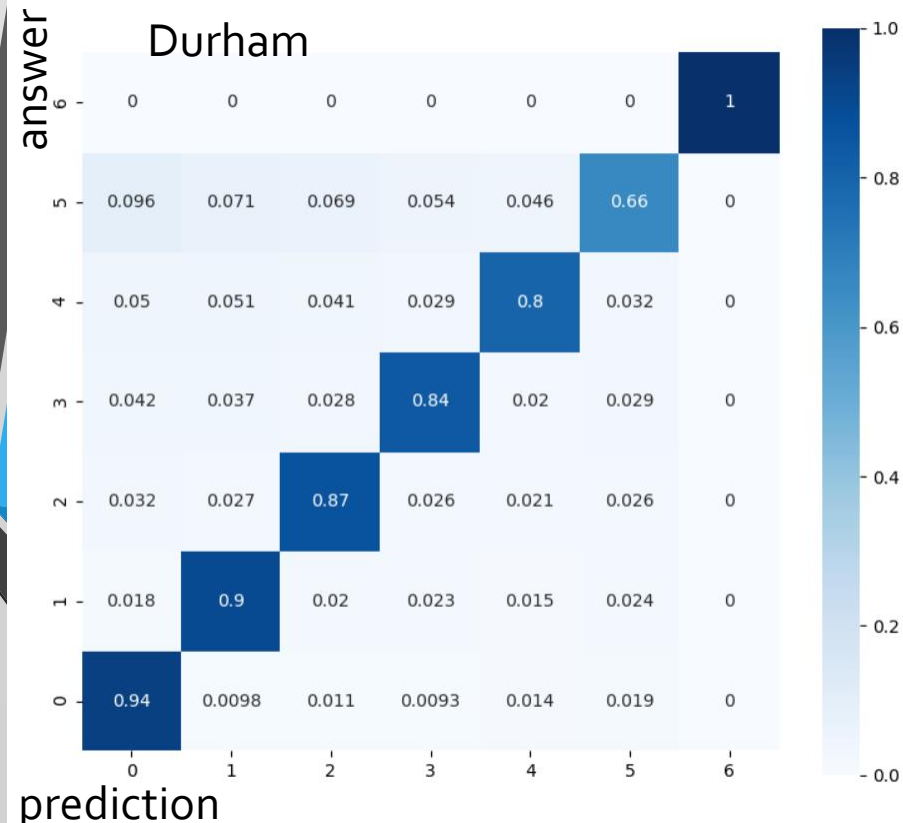
Preliminary results

- Confusion matrix
 - 1000 events
 - Num. 0-5: jet number 6: no particle
 - Off-diagonal means mis-assignment
 - Some particles locate at adjacent jets of their answer jet: should be reduce this correlation
 - Now under investigation
- Need to check resolution of Higgs mass
 - Need to improve



