

# Study of spatial resolution in the z direction for ILC-TPC

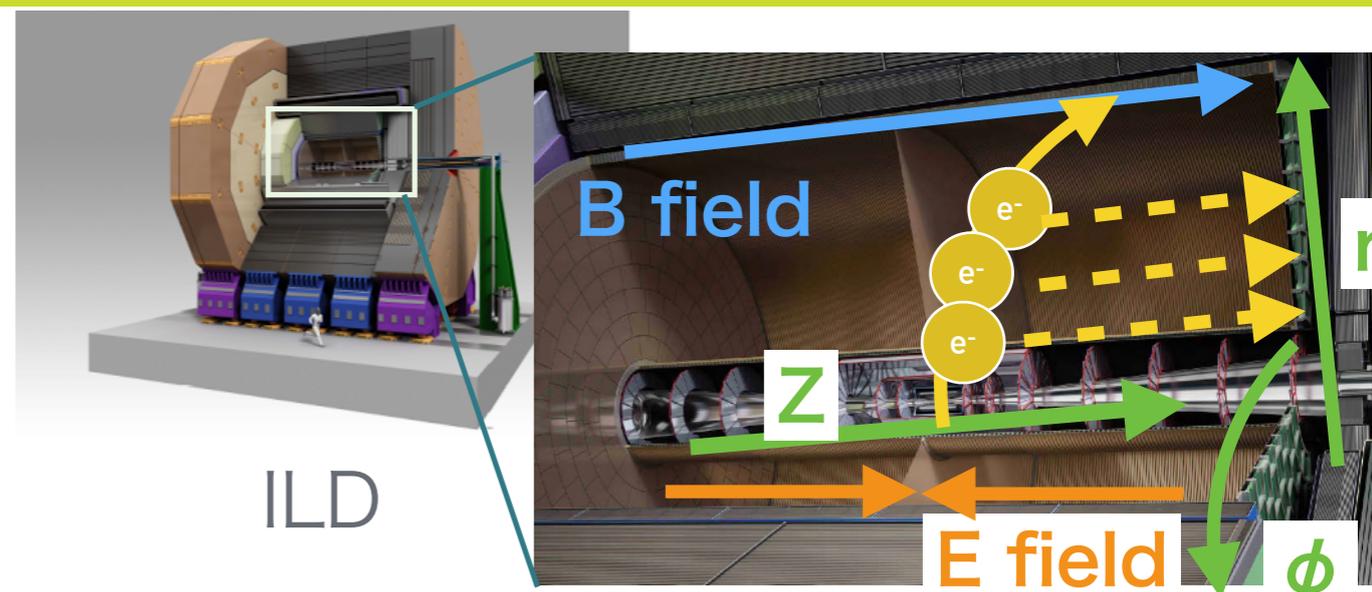
Yumi Aoki (SOKENDAI)

on behalf of LCTPC Asia group

2021. 10. 28 ILCX

## Time Projection Chamber

- Central tracker / gas detector
- Reconstruct 3D track position of charged particle



Recoil mass measurement is most important for precision Higgs study

→ high **momentum** resolution is required

Determined by the curvature of a charged particle track in magnetic field

depends on the number of hit points and their **spatial resolution.**

The goal of momentum resolution  
(TPC only)

$$\sigma_{\frac{1}{P_T}} = 1 \times 10^{-4} \text{ GeV}^{-1}$$

### ILD-TPC Goal

200 hit points with

$r\phi$  resolution :  $< 100 \mu\text{m}$

Z (time) resolution :  $\sim 0.4 - 1.4 \text{ mm}$

(for zero – full drift (2.3m))

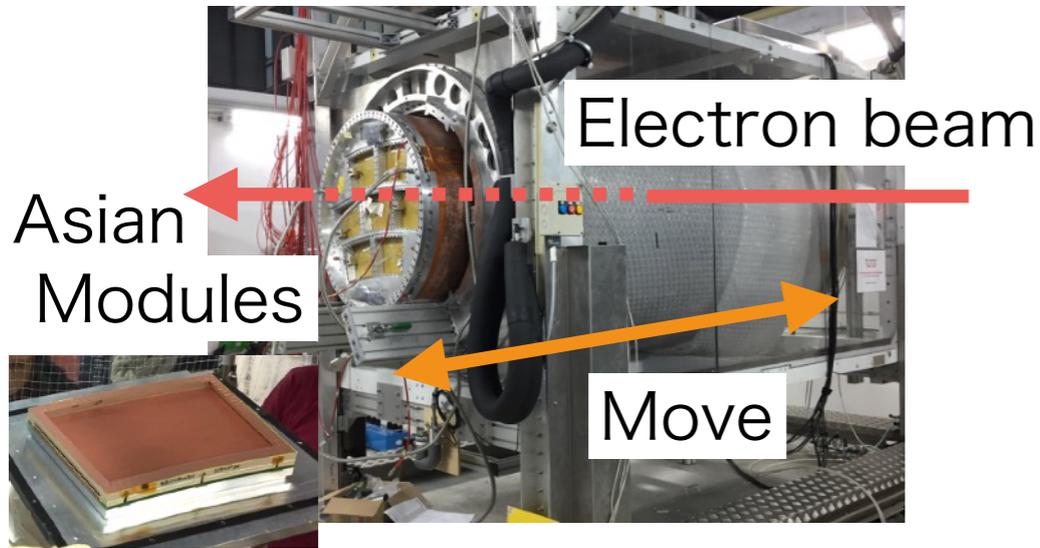
# Can we achieve $r\phi$ resolution goal?



TPC Large Prototype

B field : 1 T

Drift length : 55 cm



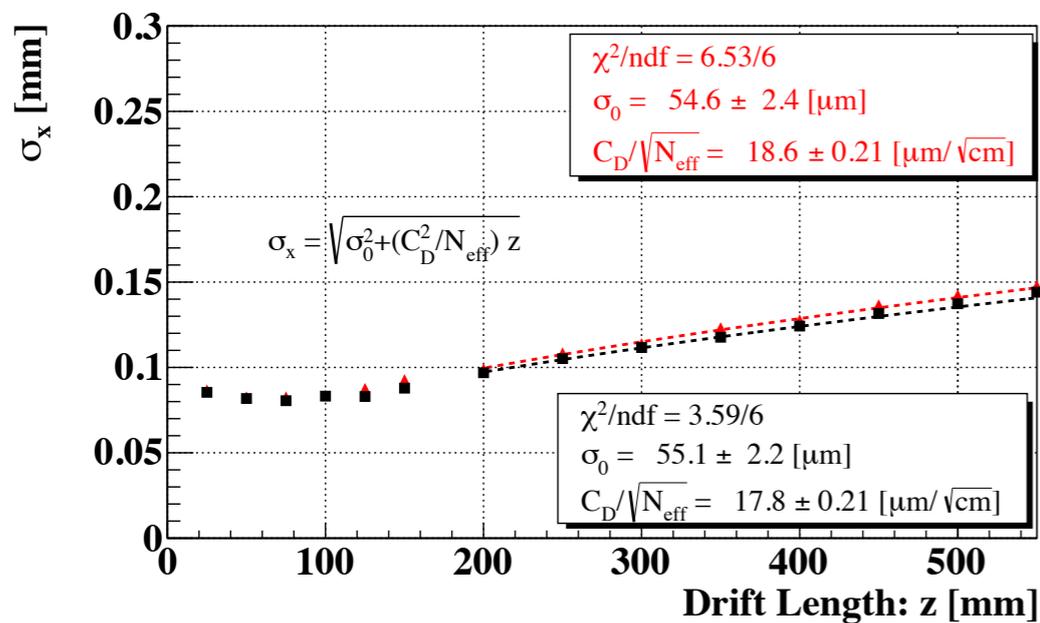
Real-size TPC

B field : 3.5 T

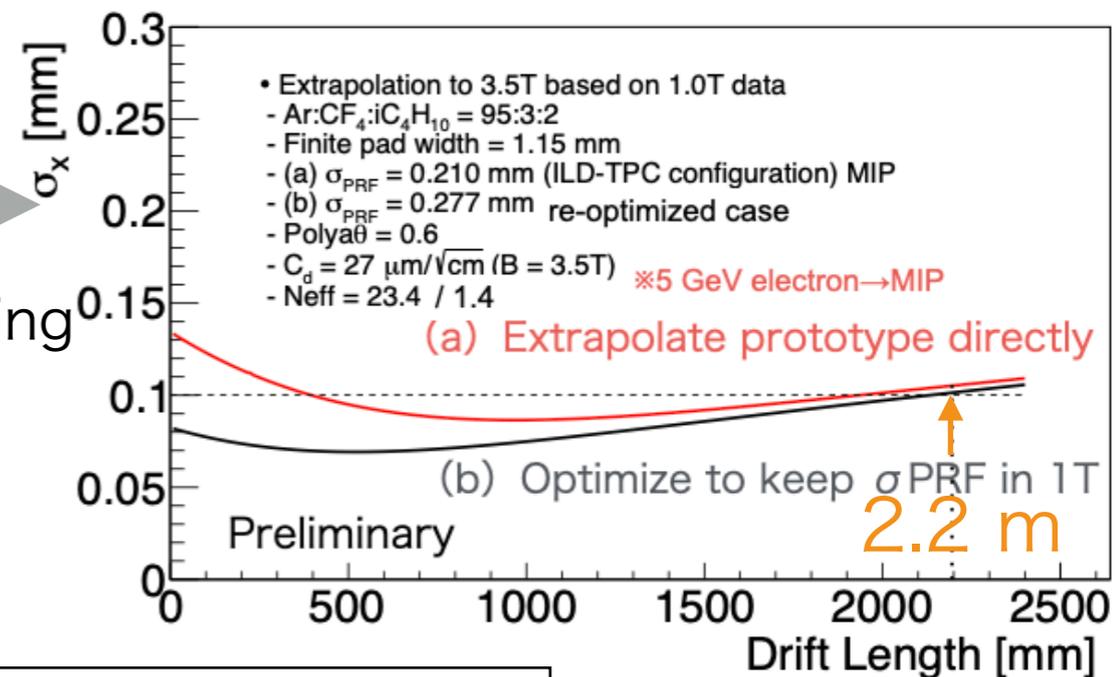
Drift length : 220 cm

$$\sigma_{r\phi}(Z)^2 = \sigma_0(w)^2 + \frac{1}{N_{eff}} C_d(B)^2 \cdot Z$$

B field  
Drift length



extrapolation using analytic formula



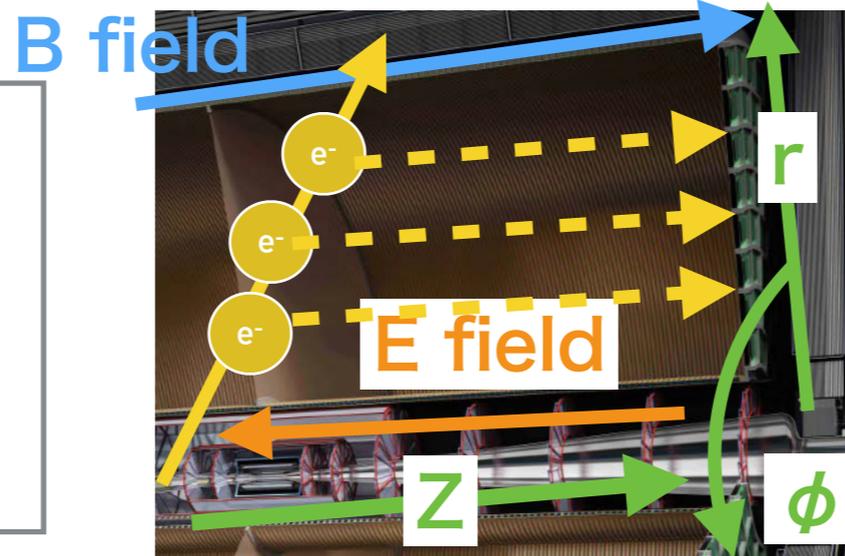
We can achieve the  $r\phi$  resolution goal !

