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Space-Point Calibration in the ALICE TPC

Jens Wiechula

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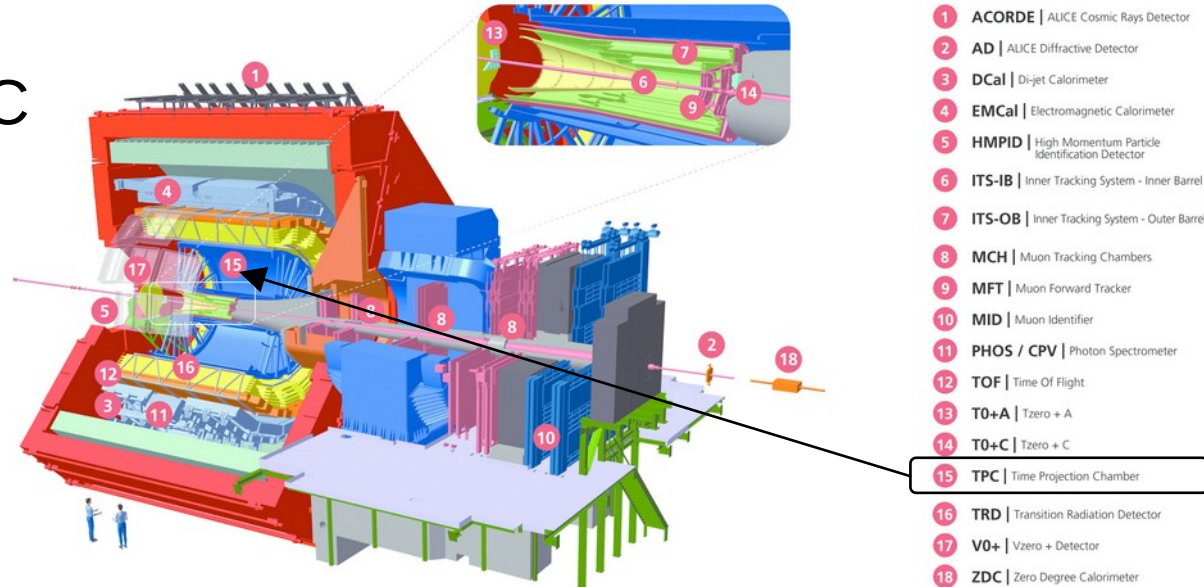
ALICE and its TPC

Technical overview

The ALICE Detector system



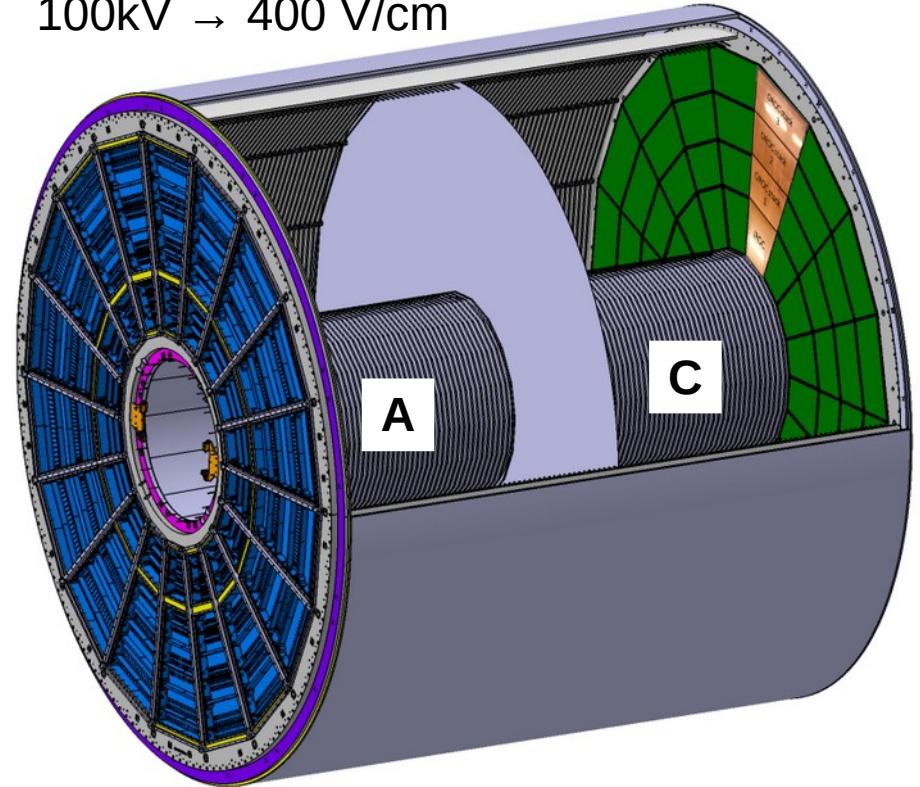
- Dedicated heavy-ion experiment at CERN LHC
- Running conditions
 - 50kHz Pb-Pb
 - Up to 5MHz pp, default 0.5-1MHz
- Main detector for particle identification and track reconstruction
 - Large-volume TPC



