

# Study on timing resolution of APD sensors with test beam



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# ILD and ECAL

## ILD (International Large Detector)

- Detector to be placed at the collision point of the ILC
- Main components: Vertex, TPC, ECAL, HCAL, Coil

## SiW-ECAL

- Sandwich calorimeter (30 layers)
- Absorption layers : Tungsten

Detection layers : Si (Pixel size:  $5 \times 5 \text{ mm}^2$ )  
or Scintillator

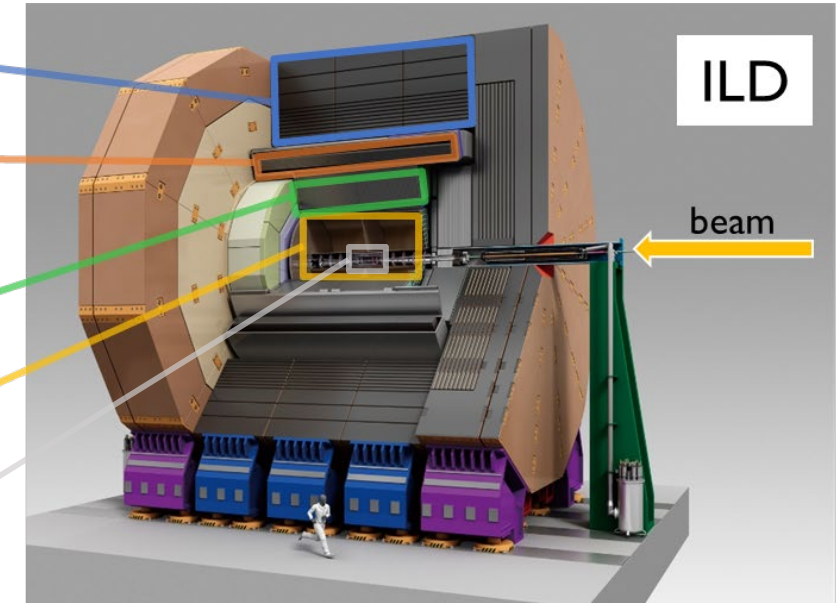
Yoke & muon detector

Coil

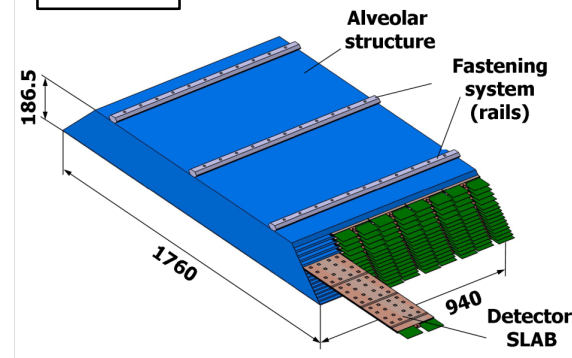
HCAL & ECAL

TPC

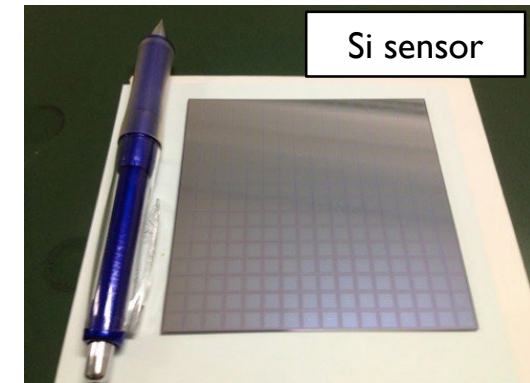
Vertex



ECAL



Si sensor



5.5 mm x 256 pixels

# Particle ID of hadrons and timing resolution

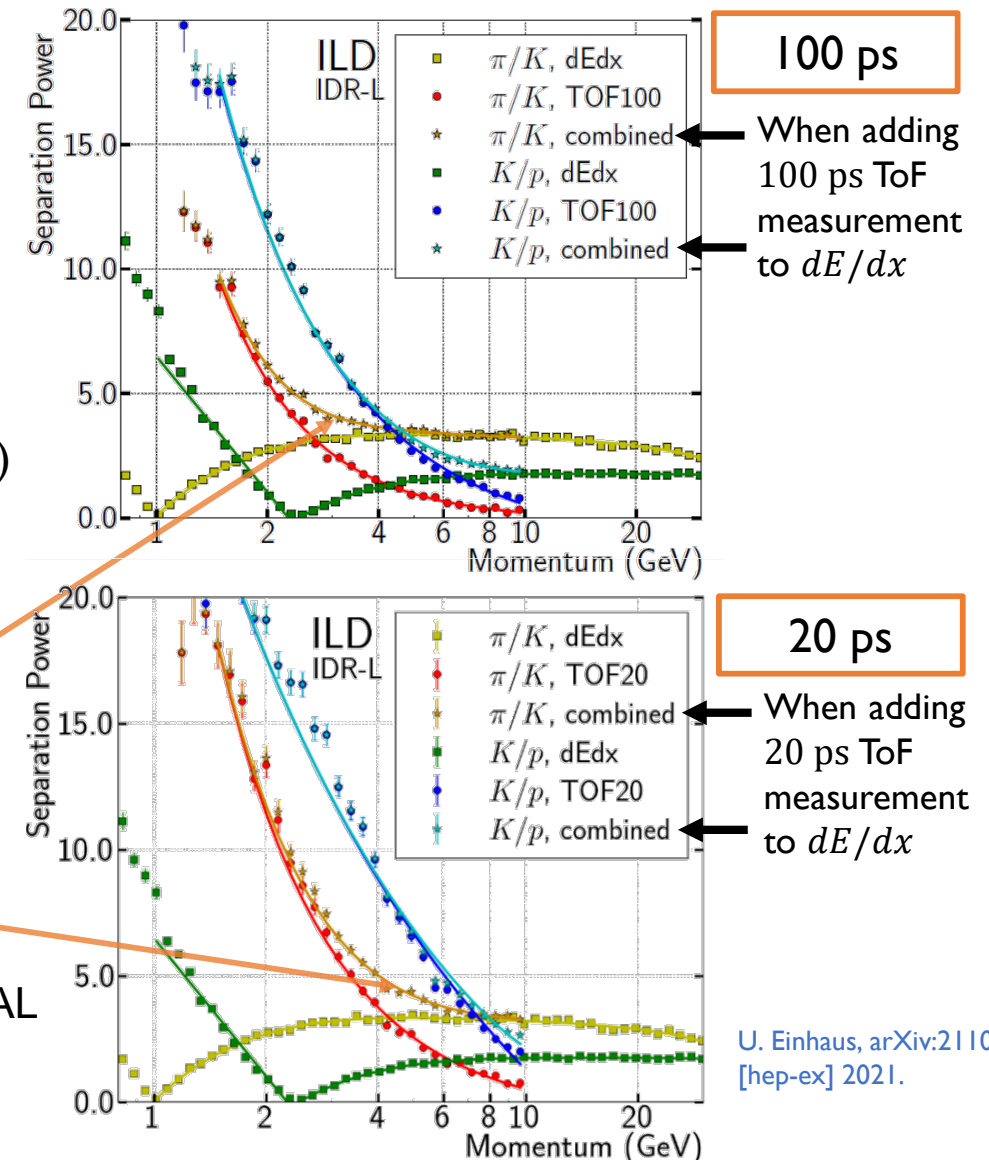