# Can we achieve z resolution goal?

So far, z resolution was thought to be independent of the magnetic field

$r\phi$  direction

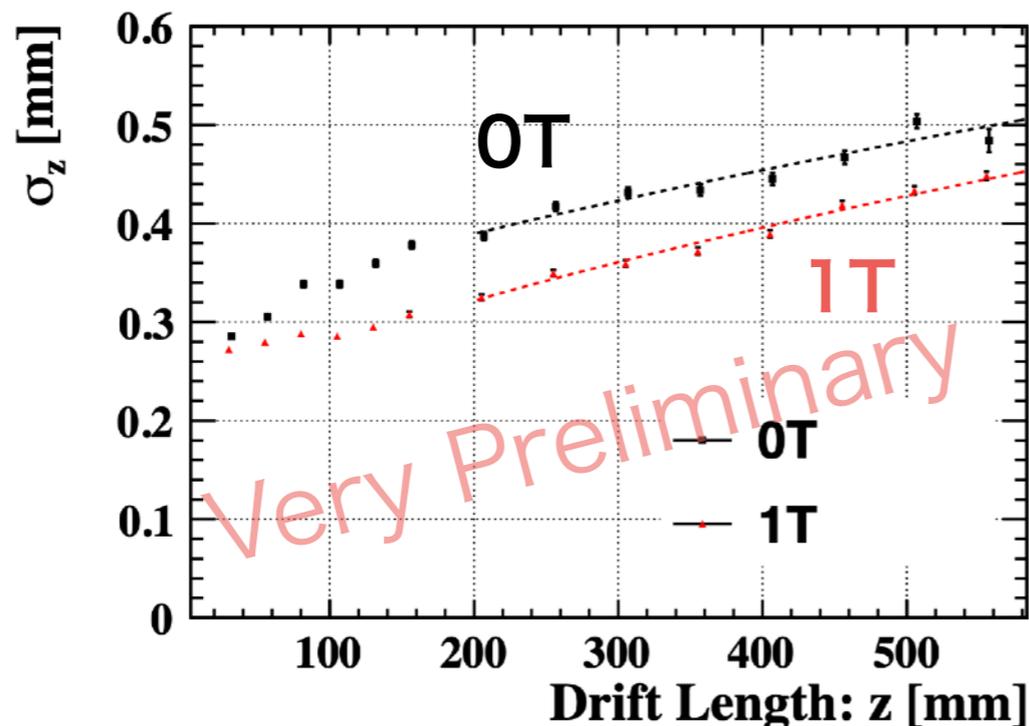
Electrons curling up  
in a magnetic field  
→ Diffusion is suppressed



z direction

No effect of electrons  
curling up  
in a magnetic field

→ Once the drift length dependence of the z resolution was measured for the large prototype, we thought that we could obtain the z resolution of the real TPC by curling up in the drift length even though the magnetic field would be increased to 3.5 T.



Significantly different !

~20%

Understand the magnetic field dependence of z resolution  
→ Check if the z resolution goal can be achieved with real-size TPC

**STEP 1** : What factors affect z resolution ?

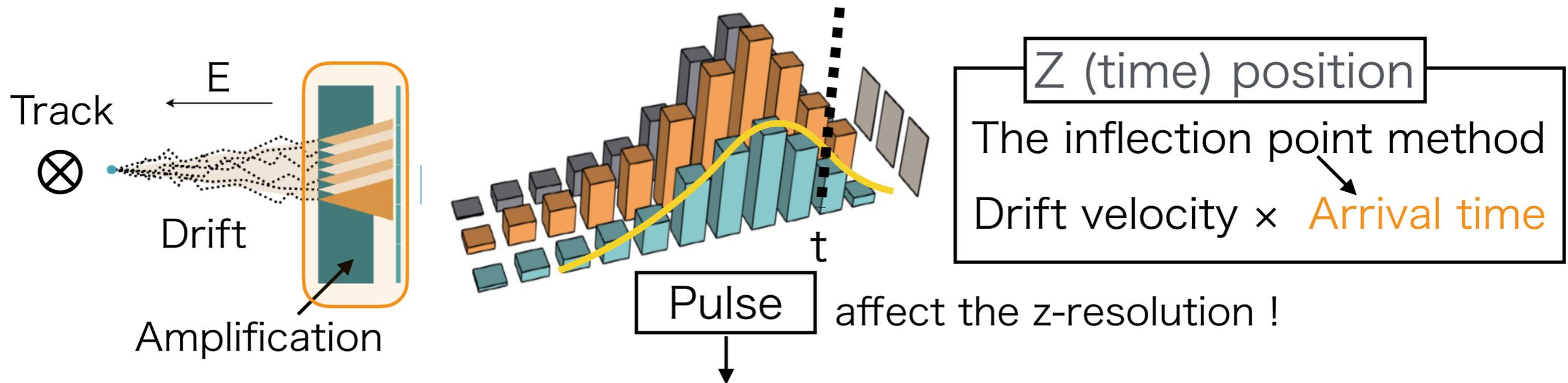
- How can we improve the analysis method of z resolution?

**STEP 2** : Which factors are related to the magnetic field?

**STEP 3** : Develop z resolution formula as a function of drift distance

→ It will then be possible to confirm whether the performance requirement of z-resolution  $< 1.4$  mm can be achieved on the real-size TPC (3.5 T, maximum drift distance 2.3 m).

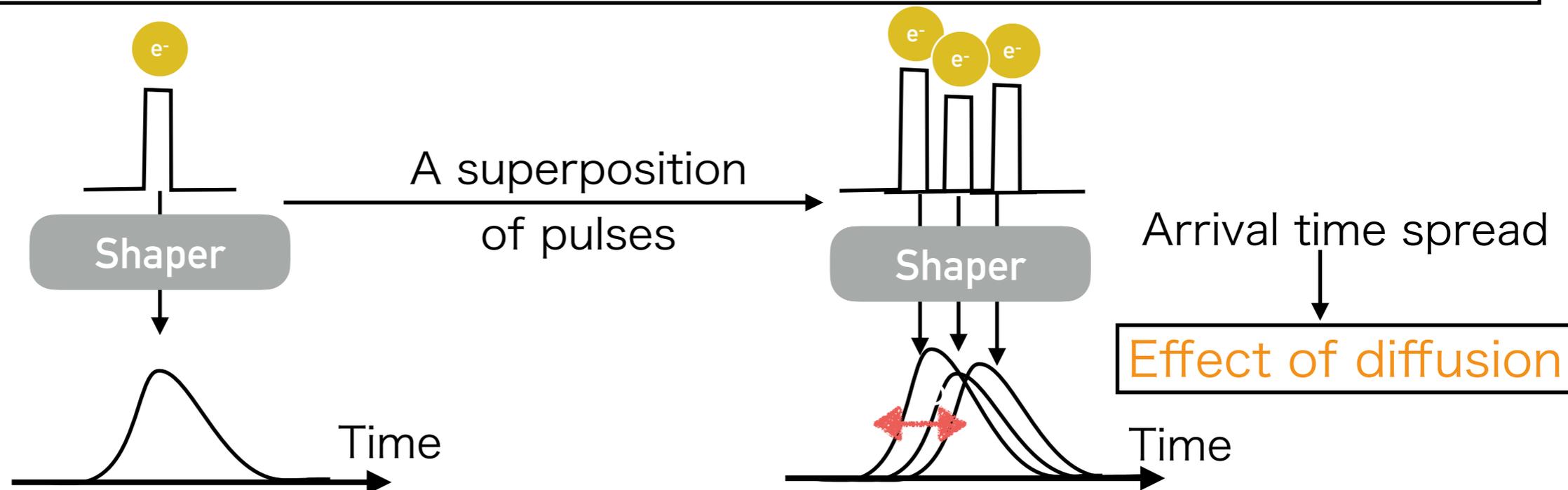
# z resolution & pulse



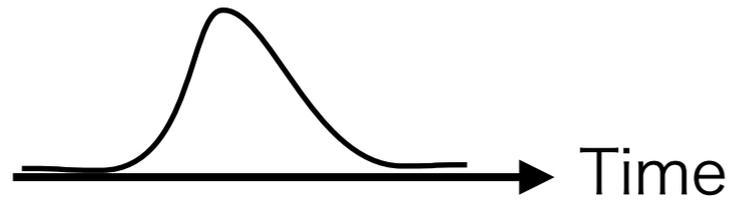
## What factors determine the pulse?

Assumption

the average pulse shape is determined only by the properties of the shaper and the longitudinal diffusion



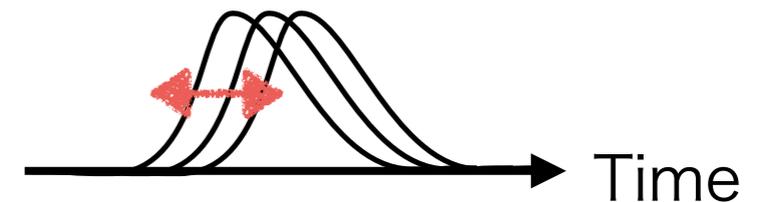
# How to check pulse shape ?



$$f(t) = \frac{1}{n!(t_{pk}/n)} \left( \frac{t}{t_{pk}/n} \right)^n e^{-\left( \frac{t}{t_{pk}/n} \right)}$$

n : shaper order , t<sub>pk</sub> : peaking time

Convolution



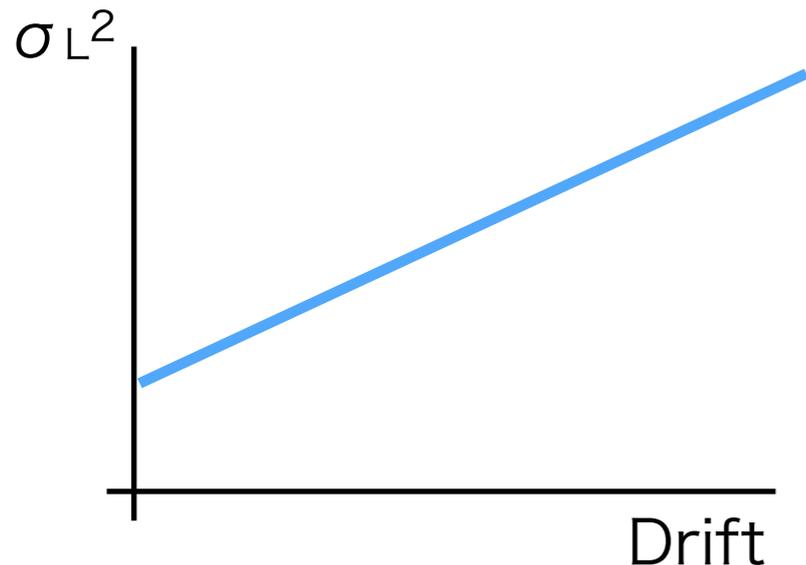
Gaussian smearing

due to the longitudinal diffusion

We can get the “longitudinal diffusion” as a standard deviation :  $\sigma$

If the assumptions are correct, the pulses in the beam test data could be fitted with this convolution function.

