

# IDT WG3 – MDI Activities

## Detector (Tracker) Alignment in ILD\*

Another trip into the past

Roman Pöschl



I am grateful to **Alexandre Gonnin** (IJCLab) who has dugged out the material for me  
All mistakes are mine

## IDT-WG3 MDI-BDS/Physis – Topical Meeting 27/1/22

\*For SiD see e.g.

[https://agenda.linearcollider.org/event/7014/contributions/34575/attachments/30232/45191/SiD\\_vtx\\_trk\\_santander16.pdf](https://agenda.linearcollider.org/event/7014/contributions/34575/attachments/30232/45191/SiD_vtx_trk_santander16.pdf)

Lots information is taken from these documents

[arxiv:2003.01116](https://arxiv.org/abs/2003.01116)

International Large Detector

[Attached to indico page](#)

## LETTER OF INTENT

### Aligning the ILD Tracker: Status Report and Answers to IDAG

---

## INTERIM DESIGN REPORT

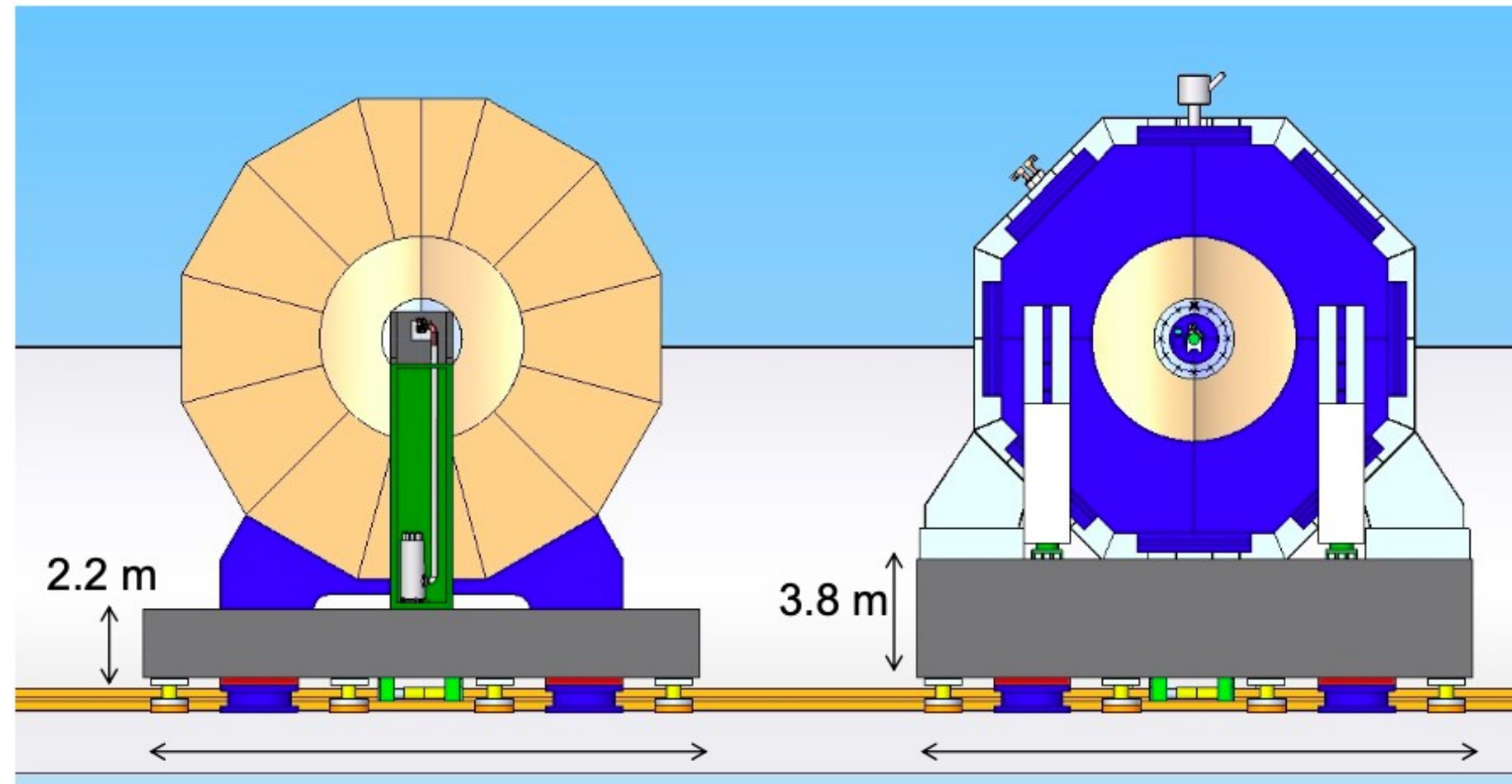
---

The ILD Concept Group

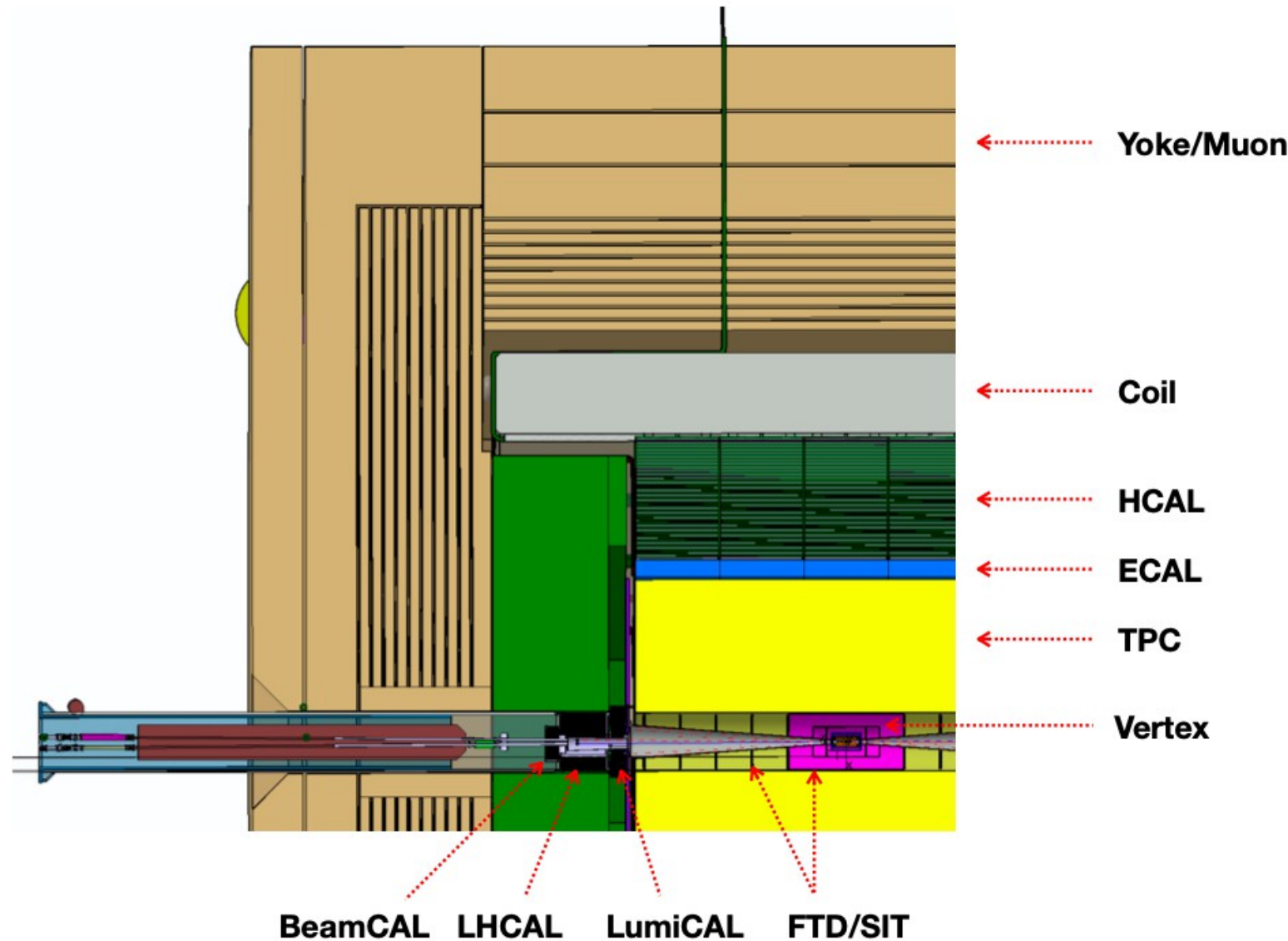


The ILD concept group

The ILD tracker alignment task force:  
T. Behnke, R. De Masi, M. Fernandez, D. Gamba, D. Imbault, T. Matsuda, P. Mereu, D. Peterson, Y. Sugimoto, A. Savoy-Navarro, R. Settles, J. Timmermans, M. Vos, M. Winter, H. Yamamoto