## Particle ID of hadrons

- Only measurement of  $dE/dx$  and momentum
  - ID of  $K/\pi \sim 3\sigma$     ID of  $K/p < 2\sigma$
  - There exists momentum ranges where we can't identify: 1-3 GeV
- Better separation power can be obtained by adding Time-of-Flight (ToF)
- Possible to separate ( $5\sigma$ )  $\pi/K$  up to 4 GeV by 20 ps ToF with  $dE/dx$

## Timing resolution and momentum range

- ECAL with standard Si:  $\sim 100$  ps    up to 3 GeV ( $3\sigma$ )
- LGAD: 20–30 ps    up to 5 GeV ( $3\sigma$ )

→ we are planning to use LGAD to replace sensor of a part of ECAL



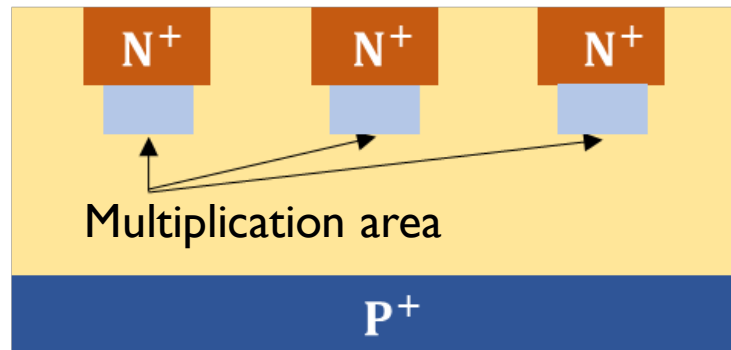
U. Einhaus, arXiv:2110.15115  
[hep-ex] 2021.