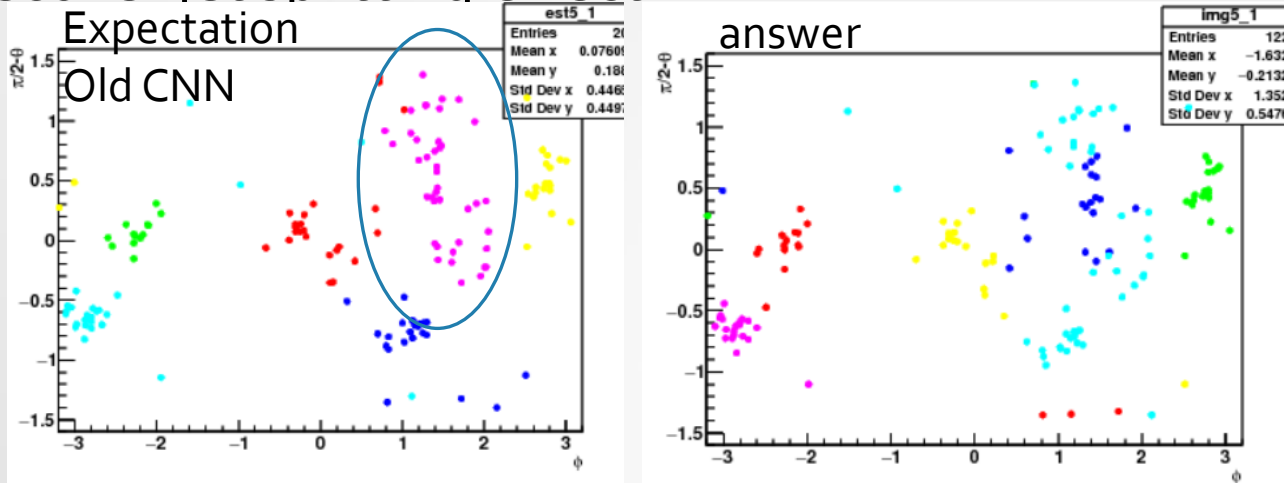
Comparison with Durham

- First 3 jets: start to improve
- Last 3 jets: a bit worse
 - Worst efficiency is improved, but need to improve more
- Correlation between adjacent jets, and asymmetric
- Need to improve circle efficiency to get better performance

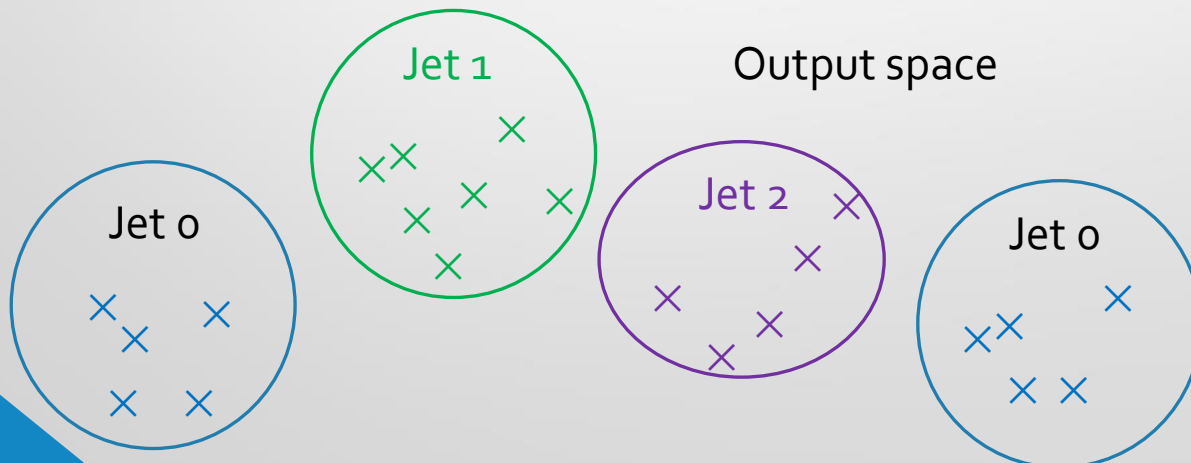


Multi Center

- Try to recover jet splitting effect (alouon emission, etc.)