- According to the previous documents two “operation principles” have an impact on alignment
  - Push-pull operation
  - Power pulsing of detectors
- Both may require different approaches for alignment



## Parameters of tracking detectors

Barrel system							
System	$r_{in}$	$r_{out}$ [mm]	$z_{max}$	technology	comments		
VTX	16	60	125	silicon pixel sensors	3 double layers at $\sigma_{r\phi,z} = 3.0 \mu m$ $\sigma_t = 2-4 \mu s$	$r_0 = 16, 37, 58 \text{ mm}$ (layers 1-6)	
SIT	153	303	644	silicon pixel sensors	2 double layers at $\sigma_{r\phi,z} = 5.0 \mu m$ $\sigma_t = 0.5-1 \mu s$	$r = 155, 301 \text{ mm}$ (layers 1-4)	
TPC	329	1770	2350	MPGD readout	220 ( $163^\circ$ ) layers $1 \times 6 \text{ mm}^2$ pads	$\sigma_{r\phi} \approx 60-100 \mu m$	
SET	1773	1776	2300	silicon strip sensors	1 double layer at $\sigma_{r\phi} = 7.0 \mu m$	$r = 1774 \text{ mm}$ $\phi_{stereo} = 7^\circ$	
End cap system							
System	$z_{min}$	$z_{max}$	$r_{in}$	$r_{out}$	technology	comments	
FTD	220	371	153	153	silicon pixel sensors	2 discs	$\sigma_{r\phi,z} = 3.0 \mu m$
	645	2212	300	300	silicon strip sensors	5 double discs	$\sigma_{r\phi} = 7.0 \mu m$ $\phi_{stereo} = 7^\circ$