# Type of LGAD

## LGAD (Low Gain Avalanche Detector)

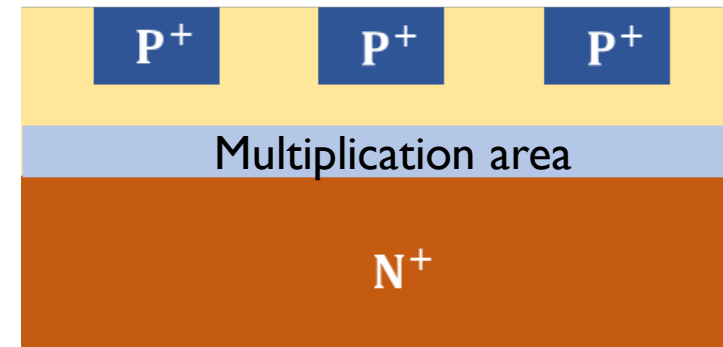
- Silicon sensor with internal avalanche multiplication mechanism
- Studies of LGAD in ATLAS group have achieved timing resolution of about 26 ps

### Reach-through type



- Multiplication area is not uniformly formed
- Amplification ratio depends on the hit position of the particle

### Inverse type



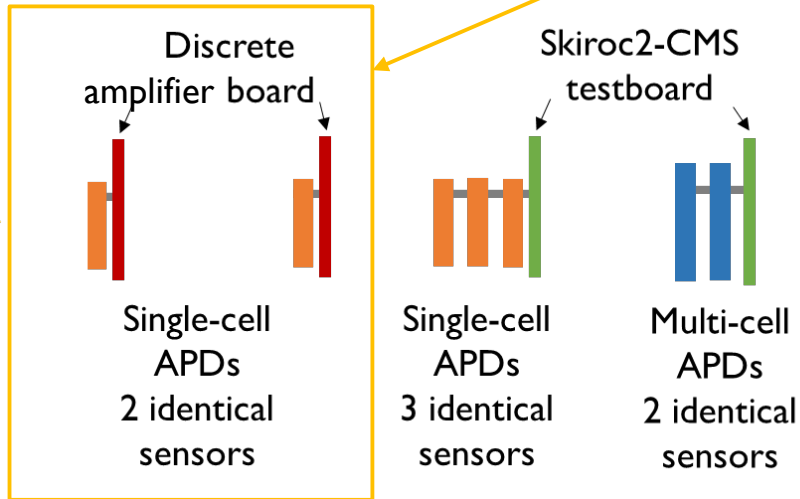
- Multiplication area is uniformly formed
- Uniform response is expected regardless of the hit position

# Test beam with discrete amplifier

6-8 Oct. 2021 at ELPH, Tohoku University

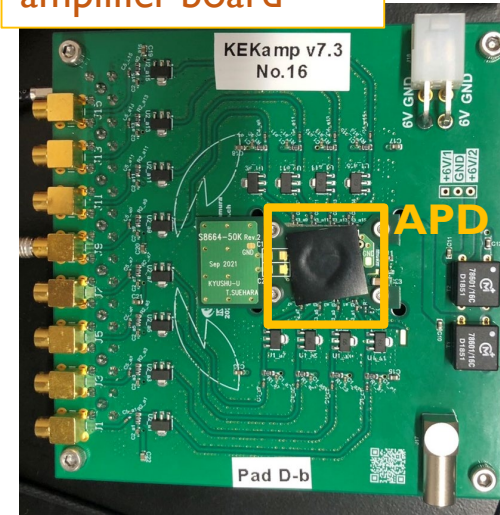
- 3 days × 12 hours positron beam: ~770 MeV

Setup

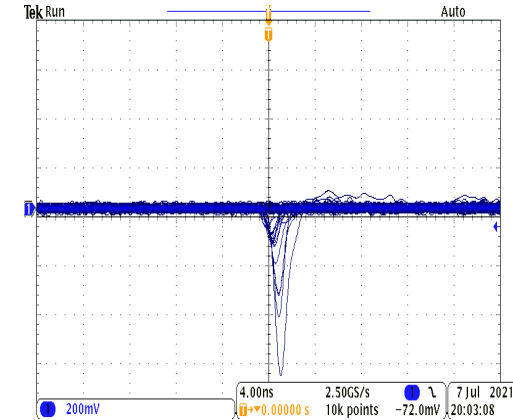


APD

amplifier board



Waveform output from the amp. board



Rising time  
~1 nsec

Amplifier chip



- GALI-S66+ (Mini-circuit)
- Gain: 20 dB
- Wide bandwidth 3GHz

APD No.	Type of APD	$V_{br}$ [V]	size [mm]	capacity [pF]
S8664-50K	Inverse	416	5φ	55 pF
S2385	Reach through	160	5φ	95 pF

# Analysis method

## Set up

- The signals from the two APDs (APD1 and APD2) amplified by the amp. board are directly acquired and analyzed by an oscilloscope.