This smearing becomes larger as the drift distance increases



$$\sigma_L^2 = \sigma_0^2 + C_{dL}^2 \cdot z$$

Effect of finite time bin width

$$\frac{\text{Drift velocity} \times \text{time bin}}{\sqrt{12}}$$

Diffusion constant is a parameter of the drift distance dependence of the diffusion in the drift region

I checked if I could calculate  $C_{dL}$  properly using this method

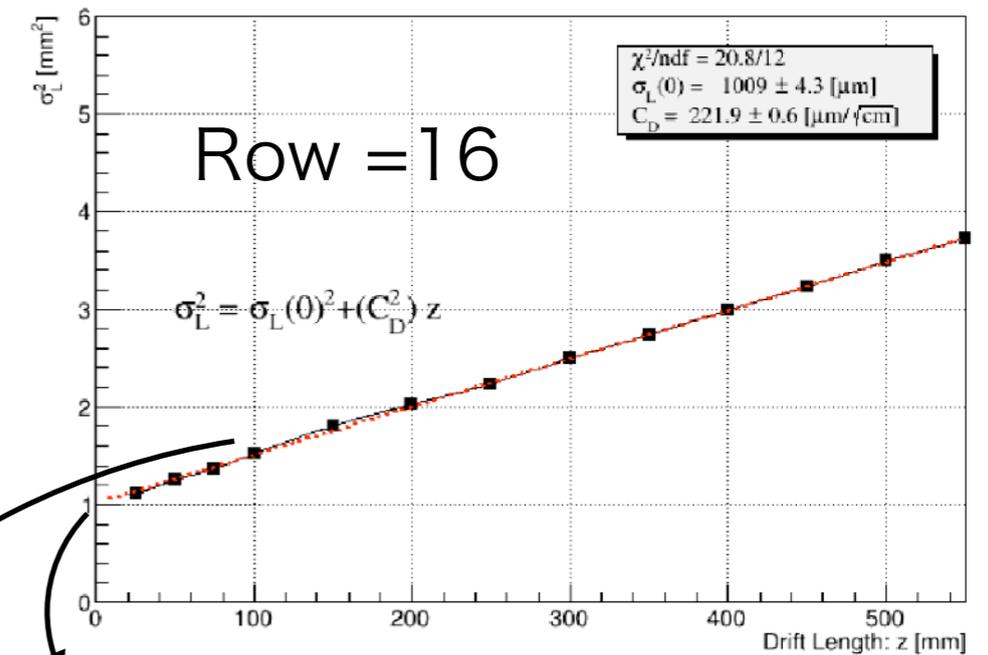
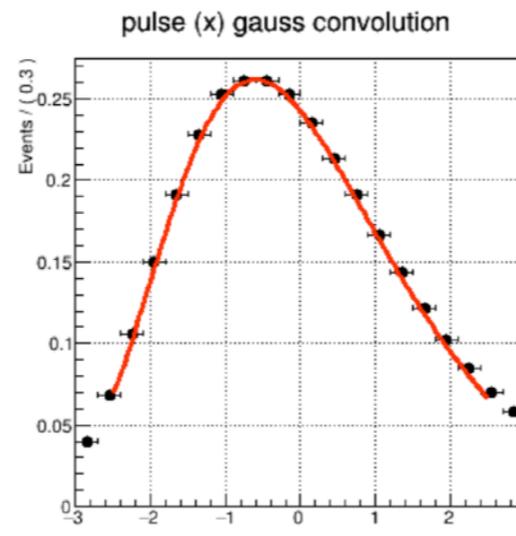
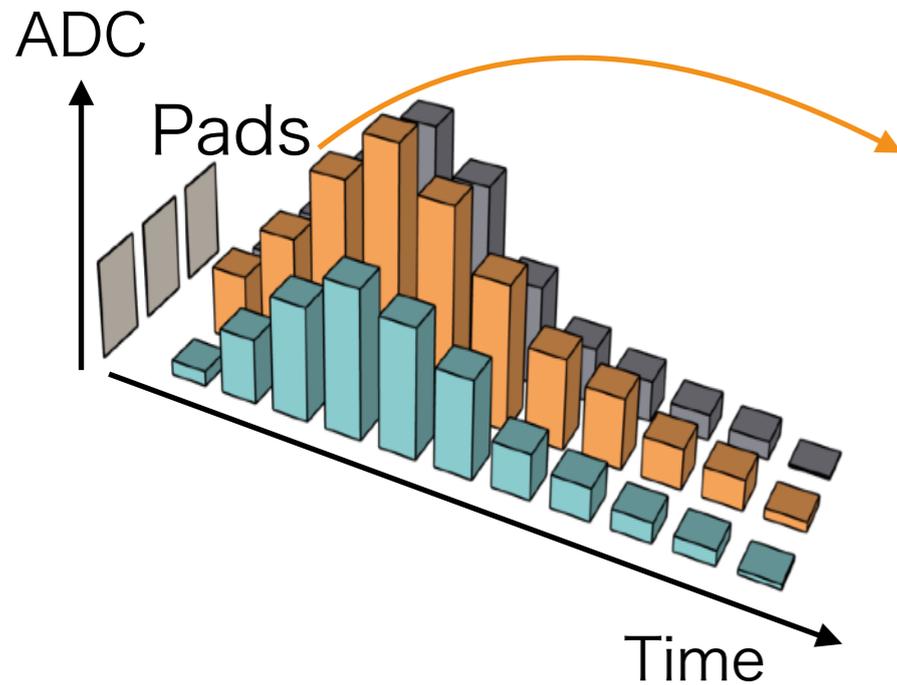
① Make pulse by simulator

Input :  $C_{dL} = 220 \mu\text{m}/\sqrt{\text{cm}}$

② convolution fit

$n=3, \text{tpk} = 120\text{ns}$

③ Plot (standard deviation)<sup>2</sup> as a function of drift length



Result

$C_{dL} \approx 221.9 \mu\text{m}/\sqrt{\text{cm}}$

Consistent with input

$\sqrt{\text{intercept}}$

$\sigma_L(0) \approx 1.0 \text{ mm}$

$$\frac{75 \mu\text{m}/\text{ns} \times 50 \text{ns}}{\sqrt{12}} = 1.08 \text{ mm}$$

Consistent

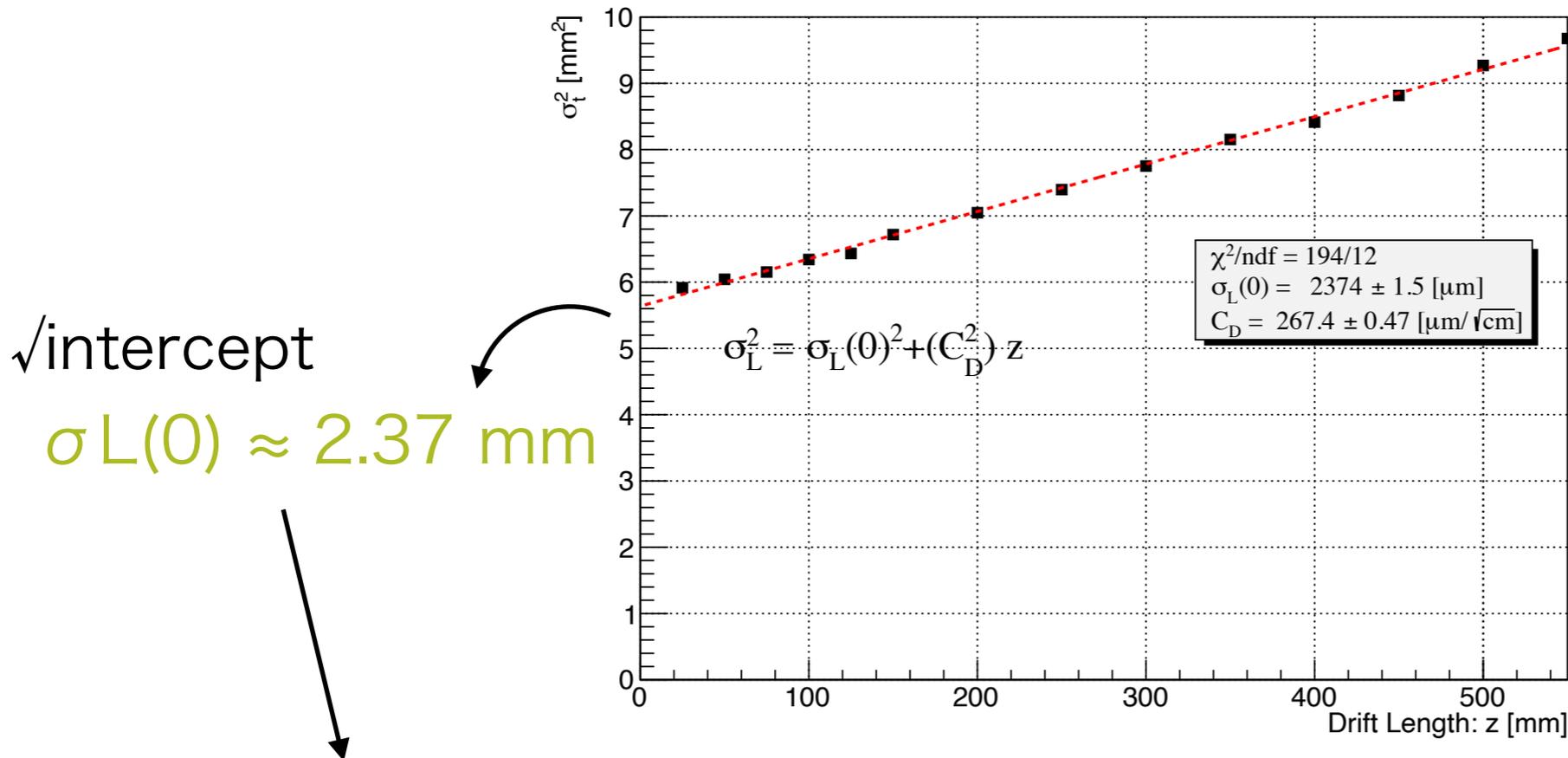
This method works for simulation data

# C<sub>dL</sub> of test beam data



By using convolution method, we calculated C<sub>dL</sub> of test beam data

Input : n = 3 , t<sub>pk</sub> = 120 ns Row = 16



C<sub>dL</sub> ≈ 267.4 μm/√cm

Difference between theory :  $\sqrt{(2.374 \text{ mm})^2 - (1.082 \text{ mm})^2} = \underline{2 \text{ mm}}$