Envisaged resolution sets boundary conditions for needs on alignment

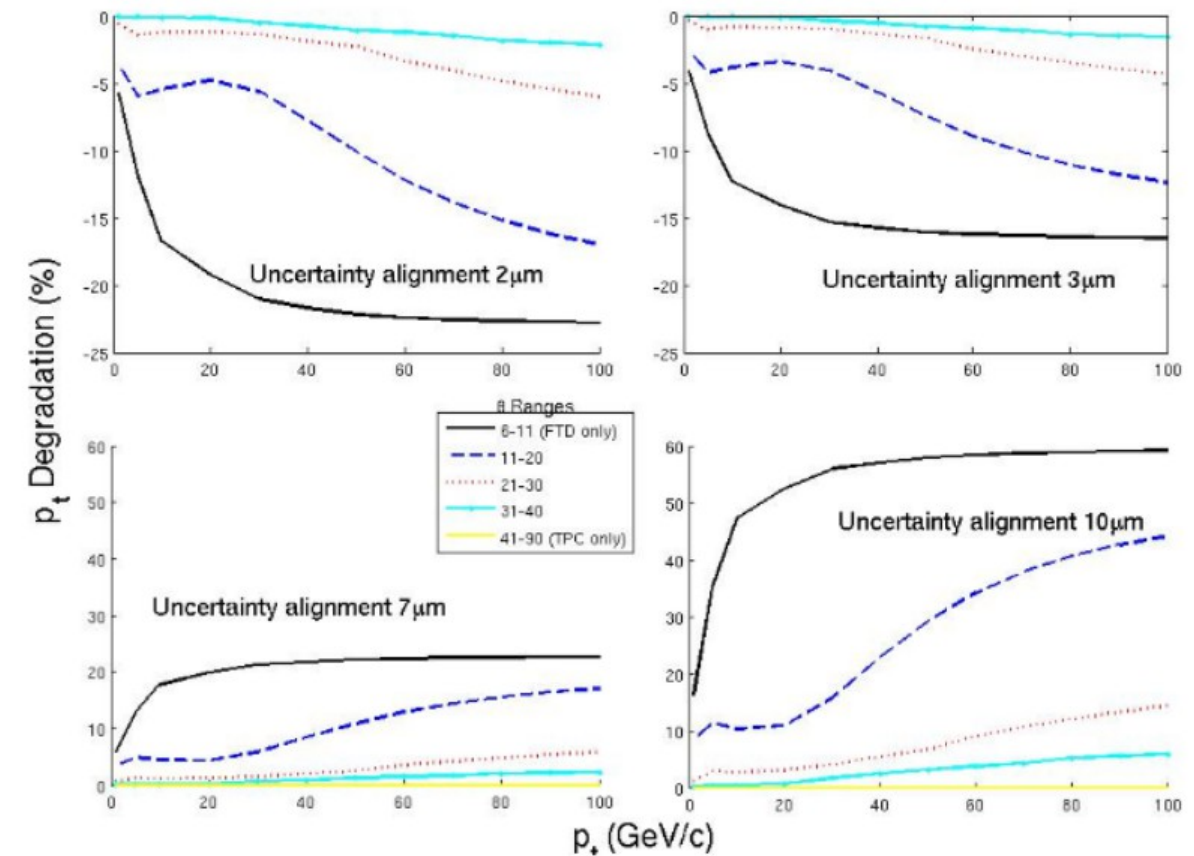
Remark: Do focus on trackers here but I don't forget that also the calorimeters in particular  
The LumiCal need a "diabolic" precision (see Wolfgang's talk in earlier meeting)

- coherent displacement of the VTX,  $2.8 \mu m$ ;
- coherent displacement of the SIT,  $3.5 \mu$ ;
- coherent displacement of the SET,  $6 \mu m$ ; and
- coherent displacement of the TPC,  $3.6 \mu m$ .