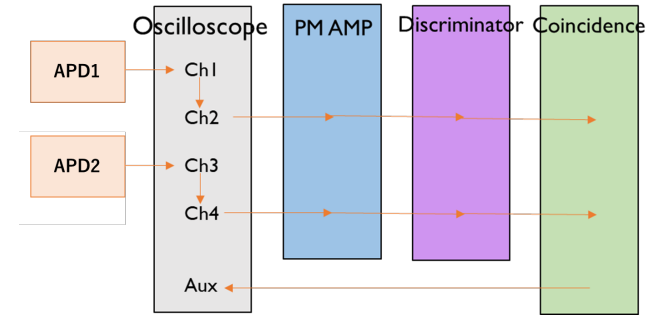
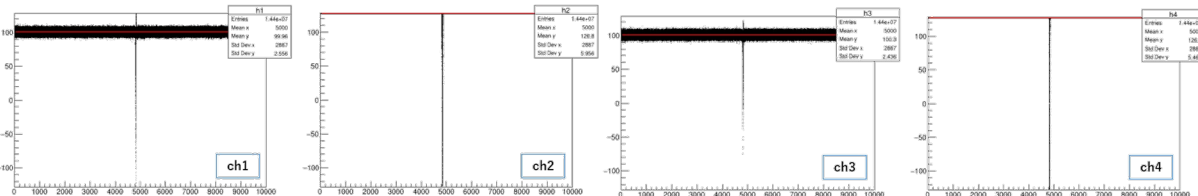
## Analysis method

signal from APD1 → ch1 (20 mV/div) and ch2 (2 mV/div)

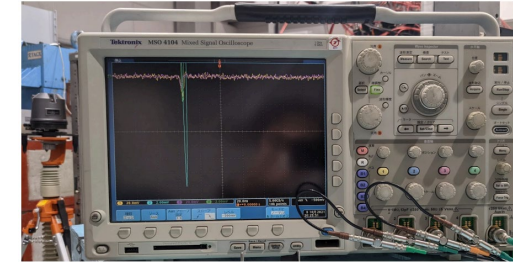
signal from APD2 → ch3 (20 mV/div) and ch4 (2 mV/div)

- Ch1 and ch3: obtain waveform height and timing information for large signals

- Ch2 and ch4: Obtain more detailed timing information for small signals



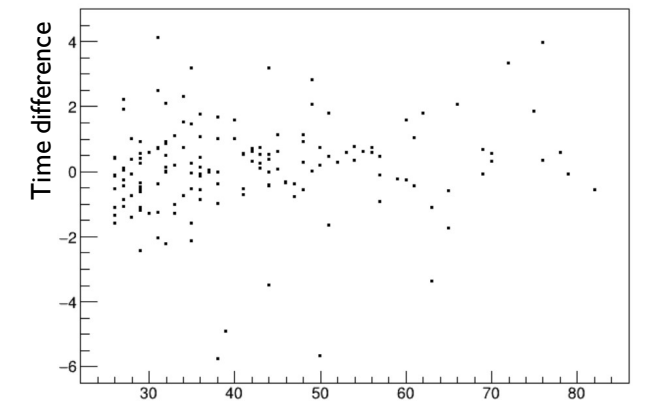
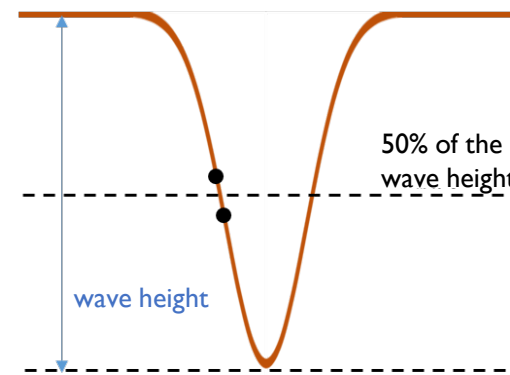
## Oscilloscope



MSO 4104 (Tektronix)

- 1 GHz, 5GS/s

Obtain the timing at the point where the voltage is 50 % of the wave height  
→ Estimate the timing resolution from the time difference between the two APDs.



↑ No effect of Timewalk

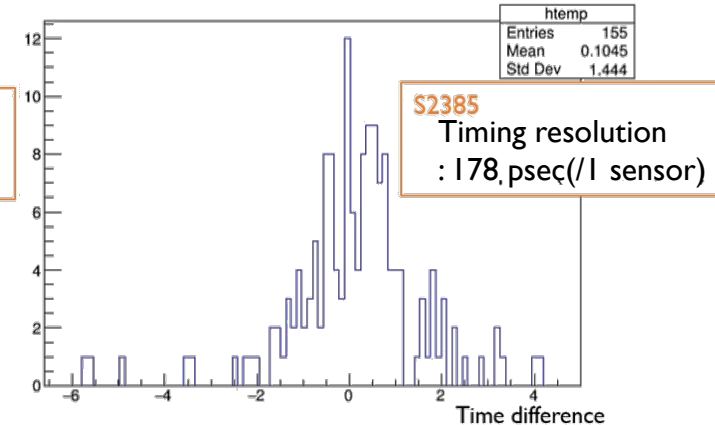
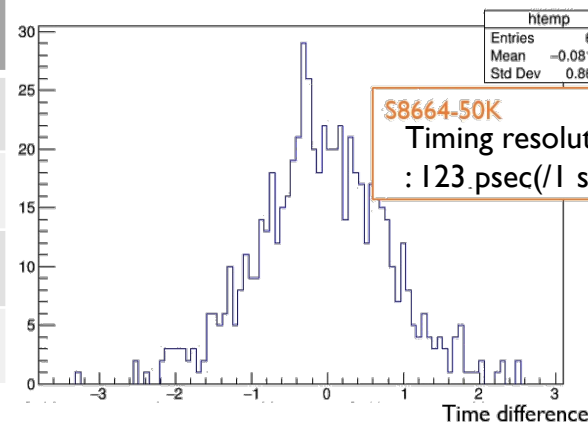
Wave height