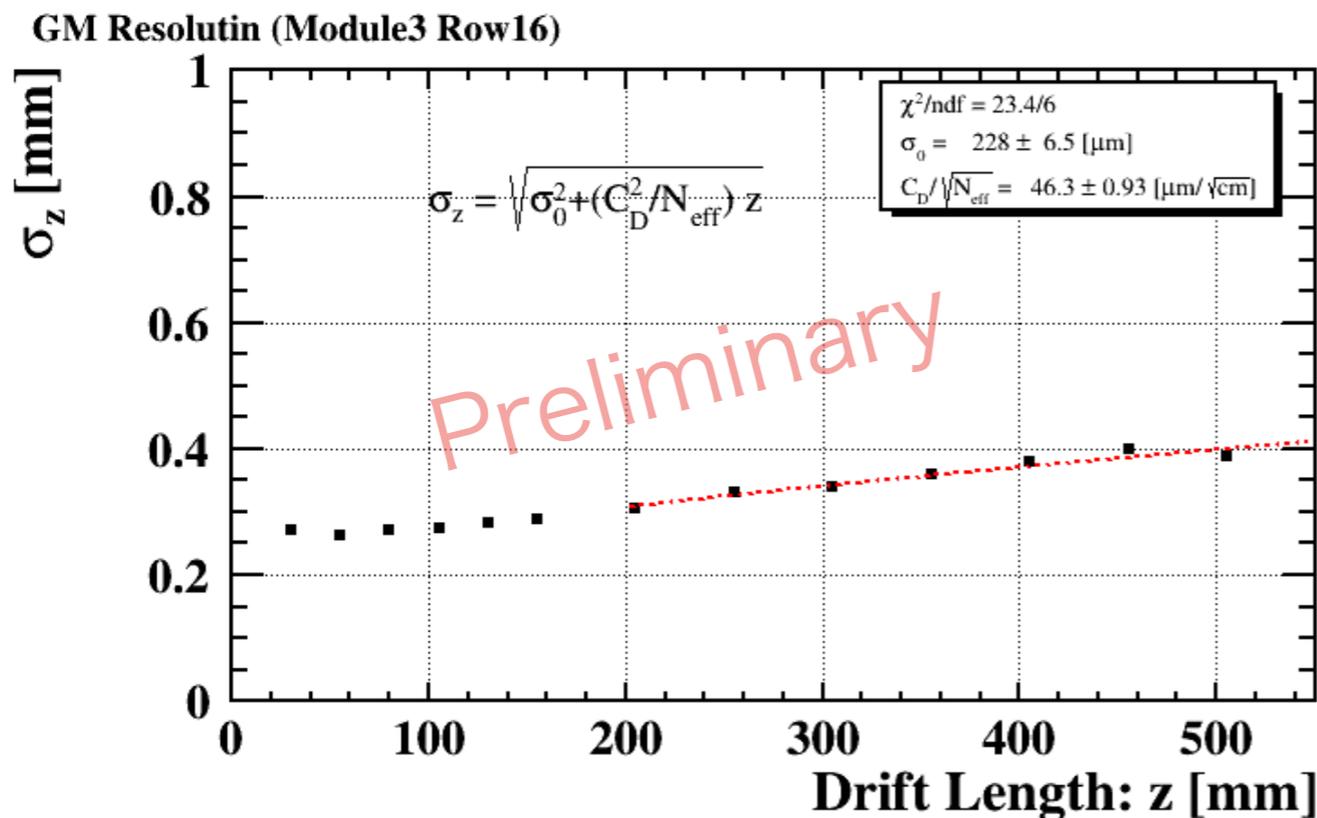
The assumption that the pulse shape is only determined by the shaper properties and longitudinal diffusion is **NOT reasonable**

There are **smearing effects** other than the diffusion in the drift region

## Garfield++ Simulation

	1 T	0 T
Temperature[K]	291.28	291.11
Pressure[hPa]	1010.79	1007.29
$C_{dL} [\mu\text{m}/\sqrt{\text{cm}}]$	$226.1 \pm 1.54\%$	$224.4 \pm 2.64\%$

If we assume that  $N_{\text{eff}}$  is the same as in the  $r\phi$  resolution at same time, we can also estimate  $C_{dL}$  from the analysis of  $z$  resolution



$$N_{\text{eff}} = 23.9 \pm 0.7 \quad (\text{From } r\phi \text{ analysis})$$

$$C_{dL}/N_{\text{eff}} = 46.3 \pm 0.93 \mu\text{m}/\sqrt{\text{cm}}$$

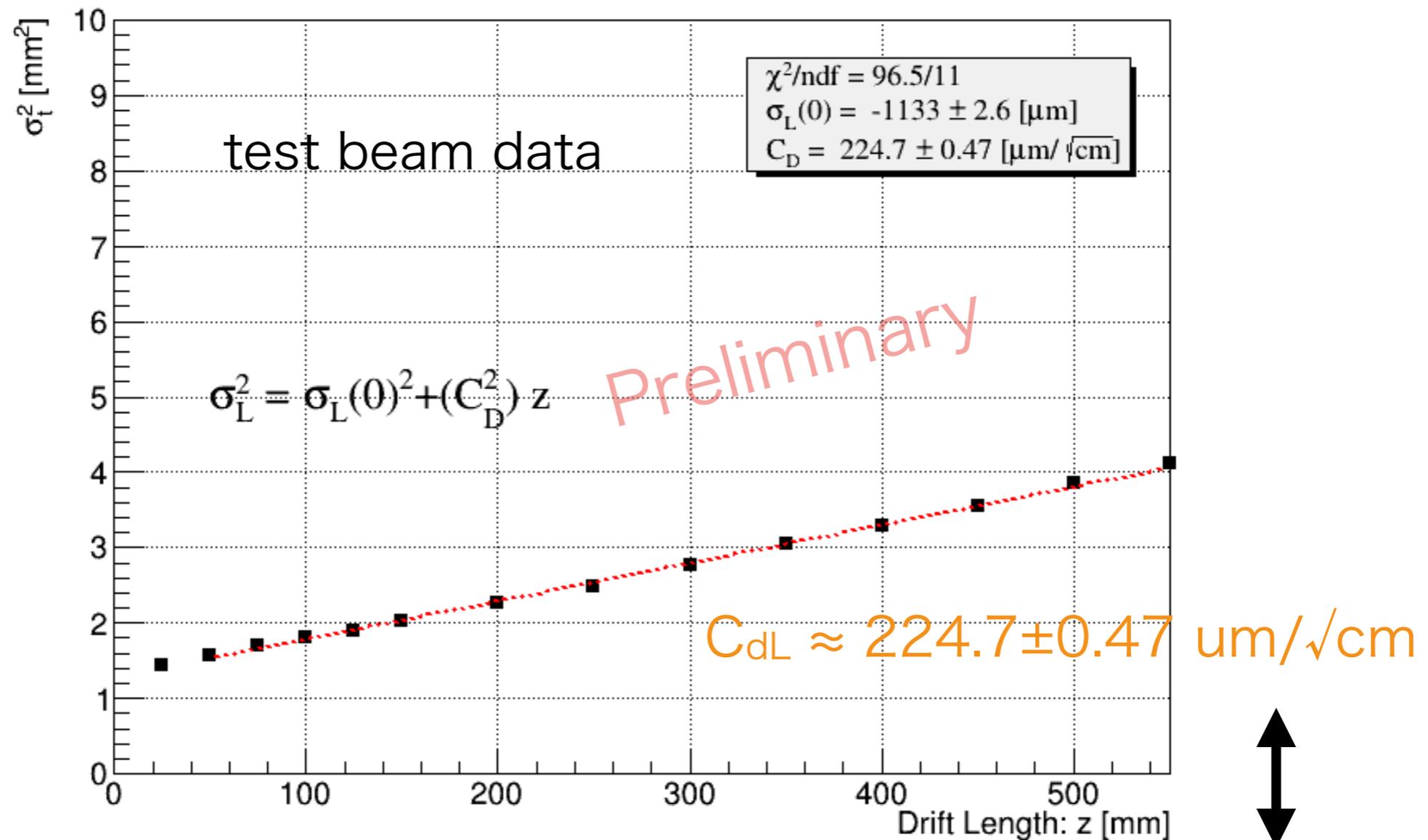


$$C_{dL} = 226.3 \pm 5.6 \mu\text{m}/\sqrt{\text{cm}}$$

# Adjusting tpk



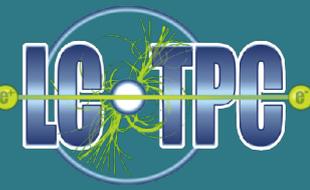
Input :  $n = 3$  ,  $tpk = 135$  ns, Row = 16 (Specification sheet:  $tpk = 120$ )



Garfield++:  $C_{dL} = 226 \pm 1.5\%$

This method of  $C_{dL}$  estimation is rather sensitive to the input shaper parameters

# What are the possible smearing effects?



## Future plans

Is the pulse shape really according to theory?

- Shaper parameter  $n=3$ ,  $t_{pk} = 120\text{ns}$  are from specification sheet

→ We are planning to measure pulse shape directly



## Future plans

There are at least 2 candidates

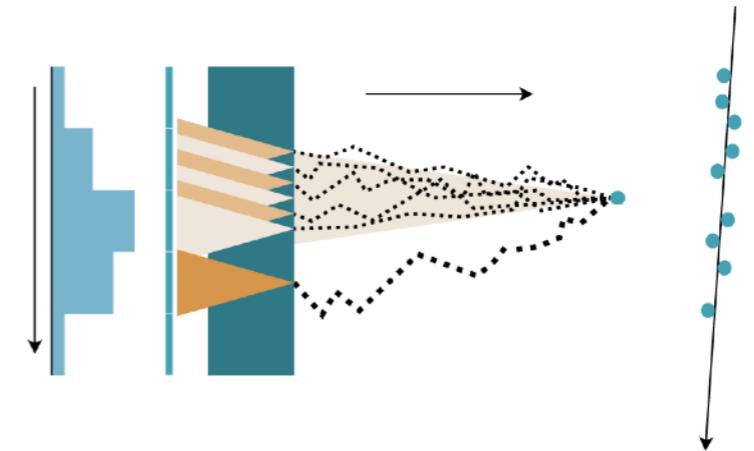
### (A) Distortion of isochron

The drift line may be distorted

by the deformation of the GEM foil, the electrode gap, etc...

In this case, the magnetic field causes the distortion of drift line due to  $E \times B$ .

→ Approach from beam test analysis

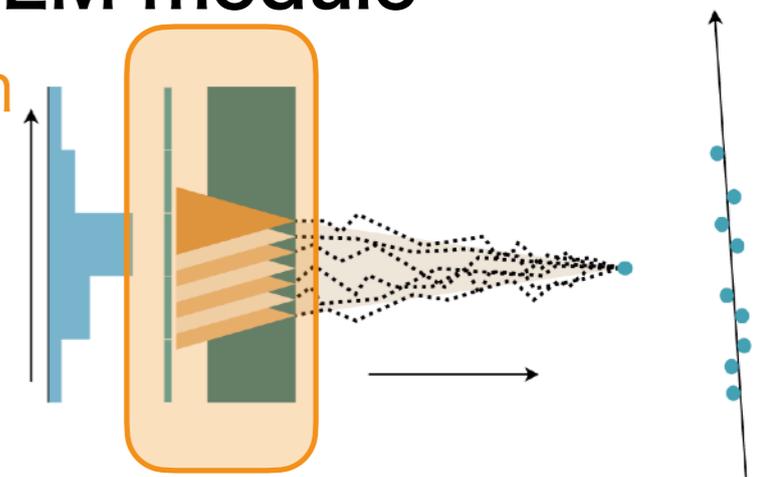


### (B) Width of arrival time due to diffusion in the GEM module

Currently, diffusion effects in the amplified region are not taken into account in our simulation.

This can be estimated since the size and electric field of each region in the GEM module are known.

→ Approach from simulator improvement



In the TPC of ILD, achieving a **high position resolution** is essential for precision Higgs measurements.