+ distortions that results in a sagitta in the TPC of 20um

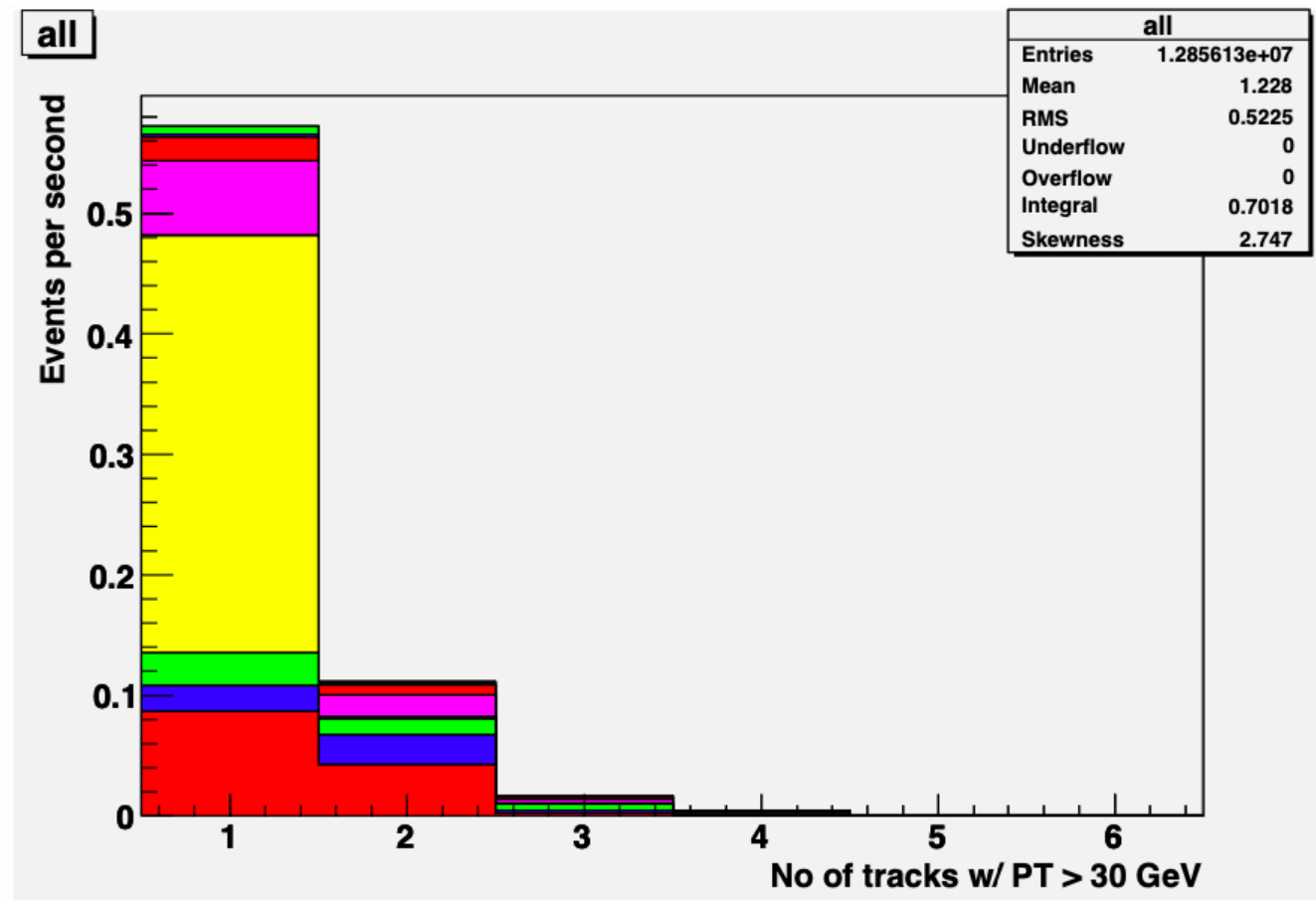
- “Intrinsic alignment” of the detecotors has to be controlled extremely well
- Reduction of degrees of freedom from  $\sim 100000$  to 26