# Result of timing resolution

## Result

APD sensor	Cut of charge	Timing resolution
S8664-50K (Inverse type)	> 18 fC	123 ps
	> 36 fC	63 ps
S2385 (reach through type)	> 18 fC	178 ps
	> 36 fC	89 ps

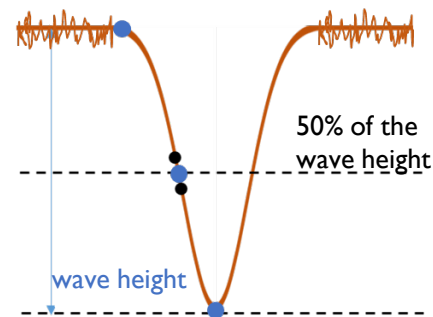
Time difference between the two APDs (charge > 18 fC)



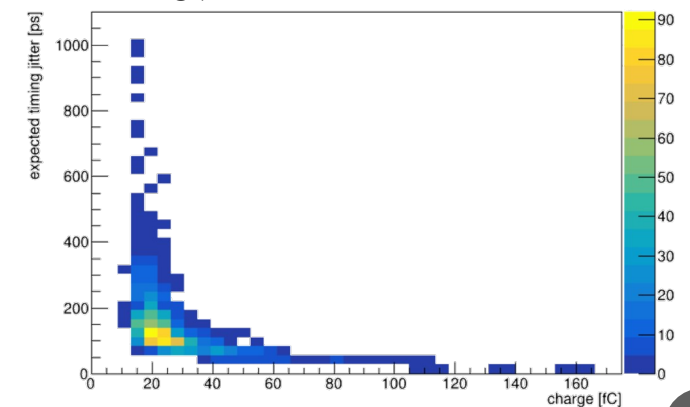
- Timing resolution of S8664-50K is better
  - Difference in capacitance related to signal rising time (S8664-50K: 55 pF S2385: 95 pF)

## Evaluation of timing jitter due to noise

- Pedestal variation as a noise effect,
  - add this effect to the pedestal, wave height, and 50% of wave height points
- Events with charge > 18 fC      S8664-50K: 120 ps,    S2385: 200 ps
- Events with charge > 36 fC      S8664-50K: 62 ps,      S2385: 106 ps
- Most of the time resolution is affected by noise caused by sensors and readout circuits



Relation between Charge of signal and Timing jitter due to noise





# For achieve high timing resolution

Timing resolution factors:  $\sigma_t^2 = \sigma_s^2 + \sigma_n^2$

- $\sigma_s^2$ : Uncertainty in the timing response of the sensor itself
  - **Landau noise**: waveform changes depending on whether energy deposit occurs more on the upper side or lower side of the sensor.
    - Making the sensitivity layer thinner decrease Landau noise, but the signal becomes smaller, so the S/N ratio becomes worse.  
(It seem that the thickness of sensitive layer of S8664-50K is 5  $\mu m$  )
  - **Avalanche amplification fluctuation**: Uncertainty in time for accelerated electrons to knock out surrounding electrons
- $\sigma_n^2$ : Uncertainty caused by noise
  - **Capacitance of sensor**: The smaller the capacitance of the sensor, the smaller the rise time of the waveform.
    - Capacitance is proportional to the size of the sensor → Smaller sensors are less affected by noise.
  - **Thermal noise**: caused by high temperatures in amplifiers and sensor → need cooling
  - **Noise due to disturbance** to the conduction path between the sensor and the amplifier or due to HV
    - devise wiring, Stabilization of supply voltage, etc...