To check if the performance goals can be achieved with Real-size TPC, we started **studying magnetic field dependence of z resolution**

Comparison of beam test results with simulations shows that **the assumption that the shape of the pulse is determined only by the shaper properties and longitudinal diffusion is not appropriate**

We found that there are some unknown effects which widen the resolution by 2 mm

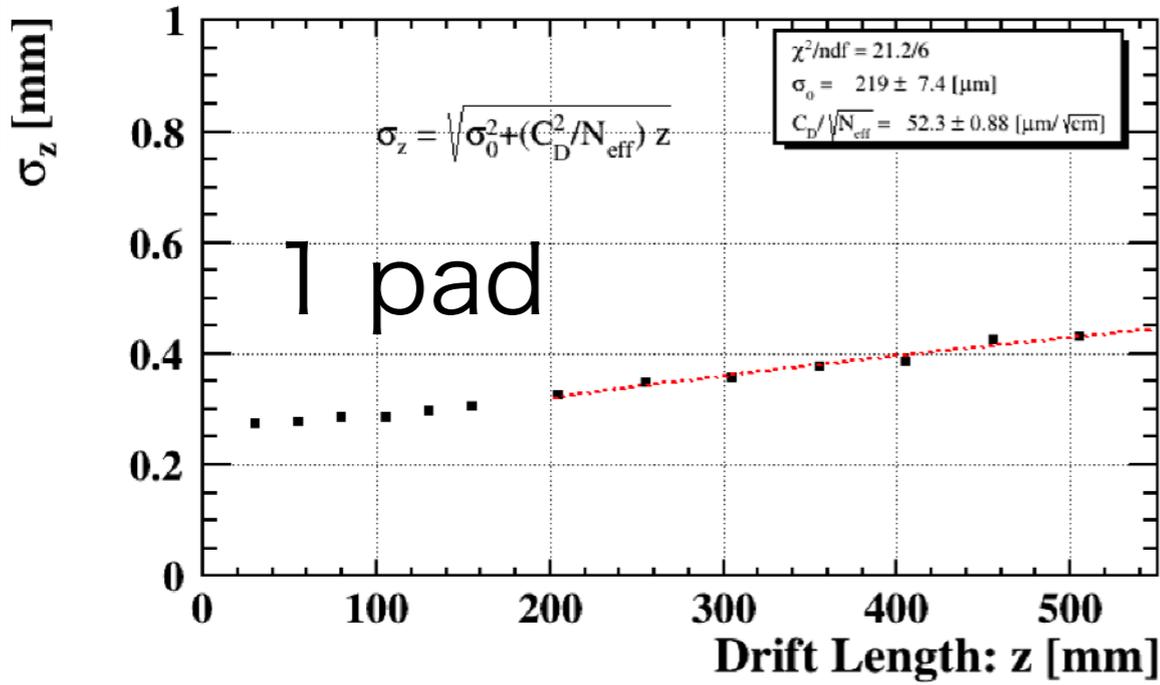
## Future work

Identify what effect is widening the position in the z direction

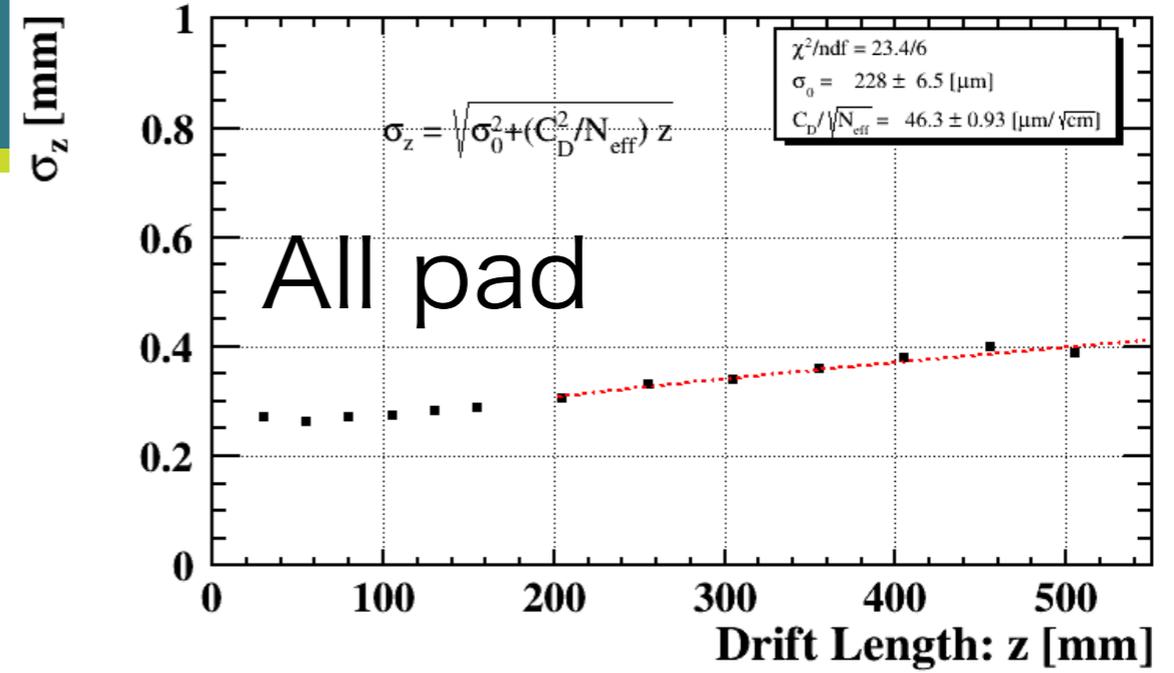
- Estimate the effect of distortion of isochron
- Simulator improvement

# Backup

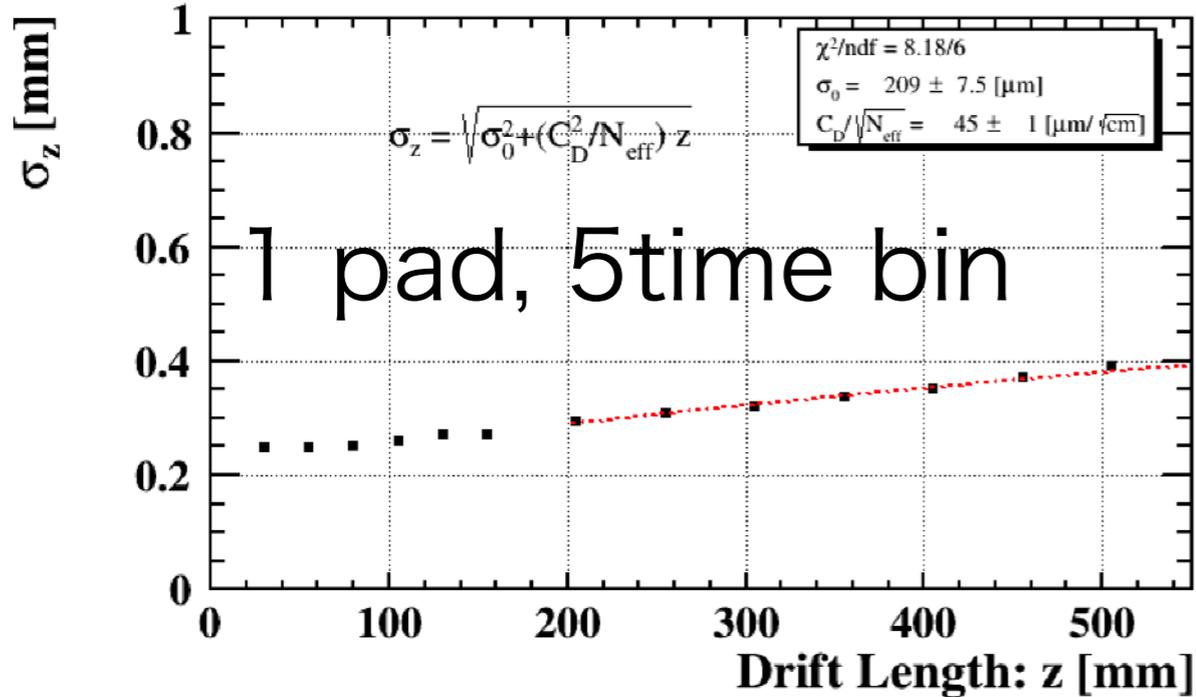
GM Resolutin (Module3 Row16)



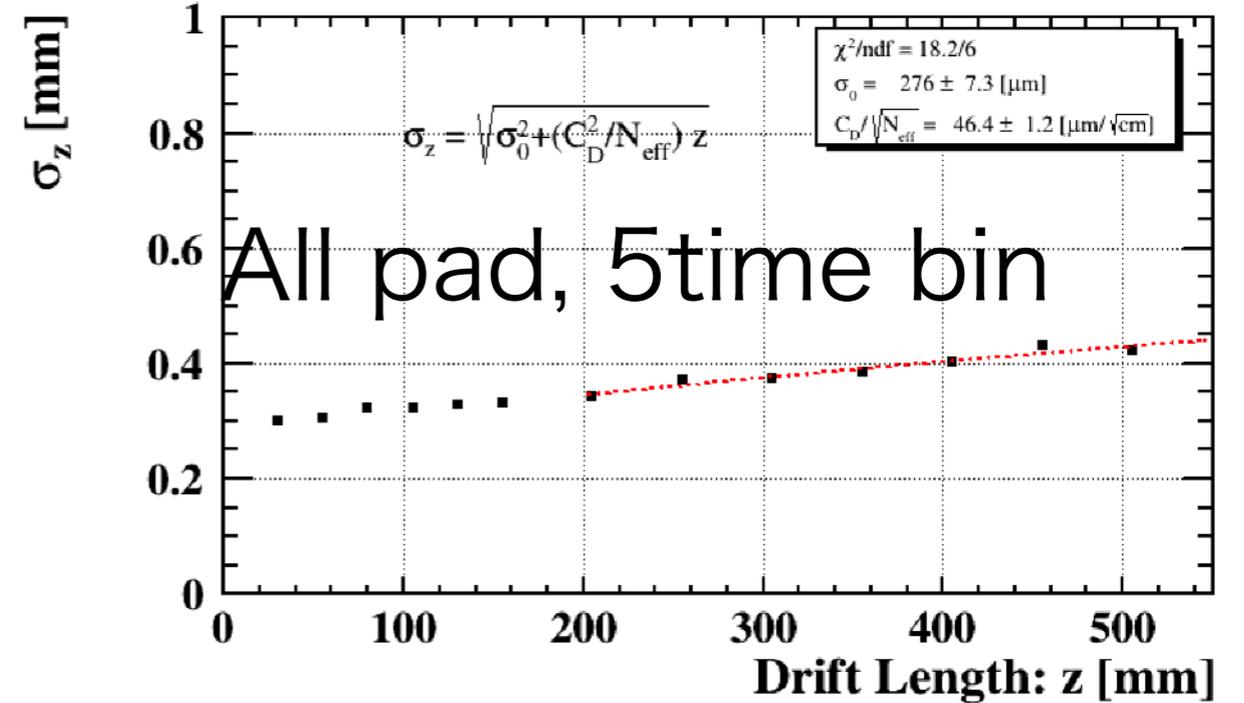
GM Resolutin (Module3 Row16)