The ALICE TPC

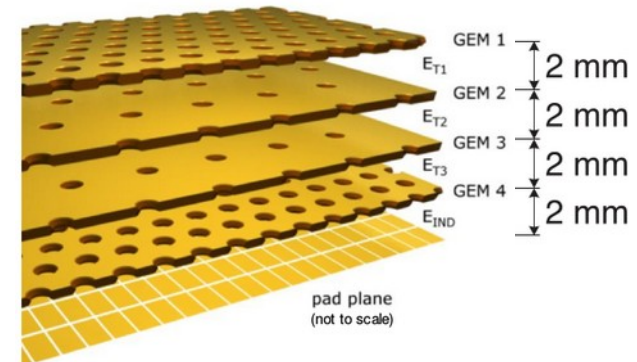
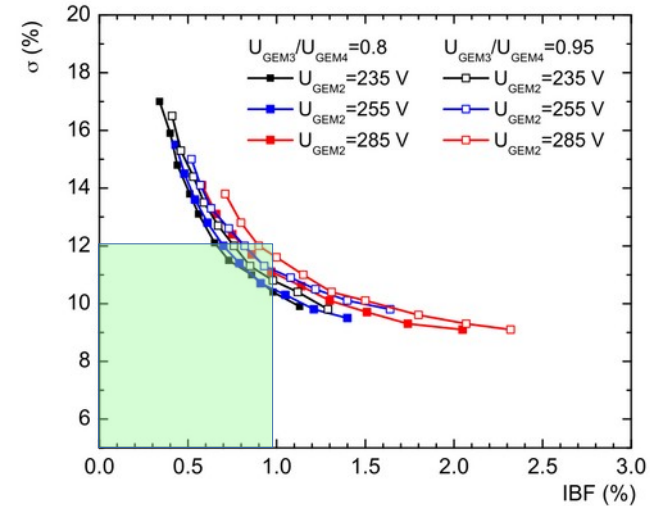
- Large volume TPC ($\sim 90\text{m}^3$)
- Gas: Ne-CO₂-N₂ (90-10-5)
- Drift voltage: 100kV, 94 μs drift time
- Two read-out halves, divided by central HV electrode
- 18 readout sectors in azimuthal direction
- Each sector divided into an inner and out readout chamber (IROC / OROC)

Central HV electrode (CE)
100kV \rightarrow 400 V/cm



Readout technology

- Readout technology:
Gas Electron Multipliers (GEMs)
 - Continuous readout
 - Good local energy resolution
 - Moderate Ion back flow
 - High operational stability
- Optimized operational point
 - Pitch layout S-LP-LP-S
 - HV settings



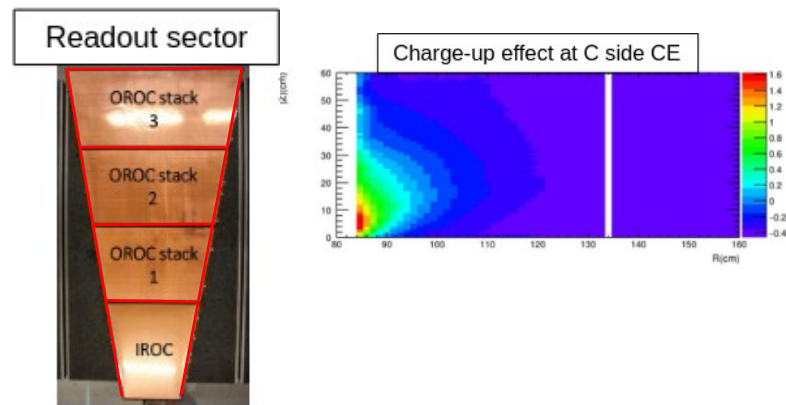
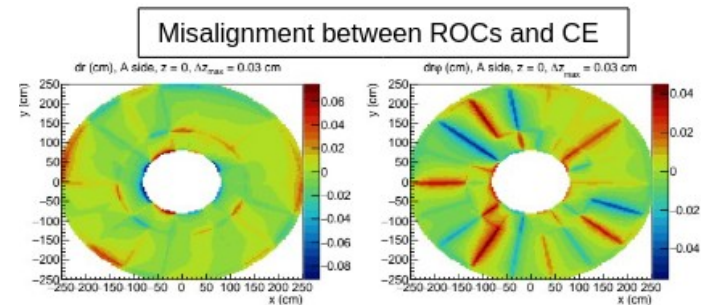
Space-point distortion contributions