# Plan for the next year

- Investigate response of the sensor in more detail
  - 2 GHz oscilloscope (R&S RTO64) to check actual rise time
  - Noise study (by temperature, by connection, difference by unit variation, etc.)
  - Dependence on capacitance: check rise time and noise with different size of the sensor
- Current APD (S8664-xx) seems to have too low signal (= too thin active thickness (5  $\mu\text{m}$ ?))  
Try other solutions
  - LGADs designed for ATLAS (reach-through)
  - New ones? (need cooperation of Hamamatsu but not too realistic, and having no fund)
  - Other than Hamamatsu? Cooperation with Europe?
- Misc
  - Position dependence (need to operate silicon strip)
    - Multi-cell measurement with SAMPIC (16ch, 1 GHz) module
  - Electronics (ALTIROC?)

# Summary

- LGAD have high timing resolution → Introduction of LGAD is expected to improve the timing resolution of ECAL
- Test beam with discrete amplifier to measure the performance of APD
  - Achieved 63 ps timing resolution with inverse S8664-50K using only large signals
  - Improved timing resolution by increasing the statistics of the large signal.
  - Increase the amount of charge by using an APD with a thicker sensitivity layer → Decrease the Jitter
  - Use an oscilloscope with good performance
  - Device to reduce noise...cooling of amplifier board, wiring etc...

BACKUP

# Timing resolution of Skiroc2-CMS

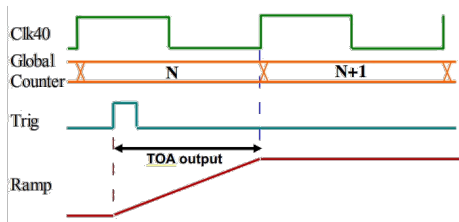
- Timing resolution  $\cong (\text{rising time})/(\text{S/N ratio}) + \text{digitization jitter} + \text{Landau noise} + \text{timewalk}$ 
  - noise of Skiroc2-CMS is large
  - **rising time** of Skiroc2-CMS fast shaper is large: 5 nsec
    - Value of **S/N ratio** ~250 required for 20 ps timing resolution equivalent to 600e- noise → too difficult
    - Fast shaper can be faster but S/N degraded (need detailed study)
  - **Digitization jitter** of Skiroc2-CMS: ~30 ps
  - **Landau noise**: waveform changes depending on whether energy deposit occurs more on the upper side or lower side of the sensor.
  - **Timewalk** can be corrected (S.Tsumura's talk)
- Noise reduction by better HV treatment
  - However, to achieve timing resolution 30 ps by noise reduction is difficult... → need another reading system

# Measurement with Skiroc2-CMS

ASIC for reading signals of silicon sensor

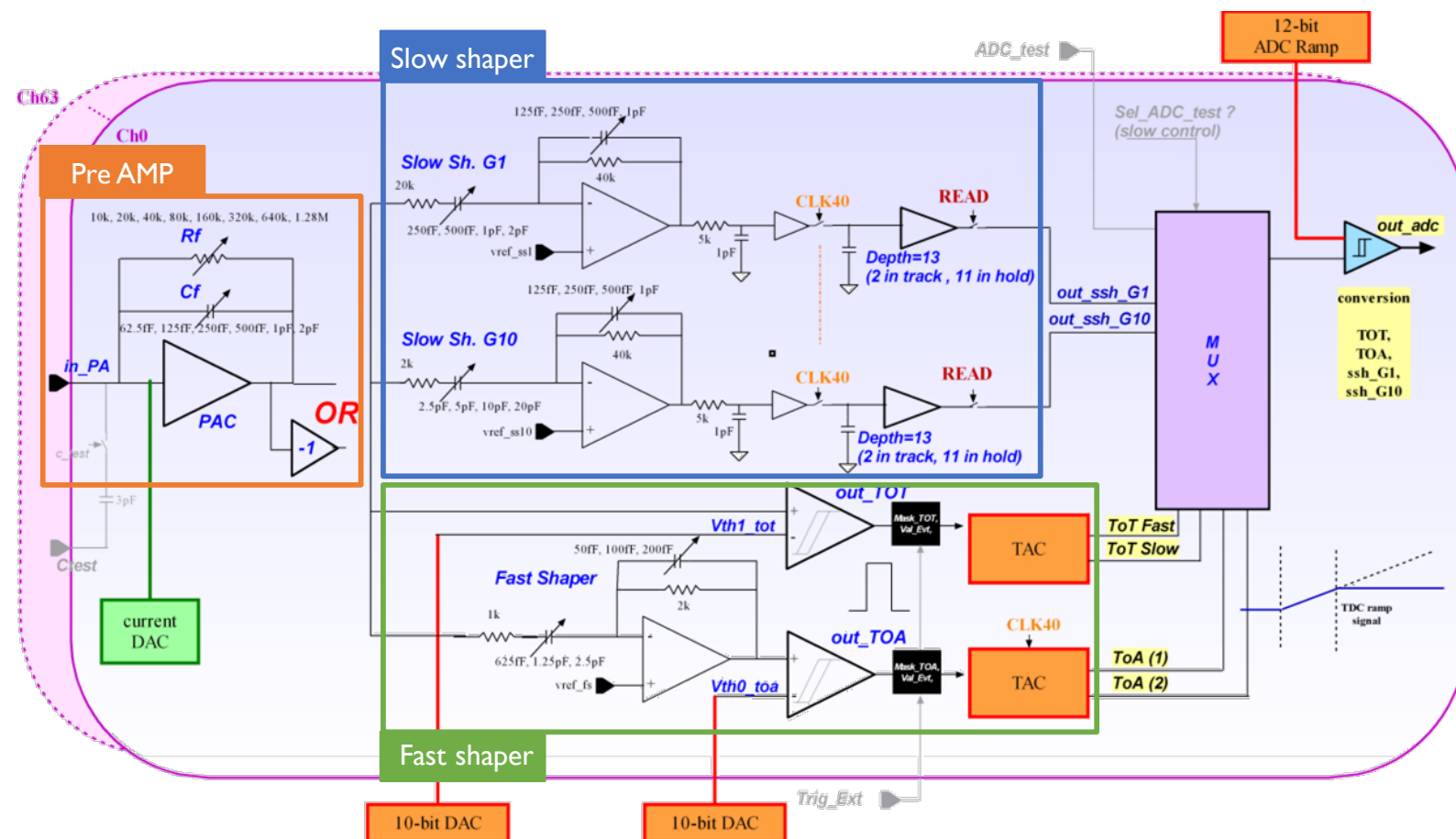
## TOA (Time Of Arrival)