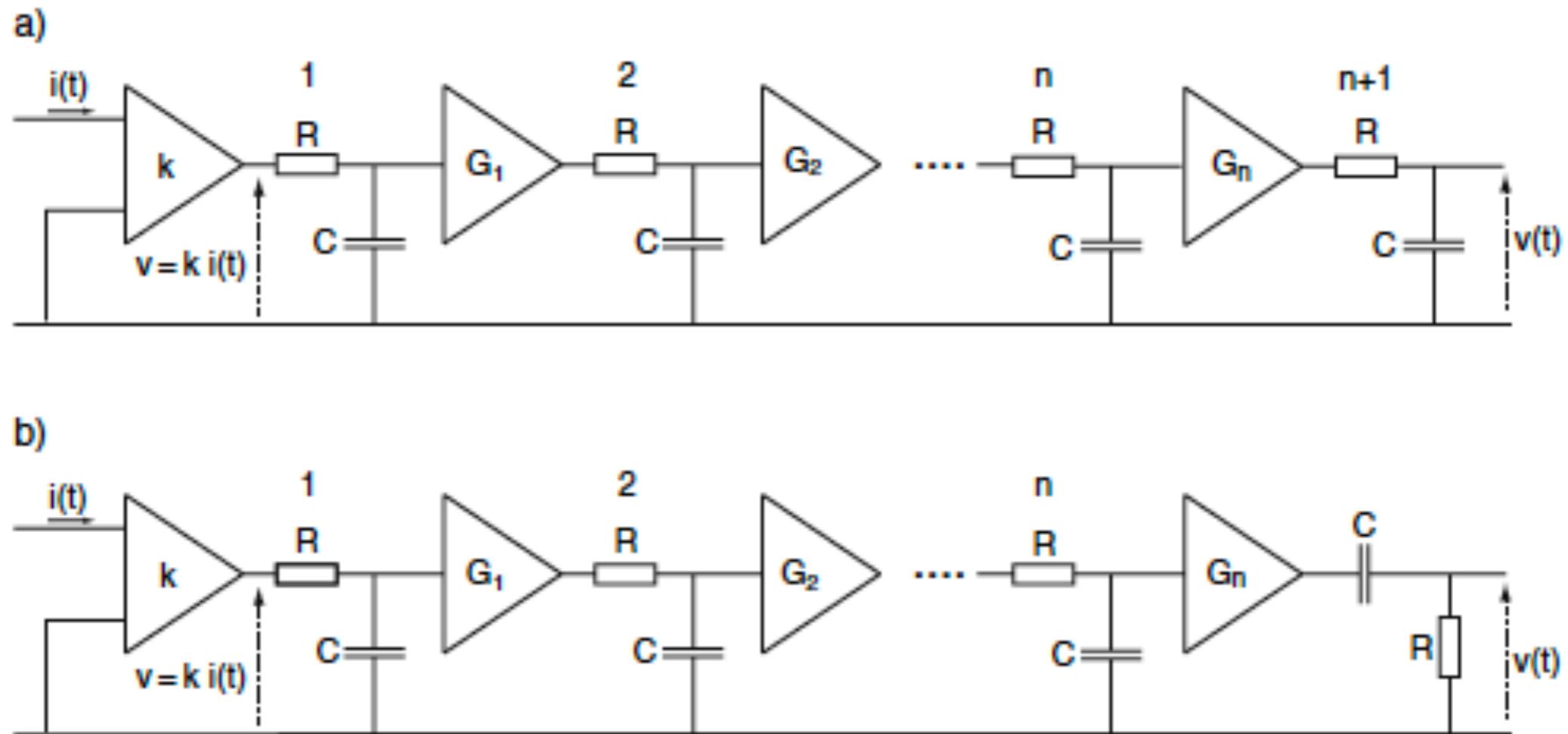
GM Resolutin (Module3 Row16)



GM Resolutin (Module3 Row16)



	$C_{dL}/N_{eff}$ [ $\mu\text{m}/\sqrt{\text{cm}}$ ]	$C_{dL}$ [ $\mu\text{m}/\sqrt{\text{cm}}$ ]
Inflection point(1 pad )	$52.3 \pm 0.88$	$255.7 \pm 5.7$
Inflection point (All pads)	$46.3 \pm 0.93$	$226.3 \pm 5.6$
C.O.G (1pad, 5 time bins)	$44.2 \pm 1.3$	$216.1 \pm 7.1$
C.O.G (All pads, 5 time bins)	$46.4 \pm 1.2$	$226.8 \pm 6.7$



**Fig. 6.13** (a) Unipolar shaping circuit consisting of  $n + 1$  identical RC filters which are separated by ideal voltage buffers. (b) Bipolar shaping circuit consisting of  $n$  identical RC filters and a single CR filter with the same time constant

## Parameter

- Position, angle of track
- # of primary ionization
- Diffusion constant

## Create the readout structure

- Pad size
- Drift velocity
- Average gas gain

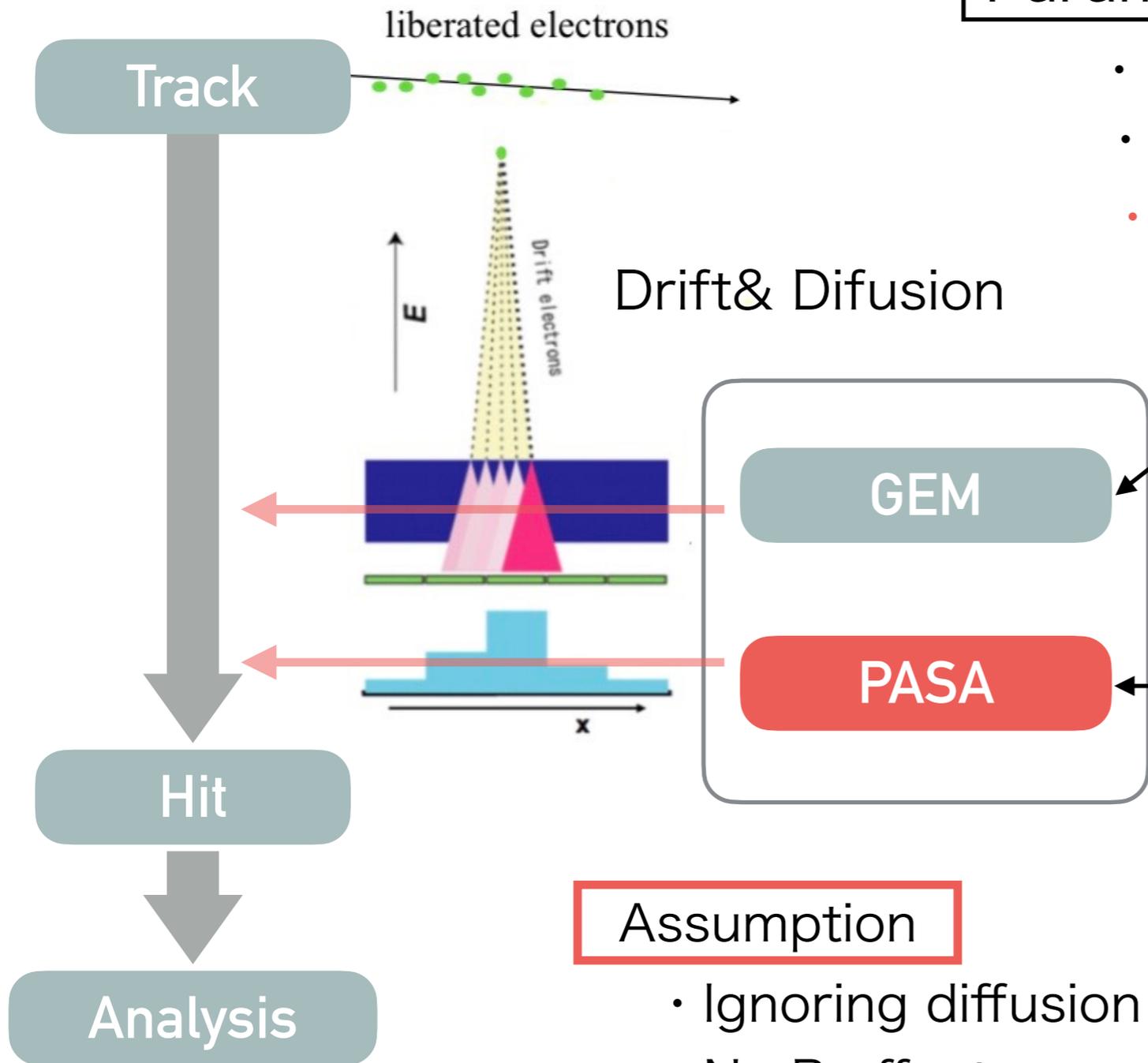
## Define how to treat electrons

- Peaking time
- Shaper order
- time bin width

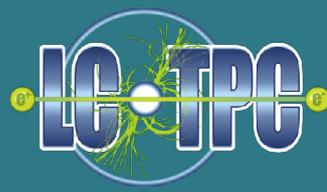
## Assumption

- Ignoring diffusion in amplification region
- No B effect

✂ I use a pad having largest charge in the row



# Comparison by # of time bins

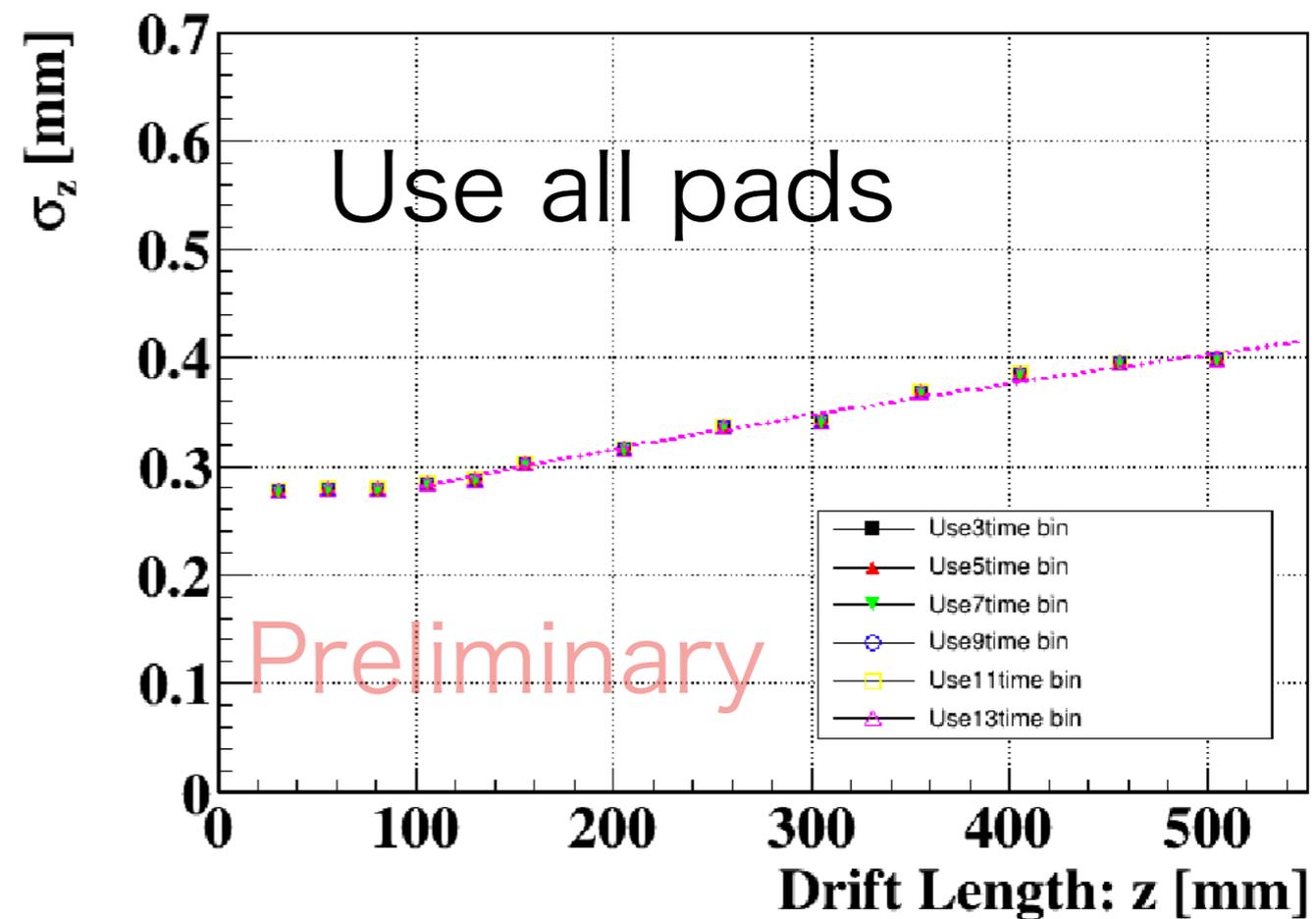
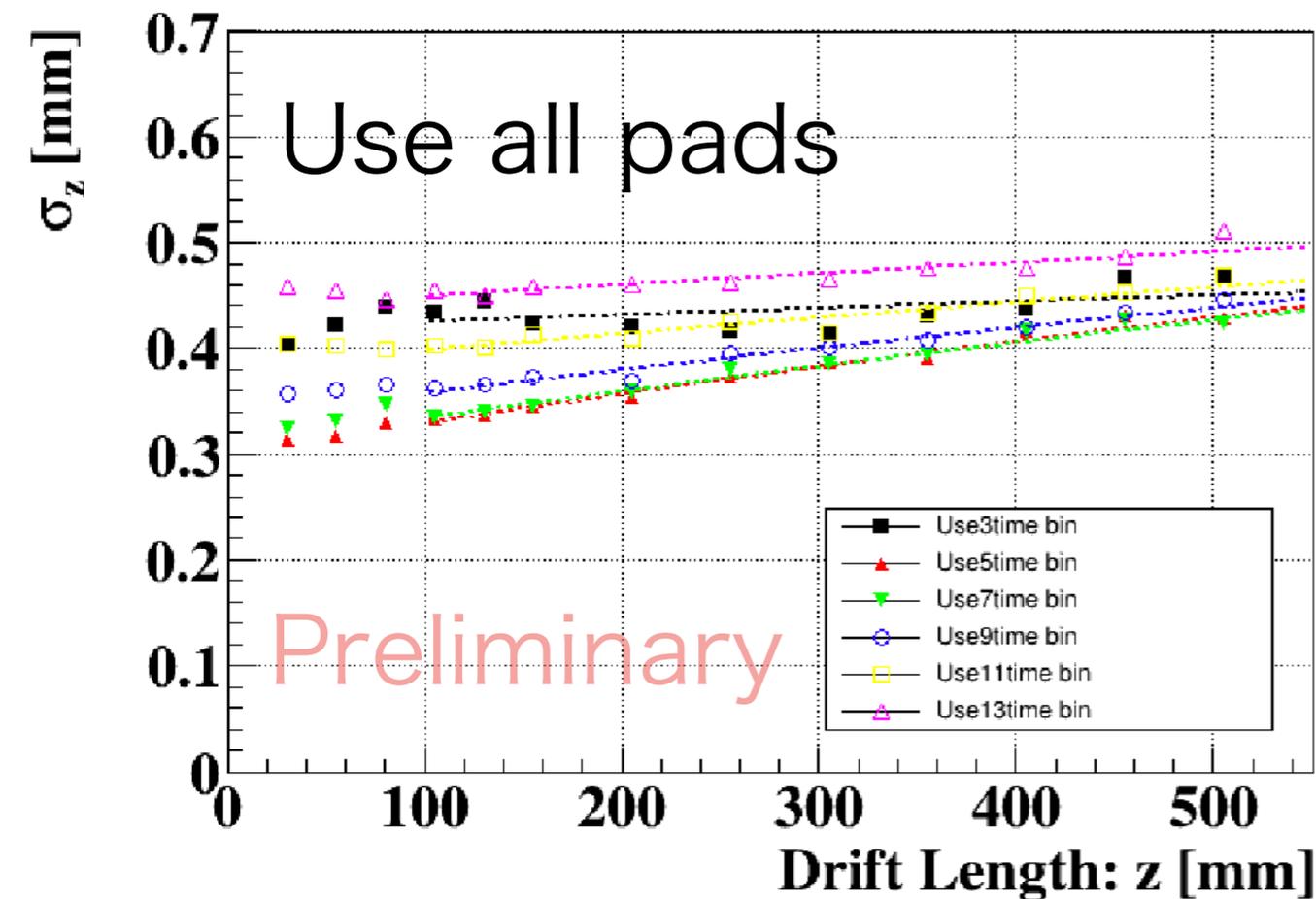