- Static distortions
 - Charge-up effect
 - Space-charge
-

Space-point distortions

Static distortions and charge-up

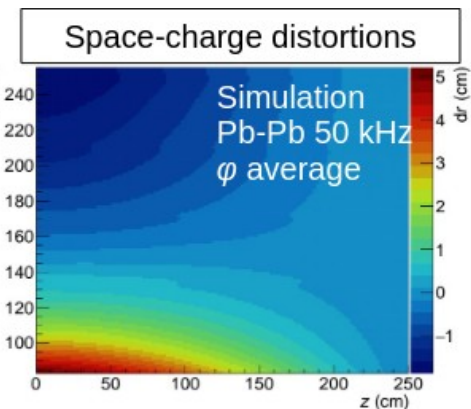
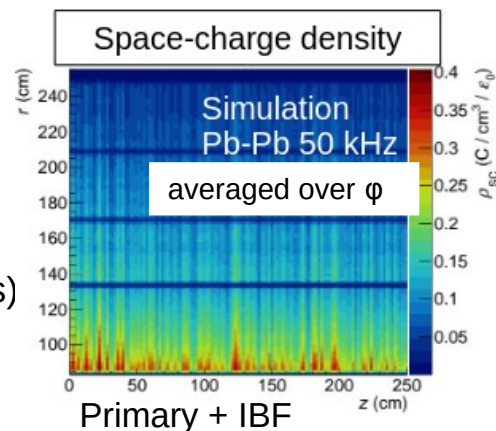
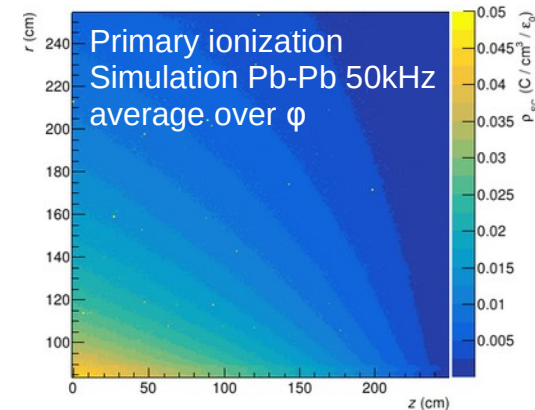
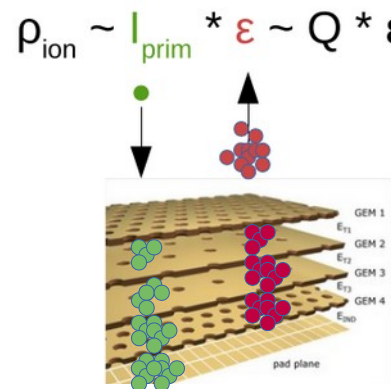
- Static distortions
 - Misalignment between readout chambers and central electrode
 - Misalignment of nominal B- and E-fields due to imperfections
 - Constant in time for given detector configuration
- Charge-up effects
 - **Non-conducting surfaces** of GEM frames
 - Inner field cage close to the central electrode on the C side
 - Time constants O(mins), scaling with load



Space-point distortion contributions

Space-charge

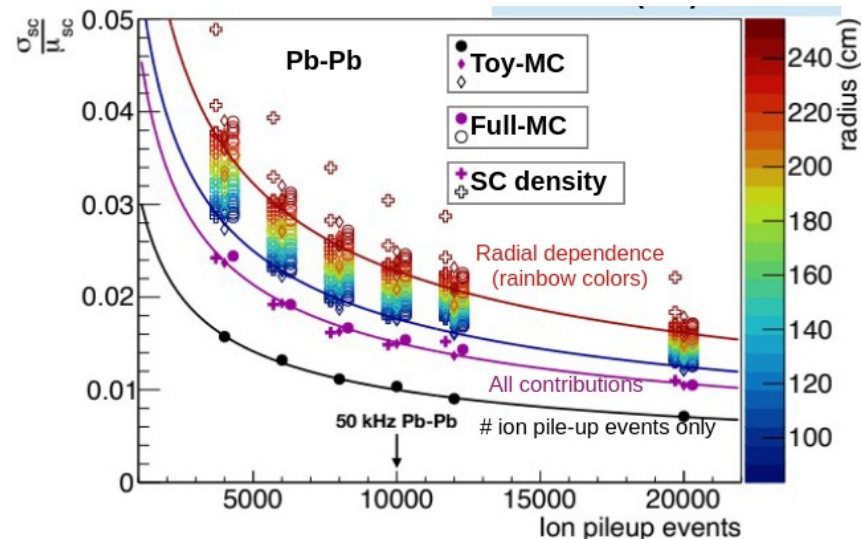
- Ions from amplification stage drift back to the drift volume (~1%)
 - Back drifting ions per primary electron:
 $\varepsilon = \text{IBF} * \text{gain} (2000) = 20$
- Slow ion drift (~200ms for full drift)
 - Ions from large number of events piling up (~10000 events @ Pb-Pb 50kHz)
 - Large space charge
 - Large average distortions (O(5-10cm))
 - Intrinsic resolution at inner wall ~200 μm
- Realistic simulation
 - full detector description (Geant4)
 - Measured relative gain map
 - Measured relative IBF map (with production HV settings)
 - Caveat: linear electron and ion transport