- Timing information between the triggered time and the next internal clock



## ADC

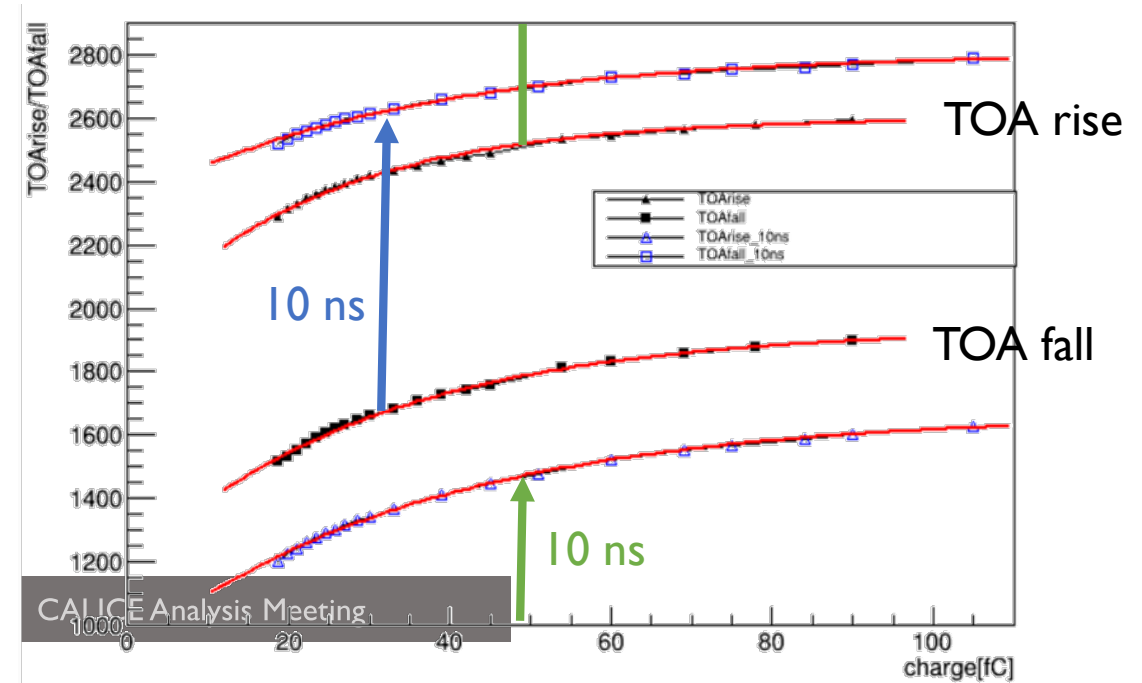
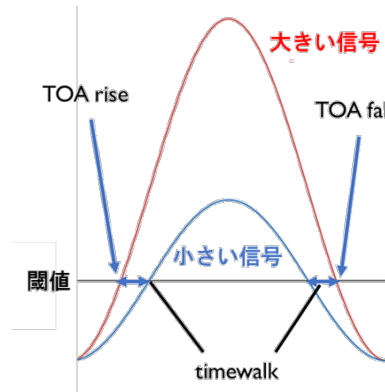
- 13 cells waveform digitizer at 50 MHz ring buffer