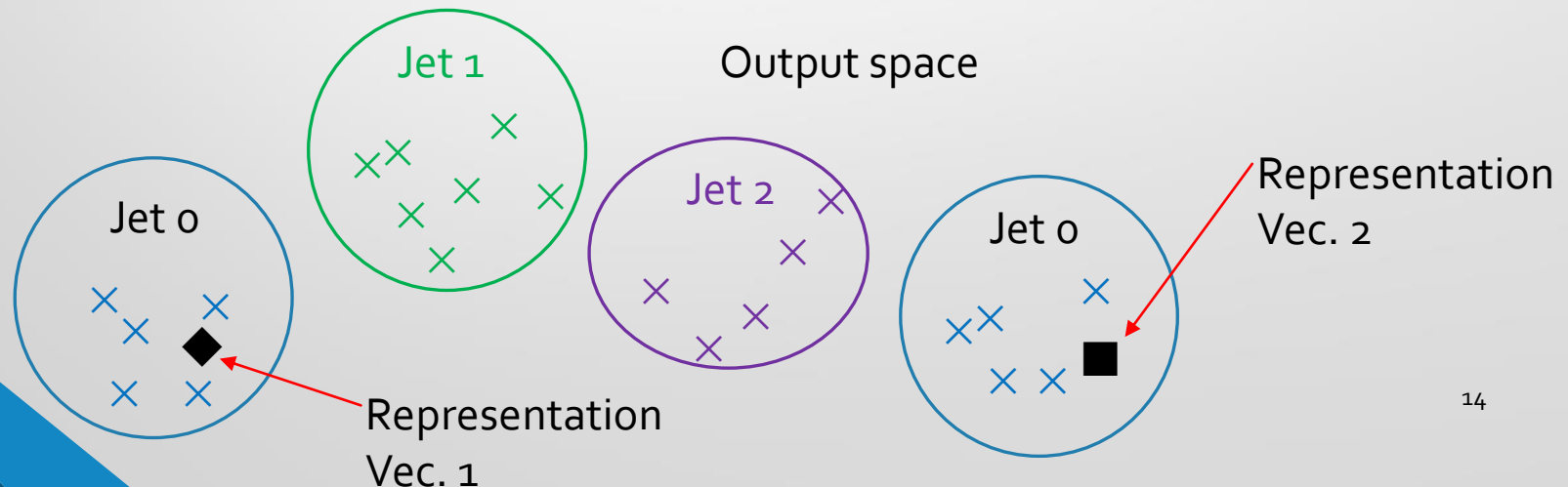


- Split clusters are difficult to merge
 - Each cluster will be located at different space
 - So, distribution will be **multimodal**



Multi Center

- Weights of before output layer in the network are representation vectors of each cluster
- So, increasing the number of final weights is increasing the representation vectors
 - Automatically assign each representation vectors to each (sub) cluster
 - Automatically determine num. of representation vectors through training
 - Done via constraint on weights



Multi Center

- Training on going
- Check the effect on multicenter

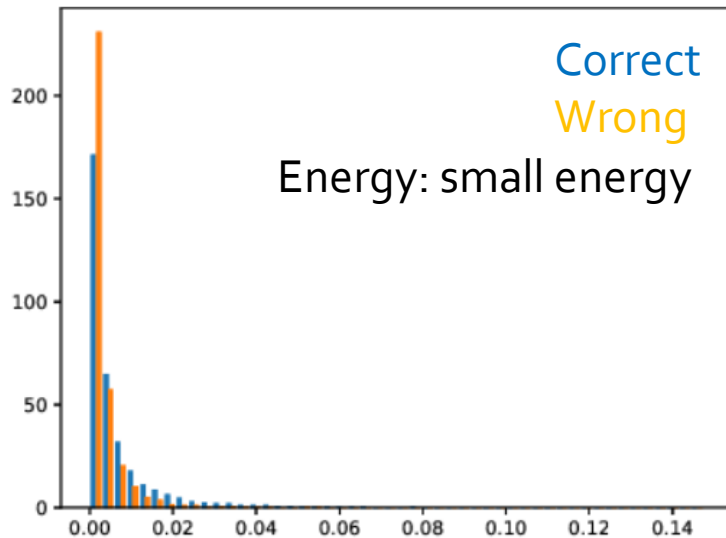
	jet0	jet1	jet2	jet3	jet4	jet5
Num. of weights prepared	5	5	5	5	5	5
Num. of weights survived	2	2	2	2	2	1

- Looks network automatically catches feature in different(?) output space
- Continue training