Space-point distortion contributions

Space-charge fluctuations

- Fluctuations driven by
 - Ion backflow x gain = ϵ
 - Number of ion pile-up events within one full ion drift time
 - Particle flux (primary, secondary particles) from collisions
 - Ionization deposited by single particles
- Relative space-charge density fluctuations σ_{sc}/μ_{sc} of $\sim 2\%$ at 50 kHz Pb-Pb
 - Distortion fluctuations of O(mm - cm) in r and $r\phi$
 - Relevant time scales: 5 - 10 ms



Direct measure for density fluctuation required

$$\frac{\sigma_{sc}}{\mu_{sc}} = \frac{1}{\sqrt{N_{pileup}^{ion}}} \sqrt{\underbrace{1 + \left(\frac{\sigma_{N_{mult,prim}}}{\mu_{N_{mult,prim}}}\right)^2 + \left(\frac{\sigma_{N_{mult,relsec}}}{\mu_{N_{mult,relsec}}}\right)^2}_{1D \text{ fluctuations}} + \frac{1}{\left(F_{prim}(r) \cdot \mu_{N_{mult,prim}} + F_{sec}(r) \cdot \mu_{N_{mult,relsec}}\right)} \left[1 + \left(\frac{\sigma_{Q_{track,prim}}(r)}{\mu_{Q_{track,prim}}(r)}\right)^2 + \left(\frac{\sigma_{Q_{track,sec}}(r)}{\mu_{Q_{track,sec}}(r)}\right)^2 \right]}_{3D \text{ fluctuations}}$$

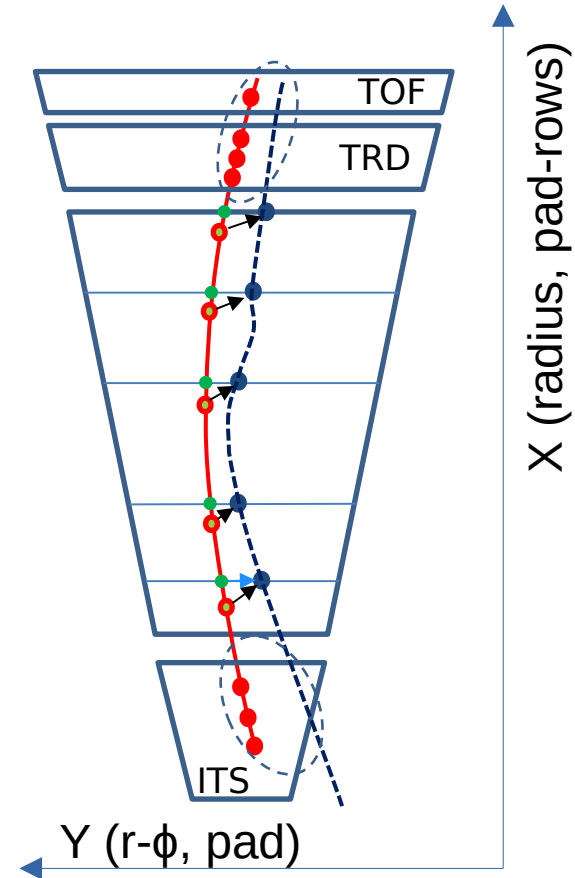
Distortion corrections

- Long term average
 - Short-term average corrections
 - Fluctuation corrections
-

Distortion corrections

Long term average – apparent distortions

- **Main input: direct measure of distortions**
- Reconstruct TPC tracks with relaxed tolerances (applying “default distortion map” if available)
- Match to ITS and TRD/TOF with relaxed tolerances
- Refit ITS-TRD-TOF part and interpolate to TPC as a **reference** of the **true track position** at every pad-row
- Collect δY , δZ differences between **distorted clusters** and **reference** points in sub-volumes (voxels) of TPC