# Timewalk measurement

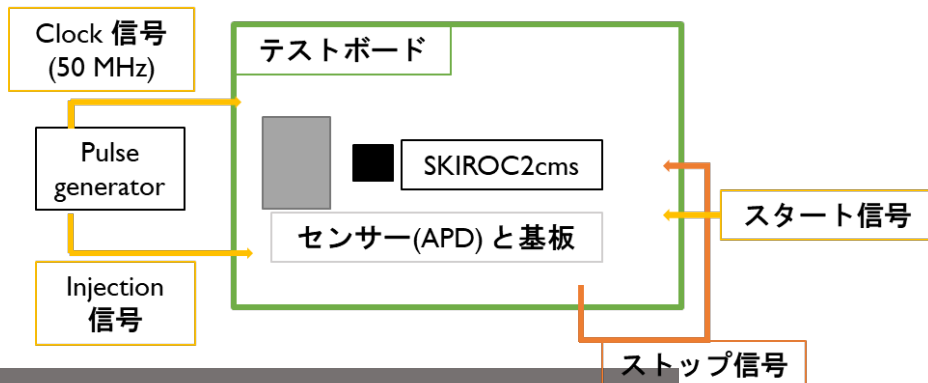
## Timewalk

- 入力された信号の大きさによって生じる時間情報の誤差
- 同じタイミングで入力されたとしても  
大きい信号のほうが小さい信号より  
閾値を超えるタイミングが早くなるため  
時間情報に誤差が生じる
- テストボードを用いてInjection信号の電圧を変えながら  
その時のTOAを記録することで、Timewalkを測定



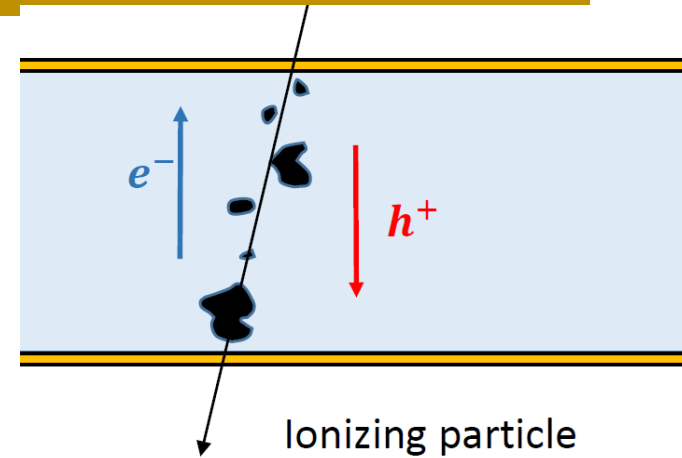
TOAと入力信号の電荷の関係から、  
timewalkが従う指数関数を決定

→実験データのtimewalk補正に使用



# TIMING LIMITATION FACTORS

- Landau fluctuations
  - Uncertainty on ratio of the energy deposit along the ionizing path
  - ~10% of the drift time
    - Typical silicon sensor (300  $\mu\text{m}$ , 300V)  $\rightarrow$  drift: 2 nsec  $\rightarrow$  typical contribution of Landau is ~200 psec
- To reduce the drift time
  - Thin sensors
    - 10  $\mu\text{m}$ , 10V  $\rightarrow$  drift: 70 psec, Landau fluctuation: 7 psec
    - Electric field in the avalanche region should not count (for avalanche silicon sensors)



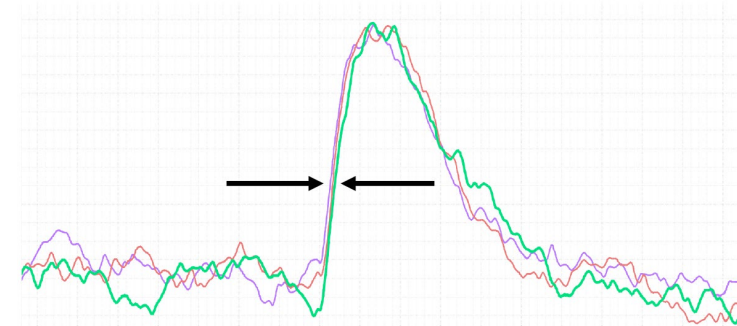
electron mobility 1350 V/cm s<sup>2</sup>



# TIMING LIMITATION FACTORS

- noise-equivalent electrons
  - Typical (hybrid): 1000 e-  
lower with monolithic
- Both ENC and rise time proportional to  $C_{in}$   
 $\rightarrow \sigma_t$  is proportional to  $C_{in}^2$
- MIP signal strength
  - 80 e- /  $\mu\text{m}$  x gain
    - Difficult to get high S/N ratio with thin sensors  
**trade-off with Landau noise**

Time jitter



Fast integration

$$\sigma_t = \frac{\sigma_V}{dV/dt} \cong \frac{ENC}{I_{Ind}}$$

eg. rise time 100 psec  
and S/N 10 gives  
10 psec timing jitter by noise