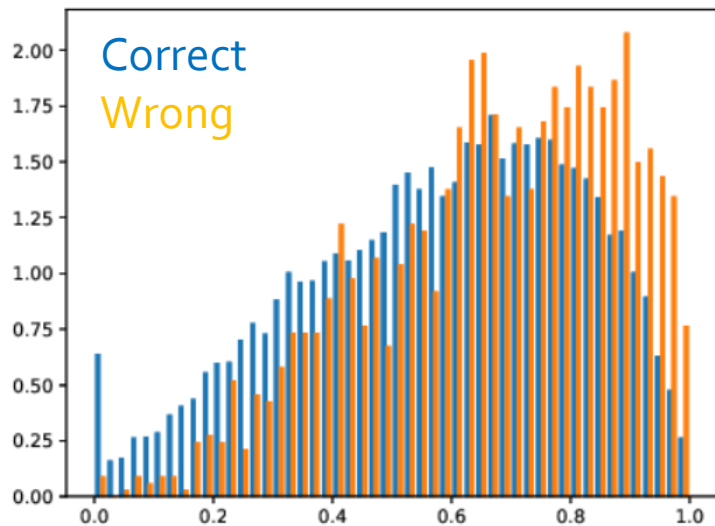


backups

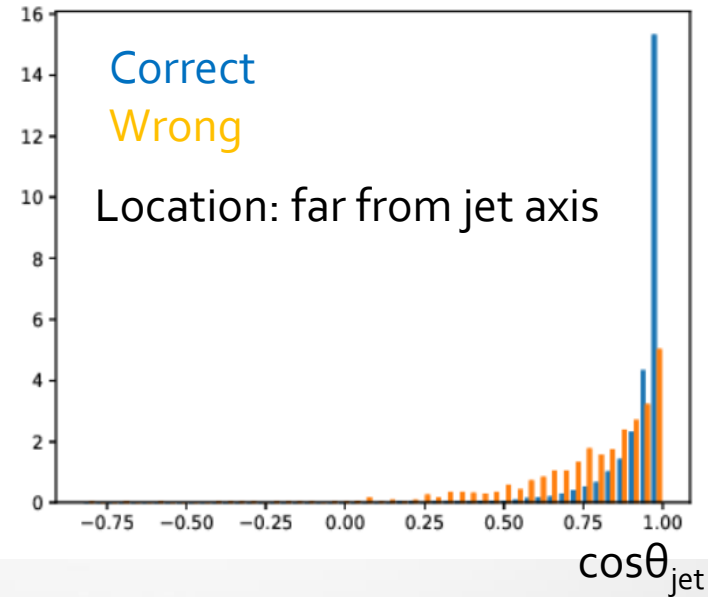
Check the mis-assignment particles



Near adjacent jet axis



$\cos\theta_{\text{adjacent}}$



- Mis-assigned particles:
 - Small energy
 - Located at jet boundary
 - 2 jets are very close
- Now trying to solve to assign such particles correctly

Basics: convolution

- Convolution: Apply the filters to extract the feature

- Sum of the product of each pixel and filter weights:

$$y_{kl} = \sum_{i,j} w_{ij} \cdot x_{(k+i)(l+j)} (+b)$$

- Slide filters over all the pixels

1 _{x1}	1 _{x0}	1 _{x1}	0	0
0 _{x0}	1 _{x1}	1 _{x0}	1	0
0 _{x1}	0 _{x0}	1 _{x1}	1	1
0	0	1	1	0
0	1	1	0	0