Distortion corrections

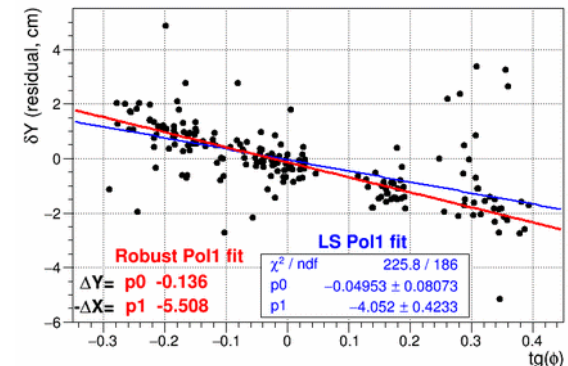
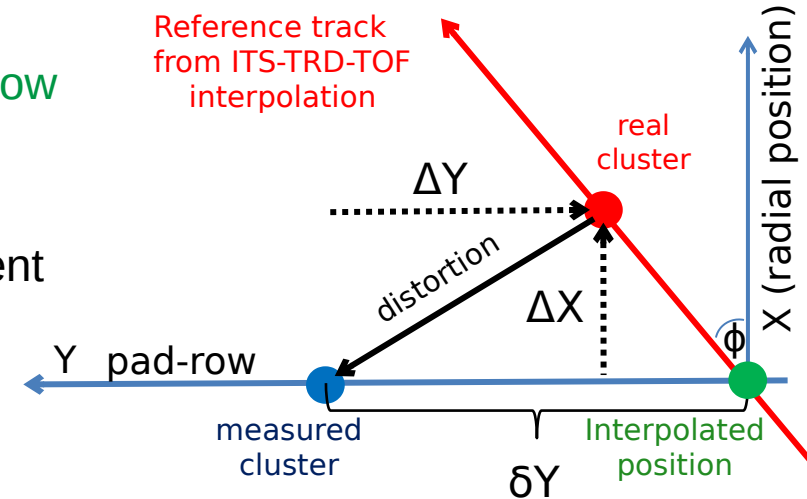
Long term average – real distortions

- We measure Y distortion δY as a difference between reference (ITS-TRD/TOF) **track intersection with pad-row** and **measured cluster**
 - Strong bias due to the X distortions
- Same TPC region (voxel) is probed by tracks at different inclinations ϕ wrt pad row
- Deconvolute real ΔX and ΔY distortions using δY dependence on $\text{tg}(\phi)$ then extract Z distortion

$$\delta Y = \Delta Y - \Delta X \text{tg}(\phi)$$

$$\delta Z = \Delta Z - \Delta X \text{tg}(\lambda)$$

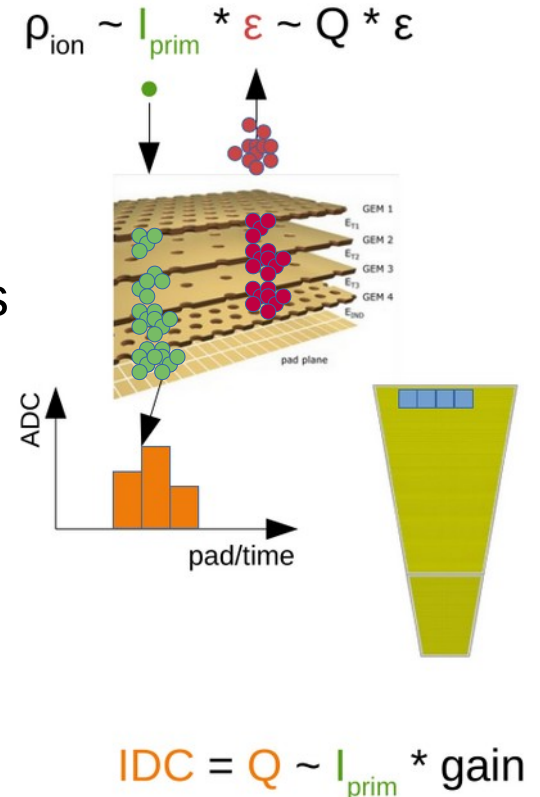
- Keep residual information for each data taking window (time frame – TF = 10ms)
- Integration over longer time intervals ~ 1 min (Pb-Pb) and $< \sim 10$ min (pp): “long term average map” $M_{L,ref}$



Space-charge distortion calibration

Fluctuation measure – Integrated Digital Currents

- **Main input: direct measure of fluctuations**
- Space-charge density related to ADC currents via IBF ($\epsilon = \text{gain} * \text{IBF}$)
 - Assume gain and IBF constant on short time scales
- Integrated Digital Currents - IDCs
 - Integrated ADC values over 1ms inside the readout uni (CRU), pad-by-pad, injected in data stream
 - Factorisation and averaging to minimize data volume at maximum information content