Center of gravity

Inflection point

ZGM Resolutin

ZGM Resolutin



In the case of C.O.G, when we use 5 time bins, the time resolutions is the best.

Since inflection point method only use former part of pulse, resolution is not affected by # of time bins using time calculation.

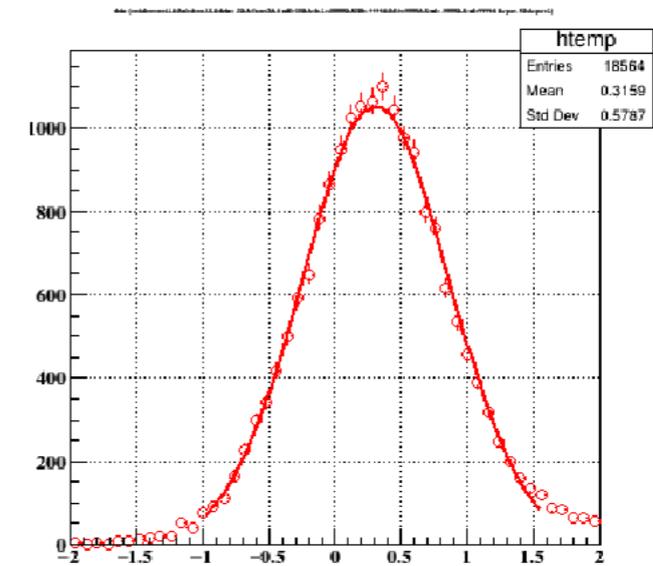
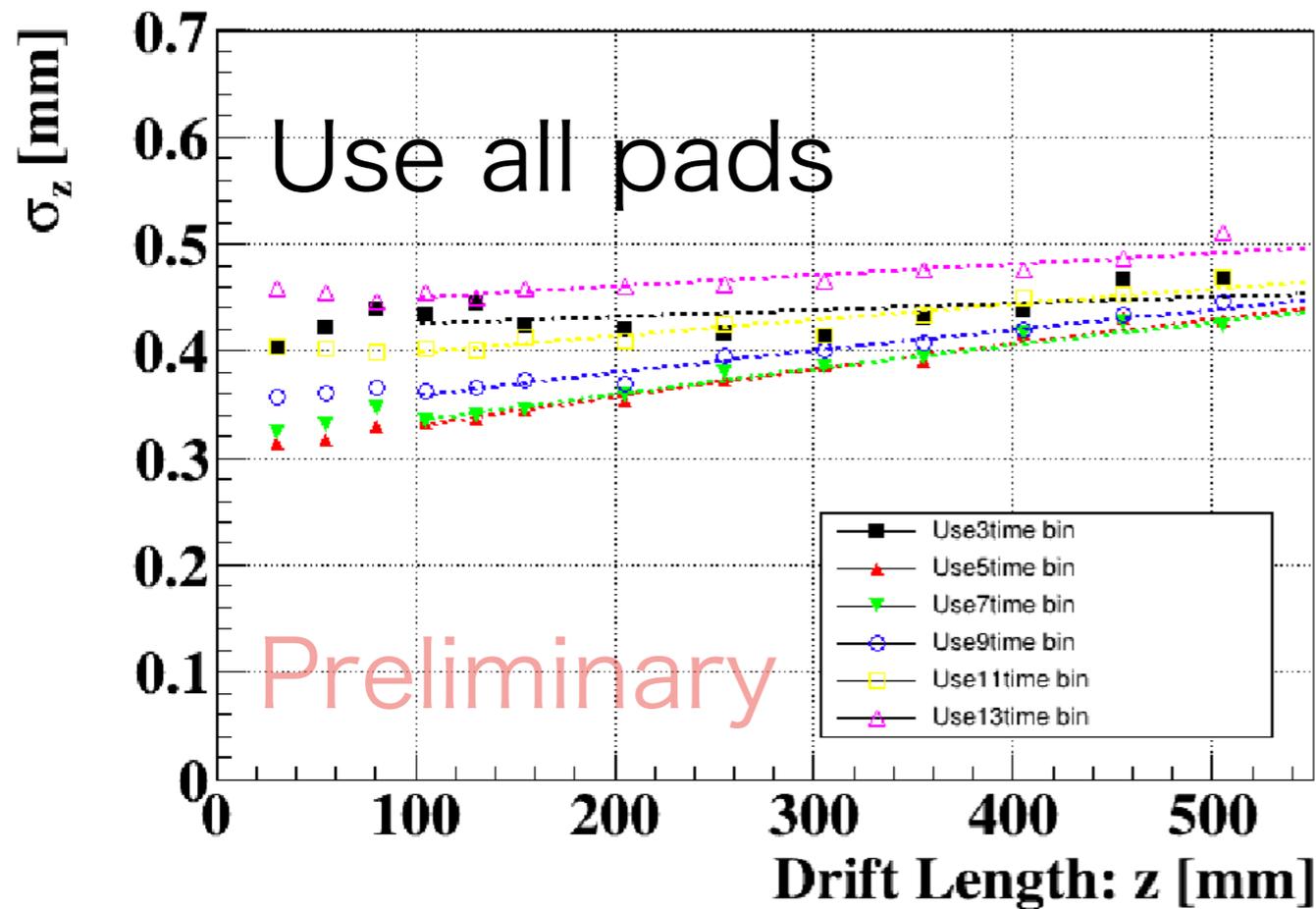
# C.O.G by # of time bins