## Effect on misalignment of forward disks (relative to “tolerated” misalignment of 5um)



Mis-alignment +/- 2um around “tolerated” value changes track resolution by  $\sim 30\%$

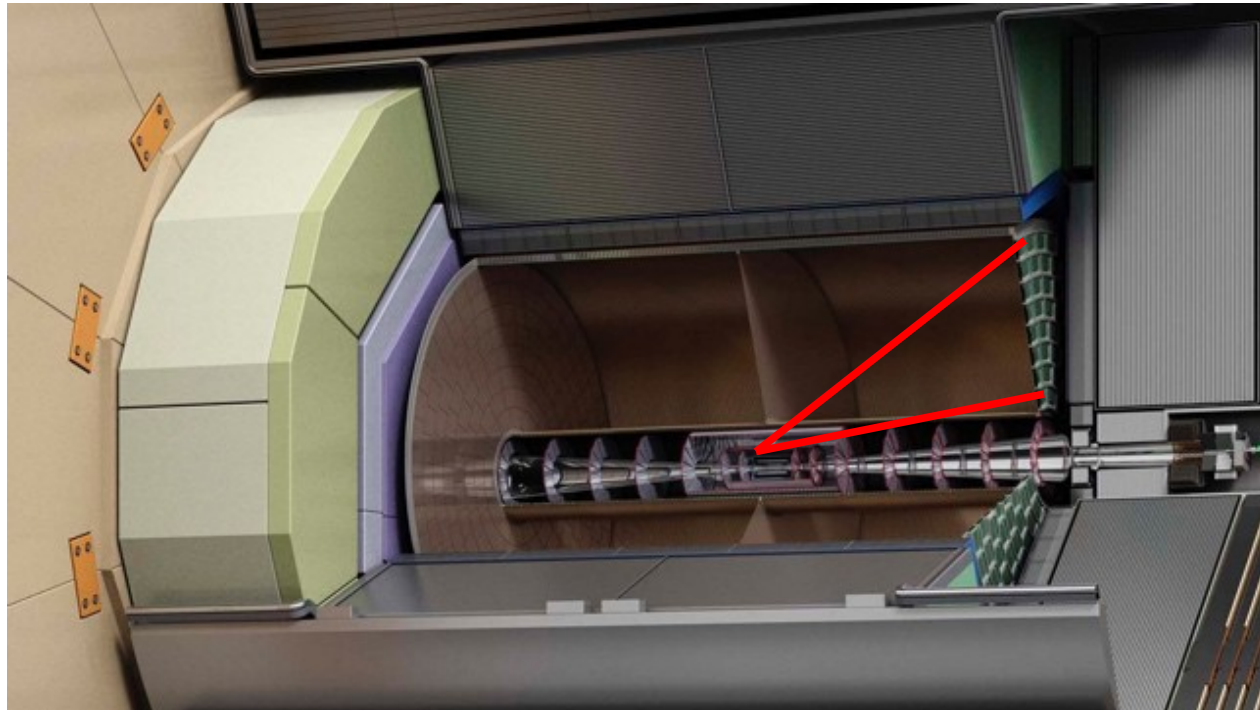
Number of tracks for 500 GeV running  
(color coding see attached note)