Space-charge distortion calibration

Integrated Digital Currents – Factorisation



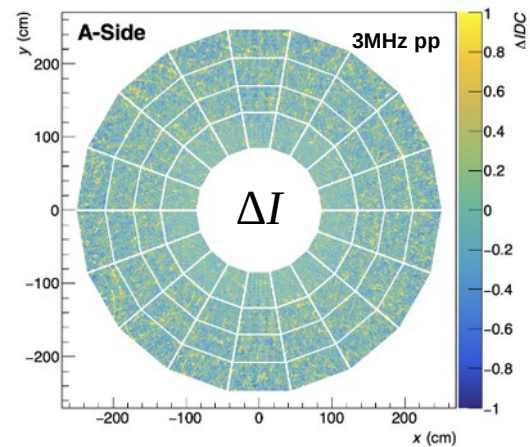
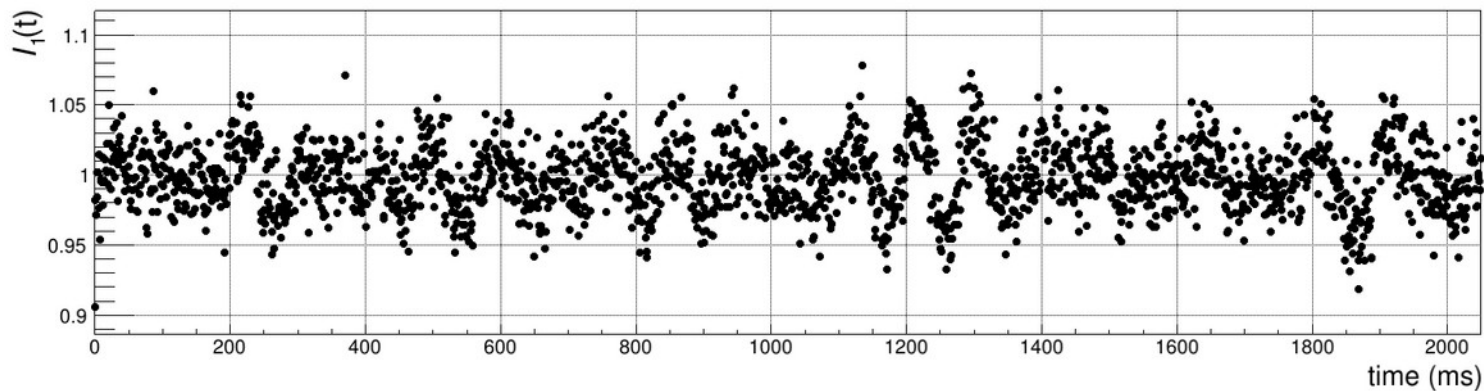
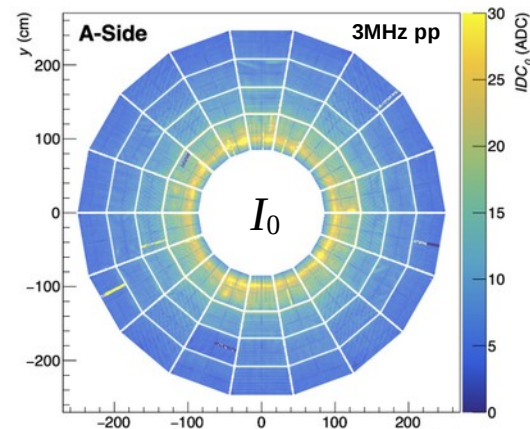
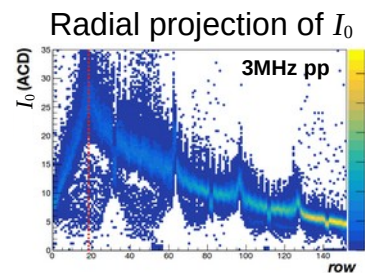
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Factorisation: $I(r, \varphi, t) = I_0(r, \varphi) \cdot I_1(t) \cdot \Delta I(r, \varphi, t)$

$I_0(r, \varphi) = \langle I(r, \varphi, t) \rangle_{t=1000TF_s}$: average IDCs

$I_1(t) = \langle I(r, \varphi, t)/I_0(r, \varphi) \rangle_{r, \varphi}$: 1D-fluctuations