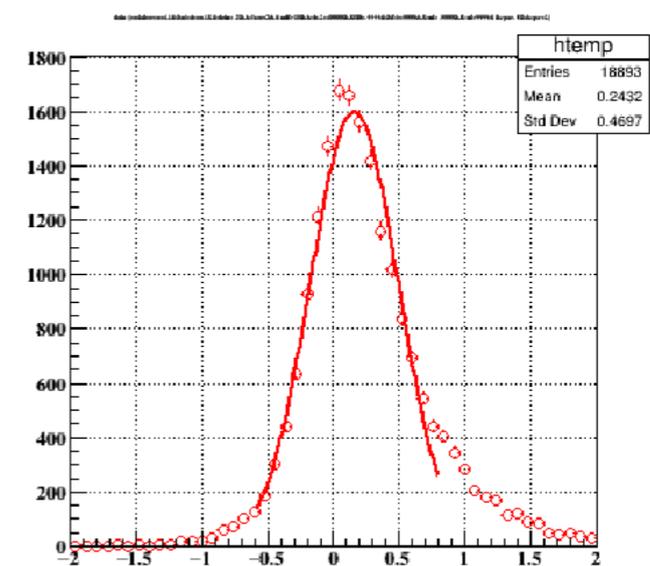
Drift length  $\approx$  15cm

Center of gravity

ZGM Resolutin



Use 17 time bins

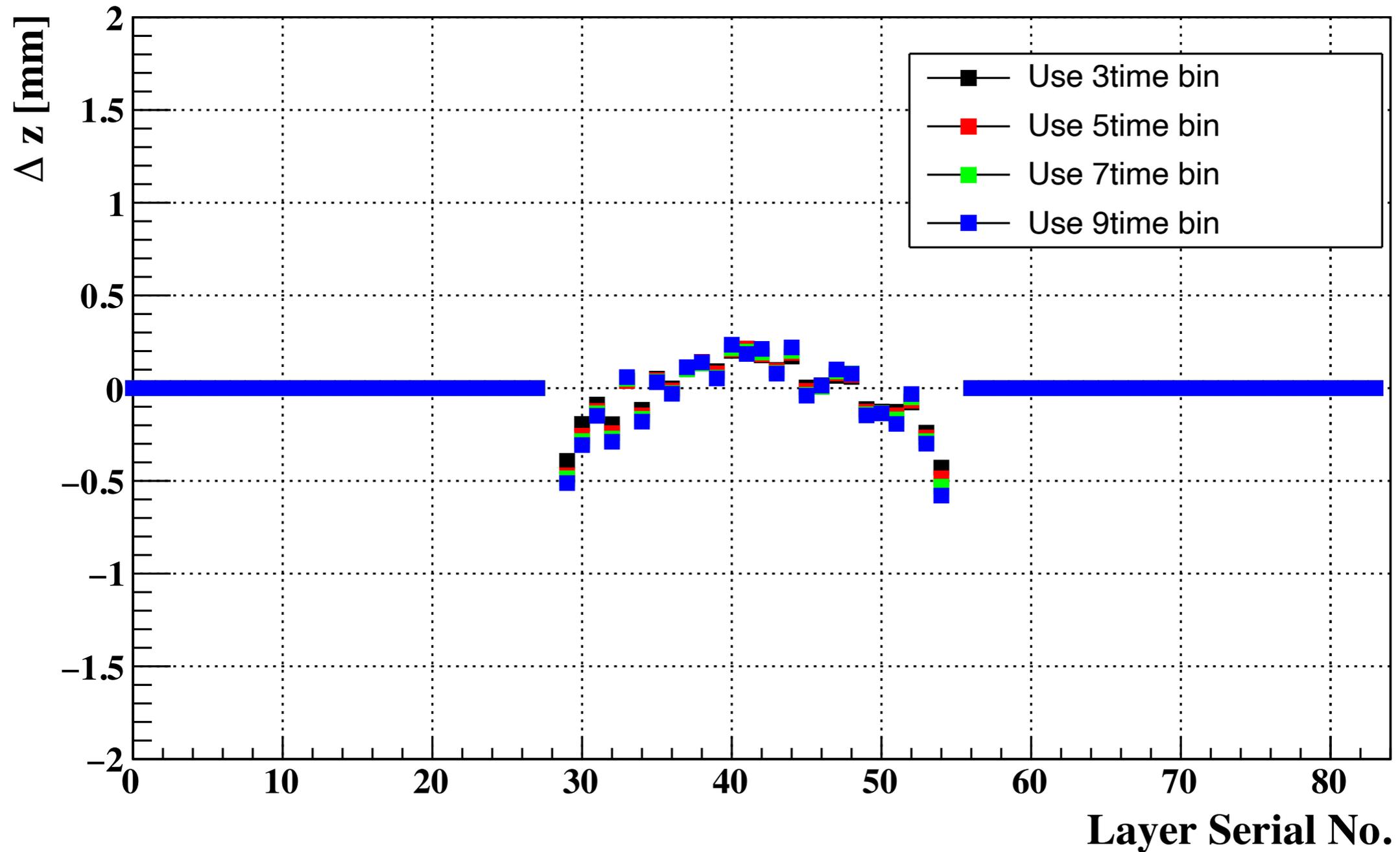


Use 5 time bins

# Comparison Z residual by # of time bins



Yoka Z Residual

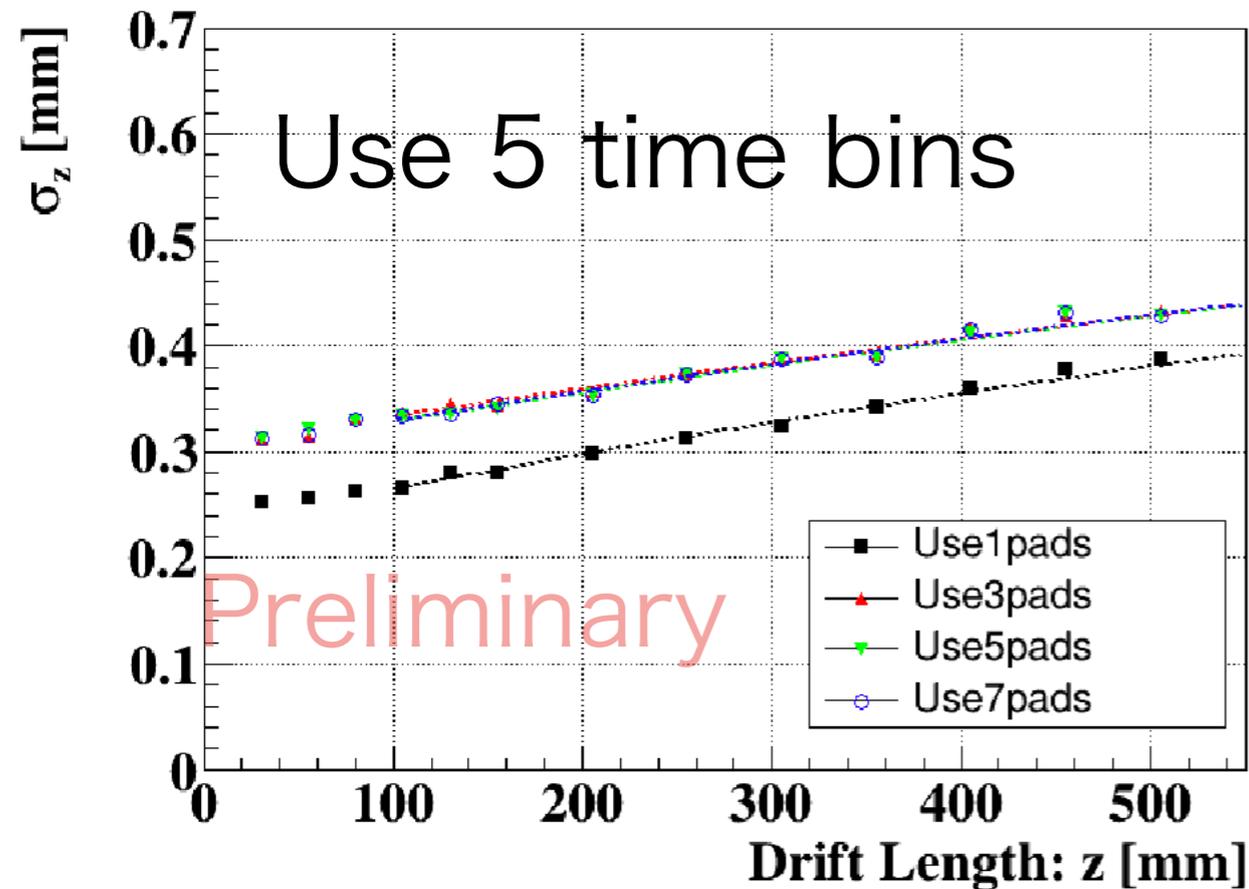


# Comparison by # of pads



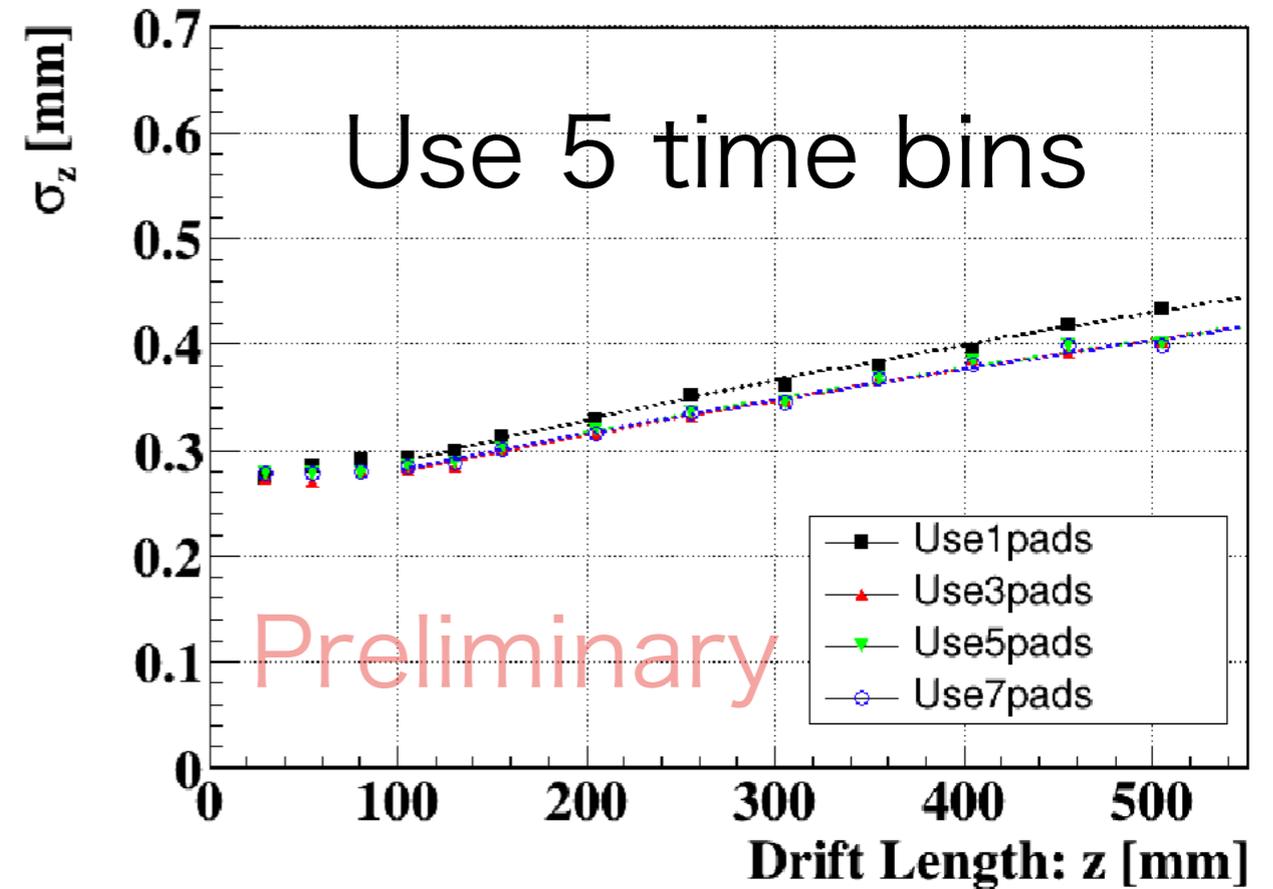
## Center of gravity

ZGM Resolutin



## Inflection point

ZGM Resolutin



Marlin framework

Both behave differently only when only one pad is used.

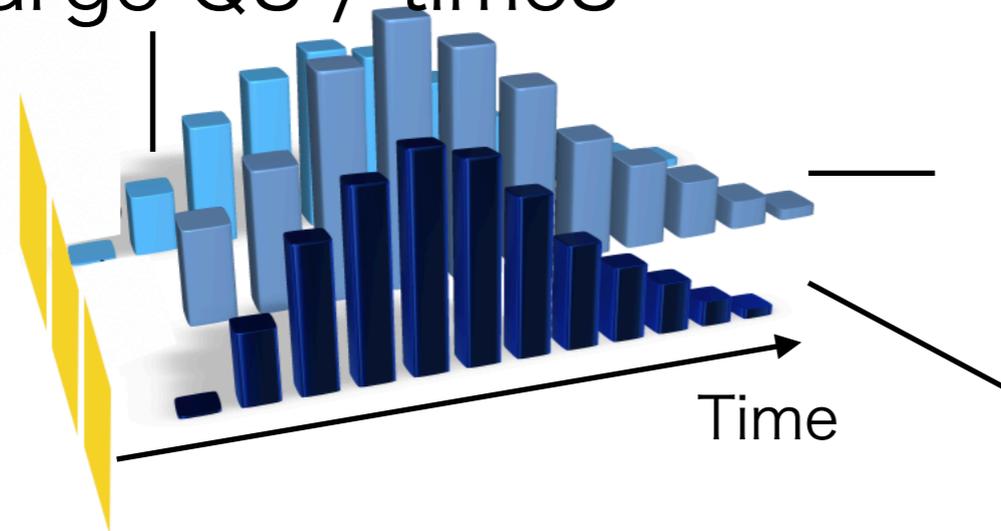
# How to gather pads?

We used to use 1 pad which having maximum charge

→ To use all information, we consider to use all pads

How to gather all pads?

Charge  $Q_3$  / time<sub>3</sub>



Charge  $Q_2$  / time<sub>2</sub>

Charge  $Q_1$  / time<sub>1</sub>

$$\frac{1}{\sum_i Q_i} \sum_i Q_i \times time_i$$

Add pulse time weighted by charge