Image

4		

Convolved
Feature

- **Filters are parameters:** CNN can obtain them automatically

- After the convolutional operation, apply non-linear transform

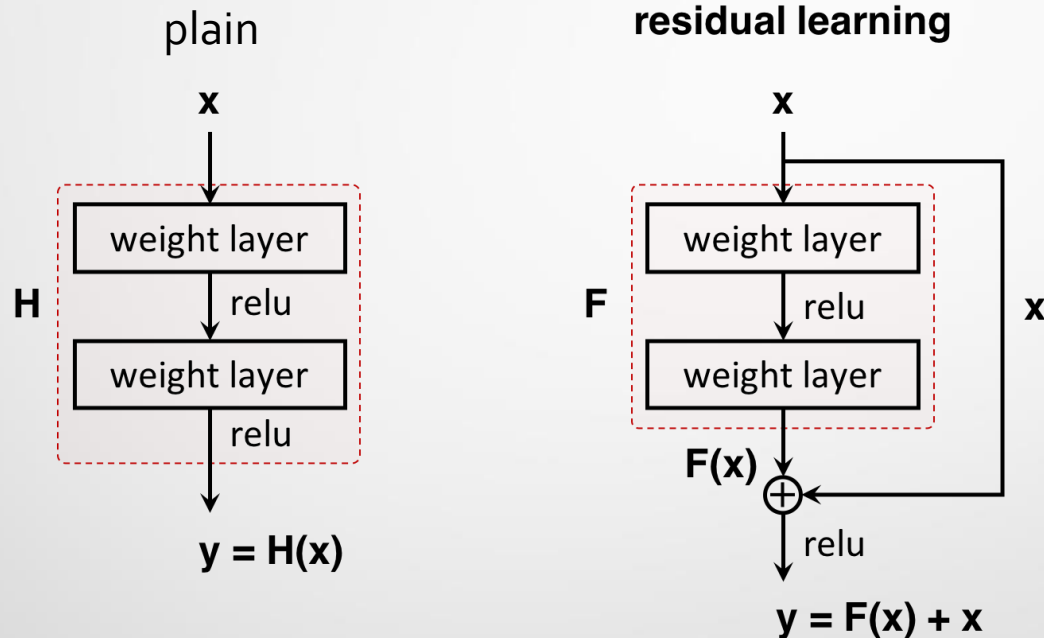
$$z_{kl} = \sigma(y_{kl})$$

- "Non-linear" is important to get good expression

- Stack these operations

Basics: Residual convolution

- Stream is divided into 2 paths:
 - Path with convolution
 - Path without any operation
- Sum up these 2 path in downstream