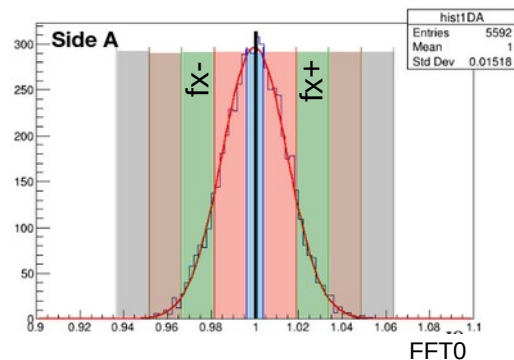
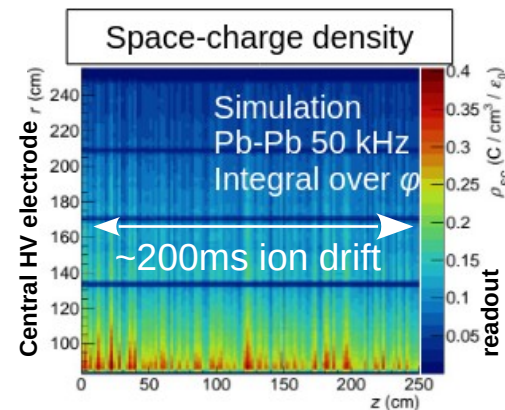
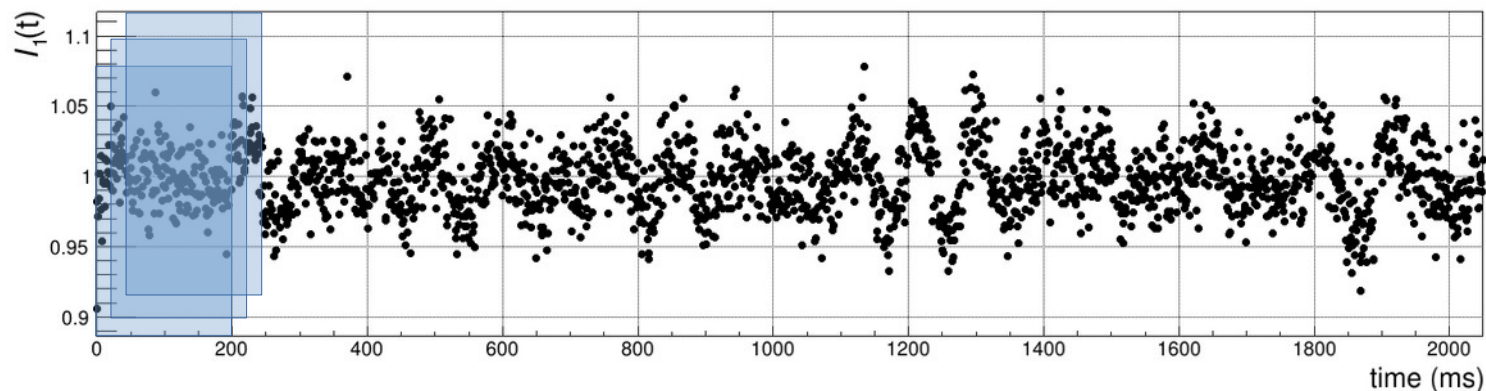
$\Delta I(r, \varphi, t) = I(r, \varphi, t)/(I_0(r, \varphi) \cdot I_1(t))$: 3D fluctuations



Space-charge distortion calibration

Integrated Digital Currents – FFT + 1D classification

- Do FFT decomposition of time intervals reflecting on ion drift (~200ms)
 - Classification of 1D (z) fluctuations
 - Ion drift time required!
- Perform this for “time frame” of 10ms (relevant time scale for fluctuations = data taking window)
- Select time frames of certain classes (e.g. window in FFT0 class) and build the average map for the selected time frames: $M_{L,fx+}$