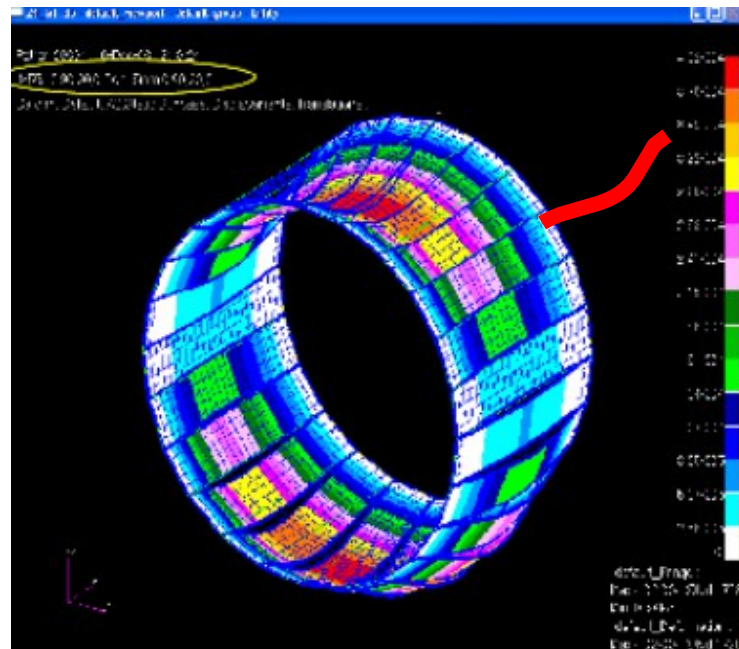
- $\sim 10^6$  tracks with  $p_T > 30$  GeV (for  $L=2 \times 10^{34}$  cm<sup>-2</sup>s<sup>-1</sup>)
- Compare with 60000 muon pairs/running year
- At 250 GeV maybe some more but number of hard tracks should decrease
  - Needs to be studied

Z-pole running for alignment?

- Short ( $\sim 1$  day) running on Z pole after each push-pull operation
- $L=1 \text{ pb}^{-1} \Leftrightarrow 30000$  Z events yielding around 1000 muon pairs
  - Felt to be feasible in IDAG Document
- **Caveats**
  - Not enough for full calibration
  - Requires that machine can switch quickly between Z pole running and nominal running