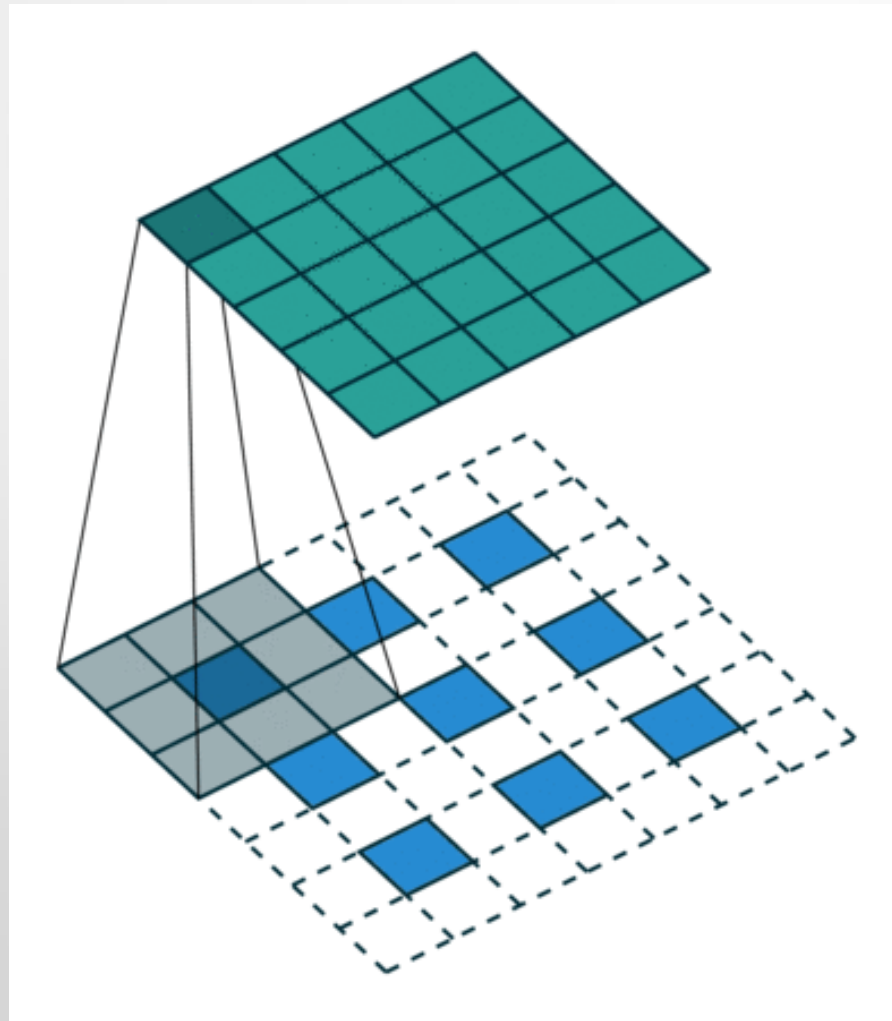


Can learn "Residuals" of previous layer features

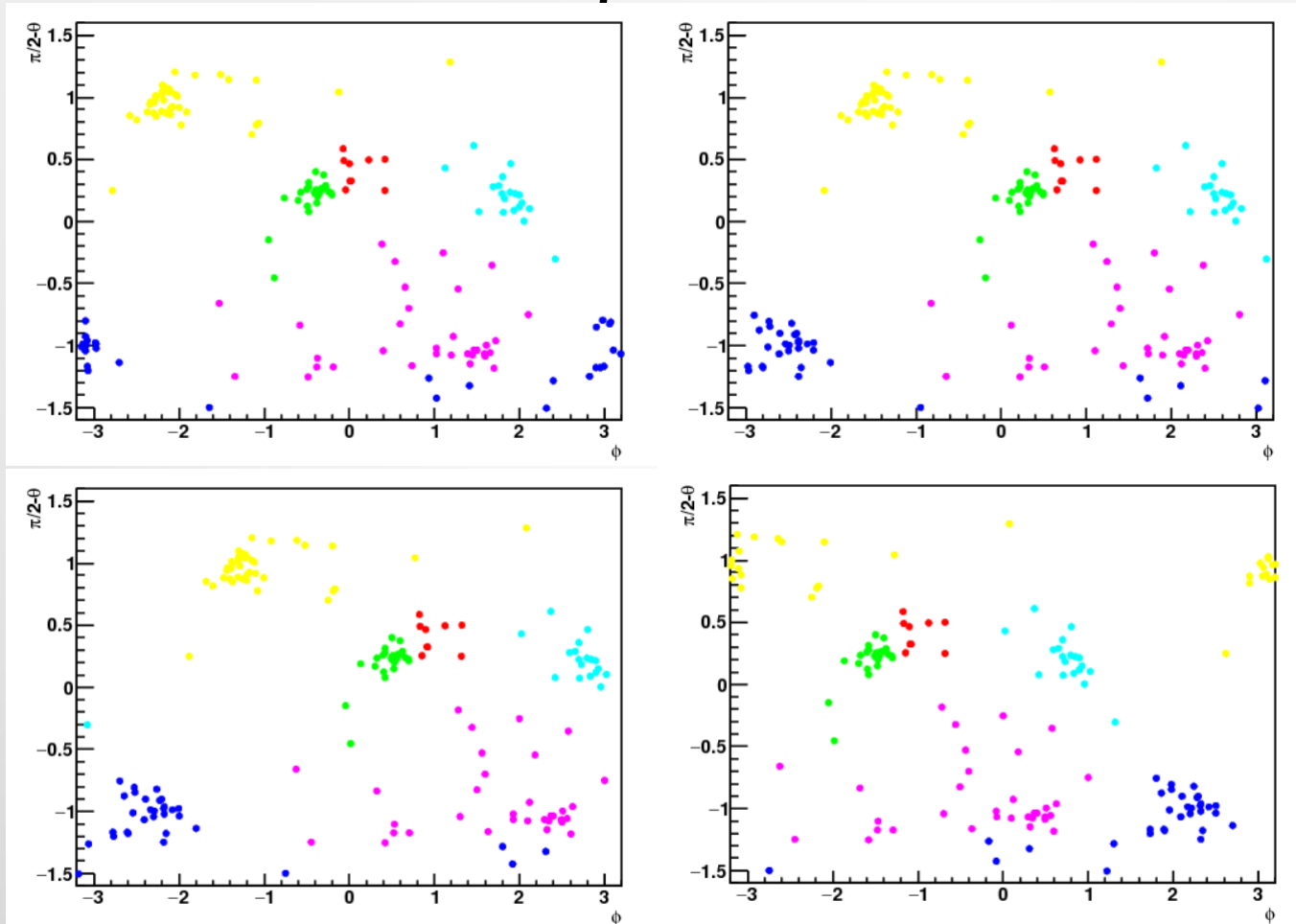
- Can construct very deep network
 - >100 layers can be constructed
 - Deeper will be better performance

Basics: Transposed convolution

- Reverse operation of convolution
 - After adding padding, do convolution
 - Use for upsampling



Data Augmentation



- Random shift for x axis
 - Considering periodic condition of ϕ angle ($f(\Phi+2\pi) = f(\Phi)$)
To suppress over fitting
- Add random y-flip (I think not good from physics point of view, but suppress over-fitting is_{2,1} important)