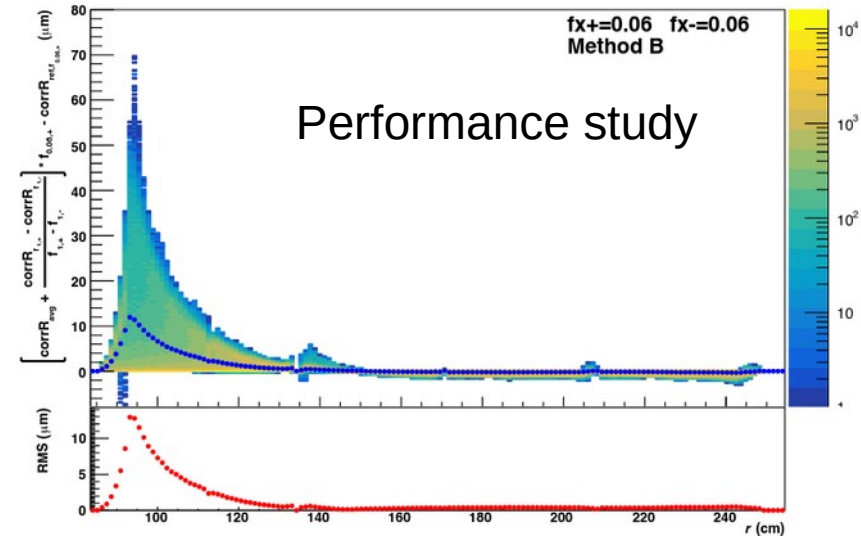


Space-charge distortion calibration

Reconstruction procedure



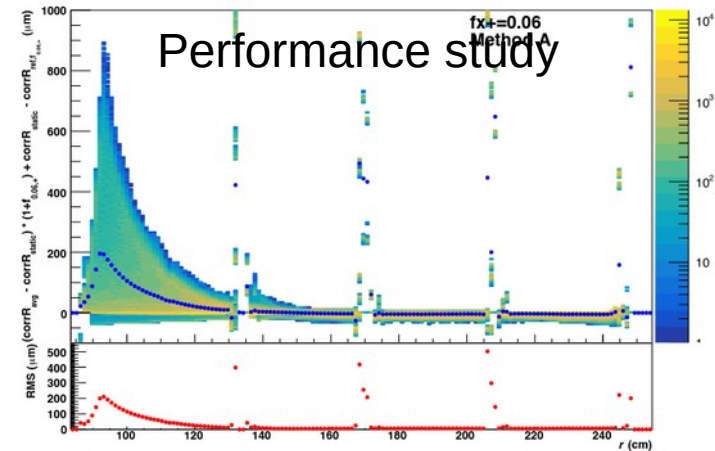
- Perform scaling using local derivatives
- $M_{\text{corr}} = M_{L,\text{ref}} + \Delta M_{L,fx+-} / \Delta \text{FFT0}(I_{1,\text{ref}}) * \text{FFT0}(I_{1,\text{now}})$
 - Alternatively ML using more FFT coefficients
- $M_{L,\text{ref}}$: long-term average map (or offset from linear fit)
- $\Delta M_{L,fx+-} / \Delta \text{FFT0}(I_{1,\text{ref}})$: map from local derivatives



Space-charge distortion calibration

Reconstruction procedure – simplistic approach

- Perform scaling using absolute map
- $M_{\text{corr}} = M_{\text{static}} + (M_{L,\text{ref}} - M_{\text{static}}) * L_{\text{now}} / L_{\text{ref}}$
- M_{static} : long-term average map, measured at low luminosity
- $M_{L,\text{ref}}$: long-term average map measured at high (reference) luminosity
- Caveat: different scaling of static, charge-up and space-charge distortions!



Space-charge distortion calibration

Further plans



- Distortion fluctuations corrections
 - Step 0: Linear regression of fluctuation corrections as a function of derivatives and coefficients for ~ 10 FFT coefficients, $1D = \text{delta of IDCs}$
 - Step 1: Use of ML (Random Forest, BDT) to correct residuals wrt step 0
 - Step 2: Use of CNN to further correct for the 3D case
 - Will depend on the size of the fluctuations and on the performance after Step 0 and Step 1



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Summary

- Different types of distortions present in the TPC (static, charge-up, space-charge)
 - Different scaling over time and detector load to be taken into account
- Large distortions due to space-charge expected $O(5-10\text{cm})$
 - Correction down to intrinsic tracking precision envisaged $O(\text{few } 100\mu\text{m})$
- Two main ingredients for distortion corrections
 - Direct measure of distortions via interpolation from external detector points
 - Measure of fluctuations using continuously integrated digital currents on the pad plane (IDCs)
- Different procedures foreseen for corrections
 - Scaling of absolute distortion map
 - Scaling of local derivative distortion map
 - Linear regression / ML using derivative map and 1D FFT coefficients of IDCs
 - ML using NDim IDC fluctuation information



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Backup

References

- The upgrade of the ALICE TPC with GEMs and continuous readout [arXiv:2012.09518v2](#)
- Reconstruction in ALICE and calibration of TPC space-charge distortions in Run 3 [arXiv:2109.12000v2](#)
- Space-point calibration of the ALICE TPC with track residuals [arXiv:2003.03174](#)
- Upgrade of the ALICE Time Projection Chamber (Technical design report) [CERN Document Server](#)

Space-charge distortion calibration

Ingredients – Ion drift time

- Required for FFT of $I_1(t)$ (1D IDCs)
- Hardware solution
 - Fast readout of CE power supply
 - Correlation currents from CE PS with
 - 1D IDCs, or
 - CE laser signal, or
 - Beam dump signature
- Software solution
 - Uses numerical derivatives of measured residuals wrt. 1D IDC FFT coefficients (same concept as advanced lumi correction)
 - Conceptually proven in toy studies