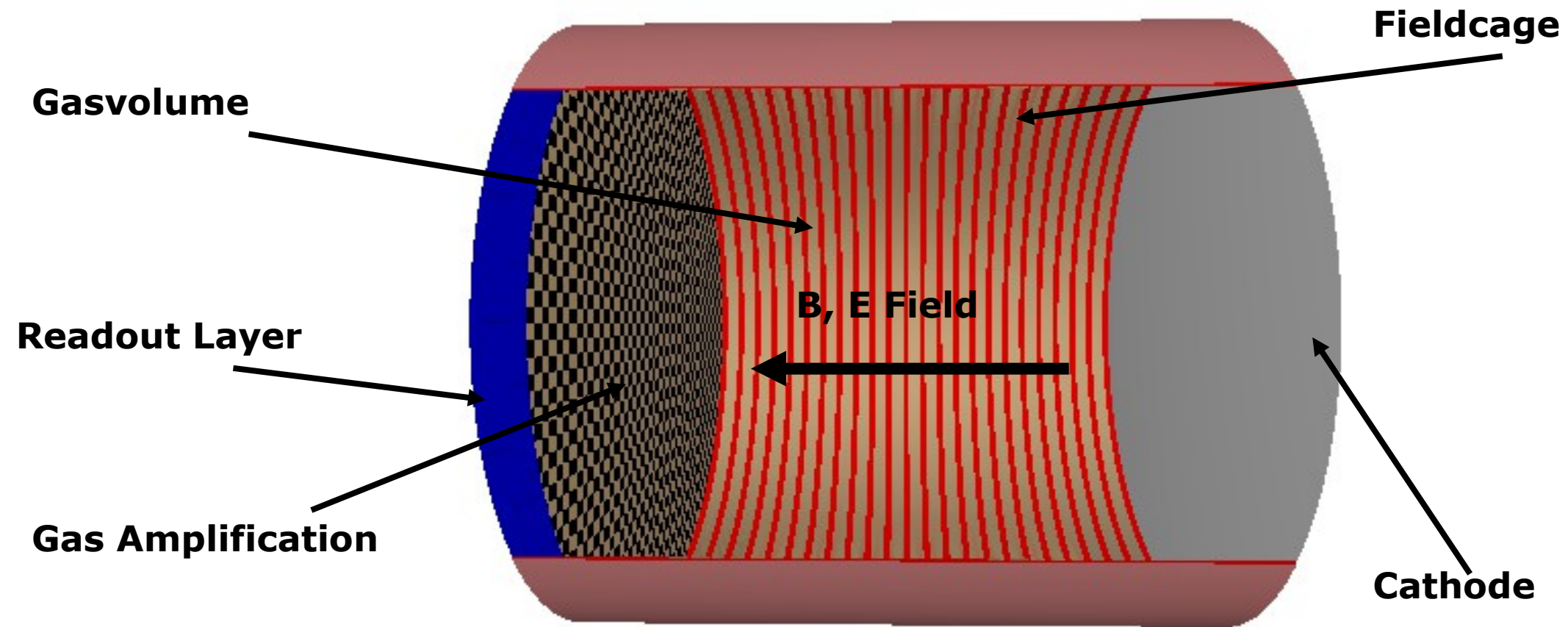


- **Laser Based System**
- Crosses layers in inner silicon detectors
- Require special pixels in outer silicon detectors



- Fibre Bragg System to monitor deformations

- Optical alignment system have to receive a special attention due to the limited capacities for track based alignments
- They have to react quickly (Order of seconds) to impact during push-pull and on power pulsing
- The integration of the alignment system requires skillful engineering work
- Misalignment can compromise the precision measurements
  - Corrective measures if a misalignment is measured?



- TPC components can be manufactured to a precision of 60um and better
- Laser system to mimick straight tracks
- Light shone on cathode surface to create a charge pattern with the help of an appropriate coating
- Don't forget that a precise field mapping of of B-Field is required  $\frac{dB}{B} \sim 10^{-4}$





- Short and for sure highly incomplete overview on ideas and studies on the alignment of the ILD Detector
- Alignment strategy needs to take push-pull and power pulsed operation into account
- Limited possibilities for track based alignment
  - Relatively small statistics
  - Alignment with Z-Pole events requires flexibility of machine
- Precise and fast reacting optical alignment systems will become of paramount importance
- The capability to align the detectors after push-pull will have an impact on the operation mode of the Project
- **News: The preparation of today's meeting brought us in contact with Armin Reichold (Oxford)**
  - Achim developed and commercialised an alignment system for ATLAS and has recently implemented an alignment system at FAIR (I don't know details at the moment)
  - Meeting with Achim on Feb. 2<sup>nd</sup> 5pm CET
  - Thanks to Tom and Phil for having established this contact

Backup